# Generalized Additive Models

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#### Overview

- What is a GAM?
- What is smoothing?
- How do GAMs work?
- Fitting GAMs using dsm
- Model checking

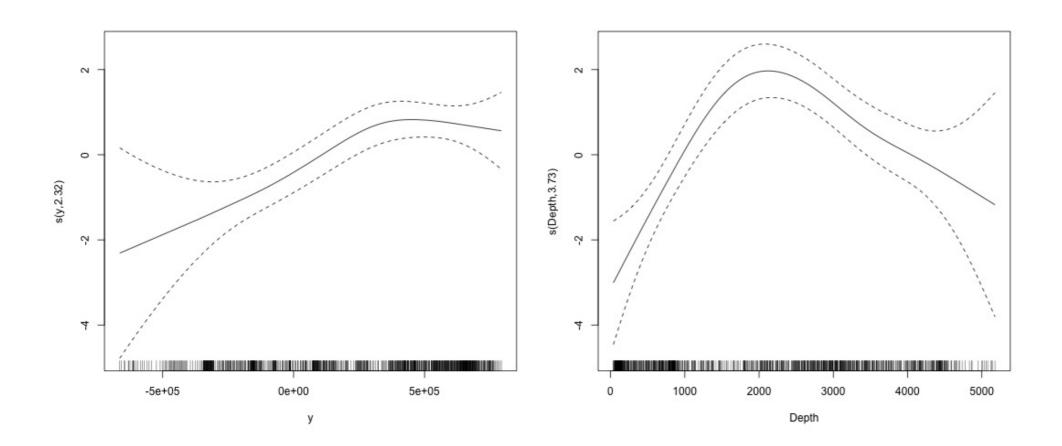
# What is a GAM?

#### Generalized Additive Models

- Generalized: many response distributions
- Additive: terms add together
- Models: well, it's a model...

#### What does a model look like?

- ullet Count  $n_j$  distributed according to some count distribution
- Model as sum of terms



#### Mathematically...

Taking the previous example...

$$n_j = A_j \beta_j \exp \left[\beta_0 + s(y_j) + s(Depth_j)\right] + \epsilon_j$$

where  $\epsilon_j \sim N(0, \sigma)$ ,  $n_j \sim$  count distribution

#### Mathematically...

Taking the previous example...

$$\mathbf{n}_{j} = \mathbf{A}_{j} \hat{\mathbf{p}}_{j} \exp \left[ \beta_{0} + \mathbf{s}(\mathbf{y}_{j}) + \mathbf{s}(\mathrm{Depth}_{j}) \right] + \epsilon_{j}$$

where  $\epsilon_j \sim N(0, \sigma)$ ,  $n_j \sim$  count distribution

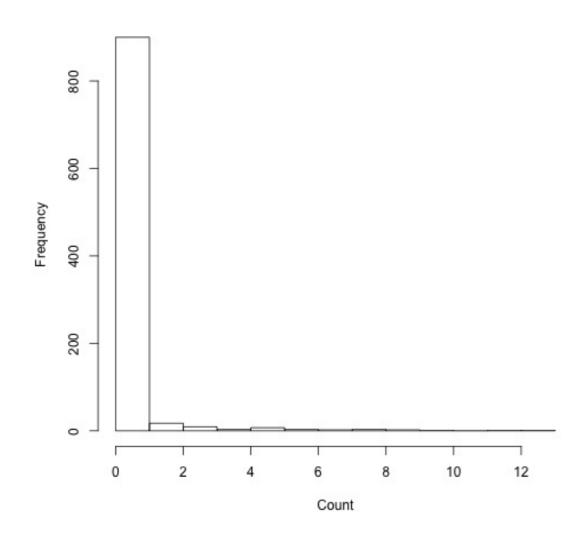
- area of segment offset
- probability of detection in segment
- link function
- model terms

#### Response

$$\mathbf{n}_{j} = A_{j} \hat{\mathbf{p}}_{j} \exp \left[\beta_{0} + s(\mathbf{y}_{j}) + s(\mathrm{Depth}_{j})\right] + \epsilon_{j}$$

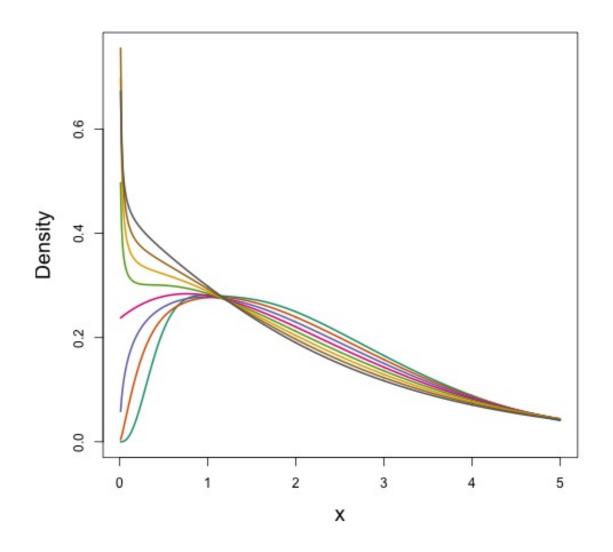
where  $\epsilon_j \sim N(0, \sigma)$ ,  $n_j \sim \text{count distribution}$ 

