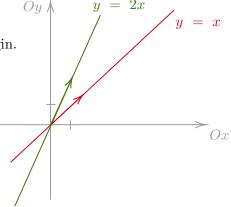
Algebra on two dimensions Math and modeling for high school, Lecture 2

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Here are two linear graphs. Note that both cross the origin.



How do we find a vector, parallel to the graph?

Answer: any pair (x, y) that solve the line equation is such vector.

Example: consider line y = -3x. The following vectors line on that line: (1, -3), (-1, 3), (3, -9), etc. In more standard vector notation they are:

$$\mathbf{r} = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \quad \mathbf{r} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}, \quad \mathbf{r} = \begin{bmatrix} 3 \\ -9 \end{bmatrix}$$
 (1)

Note that scaling a vector does not change the fact that it lines on the line: if $\mathbf{r} = \begin{bmatrix} r_x \\ r_y \end{bmatrix}$ lies on a line \mathcal{L} , than $\lambda \mathbf{r}$ also lies on \mathcal{L} (where $\lambda \in \mathbb{R}$).

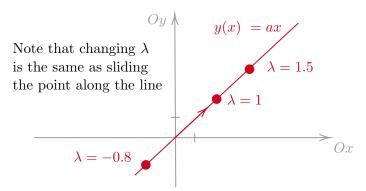
In fact, we can say the following about a line:

Theorem

If $\mathbf{r} = \begin{bmatrix} r_x \\ r_y \end{bmatrix}$ lies on a line \mathcal{L} , then all points on \mathcal{L} can be found as $\lambda \mathbf{r}$.

Let us prove it. If
$$\mathcal{L} = \{(x, y) : y = ax\}$$
 and $\mathbf{r} \in \mathcal{L}$, then $r_y = ar_x$. Then $\lambda r_y = \lambda ar_x$ and $(\lambda r_x, \lambda r_y) \in \mathcal{L}$.

That was difficult-looking. But graphically, the proof is quite obvious. We are trying to prove that any point in the line can be reached by scaling the vector lying on that line:



How do we plot a line? If we want to plot it as a collection of points \mathbf{p}_i , we could generate them by the following formula:

$$\mathbf{p}_i = \lambda_i \mathbf{v} \tag{2}$$

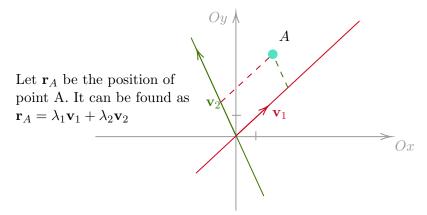
where \mathbf{v} is a vector on that line and λ_i is a sequence of numbers, for example:

$$\lambda_i = -10, -9.99, -9.98, \dots 10$$
 (3)

Then we can plug the points \mathbf{p}_i into Python library matplotlib.pyplot.plot.

SPAN

If we have two vectors which are not co-linear, we can describe any point on the plane as their linear combination:



SPAN

Let us examine the equation $\mathbf{r}_A = \lambda_1 \mathbf{v}_1 + \lambda_2 \mathbf{v}_2$ more carefully. First, we can re-write in in matrix form:

$$\begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} = \mathbf{r}_A \tag{4}$$

And we know how to solve it. Denoting the matrix $\mathbf{M} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix}$, we can say that as long as \mathbf{M} is full rank, the system can be solved exactly. And \mathbf{M} is full rank, as long as \mathbf{v}_1 and \mathbf{v}_2 are linearly independent.

We can call λ_1 and λ_2 coordinates of \mathbf{r}_A in the basis \mathbf{v}_1 and \mathbf{v}_2 .

SPAN

If $\mathbf{M} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix}$ is full rank, we say that it *spans the plane*. That simply means - any point on the plane can be expressed by its coordinates λ_1 and λ_2 .

If you know coordinates λ_1 and λ_2 of a point B, you can find its position:

$$\mathbf{r}_B = \lambda_1 \mathbf{v}_1 + \lambda_2 \mathbf{v}_2 \tag{5}$$

If we want to check if two vectors in \mathbb{R}^2 are not parallel (are linearly independent), we can see if the following determinant Δ is not zero:

$$\Delta = \det \begin{pmatrix} \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix} \end{pmatrix} \tag{6}$$

Dot product

Given two vectors $\mathbf{a} = [a_x \ a_y]$ and $\mathbf{b} = [b_x \ b_y]$, you can define their dot product as:

$$\mathbf{a} \cdot \mathbf{b} = a_x b_x + a_y b_y \tag{7}$$

We can also define dot product as follows:

$$\mathbf{a} \cdot \mathbf{b} = ||\mathbf{a}|| \ ||\mathbf{b}|| \cos(\varphi) \tag{8}$$

where φ is the angle between the two vectors. The two definitions can be used to compute the angle between vectors:

$$\cos(\varphi) = \frac{\mathbf{a} \cdot \mathbf{b}}{||\mathbf{a}|| \, ||\mathbf{b}||} \tag{9}$$

DOT PRODUCT

Some examples. If $\mathbf{a} = \begin{bmatrix} 1 & 0 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 0 & 2 \end{bmatrix}$, you can find their dot product as $\mathbf{a} \cdot \mathbf{b} = 1 \cdot 0 + 0 \cdot 2 = 0$.

