

**Conformance test specifications for  
SAE J2945/1 - On-board System Requirements for  
V2V Safety Communications  
Test Suite Structure and Test Purposes (TSS & TP)**

|                     |                |
|---------------------|----------------|
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## Table of Contents

|       |  |    |
|-------|--|----|
| 1     | Scope.....   | 3  |
| 2     | References.....  | 3  |
| 2.1   | Normative References .....   | 3  |
| 2.2   | Informative References .....                                       | 4  |
| 3     | Definitions and Abbreviations .....                                | 4  |
| 3.1   | Definitions .....  | 4  |
| 3.2   | Abbreviations.....   | 4  |
| 4     | Prerequisites and Test Configurations .....                        | 4  |
| 4.1   | Test Configurations .....  | 4  |
| 4.2   | Feature Restriction and Pre-Enrolment .....                        | 6  |
| 4.2.1 | Feature Restriction .....  | 6  |
|       | States in Initial Conditions .....                                 | 7  |
| 4.3   | Variants, Variables and Snippet Naming Convention .....            | 7  |
| 5     | Test Suite Structure (TSS) .....                                   | 7  |
| 5.1   | Structure for Content and Accuracy Tests.....                      | 7  |
| 5.2   | Test Groups .....  | 8  |
| 5.2.1 | Root.....  | 8  |
| 5.2.2 | Groups.....  | 8  |
| 5.2.3 | Categories .....   | 8  |
| 6     | Test Purposes (TP).....  | 8  |
| 6.1   | Introduction .....   | 8  |
| 6.1.1 | TP Definition Conventions .....                                    | 8  |
| 6.1.2 | TP Identifier Naming Conventions .....                             | 9  |
| 6.1.3 | Rules for the Behavior Description .....                           | 9  |
| 6.1.4 | Sources of TP Definitions .....                                    | 9  |
| 6.2   | Test Purposes for BSM.....   | 10 |
| 6.2.1 | Transmission Requirements .....                                    | 10 |
| 6.2.2 | Message Identification .....                                       | 13 |
| 6.2.3 | Security .....   | 15 |
| 6.2.4 | Data Accuracy.....   | 19 |
| 6.2.5 | Internal Timing and Prioritization.....                            | 25 |
| 6.2.6 | Hardware.....  | 26 |
| 7     | Appendix.....  | 27 |
| 7.1   | Determining Randomness of Value Sets .....                         | 27 |
| 7.2   | Requirements Traceability Matrix (Requirement to Scenario).....    | 28 |
| 7.3   | Requirements traceability Matrix (Scenario to Test Procedure)..... | 41 |

|     |  |    |
|-----|--|----|
| 7.4 | Critical Event Flag Variant Table..... | 48 |
|     | Revision History .....                 | 49 |

## 1 Scope

This document provides the Test Suite Structure and Test Purposes for Basic Safety Message structure, content, and transmission as defined in SAE J2945/1 [1].

The ISO standard for the methodology of conformance testing (ISO/IEC 9646-1 [3] and ISO/IEC 9646-2 [4]) as well as the ETSI rules for conformance testing (ETS 300 406 [5]) are used as a basis for the test methodology.

## 2 References

### 2.1 Normative References

The following referenced documents are necessary for the application of the present document.

- [1] SAE J2945/1 (2016-03): "Surface Vehicle Standard: On-board Systems Requirements for V2V Safety Communications"
- [2] SAE J2735 (2016-01): "Dedicated Short Range Communication (DSRC) Message Set Dictionary"
- [3] ISO/IEC 9646-1 (1994): "Information technology -- Open Systems Interconnection -- Conformance testing methodology and framework - Part 1: General concepts".
- [4] ISO/IEC 9646-2 (1994): "Information technology -- Open Systems Interconnection -- Conformance testing methodology and framework -- Part 2: Abstract Test Suite specification".
- [5] ETSI ETS 300 406 (1995): "Methods for testing and Specification (MTS); Protocol and profile conformance testing specifications; Standardization methodology".
- [6] IEEE Std 1609.3-2016 "IEEE Standard for Wireless Access in Vehicular Environments (WAVE) — Network Services".
- [7] IEEE Std. 1609.2-2016: "IEEE Draft Standard for Wireless Access in Vehicular Environments - security Services for Applications and Management Messages".
- [8] IEEE Std. 1609.4-2016 "IEEE Standard for Wireless Access in Vehicular Environments (WAVE) -- Multi-Channel Operation".
- [9] IEEE Std. 1609.12-2016 "IEEE Standard for Wireless Access in Vehicular Environments – Identifier Allocations".
- [10] Conformance test specifications for Wireless Access in Vehicular Environments (WAVE) – 802.11 Test Suite Structure and Test Purposes (TSS & TP)

## 2.2 Informative References

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

- [i.1] ETSI EG 202 798 (V1.1.1): "Intelligent Transport Systems (ITS); Testing; Framework for conformance and interoperability testing".

## 3 Definitions and Abbreviations

### 3.1 Definitions

For the purposes of the present document, the terms and definitions are given in SAE J2735 [2] and SAE J2945/1 [1]

### 3.2 Abbreviations

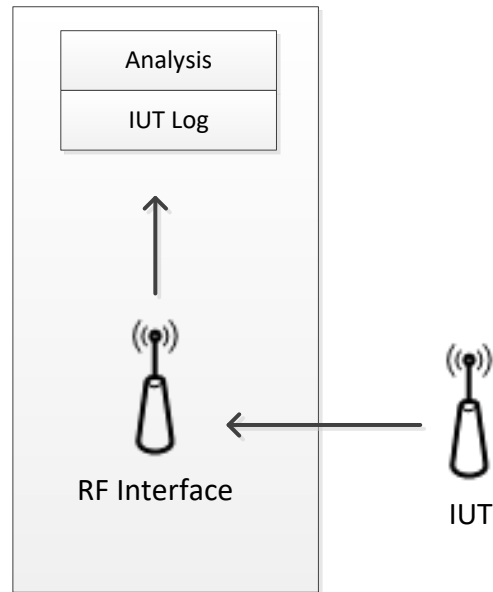
For the purposes of the present document, the following abbreviations apply:

|      |   |
|------|---|
| BI   | Behavior Invalid                          |
| BSM  | Basic Safety Message                      |
| BV   | Behavior Valid                            |
| CH   | Channel                                   |
| EDCA | Enhanced Distributed Channel Access       |
| ITS  | Intelligent Transport Systems             |
| IUT  | Implementation Under Test                 |
| MAC  | Medium Access Control                     |
| SAE  | Society of Automotive Engineers           |
| SCMS | Security Certificate Management System    |
| TAI  | International Atomic Time                 |
| TCI  | Test Control Interface                    |
| TP   | Test Purposes                             |
| TSS  | Test Suite Structure                      |
| V2V  | Vehicle-to-Vehicle                        |
| V2X  | Vehicle-to-Device                         |
| WAAS | Wide Area Augmentation System             |
| WAVE | Wireless Access in Vehicular Environments |
| WGS  | World Geodetic System                     |

## 4 Prerequisites and Test Configurations

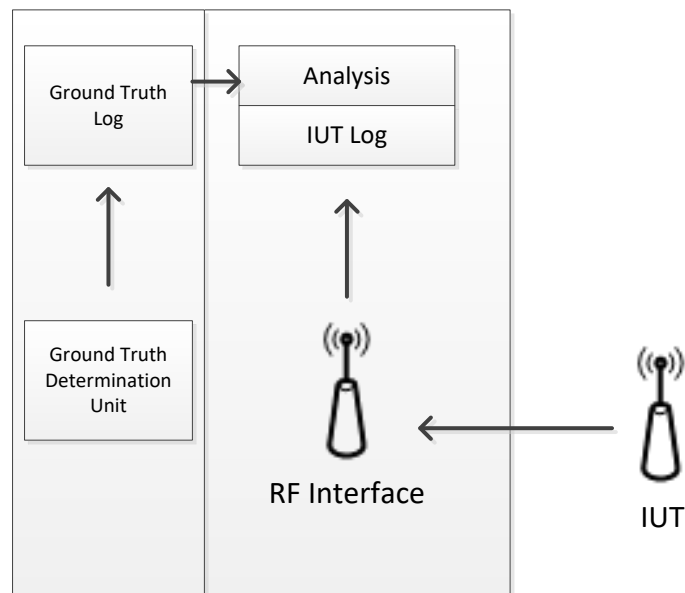
### 4.1 Test Configurations

This clause introduces the test configurations that are used for the definition of test purposes. The test configurations cover the various scenarios of the J2945/1 tests for BSM conformance. Distance between the IUT and the Test System shall not exceed five meters. In all test configurations antenna locations are located at an unspecified measured location and the test system is configured to account for the location.



**Figure 1: Test Configuration 1 (TC1)**

TC1 is used for bench tests that only require monitoring transmitted messages from a single isolated IUT. This configuration should be used for testing the functionality of the IUT in a non-strenuous environment.



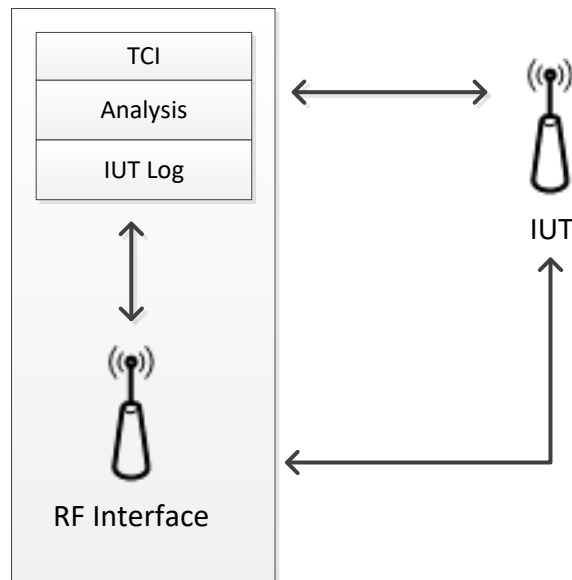
**Figure 2: Test Configuration 2 (TC2)**

TC2 is used for moving vehicle tests, related to event conditions and data accuracy. Both the IUT and test tool are mounted inside of the test vehicle.



**Figure 3: Test Configuration 3 (TC3)**

TC3 is used for situations in which the test operator requires the Test Control Interface (TCI) to execute tests on the IUT. This configuration should be used to test fringe cases that would be difficult to cause in a physical vehicle.



**Figure 4: Test Configuration 4 (TC4)**

TC4 is required for situations in which the IUT responds to BSMs sent from another source. The IUT, RF Interface, and Test System are located close enough to exchange messages.

## 4.2 Feature Restriction and Pre-Enrolment

### 4.2.1 Feature Restriction

In this clause all feature restrictions are listed:

- No external DSRC units within range of IUT, DSRC Test System, and DSRC Reference Unit are transmitting outside of the test setup.
- WAAS corrections are present for all devices.
- Signature and certificate content is assumed to be tested and validated through 1609.2 test method.
- Any reference to VehicleEventFlags only accounts for the Critical Event Flags: Hard Braking, ABS, Traction Control, and Stability Control. Testing is not required for any other VehicleEventFlags. All possible combinations of Critical Event Flags are organized in Section 7.6 of the Appendix.

## States in Initial Conditions

Each TP contains a pre-test condition. The pre-test condition defines the initial state in which the IUT has to be to apply the actual TP. Most of the TPs start from the “initial state” which is defined as follows:

- The IUT is powered up
- GNSS in open-sky conditions[1] is being received.
- Unless otherwise stated, the IUT is transmitting
- Unless otherwise stated, Congestion Control is enabled
- Unless otherwise stated, the IUT has the certificates available to successfully transmit BSMs for the duration of the test.
- Unless otherwise stated, the IUT is configured to transmit BSMs on a 10 MHz channel at vChannelNumber according to the built-in configuration and logic
- Unless otherwise stated, the IUT is configured to transmit BSMs using an 802.11 data rate of vDataRate

Some TPs start from a different initial condition which is explicitly defined in the TP. However, the “initial state” defined above is the starting point before the different initial conditions are established.

When the execution of the pre-test condition does not succeed, it leads to the assignment of an Inconclusive verdict.

### 4.3 Variants, Variables and Snippet Naming Convention

The TPs use the concept of variants. Their definition, how they are used and their naming conventions are defined in this clause.

**Variants:** In cases where for a single field multiple values can be tested, then a table is appended after the TP. This table lists all the different values which need to be tested. The TP identifier is appended with –X (e.g. **TP-BSM-ST-BV-01-X**).

**Vendor Tests:** In cases where requirements cannot be tested through black-box field tests (for example, hardware security or internal clock representation) these tests require hardware vendors to report on and confirm the functionality of the IUT. The TP identifier is appended with –V.

## 5 Test Suite Structure (TSS)

### 5.1 Structure for Content and Accuracy Tests

Table 1 shows the Test Suite Structure (TSS) including its subgroups defined for conformance testing.

**Table 1: TSS for BSM**

| Root | Group           | category |
|------|-----------------|----------|
| BSM  | Stationary Test | Valid    |
| BSM  | Stationary Test | Invalid  |
| BSM  | Moving Vehicle  | Valid    |
| BSM  | Moving Vehicle  | Invalid  |

The test suite is structured as a tree with the root defined as BSM. The tree is of rank 2 with the first rank a group and the second a category. The third rank is the standard ISO conformance test categories.

