Linear 0.6 raw error: $e = ||V \in R^3||$ 0.4 0.2 0.0 1.0 low-pass filtered error magnitude: ē 0.5 0.0 -0.5-1.01.00 0.75 bias 0.50 gain * sign(e) 0.25 0.00 -0.25-0.50-0.75-1:88 0.75 x axis distribution 0.50 0.25 0.00 -0.25-0.50-0.75-1:88 0.75 y axis distribution 0.50 0.25 0.00 -0.25-0.50-0.75-1:88 0.75 z axis distribution 0.50 0.25 0.00 -0.25-0.50-0.75-1.001000 2000 3000 4000 0