Collaborative Learning for Cyberattack Detection in Blockchain Networks

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***Abstract*—This article aims to study intrusion attacks and then develop a novel cyberattack detection framework for blockchain networks. Specifically, we first design and implement a blockchain network in our laboratory. This blockchain network will serve two purposes, i.e., generate the real traffic data (including both normal data and attack data) for our learning models and implement real-time experiments to evaluate the performance of our proposed intrusion detection framework. To the best of our knowledge, this is the first dataset that is synthesized in a laboratory for cyberattacks in a blockchain network. We then propose a novel collaborative learning model that allows efficient deployment in the blockchain network to detect attacks. The main idea of the proposed learning model is to enable blockchain nodes to actively collect data, share the knowledge learned from its data, and then exchange the knowledge with other blockchain nodes in the network. In this way, we can not only leverage the knowledge from all the nodes in the network but also do not need to gather all raw data for training at a centralized node like conventional centralized learning solutions. Such a framework can also avoid the risk of exposing local data's privacy as well as the excessive network overhead/congestion. Both intensive simulations and real-time experiments clearly show that our proposed collaborative learning-based intrusion detection framework can achieve an accuracy of up to 97.7% in detecting attacks.**

***Index Terms*—Blockchain, deep learning, collaborative learning, cyberattack detection, cybersecurity.**

I. Introduction

BLOCKCHAIN [1]–[3] has been emerging as a novel technology in storing and managing data with many advantages over conventional data management systems. In particular, unlike traditional centralized data management solutions, blockchain technology allows data to be stored in a distributed manner across multiple nodes. In this way, data can be accessed and processed simultaneously at multiple nodes, and thus avoiding the problem of bottlenecks and single point of failure. More importantly, one of the most important features of blockchain technology is to enable data to be stored in blocks, and once a block of data is verified and placed in the chain, it cannot be modified and/or deleted. In this way, the data's integrity can be protected thanks to outstanding features of blockchain, e.g., decentralization, immutability, auditability and fault tolerance [2], [4]. As a result, there are more and more applications of blockchain technology in our lives including finance, healthcare, logistics and IoT systems [2], [3], [5].

Due to the rapid success with a wide range of applications in most areas, especially in money transfer and cryptocurrency, blockchain-based systems have been becoming targets of many new generation cyberattacks. For example, in September 2020, KuCoin, a crypto exchange based in Singapore, announced that its system was hacked and the hackers stole over $281 million worth of coins and tokens [6]. In May 2019, Binance, one of the biggest cryptocurrency exchange companies in the world, reported to be hit by a major security incident. In particular, the hackers did break the exchange's security system and withdraw over 7,000 bitcoins from digital wallets, causing a total loss of approximately $40 million for the customers [6]. Most recently, in January 2022, Chainalysis reported that North Korean hackers performed seven attacks into cryptocurrency platforms and stole nearly $400 million from digital assets in 2021 [7]. Although most of current attacks target on virtual money exchange systems, a number of blockchain applications in critical areas such as healthcare [8] and food supply chains [9] could be potential for attackers in the near future. These attacks, if happen, not only cause huge losses on our assets, but can also lead to many serious issues related to human health and lives. Therefore, solutions to detect and prevent attacks in blockchain networks are becoming more urgent than ever.

In network security, Machine Learning (ML) has been being considered as the most effective solution to detect cyberattacks with very high accuracies [10]–[12]. The main reasons for the outstanding advantages of using ML for intrusion detection problems compared with other conventional detection methods such as signature-based and abnormally-based are threefold. First, unlike conventional intrusion detection solutions which are usually designed to detect a specific type of attack (e.g., virus, trojan, spam and botnet), ML solutions allow to detect many types of attacks at the same time with very high accuracies. For example, Deep Learning (DL) allows to detect cyberattacks in industrial automation and control system with an accuracy of up to 97.5% [13]. Second, while traditional solutions are often designed to detect known attacks, ML allows to detect attacks that have never been detected and reported before. For example, in [14], the authors showed that their DL model can detect attacks such as, the DDoS attack of Mirai and BASHLITE botnets, even though such types of attacks have never been learned/trained before by

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this model. Last but not least, ML algorithms, especially DL, can be deployed effectively, quickly and flexibly. For example, after a deep neural network is trained, it can be deployed in different intrusion detection systems at the same time to detect cyberattacks quickly with high accuracies. In addition, when data about new types of attacks is available, we can easily update new versions of deep neural networks through transfer learning techniques [15].

As a result, ML has been considering as a highly-effective solution to detect the cyberattacks for blockchain networks [16]. In particular, in [17], the authors proposed to use Random Forest and XGBoost to detect attacks in a blockchain-based IoT system. The results show that this solution can identify different types of attacks and normal behaviors with an accuracy of up to 99%. However, they only tested their results on the BoT-IoT dataset that is not real blockchain traffic. Similarly, in [18], the authors proposed an ML-based method, called bidirectional long short-term memory (BiLSTM) to detect attacks in an IoT network before the data is stored in the blockchain network. Although the results also showed that they can detect different kinds of attacks with an accuracy of up to 99%, they were validated only on conventional network datasets such as UNSW-NB15 and BoT-IoT datasets. These datasets are collected in conventional computer networks and thus cannot reflect actual traffic in blockchain networks. In particular, these datasets have just general attacks in computer networks without specific attacks in blockchains, e.g., changes in blockchain transactions, incorrect consensus protocol or the break of the chain of blocks.

To the best of our knowledge, there are only few works that consider to use the real blockchain traffic, e.g., try to generate artificial data or try to create data to simulate an attack for blockchain networks to train ML models such as [19]–[21]. Specifically, in [19] the authors proposed a method to collect blockchain traffic data. First, they captured traffic samples from a public Bitcoin node and used them as the normal network data. Then, for the malicious traffic data, the authors performed DoS and Eclipse attacks on a target device (this device was created to become a node in the Bitcoin network). After that, the collected data was used to train an autoencoder deep learning model. This solution showed an accuracy of attack detection up to 99%. In [20], the authors used a public dataset and a private dataset from their testbed. Then, they proposed to use a Long Short-Term Memory Network (LSTM) to learn the properties of normal samples in the datasets. After that, they deployed a Condition Generative Adversarial Networks (CGAN) model to generate the artificial Low-rate Distributed DoS (LDDoS) attack samples for their blockchain dataset. The results showed the accuracy of classification up to 93%. In addition, in [21], the authors performed a DDoS attack namely Link Flood Attack (LFA) on a the simulation Ethereum network and collected the traceroute records of the network in both normal and attack behaviors. After that, the authors used the Recurrent Neural Network (RNN) to analyze the traceroute records to identify the attacks in the network. The results showed that the attack detection rate can achieve nearly 99%.

