

Chapter 4: Expectation and Their Distributions

Introduction to Probability, 2nd Edition
Blitzstein & Hwang

DRME

December 22, 2025

Chapter Overview

What is Expectation?

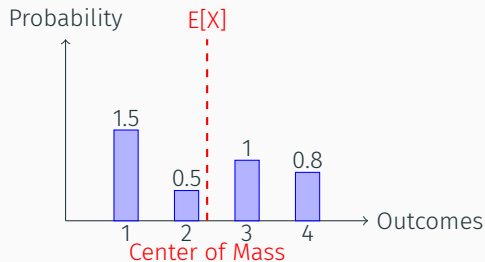
Central Idea

The **expectation** or **expected value** of a random variable is its long-run average value if the experiment is repeated many times.

Analogy: The expectation is the "center of mass" of the probability distribution.

[Wikipedia: Expected Value](#)

Visualizing Expectation: Center of Mass



The expectation balances the probability distribution like a seesaw.

Definition of Expectation

Definition (Expectation for Discrete RVs)

For a discrete random variable X with probability mass function p_X , the **expected value** is:

$$E[X] = \sum_x x \cdot p_X(x)$$

summed over all possible values of X .

Interpretation:

- Weighted average of all possible values
- Weights = probabilities of those values
- Only defined if the sum converges absolutely

Discrete Expectation Example

Example: Fair die roll

$$E[X] = 1 \cdot \frac{1}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{1}{6} + 4 \cdot \frac{1}{6} + 5 \cdot \frac{1}{6} + 6 \cdot \frac{1}{6} = 3.5$$

Why not 3.5? Even though 3.5 isn't a possible outcome, it represents the average over many rolls.

Expectation for Continuous Random Variables

Definition (Expectation for Continuous RVs)

For a continuous random variable X with probability density function f_X , the **expected value** is:

$$E[X] = \int_{-\infty}^{\infty} x \cdot f_X(x) dx$$

provided the integral converges absolutely.

Interpretation:

- Continuous analog of weighted average
- Weight at each point = density $f_X(x)$

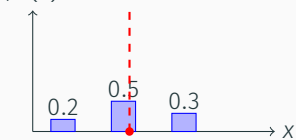
Example: $X \sim \text{Uniform}(a, b)$

$$E[X] = \int_a^b x \cdot \frac{1}{b-a} dx = \frac{1}{b-a} \cdot \frac{x^2}{2} \Big|_a^b = \frac{a+b}{2}$$

The expected value is exactly the midpoint, as we would intuitively expect.

Visualizing Discrete Expectation

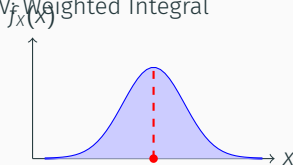
Discrete RV: Weighted Average



$$\begin{aligned} E[X] &= 0.5 \times 0.2 + 1.5 \times 0.5 + 2.5 \times 0.3 \\ &= 0.1 + 0.75 + 0.75 = 1.6 \end{aligned}$$

Visualizing Continuous Expectation

Continuous RV: Weighted Integral



$$E[X] = \int x f_X(x) dx$$

Key Insight: The expected value balances the probability mass, just like a seesaw balances weights.

Properties of Expectation

Theorem (Linearity of Expectation)

For any random variables X and Y , and constants a and b :

$$E[aX + bY] = aE[X] + bE[Y]$$

Crucial Insight: This property holds **always**, regardless of:

- Independence or dependence of X and Y
- Discrete or continuous nature
- Any special relationship between them

Proof Sketch of Linearity

Proof.

For discrete case:

$$\begin{aligned} E[aX + bY] &= \sum_x \sum_y (ax + by) p_{X,Y}(x, y) \\ &= a \sum_x x \sum_y p_{X,Y}(x, y) + b \sum_y y \sum_x p_{X,Y}(x, y) \\ &= aE[X] + bE[Y] \end{aligned}$$

□

Continuous case follows similarly using integrals instead of sums.

Example 1: Hat Check Problem (from Book)

- n people put hats in a box
- Hats are randomly redistributed
- Let X = number of people who get their own hat back
- Find $E[X]$

Without Linearity: Need full distribution of X (complicated!)

With Linearity: Much simpler approach using indicator variables

Hat Check Problem: Solution

Define indicator variables:

$$I_i = \begin{cases} 1 & \text{if person } i \text{ gets own hat} \\ 0 & \text{otherwise} \end{cases}$$

Then:

$$X = I_1 + I_2 + \cdots + I_n$$

By linearity:

$$E[X] = E[I_1] + E[I_2] + \cdots + E[I_n]$$

Since each person has probability $\frac{1}{n}$ of getting their own hat:

$$E[I_i] = 1 \cdot \frac{1}{n} + 0 \cdot \frac{n-1}{n} = \frac{1}{n}$$

Thus:

$$E[X] = n \cdot \frac{1}{n} = 1$$

Result: Expected number of fixed points is 1, regardless of n !

