

## EE2100: Matrix Theory

## Quiz - 3

## Group 1

(One among the following set of questions)

1. (3 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  given by

$$\mathbf{A} = \begin{bmatrix} 1 & a & 0 & 0 \\ 0 & 1 & b & 0 \\ 0 & 0 & 1 & c \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad (1)$$

Let  $\mathbf{B} \in \mathcal{R}^{4 \times 4}$  denote the inverse of a matrix. Compute the entry  $B_{13}$  [Hint: use the idea of inverse linear transformation].

**Solution:** The matrix  $\mathbf{A}$  represents a linear transformation (say  $T$ ) whose output (when applied to  $\mathbf{x}$ ) is given by

$$T(\mathbf{x}) = \mathbf{A}\mathbf{x} = \underbrace{\begin{bmatrix} x_1 + ax_2 \\ x_2 + bx_3 \\ x_3 + cx_4 \\ x_4 \end{bmatrix}}_{\text{say } \mathbf{y}} \quad (2)$$

The inverse of  $\mathbf{A}$  is a matrix corresponding to the inverse transformation of  $T$  i.e., the matrix corresponding to the transformation  $T_1(\mathbf{y}) = \mathbf{x}$ . The relation between the entries of  $\mathbf{y}$  and  $\mathbf{x}$  can be shown to be

$$\begin{aligned} x_4 &= y_4 \\ x_3 &= y_3 - c y_4 \\ x_2 &= y_2 - b y_3 + bc y_4 \\ x_1 &= y_1 - a y_2 + ab y_3 - abc y_4 \end{aligned} \quad (3)$$

The inverse of  $\mathbf{A}$  is thus

$$\mathbf{B} = \begin{bmatrix} 1 & -a & ab & -abc \\ 0 & 1 & -b & -bc \\ 0 & 0 & 1 & -c \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad (4)$$

The final answer to the question is  $ab$  and the exact value depends on the values of  $a$  and  $b$  given in the question.

2. (3 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  given by

$$\mathbf{A} = \begin{bmatrix} 1 & a & 0 & 0 \\ 0 & 1 & b & 0 \\ 0 & 0 & 1 & c \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad (5)$$

Let  $\mathbf{B} \in \mathcal{R}^{4 \times 4}$  denote the inverse of a matrix. Compute the entry  $B_{14}$  [Hint: use the idea of inverse linear transformation].

**Solution:** The matrix  $\mathbf{A}$  represents a linear transformation (say  $T$ ) whose output (when applied to  $\mathbf{x}$ ) is given by

$$T(\mathbf{x}) = \mathbf{A}\mathbf{x} = \underbrace{\begin{bmatrix} x_1 + ax_2 \\ x_2 + bx_3 \\ x_3 + cx_4 \\ x_4 \end{bmatrix}}_{\text{say } \mathbf{y}} \quad (6)$$

The inverse of  $\mathbf{A}$  is a matrix corresponding to the inverse transformation of  $T$  i.e., the matrix corresponding to the transformation  $T_1(\mathbf{y}) = \mathbf{x}$ . The relation between the entries of  $\mathbf{y}$  and  $\mathbf{x}$  can be shown to be

$$\begin{aligned} x_4 &= y_4 \\ x_3 &= y_3 - c y_4 \\ x_2 &= y_2 - b y_3 + bc y_4 \\ x_1 &= y_1 - a y_2 + ab y_3 - abc y_4 \end{aligned} \quad (7)$$

The inverse of  $\mathbf{A}$  is thus

$$\mathbf{B} = \begin{bmatrix} 1 & -a & ab & -abc \\ 0 & 1 & -b & -bc \\ 0 & 0 & 1 & -c \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad (8)$$

The final answer to the question is  $-abc$  and the exact value depends on the values of  $a$ ,  $b$  and  $c$  given in the question.

### Group 2

(One among the following set of questions)

- (1 point) If  $\forall \mathbf{v} \in \mathcal{R}^n$   $\mathbf{A}\mathbf{v} = \mathbf{B}\mathbf{v}$  (where  $\mathbf{A} \in \mathcal{R}^{m \times n}$ ,  $\mathbf{B} \in \mathcal{R}^{m \times n}$ ), then  $\mathbf{A} = \mathbf{B}$ .  
 A. True  
 B. False
- (1 point) If  $\exists \mathbf{v} \in \mathcal{R}^n$  such that  $\mathbf{A}\mathbf{v} = \mathbf{B}\mathbf{v}$  (where  $\mathbf{A} \in \mathcal{R}^{m \times n}$ ,  $\mathbf{B} \in \mathcal{R}^{m \times n}$ ), then  $\mathbf{A} = \mathbf{B}$ .  
 A. True  
 B. False

**Group 3** (All the questions)

- (2 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  whose column vectors are given by

$$\begin{aligned}\mathbf{a}_1 &= \mathbf{e}_1 \\ \mathbf{a}_2 &= \mathbf{e}_3 + x\mathbf{e}_2 \\ \mathbf{a}_3 &= x\mathbf{e}_3 - \mathbf{e}_2 \\ \mathbf{a}_4 &= \mathbf{e}_4\end{aligned}\tag{9}$$

The rank of the matrix is

**Solution:** The column vectors of  $\mathbf{A}$  are orthogonal (and hence, linearly independent). Thus,  $\mathbf{Rank}(\mathbf{A}) = 4$ .

