Camera Gimbal

By: Dylan Motley, Minh Nguyen, Franz Kieviet

Project Overview and Name

- We wanted to make a phone/GoPro camera gimbal for taking videos. It would have 2 stepper motors and a gyroscope/accelerometer to track/keep the phone orientation to the ground while applying adjustments using the motors to maintain this desired output.
- Power management —> ~12+V battery, Step down LDO
- Compute ESP32 SOLO microcontroller
- Digital Digital accelerometer/gyroscope over SPI
- Actuation 2 1.8 degree stepper motors

BOM

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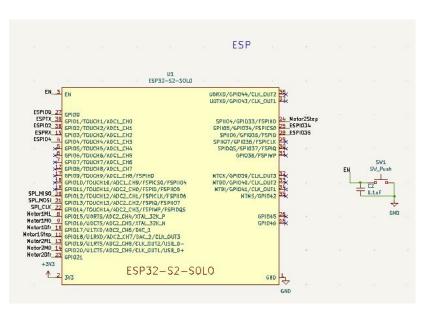
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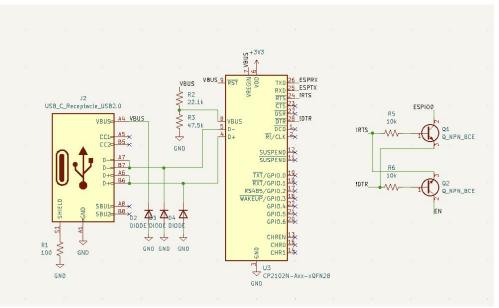
BOM

- Most expensive parts:
 - Stepper motors —> \$11.99 (per)
 - LiPo batteries —> \$24.99 (4 count)
 - Molex connectors —> \$7.99 (4 count)
 - IMU (accelerometer, gyroscope, etc.) —> \$10.70 (per)
- Total cost per board:
 - (If every part is ordered) —> \$78.48

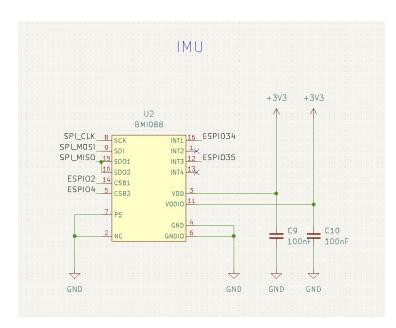
Schematic: ESP32 - S2 - SOLO

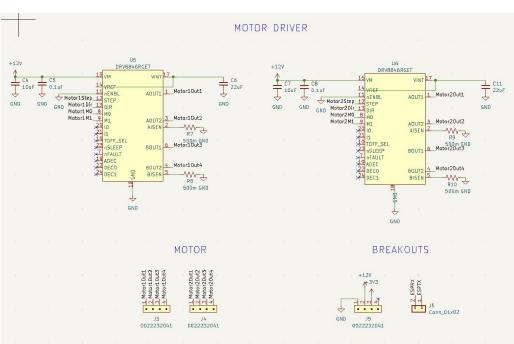
USB_C Connector & UART Bridge





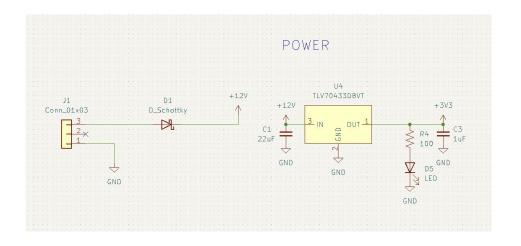
Schematic: ICs





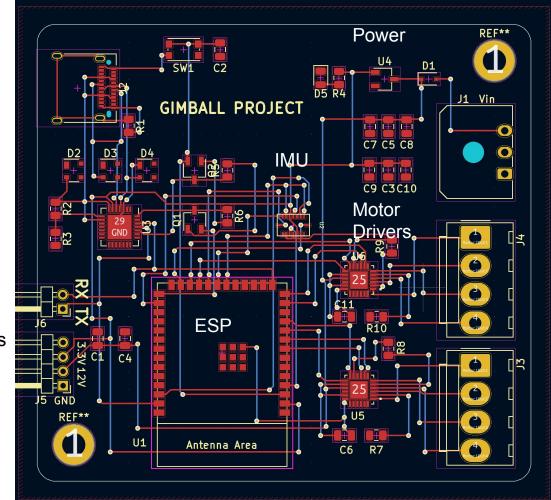
Covert headers to test points?

Schematic: Power



Layout

2.5 x 3 in



Breakouts