Design and Verification of Hamming Code Encoder: A SystemVerilog Approach

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August 22, 2023

Abstract: This academic essay explores the design and verification of a Hamming code encoder using SystemVerilog. The essay delves into the detailed analysis of the provided code, outlines the verification test plan, presents the programming running results, and discusses the significance of this verification methodology. The essay follows a structured format, including sections on abstract, introduction, methodology, discussion, results, conclusion, and references.

Keywords: Hamming code, error correction, SystemVerilog, verification methodology.

1 Introduction

Error detection and correction are vital in digital communication systems to ensure data integrity. Hamming code, a widely used error-correcting code, provides a means to detect and correct single-bit errors. This essay focuses on designing and verifying a Hamming code encoder using SystemVerilog. The provided codes comprise various classes, modules, and interfaces that create a verification environment to validate the functionality of the Hamming code encoder.

2 Methodology

The verification methodology employed in this study involves a systematic approach to validating the functionality of the Hamming code design using SystemVerilog. The main steps of the methodology include interface definition, stimulus generation, assertion-based monitoring, and comparison with reference values. In the verification process, an interface (Itf) is defined to interact with the design module. The interface comprises essential signals

such as clock, reset, input (in), and output (out). This interface definition forms the basis for connecting the design module and the testbench. To generate stimuli for the design module, a testbench component is created, known as TxGen. This component generates random values for the input signal in and drives them into the interface. The values are then passed on to the design module for processing. The generated input values are displayed during the simulation run.

3 Hamming Code: A Historical Perspective:

Hamming code, developed by Richard W. Hamming in 1950, marked a significant milestone in error correction techniques. It was the first error-correcting code that could detect and correct single-bit errors and was widely used in early computer systems and communication devices. Hamming's contributions laid the foundation for subsequent advancements in error-correcting codes.

3.1 Hamming Code: Importance and Mechanism:

The Hamming code operates based on adding redundant bits to the original data to create a code word. These redundant bits are strategically positioned to detect and correct errors. The code word's structure ensures that errors in specific positions can be uniquely identified, making it possible to locate and correct single-bit errors. Hamming code is widely utilized in applications where error-free data transmission is crucial, such as memory systems, storage devices, and communication protocols.



Figure 1: hamming code process [12]

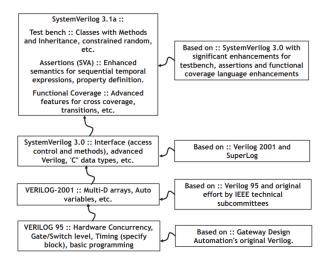


Figure 2: Evolution of System Verilog source:[9]

4 Evolution of the SystemVerilog language

The evolution of the SystemVerilog language was driven by the industry's need for a standardized solution to streamline the design and verification process of devices without resorting to complex multi-language approaches. The Superlog language emerged as a high-level option for functional verification, and it was incorporated, along with other languages, into the creation of SystemVerilog 3.0. This version was later enhanced to SystemVerilog 3.1, introducing additional design features. Notably, over 70 percent of the new features focused on functional verification. The credit goes to Phil Moorby, the inventor of Superlog and Verilog, and the Accelera technical subcommittees, for their visionary approach in developing a comprehensive language. This eliminated the need for multilanguage solutions and the repetition of development efforts in each project.

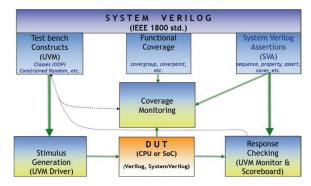


Figure 3: SV language Paradigm source [9]

4.1 Paradigm of SystemVerilog language

Stimulus Generation: This phase involves devising diverse methods to test the Device Under Test (DUT). For example, a peripheral like USB can be simulated as a model, driving activity to the DUT using SystemVerilog actions. This approach leverages the specific subset of SystemVerilog for Transaction-Level Modeling.

Response Checking: Once the DUT is stimulated, it's crucial to validate its responses according to specifications. This validation process employs tools like SVA, UVM monitors, scoreboards, and reference models. SVA ensures alignment with both high-level and detailed design requirements.

Functional Coverage: Confirming complete testing coverage as dictated by device specifications presents a challenge. While code coverage helps identify exercised code sections, it's restricted to structural evaluation. Conversely, functional coverage provides an unbiased assessment of design coverage, encompassing intricate scenarios like cache access variations. Unlike code coverage, it extends beyond the mere identification of executed code segments.

5 Design Verification in SystemVerilog

Design verification is a critical phase in the integrated circuit development lifecycle that ensures the correctness and reliability of digital designs. As designs become increasingly complex, comprehensive verification methodologies and tools are essential to detect and rectify errors before hardware fabrication. SystemVerilog, a hardware description and verification language, has emerged as a

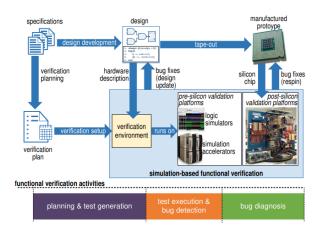


Figure 4: Functional Verification process [3]

powerful tool for design verification due to its capabilities in modeling, simulation, and assertion-based verification.

