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init specification

$$Q = \{boot_hw, senchk, tchk, psichk, ready\}$$

$$q_0 = boot_hw$$

$$\Sigma_1 = \{hw_ok, sen_ok, t_ok, psi_ok\}$$

$$\Sigma_2 = \{\}$$

$$\Lambda = \{$$

$$\rightarrow boot_hw$$

$$boot_hw \xrightarrow{hw_ok} senchk$$

$$senchk \xrightarrow{sen_ok} tchk$$

$$tchk \xrightarrow{psi_ok} psichk$$

$$psichk \xrightarrow{psi_ok} ready$$

$$\}$$

$$V = \{\}$$