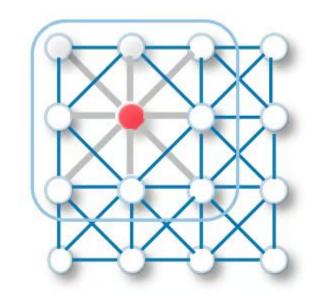
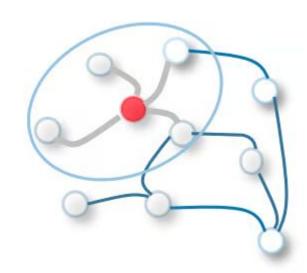
Graph Convolutional Networks (GCN)





Neighborhood Group Chat

Imagine every node (person) in a network participates in a group chat with its neighbors:

- Every node has some information about itself (features).
- In each "round" (layer), a node updates its information by listening to its neighbors and mixing their info with its own. This mixing is called message passing.
- Do it again and again soon, each node's info reflects not just itself, but its wider community's structure.

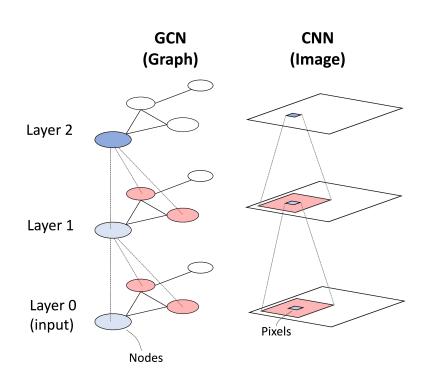
How Does a GCN Work?

Graph Input: Think of your dataset as a web of nodes and edges. Nodes have features (e.g. name, age, molecule type).

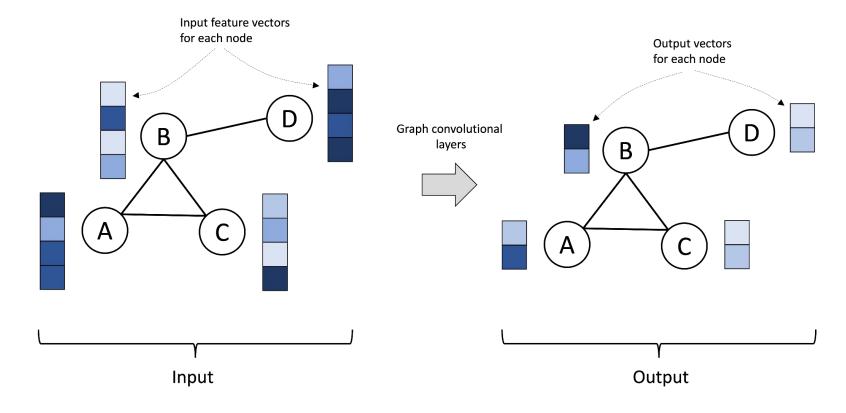
Convolution (Message Passing): Each node gathers info from its neighbors, merges it with its own, then runs it through a learnable function (like mixing ingredients in a recipe).

Multiple Layers = Wider Reach: More layers mean each node gets information from nodes that are farther away (friend-of-a-friend, then friend-of-a-friend, etc.).

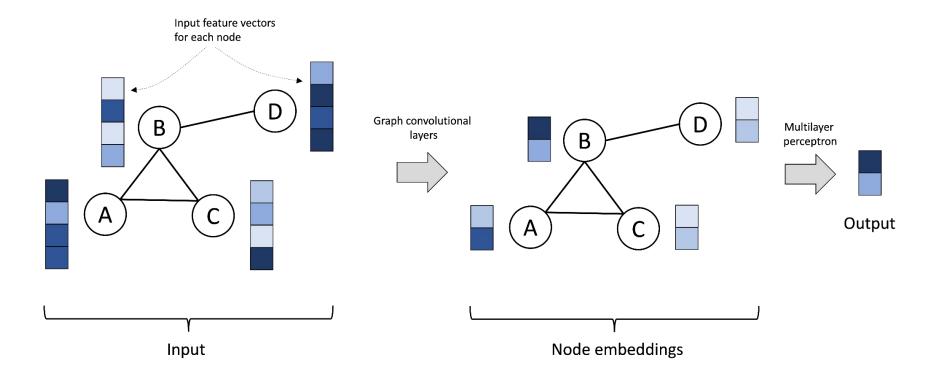
Prediction: After a few layers, nodes' new representations can be used for tasks like classifying nodes, predicting links, understanding the graph.



