

# Stabilizing Grand Cooperation of Machine Scheduling Game via Setup Cost Pricing

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# Outline

- 1 Preliminaries
- 2 Motivation and Illustrative Example
- 3 Models and Analyses
- 4 Algorithms and Computations
- 5 Extension and Generalization
- 6 Conclusion

# PRELIMINARIES

# Cooperative Game

A **cooperative game** is defined by a pair  $(V, C)$ :

- A set  $V = \{1, 2, \dots, v\}$  of players, **grand coalition**;
- A **characteristic function**  $C(S)$  = the minimum total cost achieved by the cooperation of members in coalition  $S \in \mathbb{S} = 2^V \setminus \{\emptyset\}$ .

The game requires:

- A **cost allocation**  $\alpha = [\alpha_1, \alpha_2, \dots, \alpha_v] \in \mathbb{R}^v$ , where  $\alpha_k$  = the cost allocated to each player  $k \in V$ .

Define  $\alpha(S) = \sum_{k \in S} \alpha_k$ .

A cost allocation  $\alpha \in \mathbb{R}^V$  is in the **core** if it satisfies:

- **Budget Balance** Constraint:  $\alpha(V) = C(V)$ ;
- **Coalition Stability** Constraints:  $\alpha(S) \leq C(S)$  for each  $S \in \mathbb{S}$ .

$$\text{Core}(V, C) = \left\{ \alpha : \alpha(V) = C(V), \right. \\ \left. \alpha(S) \leq C(S), \forall S \in \mathbb{S} \setminus \{V\}, \alpha \in \mathbb{R}^V \right\}.$$

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However,  $\text{Core}(V, c)$  can be empty.

# Existing Instruments

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S. Caprara and Letchford (2010, MP), [Liu et al. \(2016, IJOC\)](#)

P. Faigle et al. (2001, IJGT), Schulz and Uhan (2010, OR)

P&S [Liu et al. \(2018, OR\)](#)

Inv. Opt. [Liu et al. \(2020, under review\)](#)

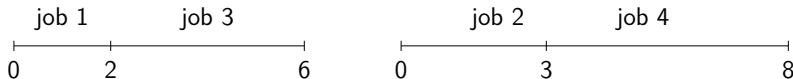
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# ILLUSTRATIVE EXAMPLE

# Example: Machine Scheduling Game (MSG)

## Game of Parallel Machine Scheduling with Setup Cost:

- Grand coalition:  $V = \{1, 2, 3, 4\}$ ;
- Processing times:  $t_1 = 2$ ,  $t_2 = 3$ ,  $t_3 = 4$ ,  $t_4 = 5$ ;
- Machine setup cost:  $t_0 = 9.5$ ;
- $c(S)$  for  $S \in \mathbb{S}$ : minimizes the total completion time of jobs in  $S$  plus the machine setup cost;
- $\pi(N) = \pi(\{1, 3\}) + \pi(\{2, 4\}) = 38$  (SPT Rule).



# Example: Empty Core

Coalitions	Cost
$\{1\}$	11.5
$\{2\}$	12.5
$\{3\}$	13.5
$\{4\}$	14.5
$\{1, 2\}$	16.5
$\{1, 3\}$	17.5
$\{1, 4\}$	18.5
$\{2, 3\}$	19.5
$\{2, 4\}$	20.5
$\{3, 4\}$	22.5
$\{1, 2, 3\}$	25.5
$\{1, 2, 4\}$	26.5
$\{1, 3, 4\}$	28.5
$\{2, 3, 4\}$	31.5
$\{1, 2, 3, 4\}$	38

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## Optimal Cost Allocation Problem

$$\begin{aligned} \max \quad & (\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4) = 37.25 < 38 \\ \text{s.t.} \quad & \alpha_1 \leq 11.5, \dots, \alpha_4 \leq 14.5, \\ & \alpha_1 + \alpha_2 \leq 16.5, \dots, \alpha_3 + \alpha_4 \leq 22.5, \\ & \dots, \\ & \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 \leq 38. \end{aligned}$$

$$\alpha^* = [6; 8.75; 10.75; 11.75]$$



# MODELS & ANALYSES

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- **Each machine Price:**  $P$  and **Each job processing time:**  $t_k$ ;
- **Characteristic function:**  $c(S) = \min(\sum_{k \in S} C_k + Pm_S)$ ,

where  $C_k$  is the completion time of job  $k \in S$  and  $m_S$  is the number of using machine for the sub-coalition  $S$ .