## 5.2 Test Groups

The test suite has a total of three levels. The first level is the root. The second level separates the root based on the IUT's operating condition. The third level is the standard ISO conformance test categories.

### 5.2.1 Root

The root identifies the on-board system requirements for V2V Safety Communications given in SAE J2945/1 [1].

### 5.2.2 Groups

This level contains two message types identified as:

Stationary Test: The IUT is tested without a vehicle

Moving Vehicle: The IUT must be connected to a test vehicle at all times during the test

### 5.2.3 Categories

This level contains the standard ISO conformance test categories limited to the behavior valid event and behavior invalid event.

## 6 Test Purposes (TP)

### 6.1 Introduction

#### 6.1.1 TP Definition Conventions

The TP definition is built according to EG 202 798 [i.1].

The TPs are defined by the rules shown in table 2.

**Table 2: TP definition rules**

|                     |  |
|---------------------|--|
| TP ID               | The TP ID is a unique identifier. It shall be specified according to the TP naming conventions defined in the clause below.  |
| Test Objective      | Short description of test purpose objective according to the requirements from the base standard.  |
| References          | The reference indicates the sub-clauses of the reference standard specifications in which the conformance requirement is expressed.  |
| Test Configuration  | References the test configuration selected for this TP   |
| Pre-test conditions | Define the initial state the IUT has to be in to apply the actual TP. In the corresponding Test Case, when the execution of the initial condition does not succeed, it leads to the assignment of an Inconclusive verdict.     |
| Test Sequence       | Definition of the events, which are parts of the TP objective, and the IUT are expected to perform in order to conform to the base specification. In the corresponding Test Case, Pass or Fail verdicts can be assigned there. |
| <b>Event Types</b>  |  |
| Stimulus            | Corresponds to an event that forces an IUT to proceed with a specific protocol action  |
| Check               | Ensures the conditions are appropriate to move to the next step in the test procedure,   |



|           |   |
|-----------|---|
|           | e.g. the receipt of protocol messages on reference points (i.e. output of the test system) with valid content, typically before the IUT stimulus is triggered. These events are not associated with the verdict evaluation (i.e. Pass/Fail) |
| Configure | Performs some internal modification of the IUT that places it in a specific behavior state  |
| Verify    | Consists of verifying that the IUT behaves according to the expected behavior (for instance the IUT behavior shows that it receives the expected message). Outcome of this event typically evaluate for verdict (i.e. Pass/Fail)            |
| Procedure | Procedural action directing the flow of TP execution.   |

### 6.1.2 TP Identifier Naming Conventions

The identifier of the TP is built according to table 2.

**Table 3: TP naming convention**

| Identifier | TP-<root>-<gr>-<x>-<nn>  |     |                                   |
|------------|--------------------------|-----|-----------------------------------|
|            | <root> = root            | BSM |                                   |
|            | <gr> = group             | ST  | Stationary Test                   |
|            |                          | MV  | Moving Vehicle                    |
|            | <x> = type of testing    | BV  | Valid Behaviour tests             |
|            |                          | BI  | Invalid Syntax or Behaviour Tests |
|            | <nn> = sequential number |     | 01 to 99                          |

### 6.1.3 Rules for the Behavior Description

The description of the TP is built according to EG 202 798 [i.1].

The base standards are not using finite state machine concept. As consequence, the test purposes use a generic "Initial State" that corresponds to a state where the IUT is ready for starting the test execution.

Being in the "Initial State" refers to the starting point of the initial device configuration. There are no pending actions, instantiated buffers, or variables which could disturb the execution of a test.

### 6.1.4 Sources of TP Definitions

All TPs are specified according to SAE J2735 [2] and SAE J2945/1 [1].

## 6.2 Test Purposes for BSM

### 6.2.1 Transmission Requirements

|  |             |   |                |
|--|-------------|---|----------------|
| <b>Identifier</b>  |             | TP-BSM-ST-BV-01-X   |                |
| <b>Test Objective</b>  |             | Verify that DE_VehicleEventFlags is only included if an event is occurring and is not included if an event is not occurring                         |                |
| <b>Test Configuration</b>  |             | TC3   |                |
| <b>Reference:</b>  |             | V2V-BSMTX-BSMCONT-006, V2V-STD-J2735-040  |                |
| <b>Pre-test conditions</b>   |             |   |                |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• No conditions corresponding to an event flag are met</li></ul> |             |   |                |
| <b>Test Sequence</b>   |             |   |                |
| <b>Step</b>  | <b>Type</b> | <b>Description</b>  | <b>Verdict</b> |
| 1  | Verify      | A BSM is transmitted with the DE_VehicleEventFlags element not included   | Pass / Fail    |
| 2  | Stimulus    | One set of conditions ( <b>X</b> ) corresponding to an <b>Event Flag</b> is met as per Section 7.4  |                |
| 3  | Verify      | A BSM is transmitted with the DE_VehicleEventFlags element included within time period = 50 ms  | Pass / Fail    |
| 4  | Verify      | A BSM is transmitted with the DE_VehicleEventFlags element included with corresponding bits set according to <b>Bit Location</b> as per Section 7.4 | Pass / Fail    |
| 5  | Stimulus    | The previously set of <b>Event Flags</b> are removed  |                |
| 6  | Verify      | The BSM contains no DE_VehicleEventFlags within time period = vEventDetectLatency   | Pass / Fail    |
| 7  | Procedure   | Steps 2 – 6 are repeated for variants from the Variants table in Section 7.4  |                |

|   |   |   |             |
|---|---|---|-------------|
| Identifier  | TP-BSM-ST-BV-02   |   |             |
| Test Objective  | Verify that the first BSM transmitted after device restart uses a random time |   |             |
| Test Configuration  | TC3   |   |             |
| Reference:  | V2V-BSMTX-GENTIM-001  |   |             |
| Pre-test conditions   |   |   |             |
| <ul style="list-style-type: none"><li>The IUT is configured to transmit BSMs automatically upon restart</li><li>The IUT is in the initial state</li></ul> |   |   |             |
| Test Sequence   |   |   |             |
| Step  | Type  | Description   | Verdict     |
| 1   | Stimulus  | The device is restarted   |             |
| 2   | Procedure   | The BSM is transmitted and the time stamp from the sniffer on reception is recorded   |             |
| 3   | Procedure   | Steps 1 – 2 are repeated enough times to ensure a statistically significant sample size, as defined in Section 7.1  |             |
| 4   | Verify  | The sample of millisecond values modded by 100 from the samples of start times is deemed sufficiently random according to criteria set in Section 7.1, where the average is 49.5 +/- 2.5 and the tolerance for the standard deviation is 28.6 +/- 1.5 | Pass / Fail |

|  |  |  |                                    |
|--|--|--|------------------------------------|
| Identifier   | TP-BSM-ST-BV-03-X  |  |                                    |
| Test Objective   | Verify BSMs are transmitted with correct contents and transmission parameters  |  |                                    |
| Test Configuration   | TC1  |  |                                    |
| Reference:   | [1] V2V-BSMTX-BSMCONT-[001-004], V2V-BSMTX-CHDATARATE-[001-002], V2V-STD-J2735-[001-015, 020-039, 041-045], V2V-BSMTX-DATAACC-001, V2V-BSMTX-MINTX-001 |  |                                    |
| Pre-test conditions  |  |  |                                    |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>Congestion Control is turned off</li></ul> |  |  |                                    |
| Test Sequence  |  |  |                                    |
| Step   | Type   | Description  | Verdict                            |
| 1  | Stimulus   | A BSM is transmitted   |                                    |
| 2  | Verify   | The BSM is signed using credentials defined by 1609.2 [6]                          | Pass / Fail                        |
| 3  | Verify   | The BSM is transmitted using a WAVE Short Message containing WSM version =3        | Pass / Fail                        |
| 4  | Verify   | The BSM is encoded using Unaligned Packed Encoding Rules (UPER)                    | Pass / Fail                        |
| 5  | Verify   | The BSM contains <b>X_BSM_CONTENT</b> with value <b>X_FRAME_VALUE</b>              | Pass / Fail                        |
| 6  | Procedure  | Repeat steps 1-5 for all variants of <b>X_BSM_CONTENT</b> and <b>X_FRAME_VALUE</b> |                                    |
| 7  | Verify   | The BSMs are transmitted on vChannelNumber   | Pass / Fail                        |
| 8  | Verify   | The BSMs are transmitted at a data rate of vDataRate                               | Pass / Fail                        |
| Variants   |  |  |                                    |
| X  | X_BSM_CONTENT  |  | X_FRAME_VALUE                      |
| 1  | DE_DSRC_MessageID, contained within Part I [V2V-STD-J2735-002]   |  | 20                                 |
| 2  | DF_BSMcoreData, contained within Part I [V2V-STD-J2735-007]  |  | Valid Frame                        |
| 3  | DF_PositionalAccuracy, contained within DF_BSMcoreData [V2V-STD-J2735-012]   |  | Valid Frame                        |
| 4  | DE_SemiMajorAxisAccuracy, contained within DF_PositionalAccuracy [V2V-STD-J2735-030]   |  | 0 <= Value <= 255                  |
| 5  | DE_SemiMajorAxisOrientation, contained within DF_PositionalAccuracy [V2V-STD-J2735-031]  |  | 0 <= Value <= 65535                |
| 6  | DE_SemiMinorAxisAccuracy, contained within DF_PositionalAccuracy [V2V-STD-J2735-032]   |  | 0 <= Value <= 255                  |
| 7  | DE_DSecond, contained within DF_BSMcoreData [V2V-STD-J2735-021]  |  | 0 <= Value <= 60999                |
| 8  | DE_Elevation, contained within DF_BSMcoreData [V2V-STD-J2735-022]  |  | -4096 <= Value <= 61439            |
| 9  | DE_Heading, contained within DF_BSMcoreData [V2V-STD-J2735-024]  |  | 0 <= Value <= 28800                |
| 10   | DE_Latitude, contained within DF_BSMcoreData [V2V-STD-J2735-025]   |  | -900000000 <= Value <= 900000001   |
| 11   | DE_Longitude, contained within DF_BSMcoreData [V2V-STD-J2735-026]  |  | -1799999999 <= Value <= 1800000001 |
| 12   | DE_MsgCount, contained within DF_BSMcoreData [V2V-STD-J2735-027]   |  | 0 <= Value <=127                   |
| 13   | DE_Speed, contained within DF_BSMcoreData [V2V-STD-J2735-033]  |  | 0 <= Value <= 8191                 |
| 14   | DE_SteeringWheelAngle, contained within DF_BSMcoreData [V2V-STD-J2735-035]   |  | -126 <= Value <= 127               |

|    |  |                            |
|----|--|----------------------------|
| 15 | DE_TemporaryID, contained within DF_BSMcoreData<br>[V2V-STD-J2735-036]                         | Octet String, Size 4       |
| 16 | DE_TransmissionState, contained within DF_BSMcoreData<br>[V2V-STD-J2735-039]                   | Enumerated (0 - 7)         |
| 17 | DF_BrakeSystemStatus, contained within DF_BSMcoreData<br>[V2V-STD-J2735-006]                   | Valid Frame                |
| 18 | DE_TractionControlStatus, contained within DF_BrakeSystemStatus<br>[V2V-STD-J2735-038]         | Enumerated (0 - 3)         |
| 19 | DE_StabilityControlStatus, contained within DF_BrakeSystemStatus<br>[V2V-STD-J2735-034]        | Enumerated (0 - 3)         |
| 20 | DF_AccelerationSet4Way, contained within DF_BSMcoreData<br>[V2V-STD-J2735-005]                 | Valid Frame                |
| 21 | DE_Acceleration (Lateral), contained within DF_AccelerationSet4Way<br>[V2V-STD-J2735-015]      | -2000 <= Value <= 2001     |
| 22 | DE_Acceleration (Longitudinal), contained within DF_AccelerationSet4Way<br>[V2V-STD-J2735-015] | -2000 <= Value <= 2001     |
| 23 | DE_VerticalAcceleration, contained within DF_AccelerationSet4Way<br>[V2V-STD-J2735-043]        | -127 <= Value <= 127       |
| 24 | DE_YawRate, contained within DF_AccelerationSet4Way<br>[V2V-STD-J2735-045]                     | -32767 <= Value <= 32767   |
| 25 | DF_VehicleSize, contained within DF_BSMcoreData<br>[V2V-STD-J2735-014]                         | Valid Frame                |
| 26 | DE_VehicleLength, contained within DF_VehicleSize<br>[V2V-STD-J2735-041]                       | 0 <= Value <= 4095         |
| 27 | DE_VehicleWidth, contained within DF_VehicleSize<br>[V2V-STD-J2735-042]                        | 0 <= Value <= 1023         |
| 28 | DF_VehicleSafetyExtensions, contained within Part II<br>[V2V-STD-J2735-013]                    | Valid Frame                |
| 29 | DF_PathHistory, contained within DF_VehicleSafetyExtensions<br>[V2V-STD-J2735-008]             | Valid Frame                |
| 30 | DF_PathHistoryPointList, contained within DF_PathHistory<br>[V2V-STD-J2735-009]                | Valid Frame                |
| 31 | DE_OffsetLL-B18, contained within DF_PathHistoryPointList<br>[V2V-STD-J2735-028]               | -131072 <= Value <= 131071 |
| 32 | DF_PathHistoryPoint, contained within DF_PathHistoryPointList<br>[V2V-STD-J2735-010]           | Valid Frame                |
| 33 | DE_TimeOffset, contained within DF_PathHistoryPoint<br>[V2V-STD-J2735-037]                     | 1 <= Value <= 65535        |
| 34 | DE_VertOffset-B12, contained within DF_PathHistoryPoint<br>[V2V-STD-J2735-044]                 | -2048 <= Value <= 2047     |
| 35 | DE_ExteriorLights, contained within DF_VehicleSafetyExtensions<br>[V2V-STD-J2735-023]          | Bit String, Size (9, ...)  |
| 36 | DF_PathPrediction, contained within DF_VehicleSafetyExtensions<br>[V2V-STD-J2735-011]          | Valid Frame                |
| 37 | DE_Confidence, contained within DF_PathPrediction<br>[V2V-STD-J2735-020]                       | 0 <= Value <= 200          |
| 38 | DE_RadiusOfCurvature, contained within DF_PathPrediction<br>[V2V-STD-J2735-029]                | -32767 <= Value <= 32767   |