From all the above works and others in the literature, we can observe two main challenges for ML-based intrusion detection systems in blockchain networks which still have not been addressed. In particular, the first challenge is lacking of a synthetic data from laboratories for training ML models. Most of current works, e.g., [17] and [18] are using conventional cybersecurity datasets (e.g., UNSW-NB15 and BoT-IoT) to train data. However, these datasets were not designed for blockchain networks, and thus they are not appropriate to use in intrusion detection systems in blockchain networks. Other works, e.g., [19]–[21], tried to build their own datasets for blockchain networks, e.g., by obtaining the normal samples from the Bitcoin network [19], creating simulation experiment to detect the LFA [21] and generating artificial attack samples by CGAN [20]. However, these methods have several issues. First, normal samples of transactions from the Bitcoin network may include attacks from public blockchain network, but all collected data are classified and labeled to be normal data. Second, the simulation experiment in [21] was to generate traceroute records only for the LFA so they cannot extend to other attacks. Furthermore, it is difficult to evaluate the effects of artificial attack samples in [20] whether they can simulate a real attack into blockchain network or not. The another challenge we can observe here is that all of current ML-based intrusion detection solutions for blockchain networks are based on centralized learning models, i.e., all data is collected at a centralized node for training and detection. However, this solution is not suitable to deploy in blockchains as they are decentralized networks. Specifically, nodes in blockchain networks may have different data to train and due to privacy concerns, they may not want to share their raw data to a centralized node (or other nodes) for training processes. Moreover, sending a huge amount of data to the network will not only cause excessive network traffic, but also risk compromising the data integrity of blockchain networks.

This article aims to address the aforementioned challenges by first introducing ***a novel intrusion detection dataset named BNaT which stands for Blockchain Network Attack Traffic***, created from a real blockchain network in our laboratory and then proposing an effective decentralized collaborative machine learning framework to detect intrusions in the blockchain network. Specifically, to develop BNaT, we first setup and implement a blockchain network in our laboratory using Ethereum (an open-source blockchain software) and perform intensive experiments to generate blockchain data (including both normal and malicious traffic data). The main objectives of producing BNaT dataset are fourfold. Firstly, we collect the BNaT in a laboratory environment to have "clean" data samples (i.e., to ensure that the obtained data is not corrupted, error and/or irrelevant), that is especially important for training ML models. Secondly, the BNaT can be easily extended to include to new kinds of blockchain attacks, e.g., 51% or double spending attacks. Thirdly, we perform experiments with real attacks in the considered blockchain network, and thus the BNaT can reflect better the actual attack behavior of network than simulations or by artificial attack data generated by GAN in the literature, e.g., [20]. Fourthly, we collect the data in different blockchain nodes to have a complete view of effects when the attacks are performed in a decentralized

manner. After that, we develop a highly-effective collaborative learning framework to make it more effective in deploying in blockchain networks to detect attacks. In particular, in our proposed learning framework, working nodes in the blockchain network (e.g., mining nodes) can be used as learning nodes to collect blockchain data (e.g., observing its own traffic and classifying data). However, unlike centralized learning models, these nodes will train their learning models by using their own datasets instead of sending their datasets to a centralized node for processing. After that, these nodes can share their trained models to other nodes in the network to improve the accuracy of the trained models. In this case, even the nodes do not need to share their raw data, they still can learn useful information from other nodes in the network through extracting information from shared trained models. The main contributions of this paper can be summarized as follows.

- We setup experiments in our laboratory to build a private blockchain network with the aims of not only obtaining real blockchain datasets, but also testing our proposed learning model in a real-time manner. To the best of our knowledge, this is the first dataset obtained from a laboratory for studying cyberattacks in blockchain networks, and thus we expect that our proposed BNaT dataset can promote the development of ML-based intrusion detection solutions in blockchain networks in the near future.
- We propose a collaborative decentralized learning model to not only improve the accuracy of identifying attacks, but also effectively deploy in decentralized blockchain networks. This model enables nodes in the network to effectively share their trained models to improve cyber-attack detection efficiency without sharing their raw data.
- We perform both intensive simulations and real-time experiments to evaluate our proposed framework. Both simulation and experimental results clearly show out-performance of our proposed framework compared with other baseline ML methods. Furthermore, our results reveal some important information in designing and implementing learning models in blockchain networks in practice, e.g., real-time monitoring and detecting attacks.

The rest of this paper is organized as follows. Section II provides fundamental backgrounds and our designed blockchain network together with the cooperative learning model. Section III presents our proposed collaborative learning model to detect cyberattacks in the blockchain network. The experiment setup, dataset collection, and evaluation method are described in Section IV. After that, the experimental results and performance evaluations are discussed more details in Section V. Finally, we conclude the paper in Section VI.

II. Blockchain Network: Fundamentals and Proposed Network Model

A. Blockchain

Blockchain is a novel method in storing and managing data in a decentralized manner. In a blockchain network, multiple nodes are used to simultaneously process and store data. In particular, when a node in the blockchain network receives transactions (e.g., money exchange in the Bitcoin network), it will gather all the transactions and put in a block. This node will then start a mining process to find a "nonce" value for this block. It is important to note that thanks to the feature of the hash function, there is only a small set of satisfying nonce values for a block, and these values can only be found through an intensive searching process [1]. This mining process is a special process of blockchain networks to provide proofs for validated blocks, and thus this tamper-proof can significantly enhance security for blockchain networks. After the node finds the nonce value for the mining block, this new block will be broadcast and verified by other nodes in the network. Finally, if this block is verified, it will be put to the chain (linked to the hash value of the previous block inside its header). After the block is added to the chain, it is nearly impossible to change information in this block, and thus this property can guarantee the immutability of the blockchain. Another aspect of blockchain is traceability due to infeasible collision of the hash function, and thus any transaction or block can be tracked correctly. In summarize, blockchain can be termed as a decentralization, immutable, traceable, and time-stamped digital data chain (ledger).

B. Designed Blockchain Network at our Laboratory

In order to launch a blockchain network, there are two main kinds of blockchain nodes namely full node and bootnode. Firstly, full nodes take responsibility to store the ledger, participate in the mining process, and verify all blocks and states. Furthermore, they can be used to serve the network and provide data on request, e.g., netstats, which is a visual interface for tracking Ethereum network status (e.g., the block number, mining status and the number of pending transactions). Secondly, bootnode is a lightweight application used for the Node Discovery Protocol. The bootnodes do not synchronize blockchain ledger but help other Ethereum nodes discover peers to set up Peer-to-Peer (P2P) connections in the network.

The system model together with essential components of our designed blockchain network are set up as illustrated in Fig. 1. Specifically, the model includes K full nodes which are used to receive transactions, mining blocks, and keep the replica of ledger. These nodes continuously synchronize their ledgers together by the P2P protocol with equal permissions and responsibilities for processing data [1]. In order to connect them together, a management node, known as bootnode, is setup. The full nodes connect and interrogate this bootnode for the location of potential peers in the blockchain network. After being connected, each full node can collect data (i.e., transactions) from its network. Transactions can come from different blockchain applications such as cryptocurrency, smart city, food supply chain, and IoT. First, when transactions are sent to a full node, they will be verified and packed into one block. After the node finds the nonce value for this block, it will broadcast the block together with this nonce value to other nodes in the network for verification. Finally, if the block is verified by majority nodes in the network, it will be added to the chain.