1. **Expectation of constant:** $E[c] = c$ for any constant c
2. **Monotonicity:** If $X \leq Y$ almost surely, then $E[X] \leq E[Y]$
3. **Non-negativity:** If $X \geq 0$, then $E[X] \geq 0$
4. **Triangle inequality:** $|E[X]| \leq E[|X|]$

Expectation of function: For any function g :

$$E[g(X)] = \begin{cases} \sum_x g(x)p_X(x) & \text{(discrete)} \\ \int_{-\infty}^{\infty} g(x)f_X(x)dx & \text{(continuous)} \end{cases}$$

(This is called the Law of the Unconscious Statistician, LOTUS)

Important Caution:

$$E[XY] \neq E[X]E[Y] \quad \text{in general}$$

Equality holds only if X and Y are uncorrelated (in particular, if independent).

Theorem (LOTUS)

For any function g and random variable X :

$$E[g(X)] = \begin{cases} \sum_x g(x)p_X(x) & (\text{discrete}) \\ \int_{-\infty}^{\infty} g(x)f_X(x)dx & (\text{continuous}) \end{cases}$$

Why "Unconscious Statistician"? Because you don't need to find the distribution of $g(X)$ first!

Example: If $X \sim \text{Uniform}(0, 1)$, find $E[X^2]$

Without LOTUS: Need to find PDF of $Y = X^2$, then compute $E[Y]$

With LOTUS:

$$E[X^2] = \int_0^1 x^2 \cdot 1 \, dx = \left. \frac{x^3}{3} \right|_0^1 = \frac{1}{3}$$

Proof Idea:

- For discrete case, group outcomes where $g(X)$ takes same value
- For continuous, use change of variables

Variance and Standard Deviation

Definition of Variance

Definition (Variance)

The **variance** of a random variable X measures its spread or dispersion:

$$\text{Var}(X) = E[(X - \mu)^2] \quad \text{where } \mu = E[X]$$

Definition (Standard Deviation)

The **standard deviation** is the square root of variance:

$$SD(X) = \sqrt{\text{Var}(X)}$$

[Wikipedia: Variance](#)

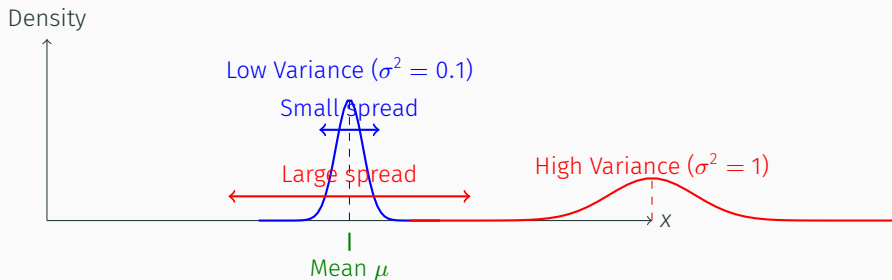
Interpretation:

- Variance = average squared distance from mean
- Standard deviation = typical distance from mean (in original units)
- Both are non-negative: $\text{Var}(X) \geq 0$, $\text{SD}(X) \geq 0$

Units:

- Variance has units squared (e.g., cm^2 if X is in cm)
- Standard deviation has same units as X (e.g., cm)

Visualizing Variance



Key Insight: Variance measures how "spread out" the distribution is around the mean.

Theorem (Alternative Variance Formula)

$$\text{Var}(X) = E[X^2] - (E[X])^2$$

Proof:

$$\begin{aligned}\text{Var}(X) &= E[(X - \mu)^2] \\ &= E[X^2 - 2\mu X + \mu^2] \\ &= E[X^2] - 2\mu E[X] + \mu^2 \quad (\text{by linearity}) \\ &= E[X^2] - 2\mu \cdot \mu + \mu^2 \\ &= E[X^2] - \mu^2\end{aligned}$$

Why the Computational Formula is Useful

Why Useful? Often easier to compute $E[X^2]$ and $(E[X])^2$ separately.

