Pset4 - answer key

September 2023

1 Basic matrix arithmetic

If

$$\mathbf{a} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

find:[1]

a. $\mathbf{a} + \mathbf{b}$

$$\text{a + b} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2+1 \\ 2+3 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

a. $-4\mathbf{b}$

$$-4\mathbf{b} = -4 \times \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -4 \\ -12 \end{bmatrix}$$

a. $3\mathbf{a} - 4\mathbf{b}$

$$3\mathbf{a} - 4\mathbf{b} = 3 \times \begin{bmatrix} 2 \\ 2 \end{bmatrix} - 4 \times \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 6 \end{bmatrix} - \begin{bmatrix} 4 \\ 12 \end{bmatrix} = \begin{bmatrix} 6-4 \\ 6-12 \end{bmatrix} = \begin{bmatrix} 2 \\ -6 \end{bmatrix}$$

2 More complex matrix arithmetic

Suppose

$$\mathbf{x} = \begin{bmatrix} 3 \\ 2q \\ 6 \end{bmatrix} \quad \text{and} \quad \mathbf{y} = \begin{bmatrix} p+2 \\ -5 \\ 3r \end{bmatrix}$$

[1] Pemberton and Rau 11.1.2

If $\mathbf{x} = 2\mathbf{y}$, find p, q, r.[2]

Solution: We can calculate each element of the vector independently, given our knowledge of the relationship between $\mathbf{x}$ and $\mathbf{y}$.

$$
\begin{aligned}
3 &= 2(p+2) \\
3 &= 2p+4 \\
-1 &= 2p \\
-\frac{1}{2} &= p
\end{aligned}
$$

$$
\begin{aligned}
2q &= 2(-5) \\
2q &= -10 \\
q &= -5
\end{aligned}
$$

$$
\begin{aligned}
6 &= 2(3r) \\
6 &= 6r \\
1 &= r
\end{aligned}
$$

So $p = -\frac{1}{2}, q = -5, r = 1$.

3 Check for linear dependence

Which of the following sets of vectors are linearly dependent? [3]

In each part, you can denote each vector as $\mathbf{a}, \mathbf{b}, \mathbf{c}$ respectively.

a. $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Yes: $\mathbf{a} + \mathbf{b} - \mathbf{c} = \mathbf{0}$

a. $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix}$

Yes: $\mathbf{a} - 2\mathbf{b} + \mathbf{c} = \mathbf{0}$

a. $\begin{bmatrix} 13 \\ 7 \\ 9 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \\ 5 \\ 8 \end{bmatrix}$

Yes: $0\mathbf{a} + 1\mathbf{b} + 0\mathbf{c} = \mathbf{0}$

a. $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$

Linearly independent.

4 Vector length

Find the length of the following vectors:$^{[}SimonandBlume10.10]$

[2] Pemberton and Rau 11.1.3

[3] Pemberton and Rau 11.1.4

a. $(3, 4)$

$$\begin{aligned}\sqrt{3^2+4^2} &= \sqrt{9+16}\\ &= \sqrt{25}\\ &= 5\end{aligned}$$

a. $(0, -3)$

$$\begin{aligned}\sqrt{0^2+(-3)^2} &= \sqrt{0+9}\\ &= \sqrt{9}\\ &= 3\end{aligned}$$

a. $(1, 1, 1)$

$$\begin{aligned}\sqrt{1^2+1^2+1^2} &= \sqrt{1+1+1}\\ &= \sqrt{3}\end{aligned}$$

a. $(1, 2, 3)$

$$\begin{aligned}\sqrt{1^2+2^2+3^2} &= \sqrt{1+4+9}\\ &= \sqrt{14}\end{aligned}$$

a. $(1, 2, 3, 4)$

$$\begin{aligned}\sqrt{1^2+2^2+3^2+4^2} &= \sqrt{1+4+9+16}\\ &= \sqrt{30}\\ &\approx 5.47726\end{aligned}$$

a. $(3, 0, 0, 0, 0)$

$$\begin{aligned}\sqrt{3^2+0^2+0^2+0^2+0^2} &= \sqrt{9+0+0+0+0}\\ &= \sqrt{3}\\ &= 3\end{aligned}$$