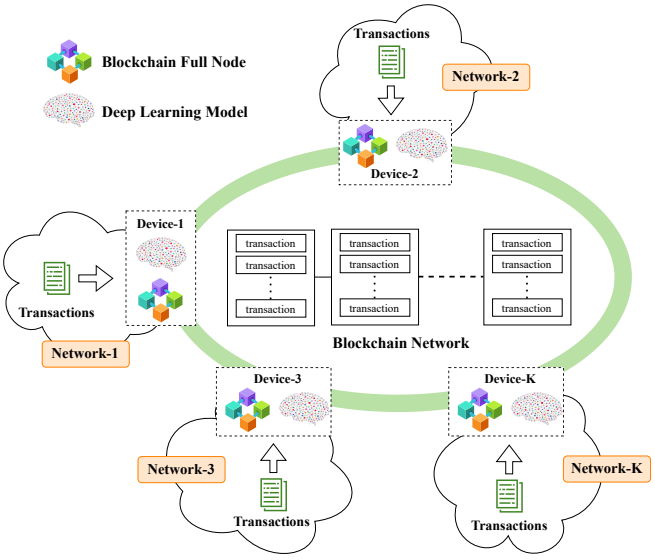


Fig. 1: Proposed collaborative learning model for blockchain network.

At our laboratory, we design a private blockchain network based on the Ethereum blockchain network. This network also uses the Proof-of-Work (PoW) consensus mechanism, but the block confirmation time is significantly faster than the older version in Bitcoin. Furthermore, the smart contract layer of Ethereum is suitable for flexible purposes of decentralized environments as mentioned above. In addition, at each node, several attacks, that can cause serious damages in the public blockchain network, will be considered. We then capture the traffic data to analyze their impacts on the blockchain network using BC-IDS. Note that, in practice, there is no software which supports automatically capturing the blockchain network traffic so far. Therefore, we have to analyze the blockchain network traffic data by using the Wireshark [22] and build a new collection tool, namely BC-IDS (more details will be explained in Section IV). In this way, we can observe effects of these attacks on different nodes in the blockchain network.

C. Proposed Cooperative Learning Model

In this section, we introduce our proposed collaborative learning model which can collaborate to effectively and decentralizedly detect attacks in the blockchain network. Our proposed model aims to leverage knowledge learned from all the nodes in the network without revealing their raw data. To do so, we first design a framework in the decentralized blockchain network in which each participated learning node (i.e., fullnode in the blockchain network) will use a deep learning model (we will explain more details in the next section) to learn from its collected data and then share its trained model to a Centralized Server (CS). The CS can be a bootnode or any full node in the blockchain network. After that, the CS will aggregate all the trained models and send

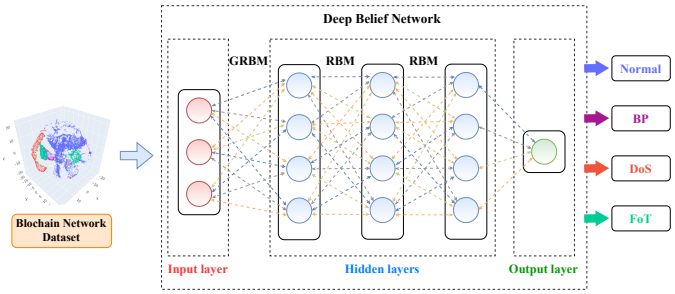


Fig. 2: The structure of classification-based for intrusion detection learning model for the blockchain network.

the aggregated model (i.e., the global model) back to the participated learning nodes. By doing this process iteratively, the learning nodes can gradually update their deep learning models and finally can reach the convergence (to the global training model). In this way, we can not only improve the accuracy of detecting cyberattacks in blockchain network but also eliminate the risks of exposing data over the network. Fig. 1 describes our proposed framework for intrusion detection in the blockchain network. In this design, all the blockchain nodes can quickly detect and prevent attacks to them. In addition, thanks to the advantages of our proposed machine learning model, our framework can detect attacks very quickly with very high accuracies (more details and results will be explained in Section V). Therefore, our proposed model can perform offline training and real-time detection to quickly and efficiently prevent attacks in decentralized blockchain networks.

III. Proposed Collaborative Learning Model for Intrusion Detection in Blockchain Network

In our proposed collaborative learning model, full nodes in the blockchain networks will be used as Learning Nodes (LNs) to learn data and share their learned knowledge to improve learning performance for the whole network. At each learning node, we propose to use a deep neural network to learn useful information from its collected data. Then, the learning nodes will share their trained learning models to the CS. After that, the CS will calculate the aggregated model (i.e., the global model) and share this model back to the LNs. When a learning node receives this aggregated model from the CS, it will integrate with its current learning model and train its local dataset. This process will be repeated until convergence or reaching a predefined maximum number of iterations. To the end, we can obtain the global learning model for all the learning nodes.

In our proposed model, each blockchain node has a set of local collected data, and we propose a deep neural network (DNN) using Deep Belief Network (DBN) to better learn knowledge from this data. The DBN is a type of deep neural network that is used as a generative model of both labeled and unlabeled data. Therefore, unlike other supervised deep neural networks which use labeled data to train the neural networks (e.g., convolutional neural networks [23]), the DBN has two stages in the training process. The first stage is the

pre-training process where the DBN trains its neural network with unlabeled dataset. The second stage is fine-tuning process where DBN uses labeled dataset to train its neural network. Thereby, the DBN can represent better the characteristics of dataset, and thus it can classify the normal behavior and different types of attacks with very high accuracies. In addition, the DBN includes multiple Restricted Boltzmann Machines (RBM) layers for latent representation [24]. In the DBN training process, the current layer generates latent representation by using latent representation of previous layer as the input. Unlike other deep neural networks which also can process both labeled and unlabeled data (e.g., autoencoder deep learning network [23]), the DBN optimizes the energy function of each layer to have better latent representations of data on each RBM layer in each iteration. Thereby, the DBN is more appropriate to analyze the blockchain network traffic where the samples and features have relatively coherence with each other.