Example: For $X \sim \text{Bernoulli}(p)$:

$$E[X] = 0 \cdot (1 - p) + 1 \cdot p = p$$

$$E[X^2] = 0^2 \cdot (1 - p) + 1^2 \cdot p = p$$

$$\text{Var}(X) = p - p^2 = p(1 - p)$$

1. **Non-negativity:** $\text{Var}(X) \geq 0$, with equality iff X is constant
2. **Scaling:** $\text{Var}(aX + b) = a^2\text{Var}(X)$
 - Adding constant doesn't change spread
 - Multiplying by constant scales variance by square of constant

Variance of Sums

Variance of sum: For any X and Y :

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$

Independent case: If X and Y are independent:

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y)$$

Variance of sample mean: If X_1, \dots, X_n are i.i.d. with variance σ^2 :

$$\text{Var} \left(\frac{1}{n} \sum_{i=1}^n X_i \right) = \frac{\sigma^2}{n}$$

Example: Variance of Binomial Distribution

Problem: Find variance of $X \sim \text{Bin}(n, p)$

Step 1: Represent as sum of indicators

$$X = I_1 + I_2 + \cdots + I_n, \quad I_i \sim \text{Bernoulli}(p) \text{ i.i.d.}$$

Example: Variance of Binomial (continued)

Step 2: Use variance properties

$$\begin{aligned}\text{Var}(X) &= \text{Var}(I_1 + I_2 + \cdots + I_n) \\ &= \text{Var}(I_1) + \text{Var}(I_2) + \cdots + \text{Var}(I_n) \quad (\text{independence}) \\ &= n \cdot \text{Var}(I_1)\end{aligned}$$

Step 3: Compute variance of Bernoulli

$$\text{Var}(I_1) = p(1 - p)$$

Step 4: Final answer

$$\text{Var}(X) = np(1 - p)$$

Covariance and Correlation

Definition (Covariance)

The **covariance** between two random variables X and Y measures their linear relationship:

$$\text{Cov}(X, Y) = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - E[X]E[Y]$$

where $\mu_X = E[X]$, $\mu_Y = E[Y]$.

[Wikipedia: Covariance](#)

Interpretation:

- $\text{Cov}(X, Y) > 0$: X and Y tend to be above/below their means together
- $\text{Cov}(X, Y) < 0$: When X is above mean, Y tends to be below mean
- $\text{Cov}(X, Y) = 0$: Uncorrelated (but not necessarily independent!)

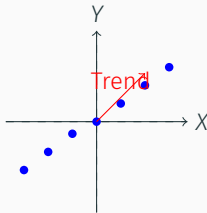
Key Insight: Covariance measures **linear** relationship.

Properties:

- $\text{Cov}(X, X) = \text{Var}(X)$
- $\text{Cov}(X, Y) = \text{Cov}(Y, X)$
- $\text{Cov}(aX + b, cY + d) = ac \text{Cov}(X, Y)$
- Bilinearity: $\text{Cov}(X + Y, Z) = \text{Cov}(X, Z) + \text{Cov}(Y, Z)$

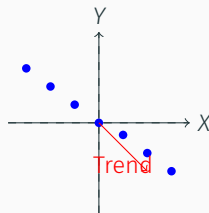
Visualizing Positive Covariance

Positive Covariance



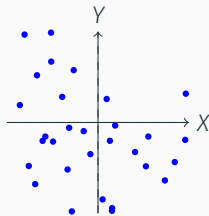
Visualizing Negative Covariance

Negative Covariance



Visualizing Zero Covariance

Zero Covariance (Uncorrelated)



Example: Computing Covariance - Setup

Problem: Roll two fair dice. Let X = number on first die, Y = sum of both dice. Find $\text{Cov}(X, Y)$.

Step 1: Compute $E[X]$ and $E[Y]$

$$E[X] = 3.5$$

$$E[Y] = E[X_1 + X_2] = E[X_1] + E[X_2] = 3.5 + 3.5 = 7$$

Example: Computing Covariance - Calculations

Step 2: Compute $E[XY]$

$$E[XY] = E[X(X_1 + X_2)] = E[X^2 + XX_2] = E[X^2] + E[X]E[X_2]$$

since X and X_2 are independent.

Step 3: Compute $E[X^2]$

$$E[X^2] = \frac{1}{6}(1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2) = \frac{91}{6}$$

Example: Computing Covariance - Final Answer

Step 4: Put it all together

$$E[XY] = \frac{91}{6} + 3.5 \times 3.5 = \frac{91}{6} + \frac{49}{4} = \frac{329}{12}$$

$$\text{Cov}(X, Y) = E[XY] - E[X]E[Y] = \frac{329}{12} - 3.5 \times 7 = \frac{35}{12} \approx 2.92$$

Positive covariance makes sense: higher first die tends to give higher sum.

