```
Help
#include<stdlib.h>
#include<math.h>
#include"pnl/pnl random.h"
#include"pnl/pnl specfun.h"
#include"pnl/pnl mathtools.h"
#include "nig1d_pad.h"
#if defined(PremiaCurrentVersion) && PremiaCurrentVersion <</pre>
     (2011+2) //The "#else" part of the code will be freely av
    ailable after the (year of creation of this file + 2)
static int CHK OPT(MC NIG FixedAsian)(void *Opt, void *Mod)
  return NONACTIVE;
}
int CALC(MC_NIG_FixedAsian)(void*Opt,void *Mod,Pricing
    Method *Met)
  return AVAILABLE_IN_FULL_PREMIA;
}
#else
//Compute the positive or negative jump size between the sm
    allest and the biggest value of cdf_jump_points of the NIG
    process
static double jump_generator_NIG(double* cdf_jump_vect,
    double* cdf jump points, int cdf jump vect size, double alpha,
    double beta, int generator)
{
   double z, v, y;
   int test,temp,l,j,q;
   test=0;
   v=pnl rand uni(generator);
   y=cdf_jump_vect[cdf_jump_vect_size]*v;
   l=cdf_jump_vect_size/2;
   j=cdf_jump_vect_size;
   if(cdf_jump_vect[1]>y)
   {
    1=0:
    j=cdf_jump_vect_size/2;
```

```
if(v==1)
     z=cdf_jump_points[cdf_jump_vect_size];
   }
   if(v==0)
   {
   z=cdf_jump_points[0];
   if(v!=1 \&\& v!=0)
    while(test==0)
     if(cdf_jump_vect[l+1]>y)
      q=1;
      test=1;
     else
      temp=(j-1-1)/2+1;
      if(cdf_jump_vect[temp]>y)
       j=temp;
       1=1+1;
      }
      else
       l=temp*(temp>l)+(l+1)*(temp<=l);
      }
     }
    }
    z=pow(1./cdf_jump_points[q]-(y-cdf_jump_vect[q])*exp(-
    beta*cdf_jump_points[q])/(pnl_bessel_k(1.,alpha*cdf_jump_po
    ints[q])*cdf_jump_points[q]),-1.);
   }
return z;
//(\exp(x)-1)/x
static double p_func(double x)
{
```

```
double s;
 int i,n;
 n=1;
 s=0;
 for(i=0;i<=n;i++)
   s+=pow(x,i)/pnl_fact(i+1);
 return s;
//(4\exp(x)+(2x-3)\exp(2x)-1)/x^3
static double var_func(double x)
{
 double s;
 int i,n;
 n=1;
 s=0;
 for(i=0;i<=n;i++)
   s+=4*pow(x,i)/pnl_fact(i+3)-3*pow(2.,i+3)*pow(x,i)/pnl_
    fact(i+3)+pow(2.,i+3)*pow(x,i)/pnl fact(i+2);
 return s;
//\exp(x)/x-(\exp(x)-1)/x^2
static double cov func(double x)
{
 double s;
 int i,n;
 n=1;
 s=0;
 for(i=0;i<=n;i++)
   s+=pow(x,i)*(1./pnl_fact(i+1)-1./pnl_fact(i+2));
 return s;
}
static int NIG_Mc_FixedAsian(NumFunc_2*P,double S0,double
T, double r, double divid, double sigma, double theta, double ka
    ppa,int generator,int n_paths,double *ptprice,double *ptde
    lta,double *priceerror,double *deltaerror)
```

```
{
    double eps,s,s1,s2,s3,s4,s5,s6,payoff,dpayoff,control,
    discount,w1,w2,drift,err,u,u0,z,sigma0;
    double lambda p, control expec, lambda m, cdf jump bound,
    pas,cov payoff control,var payoff,var control;
    double cor payoff control, control coef, var dpayoff, *cdf
    _jump_points,*cdf_jump_vect p;
    double *cdf jump vect m,*Xg,*Xd,tau,*jump time vect,*
    jump_time_vect_p,*jump_time_vect_m;
    double alpha,beta,delta,var_temp,cov_temp,*vect_temp,g_
    temp, K;
    int i,j,k,jump number p,jump number m,jump number,m1,m2
