

# ASSIGNMENT 1

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Download all latex-tikz codes from

[https://github.com/Dishank422/EE3900/blob/main/Gate-Assignment1/latex\\_code.tex](https://github.com/Dishank422/EE3900/blob/main/Gate-Assignment1/latex_code.tex)

1 EC 2019 Q.33

Let the state-space representation on an LTI system be  $\dot{x}(t) = Ax(t) + Bu(t)$ ,  $y(t) = Cx(t) + du(t)$  where  $A, B, C$  are matrices,  $d$  is a scalar,  $u(t)$  is the input to the system, and  $y(t)$  is its output. Let  $B = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}^T$  and  $d = 0$ . Which one of the following options for  $A$  and  $C$  will ensure that the transfer function of this LTI system is

$$H(s) = \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (1.0.1)$$

(A)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix}$  and  $C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$

(B)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix}$  and  $C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$

(C)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix}$  and  $C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$

(D)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix}$  and  $C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$

## 2 SOLUTION

We are given

$$\begin{pmatrix} \dot{x}(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} A & B \\ C & d \end{pmatrix} \begin{pmatrix} x(t) \\ u(t) \end{pmatrix} \quad (2.0.1)$$

Taking Laplace transform on both sides,

$$\begin{pmatrix} sX(s) \\ Y(s) \end{pmatrix} = \begin{pmatrix} A & B \\ C & d \end{pmatrix} \begin{pmatrix} X(s) \\ U(s) \end{pmatrix} \quad (2.0.2)$$

$$\Rightarrow sX(s) = AX(s) + BU(s) \quad (2.0.3)$$

$$\Rightarrow X(s) = (sI - A)^{-1}BU(s) \quad (2.0.4)$$

$$\Rightarrow Y(s) = CX(s) + dU(s) \quad (2.0.5)$$

$$= C(sI - A)^{-1}BU(s) + dU(s) \quad (2.0.6)$$

Since,  $d = 0$ ,

$$Y(s) = C(sI - A)^{-1}BU(s) \quad (2.0.7)$$

By definition,

$$Y(s) = H(s)U(s) \quad (2.0.8)$$

$$\Rightarrow H(s) = C(sI - A)^{-1}B \quad (2.0.9)$$

$$= \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (2.0.10)$$

$$\Rightarrow C(sI - A)^{-1}B = \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (2.0.11)$$

Now we substitute the options into eq 2.0.11.

(A)

$$C(sI - A)^{-1}B = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 1 & 2 & s+3 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (2.0.12)$$

$$= \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (2.0.13)$$

(B)

$$C(sI - A)^{-1}B = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 3 & 2 & s+1 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (2.0.14)$$

$$= \frac{1}{s^3 + s^2 + 2s + 3} \quad (2.0.15)$$

(C)

$$C(sI - A)^{-1}B = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 1 & 2 & s+3 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (2.0.16)$$

$$= \frac{s^2}{s^3 + 3s^2 + 2s + 3} \quad (2.0.17)$$

(D)

$$C(sI - A)^{-1}B = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 3 & 2 & s+1 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (2.0.18)$$

$$= \frac{s^2}{s^3 + s^2 + 2s + 3} \quad (2.0.19)$$

Hence only option A is the correct option.