|                   |                 |
|-------------------|-----------------|
| <b>Identifier</b> | TP-BSM-ST-BV-04 |
|-------------------|-----------------|

|  |   |   |             |
|--|---|---|-------------|
| Test Objective   | Verify that BSMs are generated randomly within $-vBSMRateTolerance$ and $+vBSMRateTolerance$ of their scheduled generation time |   |             |
| Test Configuration   | TC1   |   |             |
| Reference:   | V2V-BSMTX-GENTIM-002  |   |             |
| Pre-test conditions  |   |   |             |
| <ul style="list-style-type: none"><li>There are no external messages being transmitted that influence the Congestion Control</li><li>The IUT is configured to transmit BSMs automatically upon restart</li><li>The IUT is in the initial state</li></ul> |   |   |             |
| Test Sequence  |   |   |             |
| Step   | Type  | Description   | Verdict     |
| 1  | Stimulus  | The device is restarted.  |             |
| 2  | Procedure   | A BSM is transmitted at 10 hz nominally and the sniffer timestamp at reception is recorded. |             |
| 3  | Procedure   | The exact reception time of the BSM is within $-vBSMRateTolerance$ and $+vBSMRateTolerance$ |             |
| 4  | Verify  | Step 3 is repeated a statistically significant amount of times as defined by Section 7.1.   | Pass / Fail |

### 6.2.2 Message Identification

|                                   |  |   |             |
|-----------------------------------|--|---|-------------|
| Identifier                        | TP-BSM-ST-BV-05  |   |             |
| Test Objective                    | Verify identification data is randomized to facilitate user privacy after certificate expiration |   |             |
| Test Configuration                | TC1  |   |             |
| Reference:                        | V2V-BSMTX-DATAACC-[003,006], V2V-SECPRIV-IDRAND-002, V2V-SECPRIV-BSMSIGN-008                     |   |             |
| Pre-test conditions               |  |   |             |
| ● The IUT is in its initial state |  |   |             |
| Test Sequence                     |  |   |             |
| Step                              | Type   | Description   | Verdict     |
| 1                                 | Stimulus   | Two BSMs are transmitted without a certificate change   |             |
| 2                                 | Verify   | DE_MsgCount is incremented between BSMs   | Pass / Fail |
| 3                                 | Verify   | DSRC MAC address does not change  | Pass / Fail |
| 4                                 | Verify   | DE_TemporaryID does not change  | Pass / Fail |
| 5                                 | Stimulus   | Certificate expiration causes a certificate change  |             |
| 6                                 | Stimulus   | A first BSM is transmitted after certificate change   |             |
| 7                                 | Verify   | The IUT populates a value for DE_MsgCount   | Pass / Fail |
| 8                                 | Verify   | The IUT populates a value for DE_TemporaryID  | Pass / Fail |
| 9                                 | Verify   | The IUT populates a value for DSRC MAC Address  | Pass / Fail |
| 10                                | Verify   | A full certificate is attached to the BSM   | Pass / Fail |
| 11                                | Procedure  | Steps 5 – 10 are repeated a statistically significant amount of times as defined by Section 7.1   |             |
| 12                                | Verify   | DE_MsgCount’s values over the previous iterations are random according to criteria set in Section 7.1, where the average is 63.5 +/- 6.4 and the standard deviation is 36.7 +/- 1.9                                     | Pass / Fail |
| 13                                | Verify   | DE_TemporaryID’s values over the previous iterations are random according to criteria set in Section 7.1, where the average is 2,147,483,648 +/- 214,748,364 and the standard deviation is 1,239,850,262 +/- 61,992,513 | Pass / Fail |
| 14                                | Verify   | DSRC MAC Address’ values over the previous iterations are random according to criteria set in Section 7.1, where the average is   | Pass / Fail |

|  |  |   |  |
|--|--|---|--|
|  |  | 1.41e+14 +/- 1.41e+13 and the tolerance for the standard deviation is 8.13e+13 +/- 4.07e+12 |  |
|--|--|---|--|

|  |   |   |             |
|--|---|---|-------------|
| Identifier   | TP-BSM-ST-BV-06   |   |             |
| Test Objective   | Verify DE_MsgCount is properly incremented and rolls over when reaching 127 and DE_TemporaryID is not changed |   |             |
| Test Configuration   | TC1   |   |             |
| Reference:   | V2V-BSMTX-DATAACC-[004, 007]  |   |             |
| Pre-test conditions  |   |   |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• The IUT is configured to transmit BSMs, with the first’s DE_MsgCount less than 127</li><li>• The security certificate does not change during this test</li></ul> |   |   |             |
| Test Sequence  |   |   |             |
| Step   | Type  | Description   | Verdict     |
| 1  | Stimulus  | Two BSMs are transmitted, the first with a DE_MsgCount less than 127            |             |
| 2  | Verify  | The DE_TemporaryIDs of both BSMs are identical                                  | Pass / Fail |
| 3  | Verify  | DE_MsgCount of the second of the two BSMs is one greater than first DE_MsgCount | Pass / Fail |
| 4  | Procedure   | The IUT continues to send BSMs until the DE_MsgCount of a BSM is exactly 127    |             |
| 5  | Stimulus  | A BSM is transmitted  |             |
| 6  | Verify  | DE_TemporaryID has not changed  | Pass / Fail |
| 7  | Verify  | DE_MsgCount of the previous BSM is 0  | Pass / Fail |

|                                   |             |   |                |
|-----------------------------------|-------------|---|----------------|
| <b>Identifier</b>                 |             | TP-BSM-ST-BV-07   |                |
| <b>Test Objective</b>             |             | Verify identification data is randomized to facilitate user privacy after device restart  |                |
| <b>Test Configuration</b>         |             | TC3   |                |
| <b>Reference:</b>                 |             | V2V-BSMTX-DATAACC-[002,005], V2V-SECPRIV-IDRAND-001   |                |
| <b>Pre-test conditions</b>        |             |   |                |
| ● The IUT is in its initial state |             |   |                |
| <b>Test Sequence</b>              |             |   |                |
| <b>Step</b>                       | <b>Type</b> | <b>Description</b>  | <b>Verdict</b> |
| 1                                 | Stimulus    | The IUT is restarted  |                |
| 2                                 | Stimulus    | A BSM is transmitted  |                |
| 3                                 | Verify      | The IUT populates a value for DE_MsgCount   | Pass / Fail    |
| 4                                 | Verify      | The IUT populates a value for DE_TemporaryID  | Pass / Fail    |
| 5                                 | Verify      | The IUT populates a value for DSRC MAC Address  | Pass / Fail    |
| 6                                 | Procedure   | Steps 1 – 5 are repeated a statistically significant amount of times as defined in Section 7.1  |                |
| 7                                 | Verify      | DE_MsgCount’s values over the previous iterations are random according to criteria set in Section 7.1, where the average is 63.5 +/- 6.4 and the standard deviation is 36.7 +/- 1.9                                     | Pass / Fail    |
| 8                                 | Verify      | DE_TemporaryID’s values over the previous iterations are random according to criteria set in Section 7.1, where the average is 2,147,483,648 +/- 214,748,364 and the standard deviation is 1,239,850,262 +/- 61,992,513 | Pass / Fail    |
| 9                                 | Verify      | DSRC MAC Address’ values over the previous iterations are random according to criteria set in Section 7.1, where the average is   | Pass / Fail    |

|  |  |   |  |
|--|--|---|--|
|  |  | 1.41e+14 +/- 1.41e+13 and the tolerance for the standard deviation is 8.13e+13 +/- 4.07e+12 |  |
|--|--|---|--|

### 6.2.3 Security

|                                   |  |   |             |
|-----------------------------------|--|---|-------------|
| Identifier                        | TP-BSM-ST-BV-08  |   |             |
| Test Objective                    | Verify the IUT signs every BSM and attaches a certificate or certificate digest to every BSM |   |             |
| Test Configuration                | TC1  |   |             |
| Reference:                        | V2V-SECPRIV-BSMSIGN-[001-002]  |   |             |
| Pre-test conditions               |  |   |             |
| ● The IUT is in the initial state |  |   |             |
| Test Sequence                     |  |   |             |
| Step                              | Type   | Description   | Verdict     |
| 1                                 | Stimulus   | A BSM is transmitted  |             |
| 2                                 | Verify   | A full certificate or certificate digest is attached to the BSM | Pass / Fail |
| 3                                 | Verify   | The BSM is signed by the certificate stored in the IUT          | Pass / Fail |

|                                   |  |  |             |
|-----------------------------------|--|--|-------------|
| Identifier                        | TP-BSM-ST-BV-09  |  |             |
| Test Objective                    | Verify the IUT attaches full certificates after vMaxCertDigestInterval or more has passed since the previous transmission of a certificate |  |             |
| Test Configuration                | TC1  |  |             |
| Reference:                        | V2V-SECPRIV-BSMSIGN-003  |  |             |
| Pre-test conditions               |  |  |             |
| ● The IUT is in the initial state |  |  |             |
| Test Sequence                     |  |  |             |
| Step                              | Type   | Description  | Verdict     |
| 1                                 | Stimulus   | A BSM is transmitted with a full certificate   |             |
| 2                                 | Stimulus   | Wait for the next BSM with full certificate attached to be transmitted                                     |             |
| 3                                 | Verify   | A BSM is transmitted with a full certificate attached within interval not exceeding vMaxCertDigestInterval | Pass / Fail |

|   |  |  |             |
|---|--|--|-------------|
| Identifier  | TP-BSM-ST-BV-10-X  |  |             |
| Test Objective  | Verify the IUT attaches a full certificate when a Critical Event Flag is set |  |             |
| Test Configuration  | TC3  |  |             |
| Reference:  | V2V-SECPRIV-BSMSIGN-004  |  |             |
| Pre-test conditions   |  |  |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>No event conditions are present</li></ul> |  |  |             |
| Test Sequence   |  |  |             |
| Step  | Type   | Description  | Verdict     |
| 1   | Verify   | The IUT transmits BSMs containing no DE_VehicleEventFlags element                                | Pass / Fail |
| 2   | Stimulus   | A critical <b>Event Flag</b> set is raised   |             |
| 3   | Verify   | The BSM contains a full certificate attached to the BSM is transmitted                           | Pass / Fail |
| 4   | Stimulus   | The critical Event Flag set is cleared   |             |
| 5   | Procedure  | Steps 1 – 4 are repeated for all critical event flag sets from the Variants table in Section 7.4 |             |

|   |  |  |             |
|---|--|--|-------------|
| Identifier  | TP-BSM-ST-BV-11  |  |             |
| Test Objective  | Verify the IUT does not transmit BSMs if no certificates are available |  |             |
| Test Configuration  | TC1  |  |             |
| Reference:  | V2V-SECPRIV-BSMSIGN-[005, 006]   |  |             |
| Pre-test conditions   |  |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• One certificate is available on the IUT</li><li>• The radio is prevented from receiving new certificates</li><li>• Certificate expiration does not occur unless explicitly stated</li></ul> |  |  |             |
| Test Sequence   |  |  |             |
| Step  | Type   | Description  | Verdict     |
| 1   | Check  | At least one BSM is transmitted  |             |
| 2   | Stimulus   | Certificate validity has expired in the IUT and no other certificates are made available |             |
| 3   | Verify   | BSMs are not transmitted for 5 seconds   | Pass / Fail |

|   |  |  |             |
|---|--|--|-------------|
| Identifier  | TP-BSM-ST-BV-12  |  |             |
| Test Objective  | Verify the IUT does not transmit BSMs with certificates on a revocation list |  |             |
| Test Configuration  | TC1  |  |             |
| Reference:  | V2V-SECPRIV-CERTREV-001  |  |             |
| Pre-test conditions   |  |  |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>One certificate is available on the IUT</li></ul> |  |  |             |
| Test Sequence   |  |  |             |
| Step  | Type   | Description  | Verdict     |
| 1   | Verify   | At least one BSM is transmitted  | Pass / Fail |
| 2   | Stimulus   | The one certificate is placed on the revocation list                       |             |
| 3   | Configure  | The IUT received and verifies an update certificate revocation list        |             |
| 4   | Verify   | The IUT does not transmit BSMs with that revoked certificate for 5 seconds | Pass / Fail |

