

Problem Set 7

Problems marked **(T)** are for discussions in Tutorial sessions.

1. Does there exist a linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ satisfying $T(1, 1, 1) = (1, 2, 3, 0)$, $T(1, 2, -1) = (2, 1, 3, 0)$ and $T(1, 5, -7) = (0, 0, 0, 1)$? Give reasons for your answer.

Solution: Verify that the set $\{(1, 1, 1), (1, 2, -1), (1, 5, -7)\}$ is linearly dependent. So, their images must be linearly dependent. Which is NOT true in the given example.

2. Can we ever find a linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ which is onto?

Solution: No, use the rank-nullity theorem.

3. Find out $[\mathbf{v}]_{\mathcal{B}}$, where \mathcal{B} is an ordered basis:

$$(a) \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}, \quad \mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}. \quad (b) \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}, \quad \mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

Solution: $[\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ -1 \\ -1 \end{bmatrix}$. $[\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$.

4. Find out \mathbf{v} given $[\mathbf{v}]_{\mathcal{B}}$, where \mathcal{B} is an ordered basis:

$$(a) \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}, \quad [\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}. \quad (b) \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}, \quad [\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

Solution: $\mathbf{v} = \begin{bmatrix} 6 \\ 3 \\ 1 \end{bmatrix}$. $\mathbf{v} = \begin{bmatrix} 3 \\ 5 \\ 4 \end{bmatrix}$.

5. Give three linear transformations from \mathbb{R}^3 to $\mathbb{W} = \{\mathbf{w} \in \mathbb{R}^5 : w_1 - w_2 + w_3 - w_4 + w_5 = 0\}$.

Give their coordinate matrix w.r.t the ordered bases $\mathcal{B}_1 = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$ on \mathbb{R}^3 and some ordered basis of \mathbb{W} .

6. Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ as $T \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x - y + z \\ x + 2z \end{bmatrix}$. Find

- (a) a basis of Range (T),
- (b) rank (T),
- (c) a basis for $\mathcal{N}(T)$, and
- (d) $\dim(\mathcal{N}(T))$.

Solution: Verify $T(\mathbf{e}_1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $T(\mathbf{e}_2) = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$. So, $\text{Range}(T) = \mathbb{R}^2$ and $\text{rank}(T) = 2$.

$$\mathcal{N}(T) = \text{LS} \left(\begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \right) \text{ and } \dim(\mathcal{N}(T)) = 1.$$

7. **(T)** Find all linear transformations from $\mathbb{R}^n \rightarrow \mathbb{R}$.

Solution: Let $T(\mathbf{e}_i) = \alpha_i$, $1 \leq i \leq n$. So

$$T(\mathbf{x}) = T \left(\sum_{i=1}^n x_i \mathbf{e}_i \right) = \sum_{i=1}^n x_i T(\mathbf{e}_i) = \sum_{i=1}^n \alpha_i x_i = \langle \mathbf{x}, [\alpha_1, \dots, \alpha_n]^T \rangle.$$

Also, given any $T : \mathbb{R}^n \rightarrow \mathbb{R}$, linear, then we know the images of \mathbf{e}_i , for $1 \leq i \leq n$, the basis vectors. That is, there exists $\beta_i \in \mathbb{R}$ such that $T(\mathbf{e}_i) = \beta_i$, for $1 \leq i \leq n$. Thus,

$$T(\mathbf{x}) = \sum_{i=1}^n \beta_i x_i = \langle \mathbf{x}, [\beta_1, \dots, \beta_n]^T \rangle.$$

8. Let $\mathbf{v} \in \mathbb{R}^n$ and $\mathcal{B} = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ be an ordered basis of \mathbb{R}^n . Form a matrix $B = [\mathbf{v}_1 \ \dots \ \mathbf{v}_n]$. Is $B[\mathbf{e}_1]_{\mathcal{B}} = \mathbf{e}_1$? What is $B[[\mathbf{e}_1]_{\mathcal{B}}, \dots, [\mathbf{e}_n]_{\mathcal{B}}]$? Show that B is invertible and $[\mathbf{v}]_{\mathcal{B}} = B^{-1}\mathbf{v}$.

