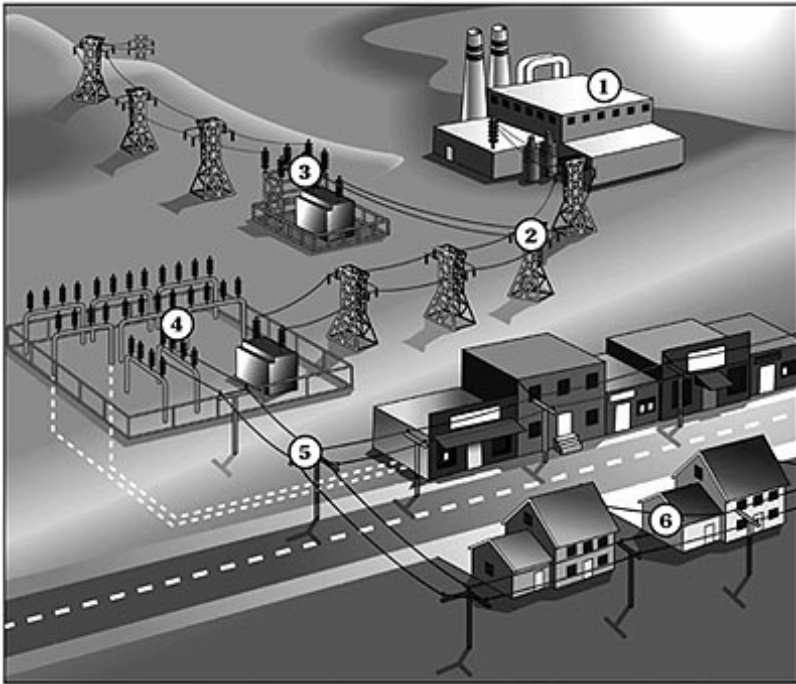


ESC201T : Introduction to Electronics

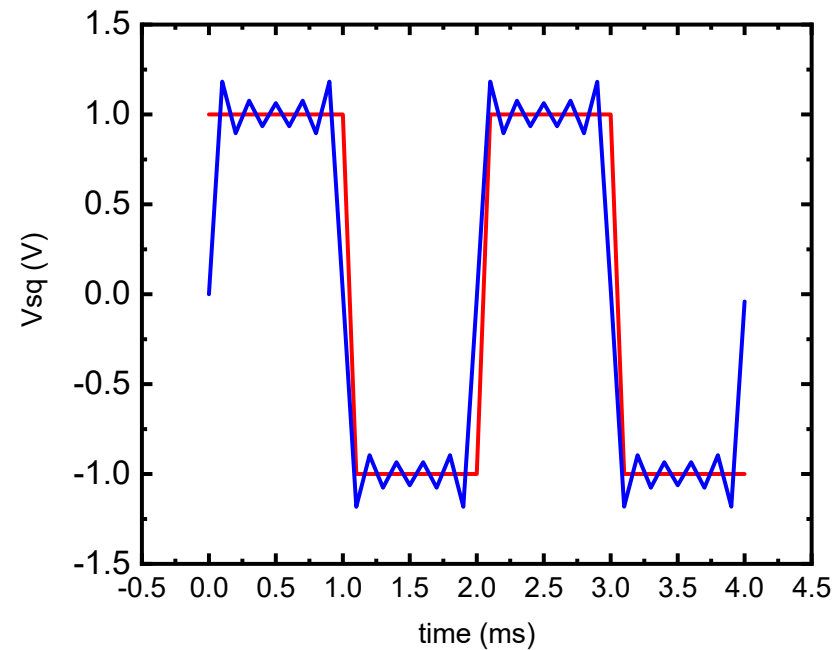
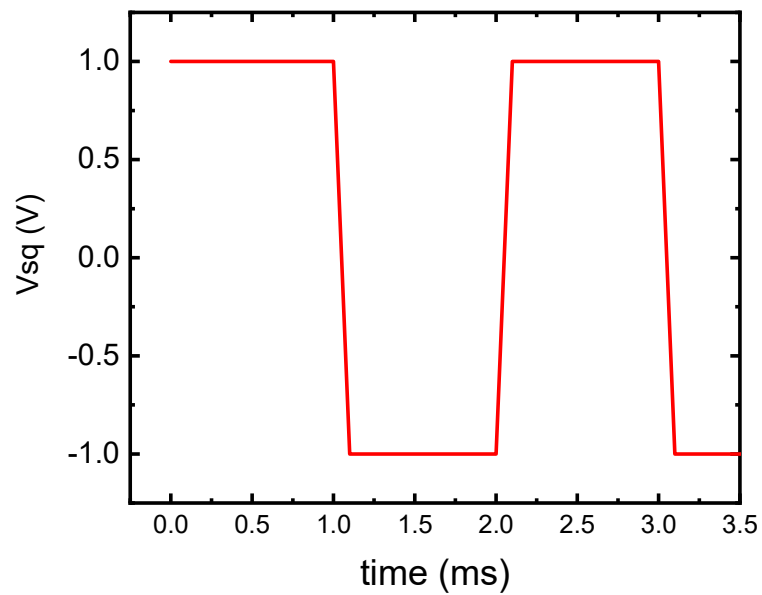
Lecture 13: Sinusoidal **Steady State** Analysis

B. Mazhari
Dept. of EE, IIT Kanpur

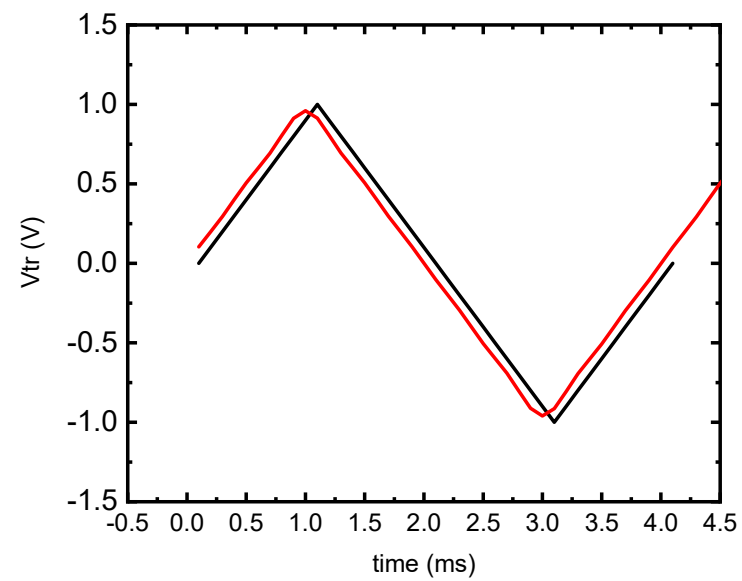
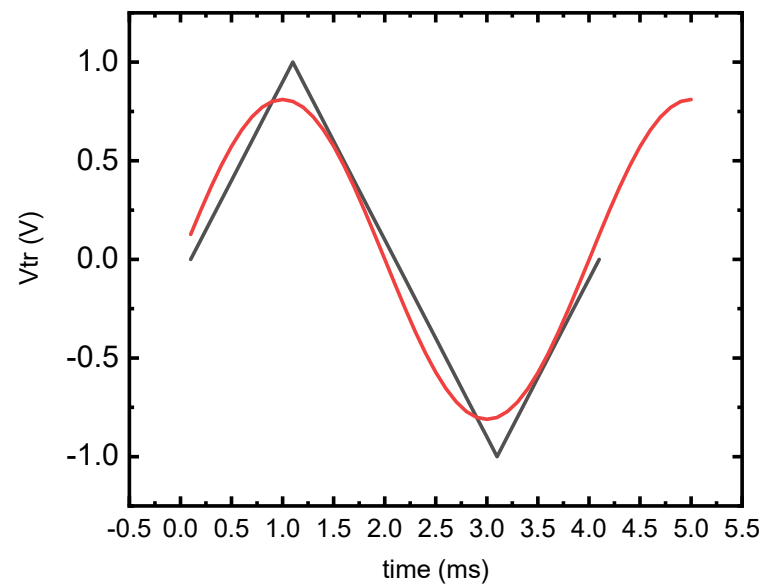
Sinusoidal Signals are widely used In Electrical Systems



Any periodic signal can be expressed as sum of sinusoids



$$f(t) = \frac{4}{\pi} \sum_{n=1,3,5}^{\infty} \frac{1}{n} \sin\left(n \frac{2\pi t}{T}\right)$$



