

Listing 1: **Construct.m**

```

1  function Construct(t)
2  % This function is used to construct the price-subsidy function.
3  % t could be set to [7, 6.5,6.5,4,4,3.5,2.5,2, 1.5,1];
4  interval = Pretreatment(t);
5  x = []; % Restore the value of price at the breakpoints.
6  y = []; % Restore the value of subsidy at the breakpoints.
7
8  for i = 1: length(interval)-1
9      aa = interval(i, 1: 2);
10     [list_x, list_y] = IPCtest(t, [aa(1), aa(2)- 0.5]);
11     x = [x, list_x];
12     y = [y, list_y];
13 end
14
15 x = [x, 0, interval(1, 2)];
16 y = [y, 0, 0];
17 point_xy = [x; y];
18 point_xy = sortrows(point_xy', 1)';
19
20 plot(point_xy(1, :),point_xy(2, :));
21 saveas(gcf, 'IPC.pdf');
22
23 end

```

Listing 2: **Pretreatment.m**

```

1  function [I, price] = Pretreatment(t)
2  % This function is used to obtain the interval of price given the
   % initial processing time of each player.
3  % t is given in a descending order.
4  % Return a list of interval.
5  % The first two elements are the interval of price, the third one is
   % the corresponding number of machines.
6  t1 = fliplr(t); % Reverse the list
7  N = length(t);
8
9  cV = zeros(1, ceil(N/2)+ 1);

```

```

10 % This loop is used to obtain the cV(i)
11 for k = 1: ceil(N/2)+ 1
12     s = floor(N/k);
13     r = rem(N, k);
14     a = (s+1): -1: 1;
15     repeat = k;
16     tmp = repmat(a, repeat, 1);
17     b = reshape(tmp, 1, length(a)* repeat);
18     b(1: k-r) = [];
19     cV(k) = dot(b, t1);
20 end
21
22 price = diff(fliplr(cV)); % [p_n/2, p_n/2-1,...,p_2]
23 p_1 = dot(0: N-1, t);
24
25 price(end+1) = p_1;
26 price = [0, price];
27 I = zeros(ceil(N/2)+ 1, 3);
28
29 for i = 1: ceil(N/2)+ 1
30     I(i, :) = [price(ceil(N/2)- i+ 2), price(ceil(N/2)- i+ 3), i];
31 end
32
33 end

```

Listing 3: **Pm.m**

```

1 function m = Pm(P, t)
2 % Give the price then return the corresponding number of machines.
3 [interval, price] = Pretreatment(t);
4 a = 1;
5 b = length(price);
6 c = floor((a + b)/2);
7 flag = 1;
8
9 if (P < 0) | (P > price(end))
10     disp('Wrong in Pm');
11     return

```

```

12 end
13
14 if abs(P- price(end)) < 1e-5
15     m = 1;
16     return
17 end
18
19 while flag
20     if price(c) <= P
21         if P < price(c + 1)
22             m = b- interval(c, 3);
23             flag = 0;
24
25         else
26             c = floor((c + b)/2);
27         end
28
29     else
30         c = floor((a + c)/2);
31     end
32 end
33
34 end

```

Listing 4: **TotalCost.m**

```

1 function cV = TotalCost(t, P)
2 % This function returns total cost when using m machines and price is
   P.
3 t1 = fliplr(t); % reverse the list
4 N = length(t);
5 k = Pm(P, t);
6
7 s = floor(N/k);
8 r = rem(N, k);
9 a = (s+ 1): -1: 1;
10 repeat = k;
11 tmp = repmat(a, repeat, 1);

```

```

12  b = reshape(tmp, 1, length(a)* repeat);
13  b(1: k-r) = [];
14  cV = dot(b, t1) + k * P;
15
16  end

```

Listing 5: **IPC.m**

```

1  function [Pstar, omega] = IPCTest(t, Pbig)
2  % Pretreatment: Give all the sub-intervals [P_m+1,P_m]
3  % Return intersection set and the corresponding subsidy.
4  % Then we just need connect these points.
5  % t = [7.5,6,5.5,4,3,1.5,1.5,1.5];
6  % Pbig is the interval of price and will gradually decrease
7  v = length(t);
8  Pstar = Pbig; % The set of breakpoints
9  omega = zeros(1, 2);
10 count = 0;
11
12 while ~isempty(Pbig)
13     [a1, b1, c1] = CP(v, t, Pbig(1, 1)); % omega K_l K_r
14     [a2, b2, c2] = CP(v, t, Pbig(1, 2));
15
16     if count < 0.5
17         omega(1) = a1;
18         omega(2) = a2;
19     end
20
21     count = count + 1;
22     slope = (a2- a1)/(Pbig(1, 2)- Pbig(1, 1)); % The value is Negative.
23     % (z_k-1 select K_r) / (z_k select K_l)
24     if (round(b2, 5) == round(slope, 5)) || (abs(c1-slope)< 1e-5)
25         Pbig(1, :) = [];
26     else
27         % How to calculate the intersection point
28         zinter = (c1*Pbig(1, 1) - Pbig(1, 2)*b2 + a2 - a1)/(c1- b2);
29         omega1 = (zinter - Pbig(1, 2))* b2 + a2;
30         [a, b, c] = CP(v, t, zinter);