|                                   |   |   |             |
|-----------------------------------|---|---|-------------|
| Identifier                        | TP-BSM-ST-BV-13   |   |             |
| Test Objective                    | After a device startup, the first BSM transmitted by the IUT has an entire certificate attached |   |             |
| Test Configuration                | TC3   |   |             |
| Reference:                        | V2V-SECPRIV-BSMSIGN-007   |   |             |
| Pre-test conditions               |   |   |             |
| ● The IUT is in the initial state |   |   |             |
| Test Sequence                     |   |   |             |
| Step                              | Type  | Description                               | Verdict     |
| 1                                 | Stimulus  | The IUT is restarted                      |             |
| 2                                 | Verify  | The IUT transmits the first BSM           | Pass / Fail |
| 3                                 | Verify  | The first BSM contains a full certificate | Pass / Fail |

|                     |  |
|---------------------|--|
| Identifier          | TP-BSM-ST-BV-14-V  |
| Test Objective      | Verify storage of certificates                                 |
| Test Configuration  | TC1  |
| Reference:          | V2V-SECMGMT-CERTSTORE-[001-004], V2V-SECMGMT-CRLLOAD-[001-002] |
| Pre-test conditions |  |



| <ul style="list-style-type: none"> <li>The IUT is off</li> </ul> |           |   |             |
|--|-----------|---|-------------|
| Test Sequence  |           |   |             |
| Step   | Type      | Description   | Verdict     |
| 1  | Stimulus  | The IUT is turned on  |             |
| 2  | Verify    | The vendor's report indicates that the IUT has at least vCertNvMemSize of non-volatile memory for storage of pseudonym certificates               | Pass / Fail |
| 3  | Verify    | The vendor's report indicates that the IUT has at least vCrIStoreSize of non-volatile memory for storing the Certificate Revocation List          | Pass / Fail |
| 4  | Verify    | The vendor's report indicates that the IUT has at least vSecMemSize of secure memory available for data requiring secure storage                  | Pass / Fail |
| 5  | Stimulus  | The IUT retrieves an individual pseudonym certificate, RA address, RA intermediate CA, PCA certificate, System configuration, and security policy |             |
| 6  | Configure | The IUT retrieves Root CA certificate, Enrollment certificate, and system private keys  |             |
| 7  | Verify    | The vendor's report indicates that the data retrieved in Step 5 is contained within secure, tamper-evident, non-volatile memory                   | Pass / Fail |
| 8  | Stimulus  | The IUT retrieves a Certificate Revocation List   |             |
| 9  | Verify    | The vendor's report indicates that the Certificate Relocation List is stored in non-volatile memory   | Pass / Fail |

|  |  |  |             |
|--|--|--|-------------|
| Identifier   | TP-BSM-ST-BV-15                                  |  |             |
| Test Objective   | Verify the IUT’s ability to verify incoming BSMs |  |             |
| Test Configuration   | TC4  |  |             |
| Reference:   | V2V-SECPRIV-BSMVERIFY-001                        |  |             |
| Pre-test conditions  |  |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• IUT is configured to verify all BSMs</li></ul> |  |  |             |
| Test Sequence  |  |  |             |
| Step   | Type   | Description  | Verdict     |
| 1  | Stimulus   | A signed BSM with a full certificate is transmitted from the reference unit to the IUT                                     |             |
| 2  | Verify   | The IUT verifies the BSM, resulting in success   | Pass / Fail |
| 3  | Stimulus   | A signed BSM with a certificate digest of the previous BSM’s certificate is transmitted from the reference unit to the IUT |             |
| 4  | Verify   | The IUT verifies the BSM using the previous BSM’s full certificate, resulting in success                                   | Pass / Fail |

|                                   |  |  |         |
|-----------------------------------|--|--|---------|
| Identifier                        | TP-BSM-ST-BV-16-V  |  |         |
| Test Objective                    | Verify the IUT’s ability to securely update root CA certificates |  |         |
| Test Configuration                | TC1  |  |         |
| Reference:                        | V2V-SECMGMT-CERTLOAD-001   |  |         |
| Pre-test conditions               |  |  |         |
| ● The IUT is in the initial state |  |  |         |
| Test Sequence                     |  |  |         |
| Step                              | Type   | Description  | Verdict |
| 1                                 | Configure  | The computer interface makes an updated root CA certificate available on the SCMS device |         |
| 2                                 | Configure  | The IUT is configured to attempt to update its root CA certificate                       |         |

|   |        |  |             |
|---|--------|--|-------------|
| 3 | Verify | The IUT's root CA is updated with the SCMS device's CA                   | Pass / Fail |
| 4 | Verify | The vendor's report indicates that the IUT's root CA is updated securely | Pass / Fail |

|  |             |  |                |
|--|-------------|--|----------------|
| <b>Identifier</b>  |             | TP-BSM-ST-BV-17-X  |                |
| <b>Test Objective</b>  |             | Verify certificate is not changed during event conditions unless the certificate expires         |                |
| <b>Test Configuration</b>  |             | TC3  |                |
| <b>Reference:</b>  |             | V2V-SECPRIV-CERTCHG-002  |                |
| <b>Pre-test conditions</b>   |             |  |                |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• Certificate expiration does not occur unless explicitly stated</li><li>• No event flag on the IUT is set</li></ul> |             |  |                |
| <b>Test Sequence</b>   |             |  |                |
| <b>Step</b>  | <b>Type</b> | <b>Description</b>   | <b>Verdict</b> |
| 1  | Verify      | The IUT transmits BSMs with the DE_VehicleEventFlags element not included                        | Pass / Fail    |
| 2  | Stimulus    | One critical set of <b>Event Flag</b> from Section 7.4 is set                                    |                |
| 3  | Verify      | The IUT transmits BSM containing full security certificate                                       | Pass / Fail    |
| 4  | Verify      | The certificate of the BSM Transmitted in Step 1 and the BSM Transmitted in Step 3 are identical | Pass / Fail    |
| 5  | Stimulus    | The certificate expiration time passes while the <b>Event Flag</b> set remains persistent        |                |
| 6  | Stimulus    | vCertChangeInterval time passes while the <b>Event Flag</b> set remains persistent               |                |
| 7  | Stimulus    | The IUT transmits at least one BSM   |                |
| 8  | Verify      | The certificate of Step 7’s BSM and Step 3’s BSM are different                                   | Pass / Fail    |
| 9  | Procedure   | Steps 1 – 7 are repeated for all critical event sets from Section 7.4                            |                |

|  |   |   |             |
|--|---|---|-------------|
| Identifier   | TP-BSM-MV-BV-01   |   |             |
| Test Objective   | Verify certificate is not changed if travel distance is less than vCertChangeDistance unless reset or the certificate expires |   |             |
| Test Configuration   | TC2   |   |             |
| Reference:   | V2V-SECPRIV-CERTCHG-[001, 003]  |   |             |
| Pre-test conditions  |   |   |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>Certificate change does not occur unless explicitly stated</li></ul> |   |   |             |
| Test Sequence  |   |   |             |
| Step   | Type  | Description   | Verdict     |
| 1  | Stimulus  | The IUT travels a distance up to vCertChangeDistance while continually transmitting BSMs over a course of time exceeding 3 times vCertChangeInterval                              |             |
| 2  | Verify  | All BSMs transmitted in Step 1 have identical certificates  | Pass / Fail |
| 3  | Stimulus  | The IUT travels more than vCertChangeDistance from the starting point   |             |
| 4  | Stimulus  | vCertChangeInterval time passes   |             |
| 4  | Verify  | BSMs transmitted after vCertChangeInterval time passes have a different certificate than those transmitted before traveling more than vCertChangeDistance from the starting point | Pass / Fail |

|   |          |  |             |
|---|----------|--|-------------|
| 5 | Stimulus | Time passes until certificate expiration while the vehicle moved less than vCertChangeDistance   |             |
| 6 | Verify   | BSMs transmitted after certificate expiration have a different certificates  | Pass / Fail |
| 7 | Stimulus | The IUT is reset while the vehicle position changes less than vCertChnageDistance from the previous position of the certificate change |             |
| 8 | Verify   | BSMs transmitted after reset have a different certificate than those transmitted after certificate expiration                          | Pass / Fail |

#### 6.2.4 Data Accuracy

|  |  |  |             |
|--|--|--|-------------|
| Identifier   | TP-BSM-ST-BV-18                          |  |             |
| Test Objective   | Verify data retention across IUT restart |  |             |
| Test Configuration   | TC3                                      |  |             |
| Reference:   | V2V-BSMTX-DATAPERSIST-[001-004]          |  |             |
| Pre-test conditions  |  |  |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>The IUT has a last known heading value and a last known path history</li></ul> |  |  |             |
| Test Sequence  |  |  |             |
| Step   | Type                                     | Description  | Verdict     |
| 1  | Stimulus                                 | The IUT travels at a speed greater than vHeadingSpeedThresh to allow the IUT to lock its heading |             |
| 2  | Verify                                   | The IUT transmits at least one BSM   | Pass / Fail |
| 3  | Stimulus                                 | The IUT is restarted   |             |
| 4  | Check                                    | The IUT completes restart  |             |
| 5  | Verify                                   | The IUT transmits at least one BSM   | Pass / Fail |
| 6  | Verify                                   | The last known headings of both BSMs are identical   | Pass / Fail |
| 7  | Verify                                   | The last known path histories of both BSMs are identical   | Pass / Fail |

|   |  |  |             |
|---|--|--|-------------|
| Identifier  | TP-BSM-MV-BV-02-V  |  |             |
| Test Objective  | Verify accuracy of localization data provided by IUT   |  |             |
| Test Configuration  | TC2  |  |             |
| Reference:  | V2V-POSTIM-WAAS-001, V2V-POSTIM-COORDSYSREF-001,<br>V2V-BSMTX-DATAACC-[011-014, 017, 024-027], V2V-POSTIM-POSDETER-001 |  |             |
| Pre-test conditions   |  |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• WAAS is available to the IUT (Note: Because WAAS must always available to the IUT to achieve the required accuracy, the effects of removing WAAS cannot be tested)</li><li>• All tests to be conducted are Open Sky and all road test conditions are of a grade less than .2% and a cross-slope less than .2%</li></ul> |  |  |             |
| Test Sequence   |  |  |             |
| Step  | Type   | Description  | Verdict     |
| 1   | Stimulus   | A statistically significant amount of BSMs are transmitted by the IUT as defined by Section 7.1          |             |
| 2   | Verify   | The IUT transmits BSMs with the correct coordinates and confidences based on the GNSS positioning system | Pass / Fail |
| 3   | Verify   | The vendor’s report indicates that the GNSS reading is supplemented with WAAS correction                 | Pass / Fail |

|    |        |  |             |
|----|--------|--|-------------|
| 4  | Verify | The horizontal position is given with reference to the WGS-84 coordinate system  | Pass / Fail |
| 5  | Verify | The DE_Longitude and DE_Latitude values are within vPosAccuracy of the baseline position under open sky conditions over 68% of the test measurements as compared to the 2D position of Ground Truth  | Pass / Fail |
| 7  | Verify | The DE_Elevation value is set to the "Height above Reference Ellipsoid" above or below the WGS-84 reference ellipsoid  | Pass / Fail |
| 8  | Verify | The DE_Elevation data element is within vElevAccuracy of the reference elevation over 68% of the test measurements as compared to the Ground Truth   | Pass / Fail |
| 9  | Verify | The DE_Speed data element is within vSpeedAccuracy of the actual vehicle speed under open sky conditions 68% of the test measurements as compared to the Ground Truth  | Pass / Fail |
| 11 | Verify | If the IUT supports the DE_SteeringWheelAngle element, DE_SteeringWheelAngle is accurate to within vStWhAnAccuracy of the actual vehicle steering wheel angle over 95% of test measurements as compared to the Ground Truth. If the IUT does not support DE_SteeringWheelAngle, it is set to unavailable | Pass / Fail |
| 12 | Verify | DE_Acceleration (Longitudinal) and DE_Acceleration (Lateral) are accurate to within vAccelAccuracy over 68% of test measurements as compared to the Ground Truth   | Pass / Fail |
| 13 | Verify | DE_VerticalAcceleration is accurate to within vVertAccelAccuracy over 68% of test measurements as compared to the Ground Truth   | Pass / Fail |
| 14 | Verify | DE_YawRate is accurate to within vYawRateAccuracy over 68% of test measurements as compared to the Ground Truth  | Pass / Fail |

