



Department of Computer Science and Engineering (Data Science)

Subject: Artificial Intelligence (DJ19DSC502)

Name: Divyesh Khunt

Sapid: 60009210116

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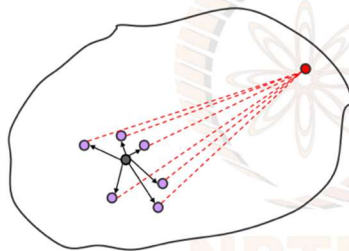
Experiment 3

(Heuristic Search)

Aim: Comparative analysis of Heuristic based methods.

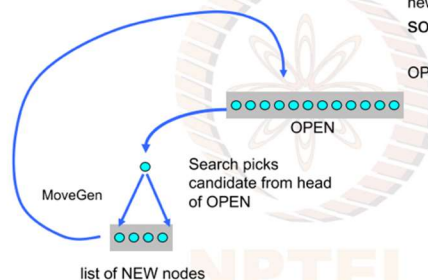
Theory:

Heuristic functions



The heuristic function estimates the distance to the goal.
This estimate, $h(n)$, can be used to decide which node to pick from OPEN

Best First Search



Best First Search inserts new candidates into OPEN sorted on $h(n)$
OPEN = PRIORITY QUEUE

Algorithm for Best First Search

```
Best-First-Search(S)
1 OPEN  $\leftarrow$  (S, null,  $h(S)$ ) []
2 CLOSED  $\leftarrow$  empty list
3 while OPEN is not empty
4   nodePair  $\leftarrow$  head OPEN
5   (N, , )  $\leftarrow$  nodePair
6   if GoalTest(N) = true
7     return ReconstructPath(nodePair, CLOSED)
8   else CLOSED  $\leftarrow$  nodePair
9   neighbours  $\leftarrow$  MoveGen(N)
10  newNodes  $\leftarrow$  RemoveSeen(neighbours, OPEN, CLOSED)
11  newPairs  $\leftarrow$  MakePairs(newNodes, N)
12  OPEN  $\leftarrow$  sort( $h$ , newPairs ++ tail OPEN)
13 return empty list
```

Algorithm Hill climbing



Shri Vile Parle Kelavani Mandal's

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Hill-Climbing(S)

1 $N \leftarrow S$

2 do bestEver $\leftarrow N$

3 $N \leftarrow \text{head sort MoveGen}(\text{bestEver})$

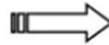
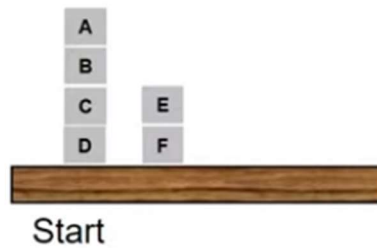
4 while $h(N)$ is better than $h(\text{bestEver})$

5 return bestEver

Lab Assignment to do:

1. Design any two different heuristics for a given blocks world problem and show that one is better than another using Hill Climbing and Best First Search.

A blocks world problem





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```
l1=[]
l2=[]
table=[l1, l2]

print("Enter the blocks from bottom to top")

n1 = int(input("Enter the number of blocks in l1: "))
for i in range(n1):
    l1.append(input())

n2 = int(input("Enter the number of blocks in l2: "))
for i in range(n2):
    l2.append(input())

print("Table: ", table, "\n")
```

Enter the blocks from bottom to top
Enter the number of blocks in l1: 4
D
C
B
A
Enter the number of blocks in l2: 2
F
E
Table: [['D', 'C', 'B', 'A'], ['F', 'E']]

```
print("Enter the goal test's blocks from bottom to top")
g1 = []
g2 = []

n3 = int(input("Enter the number of blocks in l1: "))
for i in range(n3):
    g1.append(input())

n4 = int(input("Enter the number of blocks in l1: "))
for i in range(n4):
    g2.append(input(f"{i}"))
goal_table=[g1,g2]
```

Enter the goal test's blocks from bottom to top
Enter the number of blocks in l1: 5
D
C
B
E
A
Enter the number of blocks in l1: 1
F

✓ [14] goal_table
0s
[['D', 'C', 'B', 'E', 'A'], ['F']]



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```
3] def h1(l1, l2, table):  
    score = 0  
    for stack in table:  
        for i in range(1, len(stack)):  
            if stack[i - 1] == stack[i]:  
                score += 1  
            else:  
                score -= 1  
    return score
```

```
▶ def h2(current_state, goal_state):  
    score = 0  
    for i in range(min(len(current_state), len(goal_state))):  
        if current_state[i] == goal_state[i]:  
            score += 1  
        else:  
            score -= 1  
    return score
```