Sinusoids have interesting mathematical property that their derivatives and integrals are sinusoids too

$$\frac{d(\sin x)}{dx} = \cos x = \sin(90 - x)$$

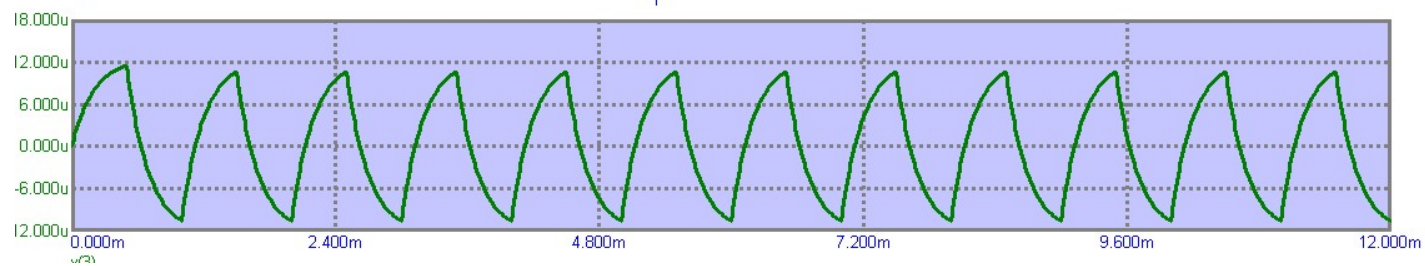
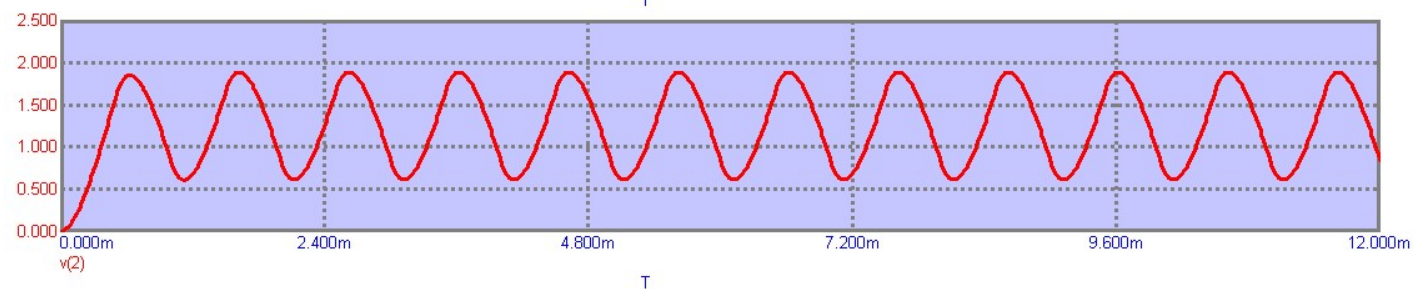
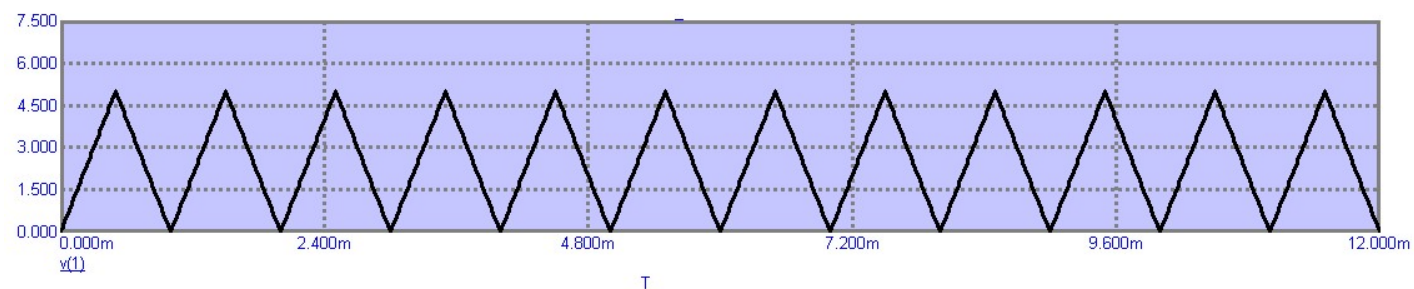
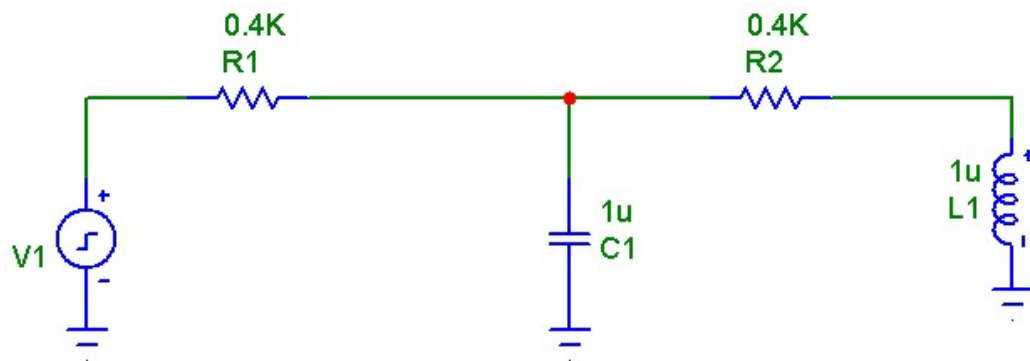
$$i_c = C \frac{dv_c}{dt}$$

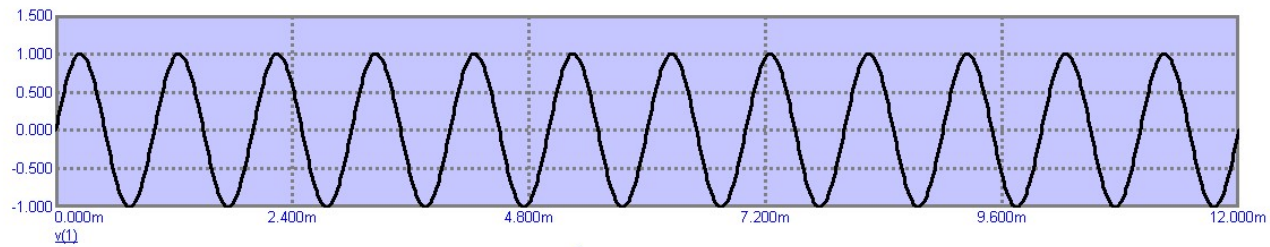
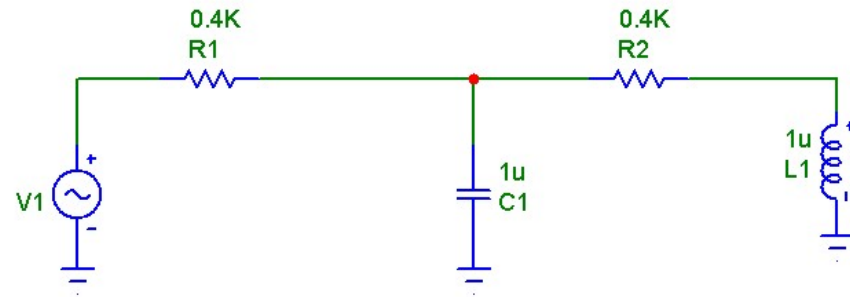
$$\int \sin x \, dx = -\cos x = \sin(x - 90)$$

$$v = L \frac{di}{dt}$$

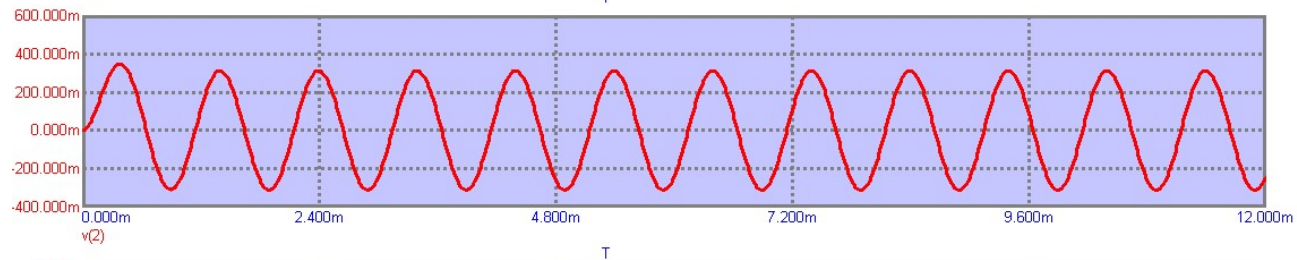
So as a sinusoidal signal goes through a linear circuit, it remains a sinusoid

