MAT351 TUTORIAL 6

PARTIAL DIFFERENTIAL EQUATIONS

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Diffusion with a source on a half-line

Recall the *inhomogeneous* IVP for the diffusion equation (on the whole line):

$$\begin{cases} u_t - k u_{xx} = f(x, t), & \text{on } \mathbb{R} \times (0, \infty) \\ u(x, 0) = \phi(x), & \text{on } \mathbb{R} \end{cases}$$
 (1.1)

Via Duhamel's principle (the textbook also calls it "the operator method"), you should have seen in class that the solution of (1.1) is

$$u(x,t) = \int_{-\infty}^{\infty} \Phi(x-y,t)\phi(y)dy + \int_{0}^{t} \int_{-\infty}^{\infty} \Phi(x-y,t-s)f(y,s)dyds$$

where as usual Φ is the heat kernel. Now, lets work on the half-line. Let us solve the inhomogeneous diffusion equation on the half-line with Dirichlet boundary condition:

$$\begin{cases} u_t - k u_{xx} = f(x, t), & \text{on } \{0 < x < \infty, 0 < t < \infty\} \\ u(x, 0) = \phi(x) \\ u(0, t) = 0 \end{cases}$$
 (1.2)

We proceed via the method of reflection; to that end let $\phi_{\text{odd}}(x)$ and $f_{\text{odd}}(x,t)$ be the odd extensions of ϕ and f with respect to x = 0. Then, the solution to

$$\begin{cases} v_t - k v_{xx} = f_{\text{odd}}(x, t), & \text{on } \{-\infty < x < \infty, 0 < t < \infty\} \\ v(x, 0) = \phi_{\text{odd}}(x) \end{cases}$$

is given by (1.1); that is:

$$v(x,t) = \int_{-\infty}^{\infty} \Phi(x-y,t)\phi_{\mathrm{odd}}(y)dy + \int_{0}^{t} \int_{-\infty}^{\infty} \Phi(x-y,t-s)f_{\mathrm{odd}}(y,s)dyds$$

But, note that since $\Phi(y,t)$ is even w.r.t. y=0 and the product of an even function and an odd function is an odd function, we have that v(0,t)=0. Hence, our solution to (1.2) is the restriction u(x,t)=v(x,t) for x>0. We now just need to simplify the formula - it is very similar to what we did in a previous tutorial. Simply split each integral over $(-\infty,0)$ and $(0,\infty)$, use the definition of the odd extensions in these intervals, and change of variables z=-y for integrals over $(-\infty,0)$. I spare you the details here as we have done this a few times

before; in any case you should arrive at

$$u(x,t) = \int_0^\infty (\Phi(x-y,t) - \Phi(x+y,t)) \phi(y) dy + \int_0^t \int_0^\infty (\Phi(x-y,t-s) - \Phi(x+y,t-s)) f(y,s) dy ds, \quad x > 0$$

Let's take it a step further and consider the *completely inhomogeneous* diffusion problem on the half-line

$$\begin{cases} u_t - k u_{xx} = f(x, t), & \text{on } \{0 < x < \infty, 0 < t < \infty\} \\ u(x, 0) = \phi(x) \\ u(0, t) = h(t) \end{cases}$$

We can actually just reduce this to the previous simpler case by letting V(x,t) = u(x,t) - h(t). Then $V_t = u_t - h'(t)$, $V_{xx} = u_{xx}$ and so $(V_t + h'(t)) - kV_{xx} = f(x,t)$, that is:

$$\begin{cases} V_t - kV_{xx} = f(x,t) - h'(t), & 0 < x < \infty, t > 0 \\ V(x,0) = u(x,0) - h(0) = \phi(x) - h(0) \\ V(0,t) = u(0,t) - h(t) = h(t) - h(t) = 0 \end{cases}$$

At this point, we can solve for V as before with the method of reflection. Our solution then is simply u(x,t) = h(t) + V(x,t).

2

Waves with a source on whole line - Duhamel's Principle

Please note that for this section, I follow [2].

We have already looked at the 1D wave equation - now we introduce an external force given by f(x,t). The corresponding IVP with inhomogeneous right hand side source term is:

$$\begin{cases} u_{tt} - c^2 u_{xx} = f(x, t), & -\infty < x < \infty, t > 0 \\ u(x, 0) = \phi(x), & -\infty < x < \infty \\ u_t(x, 0) = \psi(x), & -\infty < x < \infty \end{cases}$$
(2.1)

The claim is that the solution is the extension of D'Alembert's formula:

$$u(x,t) = \frac{1}{2} \left[\phi(x+ct) + \phi(x-ct) \right] + \frac{1}{2c} \int_{x-ct}^{x+ct} \psi(s) ds + \frac{1}{2c} \int \int_{D} f(y,\tau) dy d\tau$$
 (2.2)

where D is the "characteristic triangle" or "domain of dependence" associated with (x,t) (i.e. the triangle in the x-t plane with top point (x,t) and base points (x-ct,0), (x+ct,0)).