    ,cdf jump vect size,n int,k1,k2;
    K=P->Par[0].Val.V DOUBLE;
    n int=10000;
    discount=exp(-r*T);
    err=1E-16;
    eps=0.1;
    cdf_jump_vect_size=100000;
    if(r-divid!=0)
     control expec=S0*(exp((r-divid)*T)-1)/((r-divid)*T);
     control_expec=S0;
    s=0;
    s1=0;
    s2=0;
    s3=0;
    s4=0;
    s5=0;
    s6=0;
    alpha=sqrt(theta*theta+sigma*sigma/kappa)/(sigma*sigma)
    beta=theta/(sigma*sigma);
    delta=sigma/sqrt(kappa);
    if(alpha-fabs(beta)<1)
    printf("Function NIG_Mc_FixedAsian: invalid paramete
    rs. We must have sqrt(kappa)*(2*fabs(theta)+sigma*sigma)<=1{
    n");
    }
    while(delta*exp(-fabs(beta)*eps)/(M_PI*eps)<10)</pre>
```

```
eps=eps*0.9;
cdf jump bound=1;
   //Computation of the biggest jump that we tolerate
   while(2*sqrt(alpha/(2*M PI))*delta*exp(-(alpha-fabs(bet
   a))*cdf_jump_bound)/((alpha-fabs(beta))*pow(cdf_jump_bound,
   1.5))>err)
     cdf_jump_bound++;
   pas=(cdf_jump_bound-eps)/cdf_jump_vect_size;
   cdf_jump_points=malloc((cdf_jump_vect_size+1)*sizeof(
   double));
   cdf_jump_vect_p=malloc((cdf_jump_vect_size+1)*sizeof(
   double));
   cdf_jump_vect_m=malloc((cdf_jump_vect_size+1)*sizeof(
   double));
   cdf jump points[0]=eps;
   cdf_jump_vect_p[0]=0;
   cdf_jump_vect_m[0]=0;
   //computation of the cdf of the positive and negative
   jumps at some points
   for(i=1;i<=cdf_jump_vect_size;i++)</pre>
    cdf jump points[i]=i*pas+eps;
    cdf_jump_vect_p[i]=cdf_jump_vect_p[i-1]+exp(beta*cdf_
   jump points[i-1])*cdf jump points[i-1]*pnl bessel k(1.,alpha*
   cdf jump points[i-1])*(1/cdf jump points[i-1]-1/cdf jump po
   ints[i]);
    cdf_jump_vect_m[i]=cdf_jump_vect_m[i-1]+exp(-beta*cdf_
   jump_points[i-1])*cdf_jump_points[i-1]*pnl_bessel_k(1.,alpha*
   cdf_jump_points[i-1])*(1/cdf_jump_points[i-1]-1/cdf_jump_po
   ints[i]);
   lambda_p=cdf_jump_vect_p[cdf_jump_vect_size]*alpha*delt
   a/M PI;
   lambda_m=cdf_jump_vect_m[cdf_jump_vect_size]*alpha*delt
   a/M PI;
sigma0=0;
   for(i=1;i<=n int;i++)</pre>
    sigma0+=(eps*i/n_int)*cosh(beta*i*eps/n_int)*pnl_bess
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```
el k(1.,alpha*i*eps/n int)*eps/n int;
   sigma0=sqrt(sigma0*alpha*delta*2/M PI);
   drift=0;
   for(i=1;i<=n_int;i++)</pre>
    drift+=sinh(beta*i*eps/n_int)*pnl_bessel_k(1.,alpha*i*
   eps/n int)*eps/n int;
  drift=drift*alpha*delta*2/M PI+(r-divid)-delta*(sqrt(alp
   ha*alpha-beta*beta)-sqrt(alpha*alpha-(beta+1)*(beta+1)));
m1=(int)(1000*lambda_p*T);
   m2=(int)(1000*lambda m*T);
   jump time vect p=malloc((m1)*sizeof(double));
   jump time vect m=malloc((m2)*sizeof(double));
   jump time vect=malloc((m1+m2)*sizeof(double));
   vect temp=malloc((m1+m2)*sizeof(double));
   jump_time_vect_p[0]=0;
   jump time vect m[0]=0;
   jump time vect[0]=0;
   vect_temp[0]=0;
   Xg=malloc((m1+m2)*sizeof(double));//left value of X at
   jump times
   Xd=malloc((m1+m2)*sizeof(double));//right value of X
   at jump times
   Xg[0]=0;
   Xd[0]=0;
pnl rand init(generator,1,n paths);
