

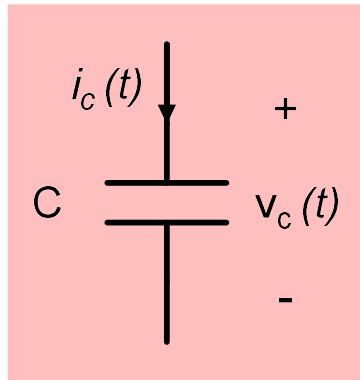
ESC201T : Introduction to **Electronics**

L11: Transient Analysis of RLC Circuits

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Two important concepts

Voltage across a capacitor cannot change instantaneously

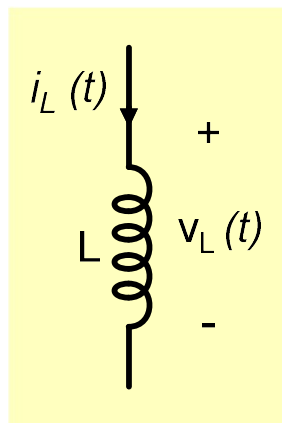


$$i_c = C \frac{dv_c}{dt}$$

$$v_c = \frac{1}{C} \int i_c(t) dt$$

Instantaneous change implies infinite current!

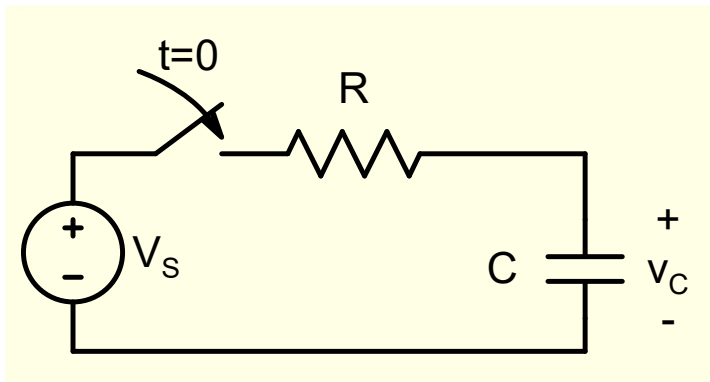
Current through an inductor cannot change instantaneously



$$v_L = L \frac{di_L}{dt}$$

$$i_L = \frac{1}{L} \int v_L(t) dt$$

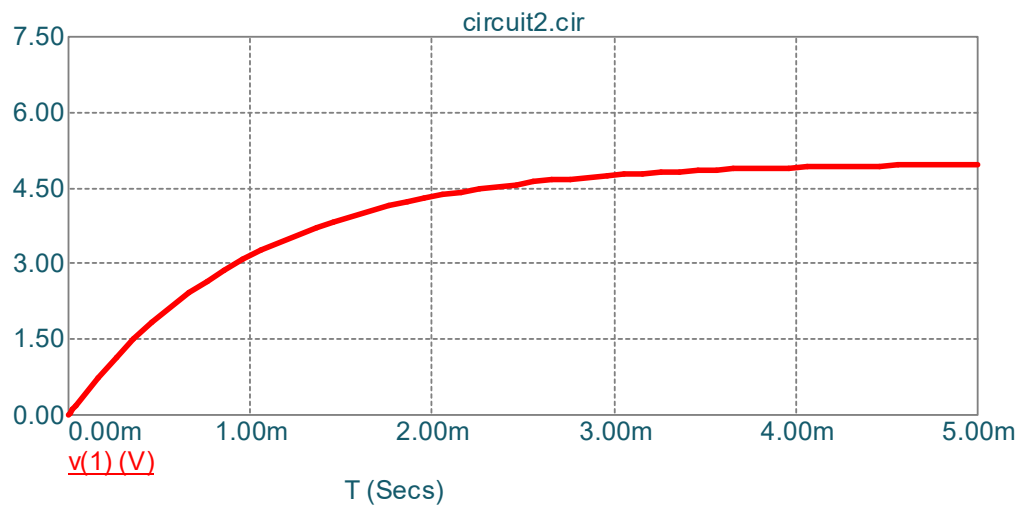
Instant change in voltage implies infinite voltage!



$$\frac{dx}{dt} = -a_1 x + a_2$$

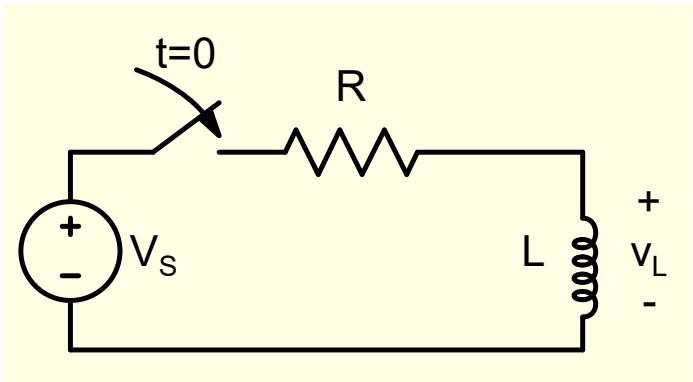
$$x(t) = x(\infty) + \{x(0) - x(\infty)\} e^{-a_1 t}$$

$$v_C(t) = V_s \left(1 - e^{-\frac{t}{RC}}\right)$$

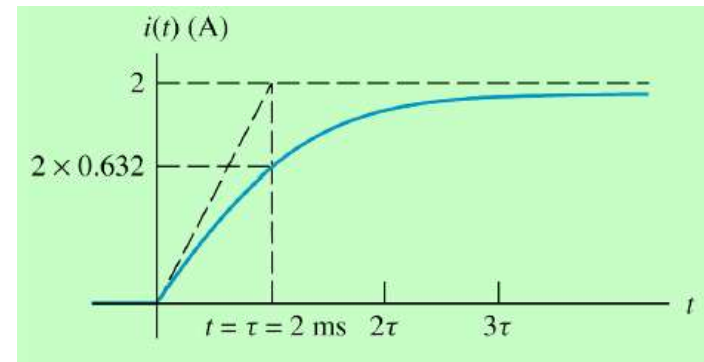


Time	τ	2τ	3τ	4τ	5τ
$V_C(t)/V_i$	0.632	0.865	.95	0.982	0.993

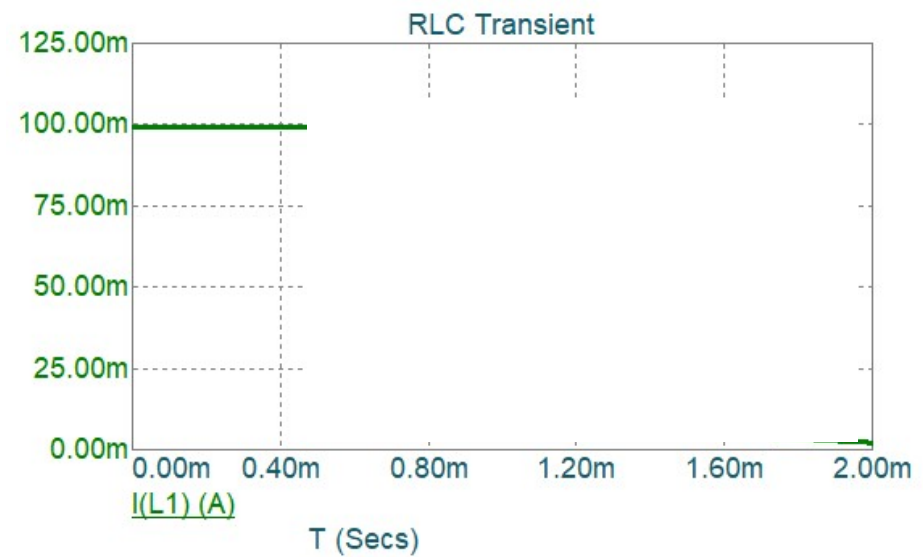
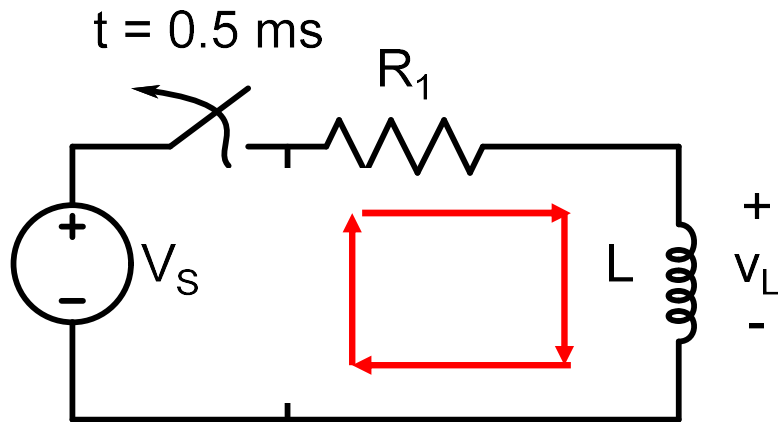
R-L Circuits For High Voltage Generation

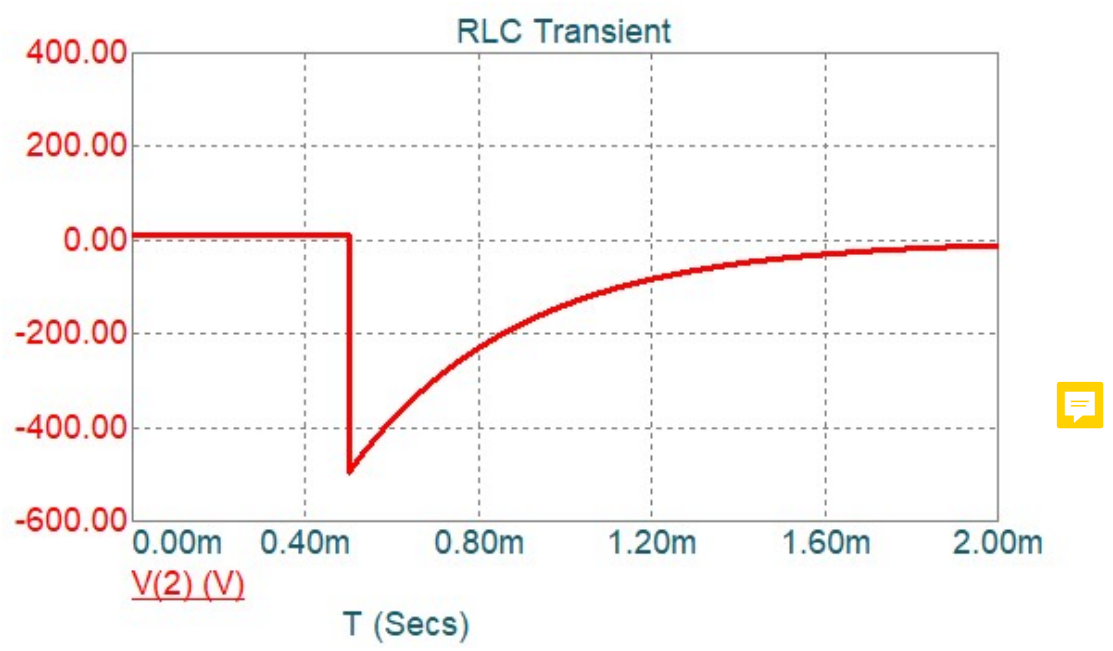
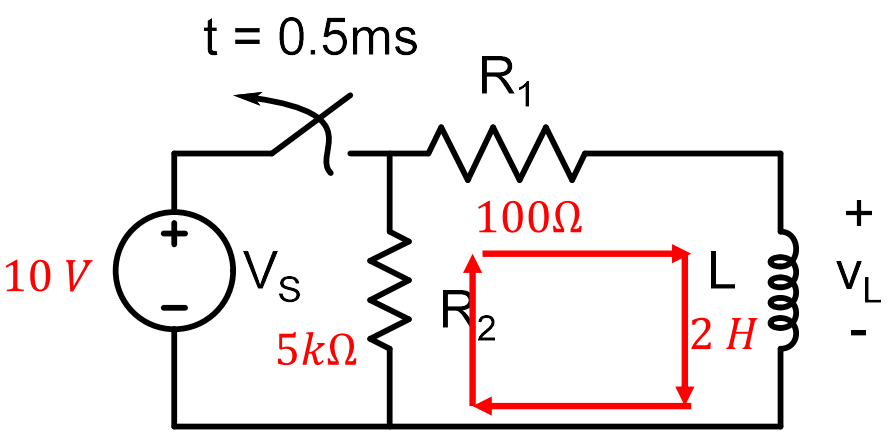


