

# Special Relativity - Summary 2 - Relativistic dynamics

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This summary is based on the book Robert Resnick: Introduction to Special Relativity, chapters 3.1 - 3.7

- SR is in contrast with some of the classical laws of physics
- In the classical case we can accelerate a body to any speed  $\Leftrightarrow$  SR the maximum speed is  $c$

## 1 Relativistic momentum

Redefine momentum so that it is invariant under Lorentz transformation. The classical definition of the momentum:  $\bar{p} = m\bar{u}$  is not invariant under Lorentz transformation.  $\rightarrow$  We need to update the definition: using **relativistic mass**:  $m = m_0/\sqrt{1 - u^2/c^2}$ .

**Relativistic momentum:**

$$\bar{p} = m\bar{u} = \frac{m_0\bar{u}}{\sqrt{1 - u^2/c^2}}$$

- In the classical case mass is invariant.
- In SR mass is not invariant (note: the rest mass is invariant  $m_0$ ).
- When  $u = 0 \rightarrow$  the body is at rest  $m = m_0$
- $m_0$  rest mass is also called proper mass.
- The mass ( $m$ ) depends on the velocity, but it is independent of the direction of the motion

**General momentum:**

When there are x, y, z, components  $u^2 = u_x^2 + u_y^2 + u_z^2$

$$p_x = \frac{m_0 u_x}{\sqrt{1 - u^2/c^2}}$$

$$p_y = \frac{m_0 u_y}{\sqrt{1 - u^2/c^2}}$$

$$p_z = \frac{m_0 u_z}{\sqrt{1 - u^2/c^2}}$$

Note:  $u^2/c^2$  has the full magnitude of  $u$  and not just the components.

### 1.1 Alternative views on mass in relativity

The relativistic momentum and mass can be interpreted in two different ways.

classical momentum:

$$p_x = m_0 \frac{dx}{dt}$$

To make the momentum relativistic we can either treat the mass as relativistic and bringing in a factor of  $\frac{1}{\sqrt{1 - u^2/c^2}}$  or we treat the velocity component relativistically and the  $\frac{1}{\sqrt{1 - u^2/c^2}}$  factor is attributed to time dilation. Both interpretations are correct and can be used for different problems.

As  $u \rightarrow c$   $m \rightarrow \infty$  for the relativistic mass. The inertia of a body increases with velocity  $\rightarrow c$  can not be reached for objects with mass.

## 2 Relativistic force and dynamics of a single body

In relativistic mechanics Newton's 2nd law generalises:

$$\bar{F} = \frac{d}{dt}(\bar{p}) = \frac{d}{dt} \left( \frac{m_0\bar{u}}{\sqrt{1 - u^2/c^2}} \right)$$

- If there is no external force  $\rightarrow$  the momentum is conserved.

- If there is an external force  $\rightarrow$  the momentum change is equal to the total impulse given to the system by the external force.
- Newtonian mechanics: The kinetic energy is defined to be equal to the work done by an external force in increasing the speed from 0 to some value.

**Relativistic kinetic energy:**

$$K = m_0 c^2 \left[ \frac{1}{\sqrt{1 - u^2/c^2}} - 1 \right]$$

The **total energy** of the particle:  $E = m_0 c^2 + K$  is the sum of the rest energy and the kinetic energy.

**Rest energy:**  $m_0 c^2$  is the energy of the particle at rest ( $u = 0$ )

- Total energy is often used in high energy and particle physics.
- if  $v \ll c$  we get the classical expression:  $K = 1/2 m_0 c^2$
- if  $u \rightarrow c$   $K \rightarrow \infty$  an infinite amount of work would be needed to accelerate a particle to  $c$
- $K = (m - m_0) c^2$  a change in kinetic energy is related to change in the relativistic mass
- There is a connection between  $K$  and the momentum:  $E = c \sqrt{p^2 + m_0^2 c^2}$
- Another often used version:  $\frac{dE}{dp} = \frac{pc^2}{E} = u$

## 2.1 Acceleration of a particle under a single force

$$\vec{F} = m \frac{d\vec{u}}{dt} + \frac{\vec{u}(\vec{F} \cdot \vec{u})}{c^2}$$

$$\vec{a} = \frac{d\vec{u}}{dt} = \frac{\vec{F}}{m} - \frac{\vec{u}}{mc^2} (\vec{F} \cdot \vec{u})$$

The acceleration by a single force is not necessarily parallel to the force, because the last term is parallel to  $\vec{u}$ .

There are two simple cases where  $\vec{a}$  is parallel to  $\vec{F}$ :

1. If  $\vec{F}$  is parallel to  $\vec{u}$ :

$$F_{\parallel} = \frac{m_0}{(1 - u^2/c^2)^{3/2}} a_{\parallel}$$

**longitudinal mass:**

$$\frac{m_0}{(1 - u^2/c^2)^{3/2}}$$

2. If  $\vec{F}$  is perpendicular to  $\vec{u}$ :

$$F_{\perp} = \frac{m_0}{\sqrt{1 - u^2/c^2}} a_{\perp}$$

**transverse mass:**

$$\frac{m_0}{\sqrt{1 - u^2/c^2}}$$

example: force on a charged particle moving in a magnetic field  $\vec{B}$  ( $\vec{F} = q\vec{u} \times \vec{B}$ )

Experimental support for the relativistic mass: An  $e^-$  from a  $\beta$  decay ( $n^0 \rightarrow p^+ + e^- + \bar{\nu}_e$ ) enters a velocity selector, which determines the speed of the  $e^-$  that can emerge from the chamber. Then the particles with the same speed enter a magnetic field, where they are going to move on a curved path that is dependent on their momentum (mass). The radius of the path can be measured  $\rightarrow$  relativistic mass can get calculated.