Definition (Correlation)

The **correlation coefficient** between X and Y is:

$$\rho(X, Y) = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}} = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$

[Wikipedia: Correlation](#)

Properties:

1. $-1 \leq \rho(X, Y) \leq 1$
2. $\rho(X, Y) = 1$ iff $Y = aX + b$ with $a > 0$ (perfect positive linear relationship)
3. $\rho(X, Y) = -1$ iff $Y = aX + b$ with $a < 0$ (perfect negative linear relationship)
4. $\rho(X, Y) = 0$: Uncorrelated (no linear relationship)
5. Invariant to scaling: $\rho(aX + b, cY + d) = \text{sign}(ac) \cdot \rho(X, Y)$

Why Use Correlation Instead of Covariance?

Why use correlation instead of covariance?

- Covariance depends on units of measurement
- Correlation is dimensionless and bounded between -1 and 1
- Easier to interpret strength of relationship

Interpretation Guide:

- $|\rho| \approx 0$: Weak linear relationship
- $|\rho| \approx 0.5$: Moderate linear relationship
- $|\rho| \approx 0.8$: Strong linear relationship
- $|\rho| \approx 1$: Very strong linear relationship

Visualizing Different Correlation Values



0.9 = 0.9 (Strong pos) 0.5 = 0.5 (Moderate positive)

Visualizing Different Correlation Values (Continued)



$0 = 0$ (No linear relationship) -0.5 (Moderate negative) -0.9 (Strong negative)

Important Notes about Correlation

Important Notes:

- $\rho = 0$ doesn't imply independence (only no linear relationship)
- ρ measures only linear relationships (nonlinear relationships can have $\rho = 0$)
- Independence $\Rightarrow \rho = 0$, but $\rho = 0 \nRightarrow$ independence

Example of nonlinear relationship with $\rho = 0$: Let $X \sim \text{Uniform}(-1, 1)$ and $Y = X^2$. Then $\text{Cov}(X, Y) = E[X^3] - E[X]E[X^2] = 0 - 0 \cdot E[X^2] = 0$, but X and Y are clearly dependent.

Conditional Expectation

Definition of Conditional Expectation

Definition (Conditional Expectation for Discrete RVs)

For discrete random variables X and Y , the **conditional expectation** of Y given $X = x$ is:

$$E[Y | X = x] = \sum_y y \cdot P(Y = y | X = x)$$

Interpretation: The average value of Y when we know $X = x$.

Definition (Conditional Expectation for Continuous RVs)

For continuous random variables X and Y , the **conditional expectation** of Y given $X = x$ is:

$$E[Y | X = x] = \int_{-\infty}^{\infty} y \cdot f_{Y|X}(y | x) dy$$

where $f_{Y|X}(y | x)$ is the conditional density.

Note: $E[Y | X]$ is itself a random variable (function of X).

1. **Linearity:** $E[aY + bZ \mid X = x] = aE[Y \mid X = x] + bE[Z \mid X = x]$
2. **Taking out what's known:** If $g(X)$ is a function of X only:

$$E[g(X)Y \mid X = x] = g(x)E[Y \mid X = x]$$

3. **Independence:** If X and Y are independent:

$$E[Y \mid X = x] = E[Y] \quad \text{for all } x$$

4. Law of Total Expectation (Tower Property):

$$E[E[Y | X]] = E[Y]$$

5. **Best predictor:** $E[Y | X]$ is the function of X that minimizes $E[(Y - g(X))^2]$ over all functions g

Example: Conditional Expectation in Two Dice Problem

Problem: Roll two fair dice. Let X = number on first die, Y = sum of both dice. Find $E[Y \mid X = 3]$.

Step 1: Identify conditional distribution Given $X = 3$, $Y = 3 + X_2$ where X_2 is second die.

Step 2: Compute conditional expectation

$$E[Y \mid X = 3] = E[3 + X_2] = 3 + E[X_2] = 3 + 3.5 = 6.5$$

Example: General Conditional Expectation

Step 3: Generalize For any x :

$$E[Y \mid X = x] = E[x + X_2] = x + 3.5$$

Step 4: Verify Law of Total Expectation

$$\begin{aligned} E[Y] &= E[E[Y \mid X]] = E[X + 3.5] = E[X] + 3.5 = 3.5 + 3.5 = 7 \\ &= \text{Direct computation: } E[Y] = 7 \quad \checkmark \end{aligned}$$

Theorem (Law of Total Expectation)

For any random variables X and Y :

$$E[Y] = E[E[Y | X]]$$

Proof of Law of Total Expectation

Proof (discrete case).

$$\begin{aligned} E[E[Y | X]] &= \sum_x E[Y | X = x]P(X = x) \\ &= \sum_x \left(\sum_y yP(Y = y | X = x) \right) P(X = x) \\ &= \sum_x \sum_y yP(Y = y, X = x) \\ &= \sum_y y \sum_x P(Y = y, X = x) \\ &= \sum_y yP(Y = y) = E[Y] \end{aligned}$$

□

Interpretation of Law of Total Expectation

Interpretation: To compute overall average of Y , average conditional averages weighted by probability of conditioning events.

