

Digital Signals in the Time Domain

- Most signals encountered in practice are analog signals
- However, increasingly these analog signals are being converted into digital form and are being processed using digital systems
- The processed digital signals are then converted back into analog form

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Digital Signals in the Time Domain

- A digital signal $\{x[n]\}$ is represented in the time-domain as a sequence of numbers called samples where each sample $x[n]$ is a function of the integer-valued variable n with $-\infty < n < +\infty$
- The integer-valued variable n is often called time

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Digital Signals in the Time Domain

$$\{x[n]\} = \{\dots, -1, 2, 5, 1, -3, 7, \dots\}$$

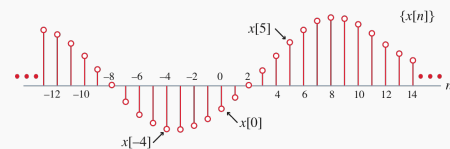
- The arrow indicates the location of the sample at $n = 0$
- If there is no ambiguity, a digital signal may be shown without the braces
- We shall often refer to a digital signal as a sequence in this course

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Digital Signals in the Time Domain

- A digital signal also sometimes represented in a graphical form as indicated below



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Digital Signals in the Time Domain

- As mentioned earlier, an analog signal $x_a(t)$ is converted into a digital signal $\{x[n]\}$ by sampling the former periodically at uniform time intervals

$$x[n] = x_a(t)|_{t=nT} = x_a(nT), -\infty < n < +\infty$$

- The spacing T between two consecutive samples of $\{x[n]\}$ is called the sampling period

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Digital Signals in the Time Domain

- The reciprocal of the sampling period is the sampling frequency:

$$F_T = \frac{1}{T}$$

- Sampling frequency is in Hz if the sampling period is in seconds
- For a real digital signal $\{x[n]\}$, all samples are real-valued and for a complex digital signal $\{x[n]\}$, one or more samples are complex-valued

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Digital Signals in the Time Domain

- A complex digital signal $\{x[n]\}$ is written in the form

$$\{x[n]\} = \underbrace{\{x_{re}[n]\}}_{\text{Real part}} + j \underbrace{\{x_{im}[n]\}}_{\text{Imaginary part}}$$

- $\{x_{re}[n]\}$ and $\{x_{im}[n]\}$ are real sequences
- Complex conjugate of $\{x[n]\}$ is

$$\{x^*[n]\} = \{x_{re}[n]\} - j\{x_{im}[n]\}$$

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Finite- and Infinite-Length Signals

- An infinite-length digital signal is called a **right-sided signal** if the amplitude of its samples is equal to zero for all values of time index n less than a finite integer N_1
- A right-sided signal is called a **causal signal** if $N_1 = 0$

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Finite- and Infinite-Length Signals

- An infinite-length digital signal is called a **left-sided signal** if the amplitude of its samples is equal to zero for all values of time index n greater than a finite integer N_2
- A left-sided signal is called an **anti-causal signal** if $N_2 = 0$

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Finite- and Infinite-Length Digital Signals

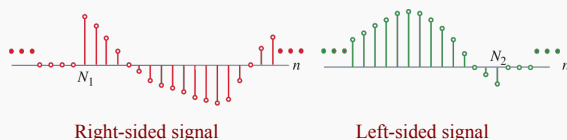
- The amplitudes of the samples of a **finite-length signal**, also called a **finite-duration or finite-extent signal**, are equal to zero for all values of time index n less than a finite value N_1 and greater than a finite value N_2 with $N_1 < N_2$
- Length or duration** N of the finite-length signal is $N = N_2 - N_1 + 1$

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Finite- and Infinite-Length Signals

- Examples of right-sided and left-sided digital signals are shown below



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Finite- and Infinite-Length Signals

- A **two-sided digital signal** is defined for both positive and negative values of time index n
- An example of a finite-length two-sided digital signal is shown below
 $\{y[n]\} = \{-3, 0.4, -2, 3.1, 5\} \quad -1 \leq n \leq 3$
- Length of the above signal is $3 - (-1) + 1 = 5$

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Finite- and Infinite-Length Signals

- For a right-sided finite-length digital signal defined for $n \geq N_1$ and without the arrow shown, the first sample of the signal is at time index $n = N_1$
- For a causal signal, the first sample is at time index $n = 0$

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Periodic and Aperiodic Signals

- An infinite-length digital signal $\tilde{x}[n]$ is called a **periodic signal**, if for a positive integer N_o , the signal satisfies the condition

$$\tilde{x}[n] = \tilde{x}[n + N_o]$$

for all values of n

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Periodic and Aperiodic Signals