5 Law of cosines

The *law of cosines* states:

$\cos(\theta) = \frac{\mathbf{v}\cdot\mathbf{w}}{\|\mathbf{v}\|\,\|\mathbf{w}\|}$

where θ is the angle from $\mathbf{w}$ to $\mathbf{v}$ measured in radians. Of importance, arccos() is the inverse of cos():

$\theta = \arccos\left(\frac{\mathbf{v}\cdot\mathbf{w}}{\|\mathbf{v}\|\,\|\mathbf{w}\|}\right)$

For each of the following pairs of vectors, calculate the angle between them. Report your answers in both radians and degrees. To convert between radians and degrees: [4]

[4] Simon and Blume 10.12

$$\text{Degrees} = \text{Radians} \times \frac{180^o}{\pi}$$

a. $\mathbf{v} = (1, 0), \quad \mathbf{w} = (2, 2)$

$$\begin{aligned}
\mathbf{v} \cdot \mathbf{w} &= (1)(2) + (0)(2) \\
&= 2 + 0 \\
&= 2 \\
\|\mathbf{v}\| &= \sqrt{1^2 + 0^2} \\
&= \sqrt{1 + 0} \\
&= \sqrt{1} \\
&= 1 \\
\|\mathbf{w}\| &= \sqrt{2^2 + 2^2} \\
&= \sqrt{4 + 4} \\
&= \sqrt{8} \\
&= \sqrt{2^2 \times 2} \\
&= 2\sqrt{2} \\
\theta &= \arccos\left(\frac{2}{1(2\sqrt{2})}\right) \\
&= \frac{\pi}{4} \\
&= 45^\circ
\end{aligned}$$

a. $\mathbf{v} = (4, 1), \quad \mathbf{w} = (2, -8)$

$$
\begin{aligned}
\mathbf{v}\cdot\mathbf{w} &= (4)(2) + (1)(-8) \\
&= 8 + (-8) \\
&= 0 \\
\|\mathbf{v}\| &= \sqrt{4^2 + 1^2} \\
&= \sqrt{16 + 1} \\
&= \sqrt{17} \\
&= 1 \\
\|\mathbf{w}\| &= \sqrt{2^2 + (-8)^2} \\
&= \sqrt{4 + 64} \\
&= \sqrt{68} \\
&= \sqrt{2^2 \times 17} \\
&= 2\sqrt{17} \\
\theta &= \arccos\left(\frac{0}{1(2\sqrt{17})}\right) \\
&= \frac{\pi}{2} \\
&= 90^\circ
\end{aligned}
$$

Note: you could stop after solving $\mathbf{v}\cdot\mathbf{w}$, because the denominator will be irrelevant.

a. $\mathbf{v} = (1, 1, 0), \quad \mathbf{w} = (1, 2, 1)$

$$
\begin{aligned}
\mathbf{v} \cdot \mathbf{w} &= (1)(1) + (1)(2) + (0)(1) \\
&= 1 + 2 + 0 \\
&= 3 \\
\|\mathbf{v}\| &= \sqrt{1^2 + 1^2 + 0^2} \\
&= \sqrt{1 + 1 + 0} \\
&= \sqrt{2} \\
\|\mathbf{w}\| &= \sqrt{1^2 + 2^2 + 1^2} \\
&= \sqrt{1 + 4 + 1} \\
&= \sqrt{6} \\
\theta &= \arccos\left(\frac{3}{\sqrt{2}(\sqrt{6})}\right) \\
&= \arccos\left(\frac{3}{\sqrt{2 \times 6}}\right) \\
&= \arccos\left(\frac{3}{\sqrt{12}}\right) \\
&= \arccos\left(\frac{3}{\sqrt{2^2 \times 3}}\right) \\
&= \arccos\left(\frac{3}{2\sqrt{3}}\right) \\
&= \arccos\left(\frac{3\sqrt{3}}{2\sqrt{3}\sqrt{3}}\right) \\
&= \arccos\left(\frac{3\sqrt{3}}{2 \times 3}\right) \\
&= \arccos\left(\frac{\sqrt{3}}{2}\right) \\
&= \frac{\pi}{6} \\
&= 30^\circ
\end{aligned}
$$

