

# Project Timeline

Date	Milestone
SAT 6/4	<ul style="list-style-type: none"><li>• Car design</li><li>• Control the stepper via controller (the robot can walk)</li></ul>
SAT 13/4	<ul style="list-style-type: none"><li>• Wireless controlling (parallel interfacing)</li><li>• Finish the car design (servo stand)</li><li>• Integrate all other robot component (servo - ultrasonic)</li></ul>
SAT 20/4	<ul style="list-style-type: none"><li>• The PC interfacing program</li><li>• Initialize the 2 modes of operation for the robot</li></ul>
SAT 27/4	Final testing And Ready to deliver
SAT 4/5	Delivery