- **Note:** If the periodicity condition holds for a value of N_o , then

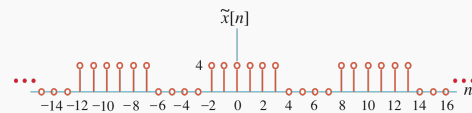
$$\tilde{x}[n + N_o] = \tilde{x}[n + kN_o]$$
 where k is a positive integer
- The smallest value of N_o satisfying the periodicity condition is called the **fundamental period** of $\tilde{x}[n]$, which is the length of one full cycle of the signal

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Periodic and Aperiodic Signals

- The square wave signal shown below is an example of a periodic digital signal



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Periodic and Aperiodic Signals

- The fundamental frequency, also called **cyclic frequency** f_o , of the periodic signal $\tilde{x}[n]$ with a fundamental period N_o is defined by

$$f_o = \frac{1}{N_o}$$

which is the number of full cycles in one period

Unit of the fundamental frequency is given by Hz, if the time index n is in seconds

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Periodic and Aperiodic Signals

- A periodic digital signal is often characterized by its **angular frequency** which is given by

$$\Omega_o = 2\pi f_o = \frac{2\pi}{N_o}$$

- The angular frequency Ω_o is in radians per second if N_o is in seconds
- **Note:** One full cycle of the periodic signal contains 2π radians

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Periodic and Aperiodic Signals

- A digital signal is called an **aperiodic signal** if it is not periodic, that is, there is no value of the constant N_o satisfying the periodicity condition
- A periodic digital signal is denoted with a tilde “ \sim ” on top

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Bounded Signals

- A digital signal $x[n]$ is said to be a **bounded digital signal** if it satisfies the condition

$$|x[n]| \leq B_x < \infty, -\infty < n < +\infty$$

where B_x is a finite real positive number

- The stability of certain types of digital systems is usually defined in terms of the boundedness of signals

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Bounded Signals

- We shall assume in this course that the amplitude of a sample of a digital signal can take any value between $-\infty$ and $+\infty$
- In practice, the signals at the input, output, and anywhere internal to the system are restricted to specific ranges, known as **dynamic ranges**

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Bounded Signals

- It is thus necessary to ensure that these signals remain as bounded signals lying in the specified dynamic ranges which can be achieved by scaling the signals appropriately
- If the sample amplitude of any of these signals at any time index n exceeds their corresponding dynamic ranges, the pertinent signal is clipped resulting in severe distortion in the processed output signal

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Energy of a Digital Signal

- The **total energy** of the digital signal $x[n]$ is defined by

$$\mathcal{E}_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

- The **energy** of a digital signal over a finite duration $-K \leq n \leq K$ is defined by

$$\mathcal{E}_{x,K} = \sum_{n=-K}^K |x[n]|^2$$

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Power and RMS Value of a Digital Signal

- The **average power** of the digital signal $x[n]$ is defined by

$$\mathcal{P}_x = \lim_{K \rightarrow \infty} \frac{1}{2K+1} \sum_{n=-K}^K |x[n]|^2$$

- The **root-mean square (rms)** value of a digital signal $x[n]$ is given by the square-root of its average power \mathcal{P}_x , that is

$$x_{rms} = \sqrt{\mathcal{P}_x}$$

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Energy and Power of Digital Signals

- The relation between the average power and the energy of a digital signal is

$$\mathcal{P}_x = \lim_{K \rightarrow \infty} \frac{1}{2K+1} \mathcal{E}_x$$

- It follows from the above relation that the average power \mathcal{P}_x of a finite energy digital signal is 0

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Energy and Power of Digital Signals

- The average power of a periodic digital signal $\tilde{x}[n]$ with a fundamental period N_o is given by

$$\mathcal{P}_{\tilde{x}} = \frac{1}{N_o} \sum_{n=0}^{N_o-1} |\tilde{x}[n]|^2$$

- A digital signal has infinite energy if the summation $\sum_{n=-\infty}^{\infty} |x[n]|^2$ does not converge to a finite number

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Unit Sample Sequence

- The unit sample sequence $\delta[n]$, also known as the unit impulse sequence, is a discrete-time function whose sample is equal to zero for all values of n except $n = 0$ where it has unity value, that is,

$$\delta[n] = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

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Unit Sample Sequence

- It follows from the definition,

$$\delta[n - N_o] = \begin{cases} 1, & n = N_o \\ 0, & n \neq N_o \end{cases}$$

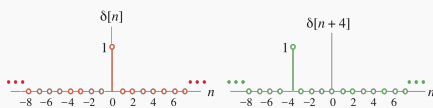
- Thus, $\delta[n - N_o]$ is an unit impulse sequence located at $n = N_o$