#### Count distributions



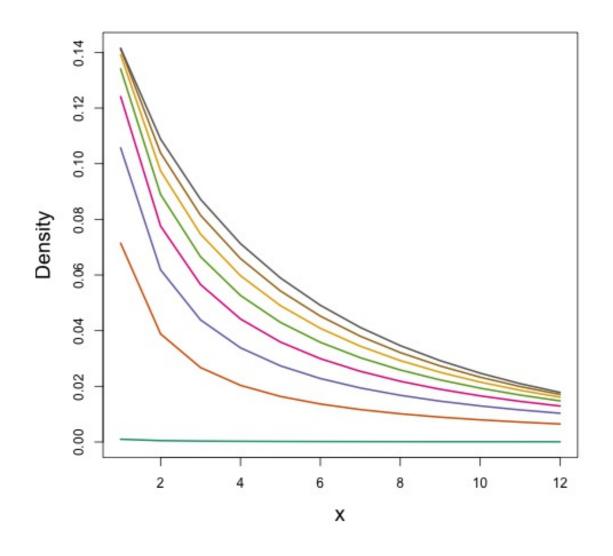
- Response is a count (not not always integer)
- Often, it's mostly zero (that's complicated)
- Want response distribution that deals with that
- Flexible mean-variance relationship

#### Tweedie distribution



- $Var(count) = \varphi(count)^q$
- Common distributions are sub-cases:
  - $\blacksquare q = 1 \Rightarrow Poisson$
  - $\blacksquare q = 2 \Longrightarrow Gamma$
  - $\mathbf{q} = 3 \Rightarrow \text{Normal}$
- We are interested in 1 < q < 2
- (here q = 1.2, 1.3, ..., 1.9)

## Negative binomial



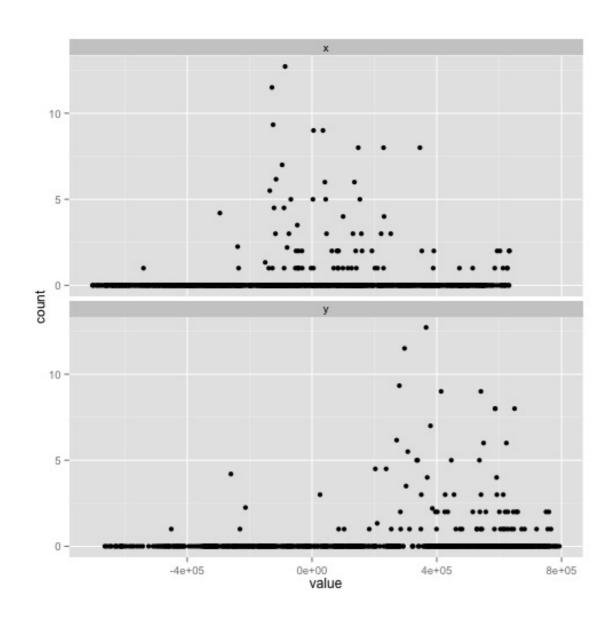
- Var(count) = $(count) + \varkappa(count)^2$
- Estimate χ
- Is quadratic relationship a "strong" assumption?
- Similar to Poisson: Var(count) = (count)

#### Smooth terms

$$n_{j} = A_{j} \beta_{j} \exp \left[\beta_{0} + s(y_{j}) + s(Depth_{j})\right] + \epsilon_{j}$$

where  $\varepsilon_j \sim N(0, \sigma)$ ,  $n_j \sim \text{count distribution}$ 

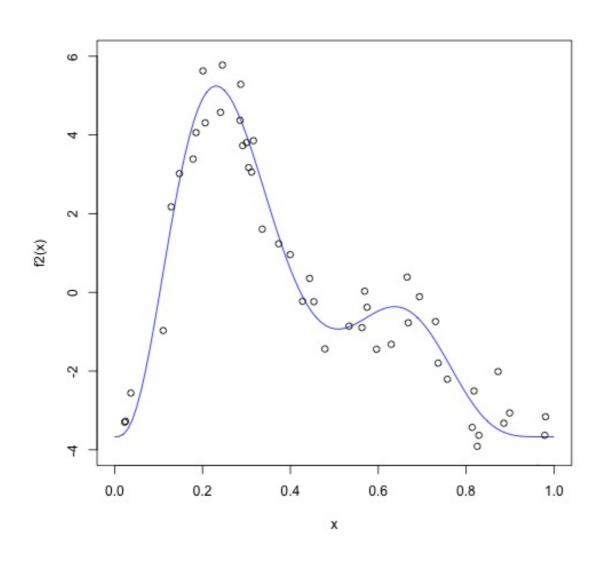
## Okay, but what about these "s" things?



- Think s=smooth
- Want to model the covariates flexibly
- Covariates and response not necessarily linearly related!
- Want some wiggles

# What is smoothing?

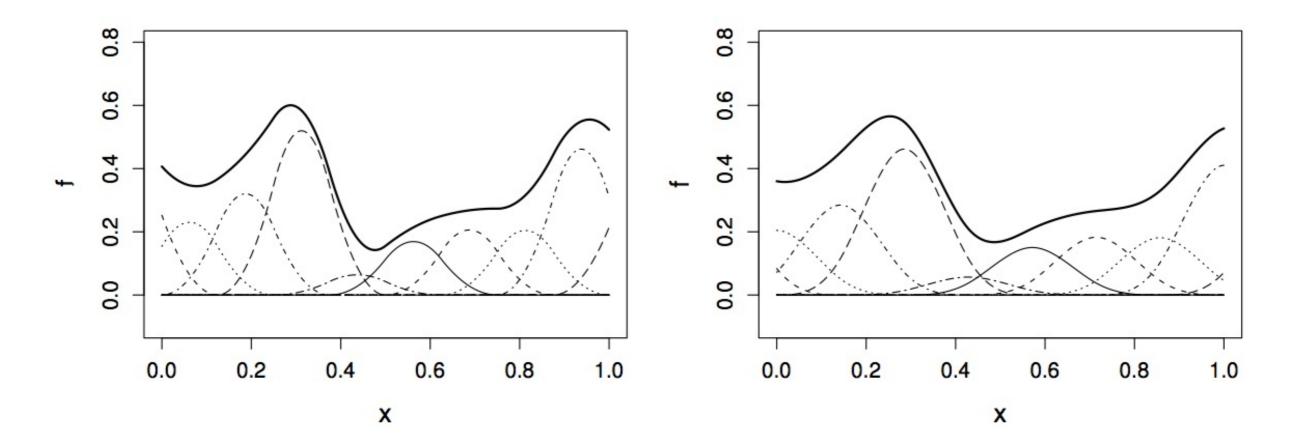
### Straight lines vs. interpolation



- Want a line that is "close" to all the data
- Don't want interpolation
   we know there is "error"
- Balance between interpolation and "fit"

