Combination's Id TTC Camera

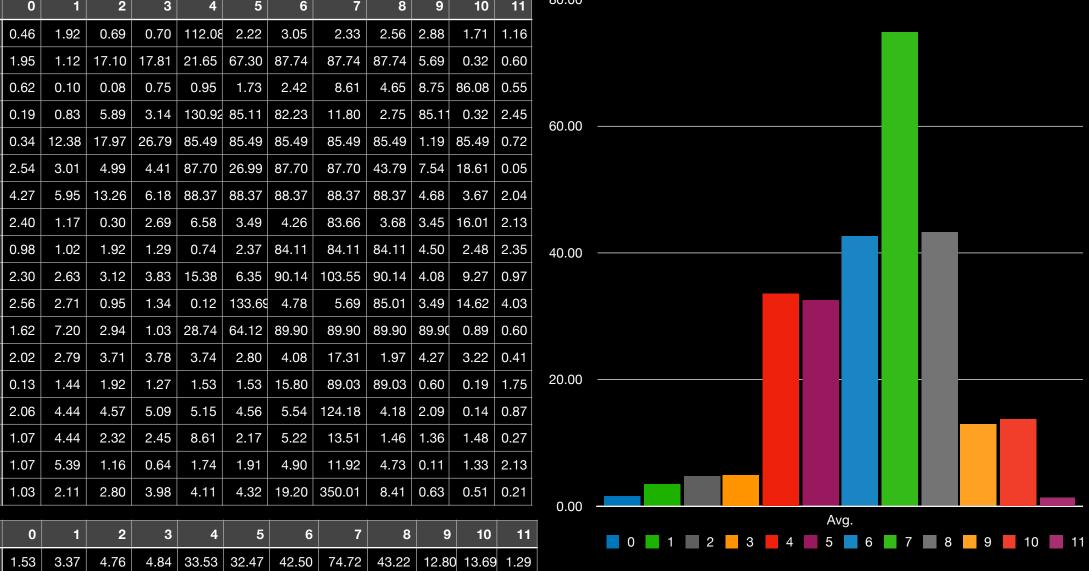
id	Detector	Descriptor	Matcher
0	AKAZE	AKAZE	FLANN
1	BRISK	BRIEF	FLANN
2	BRISK	BRISK	BF
3	BRISK	BRISK	FLANN
4	FAST	BRISK	BF
5	FAST	FREAK	BF
6	ORB	ORB	BF
7	ORB	ORB	FLANN
8	ORB	FREAK	FLANN
9	SHITOMASI	BRIEF	BF
10	SHITOMASI	BRISK	BF
11	SIFT	SIFT	FLANN

	TTC Camera									T	TC L	LiDAR			
frame	0	1	2	3	4	5	6	7	8	9	10	11	fr	ame	Lidar
1	12.51	14.89	13.66	13.68	125.05	15.20	16.02	15.30	10.42	15.86	14.69	11.81		1	12.97
2	14.21	13.39	29.37	30.07	33.91	79.566	100	100	100	17.95	12.58	12.87		2	12.26
3	13.30	13.82	14.00	14.66	14.87	15.64	11.49	22.52	18.57	22.66	100	13.37		3	13.92
4	15.08	14.06	20.78	18.03	145.81	100	97.11	26.68	12.14	100	15.20	17.33		4	14.89
5	14.85	26.88	32.47	41.29	100	100	100	100	100	15.70	100	13.78		5	14.51
6	14.84	15.31	17.29	16.709	100	39.29	100	100	56.09	19.84	30.91	12.25		6	12.30
7	15.90	17.58	24.90	17.81	100	100	100	100	100	16.31	15.30	13.68		7	11.63
8	13.94	17.51	16.64	19.03	22.92	12.85	12.08	100	12.6538	12.89	0.33	14.20		8	16.34
9	14.91	16.91	13.97	14.60	15.15	13.52	100	100	100	11.39	13.41	13.54		9	15.89
10	12.16	12.48	12.97	13.68	25.24	16.21	100	113.41	100	13.94	19.13	10.83		10	9.86
11	12.43	12.27	14.04	13.64	15.11	148.68	10.21	9.30	100	11.50	0.37	10.96		11	14.99
12	11.72	17.30	13.04	11.13	38.84	74.215	100	100	100	100	10.99	10.70		12	10.10
13	11.24	12.02	12.93	13.01	12.96	12.02	13.30	26.54	7.25	13.50	12.44	8.81		13	9.22
14	10.83	12.41	12.88	12.24	12.50	12.50	26.77	100	100	11.57	10.78	9.22		14	10.97
15	10.15	12.53	12.66	13.18	13.25	12.65	13.64	132.279	12.27	10.19	7.95	8.97		15	8.09
16	9.88	13.252	11.13	11.27	0.20	10.98	14.03	22.33	7.35	10.18	10.29	8.54		16	8.81
17	9.23	4.90	9.13	9.65	12.03	12.21	15.19	22.211	15.03	10.18	11.62	8.16		17	10.29
18	9.34	10.42	11.11	12.29	12.42	12.63	27.51	358.32	-0.10	7.68	7.80	8.10		18	8.31