Analogy: To find average grade in a class:

- Compute average grade for each section
- Weight each section average by number of students in that section
- Sum the weighted averages

Example: Law of Total Expectation Application - Setup

Problem (from Book): Suppose we have a stick of length 1. Break it at a random point $X \sim \text{Uniform}(0, 1)$. Then break the longer piece at a random point. What's the expected length of the final longest piece?

Step 1: Define variables Let X = first break point, Y = length of final longest piece.

Step 2: Use law of total expectation

$$E[Y] = E[E[Y | X]]$$

Step 3: Compute $E[Y \mid X = x]$

If $x \geq 1/2$, left piece is longer. Break it at point $U \sim \text{Uniform}(0, x)$. Longest piece length = $\max(U, x - U)$. By symmetry, $E[\max(U, x - U) \mid X = x] = \frac{3x}{4}$.

If $x < 1/2$, right piece is longer. Similar argument gives $E[Y \mid X = x] = \frac{3(1-x)}{4}$.

Step 4: Compute overall expectation

$$\begin{aligned} E[Y] &= \int_0^{1/2} \frac{3(1-x)}{4} dx + \int_{1/2}^1 \frac{3x}{4} dx \\ &= \frac{3}{4} \left[\int_0^{1/2} (1-x) dx + \int_{1/2}^1 x dx \right] \\ &= \frac{3}{4} \left[\left(\frac{1}{2} - \frac{1}{8} \right) + \left(\frac{1}{2} - \frac{1}{8} \right) \right] \\ &= \frac{3}{4} \times \frac{3}{4} = \frac{9}{16} \end{aligned}$$

Moment Generating Functions

Definition of Moment Generating Function

Definition (Moment Generating Function)

The moment generating function (MGF) of a random variable X is:

$$M_X(t) = E[e^{tX}]$$

defined for all t where the expectation exists.

[Wikipedia: Moment Generating Function](#)

Why "Moment Generating"?

The MGF generates moments because:

$$M_X^{(n)}(0) = \left. \frac{d^n}{dt^n} M_X(t) \right|_{t=0} = E[X^n]$$

The n -th derivative at 0 gives the n -th moment.

Example: For $X \sim \text{Exponential}(\lambda)$:

$$M_X(t) = E[e^{tx}] = \int_0^\infty e^{tx} \lambda e^{-\lambda x} dx = \frac{\lambda}{\lambda - t}, \quad t < \lambda$$

Then $E[X] = M'_X(0) = \frac{1}{\lambda}$, $E[X^2] = M''_X(0) = \frac{2}{\lambda^2}$.

Basic Properties of Moment Generating Functions

1. **Uniqueness:** If $M_X(t) = M_Y(t)$ for all t in neighborhood of 0, then X and Y have the same distribution.
2. **Linear transformation:** For $Y = aX + b$:

$$M_Y(t) = e^{bt}M_X(at)$$

3. **Sum of independent RVs:** If X and Y are independent:

$$M_{X+Y}(t) = M_X(t)M_Y(t)$$

4. Moments from MGF:

$$E[X^n] = M_X^{(n)}(0)$$

5. Relationship to other functions:

- Characteristic function: $\phi_X(t) = E[e^{itX}]$
- Probability generating function (for discrete): $G_X(z) = E[z^X]$

Example: MGF of Normal Distribution - Setup

Problem: Find MGF of $X \sim N(\mu, \sigma^2)$.

Step 1: Standardize Let $Z = \frac{X - \mu}{\sigma} \sim N(0, 1)$. Then $X = \mu + \sigma Z$.

Example: MGF of Standard Normal

Step 2: Find MGF of standard normal

$$\begin{aligned}M_Z(t) &= E[e^{tZ}] = \int_{-\infty}^{\infty} e^{tz} \frac{1}{\sqrt{2\pi}} e^{-z^2/2} dz \\&= \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(z^2 - 2tz)\right) dz \\&= \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}[(z-t)^2 - t^2]\right) dz \\&= e^{t^2/2} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-(z-t)^2/2} dz \\&= e^{t^2/2} \quad (\text{integral of normal PDF} = 1)\end{aligned}$$

Step 3: Transform back

$$M_X(t) = E[e^{t(\mu + \sigma Z)}] = e^{\mu t} M_Z(\sigma t) = \exp\left(\mu t + \frac{\sigma^2 t^2}{2}\right)$$

