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$$\mathbf{T}_z(d_0) \cdot \left\{ \mathbf{R}_z(q_1) \cdot \mathbf{T}_x(d_1) \cdot \mathbf{R}_y(q_2) \cdot \mathbf{T}_x(d_2) \cdot \mathbf{R}_y(q_3) \cdot \mathbf{T}_x(d_3) \cdot \mathbf{T}_z(d_4) \right\} \times \\ \times \left\{ \mathbf{R}_x(q_4) \cdot \mathbf{R}_y(q_5) \cdot \mathbf{R}_x(q_6) \right\} \cdot \mathbf{T}_x(d_6)$$

Link to the GitHub:

<https://github.com/Divinil001/FoR-Homeworks>