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Unit Sample Sequence

- Figures below show the sequence $\delta[n]$ and the sequence $\delta[n + 4]$



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Unit Step Sequence

- The unit step sequence denoted by $\mu[n]$ is a causal signal defined by

$$\mu[n] = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases}$$

- It follows from above

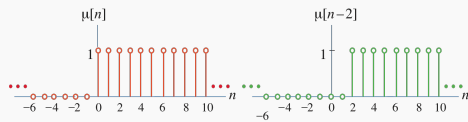
$$\mu[n - N_o] = \begin{cases} 1, & n \geq N_o \\ 0, & n < N_o \end{cases}$$

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Unit Step Sequence

- Figures below show the sequence $\mu[n]$ and the sequence $\mu[n-2]$



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Sinusoidal Sequence

- The most general form of the sinusoidal sequence is given by

$$\tilde{x}[n] = A_o \sin(2\pi f_o n + \phi_o), \quad -\infty < n < \infty$$

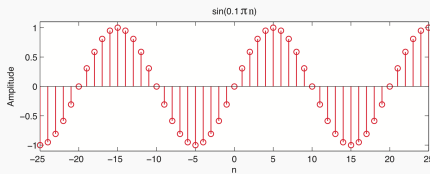
where A_o , f_o , and ϕ_o are real numbers and are called, respectively, the **peak amplitude**, **normalized frequency**, and **phase**

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Sinusoidal Sequence

- Figure below show the plot of $\tilde{x}[n] = \sin(0.1\pi n)$



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Sinusoidal Sequence

- An alternate form of the basic sinusoidal digital signal is

$$\tilde{x}[n] = A_o \sin(\omega_o n + \phi_o), \quad -\infty < n < \infty$$

where $\omega_o = 2\pi f_o$ is known as the **normalized angular frequency**

- Unit of ω_o and ϕ_o is **radians** if n is **dimensionless**

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Sinusoidal Sequence

- Units of ω_o and ϕ_o is radians per sample, and the unit of f_o is cycles per sample if n is samples
- Units of ω_o and ϕ_o is radians/second, and the unit of f_o is cycles per second or Hz, if the spacing T between two consecutive samples is in seconds

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Sinusoidal Sequence

Periodicity Property

- Unlike the sinusoidal analog signal, the sinusoidal sequence may or may not be a periodic digital signal
- The sinusoidal sequence will be a periodic signal of period N_o if and only if $2\pi f_o N_o$ is an integer multiple of 2π , that is,

$$2\pi f_o N_o = 2\pi r$$

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Sinusoidal Sequence

or equivalently, if

$$\frac{2\pi}{\omega_o} = \frac{N_o}{r}$$

where N_o and r are positive integers

- The smallest value of N_o satisfying the above condition is called the **fundamental period**

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Sinusoidal Sequence

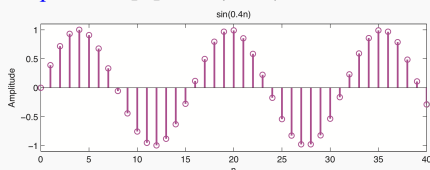
- If $2\pi/\omega_o$ is a noninteger rational number, then the period N_o of the sinusoidal sequence will be an integer multiple of $2\pi/\omega_o$
- If $2\pi/\omega_o$ is not a rational number, then the sinusoidal sequence is **aperiodic** but with a sinusoidal envelope

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Sinusoidal Sequence

- Example** – Consider the sinusoidal sequence $x[n] = \sin(0.4n)$ shown below



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Sinusoidal Sequence

- Here the condition $\omega_o N_o = 2\pi r$ leads to $N_o = 2\pi r / 0.4 = 5\pi r$
- It can be seen that there is no integer value of r to make N_o an integer
- Hence $x[n] = \sin(0.4n)$ is an **aperiodic** sinusoidal sequence

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Sinusoidal Sequence

Example – We determine the fundamental period of $\tilde{x}[n] = \sin(0.1\pi n)$

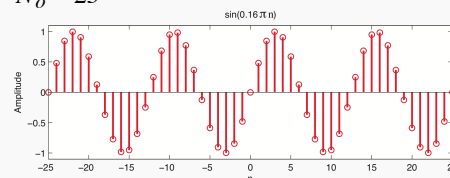
- Here $\omega_o = 0.1\pi$
- Substituting this value in $\omega_o N_o = 2\pi r$ we get $0.1\pi N_o = 2\pi r$ or $N_o = \frac{2r}{0.1}$ which is satisfied for $N_o = 20$ and $r = 1$ which can be verified from the plot

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Sinusoidal Sequence

- Example** – It can be shown that the fundamental period of $\tilde{x}[n] = \sin(0.16\pi n)$ is $N_o = 25$



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Sinusoidal Sequence

Restriction on the Frequency Range

- Recall that the angular frequency Ω_o of a sinusoidal analog signal can have any value in the range $0 \leq \Omega_o < +\infty$
- Unlike the analog case, the normalized angular frequency ω_o of a sinusoidal digital signal can have a value in a restricted range

