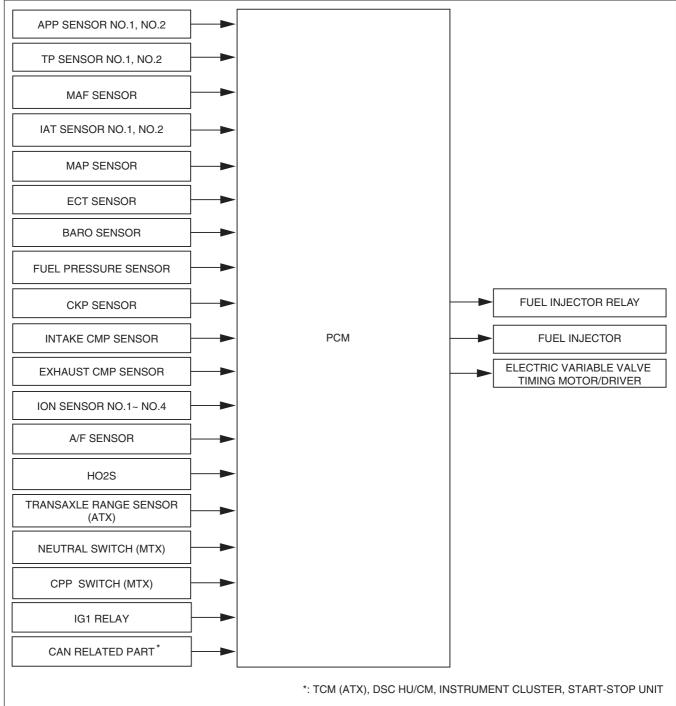
### FUEL INJECTION CONTROL SYSTEM [SKYACTIV-G 2.0, SKYACTIV-G 2.5]

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#### **Outline**

- Performs optimum fuel injection according to engine operation conditions.
- The PCM determines the engine operation conditions based on the signals from each input device and drives the fuel injectors at the optimal fuel injection time (fuel injection amount) and the fuel injection timing to inject fuel
- Optimally controls combustion based on fuel injection amount, fuel injection timing, number of fuel injections, and the fuel pressure to realize emission performance while the engine is cold and higher engine output.

#### **Block Diagram**



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# Operation Injection timing

Fuel injection timing is switched according to the engine operation conditions.

- Fuel injection is performed at the appropriate injection timing and amount based on the following sensor input signals synchronized with the crankshaft rotation during the intake or compression stroke at each cylinder.
  - MAF sensor
  - MAP sensor
  - IAT sensor No.1
  - IAT sensor No.2
  - BARO sensor
  - CKP sensor
  - ECT sensor

#### Injection time

• The PCM calculates the fuel injection amount according to the engine operation conditions as the fuel injection time and energizes the fuel injectors.

# Fuel injector energization time and operation conditions

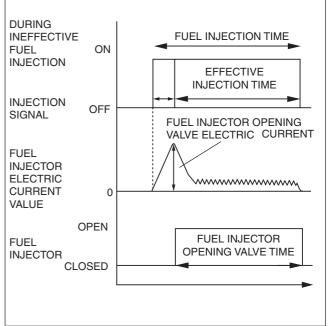
- The fuel injectors cause an operation delay with the start of energization from the PCM. The PCM calculates the fuel injection time by adding the noninjection time (ineffective injection time) due to the operation delay to the actual injection time (effective injection time), and energizes the fuel injectors for this time.
- The fuel injection time is based on the following formula:

# Fuel injection time = effective injection time + ineffective injection time Ineffective injection time

- The fuel injectors cause an operation delay with the start of energization due to a delay in the rise of operation current by coil inductance, mass of the needle valve and plunger, and spring resistance. This delay is the ineffective injection time
- The non-injection time is affected by the change in fuel pressure and the battery voltage.
   Accordingly, the PCM sets the non-injection time according to the fuel pressure and the battery voltage.

#### Effective injection time

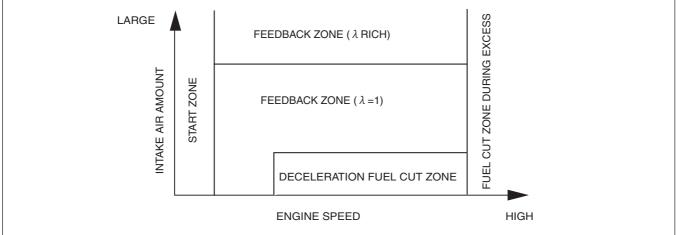
 The time when the fuel injector valve is open, which is the actual fuel injection time, is called the effective injection time.



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#### **Determination of effective injection time**

 The PCM divides the engine operation conditions into control zones according to engine speed and intake air amount, and determines the effective injection time at each control zone to perform optimum air/fuel ratio control in all engine driving ranges.