This makes analysis easier

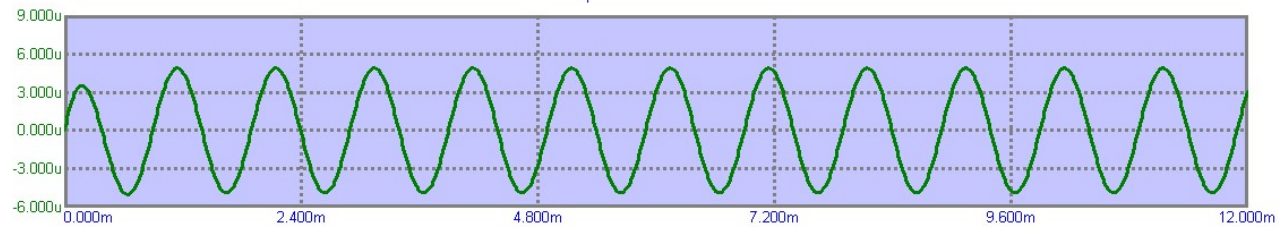




V_{IN}



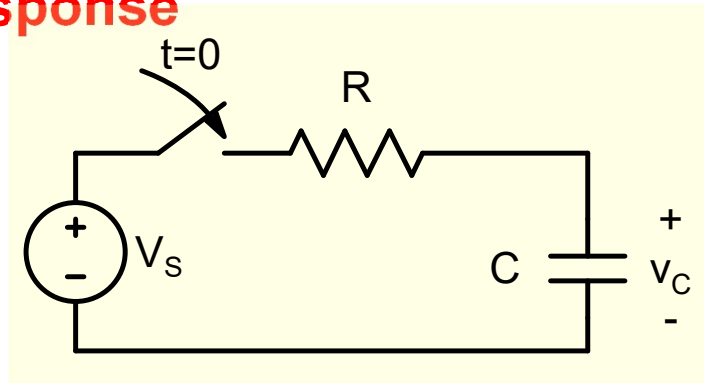
V_C



V_L

Voltage everywhere in the circuit is sinusoidal

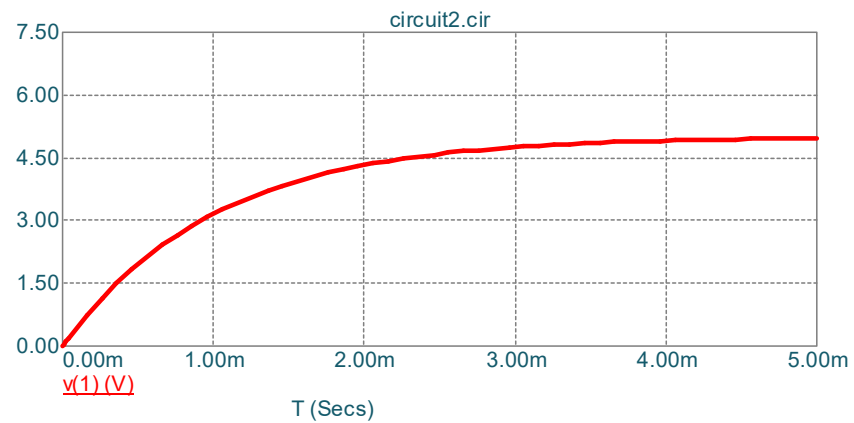
Transient and Forced Response



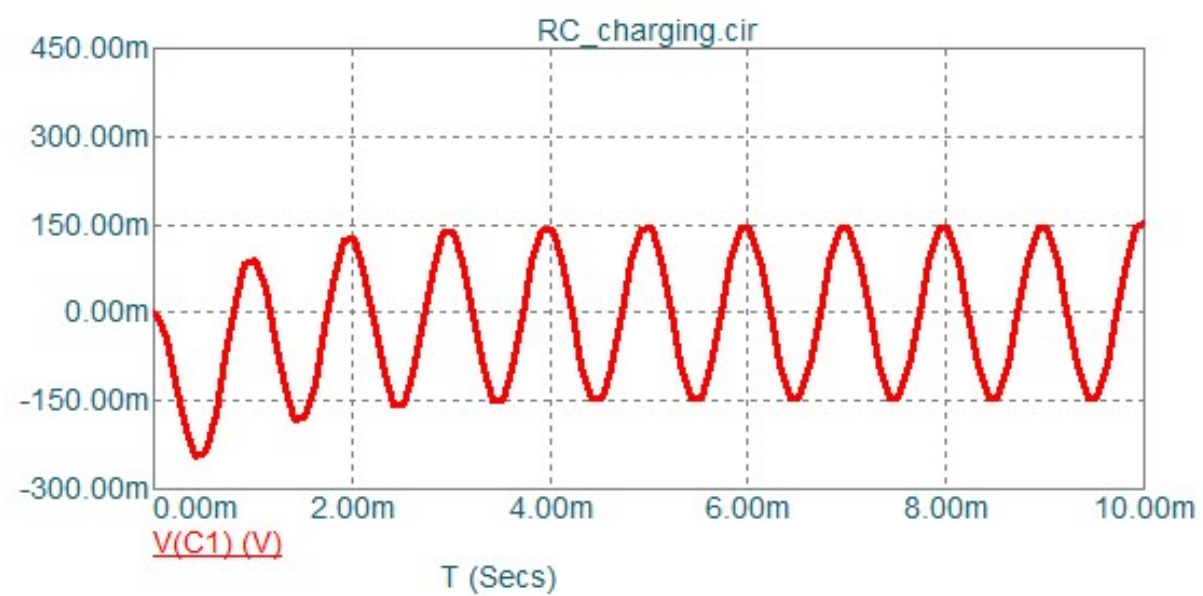
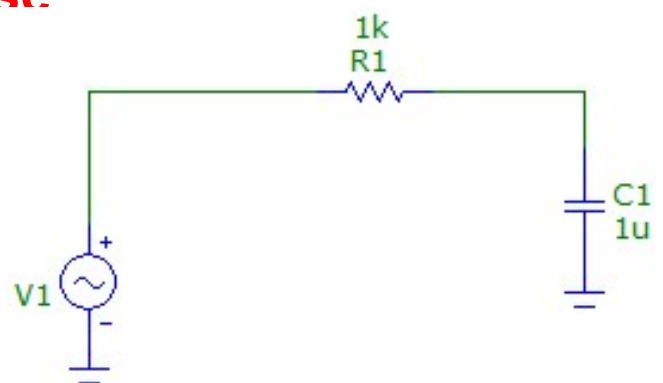
$$v_C(t) = V_S - V_S \times e^{-\frac{t}{RC}}$$

Steady-state/forced response

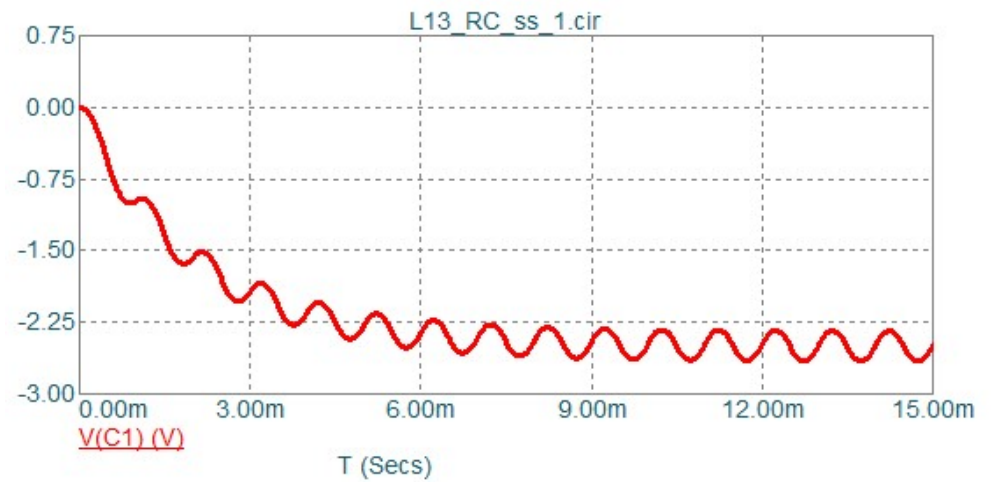
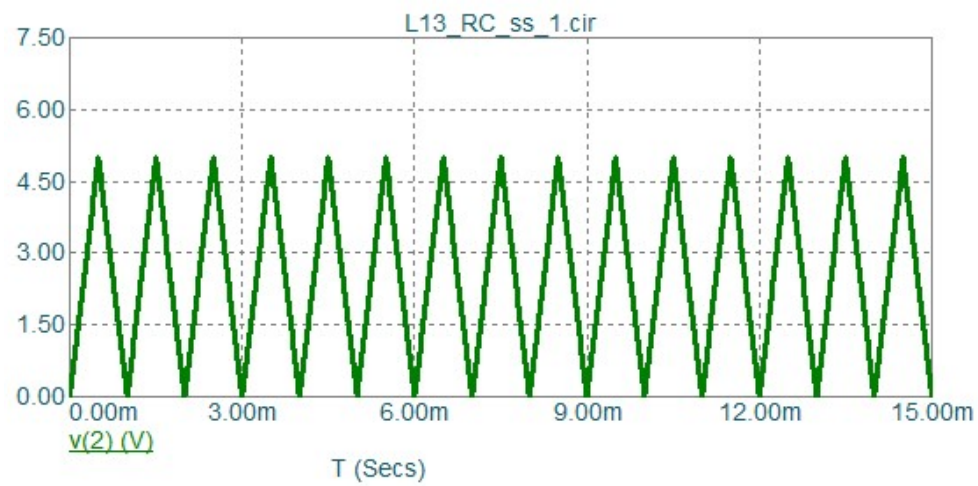
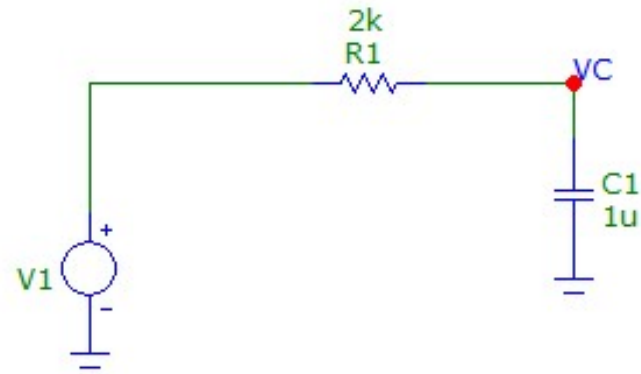
Transient response