TTC Difference between LiDAR and Camera

frame	0	1	2	3	4	5	6	7	8	9	10	11
1	0.46	1.92	0.69	0.70	112.08	2.22	3.05	2.33	2.56	2.88	1.71	1.16
2	1.95	1.12	17.10	17.81	21.65	67.30	87.74	87.74	87.74	5.69	0.32	0.60
3	0.62	0.10	0.08	0.75	0.95	1.73	2.42	8.61	4.65	8.75	86.08	0.55
4	0.19	0.83	5.89	3.14	130.92	85.11	82.23	11.80	2.75	85.11	0.32	2.45
5	0.34	12.38	17.97	26.79	85.49	85.49	85.49	85.49	85.49	1.19	85.49	0.72
6	2.54	3.01	4.99	4.41	87.70	26.99	87.70	87.70	43.79	7.54	18.61	0.05
7	4.27	5.95	13.26	6.18	88.37	88.37	88.37	88.37	88.37	4.68	3.67	2.04
8	2.40	1.17	0.30	2.69	6.58	3.49	4.26	83.66	3.68	3.45	16.01	2.13
9	0.98	1.02	1.92	1.29	0.74	2.37	84.11	84.11	84.11	4.50	2.48	2.35
10	2.30	2.63	3.12	3.83	15.38	6.35	90.14	103.55	90.14	4.08	9.27	0.97
11	2.56	2.71	0.95	1.34	0.12	133.69	4.78	5.69	85.01	3.49	14.62	4.03
12	1.62	7.20	2.94	1.03	28.74	64.12	89.90	89.90	89.90	89.90	0.89	0.60
13	2.02	2.79	3.71	3.78	3.74	2.80	4.08	17.31	1.97	4.27	3.22	0.41
14	0.13	1.44	1.92	1.27	1.53	1.53	15.80	89.03	89.03	0.60	0.19	1.75
15	2.06	4.44	4.57	5.09	5.15	4.56	5.54	124.18	4.18	2.09	0.14	0.87
16	1.07	4.44	2.32	2.45	8.61	2.17	5.22	13.51	1.46	1.36	1.48	0.27
17	1.07	5.39	1.16	0.64	1.74	1.91	4.90	11.92	4.73	0.11	1.33	2.13
18	1.03	2.11	2.80	3.98	4.11	4.32	19.20	350.01	8.41	0.63	0.51	0.21
												11
	0	1	2	3	4	5	6	7	8	9	10	

TTC Difference between LiDAR and Camera (The lower, the better)



Top 3 Combinations

Avg.

Rank	id	Detector	Descriptor	Matcher
1	11	SIFT	SIFT	FLANN
2	0	AKAZE	AKAZE	FLANN
3	1	BRISK	BRIEF	FLANN