### Splines

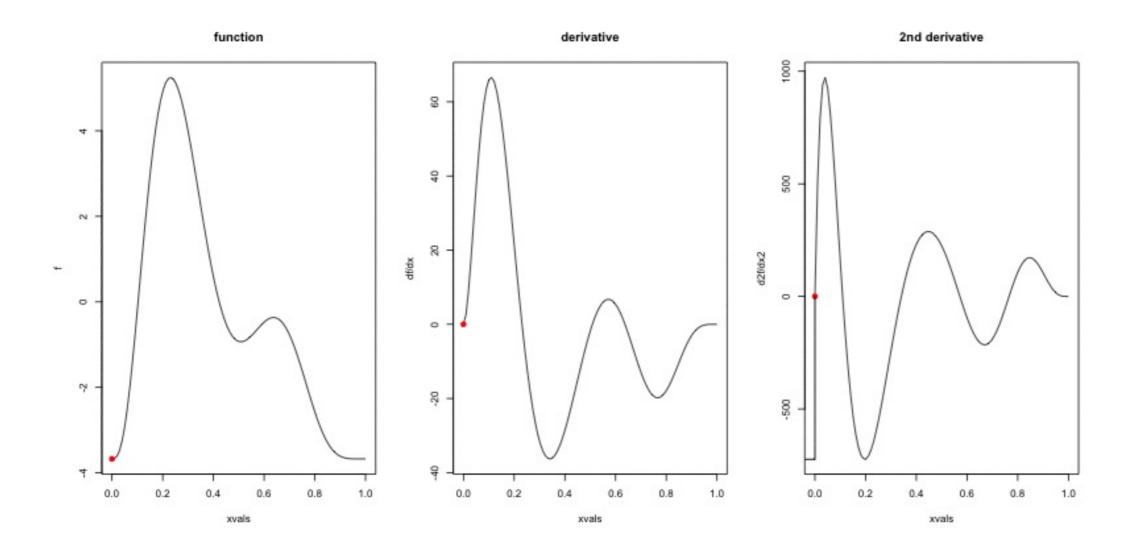
- Functions made of other, simpler functions
- Basis functions  $b_k$ , estimate  $\beta_k$
- $s(x) = \sum_{k=1}^{K} \beta_k b_k(x)$
- Makes the math(s) much easier



#### Measuring wigglyness

- Visually:
  - Lots of wiggles == NOT SMOOTH
  - Straight line == VERY SMOOTH
- How do we do this mathematically?
  - Derivatives!
  - (Calculus was a useful class afterall)

# Wigglyness by derivatives



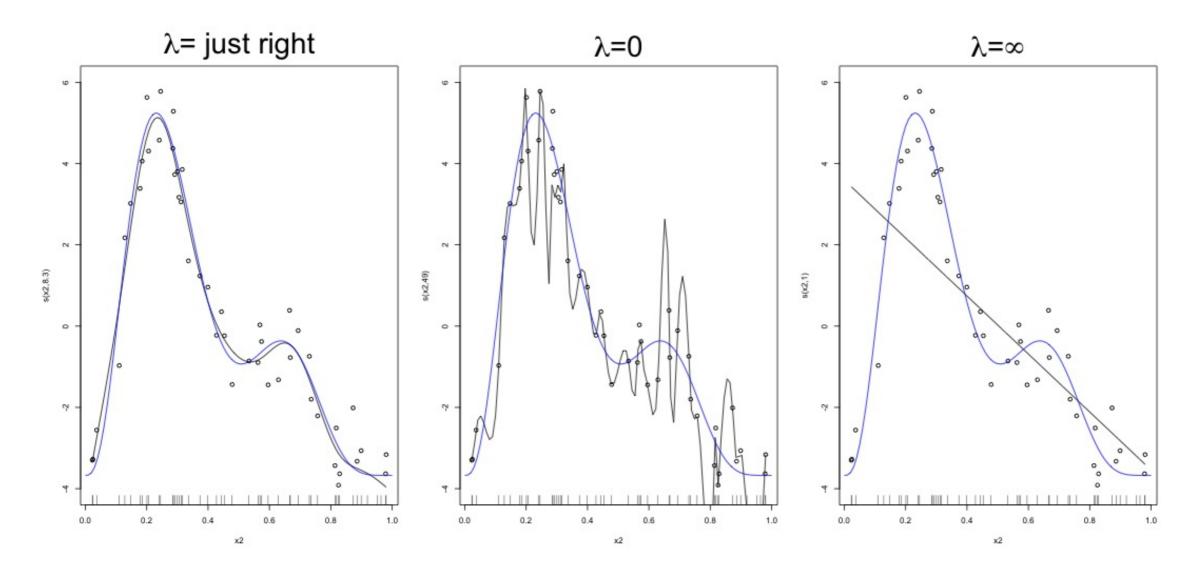
#### Making wigglyness matter

- Integration of derivative (squared) gives wigglyness
- Fit needs to be penalised
- Penalty matrix gives the wigglyness
- Estimate the  $\beta_k$  terms but penalise objective
  - "closeness to data" + penalty

### Penalty matrix

- For each  $b_k$  calculate the penalty
- Penalty is a function of  $\beta$
- S calculated once
- smoothing parameter ( $\lambda$ ) dictates influence

# Smoothing parameter



#### How wiggly are things?

- We can set basis complexity or "size" (k)
  - Maximum wigglyness
- Smooths have effective degrees of freedom (EDF)
- EDF < k
- Set k "large enough"