Transient and Forced Response

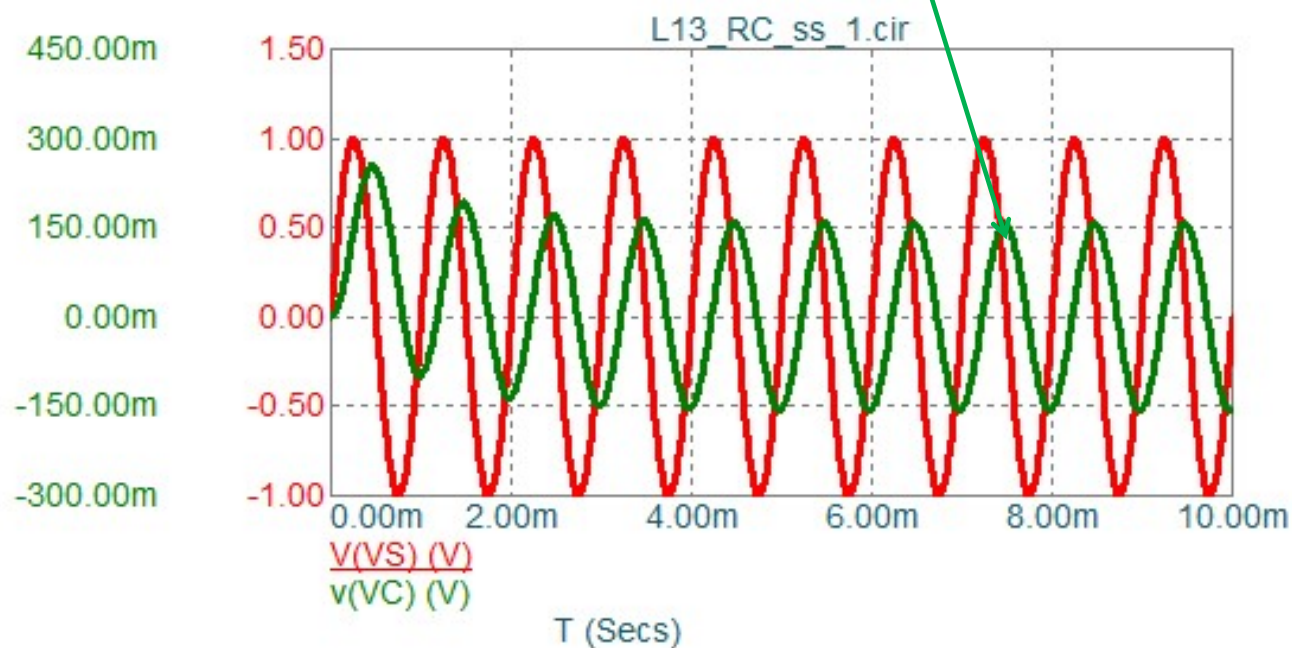
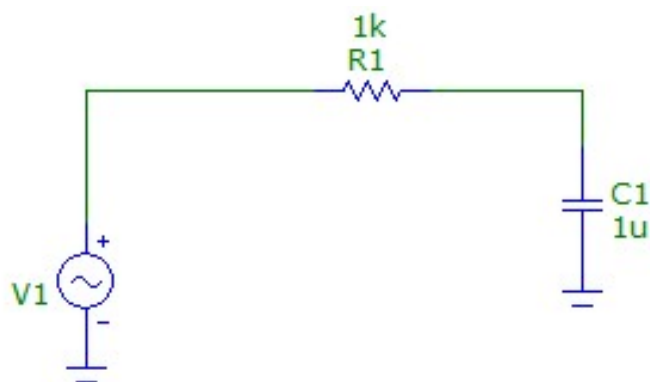


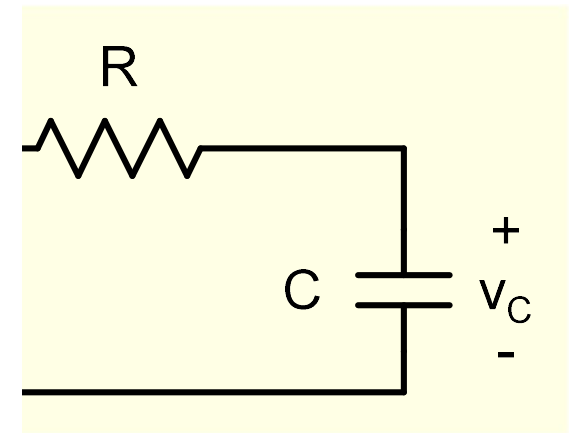
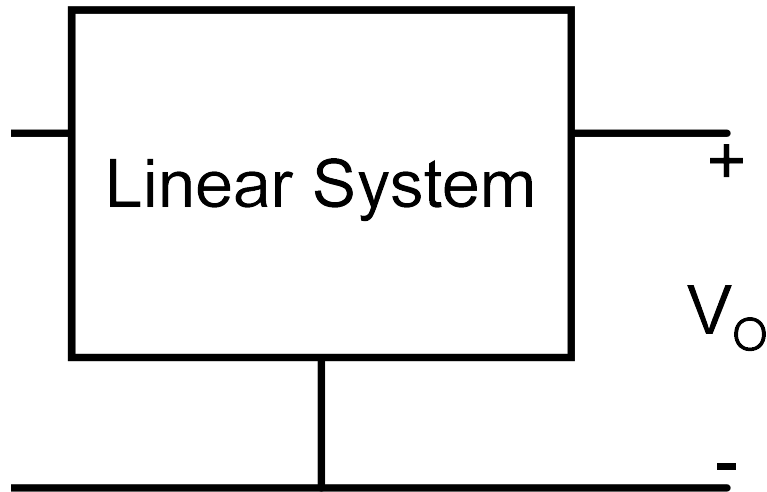
Transient and Forced Response



Sinusoidal Steady-State

When the excitation is sinusoidal, the response (voltage or currents) in linear circuit will be sinusoidal as well. If input persists, the response persists and is called steady state response



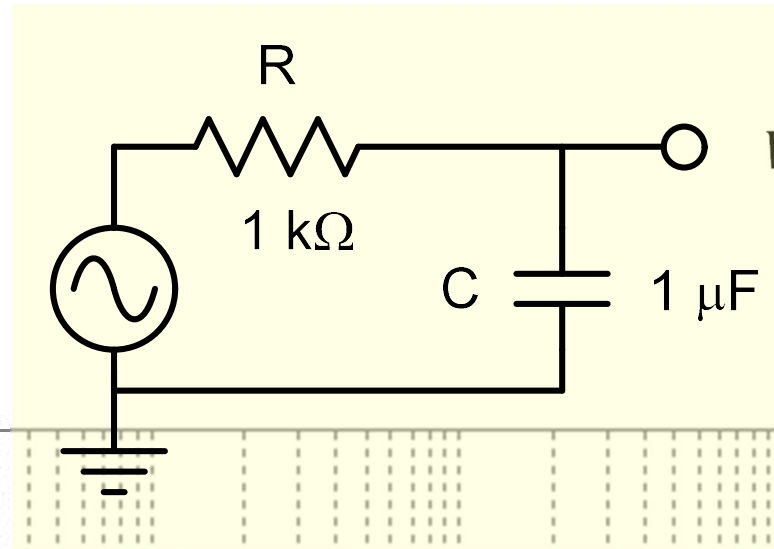


$$V_S = 1 \times \cos(\omega t)$$

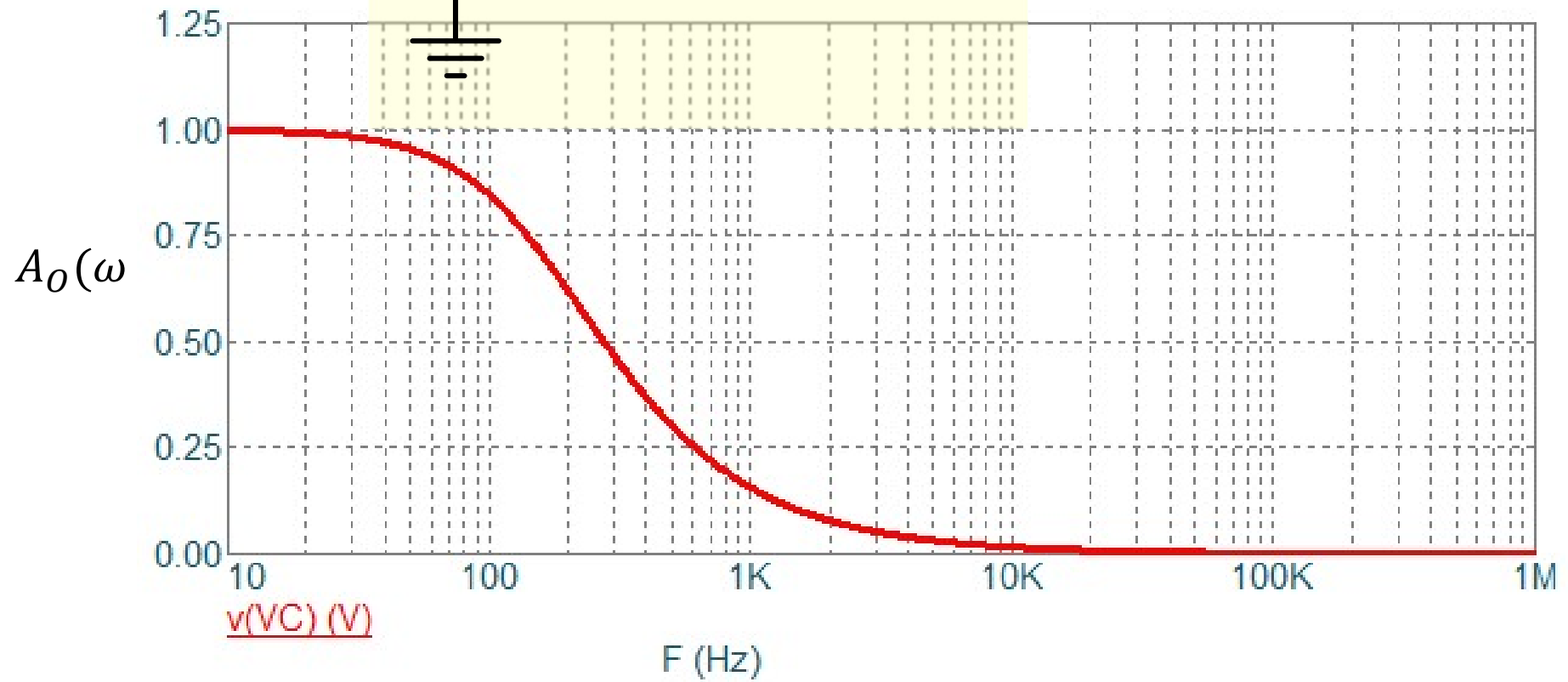
$$V_O = A_O(\omega) \times \cos(\omega t + \theta(\omega))$$