```

```

31
32     if abs(omega1-a) < 1e-5 % Two subsidy equal, this is the
        breakpoint,
33     % then delete this interval, store the breakpoint
34     omega = [omega, omega1];
35     Pstar = [Pstar, zinter];
36     Pbig(1, :) = [];
37
38     else
39         Pbig(end+1, :) = [Pbig(1,1), zinter];
40         % Notice that there is already add a new row
41         Pbig(end+1, :) = [zinter, Pbig(1,2)];
42         Pbig(1, :) = [];
43     end
44 end
45 end
46
47 end

```

Listing 6: CP.m

```

1  function [omega, K_l, K_r] = CP(v, t, P)
2  % Set the initial coalition s = {{1},{2},{3}...{v}} or |s|=v-1
3  % beta is the optimal solution.
4  % opt_s is a optimal vector solution s.
5  % t is the time cost for every player.
6  % v is number of players.
7  % P is the price.
8  % m is the number of optimal using machines.
9  % return subsidy and min / max slope
10
11  ini_s = 1 - eye(v);
12  cV = TotalCost(t, P); % c_V = m*P +sum_t;
13
14  flag = true;
15  count = 0;
16
17  while flag

```

```

18     [beta, maxr] = LP2(ini_s, v, t, P);
19     [delta, opt_s] = DP(v, t, beta, P);
20
21     if delta < -0.001
22         ini_s = [ini_s; opt_s];
23
24     else
25         omega = cV - maxr;
26         % Here use Coalition obtain all maximum unsatisfied coalitions
27         unsatisfied = Coalition(ini_s, v, t, P);
28         [K_l, K_r] = LP1(unsatisfied, t, P);
29         flag = false;
30     end
31
32     count = count + 1;
33     if count > 100
34         disp('There is something wrong in CP')
35         break
36     end
37 end
38
39 end

```

Listing 7: DP.m

```

1 function [res, s] = DP1(v, t, beta, P)
2 % v is number of players
3 % t and beta are vectors from bottom1 to topN
4 % For example, P = 9.5
5 % t = [5 4 3 2];
6 % beta = [14.5 8 12.5 4];
7 % Notice could not exist V (u \neq v) here.
8 % s is the optimal solution.
9 P = ones(v, v+1);
10 P(1, 1) = P; % P(1, 0) in DP algorithm
11 P(1, 2) = P + t(1) - beta(1); % P(1, 1) in DP algorithm
12
13 ss = cell(v, v+1); % Used to store the corresponding player vector.

```

```

14  ss(1, 1) = {Peros(1, 1)};
15  ss(1, 2) = {ones(1, 1)};
16
17  for i = 2: v
18      % s = ss(:,); % every loop only records this column
19      P(i, 1) = P(i-1, 1);
20      ss(i, 1) = {Peros(1, i)};
21
22      P(i, i+1) = P(i-1, i) + i* t(i) - beta(i);
23      ss(i, i+1) = {ones(1, i)};
24
25      for j = 1: i-1
26          if P(i-1, j+1) > (P(i-1, j)+ j* t(i)- beta(i))
27              P(i, j+1) = P(i-1, j)+ j* t(i)- beta(i); % notice that j is not
                  the ordinal number
28              ss(i, j+1) = {[ss{i-1, j}, 1]};
29
30          else
31              P(i, j+1) = P(i-1, j+1); %
32              ss(i, j+1) = {[ss{i-1, j+1}, 0]};
33          end
34      end
35
36  end
37
38  [res, ind] = min(P(v, 2: v)); % Record the P(v,u) u \in (1:v-1)
39  s = ss{v, 1+ind};
40
41  end

```

Listing 8: Coalition.m

```

1  function unsatisfied = Coalition(s, v, t, z)
2  % This function is used to obtain all the unsatisfied coalitions.
3  % Notice that s is a restricted-coalition matrix.(0-1)
4  % Which is obtained from CP method.
5  % t is a column vector arranged from large to small.
6  % Return all the unsatisfied coalitions.

