# Combination's Id TTC Camera

TTC	Lidar
	Lidar

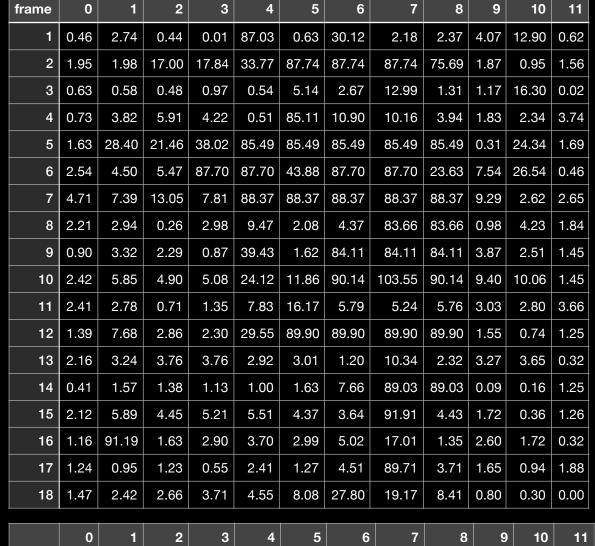
id	Detector	Descriptor	Matcher
0	AKAZE	AKAZE	FLANN
1	BRISK	BRIEF	FLANN
2	BRISK	BRISK	BF
3	BRISK	BRISK	FLANN
4	FAST	BRISK	BF
5	FAST	FREAK	BF
6	ORB	ORB	BF
7	ORB	ORB	FLANN
8	ORB	FREAK	FLANN
9	SHITOMASI	BRIEF	BF
10	SHITOMASI	BRISK	BF
11	SIFT	SIFT	FLANN

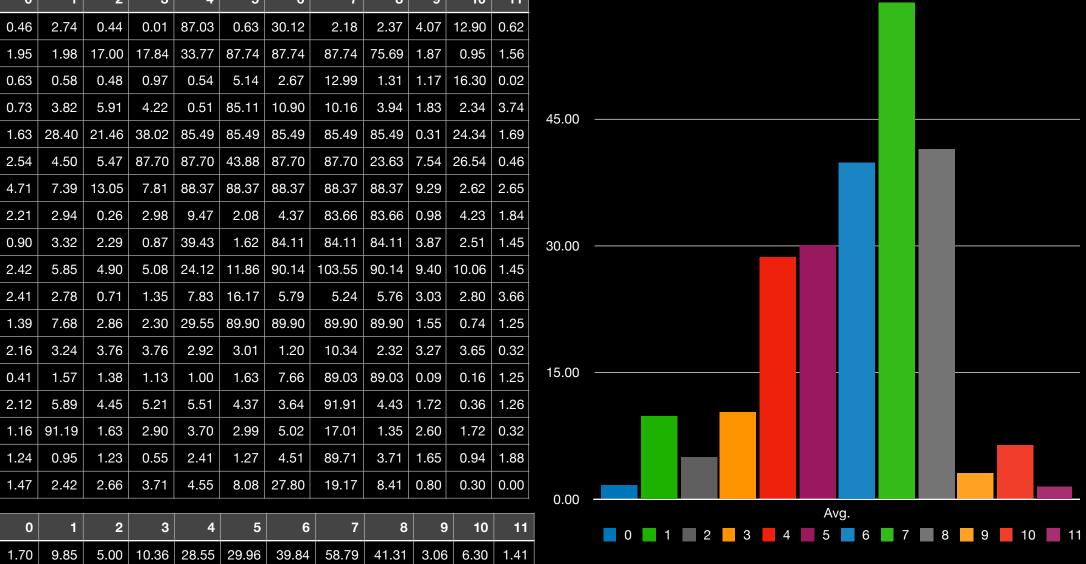
frame	0	1	2	3	4	5	6	7	8	9	10	11		Lidar
1	12.51	15.71	13.41	12.98	100	13.61	43.09	15.15	10.61	17.04	0.07	12.36	1	12.97
2	14.21	14.25	29.26	30.10	46.03	100	100	100	-63.43	14.14	13.21	13.82	2	12.26
3	13.29	13.34	14.40	14.89	14.46	19.06	16.58	26.90	12.61	15.09	30.21	13.93	3	13.92
4	15.62	18.71	20.79	19.10	15.40	100	25.78	25.04	10.94	13.05	12.54	18.62	4	14.89
5	16.14	42.90	35.97	52.53	100	100	100	100	100	14.81	38.84	16.19	5	14.51
6	14.84	16.80	17.77	100	100	56.18	100	100	35.93	19.84	38.84	12.76	6	12.30
7	16.34	19.02	24.69	19.44	100	100	100	100	100	20.92	14.26	14.28	7	11.63
8	14.13	19.28	16.60	19.32	25.81	14.26	11.97	100	100	15.36	20.57	14.50	8	16.34
9	14.99	19.21	13.60	15.02	55.32	17.51	100	100	100	12.02	13.38	14.44	9	15.89
10	12.28	15.71	14.76	14.94	33.98	21.72	100	113.41	100	19.26	19.92	11.31	10	9.86
11	12.58	12.21	14.27	13.64	22.82	31.16	9.20	9.74	9.23	11.96	12.19	11.33	11	14.99
12	11.49	17.78	12.96	12.40	39.65	100	100	100	100	11.65	10.84	11.35	12	10.10
13	11.38	12.46	12.98	12.99	12.14	12.23	10.42	19.56	6.90	12.49	12.87	8.90	13	9.22
14	10.55	12.53	12.35	12.10	11.97	12.60	18.63	100	100	11.06	10.81	9.72	14	10.97
15	10.21	13.98	12.54	13.30	13.61	12.46	11.74	100	12.52	9.81	7.73	9.36	15	8.09
16	9.97	100	10.44	11.71	12.51	11.80	13.83	25.82	7.47	11.41	10.54	9.13	16	8.81
17	9.05	9.34	9.06	9.74	12.70	11.56	14.80	100	14.01	11.94	11.23	8.41	17	10.29
18	9.78	10.73	10.97	12.02	12.86	0.23	36.11	27.48	-0.10	7.51	8.01	8.31	18	8.31

60.00

### TTC Difference between Lidar and Camera

# TTC Difference between LiDAR and Camera (The lower, the better)





## Top 3 Combinations

Avg.

Rank	id	Detector	Descriptor	Matcher		
1	11	SIFT	SIFT	FLANN		
2	0	AKAZE	AKAZE	FLANN		
3	9	SHITOMASI	BRIEF	BF		