

Linearising Flows and a Cohomological Interpretation of Lax Equations - Unpacking the Paper

Linden Disney-Hogg

November 2020

Contents

1	Introduction	1
2	The Paper	1
2.1	Laying out the Ingredients	1
2.2	The Eigenvector Mapping as a Deformation	2
2.3	Combining with the Euler Sequence	3

1 Introduction

The purpose of this document is to facilitate the understanding of [1] by discussing the terms and how they fit into the wider picture of algebraic geometry.

2 The Paper

2.1 Laying out the Ingredients

Notation. We start by laying out some notation that will be necessary for the following section. Let:

- $P = \mathbb{CP}^1$ with coordinates $[\xi_0 : \xi_1]$. We take $\xi = \frac{\xi_1}{\xi_0}$.
- \mathcal{O}_P be the natural structure sheaf on the variety P
- V be a m -dimensional vector space, $\mathcal{V} = V \otimes \mathcal{O}_P$, $\mathcal{V}(k) = V \otimes \mathcal{O}_P(k)$ where we view V as either the constant sheaf or trivial bundle over P .
- $A(t, \xi) = \sum_{k=0}^n A_k(t) \xi^k \in H^0(P, \text{Hom}(\mathcal{V}, \mathcal{V}(n)))$ for some n , where we see $A_i(t) \in \text{End}(V)$ as a time dependent $m \times m$ matrix and $\xi^k \in H^0(P, \mathcal{O}(n))$ as

$$[\xi_0 : \xi_1]^k = \underbrace{\xi_0 \otimes \cdots \otimes \xi_0}_{\times (n-k)} \otimes \underbrace{\xi_1 \otimes \cdots \otimes \xi_1}_{\times k}$$

This is homogeneous of degree n , so we allow A to not have a scale?

- $B(\xi, t) \in H^0(P, \text{Hom}(\mathcal{V}, \mathcal{V}(N)))$ for some N likewise.
- $Q(\xi, \eta) = \det[\eta I - A(\xi, t)]$ be the characteristic polynomial of A .
- σ be the tautological section of $\mathcal{O}_P(n)$.

Lemma 2.1. $Q(\xi, \sigma) \in H^0(\mathcal{O}_P(n), \pi^* \mathcal{O}_P(mn))$

Definition 2.2. The pair A, B is a Lax pair if $\dot{A} = [A, B]$.

Proposition 2.3. The Lax equation is invariant under the substitution

$$B \mapsto B + p(A, \xi)$$

for polynomial $p(x, \xi) \in \mathbb{C}[x, \xi]$.

Definition 2.4. The *spectral curve* is C given by the solution in P of

$$Q(\xi, \eta) = 0$$

Proposition 2.5. The flow $t \mapsto A(\xi, t)$ is isospectral.

It will be the understanding of this isospectral flow that we want to gain. We formulate this flow as the family of holomorphic map gained by the eigenvectors

$$f_t : C \rightarrow \mathbb{P}V \cong \mathbb{P}^{m-1}$$

Suppose that C has degree d , then we know we can define

$$L_t = f_t^* \mathcal{O}_{\mathbb{P}V}(1) \in \text{Pic}^d(C)$$

Lets choose a reference bundle $L_0 = L \in \text{Pic}^d(X)$

Lemma 2.6. The map $\text{Pic}^d(C) \xrightarrow{\otimes L^{-1}} J(C)$ is an isomorphism.

Now knowing our result about the tangent space to the Picard group we can say $\dot{L} = \frac{dL_t}{dt} \in H^1(C, \mathcal{O}_C)$.

2.2 The Eigenvector Mapping as a Deformation

Recall we have a 1-parameter family of maps

$$f_t : C \rightarrow \mathbb{P}V .$$

We want to interpret this as a deformation of the map

$$f_0 : C \rightarrow \mathbb{P}V$$

and characterise it as such, so we need to develop a little theory.