$A_O(\omega)$ and $\theta(\omega)$ determine the complete characteristics of the system

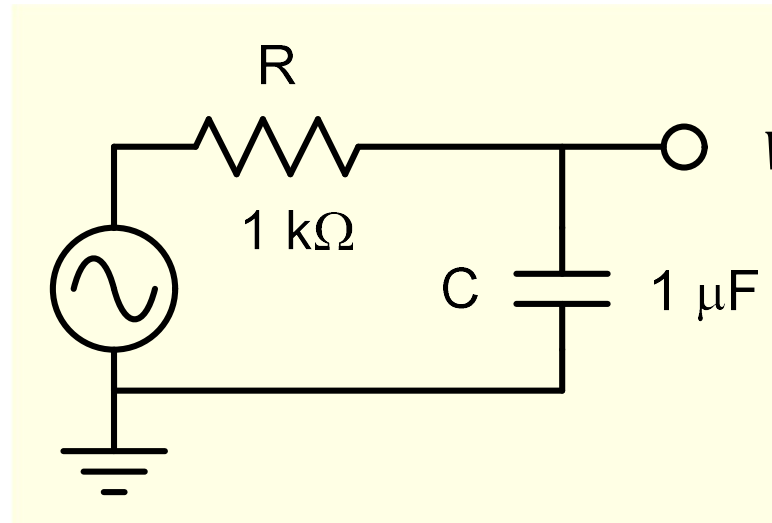
$$V_S = 1 \times \cos(\omega t)$$



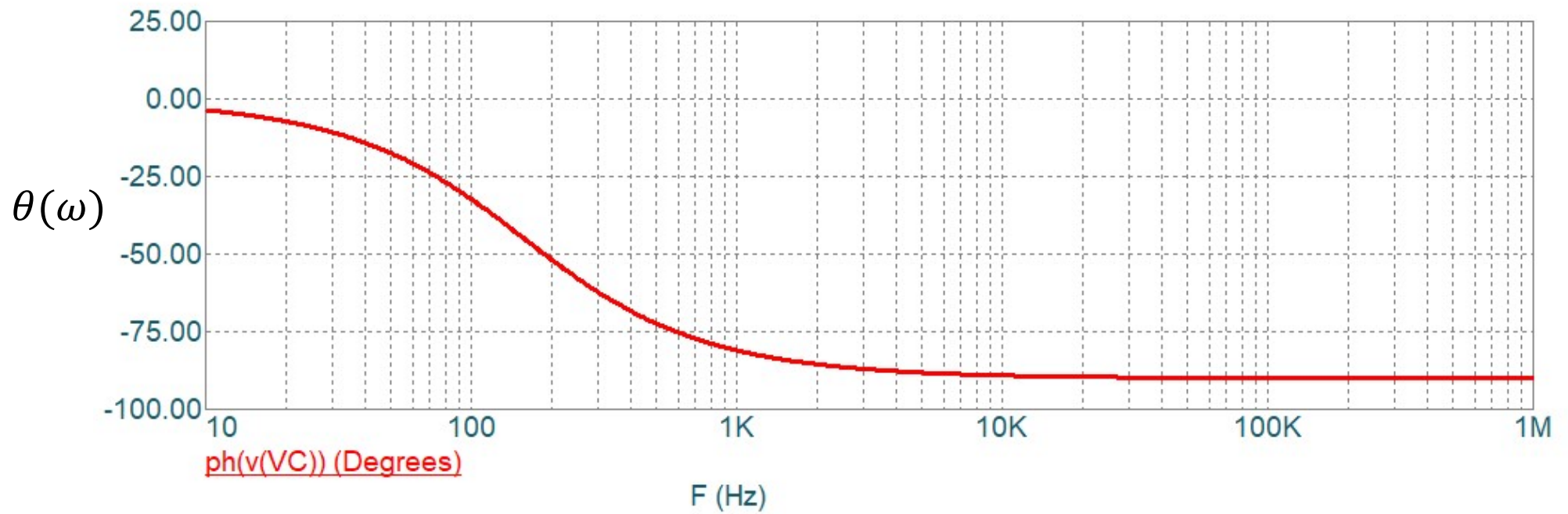
$$V_C(\omega) = A_O(\omega) \times \cos(\omega t + \theta(\omega))$$

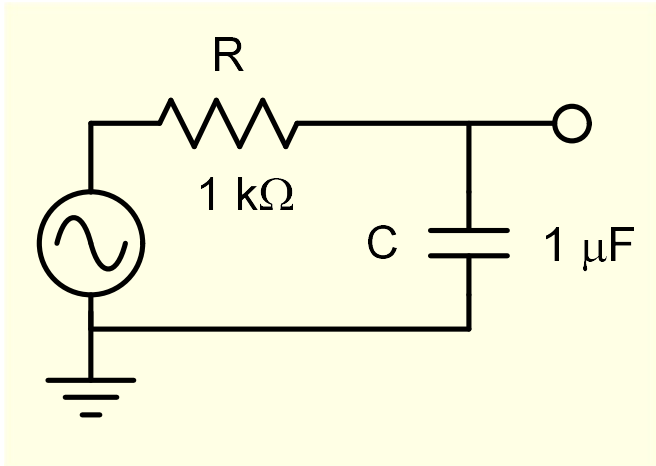


$$V_S = 1 \times \cos(\omega t)$$

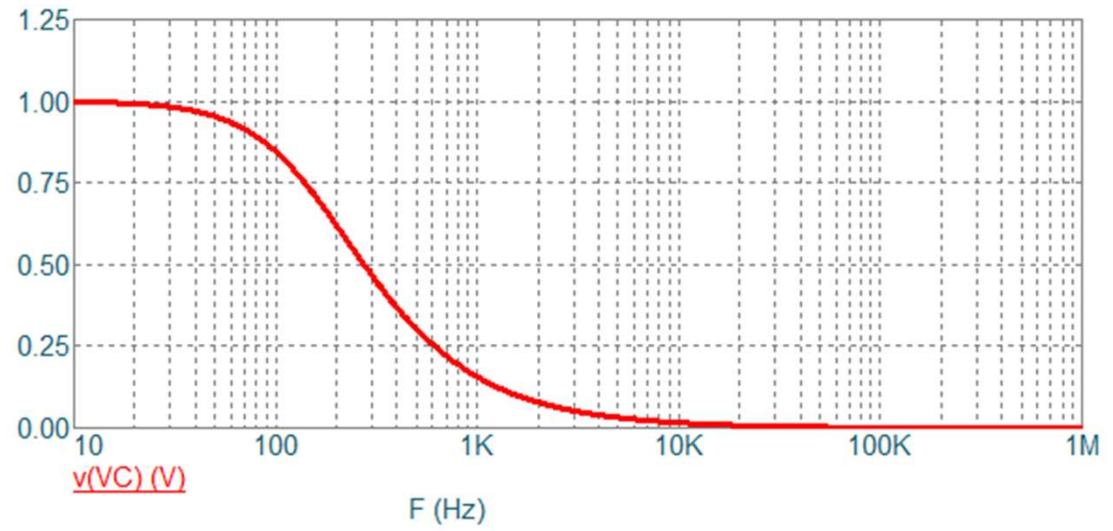


$$V_C(\omega) = A_O(\omega) \times \cos(\omega t + \theta(\omega))$$

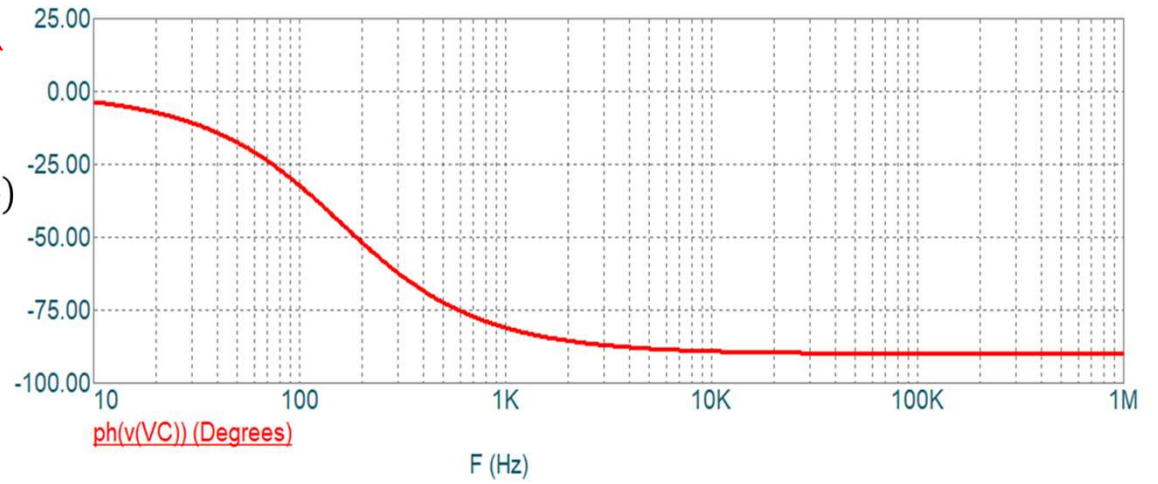




$A_o(\omega)$



$\theta(\omega)$

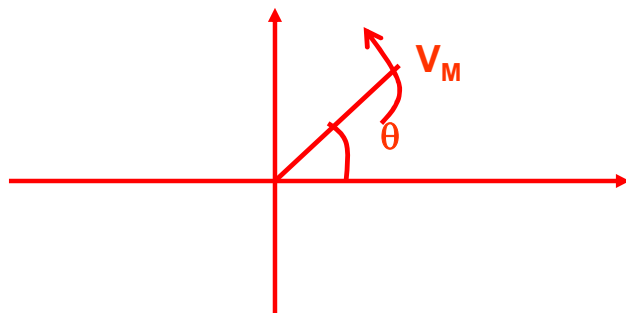


Sinusoidal Voltages and Currents

$$v(t) = V_M \times \cos(\omega t + \theta)$$

V_m is the peak value

ω is the angular frequency in radians per second



T is the period, where $f = \frac{1}{T}$ is the frequency

$$\omega = \frac{2\pi}{T}, \omega = 2\pi f; \theta \text{ is the phase angle}$$

Example-1

$$5 \sin(4\pi t - 60^\circ)$$

What is the amplitude, phase, angular frequency, time period, frequency?

