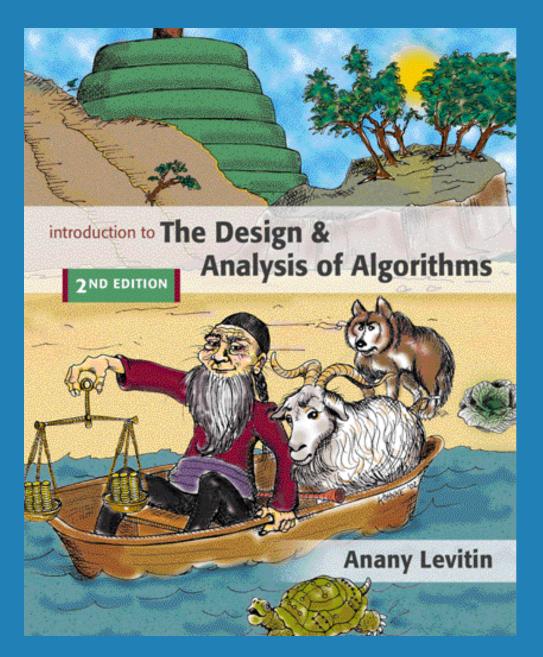
## **Chapter 8**

**Dynamic Programming** 





# **Dynamic Programming**



Dynamic Programming is a general algorithm design technique for solving problems defined by or formulated as recurrences with overlapping subinstances

- Invented by American mathematician Richard Bellman in the 1950s to solve optimization problems and
- "Programming" here means "planning"
- Main idea:
  - set up a recurrence relating a solution to a given problem with solutions to its smaller subproblems of the same type
  - solve smaller instances once
  - record solutions in a table
  - extract solution to the initial instance from that table

## **Example: Fibonacci numbers**



Recall definition of Fibonacci numbers:

$$F(n) = F(n-1) + F(n-2)$$
  
 $F(0) = 0$   
 $F(1) = 1$ 

• Computing the n<sup>th</sup> Fibonacci number recursively (top-down):

$$F(n)$$
 $F(n-1)$  +  $F(n-2)$ 
 $F(n-2)$  +  $F(n-3)$  +  $F(n-4)$ 

000

# Example: Fibonacci numbers (cont.)



Computing the  $n^{th}$  Fibonacci number using bottom-up iteration and recording results:

$$F(0) = 0$$
  
 $F(1) = 1$   
 $F(2) = 1+0 = 1$   
...  
 $F(n-2) = F(n-1) = F(n-1) + F(n-2)$ 

0	1	1	 F(n-2)	F(n-1)	F(n)
			` ` `	` '	` ′

#### **Efficiency:**

- time

n

- space

n

# **Examples of DP algorithms**



- Computing a binomial coefficient
- Warshall's algorithm for transitive closure
- Floyd's algorithm for all-pairs shortest paths
- •Some instances of difficult discrete optimization problems:
  - traveling salesman
  - knapsack



## Computing a binomial coefficient by DP

Computing a binomial coefficient is a standard example of applying dynamic programming to a nonoptimization problem. You may recall from your studies of elementary combinatorics that the **binomial coefficient**, denoted C(n, k) or  $\binom{n}{k}$ , is the number of combinations (subsets) of k elements from an n-element

set  $(0 \le k \le n)$ . The name "binomial coefficients" comes from the participation of these numbers in the binomial formula:

$$(a+b)^n = C(n, 0)a^n + \dots + C(n, k)a^{n-k}b^k + \dots + C(n, n)b^n.$$

Of the numerous properties of binomial coefficients, we concentrate on two:

$$C(n, k) = C(n-1, k-1) + C(n-1, k)$$
 for  $n > k > 0$  (8.3)

and

$$C(n, 0) = C(n, n) = 1.$$
 (8.4)



#### Value of C(n,k) can be computed by filling a table:

	0	1	2		k	-1	_	k	
0	1								
	1	1							
2	1	2	1						
•									
k	1							1	
•									
<i>n</i> -1				$C(n \cdot$	-1,k	<b>-1</b> )			
n							C	(n,k)	)

# Computing C(n,k): pseudocode and analysis

```
ALGORITHM
                Binomial(n, k)
    //Computes C(n, k) by the dynamic programming algorithm
    //Input: A pair of nonnegative integers n \ge k \ge 0
    //Output: The value of C(n, k)
    for i \leftarrow 0 to n do
         for j \leftarrow 0 to min(i, k) do
             if j = 0 or j = i
                  C[i, j] \leftarrow 1
             else C[i, j] \leftarrow C[i-1, j-1] + C[i-1, j]
    return C[n, k]
```