Remark. The double integral in (2.2) is simply equal to $\int_0^t \int_{x-c(t-\tau)}^{x+c(t-\tau)} f(y,\tau) dy d\tau$

Remark. Naturally, if $f(x,t) \equiv 0$ then we recover the regular D'Alembert's formula.

Duhamel's principle (named after Jean-Marie Duhamel B:1797-D:1872) is a general method for solving linear PDEs with inhomogeneous terms. Here we demonstrate its use with (2.1).

First we note that by superposition, we need only to solve

$$\begin{cases} u_{tt} - c^2 u_{xx} = f(x, t), & -\infty < x < \infty, t > 0 \\ u(x, 0) = 0, & -\infty < x < \infty \\ u_t(x, 0) = 0, & -\infty < x < \infty \end{cases}$$
(2.3)

Adding this solution to D'Alembert's formula for the (homogenous) wave equation with initial data $\phi(x)$ and $\psi(x)$ then yields the solution for (2.1). Introducing the temporal parameter $s \in [0, \infty)$, Duhamel's principle states that the solution to (2.3) is given by $u(x, t) = \int_0^t w(x, t; s) ds$ where for each fixed s, w(x, t; s) is solution to

$$\begin{cases} w_{tt}(x,t;s) = c^2 w_{xx}(x,t;s), & -\infty < x < \infty, t > s \\ w(x,s;s) = 0, & -\infty < x < \infty \\ w_t(x,s;s) = f(x,s), & -\infty < x < \infty \end{cases}$$

Check

Let us verify Duhamel's principle here. Recall:

Theorem 2.0.1 (Leibniz Rule). Let f(t, s) smooth, then

$$\frac{d}{dt}\left(\int_0^t f(t,s)ds\right) = f(t,t) + \int_0^t f_t(t,s)ds$$

By Leibniz rule we have that

$$u_t(x,t) = w(x,t;t) + \int_0^t w_t(x,t;s)ds = \int_0^t w_t(x,t;s)ds$$
 (2.4)

since w(x, t; t) = 0. Then by Leibniz rule again

$$u_{tt}(x,t) = w_t(x,t;t) + \int_0^t w_{tt}(x,t;s)ds = f(x,t) + \int_0^t w_{tt}(x,t;s)ds$$

since $w_t(x,t;t) = f(x,t)$. On the other hand, by differentiating under the integral, we have that $u_{xx}(x,t) = \int_0^t w_{xx}(x,t;s)ds$. Hence:

$$u_{tt} - c^2 u_{xx} = \int_0^t \left[w_{tt}(x, t; s) - c^2 w_{xx}(x, t; s) \right] ds + f(x, t) = f(x, t)$$

where we have used that $w_{tt}(x,t;s) = c^2 w_{xx}(x,t;s)$.

Now, u(x,0) = 0 trivially and $u_t(x,0) = 0$ by (2.4).

Last Comment

So far we have shown that the solution to (2.1) is

$$u(x,t) = \frac{1}{2} \left[\phi(x+ct) + \phi(x-ct) \right] + \frac{1}{2c} \int_{x-ct}^{x+ct} \psi(s) ds + \int_{0}^{t} w(x,t;s) ds$$

But, we can solve for w(x,t;s) for each fixed s as it satisfies homogenous wave equation, just now starting at t=s instead of t=0 (and now the source is incorporated into the initial data). One finds $w(x,t;s)=\frac{1}{2c}\int_{x-c(t-s)}^{x+c(t-s)}f(y,s)dy$ so that

$$u(x,t) = \frac{1}{2} \left[\phi(x+ct) + \phi(x-ct) \right] + \frac{1}{2c} \int_{x-ct}^{x+ct} \psi(s) ds + \frac{1}{2c} \int_{0}^{t} \int_{x-c(t-s)}^{x+c(t-s)} f(y,s) dy ds$$

which is precisely the extension of D'Alembert's formula which was proposed in the beginning of this section.

Bibliography

- [1] W. Strauss, Partial Differential Equations: An Introduction, 2nd edition, Wiley
- [2] R. Choksi, Partial Differential Equations: A First Course, AMS 2022