   /*Call Case*/
   if((P->Compute) == &Call OverSpot2)
   {
      for(i=0;i<n paths;i++)</pre>
       {
        //simulation of the positive jump times and number
        tau=-(1/lambda_p)*log(pnl_rand_uni(generator));
        jump number p=0;
        while(tau<T)
         jump_number_p++;
         jump time vect p[jump number p]=tau;
         tau+=-1/(lambda_p)*log(pnl_rand_uni(generator));
        }
```

```
//simulation of the negative jump times and numb
   er
        tau=-(1/lambda_m)*log(pnl_rand_uni(generator));
         jump number m=0;
        while(tau<T)</pre>
        {
         jump_number_m++;
         jump time vect m[jump number m]=tau;
         tau+=-1/(lambda m)*log(pnl rand uni(generator));
        jump_time_vect_p[jump_number_p+1]=T;
        jump time vect m[jump number m+1]=T;
        jump number=jump number p+jump number m;
//computation of Xg and Xd
      k1=1:
      k2=1;
      u0=0;
        u=0:
      for(k=1;k<=jump number;k++)</pre>
       w1=jump_time_vect_p[k1];
       w2=jump_time_vect_m[k2];
       if(w1<w2)
       {
        u=w1;
        k1++;
          z=jump_generator_NIG(cdf_jump_vect_p,cdf_jump_po
   ints,cdf_jump_vect_size,alpha,beta,generator);
       }
       else
       {
        u=w2;
        k2++;
        z=-jump_generator_NIG(cdf_jump_vect_m,cdf_jump_po
   ints,cdf_jump_vect_size,alpha,-beta,generator);
       }
         g temp=pnl rand normal(generator);
         if(fabs(drift*(u-u0))<1e-4)</pre>
         {
```

```
var temp=(u-u0)*(u-u0)*(u-u0)*var func(drift*(u-u0)*var func(dri
u0))/2:
                                cov_temp=(u-u0)*(u-u0)*cov_func(drift*(u-u0));
                            }
                            else
                                 var temp=(4*exp(drift*(u-u0))+(2*drift*(u-u0)-3)
*exp(2*drift*(u-u0))-1)/(2*drift*drift*drift);
                                 cov_temp=(u-u0)*exp(drift*(u-u0))/drift-(exp(dr
ift*(u-u0))-1)/(drift*drift);
                            }
                  jump time vect[k]=u;
                            vect_temp[k]=cov_temp*g_temp/(sqrt(u-u0))+sqrt(
var_temp-cov_temp*cov_temp/(u-u0))*pnl_rand_normal(generator);
                  Xg[k]=drift*(u-u0)+sigma0*g_temp*sqrt(u-u0)+Xd[k-1]
];
                  Xd[k]=Xg[k]+z;
                  u0=u;
             }
                       g temp=pnl rand normal(generator);
                        if(fabs(drift*(T-u0))<1e-4)</pre>
                            var temp=(T-u0)*(T-u0)*(T-u0)*var func(drift*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u
u0))/2;
                            cov temp=(T-u0)*(T-u0)*cov func(drift*(T-u0));
                        }
                       else
                        {
                            var_temp=(4*exp(drift*(T-u0))+(2*drift*(T-u0)-3)*
exp(2*drift*(T-u0))-1)/(2*drift*drift*drift);
                            cov temp=(T-u0)*exp(drift*(T-u0))/drift-(exp(drif
t*(T-u0))-1)/(drift*drift);
                        }
              jump time vect[jump number+1]=T;