The whole processes of DBN are illustrated in Fig. 2. Like other DNNs, the structure of DBN has three layers including an input layer, an output layer and multiple hidden layers. As can be seen in Fig. 2, the Gaussian Restricted Boltzmann Machines (GRBM) layer, a type of RBM which can process real values of data, is the input layer to receive and transform the input data into binary values. We denote $k = \{1, ..., K\}$ as the number of learning nodes in the collaborative learning model, $\boldsymbol{v}^k$ and $\boldsymbol{h}^k$ to be the vectors of visible and hidden layers of LN-k, respectively. In addition, M and N are the numbers of visible and hidden neurons of GRBM, and M' and N' are the numbers of visible and hidden neurons of RBM. As defined in [25] the energy functions of GRBM and RBM of LN-k are defined as follow:

$$E^k_{GRBM}(\boldsymbol{v}^k, \boldsymbol{h}^k) = \sum_{m=1}^{M} \frac{(v^k_m - b_{1,m})^2}{2\epsilon^2_m} - \sum_{m=1}^{M}\sum_{n=1}^{N} w_{m,n} h^k_n \frac{v^k_m}{\epsilon_m} - \sum_{n=1}^{N} b_{2,n} h^k_n, \tag{1}$$

$$E^k_{RBM}(\boldsymbol{v}^k, \boldsymbol{h}^k) = -\sum_{m=1}^{M'} b_{1,m} v^k_m - \sum_{m=1}^{M'}\sum_{n=1}^{N'} w_{m,n} v_m h^k_n - \sum_{n=1}^{N'} b_{2,n} h^k_n, \tag{2}$$

where $w_{m,n}$ is the weight between visible and hidden neurons, $b_{1,m}$ and $b_{2,n}$ indicate the bias of visible and hidden neurons, respectively, and ϵ_m represents the standard deviation of the neuron in the visible layer. From the energy functions, we can find the probability that is used in the visible layer of DBN [25] as follows:

$$p^k(\boldsymbol{v}^k) = \frac{\sum_{\boldsymbol{h}^k} e^{-E(\boldsymbol{v}^k, \boldsymbol{h}^k)}}{\sum_{\boldsymbol{v}^k}\sum_{\boldsymbol{h}^k} e^{-E(\boldsymbol{v}^k, \boldsymbol{h}^k)}}. \tag{3}$$

Then, we use the probability in (3) to calculate the gradients of each layer with the expectation value $\langle . \rangle$ as follows [25]:

$$\begin{aligned} \nabla g^k_{m,n} &= \frac{\partial \log p^k(\boldsymbol{v}^k)}{\partial w_{m,n}} \\ &= \langle v^k_m h^k_n \rangle_{dataset} - \langle v^k_m h^k_n \rangle_{model}. \end{aligned} \tag{4}$$

After learning with multiple GRBM and RBM layers, we define $\boldsymbol{X}^{g,r}_k$ as the output of the last hidden layer of LN-k. In this paper, the output layer utilizes the softmax regression function to classify the data samples based on the probability. We denote $\boldsymbol{W}^o$ and $\boldsymbol{b}^o$ as the weight matrix and bias vector between the output and the last hidden layer, respectively. We then can define the probability of the output Z belonging to Class-t as follows:

$$\begin{aligned} p^o_k(Z = t | \boldsymbol{X}^{g,r}_k, \boldsymbol{W}^o, \boldsymbol{b}^o) &= softmax(\boldsymbol{W}^o, \boldsymbol{b}^o) \\ &= \frac{e^{\boldsymbol{W}^o_t \boldsymbol{X}^{g,r}_k + \boldsymbol{b}^o_t}}{\sum_n e^{\boldsymbol{W}^o_n \boldsymbol{X}^{g,r}_k + \boldsymbol{b}^o_n}}, \end{aligned} \tag{5}$$

where $t \in \{1, ..., t, ..., T\}$ is a class of the output and T refers to the total classes (including different types of attacks and normal behavior). The prediction $\boldsymbol{Z}$ of the probability p^o is

$$\boldsymbol{Z}_k = \underset{t}{\operatorname{argmax}}[p_k(Z = t | \boldsymbol{X}^{g,r}_k, \boldsymbol{W}^o, \boldsymbol{b}^o)], \tag{6}$$

where Z is the output prediction from $\boldsymbol{Z}$. Then, we can calculate the gradient between the output layer and the last hidden layer from (5) as follows:

$$\nabla g^o_k = \frac{\partial p^o_k(Z = t | \boldsymbol{X}^{g,r}_k, \boldsymbol{W}^o, \boldsymbol{b}^o)}{\partial \boldsymbol{W}^o}. \tag{7}$$

After that, the results of (4) and (7) are used to calculate the total gradient ∇g^t_k of DBN with multiple GRBM, RBM layers and the output layer of LN-k as follows:

$$\begin{aligned} \nabla g^t_k &= \sum_{\boldsymbol{v}^k, \boldsymbol{h}^k} \nabla g^{GRBM}_k + \sum_{\boldsymbol{v}^k, \boldsymbol{h}^k} \nabla g^{RBM}_k + \nabla g^{output}_k \\ &= \sum_{\boldsymbol{v}^k, \boldsymbol{h}^k} \sum_{m=1}^{M}\sum_{n=1}^{N} \nabla g^k_{m,n} + \sum_{\boldsymbol{v}^k, \boldsymbol{h}^k} \sum_{m=1}^{M'}\sum_{n=1}^{N'} \nabla g^k_{m,n} + \nabla g^o_k. \end{aligned} \tag{8}$$

In the training process, the DBN first trains its neural network with unlabeled data for pre-training. Then, DBN uses its labeled data to fine-tuning its neural network. At this stage, the DBN of LN-k calculates its gradient ∇g^t_k. After that, this gradient is sent to the CS to create an updated global model for all LNs as illustrated in Fig. 3. For example, at iteration i the CS receives gradients from all K LNs, the CS first performs the average gradient function [26] as follows:

$$\nabla g^* = \frac{1}{K} \sum_{k=1}^{K} \nabla g^t_k. \tag{9}$$

We then denote $\boldsymbol{\varphi}_i$ as the global model at iteration i which includes the weight matrix for all layers of the LN's deep learning model, and μ represents the learning rate. From (9), the CS can calculate a new global model at iteration $i + 1$ as follows:

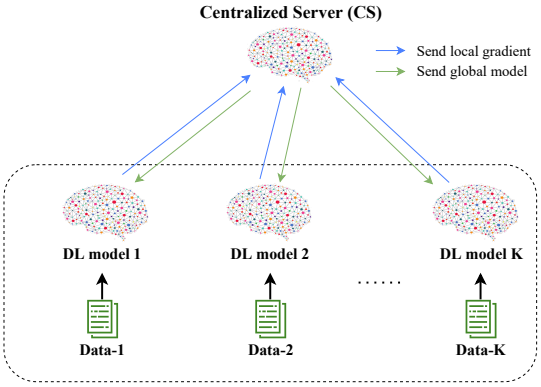


Fig. 3: The illustration of the collaborative learning between DL models and the CS.

