

# DO-GON KIM

New York, NY | (646) 315-2260 | [dk3322@columbia.edu](mailto:dk3322@columbia.edu) | [do-gon.github.io](https://do-gon.github.io) | [LinkedIn](#)

## EDUCATION

### Columbia University

Sep 2023 – May 2025

*Master of Science, Mechanical Engineering, GPA: 4.065*

Relevant Coursework: Intro to Robotics, Computational Aspects of Robotics, Applied Robotics, Robot Learning, Intro to Control Theory, Digital Manufacturing, Mechatronics and Embedded Systems, Data Science, MS Projects in MechE

### New York University

Sep 2020 – Jan 2023

*Bachelor of Science, Mechanical Engineering, GPA: 3.823*

Relevant Coursework: Robotic Manipulation and Locomotion, Robotic Vision

Honors & Awards: Tau Beta Pi, UGSRP, Founder's Day Award, Dr. Morris Young Outstanding Project Design Award

## RESEARCH INTERESTS

My past research can be categorized into three areas: **Finger Design integrated with Tactile Sensors, Signal Processing for Sensing, and Control Algorithm Development**. I have explored the design of systems that mimic the multiple sensory receptors of human touch. Moving forward, I aim to explore the design of tactile fingers and control systems that emulate human touch and realize sensing capabilities beyond the limits of human perception. Furthermore, I seek to investigate how these systems can help robots better understand and interact with their environment.

## PUBLICATIONS

### Peer-Reviewed Publications

- [U.1] E. T. Chang\*, P. Ballentine\*, Z. He\*, **D. Kim**, K. Jiang, H. Liang, J. Palacios, W. Wang, P. Piacenza, I. Kymissis, M. Ciocarlie, "SpikeATac: A Multimodal Tactile Finger with Taxelized Dynamic Sensing for Dexterous Manipulation," *Under Review*
- [C.1] K. Zhang\*, **D. Kim\***, E. T. Chang\*, H. Liang, Z. He, K. Lampo, P. Wu, I. Kymissis, M. Ciocarlie, "VibeCheck: Using Active Acoustic Tactile Sensing for Contact-Rich Manipulation," *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2025*

### Workshop Papers, Abstracts, and Posters

- [P.1] E. T. Chang\*, P. Ballentine\*, Z. He\*, **D. Kim**, K. Jiang, H. Liang, J. Palacios, W. Wang, P. Piacenza, I. Kymissis, M. Ciocarlie, "SpikeATac: A Multimodal Tactile Finger with Taxelized Dynamic Sensing for Dexterous Manipulation," *Northeast Robotics Colloquium (NERC) 2025, Cornell University*

## RESEARCH EXPERIENCE

### Robotic Manipulation and Mobility (ROAM) Laboratory, Columbia University

May 2024 – Sep 2025

Graduate Researcher, advisor: Prof. Matei Ciocarlie

- *SpikeATac: A Multimodal Tactile Finger for Manipulation*
  - Developed a ROS 2 data pipeline integrating PVDF, capacitive, and accelerometer sensors with a linear probe for finger-poking experiments to collect synchronized multimodal data and characterize sensor sensitivity
  - Developed two real-time gripper stopping algorithms based on multimodal tactile sensing: a difference-based method using a 16-channel PVDF array, and a mean-difference threshold method using 7 capacitive sensors
  - Demonstrated stable grasping with a parallel gripper on deformable and fragile objects (egg, nori, raspberry, blueberry, strawberry, flower, origami cube), showcasing SpikeATac's capability for delicate manipulation
- *VibeCheck: Active Acoustic Sensing for Manipulation*
  - Designed and developed fingers with piezoelectric sensor for active acoustic sensing for manipulation, enabling material, internal structure, and object state classification, grasp point, and contact type estimation
  - Developed and optimized tactile sensing systems and signal processing techniques, including FFT analysis for feature extraction which is the groundwork for object classification using MLP
  - Demonstrated a peg-in-hole insertion task using active acoustic sensing, achieving 90% success rates for in-distribution starting states and 50% for out-of-distribution using only acoustic tactile feedback