                       vect temp[jump number+1]=cov temp*g temp/(sqrt(T-
u0))+sqrt(var_temp-cov_temp*cov_temp/(T-u0))*pnl_rand_nor
mal(generator);
             Xg[jump number+1]=drift*(T-u0)+sigma0*g temp*sqrt(
T-u0)+Xd[jump number];
             Xd[jump_number+1] = Xg[jump_number+1];
```

```
//computation of the payoff
        payoff=0;
        for(j=1;j<=jump number+1;j++)</pre>
         if(fabs(drift*(jump_time_vect[j]-jump_time_vect[
   j-1]))<1e-4)
          payoff+=exp(Xd[j-1])*(p func(drift*(jump time v
   ect[j]-jump_time_vect[j-1]))*(jump_time_vect[j]-jump_time_v
   ect[j-1])+sigma0*vect temp[j]);
         else
          payoff+=exp(Xd[j-1])*((exp(drift*(jump time vec
   t[j]-jump time vect[j-1]))-1)/drift+sigma0*vect temp[j]);
        control=S0*payoff/T;
        dpayoff=-discount*(payoff/T)*(S0*payoff/T<K);</pre>
        payoff=discount*(K-S0*payoff/T)*(S0*payoff/T<K);</pre>
        s1+=payoff;
        s+=payoff*payoff;
        s2+=control;
        s3+=control*control;
        s4+=control*payoff;
        s5+=dpayoff;
        s6+=dpayoff*dpayoff;
       cov payoff control=s4/n paths-s1*s2/((double)n
   paths*n paths);
       var payoff=(s-s1*s1/((double)n paths))/(n paths-1);
       var control=(s3-s2*s2/((double)n paths))/(n paths-1
   );
       cor_payoff_control=cov_payoff_control/(sqrt(var pay
   off)*sqrt(var control));
       control coef=cov payoff control/var control;
       var_dpayoff=(s6-s5*s5/((double)n_paths))/(n_paths-1
   );
       if(r!=divid)
        *ptprice=(s1/n_paths-control_coef*(s2/n_paths-
   control_expec)-K*exp(-r*T)+S0*(exp(-divid*T)-exp(-r*T))/((r-
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divid)*T);
       else
         *ptprice=(s1/n_paths-control_coef*(s2/n_paths-
   control expec))+(SO-K)*exp(-r*T);
        *priceerror=1.96*sqrt(var payoff*(1-cor payoff
   control*cor payoff control))/sqrt(n paths);
       if(r!=divid)
         *ptdelta=s5/(n paths)+(exp(-divid*T)-exp(-r*T))/((
   r-divid)*T);
       else
        *ptdelta=s5/(n_paths)+exp(-r*T);
       *deltaerror=1.96*sqrt(var dpayoff)/sqrt(n paths);
  }
  /*Put case*/
   if((P->Compute) == &Put OverSpot2)
   {
      for(i=0;i<n paths;i++)</pre>
       {
        //simulation of the positive jump times and number
        tau=-(1/lambda p)*log(pnl rand uni(generator));
         jump number p=0;
        while(tau<T)</pre>
         jump number p++;
         jump_time_vect_p[jump_number_p]=tau;
         tau+=-1/(lambda p)*log(pnl rand uni(generator));
        //simulation of the negative jump times and numb
   er
        tau=-(1/lambda_m)*log(pnl_rand_uni(generator));
         jump number m=0;
        while(tau<T)</pre>
         jump_number_m++;
         jump time vect m[jump number m]=tau;
         tau+=-1/(lambda m)*log(pnl rand uni(generator));
         jump_time_vect_p[jump_number_p+1]=T;
         jump time vect m[jump number m+1]=T;
         jump_number=jump_number_p+jump_number_m;
```

```
//
                  //computation of Xg and Xd