Special case: For standard normal ($\mu = 0, \sigma^2 = 1$):

$$M_Z(t) = e^{t^2/2}$$

Application 1: Sum of Independent Normals

Application: Sum of Independent Normals

If $X \sim N(\mu_1, \sigma_1^2)$, $Y \sim N(\mu_2, \sigma_2^2)$, independent, then:

$$\begin{aligned}M_{X+Y}(t) &= M_X(t)M_Y(t) \\&= \exp\left(\mu_1 t + \frac{\sigma_1^2 t^2}{2}\right) \exp\left(\mu_2 t + \frac{\sigma_2^2 t^2}{2}\right) \\&= \exp\left((\mu_1 + \mu_2)t + \frac{(\sigma_1^2 + \sigma_2^2)t^2}{2}\right)\end{aligned}$$

Thus $X + Y \sim N(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2)$.

Application 2: Method of Moments Estimation

Application: Method of Moments Estimation

Given i.i.d. sample X_1, \dots, X_n , method of moments:

1. Compute sample moments: $m_k = \frac{1}{n} \sum_{i=1}^n X_i^k$
2. Express population moments in terms of parameters: $\mu_k(\theta) = E[X^k]$
3. Solve $\mu_k(\theta) = m_k$ for parameters θ

Example: For $X \sim \text{Exponential}(\lambda)$, $E[X] = 1/\lambda$. Method of moments estimate:
 $\hat{\lambda} = 1/\bar{X}$.

Important Inequalities

Theorem (Markov's Inequality)

For any nonnegative random variable X and any $a > 0$:

$$P(X \geq a) \leq \frac{E[X]}{a}$$

[Wikipedia: Markov's Inequality](#)

Proof of Markov's Inequality

Proof.

$$\begin{aligned} E[X] &= \int_0^{\infty} x f_X(x) dx \\ &\geq \int_a^{\infty} x f_X(x) dx \quad (\text{integral over smaller domain}) \\ &\geq \int_a^{\infty} a f_X(x) dx \quad (\text{since } x \geq a \text{ in this region}) \\ &= aP(X \geq a) \end{aligned}$$



Interpretation of Markov's Inequality

Interpretation: Probability of large values is controlled by mean.

Example: If average income is \$50,000, at most 10% can have income \geq \$500,000.

Limitation: Very conservative bound, often not tight.

Theorem (Chebyshev's Inequality)

For any random variable X with finite mean μ and variance σ^2 , and any $k > 0$:

$$P(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$

[Wikipedia: Chebyshev's Inequality](#)

Proof of Chebyshev's Inequality

Proof.

Apply Markov's inequality to $(X - \mu)^2$:

$$P(|X - \mu| \geq k\sigma) = P((X - \mu)^2 \geq k^2\sigma^2) \leq \frac{E[(X - \mu)^2]}{k^2\sigma^2} = \frac{1}{k^2}$$



Interpretation of Chebyshev's Inequality

Interpretation:

- For $k = 2$: At most 25% of probability is more than 2 SDs from mean
- For $k = 3$: At most 11% of probability is more than 3 SDs from mean
- For $k = 10$: At most 1% of probability is more than 10 SDs from mean

Example: If test scores have mean 70, SD 10, at most 25% scored below 50 or above 90.

Cauchy-Schwarz Inequality for Expectations

Theorem (Cauchy-Schwarz Inequality)

For any random variables X and Y with finite second moments:

$$|E[XY]| \leq \sqrt{E[X^2]E[Y^2]}$$

Equality holds iff $Y = aX$ almost surely for some constant a .

Proof of Cauchy-Schwarz Inequality

Proof.

Consider $E[(tX + Y)^2] \geq 0$ for all t :

$$E[X^2]t^2 + 2E[XY]t + E[Y^2] \geq 0$$

This quadratic in t has at most one real root, so discriminant ≤ 0 :

$$(2E[XY])^2 - 4E[X^2]E[Y^2] \leq 0$$

which gives the inequality. □

Application: Shows $|\rho(X, Y)| \leq 1$:

$$|\text{Cov}(X, Y)| = |E[(X - \mu_X)(Y - \mu_Y)]| \leq \sqrt{E[(X - \mu_X)^2]E[(Y - \mu_Y)^2]} = \sigma_X\sigma_Y$$

Thus:

$$|\rho(X, Y)| = \frac{|\text{Cov}(X, Y)|}{\sigma_X\sigma_Y} \leq 1$$

Jensen's Inequality

Theorem (Jensen's Inequality)

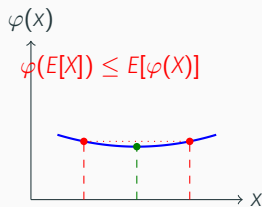
If φ is a convex function and X is a random variable, then:

$$\varphi(E[X]) \leq E[\varphi(X)]$$

If φ is concave, the inequality reverses.

