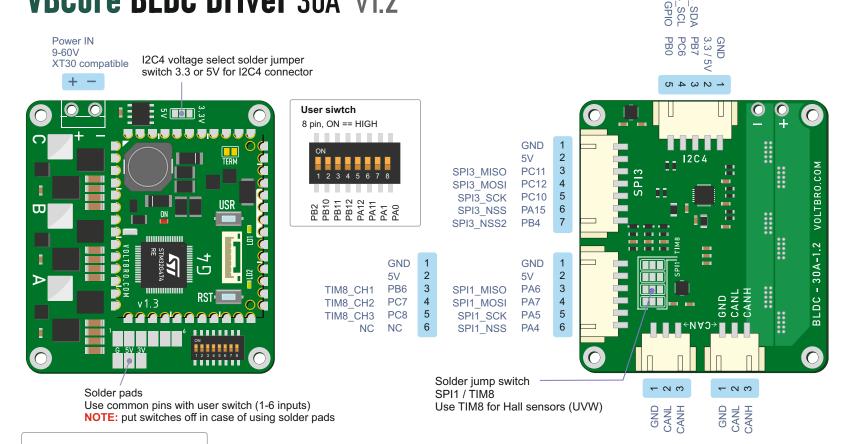
# **VBCore BLDC Driver 30A v1.2**



# **VBCore BLDC Driver** v1.2

VIN: 6-60V
MAX CURRENT 30A
MCU: VB32G4 (STM32G474RE)
BLDC DRIVER: DRV8328B
SPI encoder interface
UVW Hall encoder interface
I2C encoder interface
Current sensors
EEPROM
CAN / CAN-FD
Dimentions: 51x56mm

Mount holes: 45x50mm D2.5 mm

#### **NOTES:**

- 1. SPI1 and SPI3 connectors connected to controller via level shifters
- 2. Hall sensors connectors connected to controller via filter
- 3. I2C4 SCL and SDA lines pulled up DON'T USE internal pull-up
- 4. To enable power on I2C4 line (including EEPROM) close the voltage select solder jumper

# **VBCores**

#### www.vbcores.com

Electronics for robotics research and development

#### **Motor driver**

DRV8328B 4.5 to 60 V Three-phase BLDC Gate Driver

PIN	Timer
PB13	TIM1_CH1N
PB14	TIM1_CH2N
PB15	TIM1_CH3N
PA8	TIM1_CH1
PA9	TIM1_CH2
PA10	TIM1_CH3
PB3	
PB5	
	PB13 PB14 PB15 PA8 PA9 PA10 PB3

### **Current sensor**

ACS711KEXLT-31AB-T

Range: ± 31A Sensitivity: 45mV/A

Controll	PIN	ADC
I_A	PC1	ADC12_IN7
I_B	PC2	ADC12_IN8
I_C	PC3	ADC12_IN9

## **EEPROM**

256K

AT24C256C-SSHL-T

Controll	PIN	I2C
A0	GND	
A1	GND	
A2	GND	
SCL	PC6	I2C4_SCL
SDA	PB7	I2C4_SDA

# Voltage controll

Resistive voltage divider 16:1

Controll	PIN	ADC
V input	PC0	ADC12_IN6