          k1=1;
          k2=1;
          u0=0;
                 u=0;
          for(k=1;k<=jump_number;k++)</pre>
              w1=jump_time_vect_p[k1];
              w2=jump_time_vect_m[k2];
              if(w1<w2)
              {
                 u=w1;
                 k1++;
                         z=jump_generator_NIG(cdf_jump_vect_p,cdf_jump_po
ints,cdf_jump_vect_size,alpha,beta,generator);
              }
              else
               {
                 u=w2;
                 k2++;
                  z=-jump_generator_NIG(cdf_jump_vect_m,cdf_jump_po
ints,cdf_jump_vect_size,alpha,-beta,generator);
              }
                     g_temp=pnl_rand_normal(generator);
                     if(fabs(drift*(u-u0))<1e-4)</pre>
                         var temp=(u-u0)*(u-u0)*(u-u0)*var func(drift*(u-u0)*var func(dri
u0))/2;
                         cov_temp=(u-u0)*(u-u0)*cov_func(drift*(u-u0));
                      }
                      else
                      {
                         var_temp=(4*exp(drift*(u-u0))+(2*drift*(u-u0)-3)
*exp(2*drift*(u-u0))-1)/(2*drift*drift*drift);
                         cov_temp=(u-u0)*exp(drift*(u-u0))/drift-(exp(dr
ift*(u-u0))-1)/(drift*drift);
              jump_time_vect[k]=u;
                     vect_temp[k]=cov_temp*g_temp/(sqrt(u-u0))+sqrt(
```

```
var temp-cov temp*cov temp/(u-u0))*pnl rand normal(generator);
                     Xg[k]=drift*(u-u0)+sigma0*g temp*sqrt(u-u0)+Xd[k-1]
          ];
                    Xd[k]=Xg[k]+z;
                    u0=u;
                  }
                       g_temp=pnl_rand_normal(generator);
                        if(fabs(drift*(T-u0))<1e-4)</pre>
                          var_{temp} = (T-u0)*(T-u0)*(T-u0)*var_{func}(drift*(T-u0)*var_{func}(drift*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T
          u0))/2;
                          cov temp=(T-u0)*(T-u0)*cov func(drift*(T-u0));
                        }
                       else
                          var_temp=(4*exp(drift*(T-u0))+(2*drift*(T-u0)-3)*
          exp(2*drift*(T-u0))-1)/(2*drift*drift*drift);
                          cov temp=(T-u0)*exp(drift*(T-u0))/drift-(exp(drif
          t*(T-u0))-1)/(drift*drift);
                       }
                  jump time vect[jump number+1]=T;
                       vect_temp[jump_number+1]=cov_temp*g_temp/(sqrt(T-
          u0))+sqrt(var_temp-cov_temp*cov_temp/(T-u0))*pnl_rand_nor
          mal(generator);
                  Xg[jump number+1]=drift*(T-u0)+sigma0*g temp*sqrt(
          T-u0)+Xd[jump number];
                  Xd[jump number+1]=Xg[jump number+1];
//computation of the payoff
                       payoff=0;
                       for(j=1;j<=jump number+1;j++)</pre>
                          if(fabs(drift*(jump_time_vect[j]-jump_time_vect[
          j-1]))<1e-4)
                             payoff+=exp(Xd[j-1])*(p func(drift*(jump time v
          ect[j]-jump_time_vect[j-1]))*(jump_time_vect[j]-jump_time_v