$$i(t) = \frac{V_S}{R} \times (1 - e^{-\frac{t}{\tau}})$$

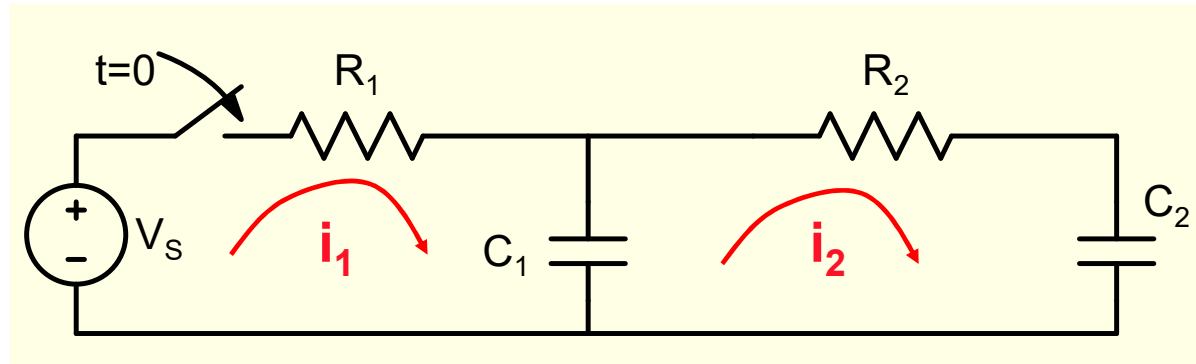


$$I_L(t) = \frac{V_S}{R_1} \times \exp(-\frac{t}{\tau})$$





Second Order System



$$V_s = i_1 R_1 + v_{C_1} \quad (1)$$

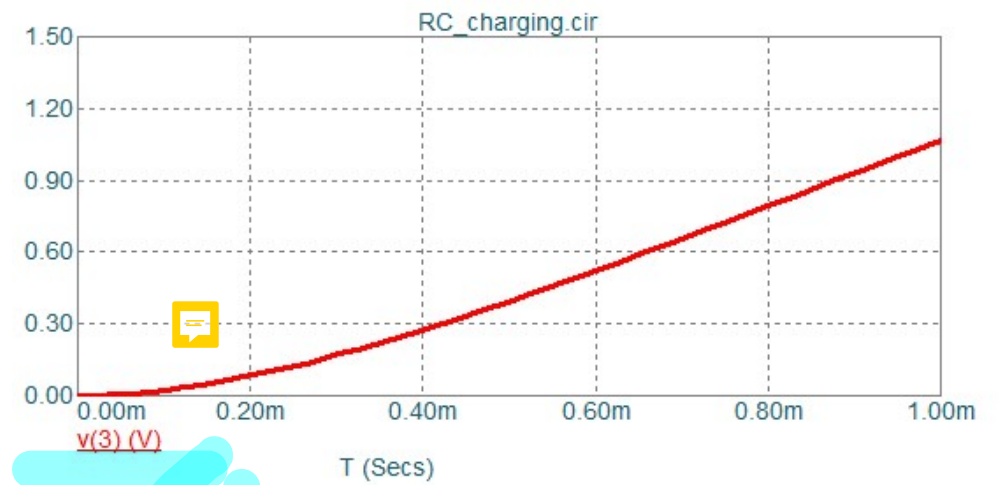
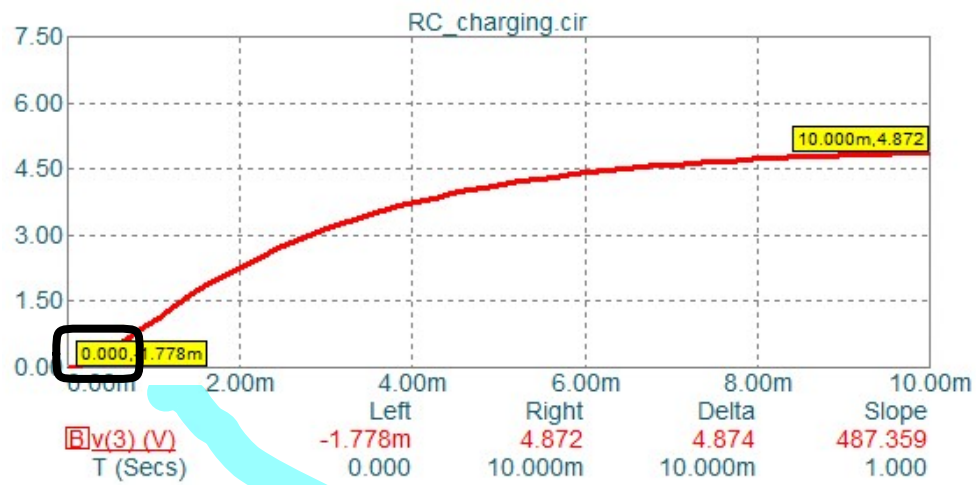
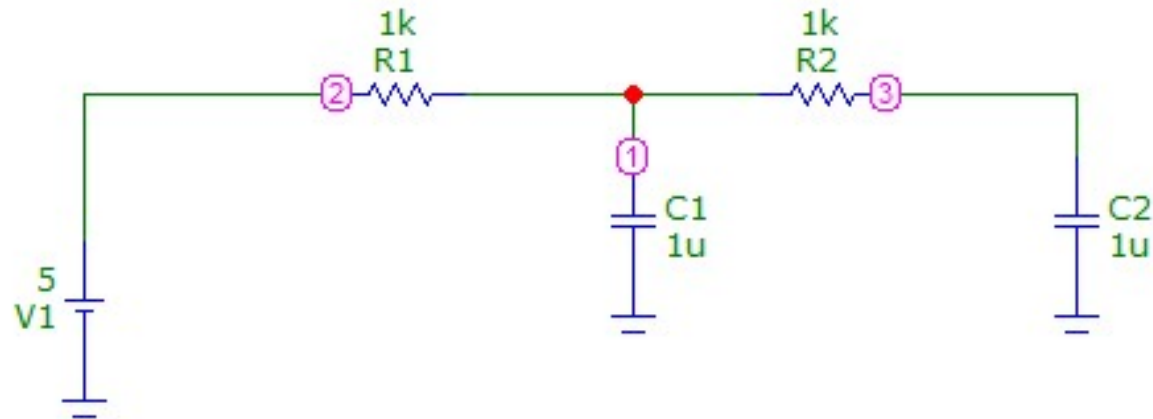
$$v_{C_1} = i_2 R_2 + v_{C_2} \quad (2)$$

$$i_1 - i_2 = C_1 \frac{dv_1}{dt} \quad (3)$$

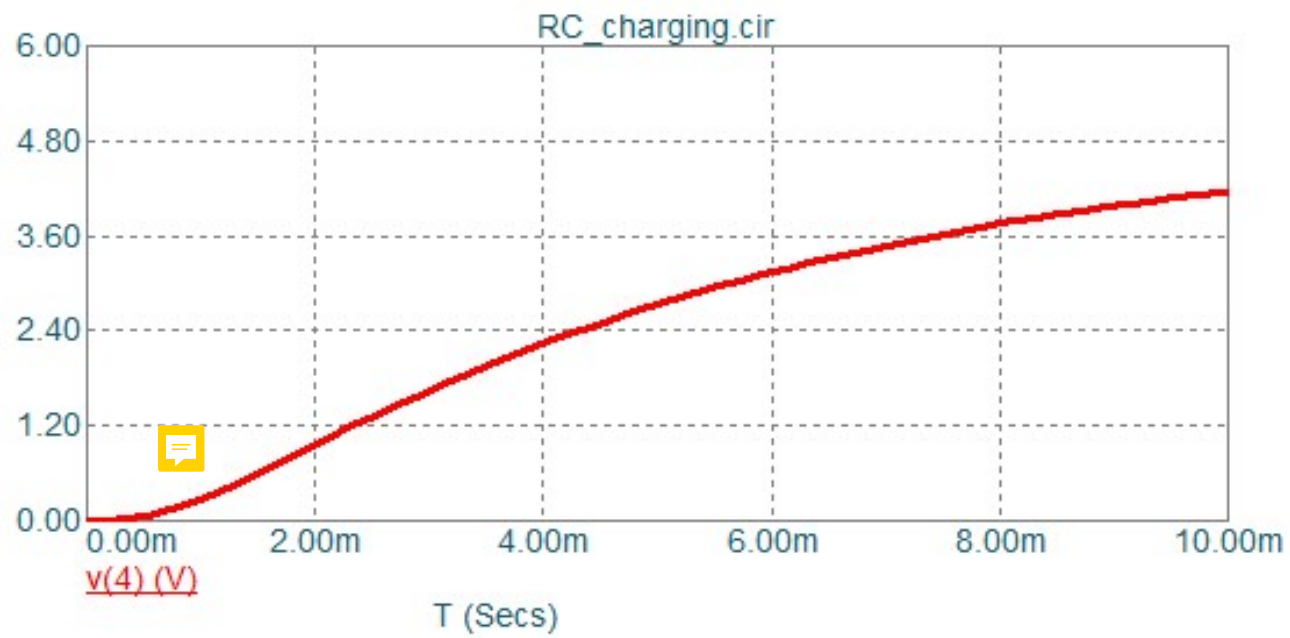
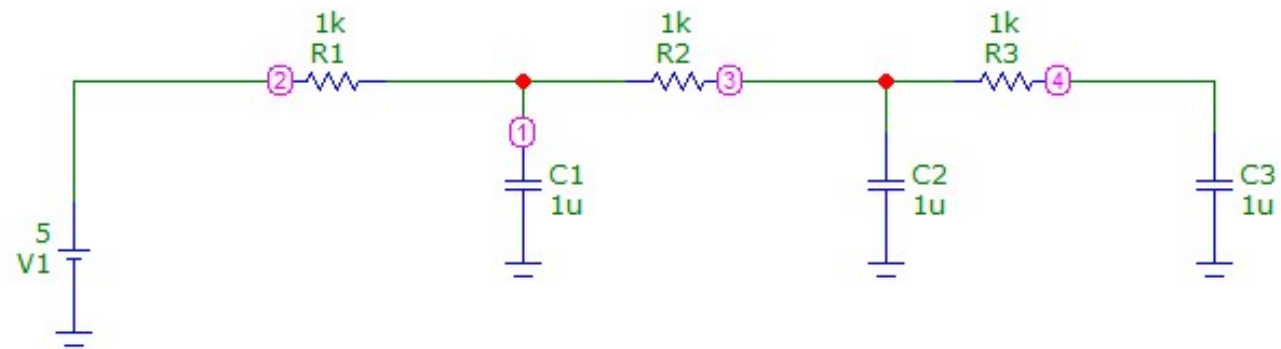
$$i_2 = C_2 \frac{dv_2}{dt} \quad (4)$$

$$R_1 R_2 C_1 C_2 \frac{d^2 v_{C_2}}{dt^2} + (R_1 C_1 + R_1 C_2 + R_2 C_2) \frac{dv_{C_2}}{dt} + v_{C_2} = V_s$$

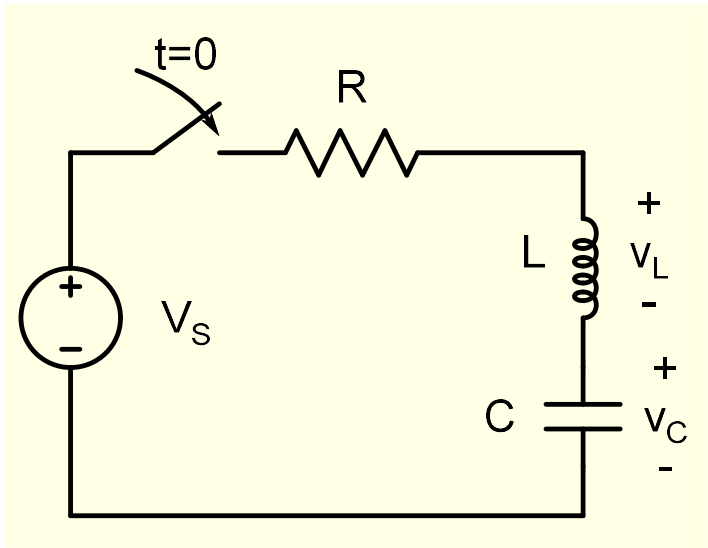
$$v_{C_2}(t) = K_0 + K_1 e^{s_1 t} + K_2 e^{s_2 t}$$



Zoomed



Series RLC Circuit



$$V_S = I \times R + L \frac{dI}{dt} + V_C$$

$$I = C \frac{dV_C}{dt}$$

$$V_S = C \frac{dV_C}{dt} \times R + LC \frac{d^2V_C}{dt^2} + V_C$$

$$\frac{d^2V_C}{dt^2} + \frac{R}{L} \times \frac{dV_C}{dt} + \frac{V_C}{LC} = \frac{V_S}{LC}$$

$$V_C(t) = A \times e^{st}$$

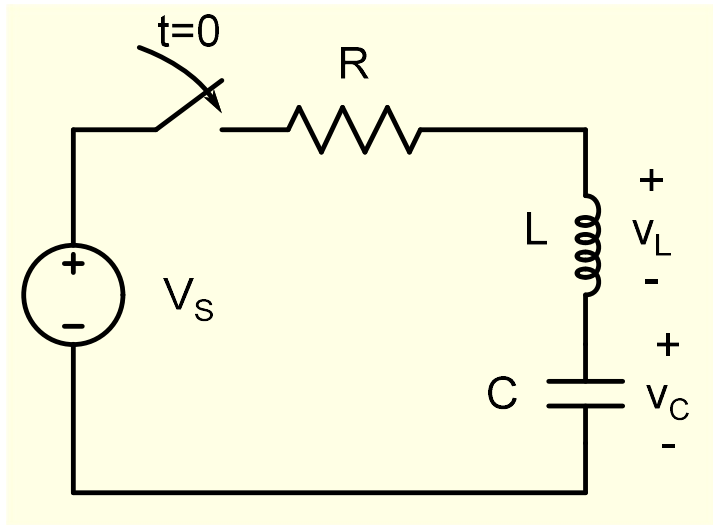
$$As^2e^{st} + \frac{R}{L}Ase^{st} + \frac{A}{LC}e^{st} = 0$$

$$s^2 + \frac{R}{L}s + \frac{1}{LC} = 0 \quad s = -\frac{R}{2L} \pm \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}}$$

$$\omega_0 = \frac{1}{\sqrt{L \times C}}$$

$$Q = \frac{\omega_0 L}{R}$$

$$\frac{s}{\omega_0} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1}$$

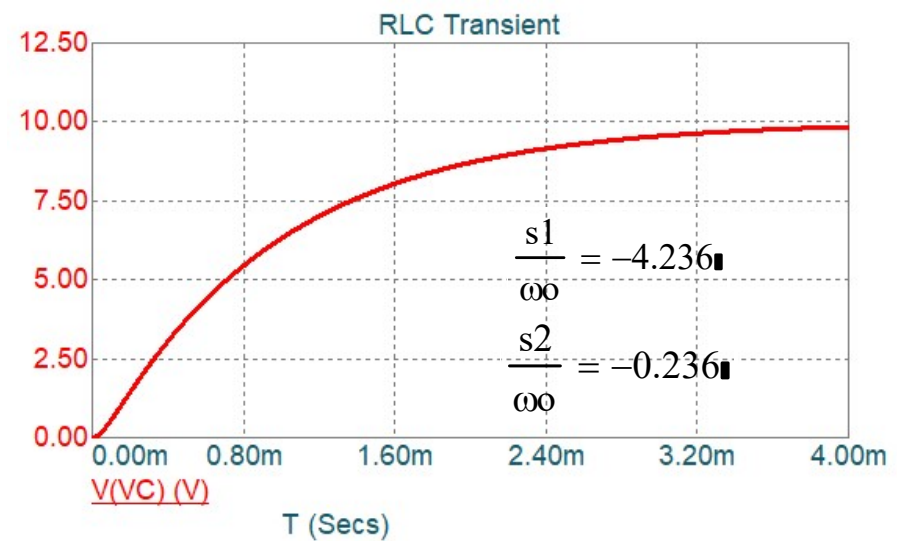
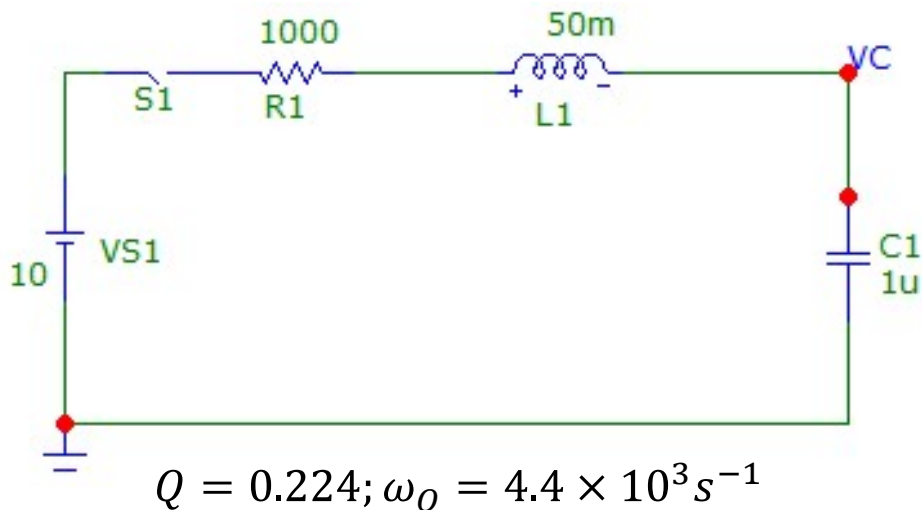


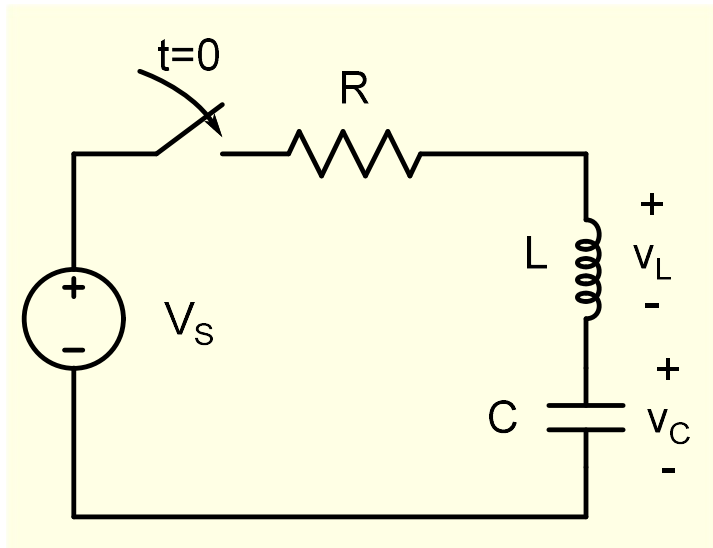
$$V_C(t) = V_S + A \times e^{s_1 t} + B \times e^{s_2 t}$$

$$\omega_o = \frac{1}{\sqrt{L \times C}} \quad Q = \frac{\omega_o L}{R} \quad \frac{s}{\omega_o} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1}$$

$$\frac{d^2 V_C}{dt^2} + \frac{R}{L} \times \frac{dV_C}{dt} + \frac{V_C}{LC} = \frac{V_S}{LC}$$