# Okay, that was a lot of theory...

# Fitting GAMs using dsm

## Translating maths into R

$$n_{j} = A_{j} \hat{p}_{j} \exp \left[\beta_{0} + s(y_{j})\right] + \epsilon_{j}$$

where  $\epsilon_j \sim N(0, \sigma)$ ,  $n_j \sim$  count distribution

- inside the link: formula=count ~ s(y)
- response distribution: family=nb() or family=tw()
- detectability: ddf.obj=df\_hr
- offset, data: segment.data=segs, observation.data=obs

#### Your first DSM

(method="REML" uses REML to select the smoothing parameter)

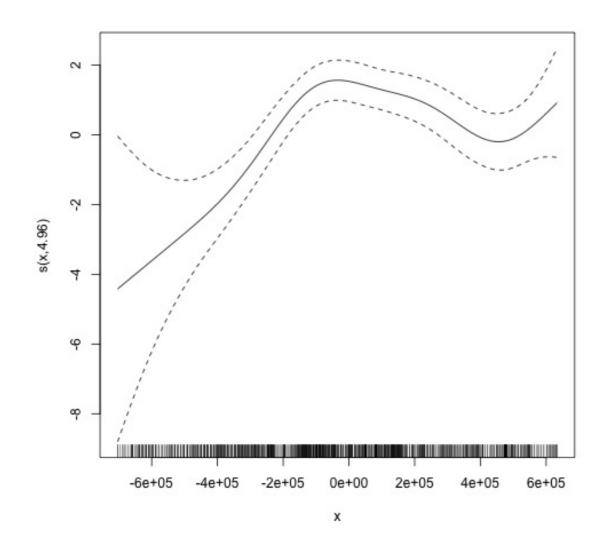
dsm is based on mgcv by Simon Wood

#### What did that do?

summary(dsm\_x\_tw)

```
Family: Tweedie(p=1.326)
Link function: log
Formula:
count \sim s(x) + offset(off.set)
Parametric coefficients:
             Estimate Std. Error t value Pr(>|t|)
(Intercept) -19.7008 0.2277 -86.52 <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
edf Ref.df F p-value
s(x) 4.962 6.047 6.403 1.07e-06 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.0283 Deviance explained = 17.7%
-REML = 409.94 Scale est. = 6.0413 n = 949
```

# Plotting



- plot(dsm\_x\_tw)
- Dashed lines indicate +/-2 standard errors
- Rug plot
- On the link scale
- EDF on y axis

#### Adding a term

Just use +

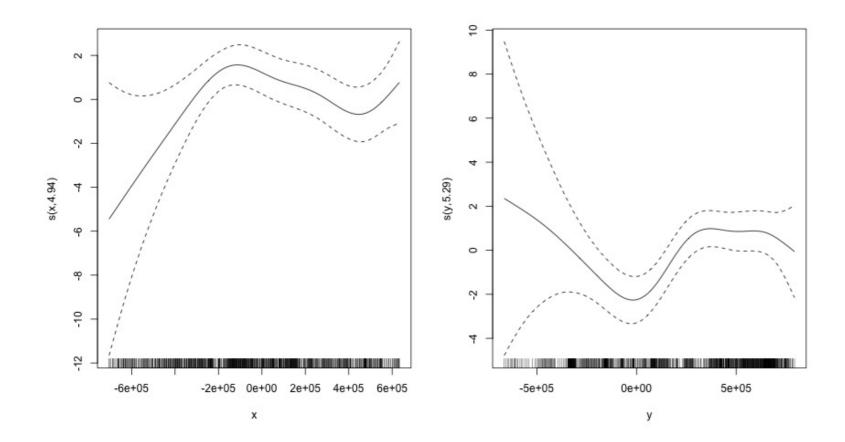
#### Summary

summary(dsm\_xy\_tw)

```
Family: Tweedie(p=1.306)
Link function: log
Formula:
count \sim s(x) + s(y) + offset(off.set)
Parametric coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept) -19.9801  0.2381 -83.93  <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
       edf Ref.df F p-value
s(x) 4.943 6.057 3.224 0.004239 **
s(y) 5.293 6.419 4.034 0.000322 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.0678 Deviance explained = 27.3%
-REML = 399.84 Scale est. = 5.3157 n = 949
```