Algorithm 1 The classification-based collaborative learning algorithm

1: **while** i $\leq$ maximum number of iterations or the training process is not converged **do**
2: **for** $\forall k \in K$ **do**
3: DBN of LN-k learns $\boldsymbol{X}_k$ and produces $\boldsymbol{Z}_k$.
4: Calculate gradient ∇g_k^t.
5: Send ∇g_k^t to CS.
6: **end for**
7: CS calculates average gradient ∇g^* and global model $\boldsymbol{\varphi}_i$.
8: $i = i + 1$.
9: CS updates global model $\boldsymbol{\varphi}_{i+1}$.
10: CS sends global model $\boldsymbol{\varphi}_{i+1}$ to all LNs.
11: LNs update their DBNs.
12: **end while**
13: DBN of LNs predict and classify $\boldsymbol{Z}_k$ from the training dataset $\boldsymbol{X}_k$ with the optimal global model $\boldsymbol{\varphi}_{opt}$.

$$\boldsymbol{\varphi}_{i+1} = \boldsymbol{\varphi}_i + \mu \nabla g^*. \tag{10}$$

Next, the CS sends the latest global model $\boldsymbol{\varphi}_{i+1}$ to the LNs to update their deep learning models. This process is repeated until it reaches the convergence or gets the maximum number of iterations. At this time, we can find the optimal global model $\boldsymbol{\varphi}_{opt}$ that includes the optimal weights of all layers. We denotes $\boldsymbol{W}_{opt}^o$ as the optimal weight matrix between the output layer and the last hidden layer from $\boldsymbol{\varphi}_{opt}$, the output prediction $\boldsymbol{Z}_k$ of LN-k thus can be calculated as follows:

$$\boldsymbol{Z}_k = \underset{t}{\text{argmax}}[p_k(Z = t|\boldsymbol{X}_k^{g,r}, \boldsymbol{W}_{opt}^o, \boldsymbol{b}^o)]. \tag{11}$$

From (11), the softmax regression of each LN can classify its the blockchain network samples to be normal behavior or a type of attacks. Algorithm 1 summarizes the process of our proposed collaborative learning model.

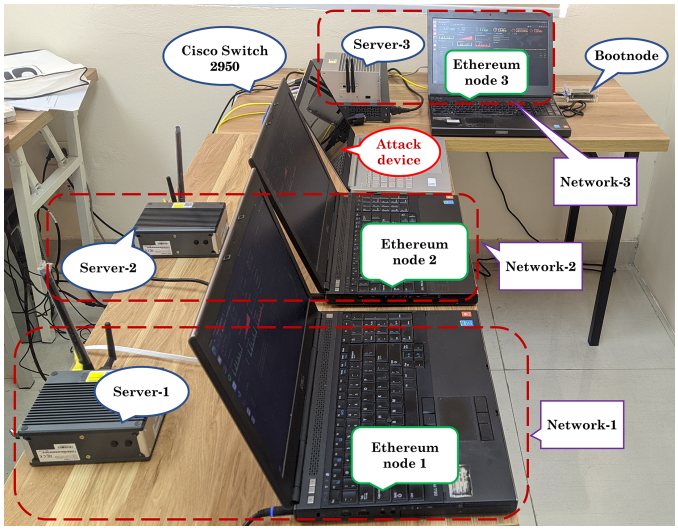


Fig. 4: Experiment setup.

IV. Experiment Setup, Dataset Collection and Evaluation Method

This section will explain more details about experiment setup, data collection, and feature extraction over our designed blockchain system.

A. Experiment Setup

In our experiments, we setup a small-scale Ethereum blockchain network in our laboratory which includes three Ethereum full nodes, an Ethereum bootnode and a netstats server. All these nodes are connected to a Cisco Switch Catalyst 2950 as illustrated in Fig. 4. The details of these nodes are as follows:

- Ethereum full nodes are launched by *Geth v1.10.14* [27] - open-source software for implementation of the Ethereum protocol. These nodes share the same initial configuration of genesis block, i.e., PoW consensus mechanism, 8,000,000 gas for block gas limit, initial difficulty 1,000,000. Each node is running on a personal computer with processor Intel® Core™ i7-4800MQ @2.7 GHz, RAM of 16 GB.
- Bootnode is also created by *Geth v1.10.14* and connected to all the three Ethereum nodes.
- Ethereum netstats is launched by an open-source software named "eth-netstats" on Github [28].

The normal traffic data is configured with the three trustful servers, while an attack device will execute abnormal/malicious activities to the blockchain network traffic. Each trustful server takes responsibility for generating data and sending transactions to the corresponding Ethereum node in its network as visualized in Fig. 4. In summary, in the normal state, the following tasks are scheduled or randomly occur in the network:

- The servers are scheduled to send transactions.
- The users call functions in the deployed smart contracts to explore the ledger. Besides transaction-related functions, the users also send requests to the Ethereum nodes

for tracking their balances or status of miners. Both of these works are randomly made by HTTP requests to the Ethereum node API (Application Programming Interface).
- Ethereum nodes broadcast transactions and mined blocks to synchronize their ledgers. The packets of bootnode are also included in this field.
- WebSockets and JSON-RPC are used when netstats get information from $Geth$ clients.
- HTTP requests and replies to view netstats interface and results of cyberattack detection.

B. Dataset Collection and Feature Extraction

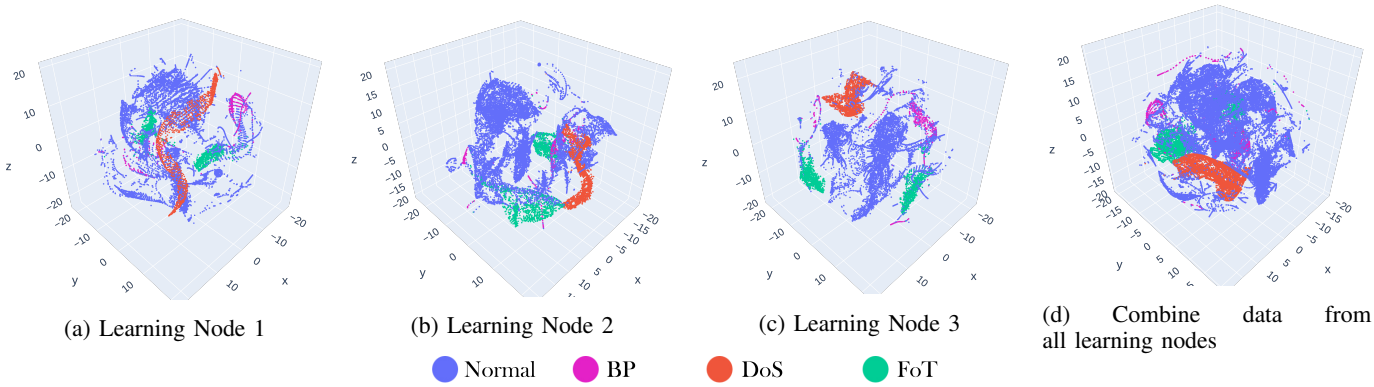
In this section, we consider network layer aspects of the permissionless blockchain [29], [30] to detect cyberattacks in blockchain network. In general, the goals of an adversary are usually the monetary benefit, e.g., chain splitting, and wallet theft, or stability of the network, e.g., delay and information loss. Hence, in our network, we perform three specific types of cyberattacks that have been reported in blockchain networks, i.e., the brute password for wallet theft, denial of service for information loss, and flooding of transactions for consensus delay. More details are as follows:

- *Brute Password (BP) attack*: is derived from traditional cyberattack when hackers perform such attacks to steal blockchain users' accounts. In this way, the hackers can access the users' wallets and steal their digital assets of the users. As mentioned in Section I, the BP attack on KuCoin caused the loss of up to $281 million [6]. To perform this attack, the attacker retries passwords of an Ethereum public key until it finds out the correct login information.
- *Denial of Service (DoS) attack*: is also another common type of attack in blockchain networks as it can be easily performed to attack blockchain nodes. For such kind of attack, the attackers will launch a huge amount of traffic to a target blockchain node in a short period of time. Consequently, the target node will not be able to work as normal, i.e., mining transactions, and even be suspended. In the real-world, Bitfinex [31] was temporarily suspended due to such kind of attack. Thus, in our setup, a simple DoS attack is simulated, i.e., an SYN flood attack, by repeatedly sending initial connection request (SYN) packets to an Ethereum node.
- *Flooding of Transactions (FoT) attack*: targets delay the PoW blockchain network by spamming the blockchain network with null or meaningless transactions. When the number of transactions per second in the Ethereum network suddenly hits the top, a mining node may face two following issues, i.e., too much traffic (similar as that of DoS), and the queue of pending transactions is full. It equates to the unnecessary time burden for mining process and block propagation [32]. In 2017, the Bitcoin mempool size was exceeded 115,000 unconfirmed transactions which led to $700 million worth of transaction stall [30]. In our work, FoT attack is implemented by continuously sending a large number of transactions to an existing smart contract.

In order to capture traffic data of these attacks, we build a dataset collection tool, named BC-IDS, which inherits the core of an open-source utility named "kdd99_feature_extractor" [33] and our new designs to fit the considered Ethereum network, i.e., correct the service of packets related to Ethereum nodes, remove meaningless features, and automate label dataset samples based on some given properties. Especially, our goal is to achieve a trained model that can be applied to our proposed real-time blockchain attack detection system, when the number of samples in a prediction frame is limited. Thus, the BC-IDS collects the dataset frames in which each frame lasts for 2 seconds and extracts their features. The BC-IDS then puts all collected data in this frame into a single file. Finally, we merge all single files together to make the full dataset. In summary, Table I shows 21 features in the designed dataset, which are separated into two types, i.e., discrete (D) and continuous (C). For continuous

TABLE I: Features of the designed dataset.

#	Features name	T	Description
Basic features			
1	*duration*	C	length of the connection (seconds)
2	*protocol_type*	D	type of the protocol (i.e., tcp, udp, icmp)
3	*service*	D	network service (e.g., http, ssh, etc)
4	*src_bytes*	C	number of data bytes from source to destination
5	*dst_bytes*	C	number of data bytes from destination to source
6	*flag*	D	normal or error status of the connection
Statistical features			
Features refer to source IP-based Statistical			
7	*count*	C	number of connections to the same source IP as the current connection
8	*srv_count*	C	number of connections to the same service as the current connection
Features refer to these same source IP connections			
9	*serror_rate*	C	% of 'SYN' errors connections
10	*same_srv_rate*	C	% of same service connections
11	*diff_srv_rate*	C	% of different services connections
Features refer to these same service connections			
12	*srv_serror_rate*	C	% of 'SYN' errors connections
13	*srv_diff_host_rate*	C	% of different host connections
Features refer to destination IP-based Statistical			
14	*dst_host_count*	C	number of connections to the same destination IP as the current connection
15	*dst_host_srv_count*	C	number of connections to the same service as the current connection
Features refer to these same destination IP connections			
16	*dst_host_same_srv_rate*	C	% of same service connections
17	*dst_host_diff_srv_rate*	C	% of different services connections
18	*dst_host_same_src_port_rate*	C	% of same both source port and destination IP connections
19	*dst_host_serror_rate*	C	% of 'SYN' errors connections
Features refer to these same service connections			
20	*dst_host_srv_diff_host_rate*	C	% of different host connections
21	*dst_host_srv_serror_rate*	C	% of 'SYN' errors connections



(a) Learning Node 1 (b) Learning Node 2 (c) Learning Node 3 (d) Combine data from all learning nodes

Fig. 5: Visualization using t-SNE for collected datasets.

TABLE II: The number of samples in the designed dataset.

Class \ Ethereum node	Node-1 (samples)	Node-2 (samples)	Node-3 (samples)
Normal	30,000	30,000	30,000
BP	3,000	3,000	3,000
DoS	3,000	3,000	3,000
FoT	3,000	3,000	3,000

features, they are calculated in 2 seconds time window (similar to that of the famous KDD99 dataset [34]).

In each Ethereum node, the separated dataset is collected in four states (classes), i.e., normal state (Class-0), BF attack (Class-1), DoS attack (Class-2), and FoT attack (Class-3). The normal state is captured in two hours, the rest of them in an hour through the designed BC-IDS tool. Note that, when a node is attacked, the normal traffic still exists. Therefore, the attack samples can be filtered out by features-based two properties, i.e., the *src_ip* and *dst_ip* of the attack device, *service*, *src_length*, and *dst_length* of the samples, which are analyzed by Wireshark [22]. To improve the diversity of the designed dataset, the normal traffic data in the attack state is mixed with traffic data in the normal state. In our experiments, a number of random samples in each state are selected to reduce the size of the bulk dataset as shown in Table II. In fact, we mix normal traffic data in an equal ratio, i.e., 7,500 samples per normal state, normal traffic data at BF, DoS, FoT, respectively.

Fig. 5 illustrates the visualization of our designed dataset using t-Distributed Stochastic Neighbor Embedding (t-SNE) [35] with three most important components. In 3D view, the DoS and FoT attack samples show a fairly clear separation from normal state points. Otherwise, the BP attack samples collide with the normal state samples. This indicates that discriminating BP samples from the normal data points would be significantly challenging.

C. Evaluation Method

The confusion matrix with accuracy, precision and recall proposed in [36], [37] is widely used to evaluate the performance of many machine learning systems. We denote TP, FP, TN, FN to be "True Positive", "False Positive", "True Negative", and "False Negative", respectively. The accuracy of total system with T classes of normal behaviors and different types of attacks as follows:

$$Accuracy = \frac{1}{T}\sum_{t=1}^{T}\frac{TP_t + TN_t}{TP_t + TN_t + FP_t + FN_t}. \quad (12)$$

In the next section, we also use the accuracy, precision, recall to evaluate and compare the performance of our proposed Collaborative Learning model (proposed CoL) with two other baseline methods, i.e., Centralized Learning model (CeL) and Independent Learning model (IL).