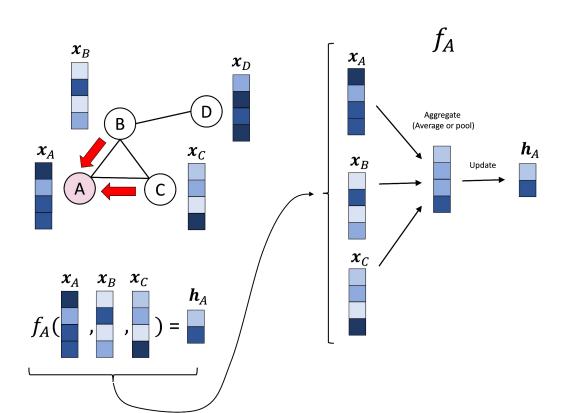
Inputs and outputs of a GCN



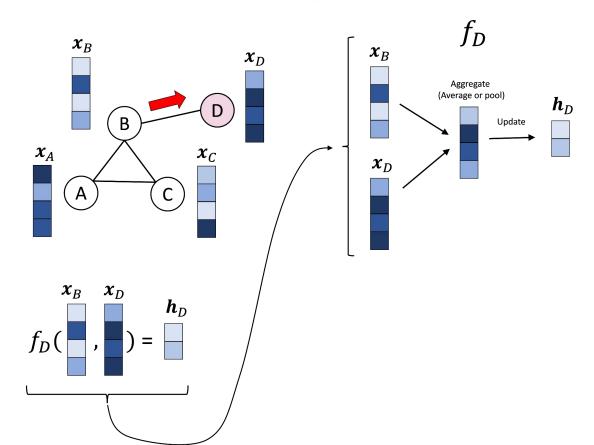
Graph Classification



The Graph Convolutional Layer



The Graph Convolutional Layer



How exactly does a GCN perform the aggregation and update?

$$f(X,A) := \sigma \left(D^{-1/2} (A + I) D^{-1/2} X W \right)$$

where,

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A \in \mathbb{R}^{n \times n} := The adjacency matrix I \in \mathbb{R}^{n \times n} := The identity matrix D \in \mathbb{R}^{n \times n} := The degree matrix of A + I X \in \mathbb{R}^{n \times d} := The input data (i.e., the per-node feature vectors) W \in \mathbb{R}^{d \times w} := The layer's weights \sigma(.) := The activation function (e.g., ReLU)
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What exactly is the equation?

$$f(X, A) \coloneqq \sigma(D^{-1/2}(A + I)D^{-1/2}XW)$$

Add self-loops

Normalize adjacency matrix

Update

Lets Decode

- A + I -> Self Loops
- D is the degree matrix of A+I

$$\mathbf{D} := \begin{bmatrix} d_{1,1} & 0 & 0 & \dots & 0 \\ 0 & d_{2,2} & 0 & \dots & 0 \\ 0 & 0 & d_{3,3} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & d_{n,n} \end{bmatrix}$$

where $d_{i,i}$ is the number of adjacent nodes (i.e., direct neighbors) to node i.