## Plotting

```
plot(dsm_xy_tw, scale=0, pages=1)
```



- scale=0: each plot on different scale
- pages=1: plot together

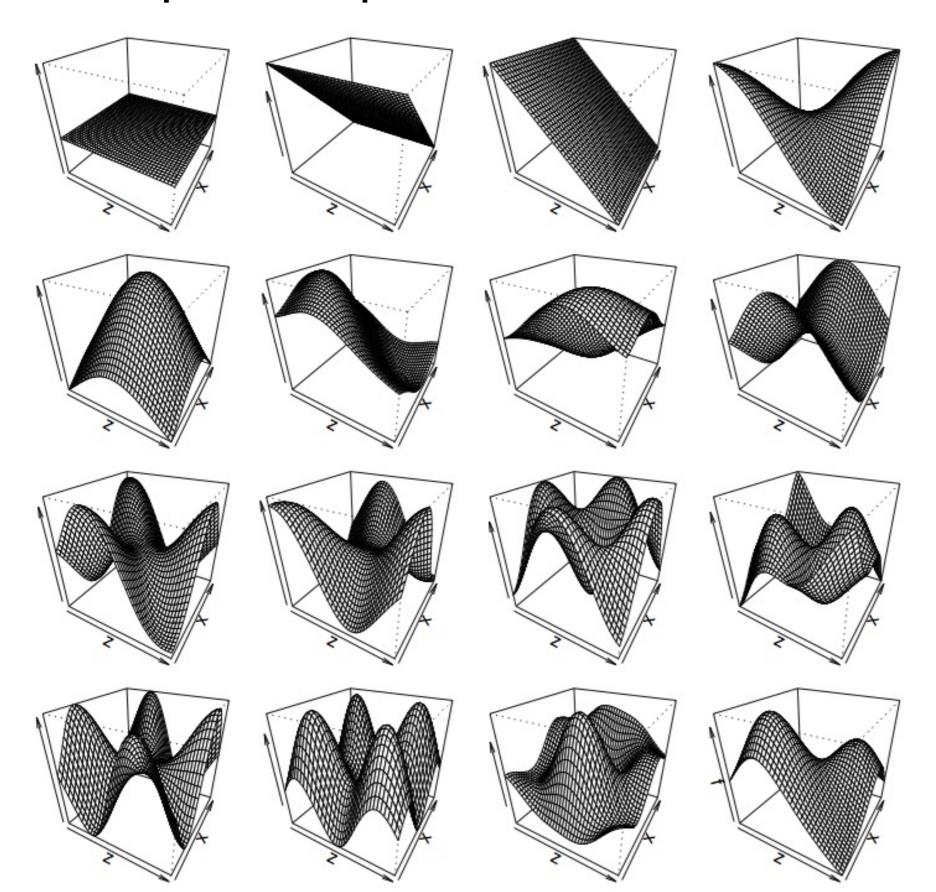
#### Bivariate terms

- Assumed an additive structure
- No interaction
- We can specify s(x,y) (and s(x,y,z,...))

#### Thin plate regression splines

- Default basis
- One basis function per data point
- Reduce # basis functions (eigendecomposition)
- Fitting on reduced problem
- Multidimensional

# Thin plate splines (2-D)



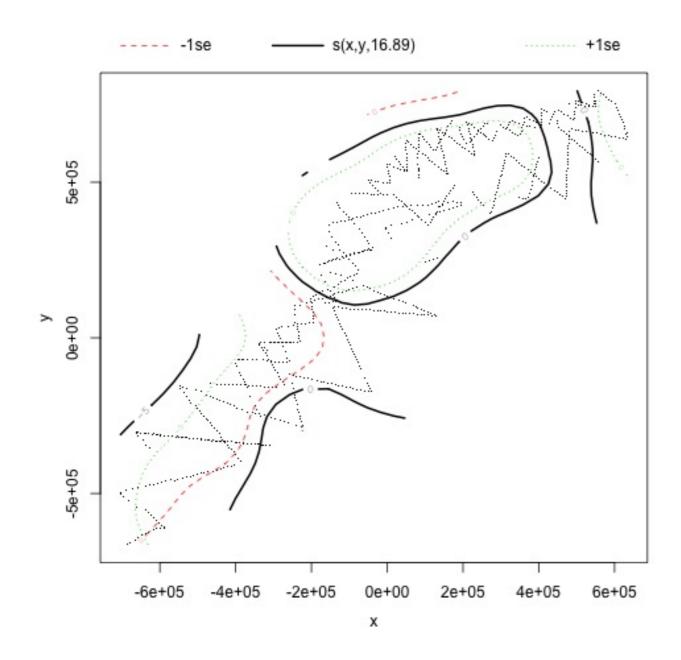
#### Bivariate spatial term

#### Summary

summary(dsm\_xyb\_tw)

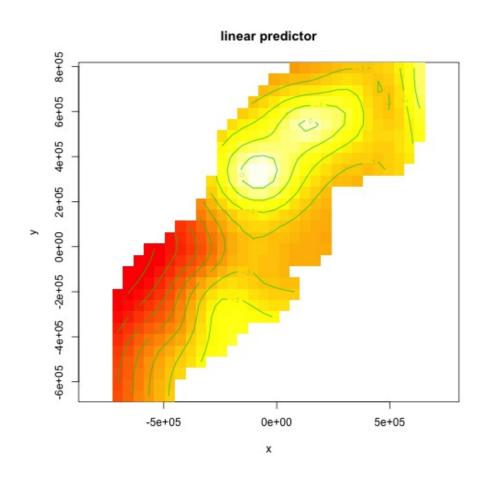
```
Family: Tweedie(p=1.29)
Link function: log
Formula:
count \sim s(x, y) + offset(off.set)
Parametric coefficients:
             Estimate Std. Error t value Pr(>|t|)
(Intercept) -20.1638  0.2477  -81.4  <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
edf Ref.df F p-value
s(x,y) 16.89 21.12 4.333 3.73e-10 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.102 Deviance explained = 34.5%
-REML = 394.86 Scale est. = 4.8248 n = 949
```

## Plotting... erm...



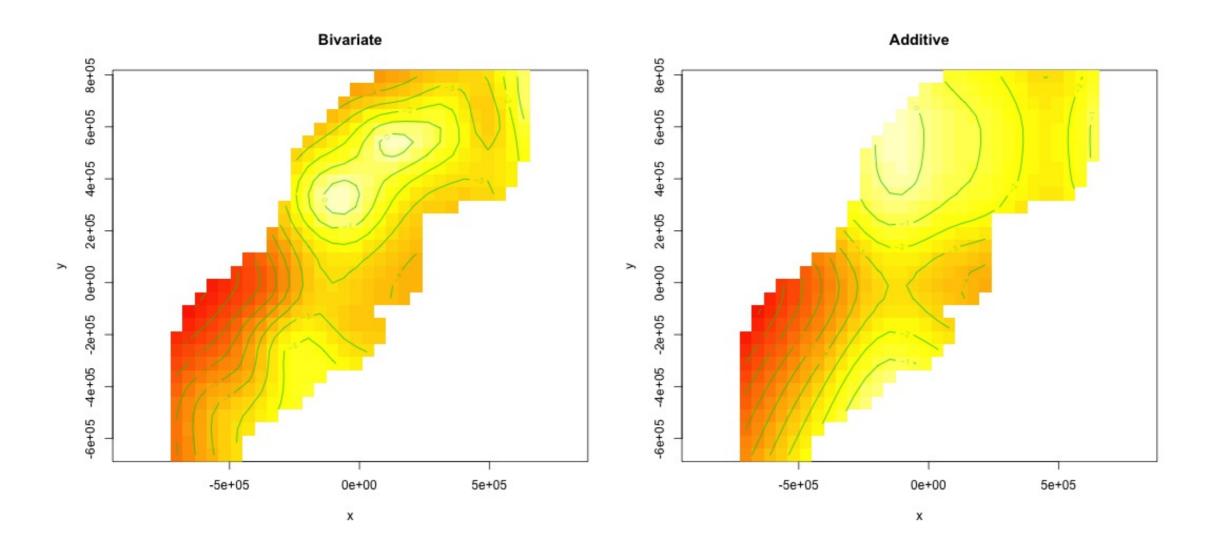
## Let's try something different

```
vis.gam(dsm_xyb_tw, view=c("x","y"), plot.type="contour",
too.far=0.1, asp=1)
```