V. Experimental Results and Performance Evaluation

In this section, we use the collected datasets of three nodes described in aforementioned section for the corresponding LNs. The dataset of each LN is randomly split into training and testing dataset. All LNs use DBN with the same structure of neural network for learning and detecting attacks. However, the LNs have to work in different learning models in various scenarios. Each LN has itself training and testing dataset, and thus we can use these datasets to evaluate and compare the performance of the proposed CoL, the CeL and the IL in different scenarios.

A. Simulation Results

In this section, we present the simulation results with the dataset of LNs in different learning models. The details of datasets using for simulation are as follows:

- **Proposed Collaborative Learning Model (proposed CoL)**: Each LN learns its training dataset and performs collaborative learning with other LNs to generate the global model. Then, we use the global model to test the merged testing dataset of all participated LNs.
- **Centralized Learning Model (CeL)**: The centralized node (e.g., one of the mining node in the network) is assumed to be able to collect data from all the nodes in the network and train the deep learning model on

TABLE III: Simulation results.

	2 Learning Nodes (LNs)				3 Learning Nodes (LNs)				
	Proposed CoL	CeL	IL		Proposed CoL	CeL	IL		
			LN-1	LN-2			LN-1	LN-2	LN-3
Accuracy	**97.780**	97.923	96.444	96.175	**97.609**	97.507	96.034	95.788	95.225
Precision	**95.497**	95.946	92.713	93.145	**95.317**	94.894	91.630	92.514	90.583
Recall	**95.560**	95.846	92.889	92.350	**95.219**	95.014	92.068	91.575	90.450

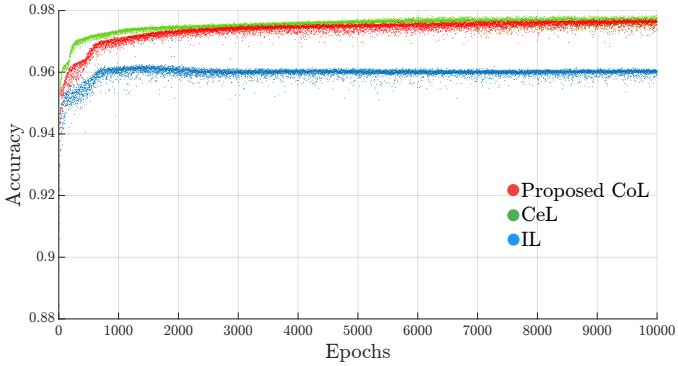


Fig. 6: Training process of considered learning models.

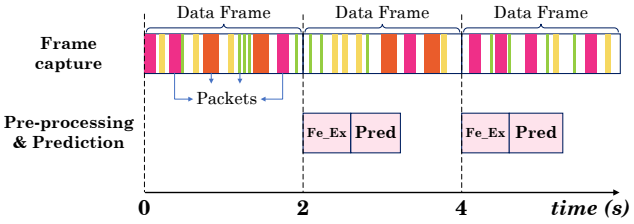


Fig. 7: Timeline of verification phase.

the collected datasets. Then, we use the trained model to test data based on the merged testing dataset of all participated LNs.

- **Independent Learning Model (IL)**: Each LN learns its training dataset without sharing knowledge with other LNs. Then, we use this model to test data based on the merged testing dataset of all participated LNs.

1) Convergence Analysis: Fig. 6 describes the convergence of the proposed CoL, the CeL and the IL (in terms of accuracy) of three LNs in the training process. The proposed CoL is obtained at the LN-1 after obtaining the global model. The CeL has a large number of training samples from three LNs so it can reach the convergence with around 97% accuracy after 300 epochs. Besides, the proposed CoL and the IL converge nearly the same after 750 epochs. After 10,000 learning epochs, we can observe that the proposed CoL has a higher accuracy compared with that of the IL (i.e., 98% vs 96%). The reason is that the proposed CoL can obtain the exchange knowledge from DL models of other LNs. Thereby, it can achieve similar performance as that of the CeL.

2) Performance Analysis: Table III presents the simulation results in two cases, i.e., two participated LNs and three participated LNs. In both cases, we can observe the same trend when the accuracy, precision and recall of the proposed CoL are higher than those of the IL and nearly equal to those of the CeL. In particular, the accuracy of the proposed CoL is higher than that obtained by LN-1 in IL (approximately 1.5%) and the precision of the proposed CoL is nearly 4% higher than that obtained by LN-1 in IL in the case of three participated LNs. These results demonstrate that the proposed CoL can exchange knowledge with other LNs to improve its ability of detection, so it can achieve better performance in classifying attacks in the blockchain network than those of the IL. It also demonstrates that the learning model of IL should not be used to classify the data of other LNs. In addition, without sharing LN's dataset to a center node for training (e.g., a cloud server), the proposed CoL can achieve nearly the same accuracy as those of the CeL in all the scenarios.

B. Experimental Results

In this section, we present the experimental results obtained through real-time experiments at our laboratory. In this experiment, each blockchain node is installed a learning model to become an LN. Each LN learns its local dataset and then performs real-time attack detection in the blockchain network. We consider the scenario of two LNs and three LNs with the proposed CoL and the CeL. In the training process, the proposed CoL and the CeL are fed with the similar datasets as explained in the previous section. We then implement the trained model to all the participated LNs to perform real-time attack detection for both learning models in the testing process.

1) Real-time capturing and processing: In a real-time system, the cyberattack detection system continuously receives a number of the Ethereum network traffic data. Therefore, the system has to perform capturing, collecting frames, extracting features, analyzing and predicting within a period of time, i.e, 2 seconds. Fig. 7 shows the timeline of the cyberattack detection program. The data frame is exploited by our feature extractor function (Fe_Ex) of BC-IDS tool, and this is input for the trained model to predict (Pred) and classify packets to be normal or attack. All processes have to complete in 2 seconds before the next data frame of IP packets coming. To verify the predicted results from the trained model, all frames and prediction results are stored. These frames are merged into a full validation dataset and labeled by own designed BC-IDS. After that, these ground truth labels are compared with the prediction results to obtain a validation report.

2) Performance Analysis: Table IV presents the experimental results of the proposed CoL and the CeL with different participated LNs. We obtain the same trends as those of the simulation results. The results obtained by two and three

TABLE IV: Real experimental results.