6 Matrix algebra

Using the matrices below, calculate the following. Some may not be defined; if that is the case, say so.[5]

[5] Grimmer HW5.3

$$\mathbf{A} = \begin{bmatrix} 3 \\ -2 \\ 9 \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} 8 \\ 0 \\ -1 \end{bmatrix} \quad \mathbf{C} = \begin{bmatrix} 7 & -1 & 5 \\ 0 & 2 & -4 \end{bmatrix} \quad \mathbf{D} = \begin{bmatrix} 3 & 1 \\ 3 & 4 \\ 3 & -7 \end{bmatrix} \quad \mathbf{E} = \begin{bmatrix} 5 & 2 & 3 \\ 1 & 0 & -4 \\ -2 & 1 & -6 \end{bmatrix}$$

$$\mathbf{F} = \begin{bmatrix} 4 & 1 & -5 \\ 0 & 7 & 7 \\ 2 & -3 & 0 \end{bmatrix} \quad \mathbf{G} = \begin{bmatrix} 2 & -8 & -5 \\ -3 & 7 & -4 \\ 1 & 0 & 3 \\ 1 & 2 & 6 \end{bmatrix} \quad \mathbf{K} = \begin{bmatrix} 9 \\ -2 \\ -1 \\ 0 \end{bmatrix}$$

$$\mathbf{L} = \begin{bmatrix} 5 & 0 & 3 & 1 \end{bmatrix} \quad \mathbf{M} = \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix}$$

a. $\mathbf{A} + \mathbf{B}$

$$\mathbf{A} + \mathbf{B} = \begin{bmatrix} 3+8 \\ -2+0 \\ 9+(-1) \end{bmatrix} = \begin{bmatrix} 11 \\ -2 \\ 8 \end{bmatrix}$$

a. $-\mathbf{G}$

$$-\mathbf{G} = (-1)\begin{bmatrix} 2 & -8 & -5 \\ -3 & 7 & -4 \\ 1 & 0 & 3 \\ 1 & 2 & 6 \end{bmatrix} = \begin{bmatrix} -2 & 8 & 5 \\ 3 & -7 & 4 \\ -1 & 0 & -3 \\ -1 & -2 & -6 \end{bmatrix}$$

a. $\mathbf{D}'$

$$\mathbf{D}' = \begin{bmatrix} 3 & 3 & 3 \\ 1 & 4 & -7 \end{bmatrix}$$

a. $\mathbf{C} + \mathbf{D}$

$\mathbf{C} + \mathbf{D}$ does not exist. The matricies are not the same dimensions.

a. $\mathbf{A}'\mathbf{B}$

This is a 1×3 matrix multiplied by a 3×1 matrix, resulting in a 1×1 matrix (aka a *dot product*).

$\mathbf{A}'\mathbf{B} = 3(8) + (-2)(0) + 9(-1) = 24 + 0 - 9 = 15$

a. $\mathbf{BC}$

$\mathbf{BC}$ does not exist. The matricies are non-conformable.

a. $\mathbf{FB}$

$$
\begin{aligned}
\mathbf{FB} &= \begin{bmatrix} 4 & 1 & -5 \\ 0 & 7 & 7 \\ 2 & -3 & 0 \end{bmatrix} \begin{bmatrix} 8 \\ 0 \\ -1 \end{bmatrix} \\
&= \begin{bmatrix} 4(8) & + & 1(0) & + & (-5)(-1) \\ 0(8) & + & 7(0) & + & 7(-1) \\ 2(8) & + & (-3)(0) & + & 0(-1) \end{bmatrix} \\
&= \begin{bmatrix} 32+0+5 \\ 0+0-7 \\ 16+0+0 \end{bmatrix} \\
&= \begin{bmatrix} 37 \\ -7 \\ 16 \end{bmatrix}
\end{aligned}
$$

a. $\mathbf{E} - 5\mathbf{I_3}$

$$
\begin{aligned}
\mathbf{E} - 5\mathbf{I}_3 &= \begin{bmatrix} 5 & 2 & 3 \\ 1 & 0 & -4 \\ -2 & 1 & -6 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\
&= \begin{bmatrix} 5 & 2 & 3 \\ 1 & 0 & -4 \\ -2 & 1 & -6 \end{bmatrix} - \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix} \\
&= \begin{bmatrix} 0 & 2 & 3 \\ 1 & -5 & -4 \\ -2 & 1 & -11 \end{bmatrix}
\end{aligned}
$$

a. $\mathbf{M}^2$

Recall that $\mathbf{M}^2 = \mathbf{MM}$, so we must pre-multiply the matrix by itself.