Meaning the angle between the two vectors is:

$$\cos(\varphi) = \frac{0}{1 \cdot 2} = 0, \quad \varphi = \pi/2 \tag{10}$$

If $\mathbf{a} = [1 \ 1]$ and $\mathbf{b} = [-2 \ 0]$, their dot product is:

$$\mathbf{a} \cdot \mathbf{b} = 1 \cdot (-2) + 1 \cdot 0 = -2 \tag{11}$$

The angle between the two vectors is:

$$\cos(\varphi) = \frac{-2}{\sqrt{2} \cdot 2} = -\sqrt{2}/2, \quad \varphi = 3\pi/4 \tag{12}$$

ORTHOGONALITY

Given one line, how do we find another, perpendicular (orthogonal) to it?

Given one vector, how do we find another, perpendicular to it? Well, by a reasonable definition, two orthogonal vectors would have angle $\varphi = \pi/2$ between them. So, if If **a** and **b** are orthogonal, their dot product is:

$$\mathbf{a} \cdot \mathbf{b} = ||\mathbf{a}|| \ ||\mathbf{b}|| \cos(\pi/2) = 0 \tag{13}$$

Which in turn means:

$$a_x b_x + a_y b_y = 0 (14)$$

ORTHOGONALITY

Consider the following problem. Given vector $\mathbf{r} = [r_x \ r_y]$, find vector $\mathbf{n} = [n_x \ n_y]$, orthogonal to it.

We know that their dot product has to be zero:

$$r_x n_x + r_y n_y = 0 (15)$$

We can rewrite it in matrix form:

$$\begin{bmatrix} r_x & r_y \end{bmatrix} \begin{bmatrix} n_x \\ n_y \end{bmatrix} = 0 \tag{16}$$

$$\mathbf{r}^{\top}\mathbf{n} = 0 \tag{17}$$

Meaning we can find **n** using lstsq.

ORTHOGONALITY

We could find **n** using lstsq. But it looks too complicated for such a simple task.

Alternatively, we can consider $r_x n_x + r_y n_y = 0$. From this, $n_y = -\frac{r_x}{r_y} n_x$. So, for example, vector $\mathbf{n} = \begin{bmatrix} 1 & -\frac{r_x}{r_y} \end{bmatrix}$ is orthogonal to \mathbf{r} .

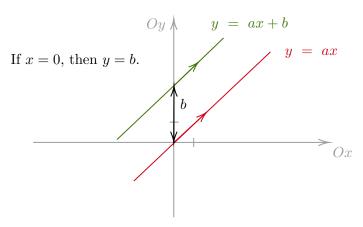
Note that in any case, we can decide we want \mathbf{n} to have certain lengths, let us say $||\mathbf{n}|| = 1$. To achieve that we can *normalize* it:

$$\mathbf{n}^* = \begin{bmatrix} 1 \\ -r_x/r_y \end{bmatrix} \tag{18}$$

$$\mathbf{n} = \frac{\mathbf{n}^*}{||\mathbf{n}^*||} \tag{19}$$

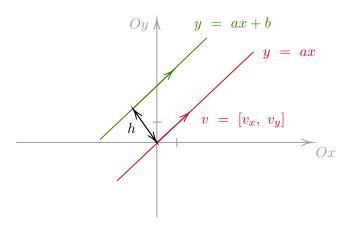
AFFINE LINES

If a line does not cross the origin, its equation would have the affine form y = ax + b:



AFFINE LINES

Consider the problem: find a line \mathcal{L} that is h-distance away from the line y = ax:



AFFINE LINES

The line \mathcal{L} is given by its equation y = ax + b. All we need to do is to find b, since a is already known. Here is one way to solve it:

- Find **v** on the line y = ax; **v** = [1, a].
- Find **n** orthogonal to **v**, $||\mathbf{n}|| = 1$ (see previous slides).
- Point $h\mathbf{n} = [hn_x, hn_y]$ lies on \mathcal{L} , so $hn_y = ahn_x + b$.
- From this, we know that $b = h(n_y an_x)$. Done.

Too many steps for such a simple problem? Maybe. But - it is hard to make a mistake doing it this way.

THANK YOU!

Lecture slides are available via Moodle.

You can help improve these slides at: github.com/SergeiSa/Extra-math-for-high-school

Check Moodle for additional links, videos, textbook suggestions.