[Wikipedia: Jensen's Inequality](#)

Visualizing Jensen's Inequality



Examples:

- $\varphi(x) = x^2$ convex: $E[X]^2 \leq E[X^2]$ (already knew from variance ≥ 0)
- $\varphi(x) = e^x$ convex: $e^{E[X]} \leq E[e^X]$
- $\varphi(x) = \log(x)$ concave: $E[\log(X)] \leq \log(E[X])$

Application: In information theory, concavity of \log gives:

$$E[\log(X)] \leq \log(E[X])$$

which is used in proving properties of entropy.

Detailed Examples

Example 1: St. Petersburg Paradox - Setup

Problem: A casino offers a game. Flip a fair coin until it lands heads. If first heads occurs on n -th toss, you win 2^n dollars. How much would you pay to play?

Step 1: Define random variable Let X = payout. $P(\text{heads on toss } n) = (1/2)^n$.

Example 1: St. Petersburg Paradox - Calculation

Step 2: Compute expected value

$$E[X] = \sum_{n=1}^{\infty} 2^n \cdot \left(\frac{1}{2}\right)^n = \sum_{n=1}^{\infty} 1 = \infty$$

Step 3: Paradox Expected value is infinite! But would you pay \$1,000 to play?
Probably not.

Example 1: St. Petersburg Paradox - Resolution

Step 4: Resolution

- Utility theory: Money has diminishing marginal utility
- Use log utility: $E[\log(X)] = \sum_{n=1}^{\infty} \log(2^n) \cdot (1/2)^n = \log(4)$
- Casino has finite wealth
- People are risk-averse

Example 2: Coupon Collector Problem - Setup

Problem: There are n different coupons. Each box contains one coupon, uniformly random. How many boxes to collect all coupons?

Step 1: Define variables Let T = total boxes needed. Let T_i = boxes to get i -th new coupon after having $i - 1$.

Example 2: Coupon Collector Problem - Analysis

Step 2: Analyze T_i After $i - 1$ coupons, probability new coupon in next box = $\frac{n-(i-1)}{n}$. So $T_i \sim \text{Geometric}(p_i)$ with $p_i = \frac{n-i+1}{n}$. Thus $E[T_i] = \frac{1}{p_i} = \frac{n}{n-i+1}$.

Example 2: Coupon Collector Problem - Solution

Step 3: Use linearity

$$\begin{aligned} E[T] &= E[T_1 + T_2 + \cdots + T_n] = \sum_{i=1}^n E[T_i] = \sum_{i=1}^n \frac{n}{n-i+1} \\ &= n \sum_{j=1}^n \frac{1}{j} = nH_n \approx n(\log n + \gamma) \end{aligned}$$

where H_n is n -th harmonic number, $\gamma \approx 0.577$ is Euler-Mascheroni constant.

Result: Need about $n \log n$ boxes on average.

Example 3: Random Walk Expectation - Setup

Problem: Start at 0. Each step, move +1 with probability p , -1 with probability $q = 1 - p$. After n steps, what's expected position?

Step 1: Define variables Let $X_i =$ step i : $X_i = \begin{cases} +1 & \text{prob } p \\ -1 & \text{prob } q \end{cases}$ Position after n steps: $S_n = X_1 + X_2 + \cdots + X_n$.

Example 3: Random Walk Expectation - Solution

Step 2: Compute expectation

$$E[X_i] = 1 \cdot p + (-1) \cdot q = p - q$$

By linearity:

$$E[S_n] = \sum_{i=1}^n E[X_i] = n(p - q)$$

Note: This uses linearity despite X_i not being independent!

Step 3: Special cases

- Fair coin ($p = q = 1/2$): $E[S_n] = 0$
- Biased ($p = 0.6$): $E[S_n] = n(0.6 - 0.4) = 0.2n$
- As $n \rightarrow \infty$ with $p > 1/2$: $E[S_n] \rightarrow \infty$

Example 4: Waiting for Patterns - Setup

Problem: Flip fair coin until pattern HTH appears. What's expected number of flips?

Step 1: Define states Let E = expected flips from start. Let:

- E_H = expected flips given we just saw H
- E_{HT} = expected flips given we just saw HT

Example 4: Waiting for Patterns - Equations

Step 2: Set up equations From start:

$$E = 1 + \frac{1}{2}E + \frac{1}{2}E_H$$

From state H:

$$E_H = 1 + \frac{1}{2}E_{HT} + \frac{1}{2}E_H \quad (\text{if T, go to HT; if H, stay at H})$$

From state HT:

$$E_{HT} = 1 + \frac{1}{2} \cdot 0 + \frac{1}{2}E_H \quad (\text{if H, done; if T, go to H})$$

Example 4: Waiting for Patterns - Solution

Step 3: Solve system Solving: $E = 10$, $E_H = 8$, $E_{HT} = 6$.