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Control zone table

Control name					
Control name	Control outline				
Start zone	Purpose  • Improved startability				
	Control condition				
	When engine speed is less than 500 rpm				
	Determination of fuel injection time				
	According to engine coolant temperature and engine speed and fuel pressure				
Feedback zone (λ					
= 1)	• Improved fuel economy				
	• Improved exhaust gas purification				
	Control condition				
	• During engine operation condition except for engine start zone and feedback zone (λ rich) and fuel cut zone				
	Determination of fuel injection time				
	• During normal driving, the various correction amounts are added to the basic injection time during normal				
	driving to obtain a ratio that is close to the theoretical air/fuel ratio.				
Feedback zone (λ	Purpose				
rich)	• Improved driveability				
	Control condition				
	• The accelerator pedal opening angle is the specified value or more				
	Determination of fuel injection time				
	Fuel amount increases according to accelerator pedal opening angle      Purpose				
	Purpose     Protection of catalytic converter and exhaust system components (suppression of gas temperature)				
	Control condition				
	The estimated exhaust temperature and estimated catalytic converter temperature are the specified value.				
	or more.				
	Determination of fuel injection time				
	• Fuel amount increases according to estimated exhaust gas temperature and estimated catalytic converter				
	temperature (promotion of cooling efficiency from vaporization heat)				
Excessive speed	Purpose				
fuel cut zone	• Engine protection				
	Control condition				
	• When engine speed is 6,800 rpm or more (SKYACTIV-G 2.0)				
	• When engine speed is 6,500 rpm or more (SKYACTIV-G 2.5)				
	• When engine speed is 2,500 rpm or more (When DTC P0089:00 is stored)				
	Determination of fuel injection time • Fuel injection stopped.				
Deceleration fuel	Purpose				
cut zone	• Improved fuel economy				
cut zone	Control condition				
	If all of the following conditions are met while the vehicle is decelerating				
	Accelerator pedal is fully closed				
	Engine speed is specified value or more				
	Vehicle speed is specified value or more				
	Determination of fuel injection time				
	• Fuel injection is stopped.				

# Fuel injection time calculation method table

(A: Fuel injection time base, B: Correction for fuel injection time)

		Control zone				
Contents (Calculation or determination method for fuel injection time and correction)		START ENGINE	FEEDBACK (λ=1)	FEEDBACK (\langle RICH)	ENGINE SPEED AT EXCESSIVE FUEL CUT	DECELERATION FUEL CUT AT
Injection time at engine start	Set value according to engine coolant temperature (low engine coolant temperature→long injection time)	Α				
Basic injection time	Basic injection time = Charging efficiency *1 × fuel flow coefficient*2 × target equivalent		А	Α		
Fuel cut Ineffective	Fuel injection time = 0 Set time according to fuel injector performance	A	Α	A	Α	Α
Volume increase correction at engine start	Purpose: Ensures engine speed stability just after engine start  Correction condition  • Specified time according to engine coolant temperature directly after engine start  Correction amount  • Low engine coolant temperature→large correction  • Low intake air temperature→large correction	В	В			
Feedback correction (A/F sensor)	Purpose: Controls air/fuel ratio to theoretical air/fuel ratio  Correction amount  • A/F sensor output current is 0 mA or less→volume decrease correction  • A/F sensor output current is 0 mA or more→volume increase correction		В	В		
Feedback correction (HO2S)	Purpose: Controls air/fuel ratio to theoretical air/fuel ratio  Correction amount  • HO2S output voltage is approx. 0.7 V or more→volume decrease correction  • HO2S output voltage is approx. 0.7 V or less→volume increase correction		В			
Warm-up volume increase correction	Purpose: Ensures combustion stability when engine coolant temperature is low  Correction condition  • When engine coolant temperature is at set value  Correction amount  • High charging efficiency, low engine coolant temperature→large correction		В	В		
Learning correction	Purpose: Corrects deviation in air/fuel ratio from deterioration over time of mechanical devices  Correction amount  Learned value based on average value of A/F deviation amount (feedback amount)		В	В		
Heavy load volume increase correction	Purpose: Improved engine output, decrease of exhaust gas temperature  Correction condition  • Based on the fixed value when the accelerator pedal opening angle is a certain value or more, otherwise, based on engine speed and charging efficiency.  Correction amount  • High engine speed, high charging efficiency→large correction			В		

<sup>\*1 :</sup> Charging efficiency is the ratio of the actual amount of intake air to the maximum air charging amount (mass volume) of the cylinder. The value increases as the engine load increases.
\*2 : Fuel flow coefficient is a coefficient to calculate a fuel injection time from a fuel injection amount required for an

intake air amount.

#### **Fuel cut**

• Includes fuel cut under the following conditions, except fuel cut at excessive engine speed and deceleration fuel cut according to engine operation.

Fuel cut table

Control name	Control outline			
Fuel cut during	Purpose			
selector lever	ATX protection			
shifting in D range	Control conditions			
(ATX)	When shifting while vehicle is stopped and engine raced			
Sensor	Purpose			
malfunction fuel	• To prevent engine damage from abnormal ignition due to a malfunction input of a cylinder identification of			
cut	the engine speed signal.			
	Control conditions			
	• When a malfunction in the crankshaft position sensor or exhaust camshaft position sensor is detected			
Dechoke control	Purpose			
	To improve engine startability when spark plugs are flooded (scavenging)			
	Control conditions			
	When cranking close to fully-open throttle valve			
Theft prevention	Purpose			
	To prevent theft			
	Control conditions			
	Immobilizer system related information (engine start prohibited) received from start stop unit			

#### **Boost Circuit**

• The battery positive voltage input via the fuel injector relay is boosted up to 40 V.

#### **Output Circuit**

- To improve fuel injection response, the plunger pulling force is strengthened by providing high current (over excitation current) when the fuel injector is open.
- To reduce fuel injector heat generation, the opening of the fuel injector is kept open using low current after it opens.

Fuel injector status	PCM operation	
Opening starts	1. Provides 40V, boosted by the boost circuit, to the opening transistor (40 V output).	
	2. Voltage is provided to the fuel injector, the ground transistor is turned on and grounded, and the fuel injector opens.	
	3. After the fuel injector is opened, the opening transistor is turned off.	
Opening held	Controls the on/off of the holding transistor (12 V output) so that the hold current of the fuel injector i constant.	
Closing	• Turns off the holding and ground transistors at the same time the fuel injection signal from the PCM is stopped, and cuts the current.	