### Nonlinear Controls Research Group, Columbia University

May 2025 – Sep 2025

Graduate Researcher, advisor: Prof. Homayoon Beigi

- Established a PD control framework in C++ within ROS 2 for developing learning-adaptive controller
- Built a control system for Jetecobot to execute simultaneous commands across multiple joints

### Data and innovative technology-driven Transportation Laboratory, Columbia University

Jan 2024 – Sep 2024

Graduate Researcher, advisor: Prof. Sharon Di

- Spearheaded the development of a simulation framework using ROS2 and PyBullet in AWS DeepRacer, enabling ML model testing without physical hardware and fostering a dynamic environment for autonomous vehicle research
- Developed visualization tools for LIDAR to detect obstacles around the autonomous vehicle
- Developed a real-time ArUco marker detection system with OpenCV to accurately determine the position, orientation, and speed of the vehicle

**Control/Robotics Research Laboratory**, New York University  
Undergraduate Research Assistant, advisor: Prof. Farshad Khorrami

Jun 2022 – Dec 2022

- Enabled Turtlebot3 Burger to detect obstacles and navigate autonomously with LIDAR, encoder, and IMU
- Investigated the accuracy of a map created by gmapping, one of the SLAM algorithms
- Studied SLAM algorithms (RTAB-Map, ORB-SLAM)

## TEACHING EXPERIENCE

---

**MECE E4601 Digital Control Systems**, Columbia University

Jan 2025 – May 2025

Teaching Assistant, advisor: Prof. Homayoon Beigi

- Topics: Sampling Theorem, z-Transform, Stability, Root Locus, Frequency Response, Controller Design

**MECE E4602 Introduction to Robotics**, Columbia University

Sep 2024 – Dec 2024

Teaching Assistant, advisor: Prof. Sunil Agrawal

- Topics: Homogeneous Transformations, Forward and Inverse Kinematics, Jacobians, Dynamics, Joint Control

**EEME E6601 Introduction to Control Theory**, Columbia University

Sep 2023 – Dec 2023

Note Taker, advisor: Prof. Nicolas Chbat

- Topics: Transfer Functions, Root Locus, Bode and Nyquist Plots, State-Space, Stability, z-Transform, LQR

## OUTREACH

---

### Outreach and Engagement with Student Groups

- Guest speaker for the *Jeju Special Self-Governing Province Office of Education's "2025 Global University Exploration for High School Students."* Presented *VibeCheck* and *Spike-A-Tac* and mentored selected high school students from Jeju, Korea on research and study abroad pathways, July 2025
- Guest speaker for *Re'Generation Movement*, a non-profit organization empowering youth leadership. Introduced research projects and discussed the importance of being part of an encouraging community, July 2025

## PROJECTS

---

**Introduction to Robotics Project – Cable Driven Parallel Robot**

Sep 2023 – Dec 2023

- Developed an adaptive velocity controller for a 4-cable-driven parallel robot, enabling dynamic speed adjustments based on the different objects to enhance safe handling
- Optimized the cable-driven system design by reducing cables from 7 to 4 to simplify kinematic solutions and to minimize collision issues
- Built 3D simulations in MATLAB to demonstrate motion planning in industrial settings like distribution warehouses

**Robotic Vision Project – Sheet Music Sight-Reader**

Feb 2022 – May 2022

- Created a Colab-based CV pipeline that takes in the image of a sheet of music and outputs a playable music file
- Trained a model to detect a position of each note in sheet music using the YOLO algorithm with 90% accuracy
- Utilized Canny Edge Detector to find five lines in sheet music and applied a vertical slice on across the five lines to calculate an accurate position of five lines

## SKILLS

---

**Programming Language:** Python, C/C++, MATLAB, G-code, LaTex

**Software/OS:** SOLIDWORKS, Onshape, ROS 2, micro-ROS, Linux, Rviz, Gazebo Simulator, Pybullet, Simulink

**Machining/Tools:** 3D printing (FDM, SLA), Laser cutting, Soldering, Silicone molding, Vertical bandsaw