External Force-Torque: In sensor frame linear_x_force 0.1 0.0 -0.10.10 linear_y_force 0.05 0.00 -0.05 linear_z_force 0.15 0.10 0.05 8:82 angular_x_force 0.01 0.00 -0.01-0.02angular_y_force 0.02 0.00 -0.020.050 angular_z_force 0.025 0.000 -0.025 -0.050 12000 0 1000 2000 3000 4000 5000 6000 7000 8000 9000 10000 11000 13000