$$
\begin{aligned}
\mathbf{M}^2 &= \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix} \\
&= \begin{bmatrix} 1 \times 1 + -1 \times 1 & 1 \times -1 + -1 \times 3 \\ 1 \times 1 + 3 \times 1 & 1 \times -1 + 3 \times 3 \end{bmatrix} \\
&= \begin{bmatrix} 1 + (-1) & -1 + (-3) \\ 1 + 3 & -1 + 9 \end{bmatrix} \\
&= \begin{bmatrix} 0 & -4 \\ 4 & 8 \end{bmatrix}
\end{aligned}
$$

7 Matrix inversion

Invert each of the following matricies by hand (you can use a calculator or computer to check your solution, but be sure to show your work). Verify you have the correct inverse by calculating $\mathbf{XX}^{-1} = \mathbf{I}$. Not all of the matrices may be invertible - if not, show why.[6]

[6] Simon and Blume 8.19

a. $\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$

Solution: Recall the rule for inverting 2×2 matrices:

$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix}$$

$$\begin{aligned} \mathbf{X}^{-1} &= |\mathbf{X}|^{-1} \begin{bmatrix} x_{22} & -x_{12} \\ -x_{21} & x_{11} \end{bmatrix} \\ &= \frac{1}{|\mathbf{X}|} \begin{bmatrix} x_{22} & -x_{12} \\ -x_{21} & x_{11} \end{bmatrix} \end{aligned}$$

Given this rule, first calculate the determinant of the matrix.

$$\begin{aligned} |\mathbf{X}| &= (2 \times 1) - (1 \times 1) \\ &= 2 - 1 \\ &= 1 \end{aligned}$$

Now we can easily solve for the inverse:

$$\begin{aligned} \mathbf{X}^{-1} &= \frac{1}{1} \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} \end{aligned}$$

a. $\begin{bmatrix} 2 & 1 \\ -4 & -2 \end{bmatrix}$

Solution: Solve for the determinant

$$\begin{aligned} |\mathbf{X}| &= (2 \times -2) - (1 \times -4) \\ &= -4 - (-4) \\ &= 0 \end{aligned}$$

At this point we are done. The matrix has a determinant of zero, making it singular. Singular matrices cannot be inverted.

a. $\begin{bmatrix} 2 & 4 & 0 \\ 4 & 6 & 3 \\ -6 & -10 & 0 \end{bmatrix}$

Solution: With a 3×3 matrix, we need to apply Gauss-Jordan elimination to obtain the inverse.

1. Setup the augmented matrix with the identity matrix

$$\left[\begin{array}{rrr|rrr} 2 & 4 & 0 & 1 & 0 & 0 \\ 4 & 6 & 3 & 0 & 1 & 0 \\ -6 & -10 & 0 & 0 & 0 & 1 \end{array}\right]$$

1. Swap row 1 with row 3

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 4 & 6 & 3 & 0 & 1 & 0 \\ 2 & 4 & 0 & 1 & 0 & 0 \end{array}\right]$$

1. Add $\frac{2}{3}\times$ row 1 to row 2

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 0 & -2/3 & 3 & 0 & 1 & 2/3 \\ 2 & 4 & 0 & 1 & 0 & 0 \end{array}\right]$$

1. Add $\frac{1}{3}\times$ row 1 to row 3

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 0 & -2/3 & 3 & 0 & 1 & 2/3 \\ 0 & 2/3 & 0 & 1 & 0 & 1/3 \end{array}\right]$$

1. Add row 2 to row 3

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 0 & -2/3 & 3 & 0 & 1 & 2/3 \\ 0 & 0 & 3 & 1 & 1 & 1 \end{array}\right]$$

1. Divide row 3 by 3

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 0 & -2/3 & 3 & 0 & 1 & 2/3 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \end{array}\right]$$