- Still on link scale
- too. far excludes points far from data

## Comparing bivariate and additive models



# Model checking

"perhaps the most important part of applied statistical modelling"

Simon Wood

## Model checking

- As with detection function, checking is important
- Want to know the model conforms to assumptions
- What assumptions should we check?

#### What to check

- Convergence (not usually an issue)
- Basis size is big enough
- Residuals

## Basis size

## Basis size (k)

- Set k per term
- e.g. s(x, k=10) or s(x, y, k=100)
- Penalty removes "extra" wigglyness
  - up to a point!
- (But computation is slower with bigger k)

## Checking basis size

gam.check(dsm\_x\_tw)

```
Method: REML Optimizer: outer newton full convergence after 7 iterations. Gradient range [-3.08755e-06,4.928062e-07] (score 409.936 & scale 6.041307). Hessian positive definite, eigenvalue range [0.7645492,302.127]. Model rank = 10 / 10

Basis dimension (k) checking results. Low p-value (k-index<1) may
```

indicate that k is too low, especially if edf is close to k'.

k' edf k-index p-value s(x) 9.000 4.962 0.763 0.44

## Increasing basis size

```
Method: REML Optimizer: outer newton full convergence after 7 iterations. Gradient range [-2.301246e-08,3.930757e-09] (score 409.9245 & scale 6.033913). Hessian positive definite, eigenvalue range [0.7678456,302.0336]. Model rank = 20 / 20

Basis dimension (k) checking results. Low p-value (k-index<1) may indicate that k is too low, especially if edf is close to k'.

k' edf k-index p-value s(x) 19.000 5.246 0.763 0.36
```

#### Sometimes basis size isn't the issue...

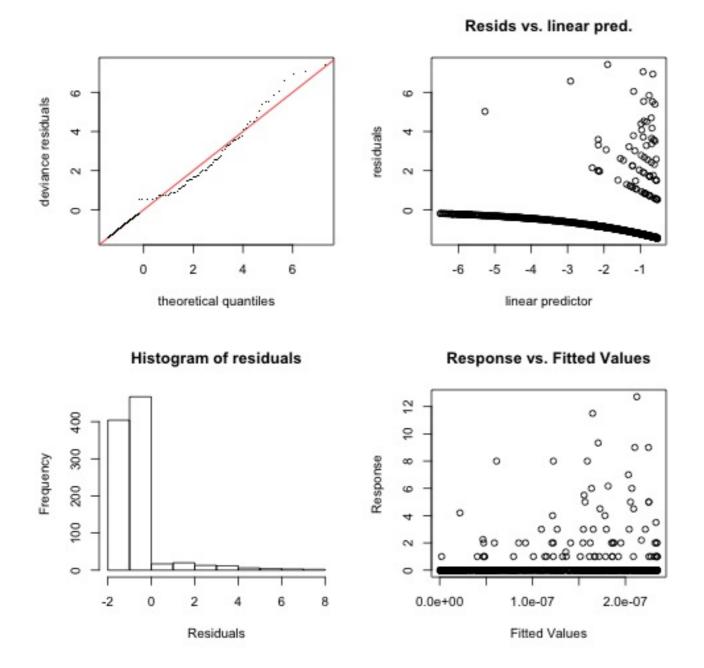
- Generally, double k and see what happens
- Didn't increase the EDF much here
- Other things can cause low "p-value" and "k-index"
- Increasing k can cause problems (nullspace)

# Don't throw away your residuals!

#### What are residuals?

- Generally residuals = observed value fitted value
- BUT hard to see patterns in these "raw" residuals
- Need to standardise deviance residuals
- Residual sum of squares ⇒ linear model
  - deviance  $\Rightarrow$  GAM
- Expect these residuals  $\sim N(0,1)$