|  |   |  |             |
|--|---|--|-------------|
| Identifier   | TP-BSM-MV-BV-03   |  |             |
| Test Objective   | Verify accuracy of DE_Heading element provided by IUT when vehicle speed is less than or equal to vHeadingSpeedThresh |  |             |
| Test Configuration   | TC2   |  |             |
| Reference:   | V2V-BSMTX-DATAACC-[019, 020]  |  |             |
| Pre-test conditions  |   |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• The vehicle speed is less than or equal to vHeadingSpeedThresh</li><li>• Test is conducted as an Open Sky Test where road test conditions are of a grade less than .2% and a cross-slope less than .2%</li></ul> |   |  |             |
| Test Sequence  |   |  |             |
| Step   | Type  | Description  | Verdict     |
| 1  | Stimulus  | At least a statistically significant amount of BSMs are transmitted by the IUT as defined in Section 7.1 with speed less than or equal to vHeadingSpeedThresh                        |             |
| 2  | Verify  | The DE_Heading data element is accurate to within vHeadAccuracyB of actual heading, indicated as clockwise from north, over 68% of test measurements as compared to the Ground Truth | Pass / Fail |

|                       |  |  |  |
|-----------------------|--|--|--|
| <b>Identifier</b>     |  | TP-BSM-MV-BV-04  |  |
| <b>Test Objective</b> |  | Verify accuracy of DE_Heading element provided by IUT when vehicle speed is greater than vHeadingSpeedThresh |  |

|   |          |  |             |
|---|----------|--|-------------|
| Test Configuration  |          | TC2  |             |
| Reference:  |          | V2V-BSMTX-DATAACC-[019, 021]   |             |
| Pre-test conditions   |          |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• The vehicle speed is greater than vHeadingSpeedThresh</li><li>• Test is conducted as an Open Sky Test where road test conditions are of a grade less than .2% and a cross-slope less than .2%</li></ul> |          |  |             |
| Test Sequence   |          |  |             |
| Step  | Type     | Description  | Verdict     |
| 1   | Stimulus | At least a statistically significant amount of BSMs are transmitted by the IUT as defined in Section 7.1 with speed greater than vHeadingSpeedThresh                                 |             |
| 2   | Verify   | The DE_Heading data element is accurate to within vHeadAccuracyA of actual heading, indicated as clockwise from north, over 68% of test measurements as compared to the Ground Truth | Pass / Fail |

|  |  |  |             |
|--|--|--|-------------|
| Identifier   | TP-BSM-MV-BV-05  |  |             |
| Test Objective   | Verify the heading latches and unlatches properly at low speed |  |             |
| Test Configuration   | TC2  |  |             |
| Reference:   | V2V-BSMTX-DATAACC-[022-023]                                    |  |             |
| Pre-test conditions  |  |  |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>The value of DE_Heading is set to the last known heading value when the speed was above vHeadLatchThresh</li></ul> |  |  |             |
| Test Sequence  |  |  |             |
| Step   | Type   | Description  | Verdict     |
| 1  | Stimulus   | The vehicle's speed drops below vHeadLatchThresh while the vehicle continues to change its heading |             |
| 2  | Verify   | The value of DE_Heading does not change  | Pass / Fail |
| 3  | Stimulus   | The vehicle's speed goes above vHeadUnlatchThresh  |             |
| 4  | Verify   | DE_Heading updates with vehicle angle  | Pass / Fail |

|  |  |  |             |
|--|--|--|-------------|
| Identifier   | TP-BSM-MV-BV-06  |  |             |
| Test Objective   | Verify content of DF_PathHistory and DF_PathPrediction |  |             |
| Test Configuration   | TC2  |  |             |
| Reference:   | V2V-BSMTX-DATAACC-[036-048]                            |  |             |
| Pre-test conditions  |  |  |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>The vehicle is moving in a steady curve above vStationarySpeedThresh</li></ul> |  |  |             |
| Test Sequence  |  |  |             |
| Step   | Type   | Description  | Verdict     |
| 1  | Stimulus   | A BSM is transmitted   |             |
| 2  | Verify   | DF_PathHistory is populated with itemCnt: Count  | Pass / Fail |
| 3  | Verify   | DF_PathHistory is populated with crumbData: DF_PathHistoryPointList  | Pass / Fail |
| 4  | Verify   | DF_PathHistory does not include any additional data elements or frames   | Pass / Fail |
| 5  | Verify   | DF_PathHistory is populated with the minimum number of path history points such that the represented PH distance is at least | Pass / Fail |

|    |          |   |             |
|----|----------|---|-------------|
|    |          | vMinPHistDistance and no more than vMaxPHistDistance unless there is less than vMinPHistDistance of PH available  |             |
| 6  | Verify   | A vehicle path is maintained that is comprised of data elements derived from the positioning system sampled at a periodic time interval, and interpolated in between by circular arcs   | Pass / Fail |
| 7  | Verify   | DF_PathHistory points are chosen as the minimum set of points such that the perpendicular distance between any point on the vehicle path and the straight line connecting two consecutive PH points is less than vPathPerpendicularDist   | Pass / Fail |
| 8  | Verify   | DF_PathHistory points are ordered chronologically, such that the first PH point is the closest in time to the current UTC time  | Pass / Fail |
| 9  | Verify   | DF_PathHistory points does not contain more than vMaxPHistPoints regardless of other requirements   | Pass / Fail |
| 10 | Verify   | DF_PathPrediction is populated with radiusOfCurve: Integer  | Pass / Fail |
| 11 | Verify   | DF_PathPrediction is populated with confidence: Integer   | Pass / Fail |
| 12 | Verify   | DF_PathPrediction is populated with a calculated radius that has less than vPPredRadiusError error from the actual radius when the vehicle is in steady state (change of yaw rate less than 0.5 deg/s/s) conditions over a range from vMinCurveRadius to vMaxCurveRadius in magnitude | Pass / Fail |
| 13 | Verify   | DF_PathPrediction is repopulated after a transition from the original constant radius R1 to the target constant radius R2 within vPPredTransitionTime under the maximum allowable error bound defined above   | Pass / Fail |
| 14 | Stimulus | The vehicle speed drops below vStationarySpeedThresh  |             |
| 15 | Verify   | The IUT reports a radius of value 32,767 and a confidence of 100%   | Pass / Fail |

|  |             |   |                |
|--|-------------|---|----------------|
| <b>Identifier</b>  |             | TP-BSM-MV-BV-07-X   |                |
| <b>Test Objective</b>  |             | Verify proper critical event flags are set in an acceptable time  |                |
| <b>Test Configuration</b>  |             | TC2   |                |
| <b>Reference:</b>  |             | V2V-BSMTX-DATAACC-[034-035]   |                |
| <b>Pre-test conditions</b>   |             |   |                |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• The IUT can communicate with the vehicle through the CAN interface</li></ul> |             |   |                |
| <b>Test Sequence</b>   |             |   |                |
| <b>Step</b>  | <b>Type</b> | <b>Description</b>  | <b>Verdict</b> |
| 1  | Stimulus    | The vehicle undergoes a critical event set ( <b>X</b> ) as listed in the table in Section 7.4 at time T0                                  |                |
| 2  | Verify      | The first BSM with the DE_VehicleEventFlags taken from the CAN interface corresponding to the <b>Event Flag</b> is transmitted at time T1 | Pass / Fail    |
| 3  | Verify      | The difference between T1 and T0 is less than or equal to vEventDetectLatency   | Pass / Fail    |
| 4  | Procedure   | Repeat steps 1-3 for all critical event sets ( <b>X</b> ) in Section 7.4  |                |

|   |   |
|---|---|
| Identifier  | TP-BSM-MV-BV-08   |
| Test Objective  | Verify proper values of Traction, ABS, SCS, brakeBoost, and auxBrakes |
| Test Configuration  | TC2   |
| Reference:  | V2V-BSMTX-DATAACC-[028, 032], V2V-STD-J2735-[016-017, 019]            |
| Pre-test conditions   |   |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li></ul> |   |

| <ul style="list-style-type: none"> <li>• The vehicle bus is available</li> <li>• Braking status is available</li> <li>• Traction, ABS, SCS, brakeBoost, and auxBrakes are either unavailable or available and off</li> <li>• The IUT can communicate with the vehicle through the CAN interface</li> </ul> |           |   |             |
|--|-----------|---|-------------|
| Test Sequence  |           |   |             |
| Step   | Type      | Description   | Verdict     |
| 1  | Stimulus  | A BSM is transmitted  |             |
| 2  | Verify    | The IUT uses the vehicle CAN bus as the data source for DF_BrakeSystemStatus              | Pass / Fail |
| 3  | Verify    | Traction, ABS, SCS, brakeBoost, and auxBrakes fields are set in accordance with J2735 [2] | Pass / Fail |
| 4  | Verify    | Traction is correctly reported as off and available or unavailable if not available       | Pass / Fail |
| 5  | Stimulus  | The vehicle turns on Traction, if available   |             |
| 6  | Verify    | Traction is correctly reported as on and available or unavailable if not available        | Pass / Fail |
| 7  | Stimulus  | The vehicle engages Traction, if available  |             |
| 8  | Verify    | Traction is correctly reported as engaged or unavailable if not available                 | Pass / Fail |
| 9  | Procedure | Steps 4 – 8 are repeated for ABS, SCS, brakeBoost, and auxBrakes                          |             |

|   |   |   |             |
|---|---|---|-------------|
| Identifier  | TP-BSM-MV-BV-09   |   |             |
| Test Objective  | Verify proper value of wheelBrakesUnavailable when no braking status is available |   |             |
| Test Configuration  | TC2   |   |             |
| Reference:  | V2V-BSMTX-DATAACC-031   |   |             |
| Pre-test conditions   |   |   |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• There is no braking status available</li><li>• The IUT can communicate with the vehicle through the CAN interface</li></ul> |   |   |             |
| Test Sequence   |   |   |             |
| Step  | Type  | Description   | Verdict     |
| 1   | Stimulus  | A BSM is transmitted  |             |
| 2   | Verify  | wheelBrakesUnavailable field populated from the CAN interface is set to 1 | Pass / Fail |

|  |  |  |             |
|--|--|--|-------------|
| Identifier   | TP-BSM-MV-BV-10                              |  |             |
| Test Objective   | Verify proper values of DE_ExteriorLights    |  |             |
| Test Configuration   | TC2  |  |             |
| Reference:   | V2V-BSMTX-DATAACC-049, V2V-BSMTX-BSMCONT-005 |  |             |
| Pre-test conditions  |  |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• DE_ExteriorLights data is available</li><li>• All exterior lights are off</li><li>• The IUT can communicate with the vehicle through the CAN interface</li></ul> |  |  |             |
| Test Sequence  |  |  |             |
| Step   | Type   | Description  | Verdict     |
| 1  | Stimulus                                     | A BSM is transmitted   |             |
| 2  | Verify                                       | The DF_VehicleSafetyExtensions data frame does not include DE_ExteriorLights | Pass / Fail |
| 3  | Stimulus                                     | At least one exterior light is turned on                                     |             |

|   |           |   |             |
|---|-----------|---|-------------|
| 4 | Stimulus  | A BSM is transmitted  |             |
| 5 | Verify    | The DF_VehicleSafetyExtensions data frame includes DE_ExteriorLights populated from the CAN interface | Pass / Fail |
| 6 | Verify    | DE_ExteriorLights data element has bits set corresponding to the turned on lights                     | Pass / Fail |
| 7 | Procedure | Steps 3 – 6 are repeated for all exterior lights  |             |

|   |  |   |             |
|---|--|---|-------------|
| Identifier  | TP-BSM-MV-BV-11  |   |             |
| Test Objective  | Verify proper values of wheelBrakes and wheelBrakesUnavailable when braking status for each wheel is available |   |             |
| Test Configuration  | TC2  |   |             |
| Reference:  | V2V-BSMTX-DATAACC-029, V2V-STD-J2735-018   |   |             |
| Pre-test conditions   |  |   |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• Braking status is available for each wheel</li><li>• The IUT can communicate with the vehicle through the CAN interface</li></ul> |  |   |             |
| Test Sequence   |  |   |             |
| Step  | Type   | Description   | Verdict     |
| 1   | Stimulus   | The vehicle carrying the IUT applies its brakes and changes the overall brake status of the IUT       |             |
| 2   | Stimulus   | A BSM is transmitted  |             |
| 3   | Verify   | Bits within the wheelBrakes field are set depending on braking status received from the CAN interface | Pass / Fail |
| 4   | Verify   | wheelBrakesUnavailable is set to false  | Pass / Fail |
| 5   | Stimulus   | The vehicle carrying the IUT releases its brakes  |             |
| 6   | Stimulus   | A BSM is transmitted  |             |
| 7   | Verify   | Bits within the wheelBrakes field received from the CAN interface are all set to false                | Pass /Fail  |

|   |  |  |             |
|---|--|--|-------------|
| Identifier  | TP-BSM-MV-BV-12  |  |             |
| Test Objective  | Verify proper values of wheelBrakes and wheelBrakesUnavailable when only a single braking status indication is available |  |             |
| Test Configuration  | TC2  |  |             |
| Reference:  | V2V-BSMTX-DATAACC-030  |  |             |
| Pre-test conditions   |  |  |             |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• A single braking status indication is available</li><li>• ABS and Stability Control is disabled on the vehicle</li><li>• The IUT can communicate with the vehicle through the CAN interface</li></ul> |  |  |             |
| Test Sequence   |  |  |             |
| Step  | Type   | Description  | Verdict     |
| 1   | Stimulus   | The vehicle carrying the IUT applies its brakes                      |             |
| 2   | Verify   | At least one BSM is transmitted within 3*vEventDetectLatency         | Pass / Fail |
| 3   | Verify   | Bits for all wheels are set on and populated from the CAN interface  | Pass / Fail |
| 4   | Verify   | wheelBrakesUnavailable is set to false                               | Pass / Fail |
| 5   | Stimulus   | The IUT removes brakes   |             |
| 6   | Verify   | At least one BSM is transmitted within 3*vEventDetectLatency         | Pass / Fail |
| 7   | Verify   | Bits for all wheels are set off and populated from the CAN interface | Pass / Fail |