Case-1 $Q < 0.5 \Rightarrow s_{1,2}$ are real and negative





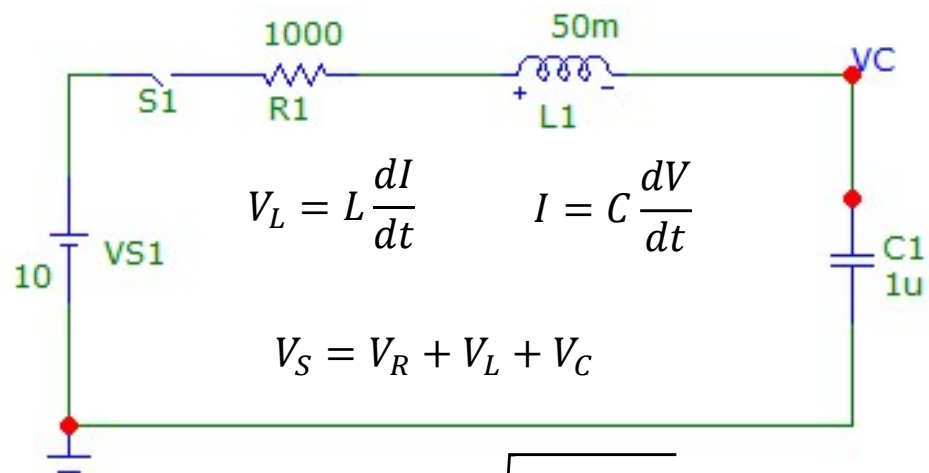
$$V_C(t) = V_S + A \times e^{s_1 t} + B \times e^{s_2 t}$$

$$\omega_o = \frac{1}{\sqrt{L \times C}} \quad Q = \frac{\omega_o L}{R} \quad \frac{s}{\omega_o} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1}$$

$$V_C(0) = V_S + A + B = 0 \quad (1)$$

$$I_C(t) = C \frac{dV_C(t)}{dt} = C\{V_S + As_1 \times e^{s_1 t} + Bs_2 \times e^{s_2 t}\}$$

$$I_C(0) = 0 = C\{V_S + As_1 + Bs_2\} \quad (2)$$

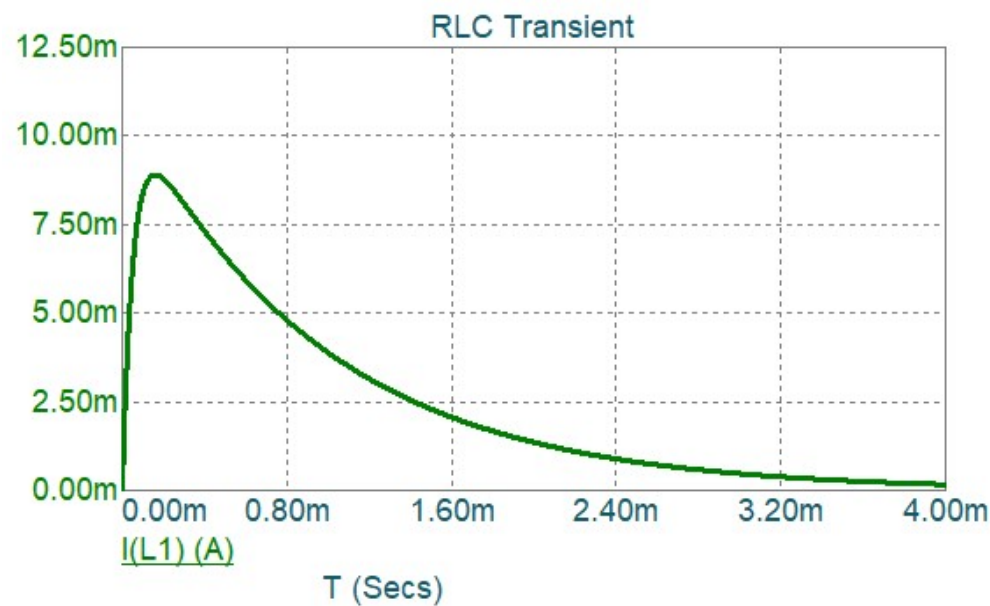
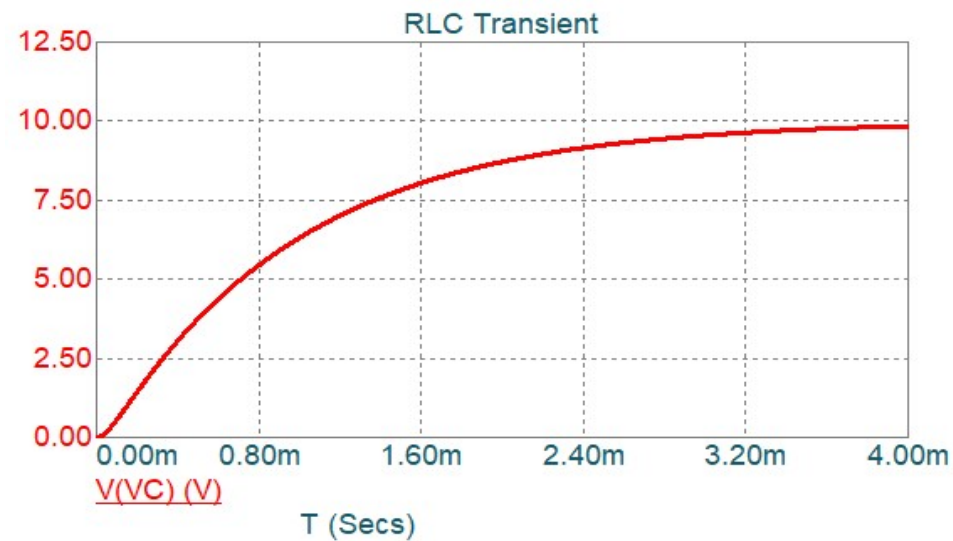


$$\frac{s}{\omega_0} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1}$$

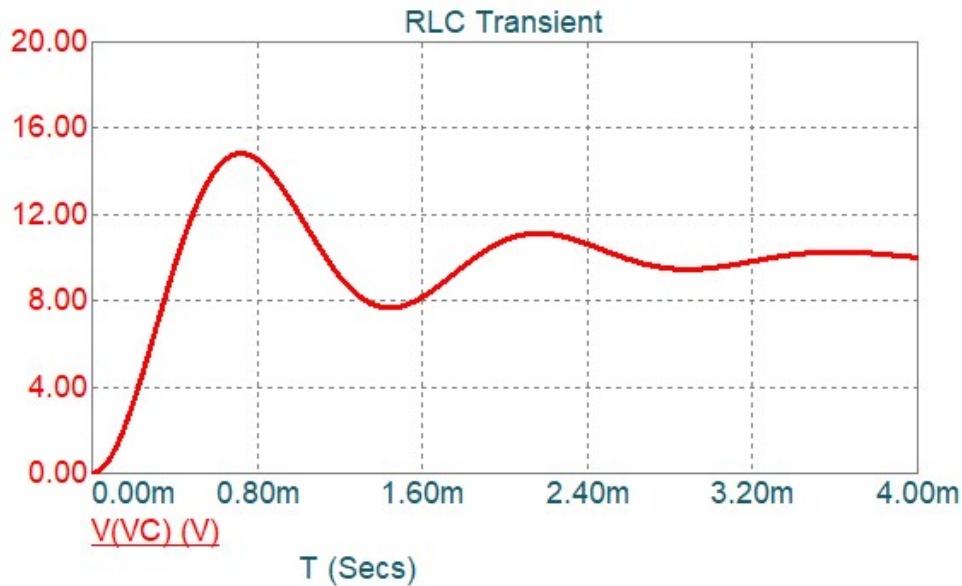
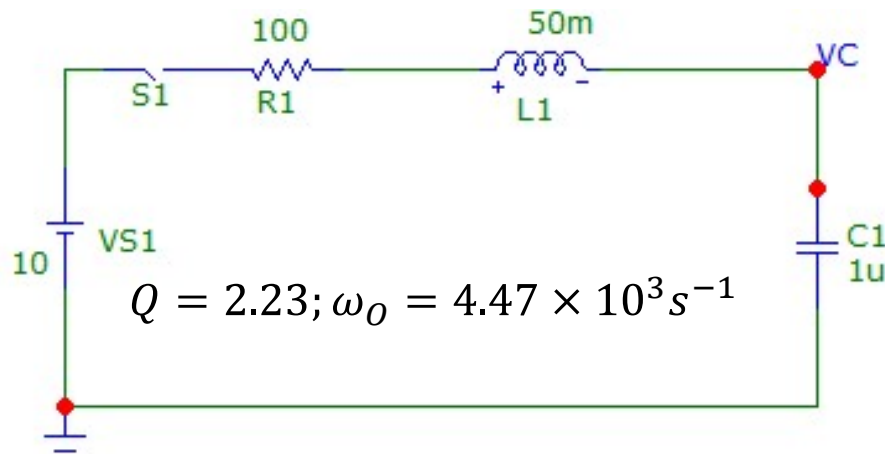
$$V_C(t) = 10 + 0.59 \times e^{-1.9 \times 10^4 t} - 10.59 \times e^{-10^3 t}$$

Q < 0.5 Overdamped Case

Case-2 : Q = 0.5 critically damped Case



Case-3 underdamped case : $Q > 0.5$



$$\frac{s}{\omega_o} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1} \quad \omega_o = \frac{1}{\sqrt{L \times C}} \quad Q = \frac{\omega_o L}{R}$$

$$s = -\frac{\omega_o}{2Q} \pm j\omega_o \sqrt{1 - \frac{1}{4Q^2}}$$

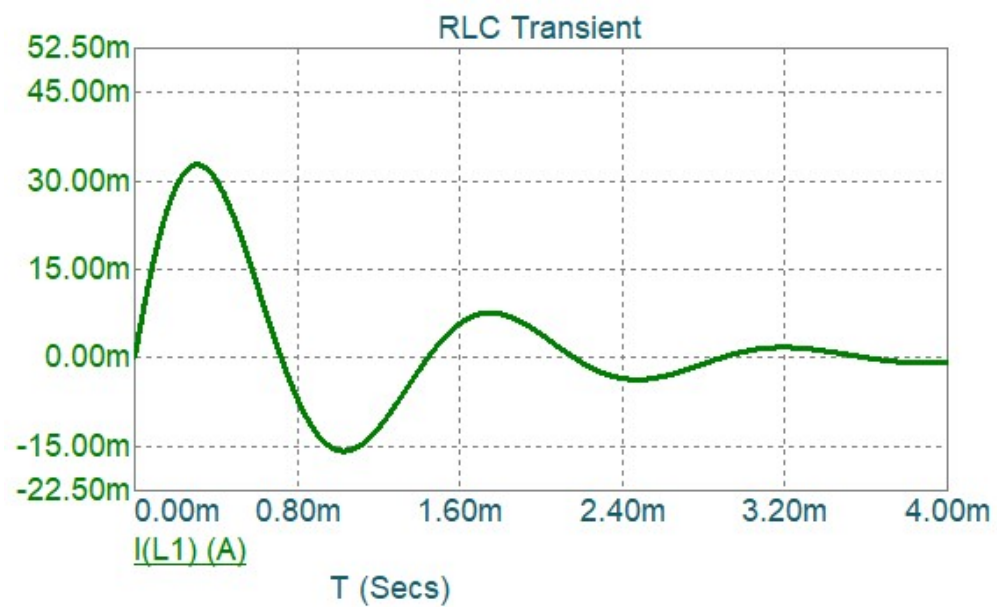
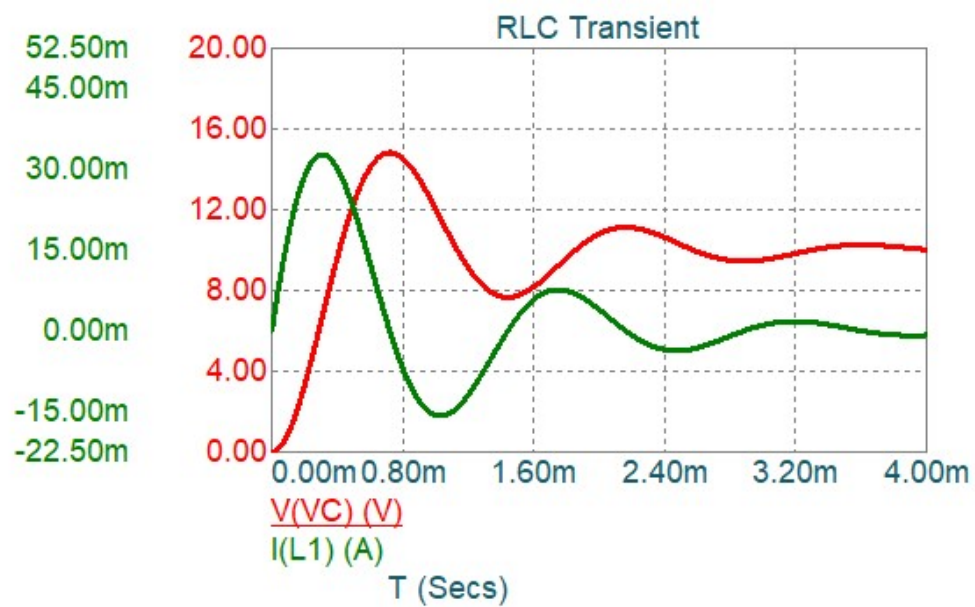
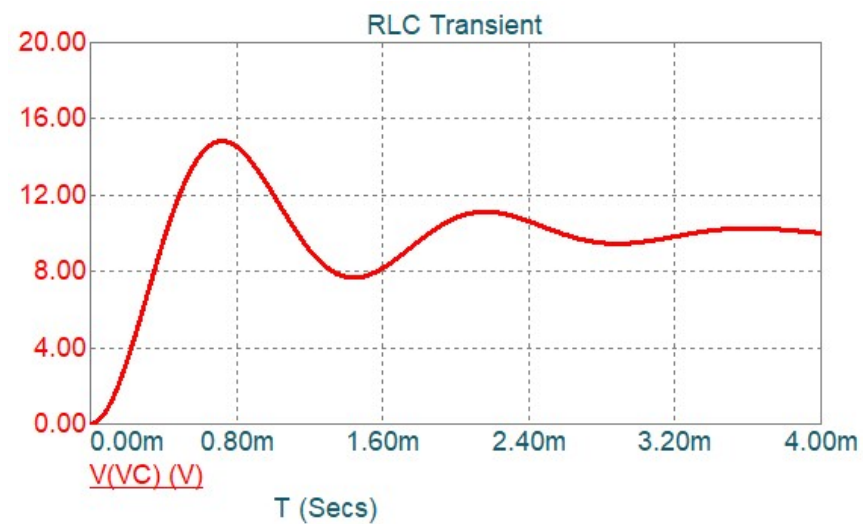
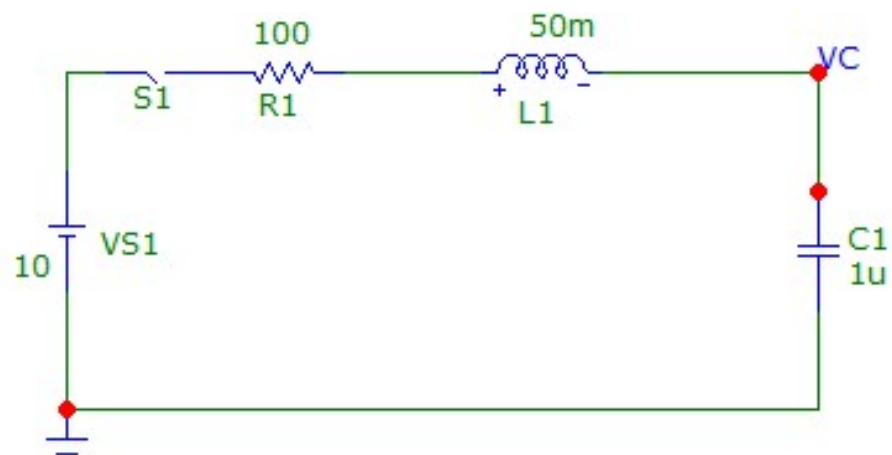
$\Rightarrow s_{1,2}$ have real and imaginary components