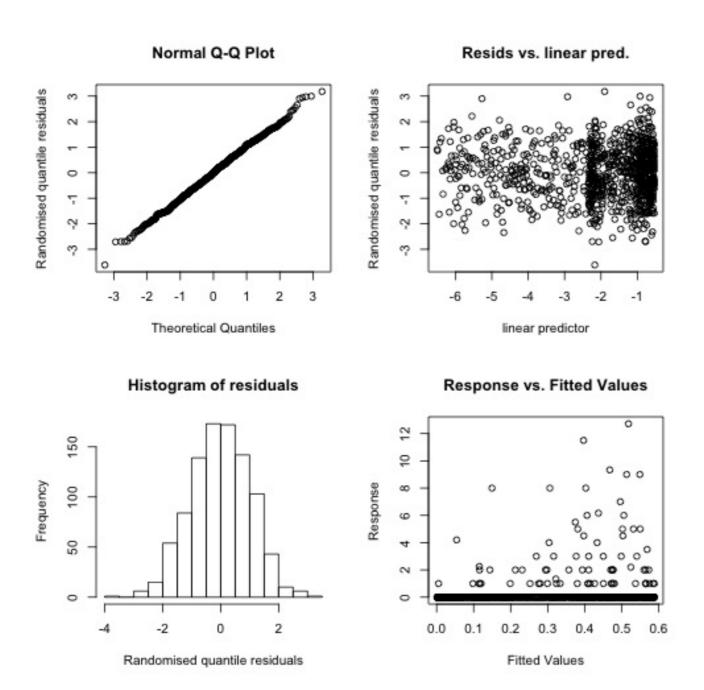
## Residual checking



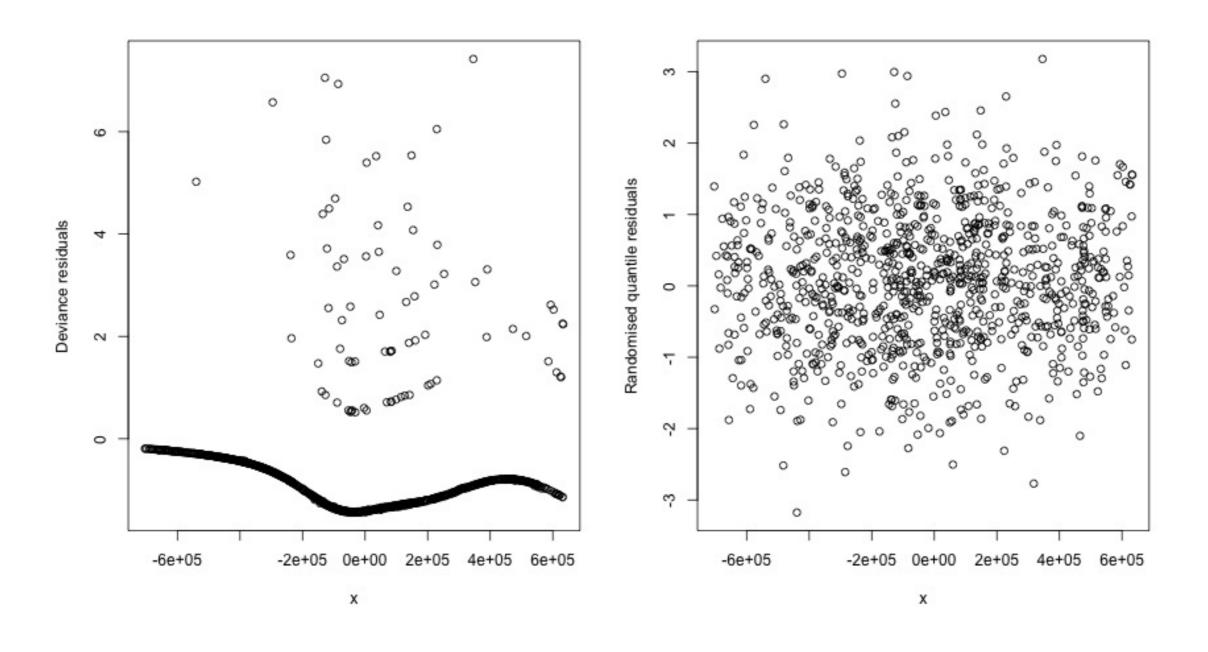
## Shortcomings

- gam. check left side can be helpful
- Right side is victim of artifacts
- Need an alternative
- "Randomised quanitle residuals" (experimental)
  - rqgam.check
  - Exactly normal residuals (left side useless)