|  |   |  |             |
|--|---|--|-------------|
| Identifier   | TP-BSM-MV-BV-13   |  |             |
| Test Objective   | Verify vehicle transmission is properly reported if available |  |             |
| Test Configuration   | TC2   |  |             |
| Reference:   | V2V-BSMTX-DATAACC-018   |  |             |
| Pre-test conditions  |   |  |             |
| <ul style="list-style-type: none"><li>The IUT is in the initial state</li><li>The IUT is in some unspecified initial transmission state</li><li>The IUT can communicate with the vehicle through the CAN interface</li></ul> |   |  |             |
| Test Sequence  |   |  |             |
| Step   | Type  | Description  | Verdict     |
| 1  | Stimulus  | The vehicle changes transmission state   |             |
| 2  | Verify  | At least one BSM is transmitted within 3*vEventDetectLatency   | Pass / Fail |
| 3  | Verify  | DE_TransmissionState properly reflects the new transmission state or not available as taken from the CAN interface | Pass / Fail |
| 4  | Procedure   | Steps 1 – 2 are repeated for each transmission state on the vehicle as defined in J2735                            |             |

|                                   |  |  |             |
|-----------------------------------|--|--|-------------|
| Identifier                        | TP-BSM-MV-BV-14                              |  |             |
| Test Objective                    | Verify vehicle length and width are accurate |  |             |
| Test Configuration                | TC2  |  |             |
| Reference:                        | V2V-BSMTX-DATAACC-033                        |  |             |
| Pre-test conditions               |  |  |             |
| ● The IUT is in the initial state |  |  |             |
| Test Sequence                     |  |  |             |
| Step                              | Type   | Description  | Verdict     |
| 1                                 | Stimulus                                     | A BSM is transmitted   |             |
| 2                                 | Verify                                       | DE_VehicleLength and DE_VehicleWidth are accurate to within vSizeAccuracy of actual vehicle length and width | Pass / Fail |

|                                   |   |   |             |
|-----------------------------------|---|---|-------------|
| Identifier                        | TP-BSM-ST-BI-19   |   |             |
| Test Objective                    | Verify IUT does not send data elements/frames not required in the J2945/1 specification |   |             |
| Test Configuration                | TC1   |   |             |
| Reference:                        | V2V-BSMTX-DATAACC-050   |   |             |
| Pre-test conditions               |   |   |             |
| ● The IUT is in the initial state |   |   |             |
| Test Sequence                     |   |   |             |
| Step                              | Type  | Description   | Verdict     |
| 1                                 | Stimulus  | A BSM is sent   |             |
| 2                                 | Verify  | There are no unallowed data elements contained within the BSM | Pass / Fail |

## 6.2.5 Internal Timing and Prioritization

|                           |   |  |  |
|---------------------------|---|--|--|
| <b>Identifier</b>         | TP-BSM-ST-BV-20-V   |  |  |
| <b>Test Objective</b>     | Verify the IUT's system clock is synchronized to facilitate communication |  |  |
| <b>Test Configuration</b> | TC1   |  |  |
| <b>Reference:</b>         | V2V-POSTIM-SYSTIMCOORD-[001-002]  |  |  |

| Pre-test conditions   |        |   |             |
|---|--------|---|-------------|
| <ul style="list-style-type: none"> <li>The IUT is in the initial state</li> </ul> |        |   |             |
| Test Sequence   |        |   |             |
| Step  | Type   | Description   | Verdict     |
| 1   | Verify | The output of the IUT's reference clock conforms to UTC                           | Pass / Fail |
| 2   | Verify | The vendor verifies that the IUT's system clock is within vTimeAccuracy ms of UTC | Pass / Fail |

|                                   |  |  |             |
|-----------------------------------|--|--|-------------|
| Identifier                        | TP-BSM-ST-BV-21-V  |  |             |
| Test Objective                    | Verify timing of message transmissions                           |  |             |
| Test Configuration                | TC1  |  |             |
| Reference:                        | V2V-BSMTX-DATAACC-[008-010, 015-016], V2V-POSTIM-SYSTIMCOORD-003 |  |             |
| Pre-test conditions               |  |  |             |
| ● The IUT is in the initial state |  |  |             |
| Test Sequence                     |  |  |             |
| Step                              | Type   | Description  | Verdict     |
| 1                                 | Stimulus   | A BSM is transmitted by the IUT  |             |
| 2                                 | Verify   | The vendor verifies that the time represented by DE_DSecond is the time at which BSM Part I IUT location data was determined, using the UTC-conformant reference by the reference positioning system | Pass / Fail |
| 3                                 | Verify   | The difference between DE_Dsecond and the transmit time is less than vMaxPosAge  | Pass / Fail |
| 4                                 | Verify   | DF_PositionalAccuracy is set with values corresponding to its accuracy estimate for the position data included in the corresponding BSM  | Pass / Fail |
| 5                                 | Verify   | DF_PositionalAccuracy provides the errors for the semi-major and semi-minor axes of the error ellipsoid at one standard deviation, as well as the orientation of the semi-major axis                 | Pass / Fail |

|   |   |  |         |
|---|---|--|---------|
| Identifier  | TP-BSM-ST-BV-22-V                                       |  |         |
| Test Objective  | Verify the IUT position updates at the proper frequency |  |         |
| Test Configuration  | TC1   |  |         |
| Reference:  | V2V-POSTIM-POSDETER-002                                 |  |         |
| Pre-test conditions   |   |  |         |
| <ul style="list-style-type: none"><li>• The IUT is in the initial state</li><li>• The IUT is not moving throughout the duration of the test</li></ul> |   |  |         |
| Test Sequence   |   |  |         |
| Step  | Type  | Description  | Verdict |
| 1   | Stimulus  | The vendor indicates that the frequency of position updates is at a nominal rate of vPosDetRate and the UTC time when at that position |         |

## 6.2.6 Hardware

|                     |   |
|---------------------|---|
| Identifier          | TP-BSM-ST-BV-23-V   |
| Test Objective      | Verify that all private key operations are performed within secure hardware |
| Test Configuration  | TC1   |
| Reference:          | V2V-SECMGMT-SECHW-[001-002]   |
| Pre-test conditions |   |

| ● The IUT is in the initial state |           |   |             |
|-----------------------------------|-----------|---|-------------|
| Test Sequence                     |           |   |             |
| Step                              | Type      | Description   | Verdict     |
| 1                                 | Configure | The IUT and computer interface is configured to attempt a private key operation                               |             |
| 2                                 | Verify    | The IUT completes the operation   | Pass / Fail |
| 3                                 | Verify    | The vendor indicates that all steps of the operation utilizing the private key is done within secure hardware | Pass / Fail |
| 4                                 | Procedure | Repeat steps 1 – 3 for all available private key operations   |             |

|                     |        |  |             |
|---------------------|--------|--|-------------|
| Identifier          |        | TP-BSM-ST-BV-24  |             |
| Test Objective      |        | Verify DSRC Receiver Sensitivity   |             |
| Test Configuration  |        | TC1  |             |
| Reference:          |        | V2V-RFPERF-DSRCRXSENS-[001-002]  |             |
| Pre-test conditions |        |  |             |
|                     |        |  |             |
| Test Sequence       |        |  |             |
| Step                | Type   | Description  | Verdict     |
| 1                   | Verify | The IUT passes TP-80211-RXT-PHY-BV-01 from the 802.11 test procedures [10] | Pass / Fail |
| 2                   | Verify | The IUT passes TP-80211-RXT-PHY-BV-02 from the 802.11 test procedures [10] | Pass / Fail |
| 3                   | Verify | The IUT passes TP-80211-RXT-PHY-BV-03 from the 802.11 test procedures [10] | Pass / Fail |

## 7 Appendix

### 7.1 Determining Randomness of Value Sets

For the purposes of testing the randomness of the values in the context of DSRC certification, a limited battery of tests will be run against a representative sample of values generated by the IUT.

$$SS = \frac{(Z^2 * (p) * (1 - p))}{c^2}$$

SS = sample size

Z = confidence level

p = a priori judgement (0.5 represents the worst case, unknown a priori)

c = confidence interval

The Z-value is selected from the following table:

| Percentage Confidence | Z-value |
|-----------------------|---------|
| 80                    | 1.28    |
| 90                    | 1.645   |
| 95                    | 1.96    |
| 98                    | 2.33    |

|    |      |
|----|------|
| 99 | 2.58 |
|----|------|

Assuming no a priori judgement on the randomness of the dataset, a worst-case value of  $p$  is used ( $p = 0.5$ ). Substituting values for a 95% confidence level ( $Z = 1.96$ ), with a confidence interval of 5% ( $c = 0.05$ ), a **sample size of 385 is necessary to achieve a statistically significant result.**

$$\frac{(1.96^2 * (0.5) * (1 - 0.5))}{0.05^2} = 384.16$$

The intent of randomness, as specified in SAE J2945/1, is to generate numbers that are not predictable and cover the whole range of valid values for a given element.

In order to determine pass/fail for a measurement of randomness, both the average and standard deviation of the data set will be used. These two values give an indication of the general distribution of the values generated (ie. an algorithm is using the correct minimum and maximum values) and that distribution are not inappropriately clumped around a sub-range (values are well spread out over the whole range).

In the representation of the values, all values are considered unsigned integers.

Take the average of the data over the sample set and determine whether the average is within an acceptable tolerance of the medium of the range. **For this test document, the tolerance is .05 of the medium of the range.**

The standard deviation of a uniform continuous distribution over a range is calculated by:

$$StdDev = \frac{(b - a)}{\sqrt{12}}$$

Take the standard deviation of the values and determine if the sample's standard deviation is within a given tolerance. **For this test document, the tolerance is .05 of the nominal standard deviation of the range.**

For example, assume variable X should be randomly selected from the valid range of 0 – 255. The medium of the range is 128. The nominal standard deviation of a continuous uniform distribution over this range is 73.6. The average of the measured values within this range should be 128 +/- 6.4. The measured standard deviation of the values should be 73.6 +/- 3.68.

## 7.2 Requirements Traceability Matrix (Requirement to Scenario)

| Requirement             | Test Procedure    | Scenario      |
|-------------------------|-------------------|---------------|
| 6.1.6-V2V-STD-J2735-001 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-002 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-003 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-004 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-005 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-006 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-007 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-008 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-009 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-010 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-011 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-012 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-013 | TP-BSM-ST-BV-03-X | All Scenarios |
| 6.1.6-V2V-STD-J2735-014 | TP-BSM-ST-BV-03-X | All Scenarios |

|                                   |                   |   |
|-----------------------------------|-------------------|---|
| 6.1.6-V2V-STD-J2735-015           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-016           | TP-BSM-MV-BV-08   | All Scenarios   |
| 6.1.6-V2V-STD-J2735-017           | TP-BSM-MV-BV-08   | All Scenarios   |
| 6.1.6-V2V-STD-J2735-018           | TP-BSM-MV-BV-11   | All Scenarios   |
| 6.1.6-V2V-STD-J2735-019           | TP-BSM-MV-BV-08   | All Scenarios   |
| 6.1.6-V2V-STD-J2735-020           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-021           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-022           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-023           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-024           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-025           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-026           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-027           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-028           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-029           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-030           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-031           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-032           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-033           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-034           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-035           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-036           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-037           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-038           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-039           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-040           | TP-BSM-ST-BV-01-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-041           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-042           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-043           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-044           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.1.6-V2V-STD-J2735-045           | TP-BSM-ST-BV-03-X | All Scenarios   |
| 6.2.1-V2V-POSTIM-<br>POSDETER-001 | TP-BSM-MV-BV-02-V | Positioning   |
| 6.2.1-V2V-POSTIM-<br>POSDETER-002 | TP-BSM-ST-BV-22   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.2.2-V2V-POSTIM-WAAS-<br>001     | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |

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| 6.2.3-V2V-POSTIM-COORDSYSREF-001 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.2.4-V2V-POSTIM-SYSTIMCOORD-001 | TP-BSM-ST-BV-20-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.2.4-V2V-POSTIM-SYSTIMCOORD-002 | TP-BSM-ST-BV-20-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.2.4-V2V-POSTIM-SYSTIMCOORD-003 | TP-BSM-ST-BV-21-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.1-V2V-BSMTX-BSMCONT-001      | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.1-V2V-BSMTX-BSMCONT-002      | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.1-V2V-BSMTX-BSMCONT-003      | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.1-V2V-BSMTX-BSMCONT-004      | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,                               |