Solution: Let $\mathbf{e}_1 = \sum_{i=1}^n \alpha_i \mathbf{v}_i$.

$$\text{Then, } [\mathbf{e}_1]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} \Rightarrow B[\mathbf{e}_1]_{\mathcal{B}} = [\mathbf{v}_1 \ \dots \ \mathbf{v}_n] \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} = \sum_{i=1}^n \alpha_i \mathbf{v}_i = \mathbf{e}_1.$$

Similarly, $B[\mathbf{e}_i]_{\mathcal{B}} = \mathbf{e}_i$, for all $i, 1 \leq i \leq n$. So,

$$B[[\mathbf{e}_1]_{\mathcal{B}}, \dots, [\mathbf{e}_n]_{\mathcal{B}}] = [B[\mathbf{e}_1]_{\mathcal{B}}, \dots, B[\mathbf{e}_n]_{\mathcal{B}}] = [\mathbf{e}_1, \dots, \mathbf{e}_n] = I.$$

Thus, $B^{-1} = [[\mathbf{e}_1]_{\mathcal{B}}, \dots, [\mathbf{e}_n]_{\mathcal{B}}]$. Further, $[\mathbf{e}_i]_{\mathcal{B}} = B^{-1}\mathbf{e}_i$, $\forall i, 1 \leq i \leq n$. Hence $[\mathbf{v}]_{\mathcal{B}} = B^{-1}\mathbf{v}$.

9. **(T)** Show that a linear transformation is one-one if and only if null-space of $\mathcal{N}(T)$ is $\{\mathbf{0}\}$.

Solution: $\mathcal{N}(T) \neq \{\mathbf{0}\} \Rightarrow$ there is an $\mathbf{x} \in \mathcal{N}(T)$, $\mathbf{x} \neq \mathbf{0} \Rightarrow T(\mathbf{x}) = T(\mathbf{0}) \Rightarrow T$ is not one-one. If $\mathcal{N}(T) = \{\mathbf{0}\}$ then $T(\mathbf{x}) = T(\mathbf{y}) \Rightarrow T(\mathbf{x} - \mathbf{y}) = \mathbf{0} \Rightarrow \mathbf{x} - \mathbf{y} \in \mathcal{N}(T) \Rightarrow \mathbf{x} = \mathbf{y}$.

10. Describe all 2×2 orthogonal matrices. Prove that action of any orthogonal matrix on a vector $\mathbf{v} \in \mathbb{R}^2$, is either a rotation or a reflection about a line.

Solution: As A preserves length, there is a $\theta \in [0, 2\pi)$ such that $A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$ ($\sin^2 \theta + \cos^2 \theta = 1$). Since $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \perp \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, we have, $A \begin{bmatrix} 1 \\ 0 \end{bmatrix} \perp A \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. Therefore, $A \begin{bmatrix} 0 \\ 1 \end{bmatrix} =$

$\begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$ or $A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} \sin \theta \\ -\cos \theta \end{bmatrix}$, which further implies that

$$A = \underbrace{\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}}_{\text{rotation by an angle } \theta}, \quad \text{or} \quad A = \underbrace{\begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}}_{\text{reflection about a line of inclination } \theta/2}.$$

11. **(T)** Let $\mathbf{v}, \mathbf{w} \in \mathbb{R}^n$, $n \geq 2$, with $\|\mathbf{v}\| = \|\mathbf{w}\| = 1$. Prove that there exist an orthogonal matrix A such that $A(\mathbf{v}) = \mathbf{w}$. Prove also that A can be chosen such that $\det(A) = 1$.
(*This is why orthogonal matrices with determinant one are called rotations.*)

Solution: As composition and inverse of orthogonal matrices are orthogonal, it is enough to choose $\mathbf{v} = \mathbf{e}_1$. So we need an orthogonal matrix A such that $A(\mathbf{e}_1) = \mathbf{w}$. Find an orthonormal basis of \mathbb{R}^n , say $\{\mathbf{w}, \mathbf{w}_2, \dots, \mathbf{w}_n\}$ by Gram Schmidt. Let $A = [\mathbf{w} \ \mathbf{w}_2 \ \cdots \ \mathbf{w}_n]$, that is, first column of A is \mathbf{w} and so on. Then A is orthogonal and $\det(A) = \pm 1$. If $\det(A) = -1$, then multiply the second column with -1 .