Given a map

$$f : X \rightarrow Y$$

we think of a deformation as a 1-parameter family of maps

$$f_t : X_t \rightarrow Y$$

with $X_0 = X$, $f_0 = f$. This gives a point in the tangent space to the moduli space of such arrangements, which by deformation theory is $H^0(X, \mathcal{N}_{X/Y})$ where \mathcal{N} is the normal bundle given by the SES

$$0 \rightarrow \mathcal{T}_X \rightarrow f^* \mathcal{T}_Y \rightarrow \mathcal{N} \rightarrow 0.$$

This short exact sequence gives rise to the segment of an LES

$$H^0(X, \mathcal{T}_X) \rightarrow H^0(X, f^* \mathcal{T}_Y) \rightarrow H^0(X, \mathcal{N}) \xrightarrow{\tilde{\delta}} H^1(X, \mathcal{T}_X).$$

Again, from deformation theory, we know that $H^1(X, \mathcal{T}_X)$ is the tangent space to the moduli space of X , so if we wanted to look at deformations that kept X fixed, we would need the kernel of $\tilde{\delta}$. Hence the eigenvector mapping gives a cohomology class

$$\dot{f} \in H^0(C, f^* \mathcal{T}_{\mathbb{P}^V}) / H^0(C, \mathcal{T}_C) \subset H^0(C, \mathcal{N}).$$

2.3 Combining with the Euler Sequence

Recall we also have the sequence

$$0 \rightarrow \mathcal{O}_{\mathbb{P}^V} \rightarrow \mathcal{V} \otimes \mathcal{O}_{\mathbb{P}^V}(1) \rightarrow \mathcal{T}_{\mathbb{P}^V} \rightarrow 0$$

which pulls back under f to give

$$0 \rightarrow \mathcal{O}_C \xrightarrow{\nu} \mathcal{V} \otimes L \rightarrow f^* \mathcal{T}_{\mathbb{P}^V} \rightarrow 0,$$

where

$$\begin{aligned} \nu : \mathcal{O}_C &\rightarrow \mathcal{V} \otimes L, \\ \phi &\mapsto \phi \nu, \end{aligned}$$

and ν is the vector defined s.t. for $z \in C$, $f_t(z) = \mathbb{C}\nu(z, t)$.

Definition 2.7. We define $\dot{\nu}$ by

$$\dot{\nu}(z) = \left. \frac{\partial \nu(z, t)}{\partial t} \right|_{t=0} \mod \nu$$

Lemma 2.8. $\dot{\nu}$ is well defined.

Proof. Suppose we had chosen a different representative $\tilde{\nu}$. Writing $\tilde{\nu} = \rho \nu$ we see

$$\dot{\tilde{\nu}} = \rho \dot{\nu} + \dot{\rho} \nu = \rho \dot{\nu} \mod \nu.$$

□

Combined with the normal sheaf sequence this gives the cohomology diagram

$$\begin{array}{ccccccc}
& & H^0(\mathcal{V} \otimes L) & & & & \\
& & \downarrow \tau & & & & \\
H^0(C, \mathcal{T}_C) & \longrightarrow & H^0(C, f^* \mathcal{T}_{\mathbb{P}^V}) & \xrightarrow{j} & H^0(C, \mathcal{N}) & \xrightarrow{\bar{\delta}} & H^1(C, \mathcal{T}_C) \\
& & \downarrow \delta & & & & \\
& & H^1(C, \mathcal{O}_C) & & & &
\end{array}$$

and we can interpret $\dot{\nu}$ as a cohomology class

$$\dot{\nu} \in H^0(C, \mathcal{V} \otimes L / \mathcal{O}_C) = H^0(C, f^* \mathcal{T}_{\mathbb{P}^V})$$

Proposition 2.9. *We have*

- $j(\dot{\nu}) = \dot{f}$,
- $\delta(\dot{\nu}) = \dot{L}$.

Corollary 2.10. $\dot{L} = 0 \Leftrightarrow \exists w \in H^0(C, \mathcal{V} \otimes L), \dot{\nu} = \tau(w)$.

References

- [1] Phillip A. Griffiths. Linearizing flows and a cohomological interpretation of lax equations. *American Journal of Mathematics*, 107(6):pp. 1445–1484, 1985. ISSN 00029327, 10806377. doi: 10.2307/2374412.