

Stabilizing Grand Cooperation of Machine Scheduling Game via Setup Cost Pricing

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Outline

- 1 Preliminaries
- 2 Motivation and Illustrative Example
- 3 Models and Analyses
- 4 Algorithms and Computations
- 5 Extension and Generalization
- 6 Conclusion

PRELIMINARIES

Cooperative Game

A **cooperative game** is defined by a pair (V, C) :

- A set $V = \{1, 2, \dots, v\}$ of players, **grand coalition**;
- A **characteristic function** $C(S)$ = the minimum total cost achieved by the cooperation of members in coalition $S \in \mathbb{S} = 2^V \setminus \{\emptyset\}$.

The game requires:

- A **cost allocation** $\alpha = [\alpha_1, \alpha_2, \dots, \alpha_v] \in \mathbb{R}^v$, where α_k = the cost allocated to each player $k \in V$.

Define $\alpha(S) = \sum_{k \in S} \alpha_k$.

A cost allocation $\alpha \in \mathbb{R}^V$ is in the **core** if it satisfies:

- **Budget Balance** Constraint: $\alpha(V) = C(V)$;
- **Coalition Stability** Constraints: $\alpha(S) \leq C(S)$ for each $S \in \mathbb{S}$.

$$\text{Core}(V, C) = \left\{ \alpha : \alpha(V) = C(V), \right. \\ \left. \alpha(S) \leq C(S), \forall S \in \mathbb{S} \setminus \{V\}, \alpha \in \mathbb{R}^V \right\}.$$

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However, $\text{Core}(V, c)$ can be empty.

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- Penalization: $\alpha(S) \leq C(S) + z$, **least core**;
- Simul. S & P: $\alpha(V) = C(V) - \theta$ and $\alpha(S) \leq C(S) + z$, **PSF**;

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S. Caprara and Letchford (2010, MP), [Liu et al. \(2016, IJOC\)](#)

P. Faigle et al. (2001, IJGT), Schulz and Uhan (2010, OR)

P&S Liu et al. (2018, OR)

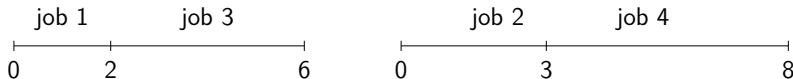
Inv. Opt. Liu et al. (2020, under review)

ILLUSTRATIVE EXAMPLE

Example: Machine Scheduling Game (MSG)

Game of Parallel Machine Scheduling with Setup Cost:

- Grand coalition: $V = \{1, 2, 3, 4\}$;
- Processing times: $t_1 = 2$, $t_2 = 3$, $t_3 = 4$, $t_4 = 5$;
- Machine setup cost: $t_0 = 9.5$;
- $c(S)$ for $S \in \mathbb{S}$: minimizes the total completion time of jobs in S plus the machine setup cost;
- $\pi(N) = \pi(\{1, 3\}) + \pi(\{2, 4\}) = 38$ (SPT Rule).



Example: Empty Core

Coalitions	Cost
$\{1\}$	11.5
$\{2\}$	12.5
$\{3\}$	13.5
$\{4\}$	14.5
$\{1, 2\}$	16.5
$\{1, 3\}$	17.5
$\{1, 4\}$	18.5
$\{2, 3\}$	19.5
$\{2, 4\}$	20.5
$\{3, 4\}$	22.5
$\{1, 2, 3\}$	25.5
$\{1, 2, 4\}$	26.5
$\{1, 3, 4\}$	28.5
$\{2, 3, 4\}$	31.5
$\{1, 2, 3, 4\}$	38

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Optimal Cost Allocation Problem

$$\begin{aligned} \max \quad & (\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4) = 37.25 < 38 \\ \text{s.t.} \quad & \alpha_1 \leq 11.5, \dots, \alpha_4 \leq 14.5, \\ & \alpha_1 + \alpha_2 \leq 16.5, \dots, \alpha_3 + \alpha_4 \leq 22.5, \\ & \dots, \\ & \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 \leq 38. \end{aligned}$$

$$\alpha^* = [6; 8.75; 10.75; 11.75]$$

MODELS & ANALYSES

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- **Identical machine:** $M = \{1, 2, \dots, m\}$;
- **Each machine Price:** P and **Each job processing time:** t_k ;
- **Characteristic function:** $c(S) = \min(\sum_{k \in S} C_k + Pm_S)$,

where C_k is the completion time of job $k \in S$ and m_S is the number of using machine for the sub-coalition S .

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$$c(S, P) = \min \sum_{k \in V} \sum_{j \in O} c_{kj} x_{kj} + P \sum_{k \in S} x_{k1}$$

$$\text{s.t.} \quad \sum_{j \in O} x_{kj} - y_k^S = 0, \forall k \in V,$$

$$\sum_{k \in V} x_{kj} \leq m, \forall j \in O,$$

$$x_{kj} \in \{0, 1\}, \forall k \in V, \forall j \in O,$$

$$y_k^S = 1, k \in S; y_k^S = 0, k \notin S.$$

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- Denote the right end of every subinterval as $P_i, 1 \leq i \leq v$, where $P_1 = P^*$.

$$\omega(P) = \min_{\alpha} \{c(V, m(V, P)) - \alpha(V) : \\ \alpha(s) \leq c(s, m(s, P)), \forall s \in S, \alpha \in \mathbb{R}^V\};$$

Properties

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- $P_i, 2 \leq i \leq v$ can be obtained by SPT rules.
- $P_1 = P_2 + \cdots + P_n = \sum_{i=2}^n P_i$.