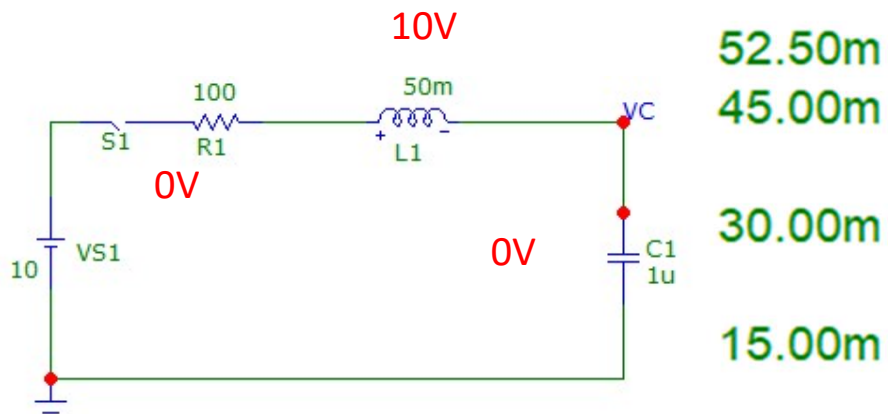
$$s_1 = -1 \times 10^3 - 4.359i \times 10^3$$

$$s_2 = -1 \times 10^3 + 4.359i \times 10^3$$

$$V_C(t) = 10 - e^{-10^3 t} \times (10 \times \cos(\omega_1 t) + 2.3 \times \sin(\omega_1 t))$$