1. Subtract $3\times$ row 3 from row 2

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 0 & -2/3 & 0 & -1 & 0 & -1/3 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \end{array}\right]$$

1. Multiply row 2 by $-\frac{3}{2}$

$$\left[\begin{array}{rrr|rrr} -6 & -10 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 3/2 & 0 & 1/2 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \end{array}\right]$$

1. Add $10\times$ row 2 to row 1

$$\left[\begin{array}{rrr|rrr} -6 & 0 & 0 & 15 & 0 & 6 \\ 0 & 1 & 0 & 3/2 & 0 & 1/2 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \end{array}\right]$$

1. Divide row 1 by -6

$$\left[\begin{array}{rrr|rrr} 1 & 0 & 0 & -5/2 & 0 & -1 \\ 0 & 1 & 0 & 3/2 & 0 & 1/2 \\ 0 & 0 & 1 & 1/3 & 1/3 & 1/3 \end{array}\right]$$

1. The inverse of the original matrix is the right part of the augmented matrix.

$$\begin{bmatrix} 2 & 4 & 0 \\ 4 & 6 & 3 \\ -6 & -10 & 0 \end{bmatrix}^{-1} = \begin{bmatrix} -5/2 & 0 & -1 \\ 3/2 & 0 & 1/2 \\ 1/3 & 1/3 & 1/3 \end{bmatrix}$$

1. Factor out common terms

$$\begin{bmatrix} 2 & 4 & 0 \\ 4 & 6 & 3 \\ -6 & -10 & 0 \end{bmatrix}^{-1} = \frac{1}{6}\begin{bmatrix} -15 & 0 & -6 \\ 9 & 0 & 3 \\ 2 & 2 & 2 \end{bmatrix}$$

8 Dummy encoding for categorical variables

Ordinary least squares regression is a common method for obtaining regression parameters relating a set of explanatory variables with a continuous outcome of interest. The vector $\hat{\mathbf{b}}$ that contains the intercept and the regression slope is calculated by the equation:

$$\hat{\mathbf{b}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$$

If an explanatory variable is nominal (i.e. ordering does not matter) with more than two classes (e.g. $\{\text{White}, \text{Black}, \text{Asian}, \text{Mixed}, \text{Other}\}$), the variable must be modified to include in the regression model. A common technique known as **dummy encoding** converts the column into a series of $n-1$ binary (0/1) columns where each column represents a single class and n is the total number of unique classes in the original column. Explain why this method converts the column into $n-1$ columns, rather than n columns, in terms of linear algebra.

Reminder: $\mathbf{X}$ contains both the dummy encoded columns as well as a column of 1s representing the intercept.[7]

Solution: In order to calculate $\hat{\mathbf{b}}$, we must be able to calculate $(\mathbf{X}'\mathbf{X})^{-1}$. And we can only invert $\mathbf{X}'\mathbf{X}$ if the matrix is **nonsingular**. What could make a matrix singular? If at least one column is **linearly dependent** (i.e. its value can be produced by linear combinations of other columns in the matrix), then the matrix will not be **full rank**. A square matrix that is not full rank will produce a determinant of 0, which as you'll recall in the case of a 2×2 matrix would require division by zero.

$$\mathbf{X}^{-1} = \frac{1}{0}\begin{bmatrix} x_{22} & -x_{12} \\ -x_{21} & x_{11} \end{bmatrix}$$

So $\mathbf{X}'\mathbf{X}$ must be full rank in order to invert it. How does this effect our one-hot encoding scheme? If we were to convert the explanatory variable into n binary variables, the matrix X is nonsingular. That is, any of the columns in $\mathbf{X}$ can be represented as a linear combination of the other columns.

This leads to the problem of what happens when we calculate $\mathbf{X}'\mathbf{X}$. Suppose

[7] My own creation

$$\mathbf{X} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

It's transpose is

$$\mathbf{X}' = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

So

$$\mathbf{X}'\mathbf{X} = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

The problem is that $\mathbf{X}'\mathbf{X}$ is still non-invertible. The determinant of $\mathbf{X}'\mathbf{X}$ is 0. Notice that the first column $\mathbf{x_1}$ is a linear combination of $\mathbf{x_2} + \mathbf{x_3}$. In fact, $\mathbf{X}$ being invertible is a necessary condition for $\mathbf{X}'\mathbf{X}$ being invertible.