#### Time efficiency: $\Theta(nk)$

What is the time efficiency of this algorithm? Clearly, the algorithm's basic operation is addition, so let A(n, k) be the total number of additions made by this algorithm in computing C(n, k). Note that computing each entry by formula (8.3) requires just one addition. Also note that because the first k + 1 rows of the table form a triangle while the remaining n - k rows form a rectangle, we have to split the sum expressing A(n, k) into two parts:

$$A(n, k) = \sum_{i=1}^{k} \sum_{j=1}^{i-1} 1 + \sum_{i=k+1}^{n} \sum_{j=1}^{k} 1 = \sum_{i=1}^{k} (i-1) + \sum_{i=k+1}^{n} k$$
$$= \frac{(k-1)k}{2} + k(n-k) \in \Theta(nk).$$



	0	1	2	3
0	1			
1	1	1		
2	1	2	1	
$\frac{2}{3}$	1	3	3	1
4	1	4	6	4
5	1	5	10	10
6	1	6	15	20



#### Warshall's Algorithm

Recall that the adjacency matrix  $A = \{a_{ij}\}$  of a directed graph is the boolean matrix that has 1 in its *i*th row and *j*th column if and only if there is a directed edge from the *i*th vertex to the *j*th vertex. We may also be interested in a matrix containing the information about the existence of directed paths of arbitrary lengths between vertices of a given graph.

**DEFINITION** The *transitive closure* of a directed graph with n vertices can be defined as the n-by-n boolean matrix  $T = \{t_{ij}\}$ , in which the element in the ith row  $(1 \le i \le n)$  and the jth column  $(1 \le j \le n)$  is 1 if there exists a nontrivial directed path (i.e., a directed path of a positive length) from the ith vertex to the jth vertex; otherwise,  $t_{ij}$  is 0.

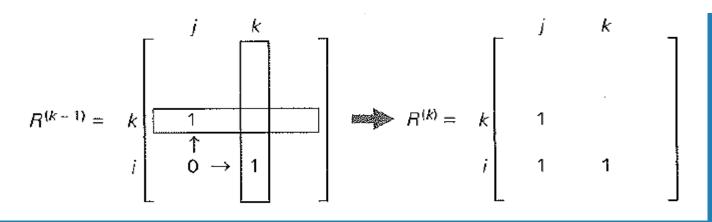
Warshall's algorithm after S. Warshall [War62]. Warshall's algorithm constructs the transitive closure of a given digraph with n vertices through a series of n-by-n boolean matrices:

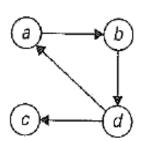
$$R^{(0)}, \ldots, R^{(k-1)}, R^{(k)}, \ldots, R^{(n)}.$$
 (8.5)

$$r_{ij}^{(k)} = r_{ij}^{(k-1)} \text{ or } \left( r_{ik}^{(k-1)} \text{ and } r_{kj}^{(k-1)} \right).$$
 (8.7)

Formula (8.7) is at the heart of Warshall's algorithm. This formula implies the following rule for generating elements of matrix  $R^{(k)}$  from elements of matrix  $R^{(k-1)}$ , which is particularly convenient for applying Warshall's algorithm by hand:

- If an element  $r_{ij}$  is 1 in  $R^{(k-1)}$ , it remains 1 in  $R^{(k)}$ .
- If an element  $r_{ij}$  is 0 in  $R^{(k-1)}$ , it has to be changed to 1 in  $R^{(k)}$  if and only if the element in its row i and column k and the element in its column j and row k are both 1's in  $R^{(k-1)}$ . (This rule is illustrated in Figure 8.3.)





c	' -
0 0	ij
0 1	
0 0	)
1 0	)
	0 0

		_ 8	D	C	α_
	а	0	1	0	0
R(1) =	b	0	0	0	1
HIII =	C	0	0	0	0
	ø	1	1	1	0
		∟ '		'	

$$R^{(2)} = \begin{array}{c|cccc} a & b & c & d \\ \hline a & 0 & 1 & 0 & 1 \\ b & 0 & 0 & 0 & 1 \\ c & 0 & 0 & 0 & 0 \\ d & 1 & 1 & 1 & 1 \end{array}$$

$$R^{(4)} = \begin{bmatrix} a & b & c & d \\ 1 & 1 & 1 & 1 \\ b & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ d & 1 & 1 & 1 & 1 \end{bmatrix}$$

Ones reflect the existence of paths with no intermediate vertices  $(R^{(0)})$  is just the adjacency matrix; boxed row and column are used for getting  $R^{(1)}$ .