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```
def movegen(i1, i2, table):
    moves = []
    if i1:
        block = i1[-1]
        new_i1 = i1[:-1]
        new_i2 = i2 + [block]
        moves.append((new_i1, new_i2, f"Move {block} from i1 to i2"))

    if i2:
        block = i2[-1]
        new_i1 = i1 + [block]
        new_i2 = i2[:-1]
        moves.append((new_i1, new_i2, f"Move {block} from i2 to i1"))

    if i1:
        block = i1[-1]
        new_i1 = i1[:-1]
        moves.append((new_i1, i2, block, f"Place {block} from i1 onto the table"))

    if i2:
        block = i2[-1]
        new_i2 = i2[:-1]
        new_table = table + [block]
        moves.append((i1, new_i2, block, f"Place {block} from i2 onto the table"))

    return moves

possible_moves = movegen(l1, l2, table)
j=1
for i in possible_moves:
    new_table = []
    print(f' move', j)
    print(i)
    new_table += list(i[:-1])
    print(new_table)
    print("Cost of h1: ")
    print(h1(l1,l2,new_table))
    print("Cost of h2: ")
    print(h2(new_table, goal_table), "\n")
    j += 1
```



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Output:

```
➡ move 1
(['D', 'C', 'B'], ['F', 'E', 'A'], 'Move A from i1 to i2')
(['D', 'C', 'B'], ['F', 'E', 'A'])
Cost of h1:
-4
Cost of h2:
-2

move 2
(['D', 'C', 'B', 'A', 'E'], ['F'], 'Move E from i2 to i1')
(['D', 'C', 'B', 'A', 'E'], ['F'])
Cost of h1:
-4
Cost of h2:
0

move 3
(['D', 'C', 'B'], ['F', 'E'], 'A', 'Place A from i1 onto the table')
(['D', 'C', 'B'], ['F', 'E'], 'A')
Cost of h1:
-3
Cost of h2:
-2

move 4
(['D', 'C', 'B', 'A'], ['F'], 'E', 'Place E from i2 onto the table')
(['D', 'C', 'B', 'A'], ['F'], 'E')
Cost of h1:
-3
Cost of h2:
0
```



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```
def movegen(i1, i2, table):
    moves = []
    if i1:
        block = i1[-1]
        new_i1 = i1[:-1]
        new_i2 = i2 + [block]
        moves.append((new_i1, new_i2))

    if i2:
        block = i2[-1]
        new_i1 = i1 + [block]
        new_i2 = i2[:-1]
        moves.append((new_i1, new_i2))

    if i1:
        block = i1[-1]
        new_i1 = i1[:-1]
        moves.append((new_i1, i2, block))

    if i2:
        block = i2[-1]
        new_i2 = i2[:-1]
        new_table = table + [block]
        moves.append((i1, new_i2, block))

    return moves

def generate_neighbors(state):
    neighbors = []
    for i in range(len(state)):
        for j in range(len(state[i])):
            if state[i][j] != ' ':
                for k in range(len(state)):
                    if i != k:
                        neighbor_state = [list(row) for row in state]
                        block = neighbor_state[i].pop(j)
                        neighbor_state[k].append(block)
                        neighbors.append(neighbor_state)
                        print(neighbors)

    return neighbors

possible_moves=movegen(l1,l2,table)
for i in possible_moves:
    generate_neighbors(i)
```




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[illegible]

```
import heapq

def best_first_search(initial_state, goal_state):
    OPEN = [(initial_state, 0)]
    CLOSED = set()
    while OPEN:
        current_state, cost = heapq.heappop(OPEN)
        if current_state == goal_state:
            return current_state
        CLOSED.add(tuple(map(tuple, current_state)))
        neighbors = generate_neighbors(current_state)
        for neighbor in neighbors:
            if tuple(map(tuple, neighbor)) not in CLOSED:
                if neighbor not in (state for state, _ in OPEN):
                    heapq.heappush(OPEN, (neighbor, heuristic(neighbor, goal_state)))

solutionbfs = best_first_search(table, goal_table)
print("Solution:", solutionbfs)
```




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```
def hill_climbing(initial_state):
    current_state = initial_state
    current_score = h2(current_state, goal_table)

    while True:
        neighbors = generate_neighbors(current_state)
        best_neighbor = None
        best_neighbor_score = current_score

        for neighbor in neighbors:
            neighbor_score = h2(neighbor, goal_table)
            if neighbor_score > best_neighbor_score:
                best_neighbor = neighbor
                best_neighbor_score = neighbor_score

        if best_neighbor_score <= current_score:
            break

        current_state = best_neighbor
        current_score = best_neighbor_score

    return current_state

final_state = hill_climbing(goal_table)
print("Final State:", final_state)
```

→ Final State: [['D', 'C', 'B', 'E', 'A'], ['F']]