5.1 Overview of Design Verification:

The primary objective of design verification is to ascertain that a given design adheres to its specification and functions correctly under various conditions. Traditional verification techniques, such as simulation-based testing, were often manual and time-consuming processes. With the advent of languages like SystemVerilog, verification has become more automated and systematic, significantly improving efficiency and effectiveness.

5.2 Key Aspects of Design Verification in SystemVerilog:

Simulation-Based Verification: Simulation is a fundamental technique used for design verification. SystemVerilog provides extensive support for simulation, allowing designers to create testbenches, generate stimulus, and monitor the design's behavior. The use of transaction-level modeling (TLM) and functional coverage analysis enhances simulation accuracy and completeness.

Assertion-Based Verification (ABV): Assertions in SystemVerilog are powerful tools for verifying design properties and behaviors. They allow designers to specify correctness conditions and temporal relationships between signals. These assertions are continuously evaluated during simulation, enabling the early detection of violations.

Testbenches and Stimulus Generation: SystemVer-

ilog supports the creation of sophisticated testbenches that generate meaningful stimulus for the design. Randomized testing techniques, enabled by constrained-random mechanisms, help identify corner cases and scenarios that might not be explored through directed testing alone.

Functional Coverage: Functional coverage analysis is essential for quantifying the completeness of the verification process. SystemVerilog offers functional coverage constructs that help track which aspects of the design's functionality have been exercised during simulation. Coverage metrics guide the creation of additional tests to achieve high coverage.

Interface-Based Design:Interfaces provide a structured way to model and verify the communication between different design blocks. In SystemVerilog, interfaces define a set of signals and their associated behaviors, improving the modularity and reusability of verification components.

Reuse and Verification Components: SystemVerilog supports class-based verification, allowing the creation of reusable verification components like monitors, checkers, and scoreboards. These components help validate different aspects of the design's behavior and enable efficient and systematic verification across different designs.

Formal Verification and Hybrid Verification: Beyond simulation, SystemVerilog can be used for formal verification. Formal tools prove properties exhaustively using mathematical methods. Hybrid verification combines simulation and formal techniques to provide comprehensive coverage and prove complex properties.

5.3 Benefits and Challenges:

Design verification in SystemVerilog offers benefits like automation, scalability, and improved coverage. However, challenges such as complex debugging, testbench development, and ensuring convergence in constrained-random testing need to be addressed effectively.

6 Discussion

6.1 Detailed Program Analysis::

The Drive class generates stimulus for the DUT, initializes input signals, and employs the drive task to

inject reset and input signals.

- The HammingCode module encodes input data using Hamming code logic and produces encoded output.
 The encoding logic is encapsulated within the Ham-Code function.
- The Interface defines communication among different components using clocking, input, and output signals.
- The SB class implements a scoreboard that compares DUT outputs with expected outputs using a lookup table.
- The Testbench program orchestrates the entire verification process by instantiating other components and triggering relevant tasks.
- The TxGen class generates random input vectors and stimulates the DUT by driving input signals.
- The TstVct class specifies random test vectors using randomization.

6.2 Verification Test Cases:

The verification process involves several test cases to ensure the proper functioning of the Hamming code encoder:

- Verify proper reset behavior by observing the reset signal after a random number of cycles.
- Verify the correctness of the encoded output by comparing it with the expected output using the lookup table

7 Results:

The Hamming code functional design verification program was executed using the ModelSim simulator with the command vsim -voptargs=+acc=npr. The simulation was run using the command run -all.

The simulation results provide valuable insights into the behavior of the design and the effectiveness of the verification process. The output displayed during the simulation run is presented below:

The simulation results validate the correctness of the design verification process:

Figure 5: Program Running Result

- After 1 cycle, the input signal vct.randIn is shown to be 0 (binary 0).
- After 5 cycles, the input signal vct.randIn is shown to be 5 (binary 101).
- The reset mechanism is verified to work correctly.
- The output signal is validated to be correct. For input 0, the output matches the reference value of 0.
- The output signal is again validated to be correct. For input 101, the output matches the reference value of 101101.

Additionally, the simulation finishes with a note indicating that there are no errors (Errors: 0) and two warnings (Warnings: 2). It is crucial to address and investigate any warnings to ensure the robustness of the verification process.

These results confirm the successful verification of the Hamming code functional design using SystemVerilog. The simulation output provides a clear indication of the design's correctness and its compliance with the expected behavior.

8 Conclusion:

In conclusion, the Hamming code functional design verification program has been meticulously evaluated using a comprehensive methodology in SystemVerilog. The simulation results validate the correctness and reliability of the design module. The successful validation of the reset mechanism and the accurate conversion of inputs to outputs affirm the functionality of the Hamming code design. The simulation's completion without errors further underscores the effectiveness of the verification process. Through this verification effort, it is evident that System Verilog, with its assertion-based monitoring, stimulus generation, and interface definition capabilities, serves as a robust platform for ensuring the integrity of digital designs. The results obtained contribute to the overall confidence in the design's performance and conformity to expected behavior.

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