Ones reflect the existence of paths with intermediate vertices numbered not higher than 1, i.e., just vertex a (note a new path from d to b); boxed row and column are used for getting  $R^{(2)}$ .

Ones reflect the existence of paths with intermediate vertices numbered not higher than 2, i.e., a and b (note two new paths); boxed row and column are used for getting R<sup>(3)</sup>.

Ones reflect the existence of paths with intermediate vertices numbered not higher than 3, i.e., a, b, and c (no new paths); boxed row and column are used for getting R<sup>(4)</sup>.

Ones reflect the existence of paths with intermediate vertices numbered not higher than 4, i.e., a, b, c, and d (note five new paths).

## **ALGORITHM** Warshall(A[1..n, 1..n])

```
//Implements Warshall's algorithm for computing the transitive closure
//Input: The adjacency matrix A of a digraph with n vertices
//Output: The transitive closure of the digraph
R^{(0)} \leftarrow A
for k \leftarrow 1 to n do
     for i \leftarrow 1 to n do
          for j \leftarrow 1 to n do
               R^{(k)}[i,j] \leftarrow R^{(k-1)}[i,j] \text{ or } (R^{(k-1)}[i,k] \text{ and } R^{(k-1)}[k,j])
return R^{(n)}
```



$$R^{(4)} = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

## Floyd's Algorithm for the All-Pairs Shortest-Paths Problem

Given a weighted connected graph (undirected or directed), the *all-pairs shortest-paths problem* asks to find the distances (the lengths of the shortest paths) from each vertex to all other vertices. It is convenient to record the lengths of shortest paths in an n-by-n matrix D called the *distance matrix*: the element  $d_{ij}$  in the ith row and the jth column of this matrix indicates the length of the shortest path from the ith vertex to the jth vertex ( $1 \le i$ ,  $j \le n$ ). For an example, see Figure 8.5.

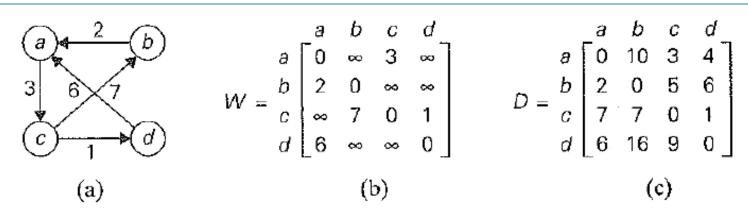
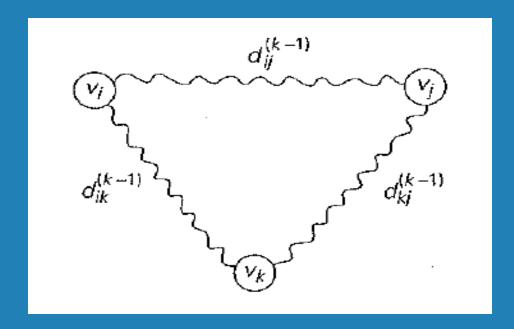


FIGURE 8.5 (a) Digraph. (b) Its weight matrix. (c) Its distance matrix.



Floyd's algorithm computes the distance matrix of a weighted graph with n vertices through a series of n-by-n matrices:

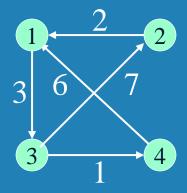
$$D^{(0)}, \ldots, D^{(k-1)}, D^{(k)}, \ldots, D^{(n)}.$$
 (8.8)



$$d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, \ d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\} \quad \text{for } k \ge 1, \quad d_{ij}^{(0)} = w_{ij}.$$

# Floyd's Algorithm (example)





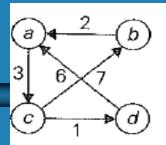
$$D^{(0)} = \begin{bmatrix} 0 & \infty & 3 & \infty \\ 2 & 0 & \infty & \infty \\ \infty & 7 & 0 & 1 \\ 6 & \infty & \infty & 0 \end{bmatrix}$$

$$D^{(1)} = \begin{array}{c|cccc} 0 & \infty & 3 & \infty \\ \hline 2 & 0 & 5 & \infty \\ \hline \infty & 7 & 0 & 1 \\ 6 & \infty & 9 & 0 \end{array}$$

$$D^{(2)} = \begin{array}{c|ccc} 0 & \infty & 3 & \infty \\ 2 & 0 & 5 & \infty \\ \hline 9 & 7 & 0 & 1 \\ \hline 6 & \infty & 9 & 0 \end{array}$$

$$D^{(3)} = \begin{array}{c} 0 & \mathbf{10} & 3 & \mathbf{4} \\ 2 & 0 & 5 & \mathbf{6} \\ 9 & 7 & 0 & 1 \\ \hline \mathbf{6} & \mathbf{16} & 9 & 0 \end{array}$$

$$D^{(4)} = \begin{array}{c} 0 & 10 & 3 & 4 \\ 2 & 0 & 5 & 6 \\ \hline 7 & 7 & 0 & 1 \\ 6 & 16 & 9 & 0 \end{array}$$