- (2 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  whose column vectors are given by

$$\begin{aligned}\mathbf{a}_1 &= \mathbf{e}_1 \\ \mathbf{a}_2 &= \mathbf{e}_3 + x\mathbf{e}_2 \\ \mathbf{a}_3 &= x\mathbf{e}_3 - \mathbf{e}_2 \\ \mathbf{a}_4 &= \mathbf{e}_4\end{aligned}\tag{10}$$

The nullity of the matrix is

**Solution:** The columns of  $\mathbf{A}$  are orthogonal (linearly independent). Thus, (by Rank-Nullity Theorem)  $\mathbf{Nullity}(\mathbf{A}) = 0$ .

3. (4 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  whose column vectors are given by

$$\begin{aligned}\mathbf{a}_1 &= \mathbf{e}_1 \\ \mathbf{a}_2 &= \mathbf{e}_3 + x\mathbf{e}_2 \\ \mathbf{a}_3 &= x\mathbf{e}_3 - \mathbf{e}_2 \\ \mathbf{a}_4 &= \mathbf{e}_4\end{aligned}\tag{11}$$

The second entry of the vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$  (where  $\mathbf{b} = [p, q, r, s]^t$ ) is

**Solution:** The second entry of  $\mathbf{x}$  is the coefficient of linear combination  $\alpha_2$  such that

$$\mathbf{b} = \sum_{i=1}^4 \alpha_i \mathbf{a}_i\tag{12}$$

Since the column vectors of  $\mathbf{A}$  are orthogonal,

$$\alpha_2 = \frac{\mathbf{b} \cdot \mathbf{a}_2}{\|\mathbf{a}_2\|^2} = \frac{qx + r}{x^2 + 1}\tag{13}$$

The exact answer depends on the values of  $x$ ,  $q$  and  $r$ .

4. (4 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  whose column vectors are given by

$$\begin{aligned}\mathbf{a}_1 &= \mathbf{e}_1 \\ \mathbf{a}_2 &= \mathbf{e}_3 + x\mathbf{e}_2 \\ \mathbf{a}_3 &= x\mathbf{e}_3 - \mathbf{e}_2 \\ \mathbf{a}_4 &= \mathbf{e}_4\end{aligned}\tag{14}$$

Let  $\mathbf{C} = \mathbf{A}^T \mathbf{A}$ . The entry  $C_{2,2}$  is

**Solution:** The column vectors of  $\mathbf{A}$  are orthogonal. Thus

$$\mathbf{C} = \mathbf{A}^T \mathbf{A} = \begin{bmatrix} \mathbf{a}_1 \cdot \mathbf{a}_1 & \mathbf{a}_1 \cdot \mathbf{a}_2 & \mathbf{a}_1 \cdot \mathbf{a}_3 & \mathbf{a}_1 \cdot \mathbf{a}_4 \\ \mathbf{a}_2 \cdot \mathbf{a}_1 & \mathbf{a}_2 \cdot \mathbf{a}_2 & \mathbf{a}_2 \cdot \mathbf{a}_3 & \mathbf{a}_2 \cdot \mathbf{a}_4 \\ \mathbf{a}_3 \cdot \mathbf{a}_1 & \mathbf{a}_3 \cdot \mathbf{a}_2 & \mathbf{a}_3 \cdot \mathbf{a}_3 & \mathbf{a}_3 \cdot \mathbf{a}_4 \\ \mathbf{a}_4 \cdot \mathbf{a}_1 & \mathbf{a}_4 \cdot \mathbf{a}_2 & \mathbf{a}_4 \cdot \mathbf{a}_3 & \mathbf{a}_4 \cdot \mathbf{a}_4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & x^2 + 1 & 0 & 0 \\ 0 & 0 & x^2 + 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}\tag{15}$$

Thus,  $C_{2,2} = x^2 + 1$ . The exact answer depends on the value of  $x$  given in the question.

5. (4 points) Consider a matrix  $\mathbf{A} \in \mathcal{R}^{4 \times 4}$  whose column vectors are given by

$$\begin{aligned}\mathbf{a}_1 &= \mathbf{e}_1 \\ \mathbf{a}_2 &= \mathbf{e}_3 + x\mathbf{e}_2 \\ \mathbf{a}_3 &= x\mathbf{e}_3 - \mathbf{e}_2 \\ \mathbf{a}_4 &= \mathbf{e}_4\end{aligned}\tag{16}$$

Let  $\mathbf{C}$  be the inverse of  $\mathbf{A}$ . The entry  $C_{2,2}$  is

**Solution:**  $C_{2,2} = \frac{x}{x^2+1}$  (See Tutorial 6) The exact answer depends on the value of  $x$  given in the question.