$$\omega_1 = 4.36 \times 10^3 s^{-1}$$

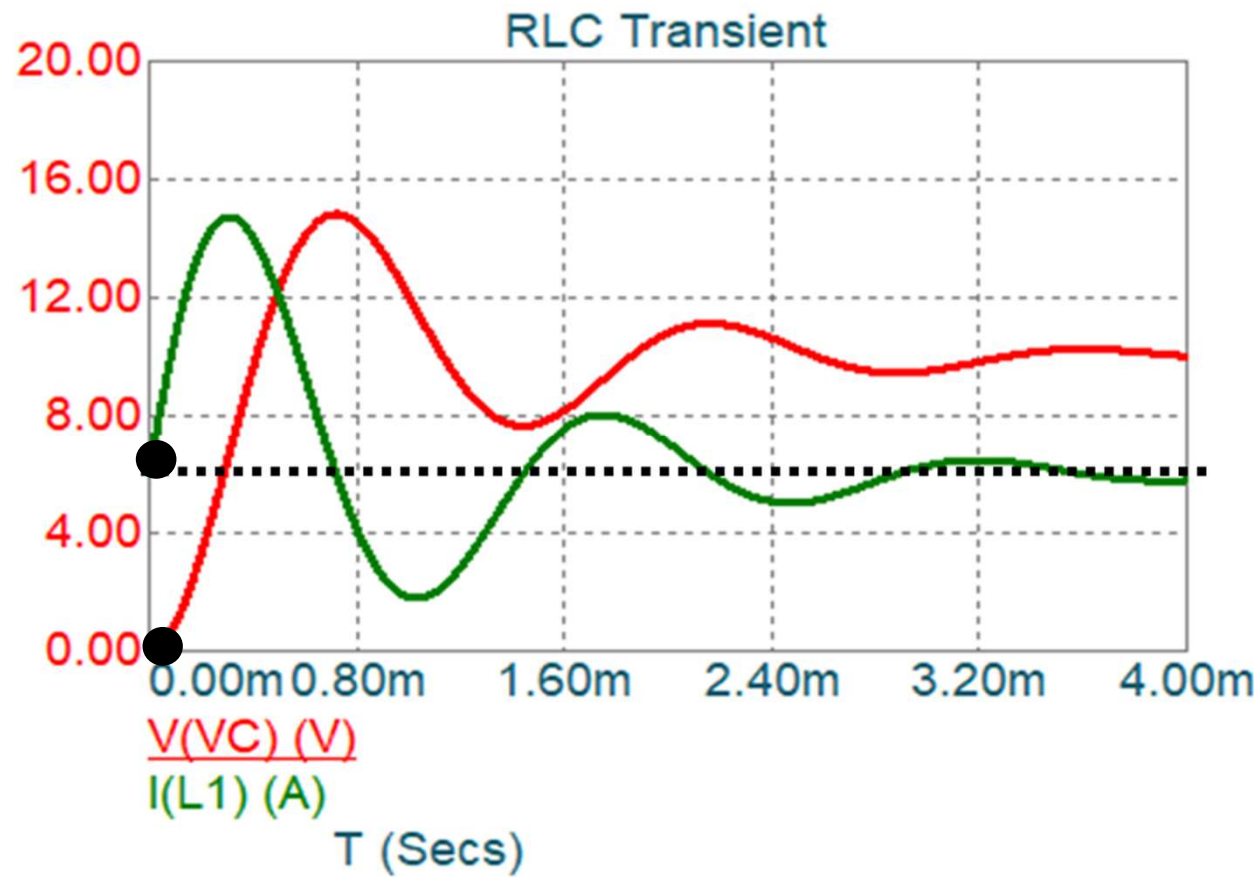


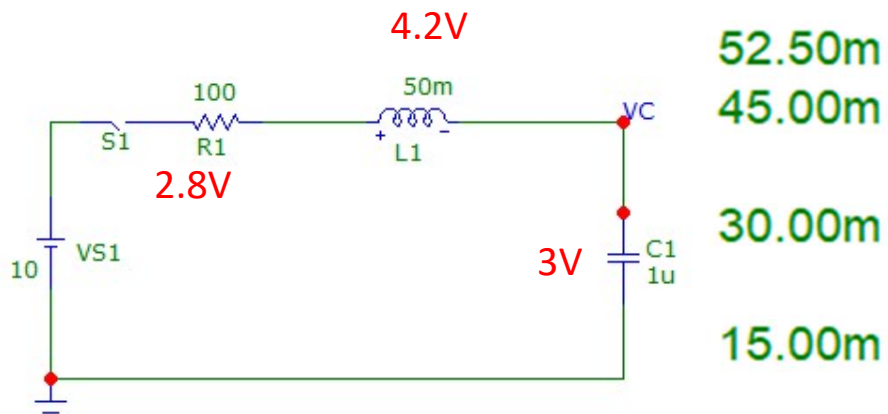


$$V_L = L \frac{dI}{dt}$$

$$I = C \frac{dV}{dt}$$

$$V_S = V_R + V_L + V_C$$

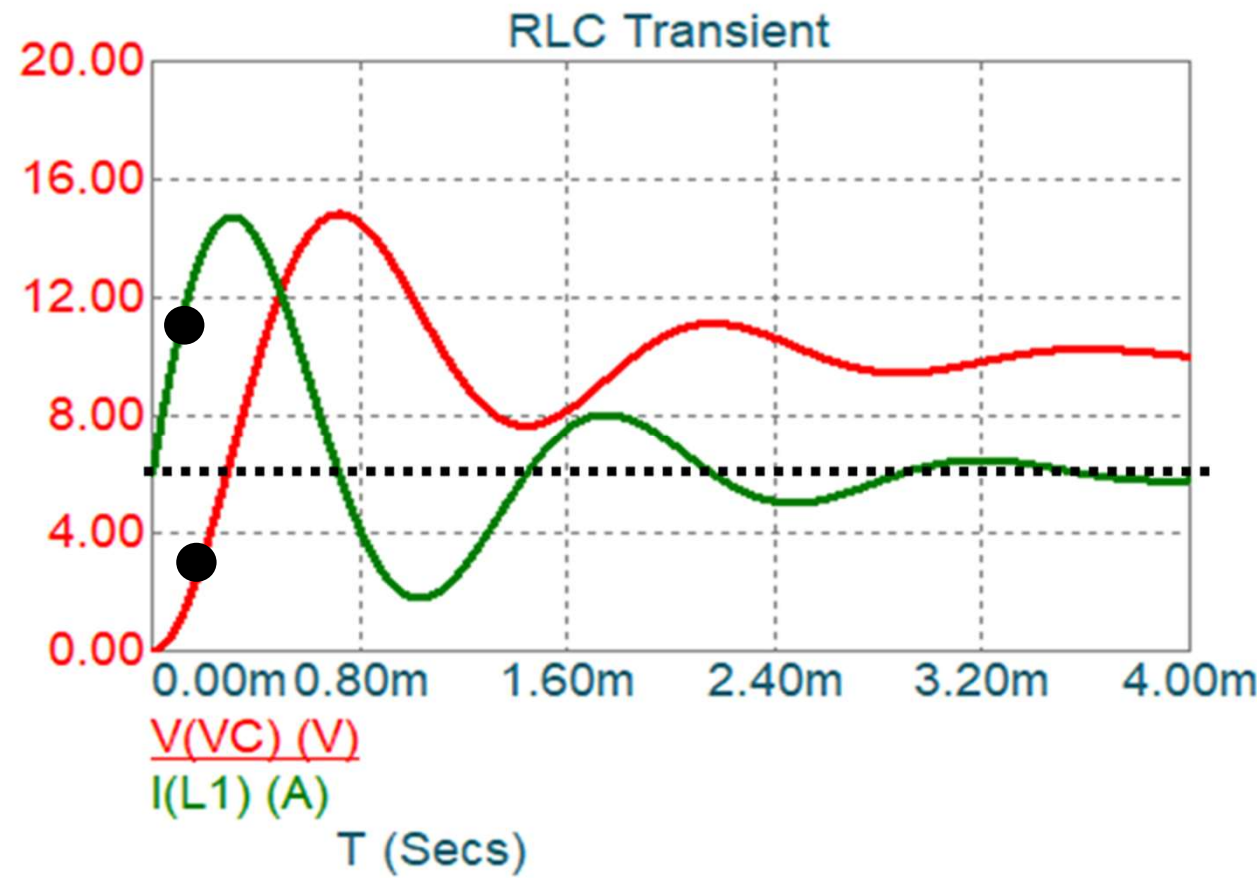


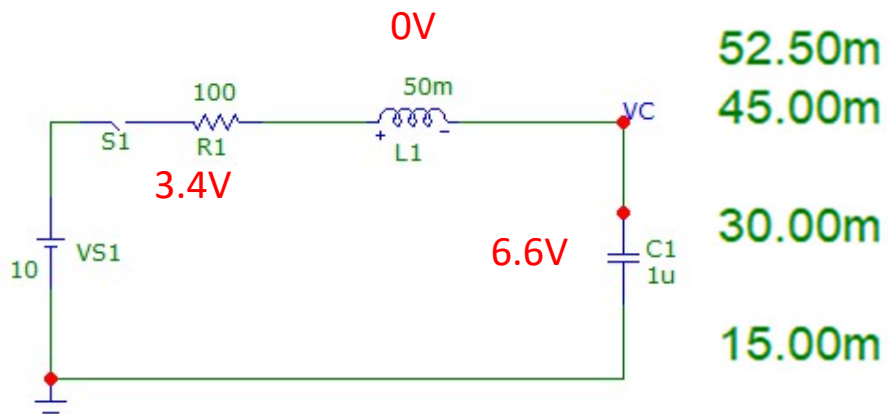


$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

$$V_S = V_R + V_L + V_C$$

52.50m
45.00m
30.00m
15.00m
0.00m
-15.00m
-22.50m

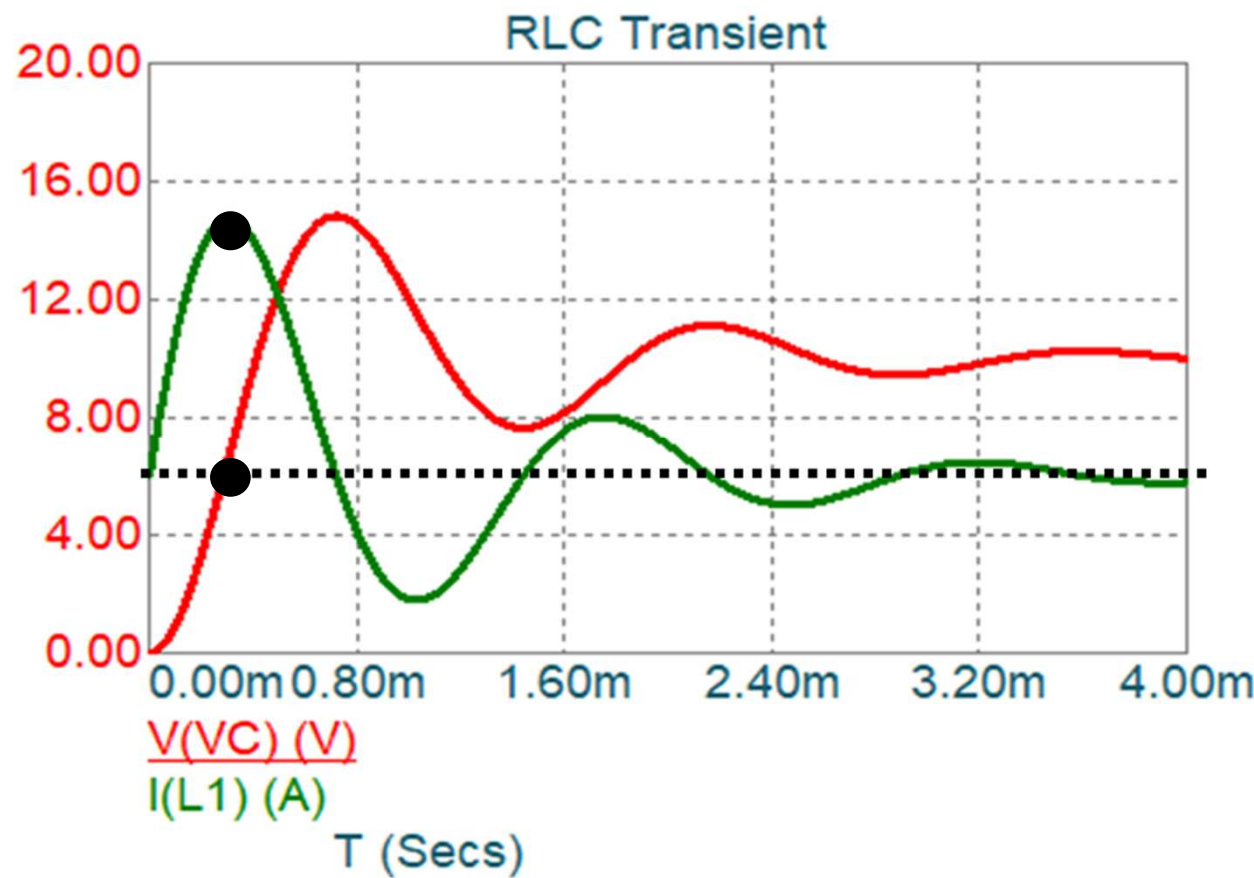


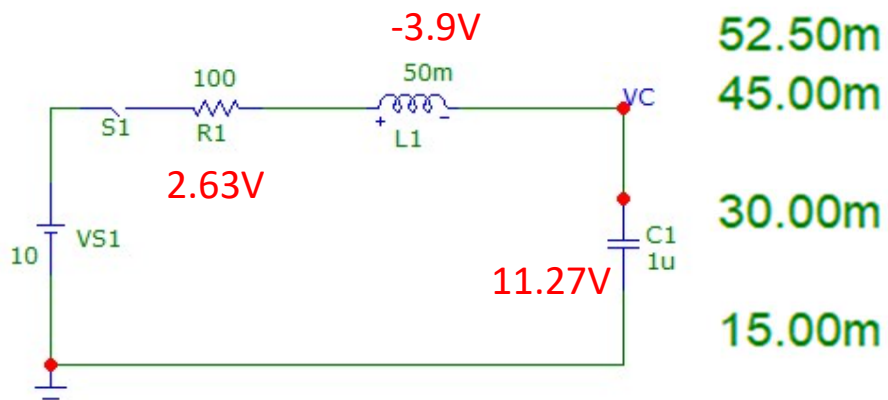


$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

$$V_S = V_R + V_L + V_C$$

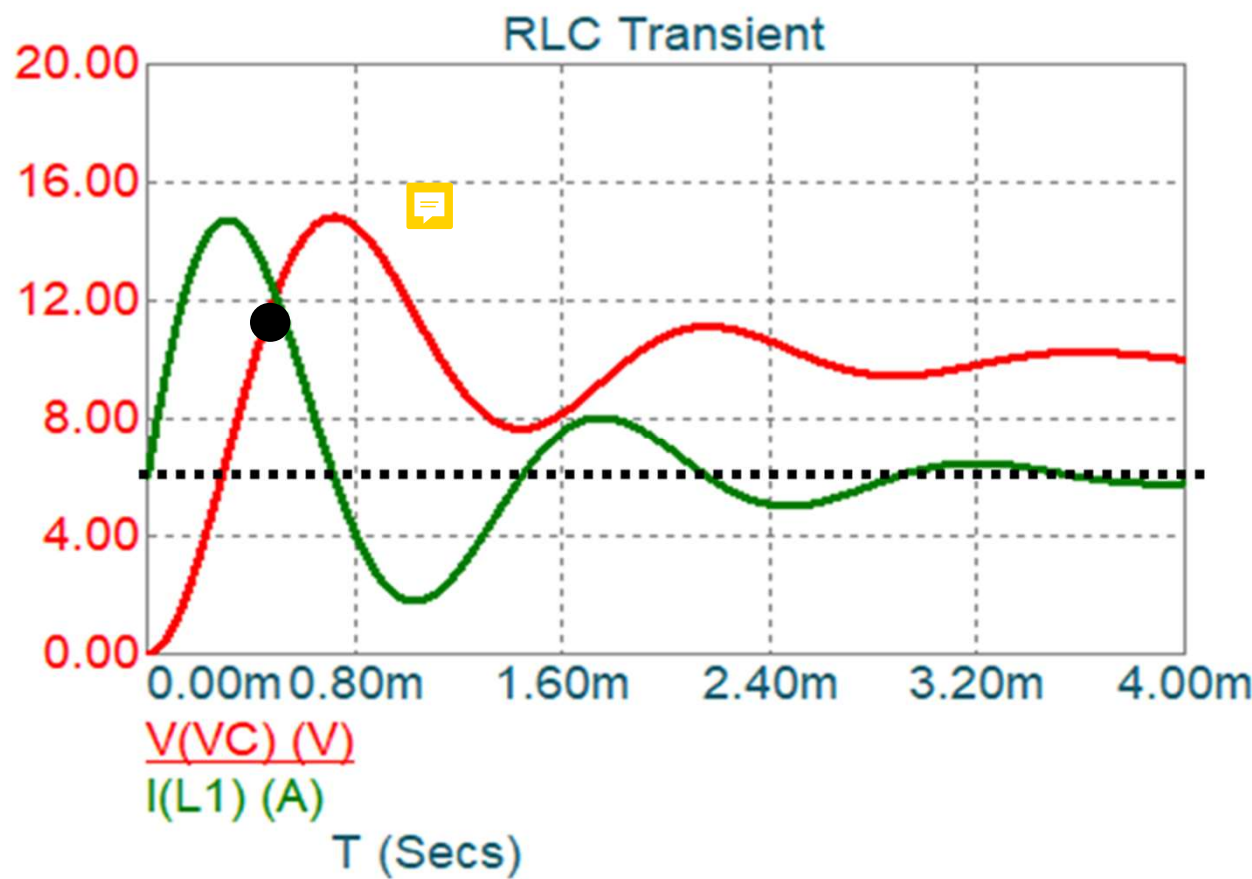
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15.00m
0.00m
-15.00m
-22.50m

