

## EE2100: Matrix Theory

## Quiz - 2

## Please Note :

1. If there are any inconsistencies in grading, please use the google form shared with you.

## Group 1

(One among the following set of questions)

1. (3 points) Consider the problem of computing the orthonormal basis of the subspace using the Gram Schmidt Approach. Let  $\mathbb{W}$  denote the subspace spanned by the vectors  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} \in \mathcal{R}^3$  where

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ a \\ 0 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 0 \\ 0 \\ b \end{bmatrix} \text{ and, } \mathbf{v}_3 = \begin{bmatrix} c \\ 0 \\ 0 \end{bmatrix} \quad (1)$$

The **first entry of the third orthonormal basis vector** for the subspace  $\mathbb{W}$  is (Please Note: Apply the Gram Schmidt algorithm by considering vectors in the following order, i.e.,  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ )

2. (3 points) Consider the problem of computing the orthonormal basis of the subspace using the Gram Schmidt Approach. Let  $\mathbb{W}$  denote the subspace spanned by the vectors  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} \in \mathcal{R}^3$  where

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ a \\ 0 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 0 \\ 0 \\ b \end{bmatrix} \text{ and, } \mathbf{v}_3 = \begin{bmatrix} c \\ 0 \\ 0 \end{bmatrix} \quad (4)$$

The **second entry of the third orthonormal basis vector** for the subspace  $\mathbb{W}$  is (Please Note: Apply the Gram Schmidt algorithm by considering vectors in the following order, i.e.,  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ )

## Group 2

(One among the following set of questions)

1. (3 points) Consider the problem of expressing the vector  $\mathbf{v} \in \mathcal{R}^3$  as a linear combination of combination of the

basis vectors  $\left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_1}, \underbrace{\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}}_{\mathbf{b}_2}, \underbrace{\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_3} \right\}$  i.e.,  $\mathbf{v} = \sum_{i=1}^3 \alpha_i \mathbf{b}_i$ . Let  $\mathbf{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ . Compute the coefficient of **linear combination**  $\alpha_3$ .

2. (3 points) Consider the problem of expressing the vector  $\mathbf{v} \in \mathcal{R}^3$  as a linear combination of combination of the

basis vectors  $\left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_1}, \underbrace{\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}}_{\mathbf{b}_2}, \underbrace{\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_3} \right\}$  i.e.,  $\mathbf{v} = \sum_{i=1}^3 \alpha_i \mathbf{b}_i$ . Let  $\mathbf{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ . Compute the coefficient of **linear** combination  $\alpha_1$ .

3. (3 points) Consider the problem of expressing the vector  $\mathbf{v} \in \mathcal{R}^3$  as a linear combination of combination of the

basis vectors  $\left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_1}, \underbrace{\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}}_{\mathbf{b}_2}, \underbrace{\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_3} \right\}$  i.e.,  $\mathbf{v} = \sum_{i=1}^3 \alpha_i \mathbf{b}_i$ . Let  $\mathbf{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ . Compute the coefficient of **linear** combination  $\alpha_2$ .

### Group 3

(One among the following set of questions)

1. (1 point) **For some**  $\mathbf{a}, \mathbf{b} \in \mathcal{R}^n$ , that satisfy  $\mathbf{b} \neq \alpha \mathbf{a}$ ,  $\mathbf{Proj}_{\mathbf{a}} \mathbf{b} = \mathbf{0}$

- A. True  
B. False

2. (1 point) **For all**  $\mathbf{a}, \mathbf{b} \in \mathcal{R}^n$ , that satisfy  $\mathbf{b} \neq \alpha \mathbf{a}$ ,  $\mathbf{Proj}_{\mathbf{a}} \mathbf{b} = \mathbf{0}$

- A. True  
B. False

### Group 4

(One among the following set of questions)

1. (1 point) Consider all possible sets of 3 linearly independent vectors (denoted by say,  $\mathbf{a}, \mathbf{b}, \mathbf{c} \in \mathcal{R}^3$ ) **such that**  $\mathbf{b} \perp \mathbf{a}$ .

Let  $\mathbf{d} = \mathbf{c} - \mathbf{Proj}_{\mathbf{b}} \mathbf{c} - \mathbf{Proj}_{\mathbf{a}} \mathbf{c}$ . Then,  $\mathbf{d} \perp \mathbf{b}$  and  $\mathbf{d} \perp \mathbf{a}$ .

- A. True  
B. False

2. (1 point) Consider all possible sets of 3 linearly independent vectors (denoted by say,  $\mathbf{a}, \mathbf{b}, \mathbf{c} \in \mathcal{R}^3$ ) . Let  $\mathbf{d} = \mathbf{c} - \mathbf{Proj}_{\mathbf{b}} \mathbf{c} - \mathbf{Proj}_{\mathbf{a}} \mathbf{c}$ . Then,  $\mathbf{d} \perp \mathbf{b}$  and  $\mathbf{d} \perp \mathbf{a}$ .

- A. True  
B. False

### Group 5

1. Consider all possible  $\mathbf{a}, \mathbf{b}, \mathbf{c} \in \mathcal{R}^3$  such that  $\mathbf{a} \perp \mathbf{b}$  and  $\mathbf{b} \perp \mathbf{c}$ . Then  $\mathbf{a} \perp \mathbf{c}$ .

A. True

B. False

### Group 6

(One among the following set of questions)

1. (3 points) The coordinate vector of  $\mathbf{x} \in \mathcal{R}^3$  in basis  $\mathcal{B} = \left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_1}, \underbrace{\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}}_{\mathbf{b}_2}, \underbrace{\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_3} \right\}$  is  $\mathbf{x}_{\mathcal{B}}$ . If  $\mathbf{x}_{\mathcal{B}} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ , the

first entry of  $\mathbf{x}$  in the standard basis is

2. (3 points) The coordinate vector of  $\mathbf{x} \in \mathcal{R}^3$  in basis  $\mathcal{B} = \left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_1}, \underbrace{\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}}_{\mathbf{b}_2}, \underbrace{\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_3} \right\}$  is  $\mathbf{x}_{\mathcal{B}}$ . If  $\mathbf{x}_{\mathcal{B}} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ , the

second entry of  $\mathbf{x}$  in the standard basis is

3. (3 points) The coordinate vector of  $\mathbf{x} \in \mathcal{R}^3$  in basis  $\mathcal{B} = \left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_1}, \underbrace{\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}}_{\mathbf{b}_2}, \underbrace{\begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}}_{\mathbf{b}_3} \right\}$  is  $\mathbf{x}_{\mathcal{B}}$ . If  $\mathbf{x}_{\mathcal{B}} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ , the

third entry of  $\mathbf{x}$  in the standard basis is