Properties

- When the number of using machines is 1 for the grand coalition, the range of slopes of the line segments in the interval is $(-1, -\frac{1}{n-1}]$, and the number of breakpoints is $O(v^2)$;

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- When the number of using machines is 1 for the grand coalition, the range of slopes of the line segments in the interval is $(-1, -\frac{1}{n-1}]$, and the number of breakpoints is $O(v^2)$;
- Define that

$$\omega_1(P) = \min_{\alpha} \{c(V, m(V, P)) - \alpha(V) : \\ \alpha(s) \leq c(s) + P, \forall s \in S, \alpha \in \mathbb{R}^v\}$$

Then the original problem $\omega(P)$ is equivalent to $\omega_1(P)$ which means that all sub-coalitions only use **one** machine.

ALGORITHMS & COMPUTATIONS

The Intersection Points Computation(IPC) Algorithm to Construct $\omega(P)$ Function.

Step 1. Initially, set $I^* = \{P_L, P_H\}$ and $\mathbb{I} = \{[P_L, P_H]\}$.

Step 2. If \mathbb{I} is not empty, update I^* and \mathbb{I} by the following steps:

Step 3. Sort values in I^* by $P_0 < P_1 < \dots < P_q$, where $P_0 = P_L, P_q = P_H$ and $q = |I^*| - 1$.

Step 4. Select any interval from \mathbb{I} , denoted by $[P_{k-1}, P_k]$ with $1 \leq k \leq q$.

Step 5. Construct two linear function $R_{k-1}(P)$ and $L_k(P)$ so that $R_{k-1}(P)$ passes $(P_{k-1}, \omega(P_{k-1}))$ with a slope equal to a right derivative $K_r^{P_{k-1}}$ of $\omega(P)$ at P_{k-1} , and that $L_k(z)$ passes $(P_k, \omega(P_k))$ with a slope equal to a left derivative $K_l^{P_k}$ of $\omega(P)$ at P_k .

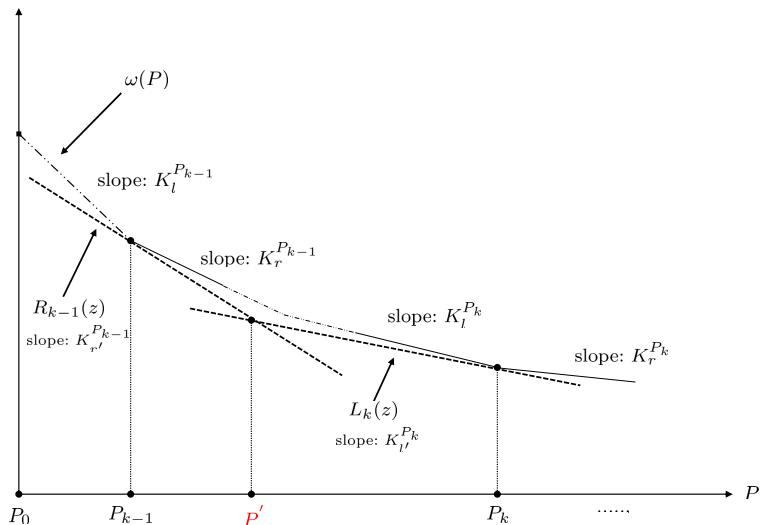
IPC Algorithm

Step 6. If $R_{k-1}(P)$ passes $(P_k, \omega(P_k))$ or $L_k(P)$ passes $(P_{k-1}, \omega(P_{k-1}))$, then update \mathbb{I} by removing $[P_{k-1}, P_k]$. Otherwise, $R_{k-1}(P)$ and $L_k(P)$ must have a unique intersection point at $P = P'$ for some $P' \in (P_{k-1}, P_k)$. Update I^* by adding P' , and update \mathbb{I} by removing $[P_{k-1}, P_k]$, adding $[P_l, P']$ and $[P', P_r]$.

Step 7. Go to step 2.

Step 8. Return a piecewise linear function by connecting points $(P, \omega(P))$ for all $P \in I^*$.

IPC Algorithm



The Cutting Plane(CP) Algorithm to compute $\omega(P)$ for a given P .

Step 1. Let $\mathbb{S}' \subseteq \mathbb{S} \setminus \{N\}$ indicates a restricted coalition set, which includes some initial coalitions, e.g., $\{1\}, \{2\}, \dots, \{v\}$.