          ect[j-1])+sigma0*vect_temp[j]);
                          else
                             payoff+=exp(Xd[j-1])*((exp(drift*(jump_time_vec
          t[j]-jump_time_vect[j-1]))-1)/drift+sigma0*vect_temp[j]);
```

```
control=S0*payoff/T;
     dpayoff=-discount*(payoff/T)*(S0*payoff/T<K);</pre>
     payoff=discount*(K-S0*payoff/T)*(S0*payoff/T<K);</pre>
     s1+=payoff;
     s+=payoff*payoff;
     s2+=control;
     s3+=control*control;
     s4+=control*payoff;
     s5+=dpayoff;
     s6+=dpayoff*dpayoff;
    }
    cov_payoff_control=s4/n_paths-s1*s2/((double)n_
paths*n paths);
    var payoff=(s-s1*s1/((double)n paths))/(n paths-1);
    var_control=(s3-s2*s2/((double)n_paths))/(n_paths-1
);
    cor payoff control=cov payoff control/(sqrt(var pay
off)*sqrt(var control));
    control_coef=cov_payoff_control/var_control;
    var dpayoff=(s6-s5*s5/((double)n_paths))/(n_paths-1
);
    *ptprice=(s1/n_paths-control_coef*(s2/n_paths-contr
ol expec));
    *priceerror=1.96*sqrt(var payoff*(1-cor payoff
control*cor payoff control))/sqrt(n paths);
    *ptdelta=s5/(n paths);
    *deltaerror=1.96*sqrt(var_dpayoff)/sqrt(n_paths);
   }
   free(Xd);
   free(Xg);
   free(cdf_jump_points);
   free(cdf jump vect p);
   free(cdf_jump_vect_m);
   free(jump_time_vect_p);
   free(jump time vect m);
   free(jump_time_vect);
   free(vect_temp);
```

```
return OK;
}
int CALC(MC NIG FixedAsian) (void*Opt, void *Mod, Pricing
    Method *Met)
{
  TYPEOPT* ptOpt=(TYPEOPT*)Opt;
  TYPEMOD* ptMod=(TYPEMOD*)Mod;
  double r, divid;
  r=log(1.+ptMod->R.Val.V DOUBLE/100.);
  divid=log(1.+ptMod->Divid.Val.V DOUBLE/100.);
  return NIG Mc FixedAsian(ptOpt->PayOff.Val.V NUMFUNC 2,
    ptMod->SO.Val.V_PDOUBLE,ptOpt->Maturity.Val.V_DATE-ptMod->
    T.Val.V DATE,r,divid,ptMod->Sigma.Val.V PDOUBLE,ptMod->Thet
    a.Val.V DOUBLE,ptMod->Kappa.Val.V SPDOUBLE,Met->Par[0].Val.
    V ENUM.value,Met->Par[1].Val.V LONG,&(Met->Res[0].Val.V
    DOUBLE),&(Met->Res[1].Val.V_DOUBLE),&(Met->Res[2].Val.V_DOUBLE),
    &(Met->Res[3].Val.V DOUBLE));
}
static int CHK OPT(MC NIG FixedAsian)(void *Opt, void *Mod)
  if ((strcmp(((Option*)Opt)->Name, "AsianCallFixedEuro")==0
    ) || (strcmp( ((Option*)Opt)->Name, "AsianPutFixedEuro")==0
    ) )
    return OK;
  return WRONG;
#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met,Option *Mod)
{
  if (Met->init == 0)
      Met->init=1;
      Met->Par[0].Val.V_ENUM.value=0;
      Met->Par[0].Val.V ENUM.members=&PremiaEnumMCRNGs;
      Met->Par[1].Val.V_LONG=100000;
    }
```

```
return OK;
}

PricingMethod MET(MC_NIG_FixedAsian) =
{
    "MC_NIG_AsianFixed",
    {{"RandomGenerator",ENUM,{100},ALLOW}, {"N iterations",
        LONG,{100},ALLOW},{" ",PREMIA_NULLTYPE,{0},FORBID}},
    CALC(MC_NIG_FixedAsian),
    {{"Price",DOUBLE,{100},FORBID},{"Delta",DOUBLE,{100},FORB
        ID},{"Price Error",DOUBLE,{100},FORBID},{"Delta Error",
        DOUBLE,{100},FORBID},{" ",PREMIA_NULLTYPE,{0},FORBID}},
    CHK_OPT(MC_NIG_FixedAsian),
    CHK_ok,
    MET(Init)
};
```

References