

## Help

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#include "bs2d_std2d.h"
#include "error_msg.h"

static int VFExplicit(int am,double s1,double s2,NumFunc_2
    *payoff,double K,double t,double r,double divid1,double
    divid2,double sigma1,double sigma2,double rho,int N, double
    *ptprice,double *ptdelta1,double *ptdelta2)
{
    int i,j,I,II1,II2,JJ2;
    double temps,hg,ee,l,la,lb,w,p,k1,k2,t1,t2,bb1,bb2,bb3,bb
        4,bb5,aa,bb,
        c0,c00,c1,c2,c3,aaa,bbb,ccc,ddd,eee,fff,ggg,hhh;
    double *u,*uap,*psi;
    double u1,u2,loc,sig1,sig2;
    double a2,c,s,b1,b2,b3,v1,v2,h,g,dt,alpha,c22,theta,k3;
    double delta1,delta2;

    /*Memory Allocation*/
    u=(double *)calloc(N*N,sizeof(double));
    if (u==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    uap=(double *)calloc(N*N,sizeof(double));
    if (uap==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    psi=(double *)calloc(N*N,sizeof(double));
    if (psi==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    /* Initialisations */
    sig1=sigma1*sigma1;
    sig2=sigma2*sigma2;
    u1=log(s1);
    u2=log(s2);

    /*Space Localization*/
    p=0.2316419;
    bb1=0.319381530;
    bb2=-0.356563782;

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bb3=1.781477937;
bb4=-1.821255978;
bb5=1.330274429;

la=0;
lb=10*K;
w=0;
for (j=0;j<20;j++)
{
    for (i=0;i<200;i++)
{
    /*Homogeneous Discretization of [la,lb]*/
    l=la+i*(lb-la)*0.005;

    k1= ( l-fabs(t*(r-divid1-0.5*sigma1*sigma1)))/( sqrt(
    t)*sigma1);
    k2= ( l-fabs(t*(r-divid2-0.5*sigma2*sigma2)))/( sqrt(
    t)*sigma2);

    t1=1/(1+p*k1);
    t2=1/(1+p*k2);

    /*Put Minimum*/
    if((payoff->Compute)==&PutMin)
        k3=4*K;
    /*Call Maximum*/
    else if((payoff->Compute)==&CallMax)
        k3=1000*64*( exp(u1+fabs(r-divid1)*t +sig1*t)+ exp(
        u2+fabs(r-divid2)*t +sig2*t))*
        ( exp(u1+fabs(r-divid1)*t +sig1*t)+ exp(u2+fabs(r-
        divid2)*t +sig2*t));
    /*Exchange option*/
    else /*if((payoff->Compute)==&Exchange)*/
        k3=1000*64*exp(2*u1+2*fabs(r-divid1)*t +2*sig1*t);

    /*Precision of 1/1000*/
    w = 1/(2.506628274631)*

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        (exp(-0.5*k1*k1)*
        (bb1*t1+bb2*t1*t1+bb3*t1*t1*t1+bb4*t1*t1*t1*t1+bb5*
t1*t1*t1*t1*t1) +
        exp(-0.5*k2*k2)*
        (bb1*t2+bb2*t2*t2+bb3*t2*t2*t2+bb4*t2*t2*t2*t2+bb5*
t2*t2*t2*t2*t2))-0.001/k3;

if(w<0) {
    break;      }
}

/*[la,lb] contains the solution w(l)=0 */
la=l-(lb-la)*0.005;
lb=l;
/*Frame of the solution*/
if(lb-la<0.00001) break;
}
loc=l;

/* Rotation */

if (sig1==sig2) {

    theta = atan(1);
    alpha=sig1*0.5*(1+rho);
    a2=sig2*0.5*(1-rho);

    c = cos(theta);
    s = sin(theta);

    b1 = (r - divid1 - sig1*0.5)*c + (r - divid2 - sig2*0.
5)*s;
    b2 = (r - divid2 - sig2*0.5)*c - (r-divid1 - sig1*0.5
)*s ;
}else{
    theta = atan(2*rho*sigma1*sigma2/(sig1-sig2))/2;

    c = cos(theta);
    c2 = cos(2*theta);
    s = sin(theta);