The matrix $D^{-1/2}$ is the matrix formed by taking the reciprocal of the square root of each entry in D. That is,

$$\mathbf{D}^{-1/2} := \begin{bmatrix} \frac{1}{\sqrt{d_{1,1}}} & 0 & 0 & \dots & 0\\ 0 & \frac{1}{\sqrt{d_{2,2}}} & 0 & \dots & 0\\ 0 & 0 & \frac{1}{\sqrt{d_{3,3}}} & \dots & 0\\ \vdots & \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & 0 & \dots & \frac{1}{\sqrt{d_{n,n}}} \end{bmatrix}$$

"Normalizing" the adjacency matrix

$$\vec{A} := \vec{D}^{-1/2} (A + \vec{I}) \vec{D}^{-1/2}$$

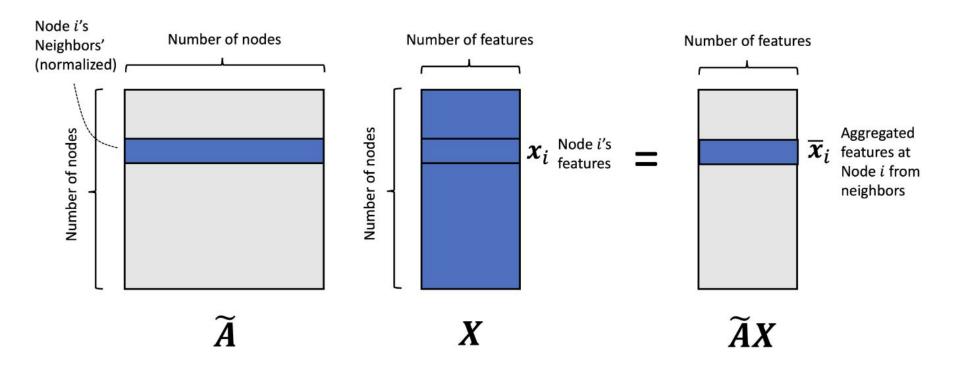
Then,

$$\tilde{A_{i,j}} := \begin{cases} \frac{1}{\sqrt{d_{i,i}d_{j,j}}}, & \text{if there is an edge between node i and j} \\ 0, & \text{otherwise} \end{cases}$$

With this notation, we can simplify the graph convolutional layer function as follows:

$$f(X,A) := \sigma(\tilde{AXW})$$

Lets Combine



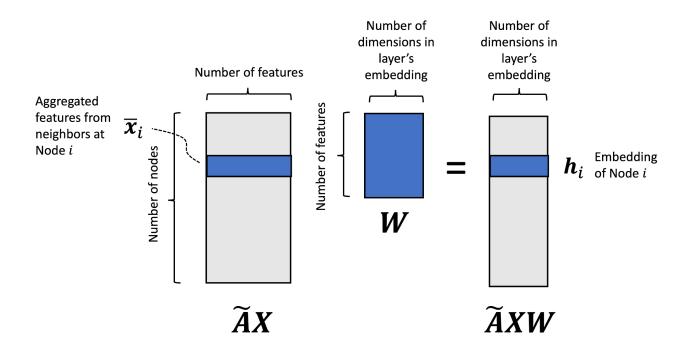
Weighted Sum

$$\bar{x}_{i} = \sum_{j=1}^{n} a_{i,j}^{*} x_{j}$$

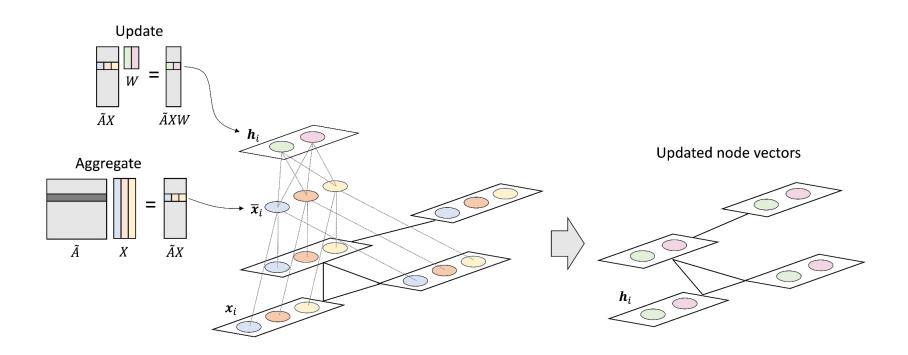
$$= \sum_{j \in \text{Neigh(i)}} a_{i,j}^{*} x_{j}$$