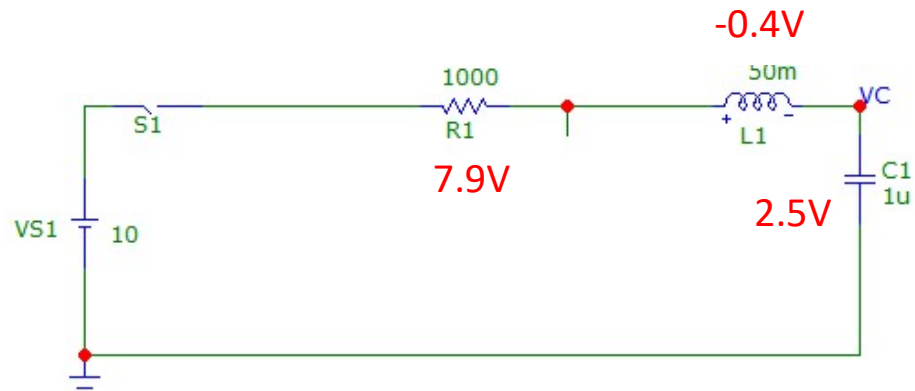




$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

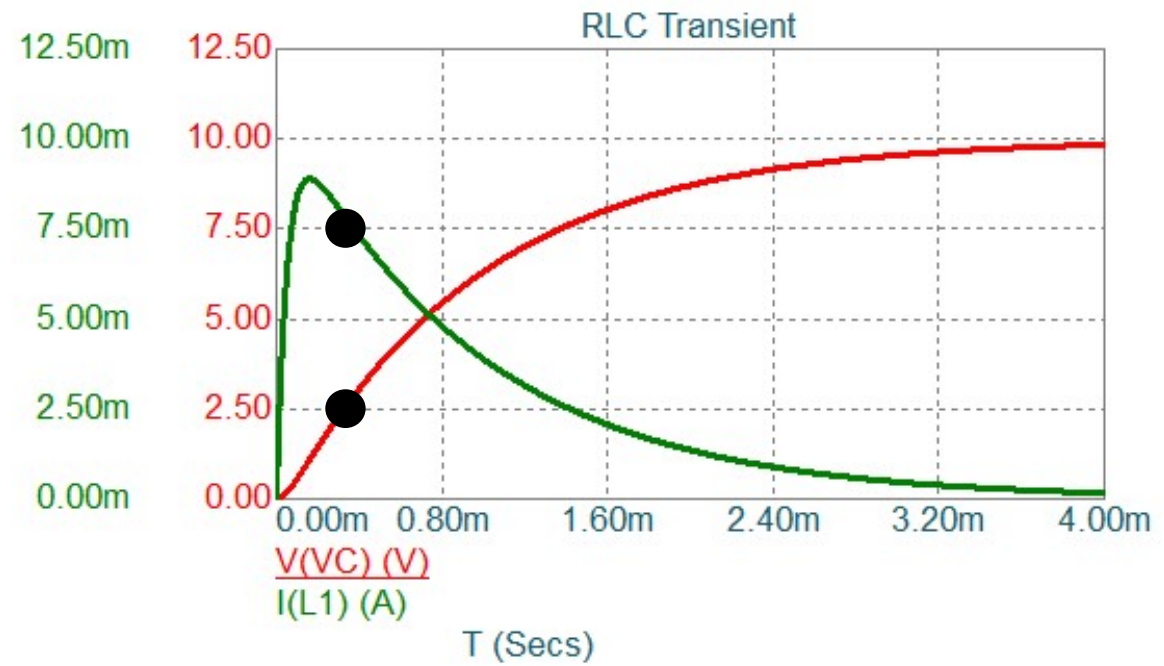
$$V_S = V_R + V_L + V_C$$

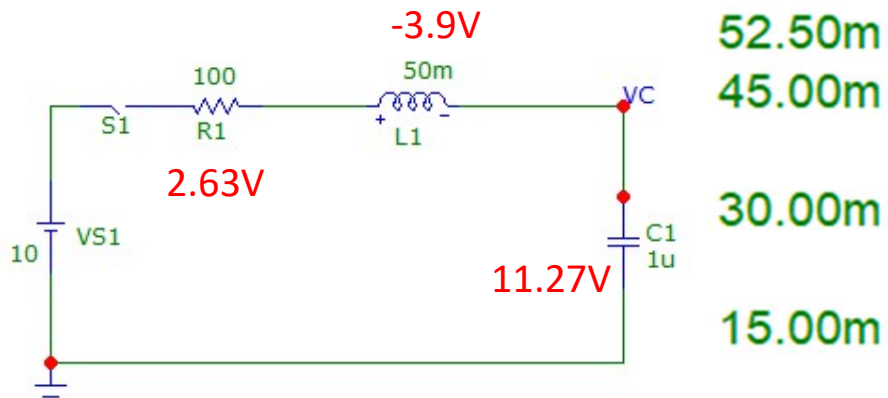




$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

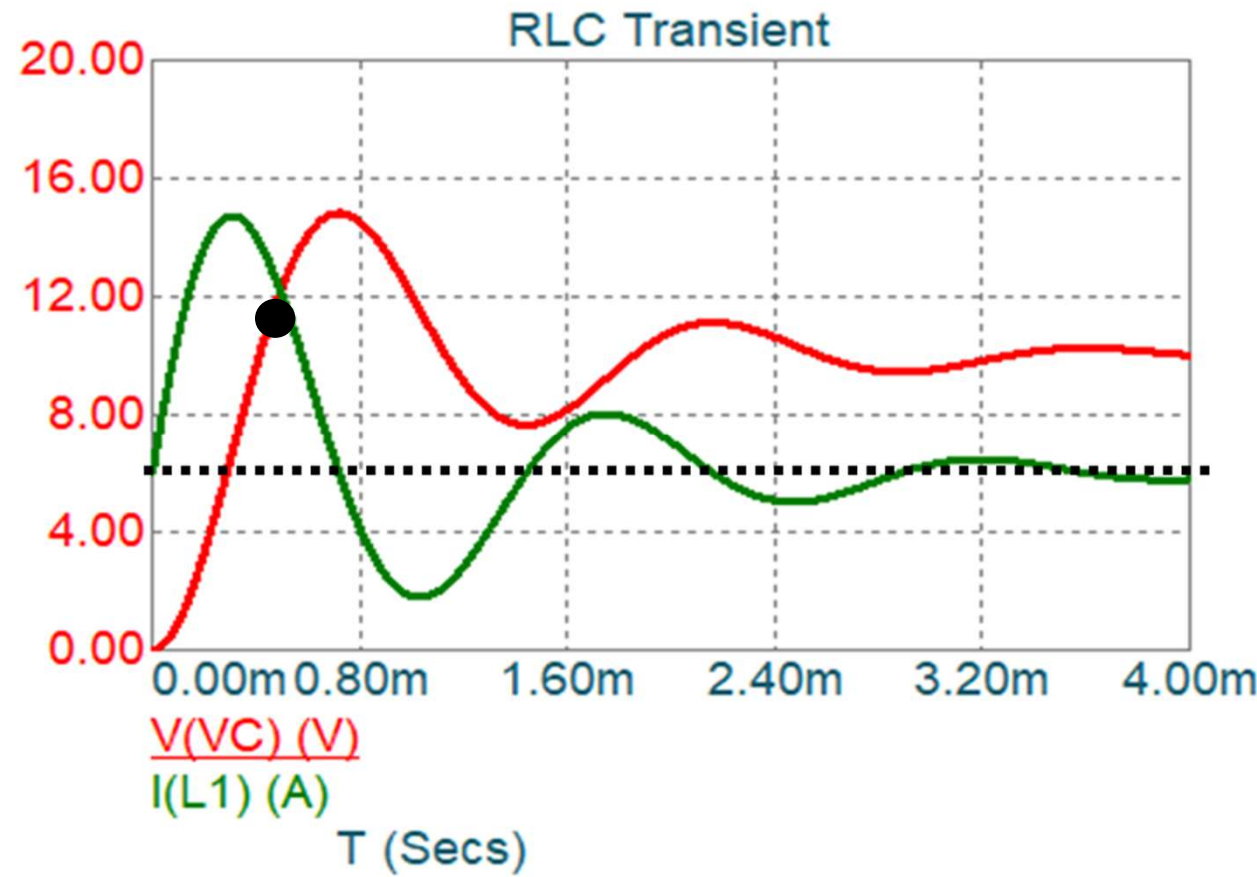
$$V_S = V_R + V_L + V_C$$

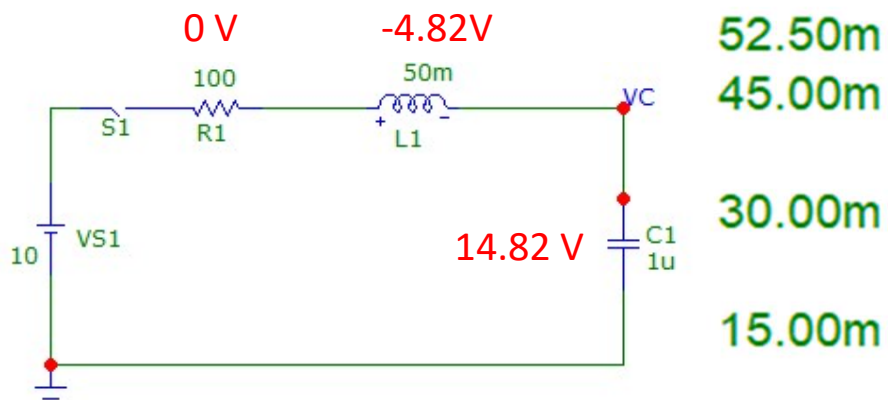




$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

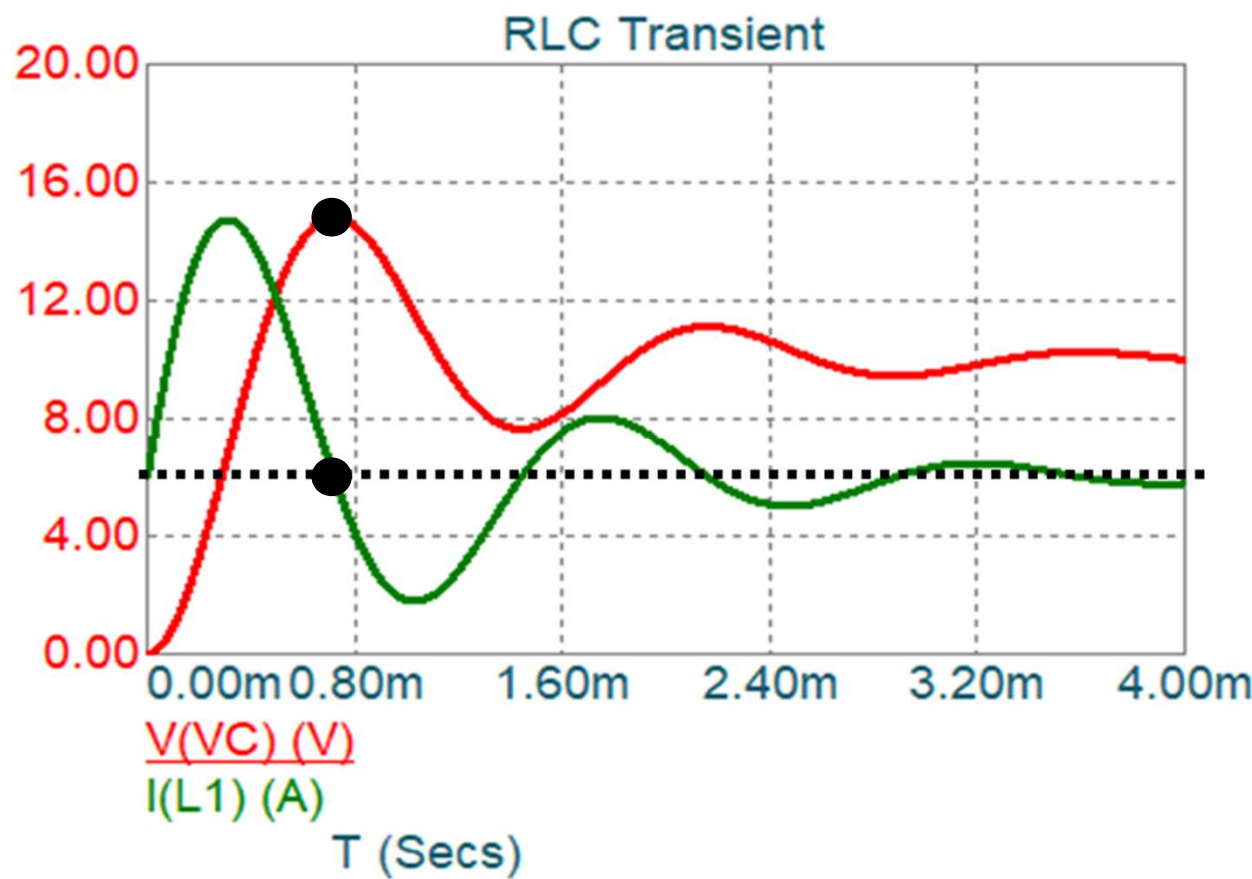
$$V_S = V_R + V_L + V_C$$

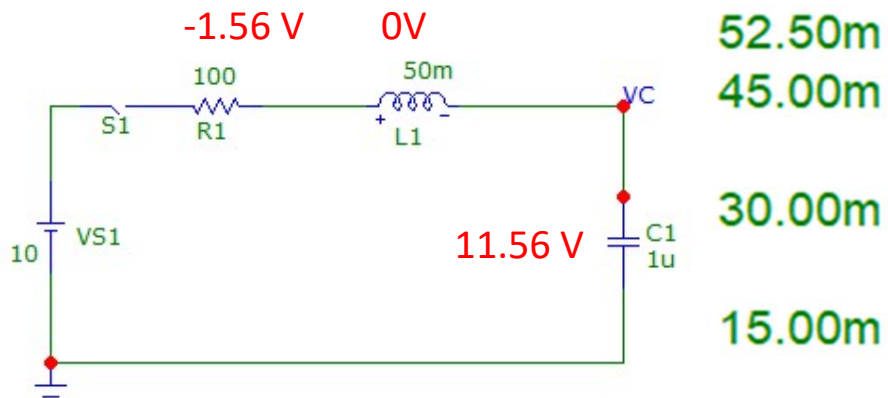




$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

$$V_S = V_R + V_L + V_C$$

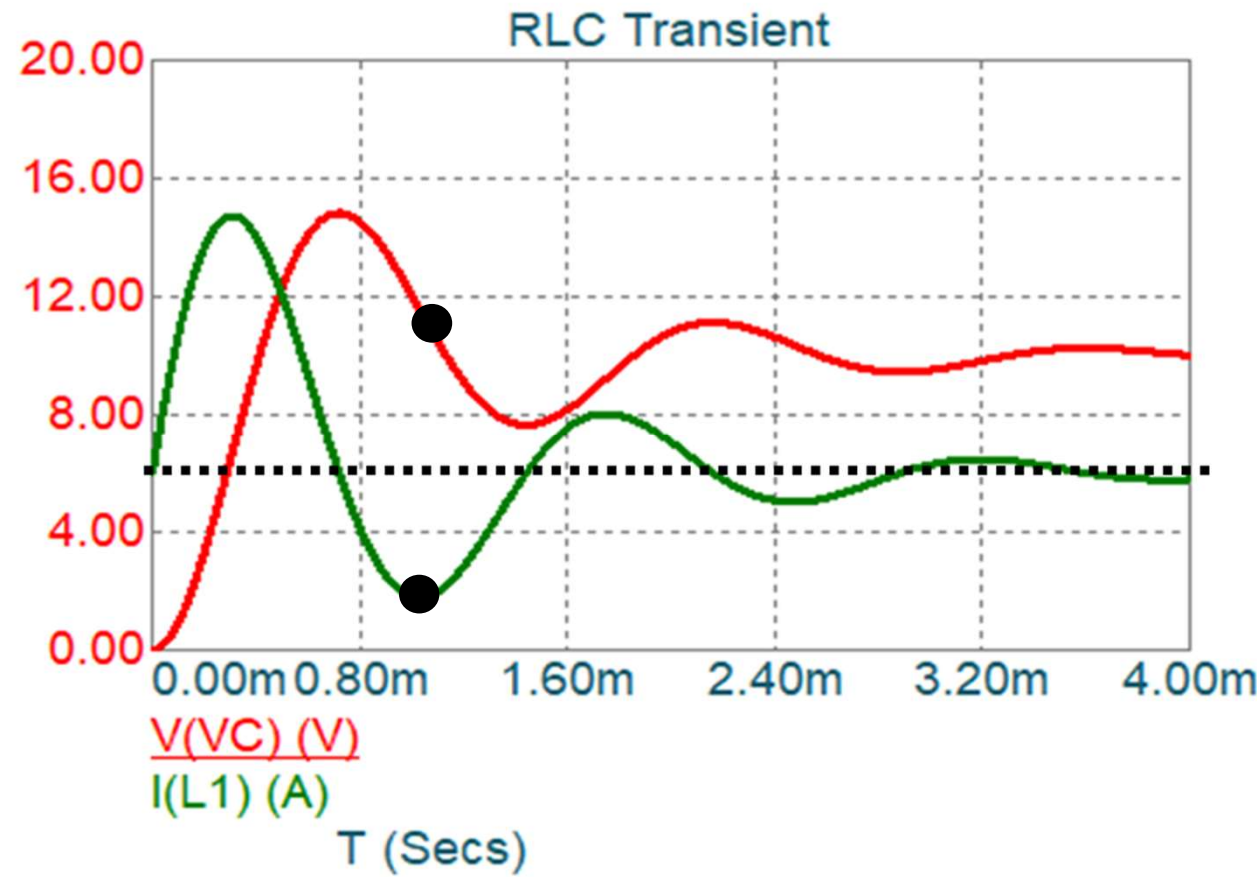


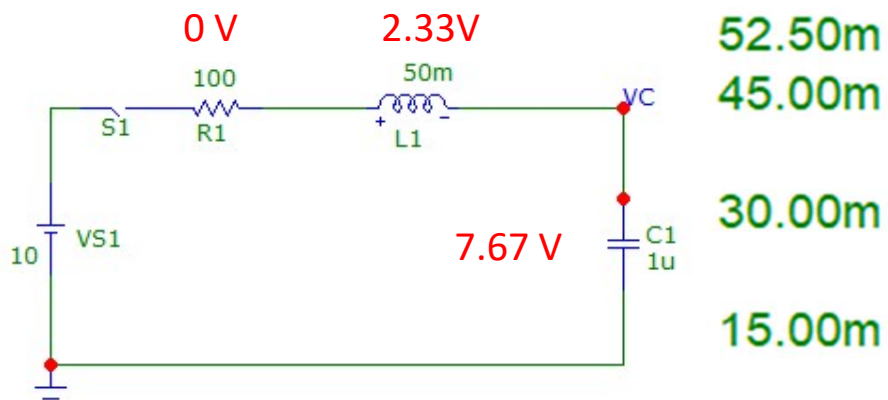


$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

$$V_S = V_R + V_L + V_C$$

52.50m
45.00m
30.00m
15.00m
0.00m
-15.00m
-22.50m





$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

$$V_S = V_R + V_L + V_C$$

45.00m