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|                              |                   | CLW - Control Loss Warning   |
| 6.3.1-V2V-BSMTX-BSMCONT-005  | TP-BSM-MV-BV-10   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.1-V2V-BSMTX-BSMCONT-006  | TP-BSM-ST-BV-01-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.2-V2V-BSMTX-CHDARATE-001 | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.2-V2V-BSMTX-CHDARATE-002 | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.3-V2V-BSMTX-GENTIM-001   | TP-BSM-ST-BV-02   | BSM Exchange   |
| 6.3.3-V2V-BSMTX-GENTIM-002   | TP-BSM-ST-BV-04   | BSM Exchange   |
| 6.3.4-V2V-BSMTX-UPEDCA-001   | N/A               | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.4-V2V-BSMTX-UPEDCA-002   | N/A               | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |

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| 6.3.4-V2V-BSMTX-UPEDCA-003  | N/A               | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.5-V2V-BSMTX-MINTX-001   | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning, IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning    |
| 6.3.6-V2V-BSMTX-DATAACC-001 | TP-BSM-ST-BV-03-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-002 | TP-BSM-ST-BV-07   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-003 | TP-BSM-ST-BV-05   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-004 | TP-BSM-ST-BV-06   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-005 | TP-BSM-ST-BV-07   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-006 | TP-BSM-ST-BV-05   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |



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| 6.3.6-V2V-BSMTX-DATAACC-007 | TP-BSM-ST-BV-06   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-008 | TP-BSM-ST-BV-21-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-009 | TP-BSM-ST-BV-21-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-010 | TP-BSM-ST-BV-21-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-011 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-012 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-013 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-014 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,  |

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|                                 |                   | LTA - Left Turn Assist,<br>CLW - Control Loss Warning   |
| 6.3.6-V2V-BSMTX-<br>DATAACC-015 | TP-BSM-ST-BV-21-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-016 | TP-BSM-ST-BV-21-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-017 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-018 | TP-BSM-MV-BV-13   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-019 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-020 | TP-BSM-MV-BV-03   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-021 | TP-BSM-MV-BV-04   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |

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| 6.3.6-V2V-BSMTX-DATAACC-022 | TP-BSM-MV-BV-05   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-023 | TP-BSM-MV-BV-05   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-024 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-025 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-026 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-027 | TP-BSM-MV-BV-02-V | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-028 | TP-BSM-MV-BV-08   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-029 | TP-BSM-MV-BV-11   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,  |

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|                                 |                   | LTA - Left Turn Assist,<br>CLW - Control Loss Warning   |
| 6.3.6-V2V-BSMTX-<br>DATAACC-030 | TP-BSM-MV-BV-12   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-031 | TP-BSM-MV-BV-09   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-032 | TP-BSM-MV-BV-08   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-033 | TP-BSM-MV-BV-14   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-034 | TP-BSM-MV-BV-07-X | EEBL - Lead Vehicle Decelerating  |
| 6.3.6-V2V-BSMTX-<br>DATAACC-035 | TP-BSM-MV-BV-07-X | EEBL - Lead Vehicle Decelerating  |
| 6.3.6-V2V-BSMTX-<br>DATAACC-036 | TP-BSM-MV-BV-06   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-037 | TP-BSM-MV-BV-06   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-038 | TP-BSM-MV-BV-06   | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,   |

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|                                 |                 | IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning  |
| 6.3.6-V2V-BSMTX-<br>DATAACC-039 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-040 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-041 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-042 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-043 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-044 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-<br>DATAACC-045 | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |

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| 6.3.6-V2V-BSMTX-DATAACC-046     | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-047     | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-048     | TP-BSM-MV-BV-06 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-049     | TP-BSM-MV-BV-10 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-050     | TP-BSM-ST-BI-19 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.6-V2V-BSMTX-DATAACC-051     | N/A             | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.3.7-V2V-BSMTX-DATAPERSIST-001 | TP-BSM-ST-BV-18 | Shutdown   |
| 6.3.7-V2V-BSMTX-DATAPERSIST-002 | TP-BSM-ST-BV-18 | Startup  |
| 6.3.7-V2V-BSMTX-DATAPERSIST-003 | TP-BSM-ST-BV-18 | Shutdown   |
| 6.3.7-V2V-BSMTX-DATAPERSIST-004 | TP-BSM-ST-BV-18 | Startup  |
| 6.3.8-V2V-BSMTX-CONGCTRL-001    | N/A             | BSM Exchange,<br>EEBL - Lead Vehicle Decelerating,<br>FCW- Forward,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change  |

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|                                     |                 | Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning  |
| 6.4.1-V2V-RFPERF-<br>DSRCTX-001     | N/A             | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.4.1-V2V-RFPERF-<br>DSRCTX-002     | N/A             | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.4.1-V2V-RFPERF-<br>DSRCTX-003     | N/A             | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.4.1-V2V-RFPERF-<br>DSRCTX-004     | N/A             | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.4.2-V2V-RFPERF-<br>DSRCRXSENS-001 | TP-BSM-ST-BV-24 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.4.2-V2V-RFPERF-<br>DSRCRXSENS-002 | TP-BSM-ST-BV-24 | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change<br>Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.5.1-V2V-SECPRIV-<br>IDRAND-001    | TP-BSM-ST-BV-07 | Startup   |
| 6.5.1-V2V-SECPRIV-<br>IDRAND-002    | TP-BSM-ST-BV-05 | Privacy   |
| 6.5.2-V2V-SECPRIV-<br>BSMSIGN-001   | TP-BSM-ST-BV-08 | Security  |
| 6.5.2-V2V-SECPRIV-<br>BSMSIGN-002   | TP-BSM-ST-BV-08 | Security  |

|                                 |                   |   |
|---------------------------------|-------------------|---|
| 6.5.2-V2V-SECPRIV-BSMSIGN-003   | TP-BSM-ST-BV-09   | Security  |
| 6.5.2-V2V-SECPRIV-BSMSIGN-004   | TP-BSM-ST-BV-10-X | EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning              |
| 6.5.2-V2V-SECPRIV-BSMSIGN-005   | TP-BSM-ST-BV-11   | Security  |
| 6.5.2-V2V-SECPRIV-BSMSIGN-006   | TP-BSM-ST-BV-11   | Security  |
| 6.5.2-V2V-SECPRIV-BSMSIGN-007   | TP-BSM-ST-BV-13   | Security  |
| 6.5.2-V2V-SECPRIV-BSMSIGN-008   | TP-BSM-ST-BV-05   | Security  |
| 6.5.3-V2V-SECPRIV-CERTCHG-001   | TP-BSM-MV-BV-01   | Privacy   |
| 6.5.3-V2V-SECPRIV-CERTCHG-002   | TP-BSM-ST-BV-17-X | Privacy   |
| 6.5.3-V2V-SECPRIV-CERTCHG-003   | TP-BSM-MV-BV-01   | Privacy   |
| 6.5.4-V2V-SECPRIV-BSMVERIFY-001 | TP-BSM-ST-BV-15   | Security,<br>EEBL - Lead Vehicle Decelerating,<br>Crash Warning,<br>BSW /LCW- Blind Spot Warning/Lane Change Warning,<br>IMA-Intersection Movement Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning |
| 6.5.5-V2V-SECPRIV-CERTREV-001   | TP-BSM-ST-BV-12   |   |
| 6.6.2-V2V-SECMGMT-CERTLOAD-001  | TP-BSM-ST-BV-16-V | Security  |
| 6.6.3-V2V-SECMGMT-CERTSTORE-001 | TP-BSM-ST-BV-14-V | Security  |
| 6.6.3-V2V-SECMGMT-CERTSTORE-002 | TP-BSM-ST-BV-14-V | Security  |
| 6.6.3-V2V-SECMGMT-CERTSTORE-003 | TP-BSM-ST-BV-14-V | Security  |
| 6.6.3-V2V-SECMGMT-CERTSTORE-004 | TP-BSM-ST-BV-14-V | Security  |
| 6.6.4-V2V-SECMGMT-CRLLOAD-001   | TP-BSM-ST-BV-14-V |   |
| 6.6.4-V2V-SECMGMT-CRLLOAD-002   | TP-BSM-ST-BV-14-V |   |
| 6.6.5-V2V-SECMGMT-SECHW-001     | TP-BSM-ST-BV-23-V | Security  |
| 6.6.5-V2V-SECMGMT-SECHW-002     | TP-BSM-ST-BV-23-V | Security  |



### 7.3 Requirements traceability Matrix (Scenario to Test Procedure)

| Scenario     | Test Procedure    | Requirement                     |
|--------------|-------------------|---------------------------------|
| Startup      | TP-BSM-ST-BV-18   | 6.3.7-V2V-BSMTX-DATAPERSIST-002 |
|              | TP-BSM-ST-BV-18   | 6.3.7-V2V-BSMTX-DATAPERSIST-004 |
|              | TP-BSM-ST-BV-07   | 6.5.1-V2V-SECPRIV-IDRAND-001    |
| Shutdown     | TP-BSM-ST-BV-18   | 6.3.7-V2V-BSMTX-DATAPERSIST-001 |
|              | TP-BSM-ST-BV-18   | 6.3.7-V2V-BSMTX-DATAPERSIST-003 |
| Security     | TP-BSM-ST-BV-08   | 6.5.2-V2V-SECPRIV-BSMSIGN-001   |
|              | TP-BSM-ST-BV-08   | 6.5.2-V2V-SECPRIV-BSMSIGN-002   |
|              | TP-BSM-ST-BV-09   | 6.5.2-V2V-SECPRIV-BSMSIGN-003   |
|              | TP-BSM-ST-BV-11   | 6.5.2-V2V-SECPRIV-BSMSIGN-005   |
|              | TP-BSM-ST-BV-11   | 6.5.2-V2V-SECPRIV-BSMSIGN-006   |
|              | TP-BSM-ST-BV-13   | 6.5.2-V2V-SECPRIV-BSMSIGN-007   |
|              | TP-BSM-ST-BV-05   | 6.5.2-V2V-SECPRIV-BSMSIGN-008   |
|              | TP-BSM-ST-BV-15   | 6.5.4-V2V-SECPRIV-BSMVERIFY-001 |
|              | TP-BSM-ST-BV-16-V | 6.6.2-V2V-SECMGMT-CERTLOAD-001  |
|              | TP-BSM-ST-BV-14-V | 6.6.3-V2V-SECMGMT-CERTSTORE-001 |
|              | TP-BSM-ST-BV-14-V | 6.6.3-V2V-SECMGMT-CERTSTORE-002 |
|              | TP-BSM-ST-BV-14-V | 6.6.3-V2V-SECMGMT-CERTSTORE-003 |
|              | TP-BSM-ST-BV-14-V | 6.6.3-V2V-SECMGMT-CERTSTORE-004 |
|              | TP-BSM-ST-BV-23-V | 6.6.5-V2V-SECMGMT-SECHW-001     |
|              | TP-BSM-ST-BV-23-V | 6.6.5-V2V-SECMGMT-SECHW-002     |
| BSM Exchange | TP-BSM-ST-BV-02   | 6.3.3-V2V-BSMTX-GENTIM-001      |
|              | TP-BSM-ST-BV-04   | 6.3.3-V2V-BSMTX-GENTIM-002      |
|              | N/A               | 6.3.8-V2V-BSMTX-CONGCTRL-001    |
| Privacy      | TP-BSM-ST-BV-05   | 6.5.1-V2V-SECPRIV-IDRAND-002    |
|              | TP-BSM-MV-BV-01   | 6.5.3-V2V-SECPRIV-CERTCHG-001   |
|              | TP-BSM-ST-BV-17-X | 6.5.3-V2V-SECPRIV-CERTCHG-002   |
|              | TP-BSM-MV-BV-01   | 6.5.3-V2V-SECPRIV-CERTCHG-003   |
| Positioning  | TP-BSM-MV-BV-02-V | 6.2.1-V2V-POSTIM-POSDETER-001   |

|                                  |                   |                                  |
|----------------------------------|-------------------|----------------------------------|
| EEBL - Lead Vehicle Decelerating | TP-BSM-ST-BV-22   | 6.2.1-V2V-POSTIM-POSDETER-002    |
|                                  | TP-BSM-MV-BV-02-V | 6.2.2-V2V-POSTIM-WAAS-001        |
|                                  | TP-BSM-MV-BV-02-V | 6.2.3-V2V-POSTIM-COORDSYSREF-001 |
|                                  | TP-BSM-ST-BV-20-V | 6.2.4-V2V-POSTIM-SYSTIMCOORD-001 |
|                                  | TP-BSM-ST-BV-20-V | 6.2.4-V2V-POSTIM-SYSTIMCOORD-002 |
|                                  | TP-BSM-ST-BV-21-V | 6.2.4-V2V-POSTIM-SYSTIMCOORD-003 |
|                                  | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-001      |
|                                  | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-002      |
|                                  | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-003      |
|                                  | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-004      |
|                                  | TP-BSM-MV-BV-10   | 6.3.1-V2V-BSMTX-BSMCONT-005      |
|                                  | TP-BSM-ST-BV-01-X | 6.3.1-V2V-BSMTX-BSMCONT-006      |
|                                  | TP-BSM-ST-BV-03-X | 6.3.2-V2V-BSMTX-CHDATARATE-001   |
|                                  | TP-BSM-ST-BV-03-X | 6.3.2-V2V-BSMTX-CHDATARATE-002   |
|                                  | N/A               | 6.3.4-V2V-BSMTX-UPEDCA-001       |
|                                  | N/A               | 6.3.4-V2V-BSMTX-UPEDCA-002       |
|                                  | N/A               | 6.3.4-V2V-BSMTX-UPEDCA-003       |
|                                  | TP-BSM-ST-BV-03-X | 6.3.5-V2V-BSMTX-MINTX-001        |
|                                  | TP-BSM-ST-BV-03-X | 6.3.6-V2V-BSMTX-DATAACC-001      |
|                                  | TP-BSM-ST-BV-07   | 6.3.6-V2V-BSMTX-DATAACC-002      |
|                                  | TP-BSM-ST-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-003      |
|                                  | TP-BSM-ST-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-004      |
|                                  | TP-BSM-ST-BV-07   | 6.3.6-V2V-BSMTX-DATAACC-005      |
|                                  | TP-BSM-ST-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-006      |
|                                  | TP-BSM-ST-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-007      |
|                                  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-008      |
|                                  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-009      |
|                                  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-010      |
|                                  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-011      |
|                                  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-012      |