	2 Learning Nodes (LNs)				3 Learning Nodes (LNs)					
	Proposed CoL		CeL		Proposed CoL			CeL		
	LN-1	LN-2	LN-1	LN-2	LN-1	LN-2	LN-3	LN-1	LN-2	LN-3
Accuracy	**97.520**	**97.342**	97.164	97.186	**97.582**	**97.383**	**96.693**	96.709	96.976	96.429
Precision	**95.796**	**95.830**	95.765	95.926	**96.253**	**96.081**	**94.718**	93.985	94.662	93.172
Recall	**95.040**	**94.685**	94.328	94.373	**95.164**	**94.765**	**93.387**	93.418	93.951	92.859

learning models of both proposed CoL and CeL are slightly lower than those of the simulations at about 0.2%. This is because each type of attack has different distributions of attack samples in a period of time. Table V presents the number of samples of each class collecting in 15 minutes. In this table, we can observe that Class-1 has a very small number of samples during this period, this can lead to a low accuracy in statistics for this class and reduce the total accuracy of the model. However, our proposed CoL still has better performance than those of the the CeL and LN-1 in the three LNs case (i.e., up to 0.8% of accuracy, 2.3% precision and 1.7% recall). Overall, our proposed CoL always achieves the best performance with approximately 97.5% accuracy, 95.7% precision and 95% recall with two LNs and 97.5% accuracy, 96.2% precision and 95.1% recall with three LNs. These results demonstrate that our proposed CoL can detect attacks with higher accuracies for all participated LNs than those of CeL.

3) Real-time Monitoring and Detection: Fig. 8 illustrates the real-time monitoring of our proposed CoL for normal state and three types of attacks in the network. Fig. 8(a) is the normal state (Class-0) of the network with a high number of normal samples and a low number of attack samples. Then, the BP attack is performed, and Fig. 8(b) shows a slightly increase in the number of BP attacks. This is because, the number of BP attack samples is much smaller than other states in a period of time as in Table V. In this case, the detection mechanism is activated and alarms the network under the BP attack (Class-1). Similarly, the DDoS attack in the network is described in Fig. 8(c) with a high increase in the number of samples of DoS attack. Finally, Fig. 8(d) describes the FoT attack. Unlike other attacks, the FoT attack includes a large number samples, thus it increases both the number of normal and attack samples (above 300 traffic samples per 2 seconds) than other attacks (under 50 traffic samples per 2 seconds). Thereby, in all the cases, we can observe that our proposed intrusion detection system can detect attacks effectively in a real-time manner.

4) Real-time Processing Capacity: In this experiment, we fix the number of input samples in our proposed model to find the maximum real-time processing capacity in capturing and detecting attacks. Fig. 9 illustrates the real-time processing capacity of our proposed model. The processing time τ is counted from the time our proposed model reads the file containing the samples, until completing classification and producing the output. This work is repeated 20,000 times to determine the stability of the detection time of our proposed model. We vary the number of input samples multiple times to find the appropriate number that is adapted to the condition in Fig. 7. In most of the cases (98%), our proposed framework can classify 85,000 samples with less than 2 seconds. These results demonstrate that our proposed detection framework can be very potential to deploy to detect attacks in real-world blockchain networks.

TABLE V: The number of samples on Ethereum node 1 in an hour.

	Class-0	Class-1	Class-2	Class-3
Number of samples	242,298	828	10,858	128,509
Percentage (%)	63.347	0.216	2.839	33.598

VI. Conclusion

In this work, we have proposed a novel collaborative learning framework for a cyberattack detection system in a blockchain network. First, we have implemented a private blockchain network in our laboratory. This blockchain network is used to (1) generate data (both normal and attack data) to serve the proposed learning models and (2) validate the performance of our proposed learning framework in real-time experiments. After that, we have proposed a highly-effective learning model that allows to be effectively deployed in the blockchain network. This learning model allows nodes in the blockchain can be actively involved in the detection process by collecting data, learning knowledge from their data, and then exchanging knowledge together to improve the attack detection ability. In this way, we can not only avoid problems of conventional centralized learning (e.g., congestion and single point of failure) but also protect the blockchain network right at the edge. Both simulation and real-time experimental results then have clearly shown the efficiency of our proposed framework. In future, we plan to continue developing this dataset with other emerging types of attacks and develop more effective methods to to protect blockchain networks.

VII. Acknowledgement

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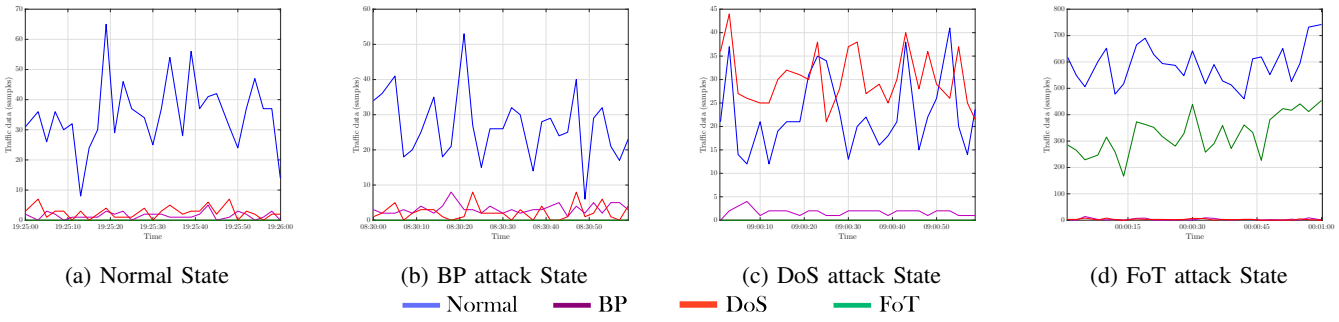

(a) Normal State (b) BP attack State (c) DoS attack State (d) FoT attack State

Fig. 8: Real-time blockchain cyberattack detection: proposed CoL model of 3 LNs in Ethereum node 1.

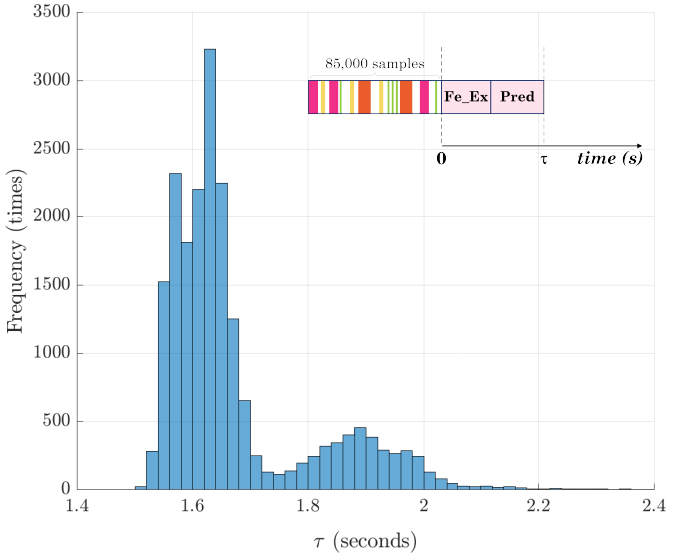

Fig. 9: Histogram of real-time detection duration for 85,000 samples.

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