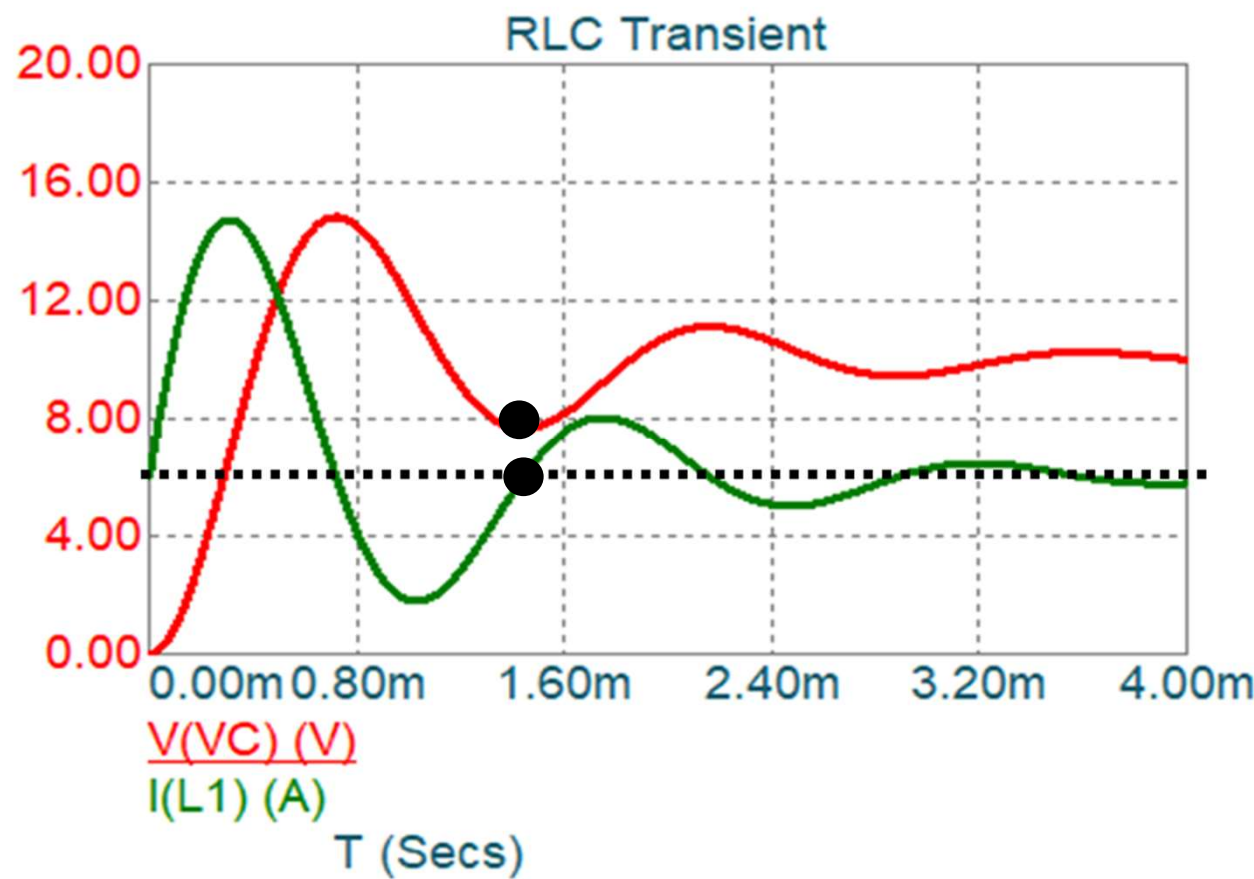
30.00m

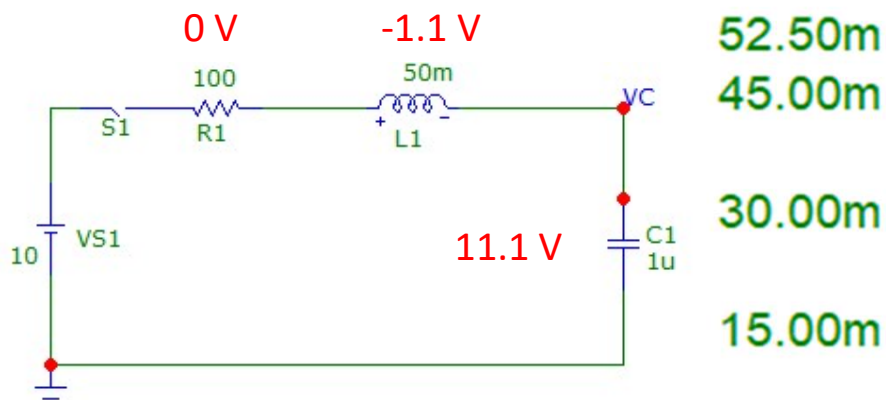
15.00m

0.00m

-15.00m

-22.50m





$$V_L = L \frac{dI}{dt} \quad I = C \frac{dV}{dt}$$

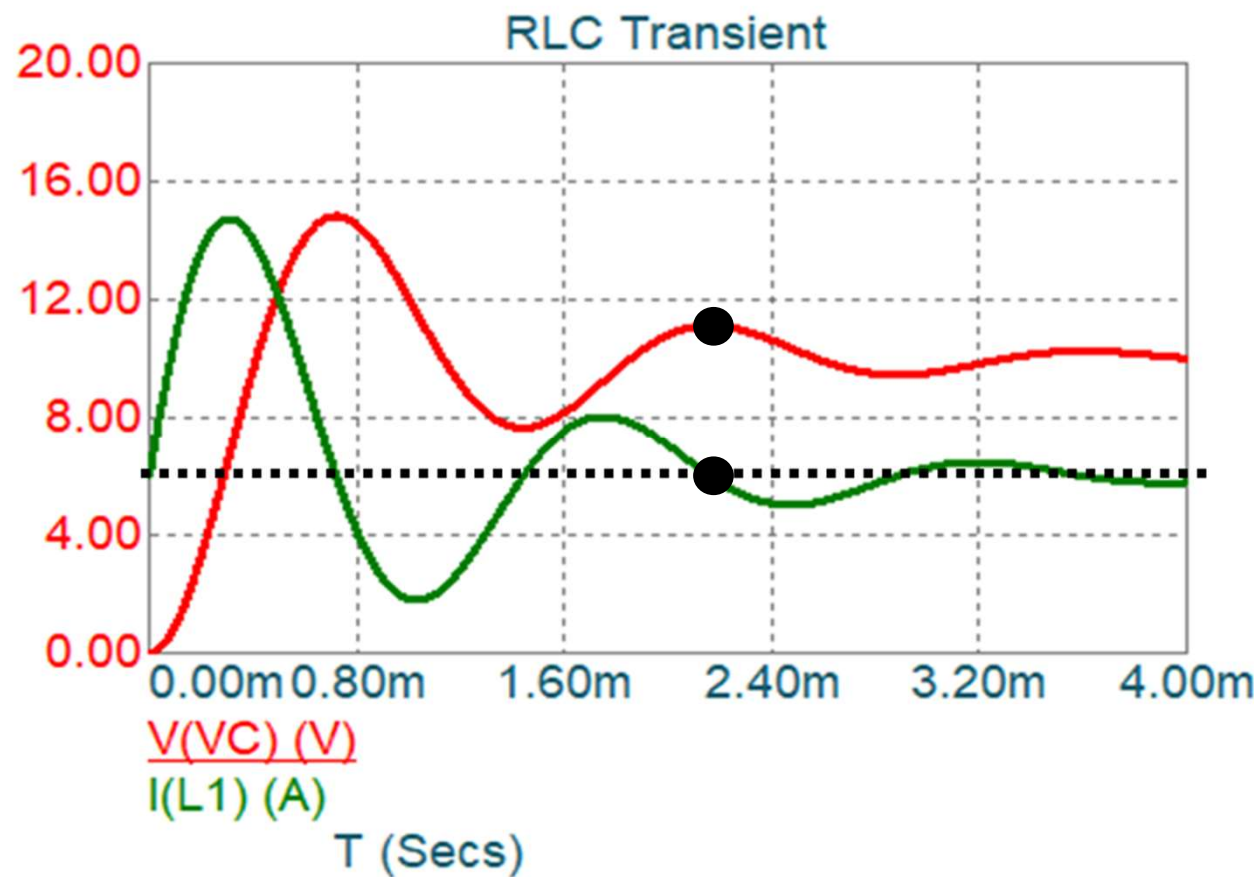
$$V_S = V_R + V_L + V_C$$

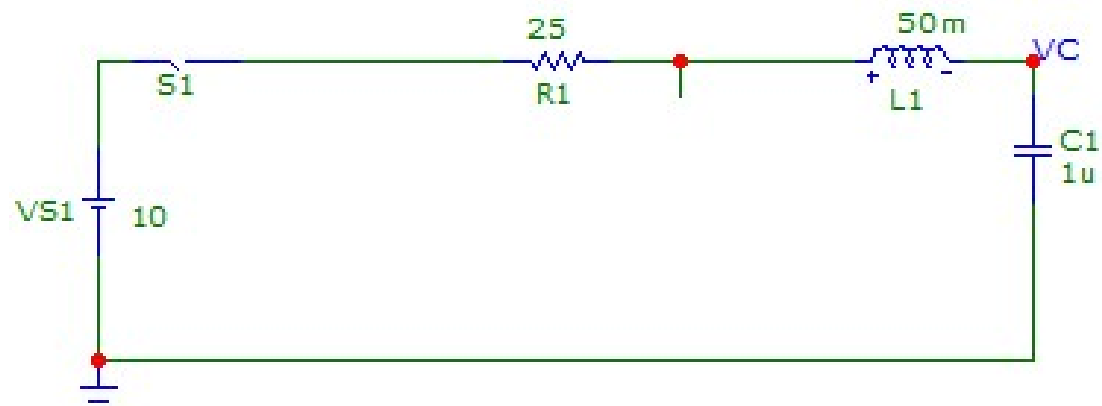
$$V_C(t) = 10 - e^{-10^3 t} \times (10 \times \cos(\omega_1 t) + 2.3 \times \sin(\omega_1 t))$$

$$s = -\frac{\omega_o}{2Q} \pm j\omega_o \sqrt{1 - \frac{1}{4Q^2}}$$

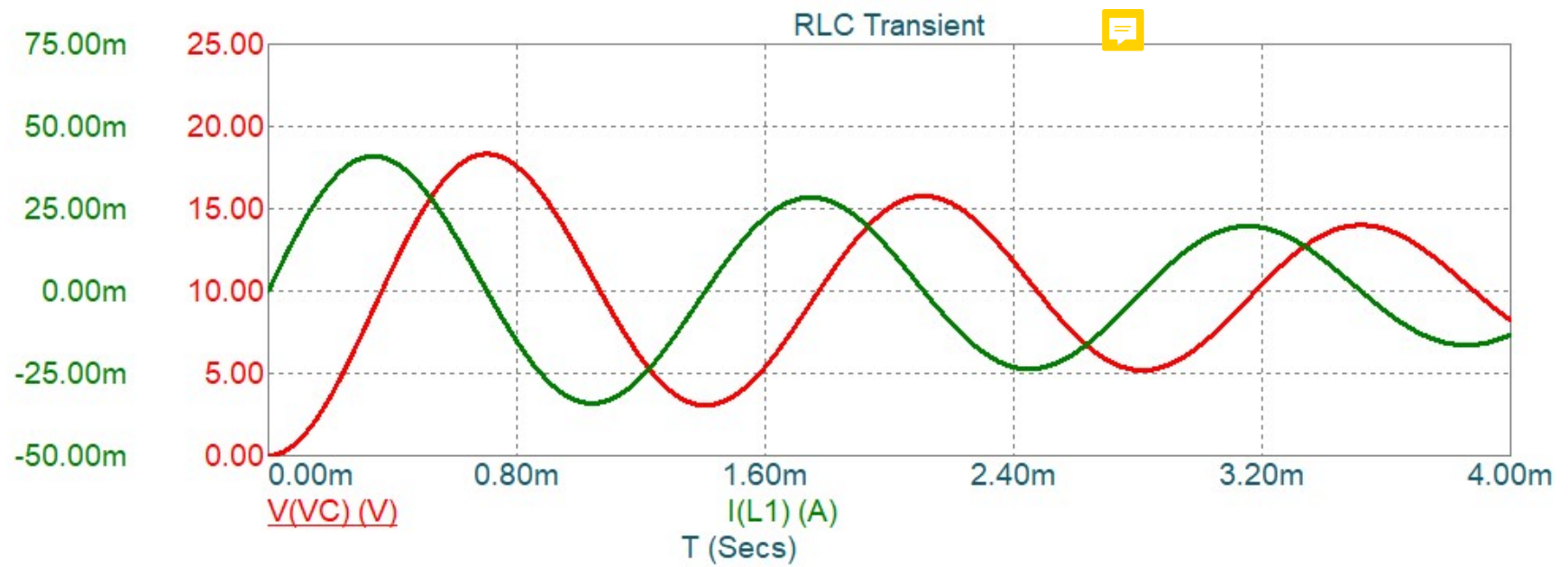
$$Q = \frac{\omega_o L}{R}$$

$$\sim e^{-\frac{R}{2L}t}$$

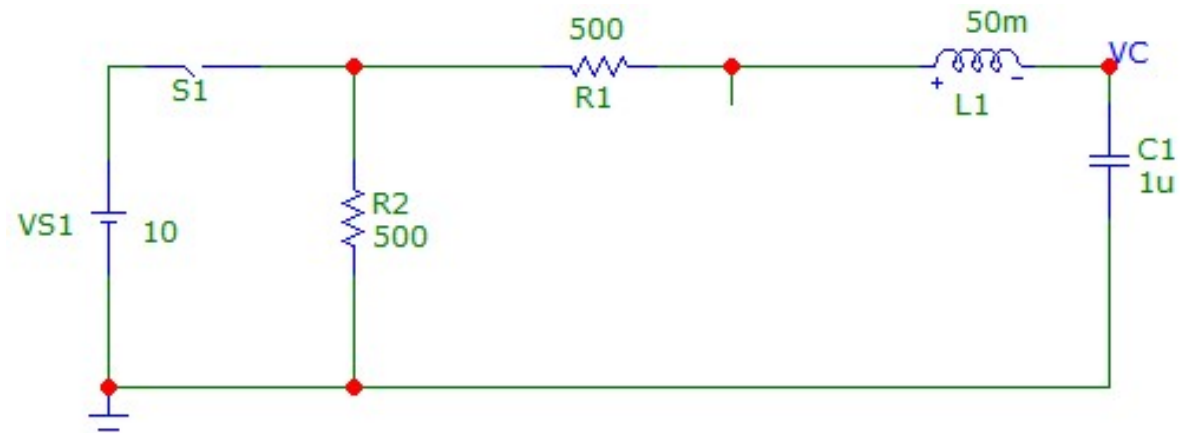




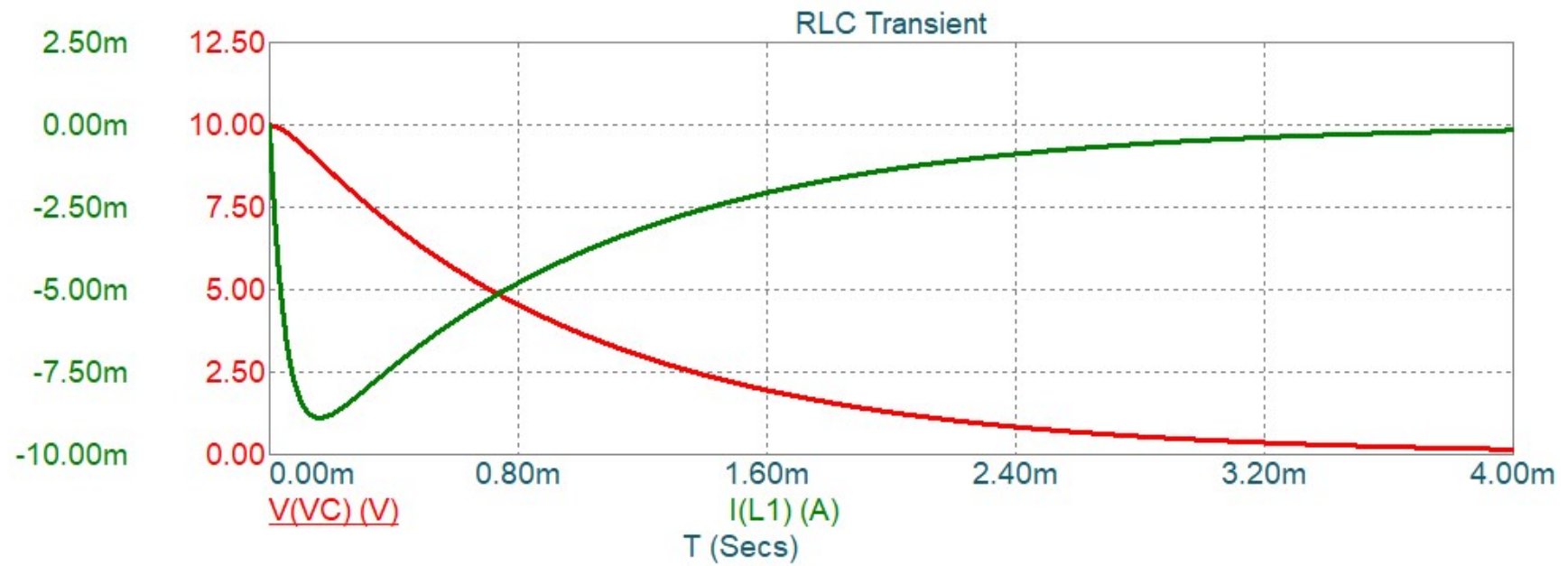
$$Q = 8.92$$

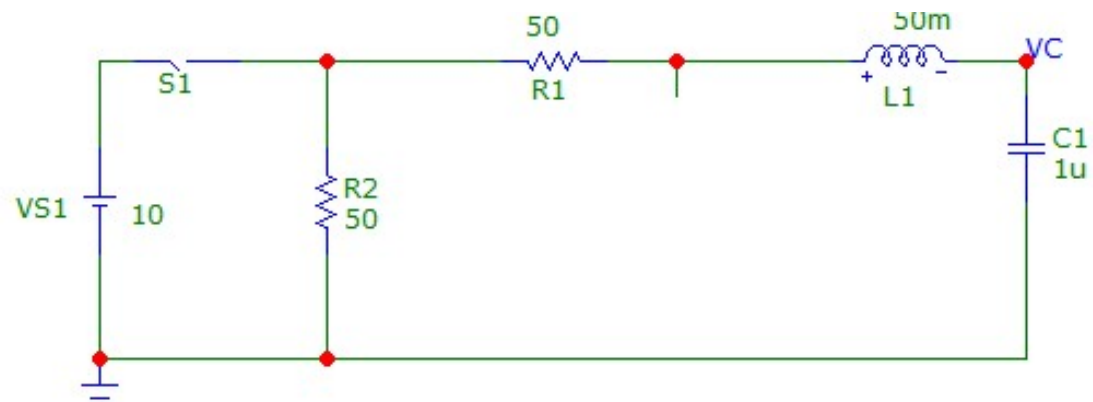


RLC Discharge

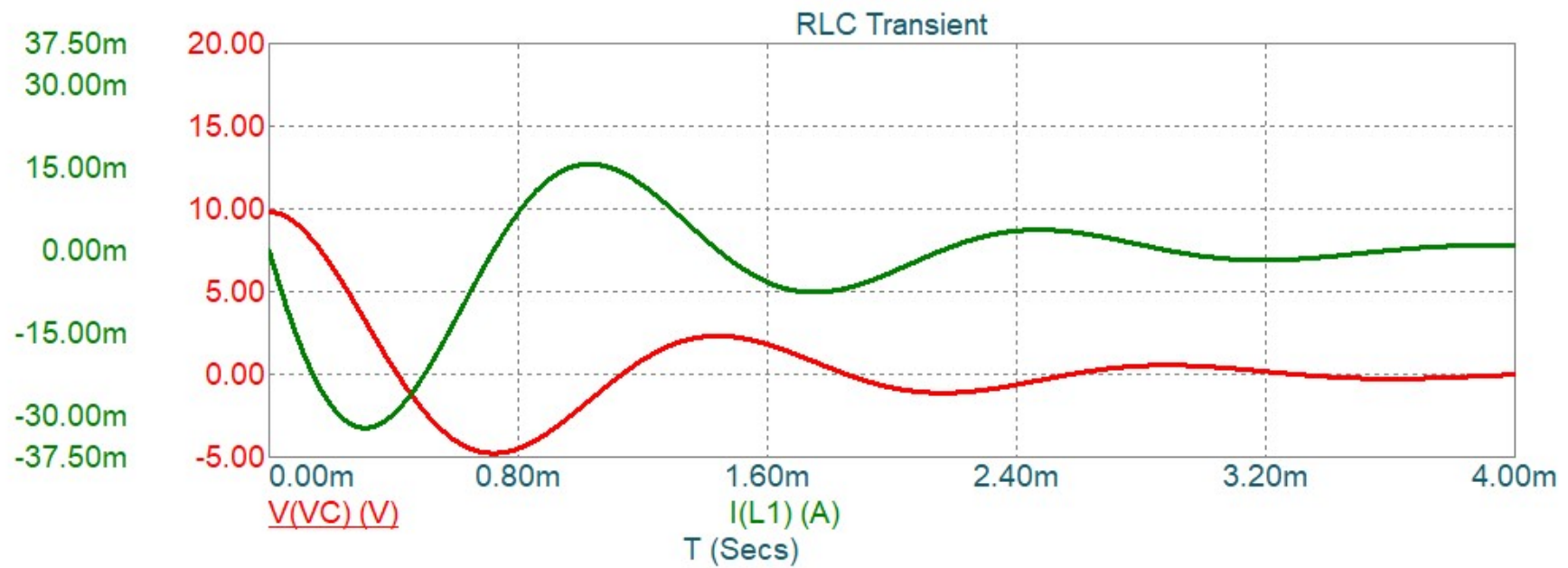


Over-damped Case

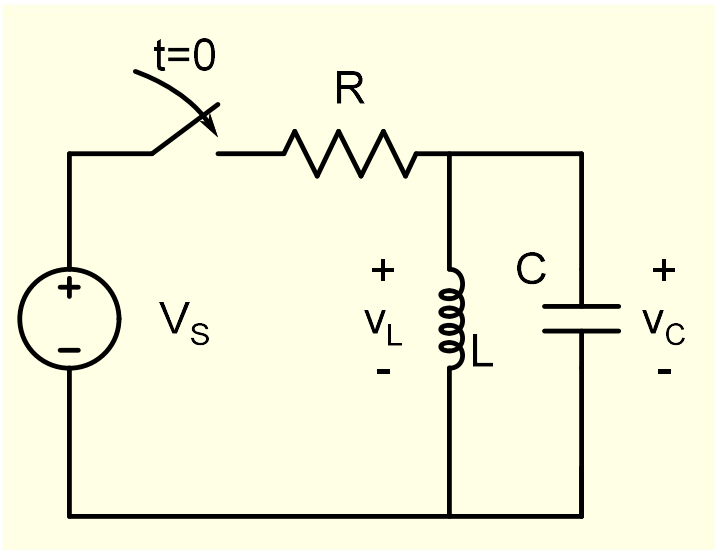




Under-damped Case



Parallel RLC circuit



$$V_S = I \times R + V_L \qquad I = C \frac{dV_C}{dt} + I_L \qquad V_L = L \frac{dI_L}{dt}$$