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|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-013 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-014 |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-015 |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-016 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-017 |
|  | TP-BSM-MV-BV-13   | 6.3.6-V2V-BSMTX-DATAACC-018 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-019 |
|  | TP-BSM-MV-BV-03   | 6.3.6-V2V-BSMTX-DATAACC-020 |
|  | TP-BSM-MV-BV-04   | 6.3.6-V2V-BSMTX-DATAACC-021 |
|  | TP-BSM-MV-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-022 |
|  | TP-BSM-MV-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-023 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-024 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-025 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-026 |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-027 |
|  | TP-BSM-MV-BV-08   | 6.3.6-V2V-BSMTX-DATAACC-028 |
|  | TP-BSM-MV-BV-11   | 6.3.6-V2V-BSMTX-DATAACC-029 |
|  | TP-BSM-MV-BV-12   | 6.3.6-V2V-BSMTX-DATAACC-030 |
|  | TP-BSM-MV-BV-09   | 6.3.6-V2V-BSMTX-DATAACC-031 |
|  | TP-BSM-MV-BV-08   | 6.3.6-V2V-BSMTX-DATAACC-032 |
|  | TP-BSM-MV-BV-14   | 6.3.6-V2V-BSMTX-DATAACC-033 |
|  | TP-BSM-MV-BV-07-X | 6.3.6-V2V-BSMTX-DATAACC-034 |
|  | TP-BSM-MV-BV-07-X | 6.3.6-V2V-BSMTX-DATAACC-035 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-036 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-037 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-038 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-039 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-040 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-041 |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-042 |

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|   | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-043      |
|   | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-044      |
|   | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-045      |
|   | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-046      |
|   | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-047      |
|   | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-048      |
|   | TP-BSM-MV-BV-10   | 6.3.6-V2V-BSMTX-DATAACC-049      |
|   | TP-BSM-ST-BI-19   | 6.3.6-V2V-BSMTX-DATAACC-050      |
|   | N/A               | 6.3.6-V2V-BSMTX-DATAACC-051      |
|   | N/A               | 6.3.8-V2V-BSMTX-CONGCTRL-001     |
|   | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-001      |
|   | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-002      |
|   | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-003      |
|   | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-004      |
|   | TP-BSM-ST-BV-24   | 6.4.2-V2V-RFPERF-DSRCRXSENS-001  |
|   | TP-BSM-ST-BV-24   | 6.4.2-V2V-RFPERF-DSRCRXSENS-002  |
|   | TP-BSM-ST-BV-10-X | 6.5.2-V2V-SECPRIV-BSMSIGN-004    |
|   | TP-BSM-ST-BV-15   | 6.5.4-V2V-SECPRIV-BSMVERIFY-001  |
| FCW-Forward   | N/A               | 6.3.8-V2V-BSMTX-CONGCTRL-001     |
| Crash Warning,<br>BSW /LCW- Blind Spot<br>Warning/Lane Change Warning,<br>IMA-Intersection Movement<br>Assist,<br>LTA - Left Turn Assist,<br>CLW - Control Loss Warning | TP-BSM-ST-BV-22   | 6.2.1-V2V-POSTIM-POSDETER-002    |
|   | TP-BSM-MV-BV-02-V | 6.2.2-V2V-POSTIM-WAAS-001        |
|   | TP-BSM-MV-BV-02-V | 6.2.3-V2V-POSTIM-COORDSYSREF-001 |
|   | TP-BSM-ST-BV-20-V | 6.2.4-V2V-POSTIM-SYSTIMCOORD-001 |
|   | TP-BSM-ST-BV-20-V | 6.2.4-V2V-POSTIM-SYSTIMCOORD-002 |
|   | TP-BSM-ST-BV-21-V | 6.2.4-V2V-POSTIM-SYSTIMCOORD-003 |
|   | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-001      |
|   | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-002      |

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|  | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-003    |
|  | TP-BSM-ST-BV-03-X | 6.3.1-V2V-BSMTX-BSMCONT-004    |
|  | TP-BSM-MV-BV-10   | 6.3.1-V2V-BSMTX-BSMCONT-005    |
|  | TP-BSM-ST-BV-01-X | 6.3.1-V2V-BSMTX-BSMCONT-006    |
|  | TP-BSM-ST-BV-03-X | 6.3.2-V2V-BSMTX-CHDATARATE-001 |
|  | TP-BSM-ST-BV-03-X | 6.3.2-V2V-BSMTX-CHDATARATE-002 |
|  | N/A               | 6.3.4-V2V-BSMTX-UPEDCA-001     |
|  | N/A               | 6.3.4-V2V-BSMTX-UPEDCA-002     |
|  | N/A               | 6.3.4-V2V-BSMTX-UPEDCA-003     |
|  | TP-BSM-ST-BV-03-X | 6.3.5-V2V-BSMTX-MINTX-001      |
|  | TP-BSM-ST-BV-03-X | 6.3.6-V2V-BSMTX-DATAACC-001    |
|  | TP-BSM-ST-BV-07   | 6.3.6-V2V-BSMTX-DATAACC-002    |
|  | TP-BSM-ST-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-003    |
|  | TP-BSM-ST-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-004    |
|  | TP-BSM-ST-BV-07   | 6.3.6-V2V-BSMTX-DATAACC-005    |
|  | TP-BSM-ST-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-006    |
|  | TP-BSM-ST-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-007    |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-008    |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-009    |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-010    |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-011    |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-012    |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-013    |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-014    |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-015    |
|  | TP-BSM-ST-BV-21-V | 6.3.6-V2V-BSMTX-DATAACC-016    |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-017    |
|  | TP-BSM-MV-BV-13   | 6.3.6-V2V-BSMTX-DATAACC-018    |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-019    |
|  | TP-BSM-MV-BV-03   | 6.3.6-V2V-BSMTX-DATAACC-020    |

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|  | TP-BSM-MV-BV-04   | 6.3.6-V2V-BSMTX-DATAACC-021  |
|  | TP-BSM-MV-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-022  |
|  | TP-BSM-MV-BV-05   | 6.3.6-V2V-BSMTX-DATAACC-023  |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-024  |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-025  |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-026  |
|  | TP-BSM-MV-BV-02-V | 6.3.6-V2V-BSMTX-DATAACC-027  |
|  | TP-BSM-MV-BV-08   | 6.3.6-V2V-BSMTX-DATAACC-028  |
|  | TP-BSM-MV-BV-11   | 6.3.6-V2V-BSMTX-DATAACC-029  |
|  | TP-BSM-MV-BV-12   | 6.3.6-V2V-BSMTX-DATAACC-030  |
|  | TP-BSM-MV-BV-09   | 6.3.6-V2V-BSMTX-DATAACC-031  |
|  | TP-BSM-MV-BV-08   | 6.3.6-V2V-BSMTX-DATAACC-032  |
|  | TP-BSM-MV-BV-14   | 6.3.6-V2V-BSMTX-DATAACC-033  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-036  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-037  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-038  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-039  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-040  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-041  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-042  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-043  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-044  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-045  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-046  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-047  |
|  | TP-BSM-MV-BV-06   | 6.3.6-V2V-BSMTX-DATAACC-048  |
|  | TP-BSM-MV-BV-10   | 6.3.6-V2V-BSMTX-DATAACC-049  |
|  | TP-BSM-ST-BI-19   | 6.3.6-V2V-BSMTX-DATAACC-050  |
|  | N/A               | 6.3.6-V2V-BSMTX-DATAACC-051  |
|  | N/A               | 6.3.8-V2V-BSMTX-CONGCTRL-001 |

|               |                   |                                 |
|---------------|-------------------|---------------------------------|
|               | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-001     |
|               | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-002     |
|               | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-003     |
|               | N/A               | 6.4.1-V2V-RFPERF-DSRCTX-004     |
|               | TP-BSM-ST-BV-24   | 6.4.2-V2V-RFPERF-DSRCRXSENS-001 |
|               | TP-BSM-ST-BV-24   | 6.4.2-V2V-RFPERF-DSRCRXSENS-002 |
|               | TP-BSM-ST-BV-10-X | 6.5.2-V2V-SECPRIV-BSMSIGN-004   |
|               | TP-BSM-ST-BV-15   | 6.5.4-V2V-SECPRIV-BSMVERIFY-001 |
| All Scenarios | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-001         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-002         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-003         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-004         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-005         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-006         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-007         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-008         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-009         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-010         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-011         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-012         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-013         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-014         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-015         |
|               | TP-BSM-MV-BV-08   | 6.1.6-V2V-STD-J2735-016         |
|               | TP-BSM-MV-BV-08   | 6.1.6-V2V-STD-J2735-017         |
|               | TP-BSM-MV-BV-11   | 6.1.6-V2V-STD-J2735-018         |
|               | TP-BSM-MV-BV-08   | 6.1.6-V2V-STD-J2735-019         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-020         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-021         |
|               | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-022         |

|  |                   |                         |
|--|-------------------|-------------------------|
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-023 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-024 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-025 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-026 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-027 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-028 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-029 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-030 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-031 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-032 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-033 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-034 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-035 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-036 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-037 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-038 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-039 |
|  | TP-BSM-ST-BV-01-X | 6.1.6-V2V-STD-J2735-040 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-041 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-042 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-043 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-044 |
|  | TP-BSM-ST-BV-03-X | 6.1.6-V2V-STD-J2735-045 |

#### 7.4 Critical Event Flag Variant Table

| Critical Event Flag Variants |   |              |
|------------------------------|---|--------------|
| X                            | Event Flag                              | Bit Location |
| 1                            | ABS Activated                           | 2            |
| 2                            | Traction Control Loss                   | 3            |
| 3                            | Stability Control Activated             | 4            |
| 4                            | Hard Braking                            | 7            |
| 5                            | ABS Activated,<br>Traction Control Loss | 2,<br>3      |



|    |  |                     |
|----|--|---------------------|
| 6  | ABS Activated,<br>Stability Control Activated  | 2,<br>4             |
| 7  | ABS Activated,<br>Hard Braking   | 2,<br>7             |
| 8  | Traction Control Loss,<br>Stability Control Activated                                    | 3,<br>4             |
| 9  | Traction Control Loss,<br>Hard Braking   | 3,<br>7             |
| 10 | Stability Control Activated,<br>Hard Braking   | 4,<br>7             |
| 11 | ABS Activated,<br>Traction Control Loss,<br>Stability Control Activated                  | 2,<br>3,<br>4       |
| 12 | ABS Activated,<br>Traction Control Loss,<br>Hard Braking                                 | 2,<br>3,<br>7       |
| 13 | ABS Activated,<br>Stability Control Activated,<br>Hard Braking                           | 2,<br>4,<br>7       |
| 14 | Traction Control Loss,<br>Stability Control Activated,<br>Hard Braking                   | 3,<br>4,<br>7       |
| 15 | ABS Activated,<br>Traction Control Loss,<br>Stability Control Activated,<br>Hard Braking | 2,<br>3,<br>4,<br>7 |

## Revision History

|               |                   |  |
|---------------|-------------------|--|
| <b>V0.1.0</b> | <b>Aug 2015</b>   | <b>Initial Draft</b>   |
| <b>V0.2.0</b> | <b>Jan 2016</b>   | <b>Updated to agreed upon format and Draft 5 of the J2945/1 standard</b> |
| <b>V0.3.0</b> | <b>Feb 2016</b>   | <b>Updated based on comments received from USDOT and walkthrough</b>     |
| <b>V0.4.0</b> | <b>April 2016</b> | <b>Updated based on comments received from industry review</b>           |
| <b>V0.5.0</b> | <b>March 2017</b> | <b>Updated based on concerns before May Plugfest</b>                     |
| <b>V0.5.1</b> | <b>March 2017</b> | <b>Updated based on Plugfest comments</b>                                |
| <b>V0.5.2</b> | <b>April 2017</b> | <b>Updated based on Plugfest comments</b>                                |
| <b>V0.5.3</b> | <b>April 2017</b> | <b>Updated based on Plugfest comments</b>                                |
| <b>V0.5.4</b> | <b>April 2017</b> | <b>Updated based on Plugfest comments</b>                                |

■ End of Document ■