## 3 The equivalence of mass and energy

The rest mass of a body is equivalent to energy  $\rightarrow$  **rest-mass energy**.

- This follows from the Lorentz transformation and the momentum conservation.
- The total energy is conserved in inelastic collisions
- The conservation of total energy is equivalent to conservation of rest mass

- Mass and energy are equivalent  $\rightarrow$  they form a **single invariant: mass-energy**
- relation:  $E = mc^2$  or  $m = E/c^2 \rightarrow$  we can convert one into the other
- The conversion of mass into energy is often used in nuclear physics: e.g. eV or MeV units for the mass of particles
- Or a mass less particle (e.g. photon) can get a "mass" assigned to it based on its energy
- We can think of the kinetic energy as an **external energy** and of the rest-mass energy as an internal energy.
- **Internal energy** is to the largest part made up of the total rest-mass energy of the constituent fundamental particles, but it can also include:
  - molecular motion,
  - intermolecular potential energy,
  - atomic potential energy,
  - nuclear potential energy
- The rest mass or (proper mass) of a body is generally not constant.
- We can assign a rest mass to any collection of particles in motion in a frame at which the centre of mass is at rest.
- In classical physics we have 2 conservation laws: energy and mass conservation  $\rightarrow$  in SR we have 1: mass-energy conservation.

## 4 Lorentz transformation of momentum, energy, mass and force

### 4.1 Momentum and energy

$$p_x = \frac{1}{\sqrt{1-v^2/c^2}} \left( p'_x + \frac{E'v}{c^2} \right) \quad p'_x = \frac{1}{\sqrt{1-v^2/c^2}} \left( p_x - \frac{Ev}{c^2} \right)$$

$$p_y = p'_y$$

$$p_z = p'_z$$

$$E = \frac{1}{\sqrt{1-v^2/c^2}} (E' + vp_x) \quad E' = \frac{1}{\sqrt{1-v^2/c^2}} (E - vp_x)$$

Very similar to the Lorentz transformation of x, y, z, t:

$$x' = \frac{x - vt}{\sqrt{1-v^2/c^2}} \quad p'_x = \frac{p_x - v(E/c^2)}{\sqrt{1-v^2/c^2}}$$

$$t' = \frac{t - (v/c^2)x}{\sqrt{1-v^2/c^2}} \quad \frac{E'}{c^2} = \frac{(E/c^2) - (v/c^2)p_x}{\sqrt{1-v^2/c^2}}$$

- When relativity is put into 4 dimensional space-time form a four-vector can be created out of the space and time coordinates
- Similarly a four-vector can be created out of the three momentum components and the energy
- If energy and momentum are conserved in one interaction in an inertial frame  $\rightarrow$  then they are also conserved for the interaction in another inertial frame
- If momentum is conserved  $\rightarrow$  energy must be conserved as well.

### 4.2 Mass

The transformation of mass follows directly from the transformation of energy:

$$m = \frac{m'(1 + u'_x v/c^2)}{\sqrt{1-v^2/c^2}} \quad m' = \frac{m(1 - u_x v/c^2)}{\sqrt{1-v^2/c^2}}$$

### 4.3 Force

$$F_x = F'_x + \frac{u'_y v}{c^2 + u'_x v} F'_y + \frac{u'_z v}{c^2 + u'_x v} F'_z \quad F'_x = F_x - \frac{u_y v}{c^2 - u_x v} F_y - \frac{u_z v}{c^2 - u_x v} F_z$$

$$F_y = \frac{\sqrt{1 - v^2/c^2}}{1 + u'_x v/c^2} F'_y \quad F'_y = \frac{\sqrt{1 - v^2/c^2}}{1 - u_x v/c^2} F_y$$

$$F_z = \frac{\sqrt{1 - v^2/c^2}}{1 + u'_x v/c^2} F'_z \quad F'_z = \frac{\sqrt{1 - v^2/c^2}}{1 - u_x v/c^2} F_z$$

A more **compact version**:

$$\frac{1}{\sqrt{1 - v^2/c^2}} = \gamma$$

$$F_x = \frac{F'_x + (v/c^2) \bar{u}' \cdot \bar{F}'}{1 + u'_x v/c^2} \quad F'_x = \frac{F_x - (v/c^2) \bar{u} \cdot \bar{F}}{1 - u_x v/c^2}$$

$$F_y = \frac{F'_y}{1 + u'_x v/c^2} \quad F'_y = \frac{F_y}{1 - u_x v/c^2}$$

$$F_z = \frac{F'_z}{1 + u'_x v/c^2} \quad F'_z = \frac{F_z}{1 - u_x v/c^2}$$

$F_x$  depends on  $\bar{u} \cdot \bar{F}$  the power developed by the force in another frame  $\rightarrow$  power and force are related in 4D space, similar to momentum and energy.

**The 4th relation that goes together with the force is:**

$$\bar{u} \cdot \bar{F} = \frac{\bar{u}' \cdot \bar{F}' + v F_x}{1 + u'_x v/c^2} \quad \bar{u}' \cdot \bar{F}' = \frac{\bar{u} \cdot \bar{F} - v F_x}{1 - u_x v/c^2}$$

**Special case:** if a body is at rest ( $u' = 0$ ) in the S' frame and it is subjected to a force with components  $F'_x, F'_y, F'_z$

$$F_x = F'_x$$

$$F_y = \frac{F'_y}{\gamma} = \frac{F'_y}{\sqrt{1 - v^2/c^2}}$$

$$F_z = \frac{F'_z}{\gamma} = \frac{F'_z}{\sqrt{1 - v^2/c^2}}$$

The force is the greatest in the rest frame of the object and smaller in all other inertial frames.