		_ a	b	C	ď
	а	0	00	3	00
D(0) ==	b	2	0	00	60
Dio =	c	•	7	0	1
	d	6	000	00	O
	L				_

$$D^{(1)} = \begin{array}{c|cccc} a & b & c & d \\ \hline 0 & \infty & 3 & \infty \\ \hline 2 & 0 & \mathbf{5} & \infty \\ \hline c & \infty & 7 & 0 & 1 \\ d & 6 & \infty & \mathbf{9} & 0 \\ \hline \end{array}$$

$$D^{(2)} = \begin{array}{c|cccc} a & b & c & d \\ \hline a & 0 & \infty & 3 & \infty \\ b & 2 & 0 & 5 & \infty \\ \hline c & \mathbf{9} & 7 & 0 & 1 \\ d & 6 & \infty & 9 & 0 \\ \end{array}$$

$$D^{(3)} = \begin{array}{c|cccc} a & b & c & d \\ \hline a & 0 & \mathbf{10} & 3 & \mathbf{4} \\ b & 2 & 0 & 5 & \mathbf{6} \\ c & 9 & 7 & 0 & 1 \\ d & \mathbf{6} & \mathbf{16} & 9 & 0 \\ \hline \end{array}$$

$$D^{(4)} = \begin{bmatrix} a & b & c & d \\ 0 & 10 & 3 & 4 \\ 2 & 0 & 5 & 6 \\ c & 7 & 7 & 0 & 1 \\ d & 6 & 16 & 9 & 0 \end{bmatrix}$$

Lengths of the shortest paths with no intermediate vertices  $(D^{(0)})$  is simply the weight matrix).

Lengths of the shortest paths with intermediate vertices numbered not higher than 1, i.e. just a (note two new shortest paths from b to c and from d to c).

Lengths of the shortest paths with intermediate vertices numbered not higher than 2, i.e. a and b (note a new shortest path from c to a).

Lengths of the shortest paths with intermediate vertices numbered not higher than 3, i.e. a, b, and c (note four new shortest paths from a to b, from a to d, from b to d, and from d to b).

Lengths of the shortest paths with intermediate vertices numbered not higher than 4, i.e. a, b, c, and d (note a new shortest path from c to a).

# Floyd's Algorithm (pseudocode and analysis)

# **ALGORITHM** Floyd(W[1..n, 1..n])//Implements Floyd's algorithm for the all-pairs shortest-paths problem //Input: The weight matrix W of a graph with no negative-length cycle //Output: The distance matrix of the shortest paths' lengths $D \leftarrow W$ //is not necessary if W can be overwritten for $k \leftarrow 1$ to n do for $i \leftarrow 1$ to n do for $j \leftarrow 1$ to n do $D[i, j] \leftarrow \min\{D[i, j], D[i, k] + D[k, j]\}$ return D

## **Problem**



Solve the all-pairs shortest-path problem for the digraph with the weight matrix.

0	2 00	1	8			
6 (		0	2	3	1	4
$\infty$		6	0	3	2	5
$\infty$	$D^{(5)} =$	10	12	0	4	7
3		6	8	2	0	3
		<b>6</b> 3	5	6	4	0
	'					_

# Knapsack Problem by DP



#### Given *n* items of

integer weights:  $w_1$   $w_2$  ...  $w_n$ 

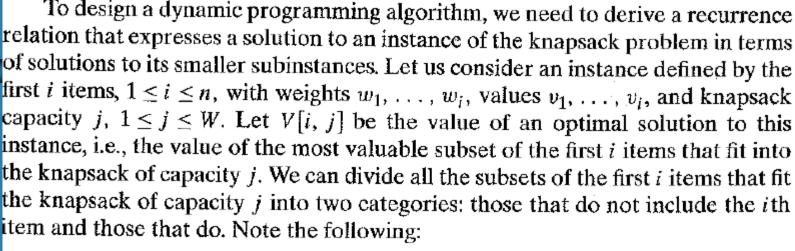
values:  $v_1 \quad v_2 \quad \dots \quad v_n$ 