$$v(t) = V_m \cos(\omega t + \theta)$$

$$\sin(z) = \cos(z - 90^\circ)$$

$$v(t) = 5 \cos(4\pi t - 60^\circ - 90^\circ)$$

Amplitude = 5 ; Phase = -150°

Phase in radians: $360^\circ = 2\pi$ $\theta = \frac{-150}{360} \times 2\pi = -2.618 \text{ Radians}$

$$\omega = 4\pi \text{ r / s}$$

$$\omega = \frac{2\pi}{T} = 4\pi \Rightarrow T = 0.5 \text{ s}$$

$$f = \frac{1}{T} = 2 \text{ Hz}$$

Example-2

Find the phase difference between the two currents

$$i_1 = 4 \sin(377t + 25^\circ) \quad i_2 = -5 \cos(377t - 40^\circ)$$

$$x(t) = x_m \cos(\omega t + \theta)$$

$$i_1 = 4 \cos(377t + 25^\circ - 90^\circ) \quad \theta_1 = -65^\circ$$

$$i_2 = 5 \cos(377t - 40^\circ + 180^\circ) \quad \theta_2 = 140^\circ$$

$$\sin(\omega t \pm 180^\circ) = -\sin \omega t$$

$$\cos(\omega t \pm 180^\circ) = -\cos \omega t$$

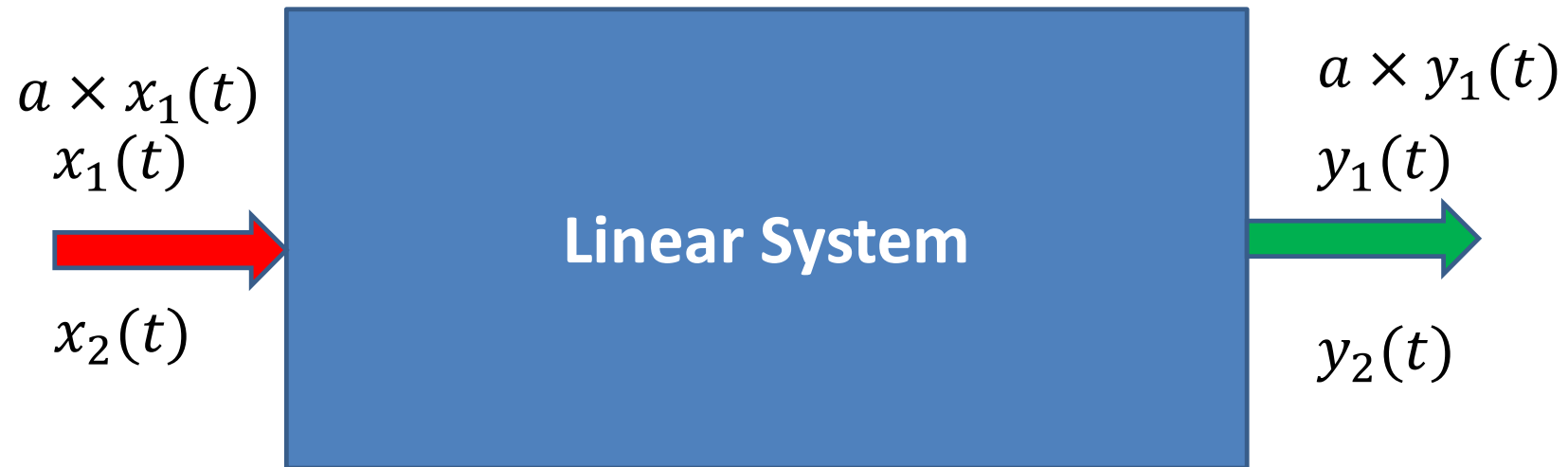
$$\sin(\omega t \pm 90^\circ) = \pm \cos \omega t$$

$$\cos(\omega t \pm 90^\circ) = \mp \sin \omega t$$

$$\theta_1 - \theta_2 = -205^\circ$$

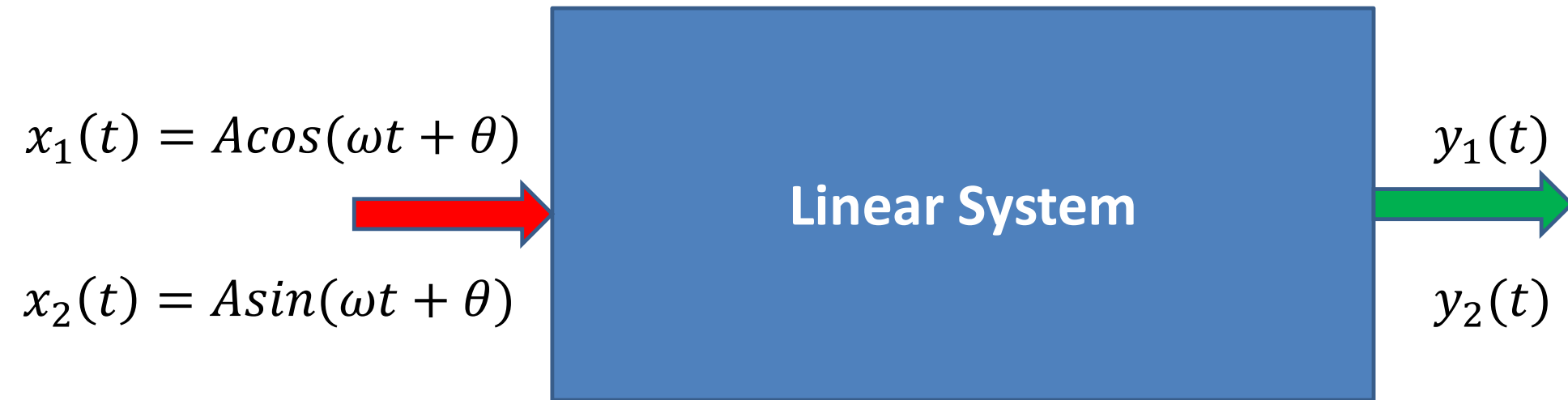
$$\theta_1 - \theta_2 = -205 + 180 = -25^\circ$$