Step 2. Find an optimal solution $\bar{\alpha}(\cdot, P)$ to LP $\tau(P)$:

$$\max_{\alpha \in \mathbb{R}^n} \left\{ \alpha(N, P) : \alpha(s, P) \leq c(s) + P, \text{ for all } s \in \mathbb{S}' \right\}.$$

Step 3. Find an optimal solution s^* to **the separation problem**:

$$\delta = \min \left\{ c(s) + P - \bar{\alpha}(s, z) : \forall s \in \mathbb{S} \setminus \{N\} \right\}.$$

Step 4. If $\delta < 0$, then add s^* to \mathbb{S}' , and go to step 2; otherwise, return $\omega(P) = c(N) - \bar{\alpha}(N, P)$.

The Dynamic Programming(DP) Algorithm to solve the separation problem.

Step 1. Initially, let $D(k, u)$ indicate the minimum objective value of the restricted problem of separation problem, where $k \in \{1, 2, \dots, v\}$ and $u \in \{0, 1, \dots, v\}$.

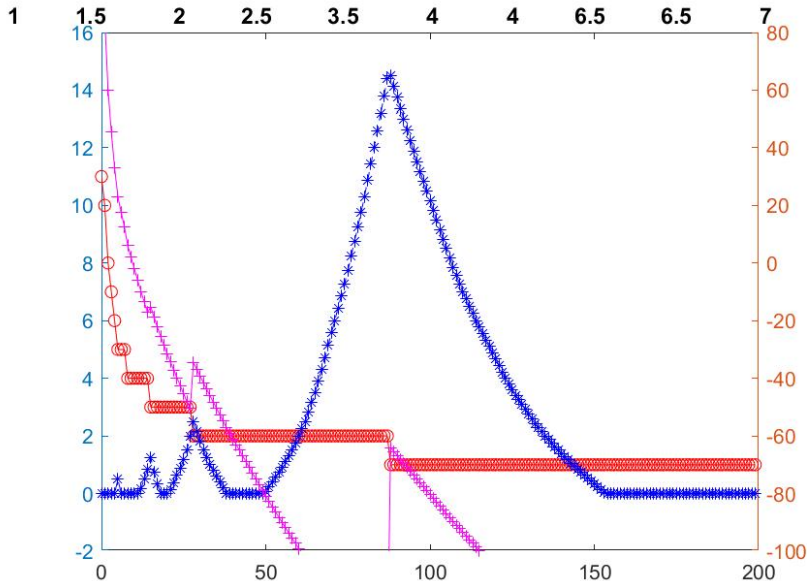
Step 2. Given the initial conditions $D(1, 0) = P$ and $D(1, 1) = t_1 - \beta_1 + P$. The boundary conditions are $D(k, u) = P$ if $u > k$, for all $k \in V$.

Step 3. Given the recursion:

$$D(k, u) = \min \begin{cases} D(k-1, u), & \text{for the case when } s^* \text{ does not contain } k, \\ D(k-1, u-1) + ut_k - \alpha_k, & \text{for the case when } s^* \text{ contains } k. \end{cases}$$

Step 4. Obtain the optimal objective value of separation problem by $\delta_{AIPU} = \min\{D(v, u) : u \in \{1, 2, \dots, v-1\}\}$. return δ_{AIPU} .

Computational Results



EXTENSION & GENERALIZATION

Machine Scheduling Game with Weighted Jobs

- Each job $k \in V$ has a processing time and a weight denoted by t_k, ω_k , respectively.
- $c(S)$ can be obtained by assuming that
$$t_1/\omega_1 \leq t_2/\omega_2 \leq \dots \leq t_v/\omega_v.$$
- $P_m = c_0(V, m) - c_0(V, m - 1), 2 \leq m \leq v.$
- $\omega(P)$ is piecewise linear, and convex in price P at each subinterval.
- The separation problem can be solved in polynomial time.

Pricing in General IM Games

- **ILP**: $c(S, m(S, P)) = \min_x \{cx + Pm(x) : Ax \geq By^s + D, \tilde{\alpha}x \leq m, x \in \mathbb{Z}^{t \times 1}\}$
- **Decompose** $c(S, m(S, P))$ into $c_0(S, m(S)) + Pm$.
- $c_0(V, m) - c_0(V, m-1) > 0 \Leftrightarrow P_m > 0, m = 2, \dots, v$.
- $c_0(V, m) - c_0(V, m+1) < c_0(V, m-1) - c_0(V, m) \Leftrightarrow P_m < P_{m+1}, m = 2, 3, \dots, v-1$.
- $c_0(S_1, m-1) - c_0(S_1, m) \geq c_0(S_1, m) - c_0(S_1, m+1) \quad m = 2, \dots, v-1$.
- $c_0(S_1, m-1) - c_0(S_1, m) \leq c_0(S_2, m-1) - c_0(S_2, m)$
 $m=2, \dots, v$, where $S_1 \subset S_2$.

CONCLUSIONS

- ★ **Cooperative Game Theory:**
 - New Instrument for Stabilization via Setup cost Pricing.
- ★ **Scheduling Problem:**
 - Parallel Machine Scheduling with Setup Cost.
- ★ **Models, Solution Methods and Applications:**
 - Several ILP formulations;
 - Cutting Plane to solve the separation problem;
 - Implementations on the MSGW game.

Thank you!