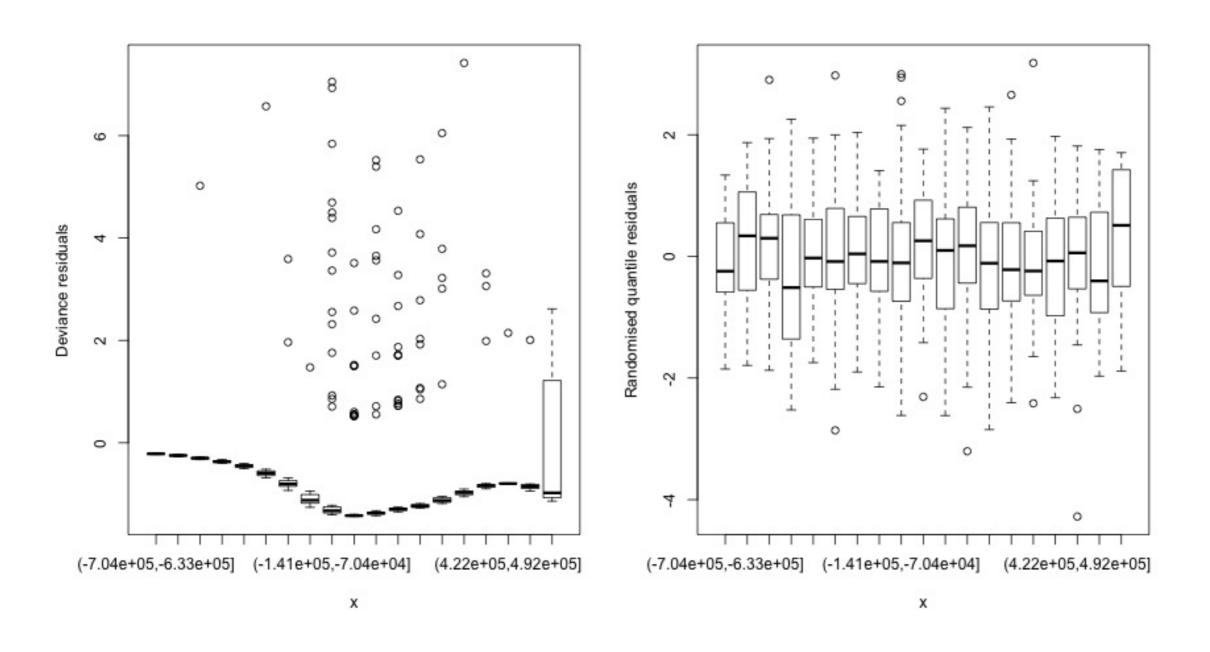
## Randomised quantile residuals



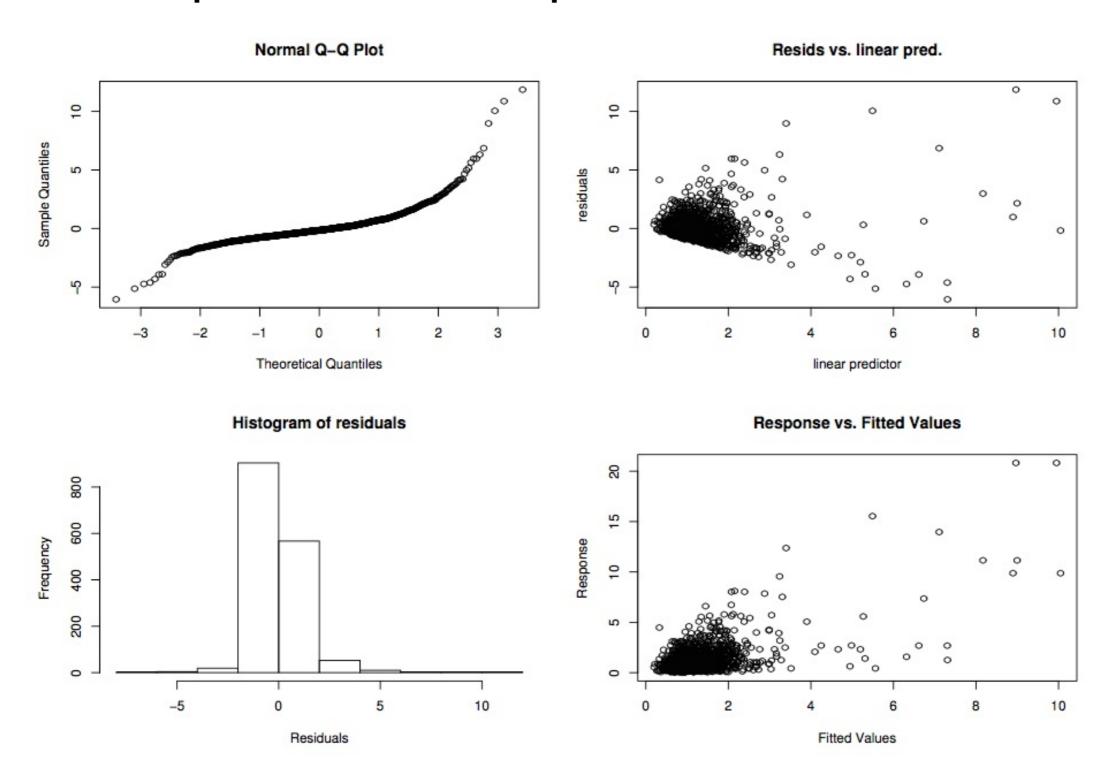
#### Residuals vs. covariates



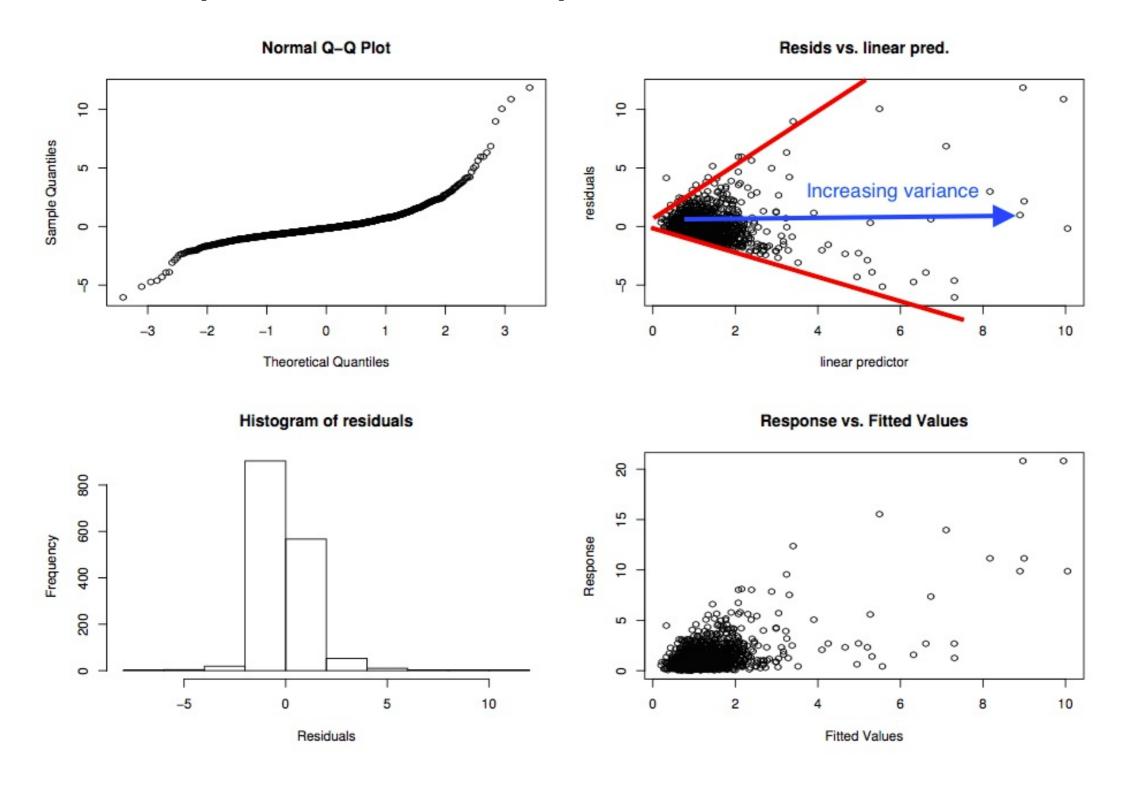
## Residuals vs. covariates (boxplots)



## Example of "bad" plots



## Example of "bad" plots



#### Residual checks

- Looking for patterns (not artifacts)
- This can be tricky
- Need to use a mixture of techniques

# Let's have a go...