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$$c(S, P) = \min \sum_{k \in V} \sum_{j \in O} c_{kj} x_{kj} + P \sum_{k \in s} x_{k1}$$

$$\text{s.t.} \quad \sum_{j \in O} x_{kj} - y_k^s = 0, \forall k \in V,$$

$$\sum_{k \in V} x_{kj} \leq m, \forall j \in O,$$

$$x_{kj} \in \{0, 1\}, \forall k \in V, \forall j \in O,$$

$$y_k^s = 1, k \in s; y_k^s = 0, k \notin s.$$



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- Denote the right end of every subinterval as  $P_i, 1 \leq i \leq v$ , where  $P_1 = P^*$ .

$$\omega(P) = \min_{\alpha} \{c(V, m(V, P)) - \alpha(V) : \\ \alpha(s) \leq c(s, m(s, P)), \forall s \in S, \alpha \in \mathbb{R}^V\};$$

# Properties

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- $P_i, 2 \leq i \leq v$  can be obtained by SPT rules.
- $P_1 = P_2 + \dots + P_n = \sum_{i=2}^n P_i$ .



# Properties

- When the number of using machines is 1 for the grand coalition, the range of slopes of the line segments in the interval is  $(-1, -\frac{1}{n-1}]$ , and the number of breakpoints is  $O(v^2)$ ;

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- When the number of using machines is 1 for the grand coalition, the range of slopes of the line segments in the interval is  $(-1, -\frac{1}{n-1}]$ , and the number of break-points is  $O(v^2)$ ;
- Define that

$$\omega_1(P) = \min_{\alpha} \{ c(V, m(V, P)) - \alpha(V) : \\ \alpha(s) \leq c(s) + P, \forall s \in S, \alpha \in \mathbb{R}^v \}$$

Then the original problem  $\omega(P)$  is equivalent to  $\omega_1(P)$  which means that all sub-coalitions only use **one** machine.

# ALGORITHMS & COMPUTATIONS

## The Intersection Points Computation(IPC) Algorithm to Construct $\omega(P)$ Function.

**Step 1.** Initially, set  $I^* = \{P_L, P_H\}$  and  $\mathbb{I} = \{[P_L, P_H]\}$ .

**Step 2.** When  $\mathbb{I}$  is not empty: Sort values in  $I^*$  by  $P_0 < P_1 < \dots < P_q$ , where  $P_0 = P_L, P_q = P_H$  and  $q = |I^*| - 1$ .

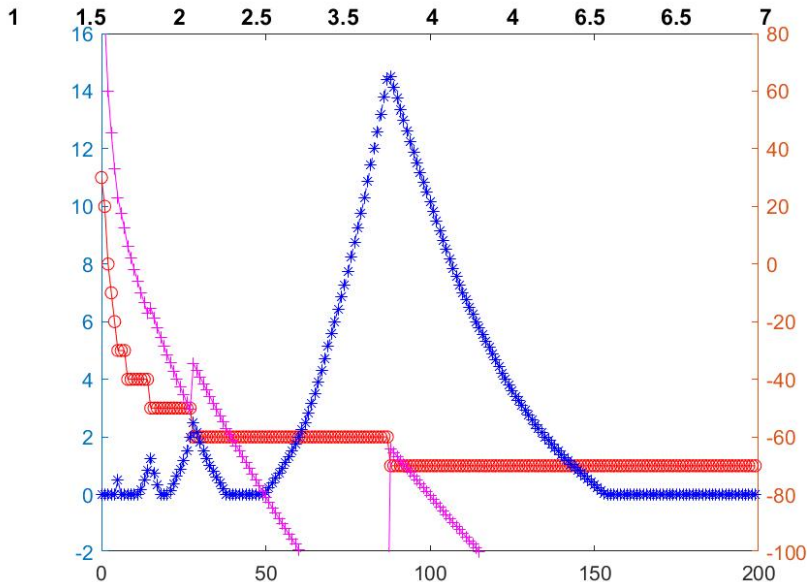
**Step 3.** Obtain an LPB cost allocation  $\alpha_{LP}^{GF}$  with  $\alpha_{LP}^{GF}(N) = \pi_{LP}(N)$ .

# Computational Results

# Instrument 1: LRB Cost Allocation

- Step 1.** Find an LP  $\min_x \{cx : Gx \geq F\gamma^s\}$  giving a lower bound  $\pi_{LP}(S)$  to  $\pi(S)$ ;
- Step 2.** Compute  $(\alpha_{LP}^{GF})_j = (\mu^*)^T F_{.j}$ , where  $\mu^*$ : dual solution;  $F_{.j}$ :  $j$ -th column.
- Step 3.** Obtain an LPB cost allocation  $\alpha_{LP}^{GF}$  with  $\alpha_{LP}^{GF}(N) = \pi_{LP}(N)$ .

# Image



# EXTENSION & GENERALIZATION



# Machine Scheduling Game with Weighted Jobs

# Pricing in General IM Games

## CONCLUSIONS

- ★ **Cooperative Game Theory:**
  - New Instrument for Stabilization via Cost Adjustment.
- ★ **Inverse Problem:**
  - Constrained Inverse Optimization Problem.
- ★ **Models, Solution Methods and Applications:**
  - Several equivalent LP formulations;
  - Feasibility analyses & How to handle infeasibility;
  - Implementations on WMG and UFL games.

Thank you!