```

```

7  s1 = length(s(:, 1)); % The number of constraints
8  c_s = zeros(s1, 1);
9
10 for i = 1: s1
11     tot = sum(s(i, :) == 1);
12     inde = s(i,:) == 1; % May not use the function 'find'
13     c_s(i) = dot(1: tot, t(inde)) + z;
14 end
15
16 f = ones(v, 1);
17 b = c_s;
18 % optimset('Display','off');
19 [x, fval, exitflag, output, lambda] = linprog(-f, s, b);
20 inde = lambda.ineqlin ~= 0;
21 normal_order = (1: s1)';
22 normal_order = normal_order(inde);
23 unsatisfied = s(normal_order, :);
24
25 end

```

Listing 9: **LP1.m**

```

1  function [minr, maxr] = LP9(s, t, P)
2  % This function is used to give the min and max slope value.
3  % Notice that s is a matrix. (0-1)
4  % For example, v = 4
5  % s=[0 1 1 0;
6  %    0 1 0 1;
7  %    0 0 1 1;
8  %    1 1 1 0;
9  %    1 1 0 1;
10 %    1 0 1 1;]
11 v = length(t);
12 m_v = Pm(P, t); % Notice that the result has to add m_v.
13 s1 = length(s(:, 1));
14 f = ones(s1, 1);
15 b = ones(v, 1);
16 lb = zeros(s1, 1);

```



```

17  ub = ones(s1, 1);
18
19  [x, fval1] = linprog(-f, [], [], s', b, lb, ub);
20  minr = m_v+ fval1;
21  [x, fval2] = linprog(f, [], [], s', b, lb, ub);
22  maxr = m_v- fval2;
23
24  end

```

Listing 10: **LP2.m**

```

1  function [x, maxr] = LP12(s, v, t, z)
2  % Notice that s is a restricted-coalition matrix.(0-1)
3  % Which is obtained from CP method.
4  % t is a column vector arranged from large to small.
5  % Return the solution vector x and value maxr.
6  s1 = length(s(:, 1)); % The number of constraints
7  c_s = zeros(s1, 1);
8
9  for i =1: s1
10     tot = sum(s(i, :) == 1);
11     inde = s(i, :) == 1; % May not use the function 'find'
12     c_s(i) = dot(1: tot, t(inde)) + z;
13  end
14
15  f = ones(v, 1);
16  b = c_s;
17  [x, fval1] = linprog(-f, s, b);
18  maxr = -fval1;
19
20  end

```

Listing 11: **Players.m**

```

1  function [an, index, Subsidy, difference] = Players(n, S0, an)
2  % At first, we should set up an array to storage the number we need
   later.
3  % n is the quantity of players, and m is the number of machine.

```

```

4  % And we suppose  $m > n$ .
5  ann = []; % ann will be a matrix whose dimension is  $(2^n-1, n)$ .
6  A = eye(n);
7  f = (-1)* ones(n, 1);
8  % ff2n: Two-level full factorial design
9  a1 = ff2n(n);
10 b1 = sum(a1, 2);
11 c1 = [a1, b1];
12 d1 = sortrows(c1, [n+1 1:n], 'descend');
13 e1 = sortrows(d1, n+1);
14 A = e1(:, 1: n);
15 A(1, :) = []; % delete the first row
16
17 for i = 1 : n % i is the number of players
18 % In the first loop, find all combinations of k players and put it in
    an ascending order by default.
19     bn = zeros(1, nchoosek(n, i)); % Store the final result.
20     dn = zeros(1, i);
21     cn = nchoosek(an, i); % Store the temporary sort result.
22     for j = 1: nchoosek(n, i)
23         % The second loop obtain the result in every coalition.
24         for k = 1: i % k in the number of machines.
25             s = floor(i/k); % Obtain the quotient.
26             r = rem(i,k);
27             a = (s+1): -1: 1;
28             repeat = k; % Repeat the number of machines.
29             tmp = repmat(a, repeat, 1);
30             b = reshape(tmp, 1, length(a)* repeat);
31             b(r+1: k) = [];
32             dn(k) = dot(b, cn(j, :)) + k* S0;
33         end
34
35         [minofdn index] = min(dn); % Find the minimum.
36         bn(j) = min(dn);
37     end
38
39     ann = [ann bn];
40 end
41

```

```
42     [x,y] = linprog(f,A,ann);  
43     Subsidy = ann(end)+y;  
44     Taxation = index * S0 ;  
45     difference = Subsidy - Taxation;  
46  
47     end
```