Result: Expect 10 flips to see HTH.

Note: Different patterns have different expected waiting times!

Summary and Key Formulas

Key Formulas 1: Expectation and Variance

1. Expectation:

$$E[X] = \begin{cases} \sum x p_X(x) & \text{(discrete)} \\ \int_{-\infty}^{\infty} x f_X(x) dx & \text{(continuous)} \end{cases}$$

2. Linearity: $E[aX + bY] = aE[X] + bE[Y]$

3. LOTUS: $E[g(X)] = \sum g(x)p_X(x)$ or $\int g(x)f_X(x)dx$

Key Formulas 2: Variance and Covariance

- 4. **Variance:** $\text{Var}(X) = E[(X - \mu)^2] = E[X^2] - (E[X])^2$
- 5. **Variance properties:** $\text{Var}(aX + b) = a^2\text{Var}(X)$
- 6. **Standard deviation:** $SD(X) = \sqrt{\text{Var}(X)}$
- 7. **Covariance:** $\text{Cov}(X, Y) = E[XY] - E[X]E[Y]$
- 8. **Correlation:** $\rho(X, Y) = \frac{\text{Cov}(X, Y)}{SD(X)SD(Y)}$

- 9. **Variance of sum:** $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$
- 10. **Independent sum:** If X, Y independent: $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y)$

Key Formulas 4: Conditional Expectation

1. Conditional expectation:

$$E[Y | X = x] = \begin{cases} \sum y P(Y = y | X = x) & \text{(discrete)} \\ \int_{-\infty}^{\infty} y f_{Y|X}(y | x) dy & \text{(continuous)} \end{cases}$$

2. Law of Total Expectation: $E[Y] = E[E[Y | X]]$

Key Formulas 5: Moment Generating Functions

3. **MGF:** $M_X(t) = E[e^{tX}]$
4. **Moments from MGF:** $E[X^n] = M_X^{(n)}(0)$
5. **MGF of sum:** If X, Y independent, $M_{X+Y}(t) = M_X(t)M_Y(t)$

Key Formulas 6: Important Inequalities

1. Markov's inequality: $P(X \geq a) \leq \frac{E[X]}{a}$ for $X \geq 0$
2. Chebyshev's inequality: $P(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$
3. Cauchy-Schwarz: $|E[XY]| \leq \sqrt{E[X^2]E[Y^2]}$
4. Jensen's inequality: $\varphi(E[X]) \leq E[\varphi(X)]$ for convex φ

Common Expectations and Variances

Distribution	PMF/PDF	$E[X]$	$\text{Var}(X)$
Bernoulli(p)	$p^x(1-p)^{1-x}$	p	$p(1-p)$
Binomial(n, p)	$\binom{n}{k}p^k(1-p)^{n-k}$	np	$np(1-p)$
Poisson(λ)	$\frac{e^{-\lambda}\lambda^k}{k!}$	λ	λ
Geometric(p)	$(1-p)^{k-1}p$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
Uniform(a, b)	$\frac{1}{b-a}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Exponential(λ)	$\lambda e^{-\lambda x}$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$
Normal(μ, σ^2)	$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$	μ	σ^2

When asked to find $E[X]$:

1. Check if X is sum of simpler RVs \rightarrow use linearity
2. Check if can use LOTUS \rightarrow compute $E[g(Y)]$ without finding distribution of $g(Y)$
3. Check if can use law of total expectation \rightarrow condition on appropriate variable
4. Check if known distribution \rightarrow use known formula

Problem-Solving Strategy 2: Finding $\text{Var}(X)$

When asked to find $\text{Var}(X)$:

1. Use formula $\text{Var}(X) = E[X^2] - (E[X])^2$
2. If X is sum, check if independent \rightarrow variance adds
3. If X is transformation of known RV, use properties

When dealing with dependence:

1. Use covariance/correlation to quantify dependence
2. Remember: independence \Rightarrow uncorrelated, but converse false
3. For variance of sum, always include covariance term

For inequalities:

1. Markov: for nonnegative RVs, bounds tail probability
2. Chebyshev: for any RV with finite variance, bounds deviation from mean
3. Cauchy-Schwarz: bounds covariance/correlation
4. Jensen: relates $E[g(X)]$ and $g(E[X])$ for convex/concave g

End of Chapter 4

Thank You!

Complete problem sets and solutions available at <http://stat110.net>

Next: Chapter 5 - Limit Theorems