

# Project Presentation

## Driver Drowsiness Detection

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# Introduction

Road safety is significantly impacted by driver fatigue, making drowsiness detection a critical area of research and development.

**Project Goal:** Implement a **Driver Drowsiness Detection** system.

**Core Technology:** **Siamese Neural Networks** for similarity learning.

**Mechanism:** Compare real-time facial features against baseline states.

# Introduction: Fatigue Indicators

The system analyzes multiple indicators of fatigue:

**Eye State:** Prolonged closures, rapid blinking. **Head Pose:** Nodding, slumping.

**Mouth Movements:** Yawning.

Integrated analysis aims for timely warnings to enhance driver safety.

# Features

Key functionalities:

**Real-Time Detection:** Continuous monitoring via camera.

**Eye Aspect Ratio (EAR) Analysis:** (*Potential/Planned Feature*) Quantitative measure of eye openness.

**Head Pose Estimation:** (*Details TBD*) Detects nodding/tilting.

**Mouth/Yawning Detection:** Identifies yawn characteristics.

**Siamese Network Core:** Compares image pairs (e.g., current vs. baseline) for state changes.

# Technologies Used

**Python:** 3.8+ **Tensorflow (2.17.0) & Keras (3.6.0):** Core deep learning.

**OpenCV:** Camera access, image manipulation.

**Dlib:** *(Inferred)* Facial landmark detection. **Imutils:** *(Inferred)* Image processing utilities.

**Numpy:** Numerical operations. **Matplotlib:** Data visualization.

**OS module:** Path/directory operations.

# Project Structure

```
.  
├── .editorconfig  
├── .envrc  
├── .gitattributes  
├── .gitignore  
├── deep learning report.docx  
├── flake.lock  
├── flake.nix  
├── LICENSE  
├── pyproject.toml  
├── README.md  
├── siamese_network.ipynb  
├── uv.lock  
└── docs/
```

*Note: dataset directory is missing.*

# Data Processing: Overview

**Siamese Network Requirement:** Paired images (similar/dissimilar).

**Datasets:** Eye state, Yawning detection.

**Structure:** Anchor, Positive (similar), Negative (dissimilar) samples.

# Data Processing: Paths & Setup

Required directory structure (under dataset/):

## Eyes Dataset:

eyes/anchor/ eyes/positive/ eyes/negative/

## Yawn Dataset:

yawn/anchor/ yawn/positive/ yawn/negative/

*Important: dataset directory needs to be populated externally.*



# Data Processing: Preprocessing Pipeline

TensorFlow (`tf.data`) pipeline steps:

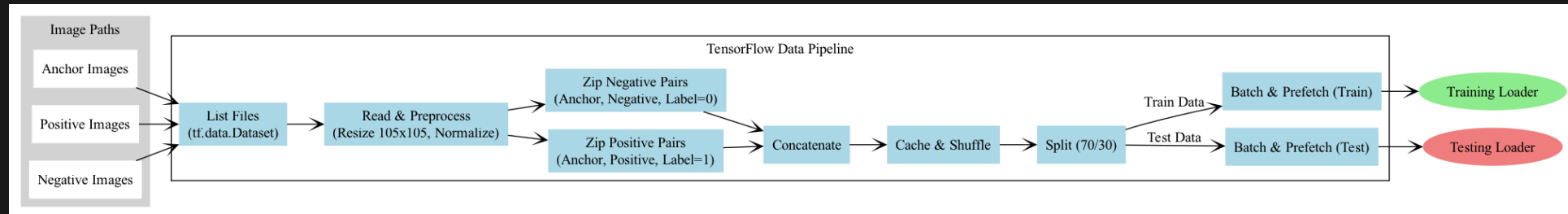
List Files (`.jpg`) Read Files Decode JPEG Resize (105x105) Normalize (0-1)

Pair & Label (Anchor/Positive=1, Anchor/Negative=0) Concatenate Pairs Cache Shuffle

Train/Test Split (70/30) Batch (Size 16) Prefetch

# Data Processing: Pipeline Diagram

This diagram illustrates the data flow:



# Model Architecture: Siamese Network

**Purpose:** Similarity comparison (e.g., same state or different state).

**Core:** Shared CNN acts as an **embedding generator**.

# Model Architecture: Embedding Network (CNN)

**Input:** Image (105x105x3) **Output:** Embedding Vector (4096 dimensions)

**Key:** Shared weights for both images in a pair.

Architecture:

Conv Block 1 (64 filters, 10x10) -> MaxPool Conv Block 2 (128 filters, 7x7) -> MaxPool

Conv Block 3 (128 filters, 4x4) -> MaxPool Conv Block 4 (256 filters, 4x4) Flatten

Dense (4096 units, Sigmoid) -> Embedding

# Model Architecture: Siamese Structure

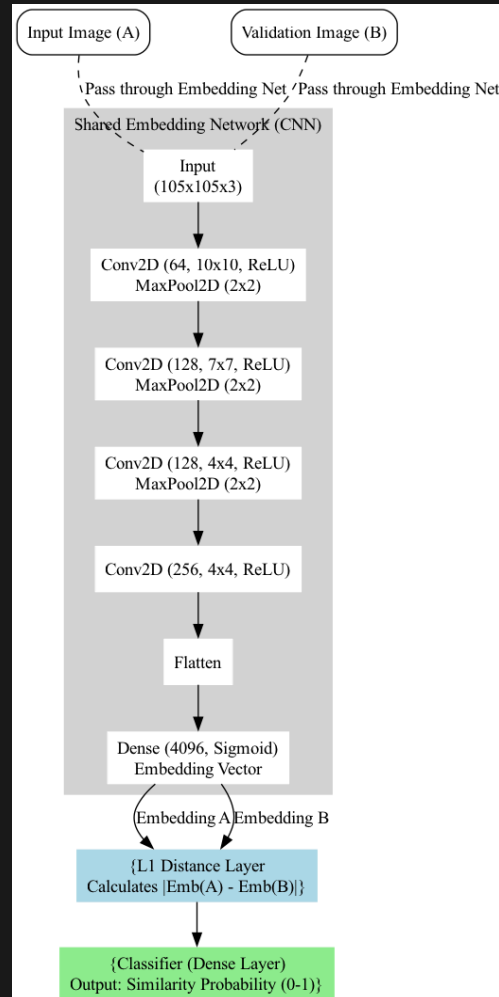
**Inputs:** `input_image (A)`, `validation_image (B)`.

**Embedding:** Both A & B pass through the **shared** Embedding Network  $\rightarrow$   $\text{Emb}(A)$ ,  $\text{Emb}(B)$ .

**Distance:** L1Dist layer calculates  $|\text{Emb}(A) - \text{Emb}(B)|$ .

**Classifier:** Dense layer (1 unit, Sigmoid) predicts similarity (0-1).

# Model Architecture: Diagram



# Training Configuration

**Optimizer:** Adam (learning rate  $1e-4$ ) **Loss Function:** Binary Crossentropy

**Training Loop:** Custom `@tf.function` loop (`train_step`)

**Epochs:** Iterates, uses Progbar for progress.

**Checkpoints:** Saves model state every 4 epochs (`./training_checkpoints`).