Linear Systems



$$x(t) = a_1 x_1(t) + a_2 x_2(t)$$

$$y(t) = a_1 y_1(t) + a_2 y_2(t)$$



$$x(t) = x_1(t) + jx_2(t)$$

$$y(t) = y_1(t) + jy_2(t)$$

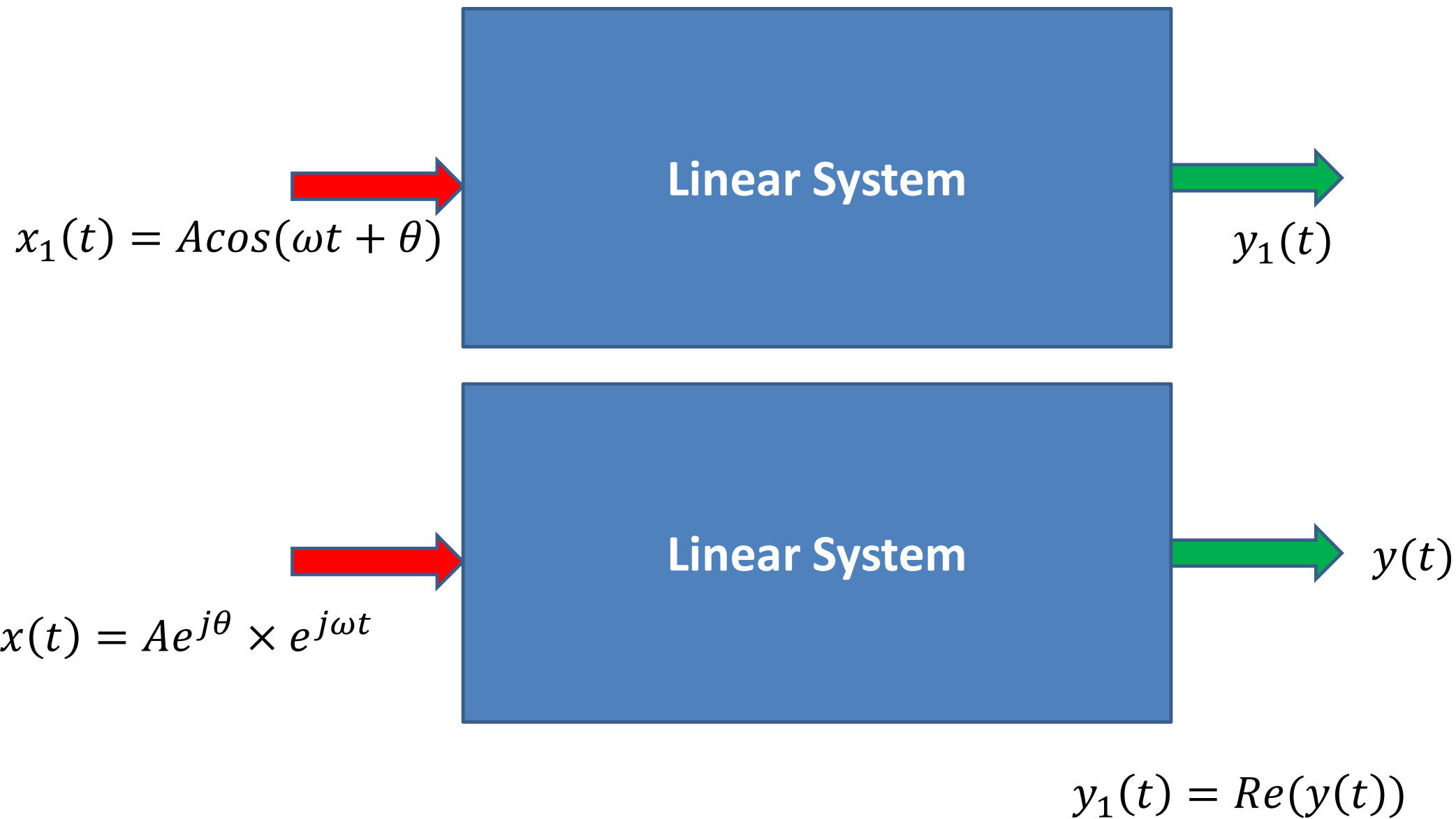
$$j = \sqrt{-1}$$

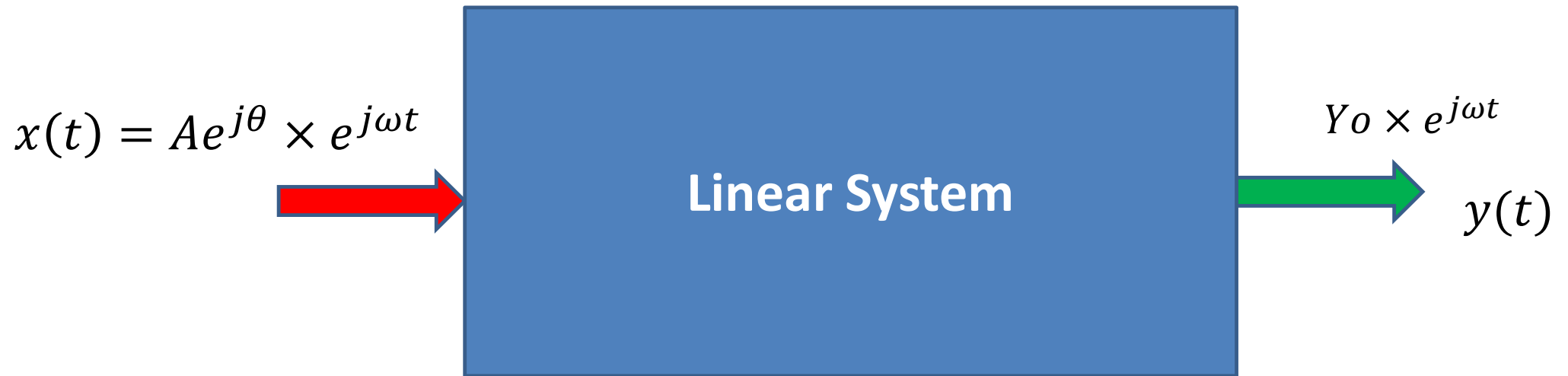
$$x(t) = Ae^{j\theta} \times e^{j\omega t}$$

$$y_1(t) = \text{Re}(y(t))$$

$$y_2(t) = \text{Im}(y(t))$$

$$e^{j\omega t} = \cos(\omega t) + j\sin(\omega t)$$



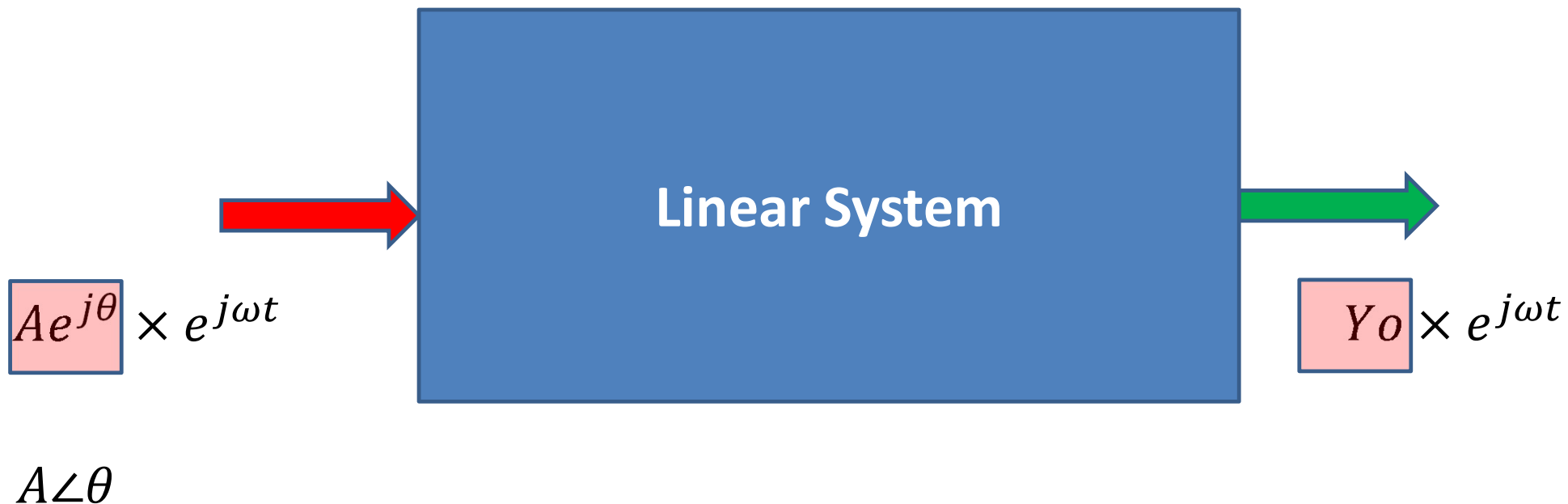


$$a_n \frac{d^n y}{dt^n} + a_{n-1} \frac{d^{n-1} y}{dt^{n-1}} + \cdots + a_o y = Ae^{j\theta} \times e^{j\omega t}$$

$$\text{Solution : } y(t) = Y_o \times e^{j\omega t}$$

$$a_n (j\omega)^n Y_o + a_{n-1} (j\omega)^{n-1} Y_o + \cdots + a_o Y_o = A \times e^{j\theta}$$

Solve an algebraic equation in complex variables



Different Representations of a complex Number

$$\text{Rectangular form: } Z = 4 + j3$$

$$\text{Polar form: } Z = \sqrt{4^2 + 3^2} \angle \tan^{-1} \left(\frac{3}{4} \right) = 5 \angle 36.87^\circ$$

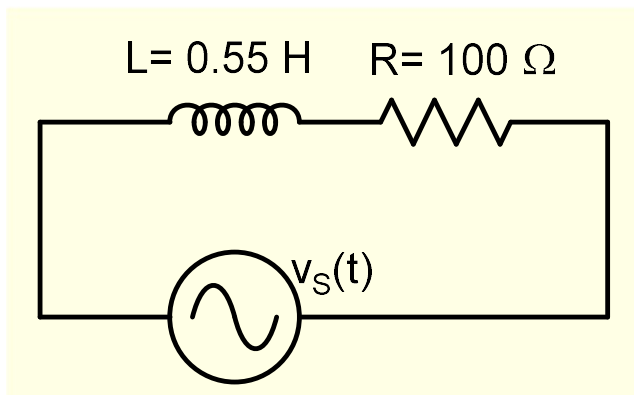
$$\text{Exponential form: } Z = 5 \times e^{j36.87}$$

$$Z_1 = 4 \angle 30^\circ \quad Z_2 = 6 \angle 60^\circ$$

$$Z_2 \times Z_1 = 6 \times 4 \angle 60^\circ + 30^\circ = 24 \angle 90^\circ$$

$$\frac{Z_2}{Z_1} = \frac{6}{4} \angle 60^\circ - 30^\circ = 1.5 \angle 30^\circ$$