a knapsack of integer capacity W

find most valuable subset of the items that fit into the knapsack



To design a dynamic programming algorithm, we need to derive a recurrence relation that expresses a solution to an instance of the knapsack problem in terms of solutions to its smaller subinstances. Let us consider an instance defined by the first i items,  $1 \le i \le n$ , with weights  $w_1, \ldots, w_i$ , values  $v_1, \ldots, v_i$ , and knapsack capacity j,  $1 \le j \le W$ . Let V[i, j] be the value of an optimal solution to this instance, i.e., the value of the most valuable subset of the first i items that fit into the knapsack of capacity j. We can divide all the subsets of the first i items that fit the knapsack of capacity j into two categories: those that do not include the ith item and those that do. Note the following:



- Among the subsets that do not include the ith item, the value of an optimal subset is, by definition, V[i-1, j].
- Among the subsets that do include the *i*th item (hence,  $j w_i \ge 0$ ), an optimal subset is made up of this item and an optimal subset of the first i-1 items that fit into the knapsack of capacity  $j - w_i$ . The value of such an optimal subset is  $v_i + V[i-1, j-w_i]$ .

		0	$j$ – $w_i$	j	W
	0	0	0	0	0
w <sub>i</sub> , v <sub>i</sub>	i-1 i	0	$V[i-1, j-w_i]$	V[i-1, j] V[i, j]	ANAMERE
	n	0			goal





Consider instance defined by first *i* items and capacity j ( $j \le W$ ).

Let V[i,j] be optimal value of such an instance. Then

$$V[i,j] = \begin{cases} \max \left\{ V[i-1,j], \, v_i + V[i-1,j-w_i] \right\} & \text{if } j\text{-}\ w_i \geq 0 \\ \\ V[i-1,j] & \text{if } j\text{-}\ w_i \leq 0 \end{cases}$$

Initial conditions: V[0,j] = 0 and V[i,0] = 0

# Knapsack Problem by DP (example)



### Example: Knapsack of capacity W = 5

\$15

ite	em	weight	value		may (I/R 1 d) u ± I/R 1 d u 1)	18 t 10 > 0
	1	2	\$12	V[i,j] =	$\max \{V[i-1,j], v_i + V[i-1,j-w_i]\}$	$11 - m_i \leq 0$
,	2	1	<b>\$10</b>	\ [3]	V[i-1,j]	if $j$ - $w_i < 0$
•	3	3	<b>\$20</b>		' [º <del>-</del> Ŋ]	IIJ M
	4		<b>₼</b> 4 <b>=</b>		• 4	

#### capacity j

		U	1	2	3	4	5	
	0	0	0	0	0	0	0	
$w_1 = 2, v_1 = 12$	1	0	0	12	12	12	12	
$w_2 = 1, v_2 = 10$	2	0	10	12	22	22	22	
$w_3 = 3, v_3 = 20$	3	0	10	12	22	30	32	4
$w_4 = 2, v_4 = 15$	4				25	30	37	

Backtracing finds the actual optimal subset, i.e. solution.

# **Memory functions**

```
ALGORITHM
                MFKnapsack(i, j)
    //Implements the memory function method for the knapsack problem
    //Input: A nonnegative integer i indicating the number of the first
            items being considered and a nonnegative integer j indicating
            the knapsack's capacity
    //Output: The value of an optimal feasible subset of the first i items
    //Note: Uses as global variables input arrays Weights[1..n], Values[1..n],
    //and table V[0..n, 0..W] whose entries are initialized with -1's except for
    //row 0 and column 0 initialized with 0's
    if V[i, j] < 0
        if j < Weights[i]
            value \leftarrow MFKnapsack(i-1, j)
        else
            value \leftarrow \max(MFKnapsack(i-1, j),
                           Values[i] + MFKnapsack(i-1, j-Weights[i])
        V[i, j] \leftarrow value
    return V[i, j]
```

# Example

### **Example: Knapsack of capacity**

W = 5

<u>item</u>	weight	<u>value</u>
1	2	<b>\$12</b>
2	1	<b>\$10</b>
3	3	<b>\$20</b>
4	2	<b>\$15</b>

i/j	0	1	2	3	4	5
0	0	0	0	0	0	0
1	0	0	12	12	12	12
2	0	-	12	22	-	22
3	0	-	-	22	-	32
4	0	-	-	-	-	37







	value	weight	item
	\$25	3	1
	\$20	2	2
capacity W =	\$15	1	3
	\$40	4	4
	\$50	5	5