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alpha=((sig1+sig2)*c2+sig1-sig2)/(4*c2);
a2= ((sig1+sig2)*c2+sig2-sig1)/(4*c2);
b1 = (r - divid1 - sig1*0.5)*c + (r - divid2 - sig2*0.
5)*s;
b2 = (r - divid2 - sig2*0.5)*c - (r-divid1 - sig1*0.5
)*s ;

}

/*homothetie*/

b3 = sqrt(alpha/a2);

/*Space steps*/
h = (double)(2.0*loc/((double)1.0*N));
g = (double)(2.0*b3*loc/((double)1.0*N) );
hg = h*g;

/*Localization after rotation and homothetie*/

v1=u1*c+u2*s;
v2=(u2*c-u1*s)*b3;

/*Stability Condition*/

/* if(2*a1 < (h,g)*MAX(fabs(b1),fabs(b2*b3))) */
/*Pechlet Condition*/
if(2*alpha - MAX(h*fabs(b1),g*fabs(b2*b3))<0)
{
    /*Upwind Scheme*/

    /*Stability Condition Time Step*/
    dt=hg/(r*hg+3*alpha*(h/g+g/h)+g*fabs(b1)+h*fabs(b2*b3
));
    /*Constants*/
    c0 = alpha*dt/(h*h);
    c00 = alpha*dt/(g*g);
    c1 = b1*dt/h;

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    c22 = b2*b3*dt/g;
    c3 = r*dt;
    aaa=1-2*(c0+c00)-c3-(fabs(c1)+fabs(c22));
    bbb=c0+MAX(-c1,0);
    ccc=c0+MAX(c1,0);
    ddd=c00+MAX(-c22,0);
    eee=c00+MAX(c22,0);
    fff=aaa-c00;
    ggg=aaa-c0;
    hhh=aaa-c0-c00;

}
else
{

    /*Central Scheme*/

    /*Stability Condition Time Step*/

    dt= hg/(0.5*r*hg+(h/g+g/h)*2*alpha+0.5*(g*fabs(b1)+h*
fabs(b2*b3)) );
    /*Constants*/
    c0 = alpha*dt/(h*h);
    c00 = alpha*dt/(g*g);
    c1 = 0.5*b1*dt/h;
    c22 = 0.5*b2*b3*dt/g;
    c3 = r*dt;
    aaa=1-2*(c0+c00)-c3;
    bbb=c0-c1;
    ccc=c0+c1;/*Deltas*/
    ddd=c00-c22;
    eee=c00+c22;
    fff=1-2*c0-3*c00-c3;
    ggg=1-3*c0-2*c00-c3;
    hhh=1-3*(c0+c00)-c3;

}

/*Maturity Conditions*/

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ee = N*0.5;
for(j=0;j<N;j++)
{
    for (i=0;i<N;i++)
{
    I = i*N+j;

    aa=v1+i*h-h*ee;
    bb=v2+j*g-g*ee;
    psi[I] =(payoff->Compute)(payoff->Par,exp(aa*c-bb*s/b3
    ),exp(aa*s+bb*c/b3));
    /*psi[I] = Payoff(aa*c-bb*s/b3,aa*s+bb*c/b3,K,mu);*/

    uap[I] = psi[I];
    u[I] = psi[I];

}
}

/*Explicit Finite Difference Cycle*/
temps = 0;
while (temps<t)
{
    temps += dt;
    for (i=1;i<N-1;i++)
{
    for (j=1;j<N-1;j++)
    {
        I=i*N+j;
        u[I] = uap[I]*aaa+uap[I-N]*bbb+uap[I+N]*ccc+
        uap[I-1]*ddd+uap[I+1]*eee;