$$= \sum_{j \in \text{Neigh(i)}} \frac{1}{\sqrt{d_{i,i} d_{j,j}}} x_{j}$$

Learned weights/parameters

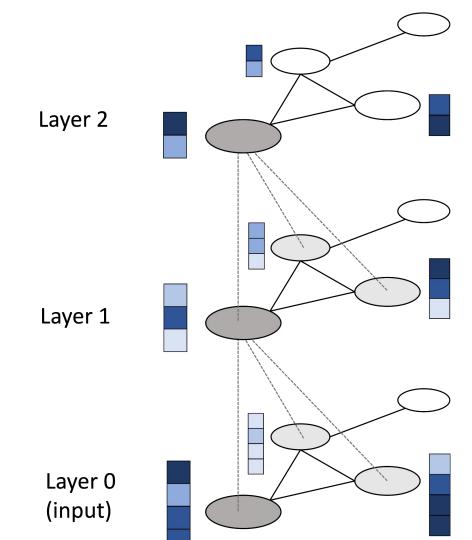


Visualization of the graph convolutional layer



Multi-Layer GCN

$$H_1 := f_{W_1}(X, A)$$
 $H_2 := f_{W_2}(H_1, A)$
 $H_3 := f_{W_3}(H_2, A)$



Why to normalize adjacency matrix?

Issue 1: Neighbor count bias

- Nodes with many neighbors → large aggregated vectors
- Nodes with few neighbors → small aggregated vectors
- Leads to embeddings whose magnitudes depend on node degree, not underlying features

Issue 2: Training instability

- Harder to learn weights that detect meaningful patterns independent of neighbor count
- In deeper layers, magnitudes can explode, causing numerical instability

Key takeaway:

- Need an aggregation method that produces vectors of comparable scale
- Aggregation should be independent of the number of neighbors

Why to normalize adjacency matrix?

- Example setup:
 - Node i has two neighbors:
 - Neighbor 1: only connected to i
 - Neighbor 2: connected to i and many others
- Observation:
 - Neighbor 2's message influences many nodes → stronger impact
 - Neighbor 1 can only reach the graph through Node $i \rightarrow$ weaker influence
- Problem:
 - Nodes' influence is uneven, depending on their degree (number of neighbors)
- Solution:
 - Apply degree-based normalization $\rightarrow \mathbf{D}^{-1/2} \hat{\mathbf{A}} \mathbf{D}^{-1/2}$
 - This balances contributions from high- and low-degree nodes
 - Ensures fair message passing and stable training across the graph

Filter **Comparing GCNs and CNNs** Centered Filter pixel Centered node

What is the primary data structure GCNs operate on?

- A) Images
- B) Text sequences
- C) Graphs
- D) Tabular data

In a GCN, what does the AGGREGATE step refer to?

- A) Combining the node's own features with a neural network
- B) Summing or averaging the features of neighboring nodes
- C) Applying non-linear activation functions
- D) Calculating loss during training

What is the purpose of the degree matrix in GCNs?

- A) To count the number of self-loops in the graph
- B) To normalize how neighbor information is weighted based on the number of neighbors
- C) To store the feature vectors of nodes
- D) To predict node labels

Why is the adjacency matrix often normalized in GCNs?

- A) To simplify matrix multiplication
- B) To handle varying node degrees by balancing contributions from nodes with many vs few neighbors
- C) To reduce the number of layers in the network
- D) To remove edges with low weights

What determines the "receptive field" (how far information flows) for each node in a GCN?

- A) The size of the node features
- B) The number of layers in the GCN
- C) The activation function used
- D) The training data size