#### 1

# **ASSIGNMENT 1**

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Download all latex-tikz codes from

https://github.com/Dishank422/EE3900/blob/main/ Gate-Assignment1/latex code.tex

## 1 EC 2019 Q.33

Let the state-space representation on an LTI system be  $\dot{x}(t) = Ax(t) + Bu(t)$ , y(t) = Cx(t) + du(t) where A,B,C are matrices, d is a scalar, u(t) is the input to the system, and y(t) is its output. Let  $B = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$ and d = 0. Which one of the following options for A and C will ensure that the transfer function of this LTI system is

$$H(s) = \frac{1}{s^3 + 3s^2 + 2s + 1}$$
 (1.0.1)

(A) 
$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix}$$
 and  $C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$   
(B)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix}$  and  $C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$   
(C)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix}$  and  $C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$   
(D)  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix}$  and  $C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$ 

(B) 
$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix}$$
 and  $C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$ 

(C) 
$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix}$$
 and  $C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$ 

(D) 
$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix}$$
 and  $C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$ 

### 2 Solution

We are given

$$\begin{pmatrix} \dot{x}(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} A & B \\ C & d \end{pmatrix} \begin{pmatrix} x(t) \\ u(t) \end{pmatrix}$$
 (2.0.1)

Taking Laplace transform on both sides,

$$\begin{pmatrix} sX(s) \\ Y(s) \end{pmatrix} = \begin{pmatrix} A & B \\ C & d \end{pmatrix} \begin{pmatrix} X(s) \\ U(s) \end{pmatrix}$$
 (2.0.2)

$$\implies sX(s) = AX(s) + BU(s)$$
 (2.0.3)

$$\implies X(s) = (sI - A)^{-1}BU(s) \tag{2.0.4}$$

$$\implies Y(s) = CX(s) + dU(s)$$
 (2.0.5)

$$= C(sI - A)^{-1}BU(s)$$
 (2.0.6)

By definition,

(B)

$$Y(s) = H(s)U(s) \tag{2.0.7}$$

$$\implies H(s) = C(sI - A)^{-1}B \qquad (2.0.8)$$

$$=\frac{1}{s^3+3s^2+2s+1}$$
 (2.0.9)

$$\implies C(sI - A)^{-1}B = \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (2.0.10)$$

Now we substitute the options into eq 2.0.10.

(A)  $C(sI - A)^{-1}B = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 1 & 2 & s+3 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ 

$$=\frac{1}{s^3+3s^2+2s+1}$$
 (2.0.12)

$$C(sI - A)^{-1}B = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 3 & 2 & s+1 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$
(2.0.13)

$$=\frac{1}{s^3+s^2+2s+3}$$
 (2.0.14)

$$C(sI - A)^{-1}B = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 1 & 2 & s+3 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$(2.0.15)$$

$$= \frac{s^2}{s^3 + 3s^2 + 2s + 3} \qquad (2.0.16)$$

$$C(sI - A)^{-1}B = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 3 & 2 & s+1 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$(2.0.17)$$

$$= \frac{s^2}{s^3 + s^2 + 2s + 3} \qquad (2.0.18)$$

Hence only option A is the correct option.