9 Solve the system of equations

Solve the following systems of equations for x, y, z, either via matrix inversion or substitution:[8]

a. System 1

$$\begin{aligned} x + y + 2z &= 2 \\ 3x - 2y + z &= 1 \\ y - z &= 3 \end{aligned}$$

Using matrix inversion

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 2 \\ 3 & -2 & 2 \\ 0 & 1 & -1 \end{bmatrix} \quad \mathbf{y} = [2, 1, 3]' \quad \mathbf{x} = [x, y, z]$$

$\mathbf{Ax} = \mathbf{y}$

$\mathbf{A^{-1}y} = \mathbf{x}$

You can use (a lot) of Gauss-Jordan elimination to invert the matrix. Or I can just use R.

```
##      [,1] [,2] [,3]
## [1,]  0.1  0.3  0.5
## [2,]  0.3 -0.1  0.5
## [3,]  0.3 -0.1 -0.5
## [1]  2  2 -1
```

[8] Gill 4.19

Using substitution

Step 1. 1 x third row added to second row and 2 x third row added to first row.

$$x + 3y = 8$$
$$3x - y = 4$$
$$y - z = 3$$

Step 2. -3 x first row added to second row

$$x + 3y = 8$$
$$-10y = -20$$
$$y - z = 3$$

Step 3. Solve for y and z

$$-10y = -20 \rightarrow y = 2$$
$$y - z = 3 \rightarrow z = -1$$

Step 4. Substitute y into the first equation
$x + 3(2) = 8 \rightarrow x = 2$
$x = 2, y = 2, z = -1$
b. System 2

$$x - y + 2z = 2$$
$$4x + y - 2z = 10$$
$$x + 3y + z = 0$$

Using matrix inversion

```
##        [,1]    [,2]     [,3]
## [1,]  0.200  0.2000 1.39e-17
## [2,] -0.171 -0.0286 2.86e-01
## [3,]  0.314 -0.1143 1.43e-01
## [1]  2.400 -0.629 -0.514
```

Using substitution

Step 1. Add row 1 to row 2

$$x - y + 2z = 2$$
$$5x = 12$$
$$x + 3y + z = 0$$

Step 2. Solve for x
$5x = 12 \to x = \frac{12}{5}$
Step 3. Plug in $x = 2$ and add row 1 x 3 to row 3

$$\frac{12}{5} - y + 2z = 2$$
$$4\left(\frac{12}{5}\right) + 7z = 6$$

Step 4. Solve for z
$4\left(\frac{12}{5}\right) + 7z = 6 \to z = -\frac{18}{35}$
Step 5. Solve for y
$\frac{12}{5} - y + 2\left(-\frac{18}{35}\right) = 2 \to y = -\frac{22}{35}$
$x = \frac{12}{5}, y = -\frac{22}{35}, z = -\frac{18}{35}$

10 Multiplying by 0

When it comes to real numbers, we know that if $xy = 0$, then either $x = 0$ or $y = 0$ or both. One might believe that a similar idea applies to matrices, but one would be wrong. Prove that if the matrix product $\mathbf{AB} = \mathbf{0}$ (by which we mean a matrix of appropriate dimensionality made up entirely of zeroes), then it is not necessarily true that either $\mathbf{A} = \mathbf{0}$ or $\mathbf{B} = \mathbf{0}$. Hint: in order to prove that something is not always true, simply identify one example where $\mathbf{AB} = \mathbf{0}$, $\mathbf{A}, \mathbf{B} \neq \mathbf{0}$.[9]

Solution: Generally speaking, it is easy to show that something is *not* necessarily true. All that is needed is a single counterexample! And in this case, there are infinitely many counterexamples. Here's one:

$$\mathbf{A} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \qquad \mathbf{B} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\mathbf{AB} = \begin{bmatrix} 1(1) + 1(-1) & 1(1) + 1(-1) \\ 1(-1) + 1(1) & 1(-1) + 1(1) \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

[9]Grimmer HW5.5