    }
}

}

/*Homogeneous Dirichlet Conditions*/
for (i=1;i<N-1;i++)
{

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II1=i*N;
II2=i*N+(N-1);
JJ2=(N-1)*N + i;

u[II1] = uap[II1]*fff + uap[II1-N]*bbb + uap[II1+N]*cc
c+
    uap[II1+1]*eee;

u[II2]=uap[II2]*fff+uap[II2-N]*bbb+ uap[II2+N]*ccc+ua
p[II2-1]*ddd;

u[i] = uap[i]*ggg+uap[i+N]*ccc+uap[i-1]*ddd+uap[i+1]*
eee;

u[JJ2] = uap[JJ2]*ggg+uap[JJ2-N]*bbb+uap[JJ2-1]*ddd+ua
p[JJ2+1]*eee;

}

u[0] = uap[0]*hhh+uap[N]*ccc+uap[1]*eee;

u[N-1] = uap[N-1]*hhh+uap[N+N-1]*ccc+
uap[N-2]*ddd;

u[(N-1)*N+(N-1)]=uap[(N-1)*N + (N-1)]*
hhh+uap[(N-2)*N + (N-1)] *bbb+
uap[(N-1)*N + (N-2)]*ddd;

u[(N-1)*N]= uap[(N-1)*N]*hhh+
uap[(N-2)*N]*bbb+uap[(N-1)*N+1]*eee;

for (i=0;i<N;i++)
{
for (j=0;j<N;j++)
{
I = i*N+j;
/*Splitting for the american case*/
uap[I] = MAX(u[I],psi[I]);

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    }
}
}

/*Price*/
i= ((int)(N/2))*N+(int)(N/2);
*ptprice=uap[i];

/*Deltas*/
delta1=(uap[i+N]-uap[i-N])/(2*h);
delta2=(uap[i+1]-uap[i-1])/(2*g);
*ptdelta1=(delta1*c-delta2*s*b3)*exp(-u1);
*ptdelta2=(delta2*b3*c+delta1*s)*exp(-u2);

/*Memory desallocation*/
free(u);
free(uap);
free(psi);

return OK;
}

int CALC(FD_VFExplicit)(void *Opt,void *Mod,PricingMethod *
    Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid1,divid2;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid1=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.);
    divid2=log(1.+ptMod->Divid2.Val.V_DOUBLE/100.);

    return VFExplicit(ptOpt->EuOrAm.Val.V_BOOL,ptMod->S01.Val
        .V_PDOUBLE,
        ptMod->S02.Val.V_PDOUBLE,ptOpt->PayOff.Val.V_
        NUMFUNC_2,(ptOpt->PayOff.Val.V_NUMFUNC_2)->Par[0].Val.V_PDOUBLE,
        ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.V_DATE,
        r,divid1,divid2,ptMod->Sigma1.Val.V_PDOUBLE,pt
        Mod->Sigma2.Val.V_PDOUBLE,ptMod->Rho.Val.V_RGDOUBLE,
        Met->Par[0].Val.V_INT,

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        &(Met->Res[0].Val.V_DOUBLE), &(Met->Res[1].Val.V_
        DOUBLE), &(Met->Res[2].Val.V_DOUBLE) );
    }

static int CHK_OPT(FD_VFExplicit)(void *Opt, void *Mod)
{
    if ( (strcmp(((Option*)Opt)->Name, "PutMinimumAmer")==0)
        || (strcmp( ((Option*)Opt)->Name, "CallMaximumAmer")==
        =0)
        || (strcmp(((Option*)Opt)->Name, "ExchangeAmer")==0) )
        return OK;
    return WRONG;
}

static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    if ( Met->init == 0)
    {
        Met->init=1;

        Met->Par[0].Val.V_INT2=100;

    }

    return OK;
}

PricingMethod MET(FD_VFExplicit)=
{
    "FD_FVExpl",
    {{"StepNumber", INT2, {100}, ALLOW}, {" ", PREMIA_NULLTYPE, {0}
    , FORBID}},
    CALC(FD_VFExplicit),
    {{"Price", DOUBLE, {100}, FORBID}, {"Delta1", DOUBLE, {100}, FO
    RBID} ,
    {"Delta2", DOUBLE, {100}, FORBID} ,
    {" ", PREMIA_NULLTYPE, {0}, FORBID}},
    CHK_OPT(FD_VFExplicit),

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    CHK_ok,  
    MET(Init)  
};
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## References