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Sinusoidal Sequence

- Consider two sinusoidal sequences given by $\tilde{x}_a[n] = \sin(\omega_a n)$ and $\tilde{x}_b[n] = \sin(\omega_b n)$ with $0 \leq \omega_a < 2\pi$ and $\omega_b = \omega_a + 2\pi k$ where k is any positive integer
- We note

$$\tilde{x}_b[n] = \sin(\omega_b n) = \sin(\omega_a n + 2\pi k n)$$

$$= \sin(\omega_a n) \cos(2\pi k n) + \cos(\omega_a n) \sin(2\pi k n)$$
- Now $\cos(2\pi k n) = 1$ and $\sin(2\pi k n) = 0$

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Sinusoidal Sequence

- Hence $\tilde{x}_b[n] = \sin(\omega_a n) = \tilde{x}_a[n]$
- As a result, the two sinusoidal sequences $\tilde{x}_a[n]$ and $\tilde{x}_b[n]$ are indistinguishable
- Another restriction on the frequency range is due to an inherent property of sine and cosine functions which limits the angular frequency to the range $0 \leq \omega < \pi$

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Sinusoidal Sequence

- Consider $\tilde{x}_a[n] = \sin(\omega_a n)$ and $\tilde{x}_b[n] = \sin(\omega_b n)$ with $0 \leq \omega_a < \pi$ and $\omega_b = 2\pi - \omega_a$
- We note

$$\tilde{x}_b[n] = \sin(\omega_b n) = \sin((2\pi - \omega_a)n)$$

$$= \sin(2\pi n) \cos(\omega_a n) - \cos(2\pi n) \sin(\omega_a n)$$
- Now $\cos(2\pi k n) = 1$ and $\sin(2\pi k n) = 0$
- Hence $\tilde{x}_b[n] = -\sin(\omega_a n) = -\tilde{x}_a[n]$

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Sinusoidal Sequence

- Thus, a sinusoidal sequence with a normalized angular frequency ω_b in the range $\pi \leq \omega_b < 2\pi$ becomes a sinusoidal sequence with a normalized angular frequency $\omega_a = \pi - \omega_b$
- The angular frequency π is referred to as the folding frequency

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Sinusoidal Sequence

- Hence, the allowable range of the normalized angular frequency of a sinusoidal digital signal is $0 \leq \omega < \pi$
- Frequencies with small values near dc ($\omega = 0$) are called low frequencies
- Frequencies with high values near π are called the high frequencies

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Sinusoidal Sequence

Example – The sequence $\sin(0.2\pi n)$ is a low-frequency digital signal, whereas, the sequence $\sin(0.8\pi n)$ is a high-frequency digital signal

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Complex Exponential Sequence

- Most general form

$$x[n] = A\alpha^n, \quad -\infty < n < +\infty$$

where A and α are complex numbers

- Expressing the parameter A in polar form and α in rectangular form:

$$A = |A|e^{j\phi}, \quad \alpha = \sigma_o + j\omega_o$$

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Complex Exponential Sequence

we arrive at

$$\begin{aligned} x[n] &= A\alpha^n = |A|e^{j\phi}e^{(\sigma_o + j\omega_o)n} = |A|e^{j\phi}e^{\sigma_o n}e^{j\omega_o n} \\ &= |A|e^{j\phi}e^{\sigma_o n}(\cos \omega_o n + j \sin \omega_o n) \\ &= |A|e^{\sigma_o n} \underbrace{\cos(\omega_o n + \phi)}_{\text{Re}\{x[n]\}} + j|A|e^{\sigma_o n} \underbrace{\sin(\omega_o n + \phi)}_{\text{Im}\{x[n]\}} \end{aligned}$$

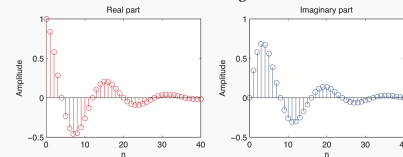
- The real and imaginary parts of the complex sequence $x[n]$ are real sequences with amplitudes $|A|e^{\sigma_o n}$

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Complex Exponential Sequence

- For $n > 0$, the sample amplitudes of the complex exponential sequence are growing for $\sigma_o > 0$, decaying for $\sigma_o < 0$, and remains constant for $\sigma_o = 0$



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Complex Exponential Sequence

- A complex exponential sequence $Ae^{j\omega_o n}$ is a periodic sequence with a period N_o , if the condition $\omega_o N_o = 2\pi r$ is satisfied

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Real Exponential Sequence

- The sequence $x[n] = A\alpha^n, -\infty < n < +\infty$, is a real exponential sequence when A and α are real numbers

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