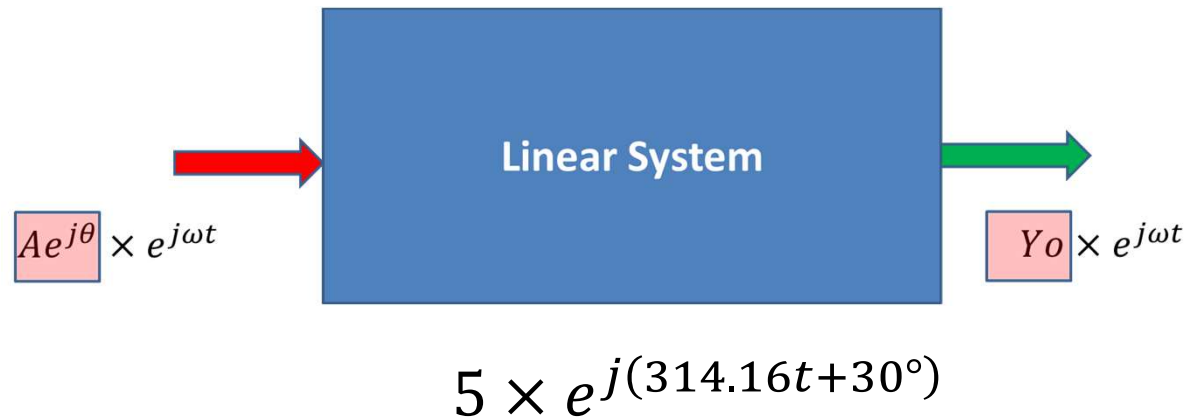
Example-1



$$v_S(t) = 5 \times \cos(314.16t + 30^\circ)$$

$$v_R(t) = 2.5 \times \cos(314.16t - 30^\circ)$$

$$v_L(t) = v_S(t) - v_R(t)$$



$$V_S = 5 \times e^{j30} \quad V_R = 2.5 \times e^{-j3}$$

$$V_L = V_S - V_R$$

$$V_S - V_R = 2.165 + j3.75 = 4.33 \times e^{j60}$$

$$v_L(t) = \text{Re}(4.33 \times e^{j60} \times e^{j\omega t})$$

$$v_L(t) = 4.33 \times \cos(314.16t + 60^\circ)$$

$$v_S(t) = 5 \times \cos(314.16t + 30^\circ)$$

$$v_R(t) = 2.5 \times \cos(314.16t - 30^\circ)$$

$$v_S(t) - v_R(t) = ?$$

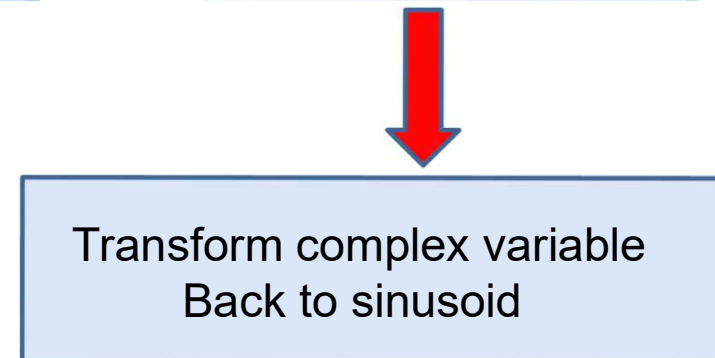
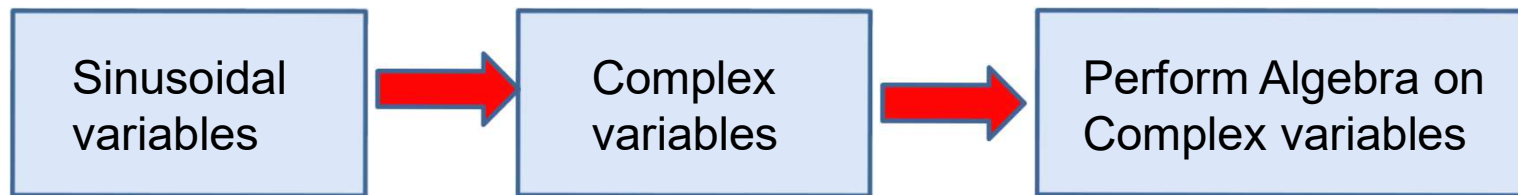
Strategy

$$V_S = 2.16 - j1.25$$

$$V_R = 4.33 + j2.5$$

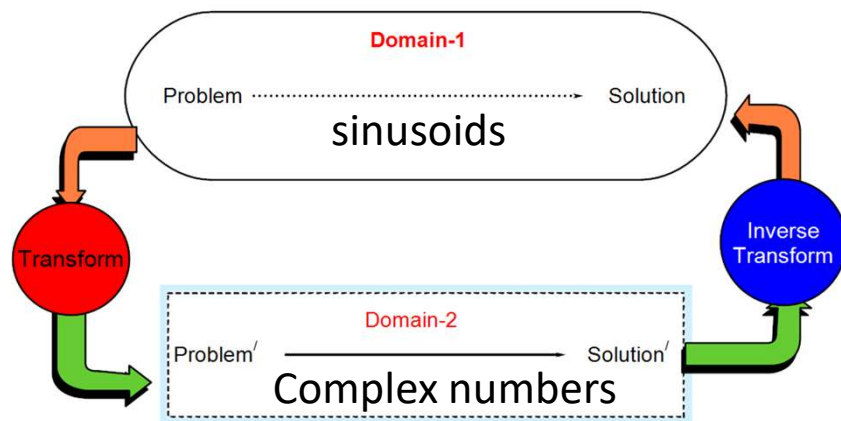
$$V_S - V_R = 4.33 + j2.5 - 2.16 + j1.25$$

$$= 2.165 + j3.75$$



$$v_L(t) = \text{Re}(4.33 \times e^{j60} \times e^{j\omega t})$$

$$v_L(t) = 4.33 \times \cos(314.16t + 60^\circ)$$



$$v(t) = V_m \cos(\omega t + \theta)$$

$$v(t) = \operatorname{Re}(V_m \times e^{j(\omega t + \theta)})$$



$$\operatorname{Re}(V_m \angle \omega t + \theta)$$

$$v(t) = V_m \cos(\omega t + \theta)$$

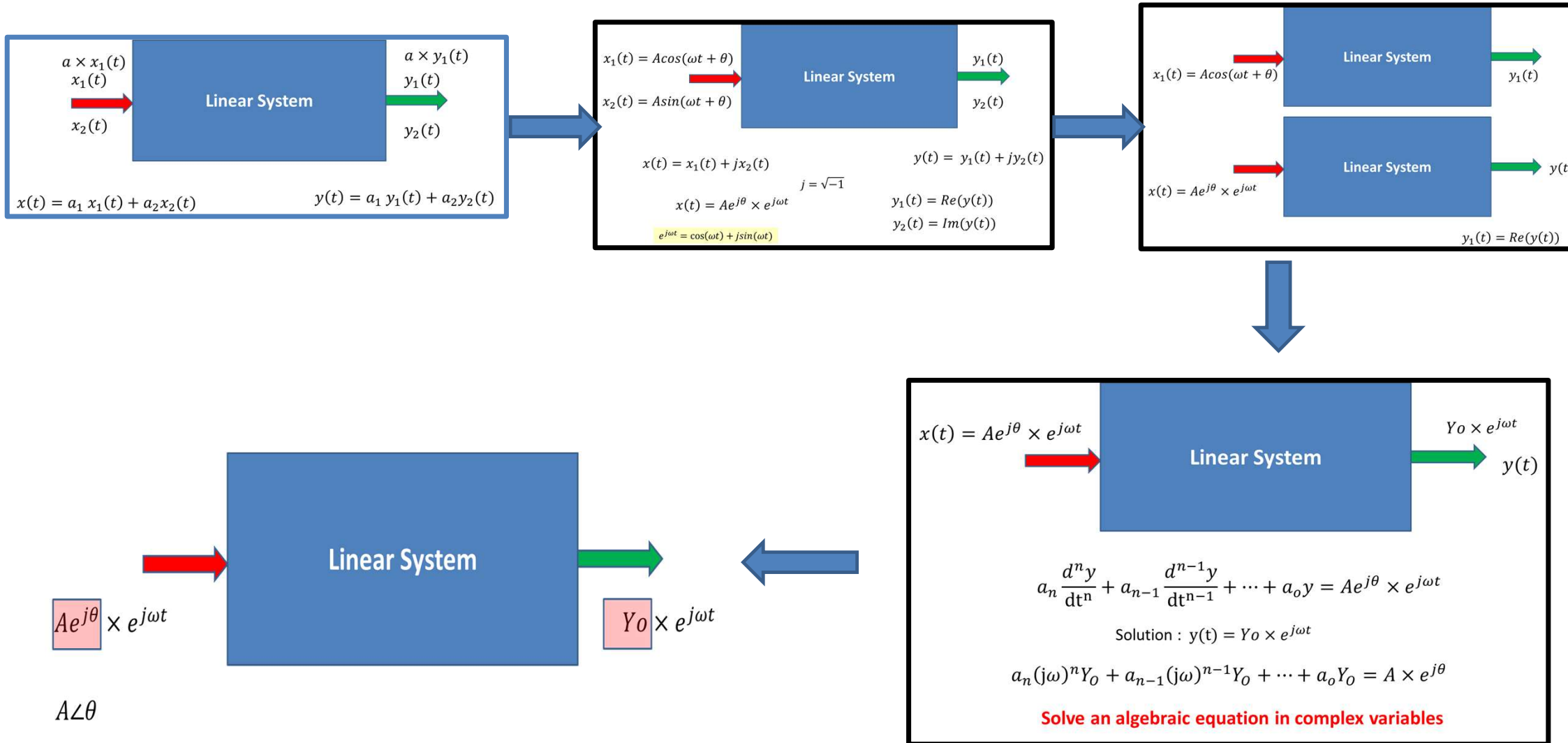


$$V_m \angle \theta$$

Phasor

$$V_M \angle \theta \rightarrow V_m \times e^{j\theta}$$

Phasor Analysis



$$v(t) = 3 \cos(\omega t + 45) \Rightarrow 3 \angle 45 \Rightarrow 3 \cos(45) + j3 \sin(45)$$

$$v(t) = 5 \cos(\omega t - 60) \leftarrow 5 \angle -60$$