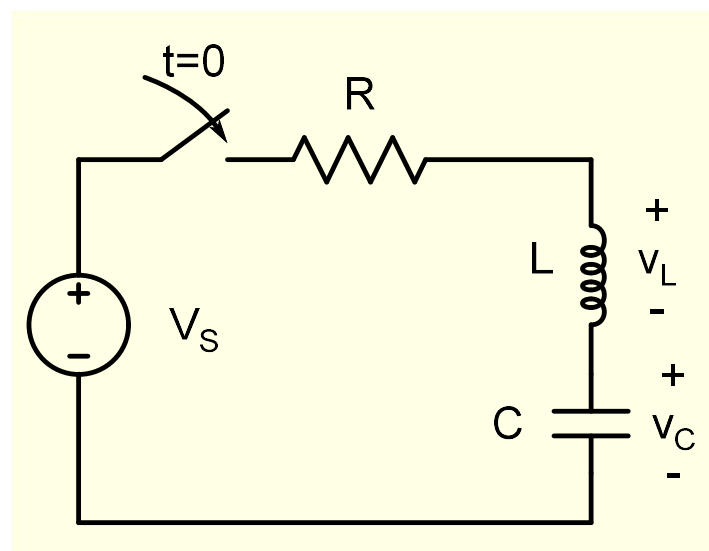
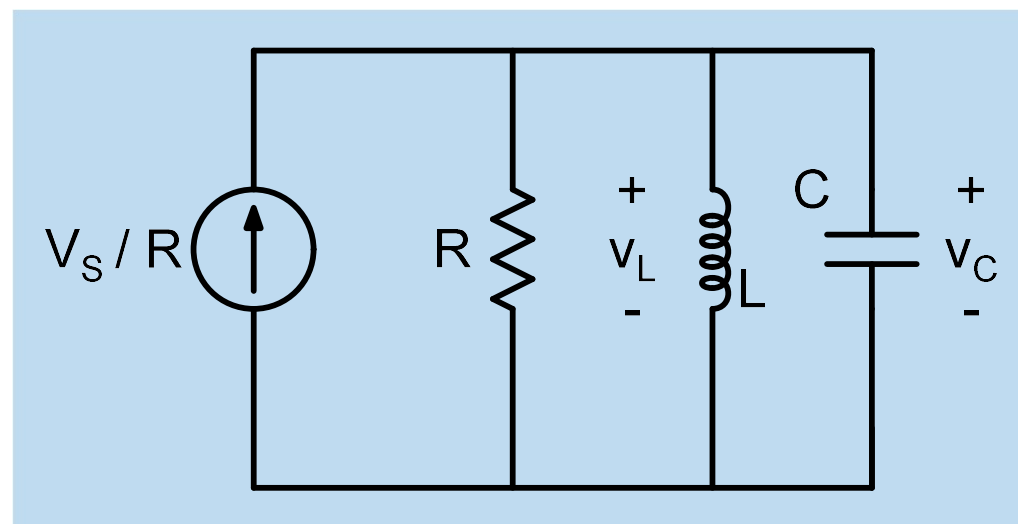
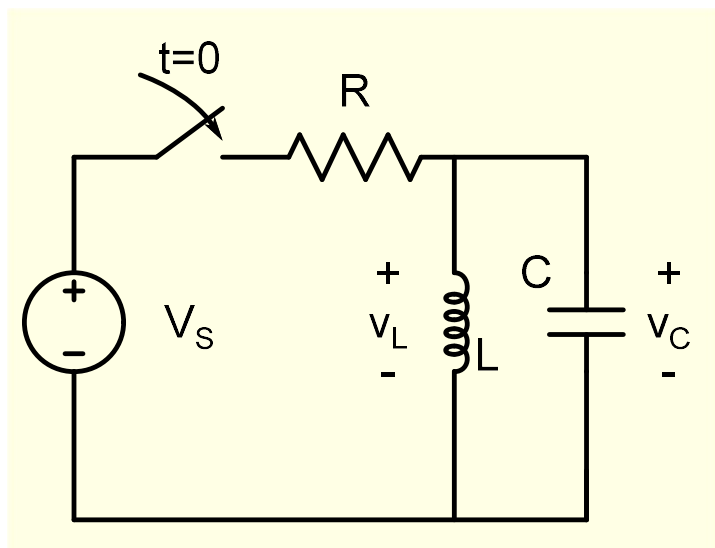
$$\frac{V_S}{R} = LC \frac{d^2 I_L}{dt^2} + \frac{L}{R} \times \frac{dV_L}{dt} + I_L$$

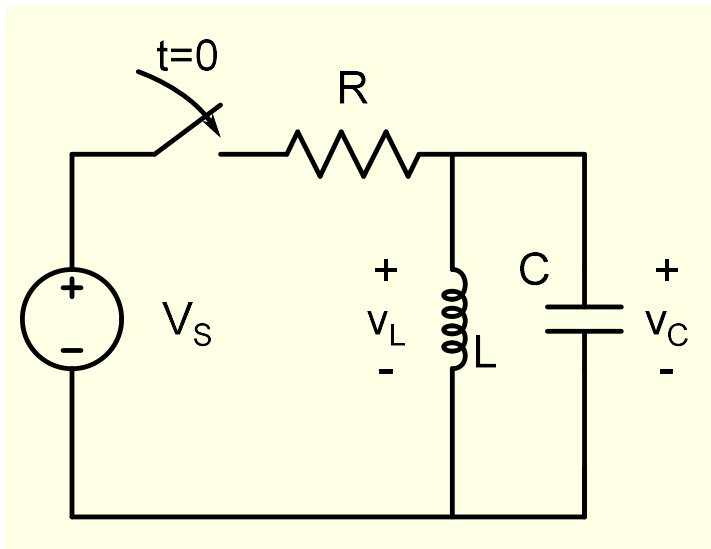
$$I_L(t) = A \times e^{st} \qquad As^2 e^{st} + \frac{1}{RC} A s e^{st} + \frac{A}{LC} e^{st} = 0$$

$$\frac{d^2 I_L}{dt^2} + \frac{1}{RC} \times \frac{dI_L}{dt} + \frac{I_L}{LC} = \frac{V_S}{RLC}$$

$$s^2 + \frac{1}{RC} s + \frac{1}{LC} = 0 \qquad s = -\frac{1}{2RC} \pm \sqrt{\frac{1}{4R^2C^2} - \frac{1}{LC}}$$

$$\omega_o = \frac{1}{\sqrt{L \times C}} \qquad Q = \frac{R}{\omega_o \times L} \qquad \frac{s}{\omega_o} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1}$$





$$\frac{d^2 I_L}{dt^2} + \frac{1}{RC} \times \frac{dI_L}{dt} + \frac{I_L}{LC} = \frac{V_S}{RLC}$$

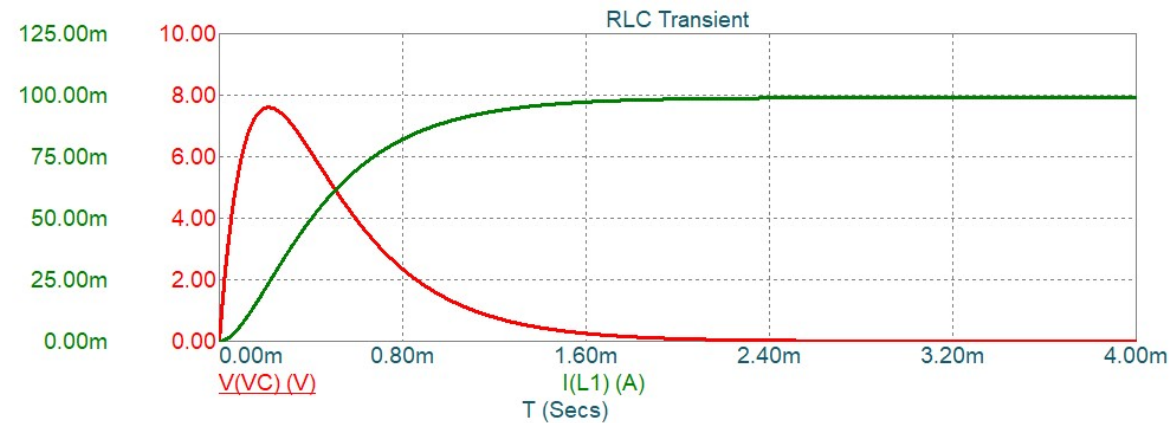
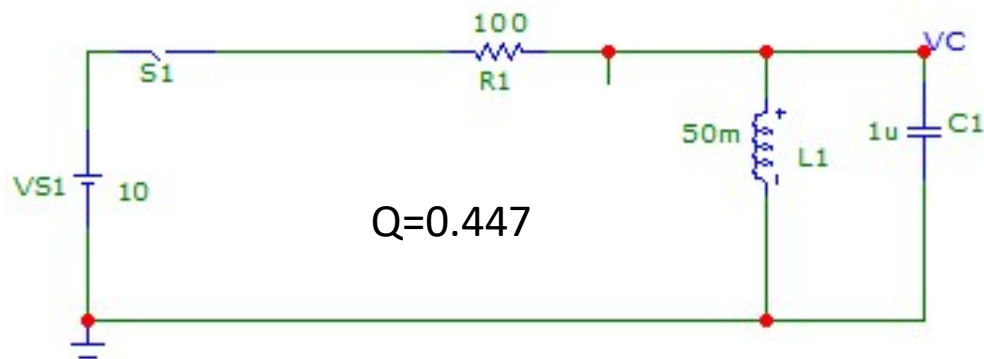
$$I_L(t) = \frac{V_S}{R} + A \times e^{s_1 t} + B \times e^{s_2 t}$$

$$\omega_o = \frac{1}{\sqrt{L \times C}}$$

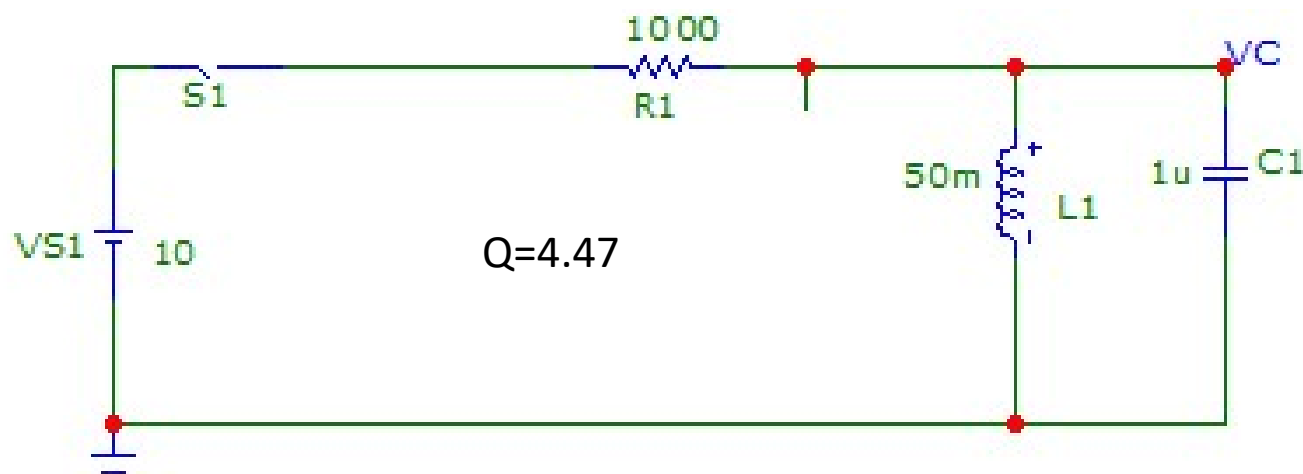
$$Q = \frac{R}{\omega_o \times L}$$

$$\frac{s}{\omega_o} = -\frac{1}{2Q} \pm \sqrt{\frac{1}{4Q^2} - 1}$$

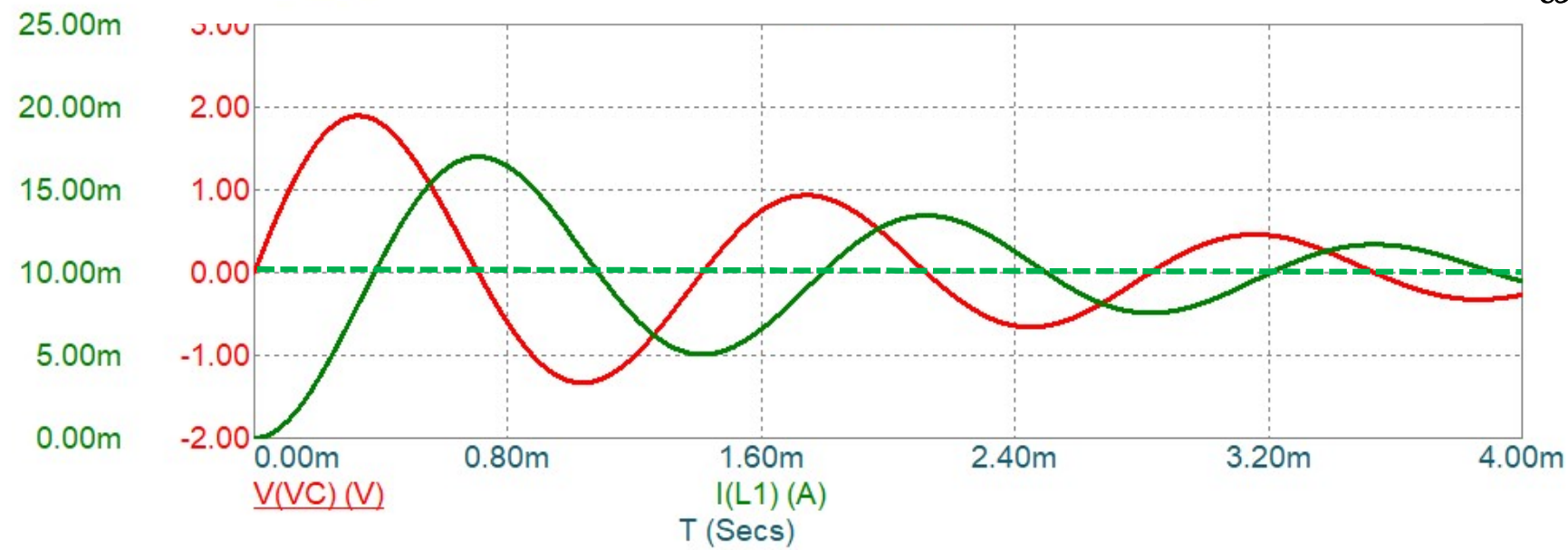
Case-1: Overdamped : $Q < 0.5$



Underdamped Case



$$Q = \frac{R}{\omega_o \times L}$$



LC Oscillators exploit this feature