

## Help

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#include "bs1d_std.h"
#include <stdlib.h>

#define CALLOC_1D(P,N)  P=(double*)calloc(N+1,sizeof(
    double));{
    if (P==NULL){
        return 1;{

#define CALLOC_2D(P,N)  P=(double**)calloc(N+1,sizeof(
    double*));{
    if (P==NULL){
        return 1;{
    for (i=0;i<N+1;i++){
        {{
            P[i]=(double*)calloc(N+1,sizeof(double));{
            if (P[i]==NULL){
        return 1;{
        }{

#define DESALLOC_2D(P,N)  for (i=0;i<N+1;i++){
    free(P[i]);{
    free(P){

#define DESALLOC_1D(P,N)  free(P)

static int CoxPatry_98(double s,NumFunc_1 *p,double t,
    double r,double divid,double sigma,int N,int N_Hedge,int N_Sampl
    e,double alpha_min,double alpha_max,double *ptprice,double
    *ptdelta,double *ptvariance,int *pthedge,double alphacour
    ant)
{
    int i,iStar,j,k,n;
    double u,d,pu,pd,a1,price=0.,stock,lowerstock,h;
    double **Spot,**Price,**CurrentVStar,**PrevVStar;
    double *SqrSpot,*SqrPrice,*SpotPrice,*CurrentV;
    double alpha,alpha_step,alphaStar,obstacle_value,current_
        value,price_minus_alpha_spot,alphaStar0;

    /*Price, Variance arrays*/
    CALLOC_2D(Spot,N);

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CALLOC_2D(Price,N);
CALLOC_2D(CurrentVStar,N);
CALLOC_2D(PrevVStar,N);

CALLOC_1D(CurrentV,N);
CALLOC_1D(SqrSpot,N);
CALLOC_1D(SqrPrice,N);
CALLOC_1D(SpotPrice,N);

/*Up and Down factors*/
h=t/(double)N;
a1= exp(h*(r-divid));
u = exp(sigma*sqrt(h));
d= 1./u;

/*Risk-Neutral Probability*/
pu=(a1-d)/(u-d);
pd=1.-pu;

/*FirstStep: Spot, Price, VStarZero (PrevVStar) computation*/
/*Price initialisation*/
lowerstock=s;
for (i=0;i<N;i++)
    lowerstock*=d;

stock=lowerstock*exp(-r*t);

for (i=0;i<=N;i++)
{
    price=Price[N][i]=(p->Compute)(p->Par,stock*exp(r*t))
    *exp(-r*t);

    Spot[N][i]=stock;
    SqrSpot[i]=stock*stock;
    SqrPrice[i]=price*price;
    SpotPrice[i]=stock*price;
    stock*=(u/d);
}

/*Backward Resolution*/

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for (i=N-1;i>=0;i--)
    for (j=0;j<=i;j++)
    {
price=Price[i][j]=pu*Price[i+1][j+1]+ pd*Price[i+1][j];
stock=Spot[i][j]=pu*Spot[i+1][j+1]+ pd*Spot[i+1][j];
SqrSpot[j]=pu*SqrSpot[j+1]+ pd*SqrSpot[j];
SqrPrice[j]=pu*SqrPrice[j+1]+ pd*SqrPrice[j];

SpotPrice[j]=pu*SpotPrice[j+1]+ pd*SpotPrice[j];

PrevVStar[i][j]=SqrPrice[j]-price*price-{
    (SpotPrice[j]-price*stock)*(SpotPrice[j]-price*stock)/
    (SqrSpot[j]-stock*stock);
}

alphaStar0=(SpotPrice[0]-price*stock)/(SqrSpot[0]-stock*
stock);

iStar=1;

alphaStar=alphaStar0;

/*SecondStep: Vstar_n computation*/
alpha_step=(alpha_max-alpha_min)/(double)N_Sample;

if (N_Hedge==0)
    {iStar=1;CurrentVStar[0][0]=PrevVStar[0][0];}
else
    {
        if (N==N_Hedge)
        {
            iStar=0;
            alphaStar=(Price[1][1]-Price[1][0])*exp(r*h)/(s*(u-d))
            ;
            CurrentVStar[0][0]=0.;
        }
        else
        {
            if (PrevVStar[0][0]==0.)
                {iStar=0;CurrentVStar[0][0]=0.;}
            else

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{
    for (n=1;n<=N_Hedge;n++)
{
    alpha=alpha_min;
    if (n<N_Hedge)
        alphaStar=alpha_min;
    for (k=0;k<=N_Sample;k++)
    {
        /*CurrentV Initialisation*/
        for (j=0;j<=N-n;j++)
        {
            price_minus_alpha_spot=Price[N-n][j]-alpha*Spot[N-n][j];
            CurrentV[j]=price_minus_alpha_spot*price_minus_alpha_spot;
        }

        /*We start the computation at time N-n-1*/
        for (i=N-n-1;i>=0;i--)
        for (j=0;j<=i;j++)
        {
            CurrentV[j]=pu*CurrentV[j+1]+pd*CurrentV[j];
            price_minus_alpha_spot=Price[i][j]-alpha*Spot[i][j];
            obstacle_value=price_minus_alpha_spot*price_minus_alpha_spot+PrevVStar[i][j];

            if (CurrentV[j]>obstacle_value)
            {
                if ((n==N_Hedge) && (alpha==alphacourant) && (i==0))
                    iStar=0;
                CurrentV[j]=obstacle_value;
            }

            /*Compute the new current minimum of V_n(alpha)*/
            current_value=CurrentV[j]-price_minus_alpha_spot*price_minus_alpha_spot;
            if (k>0)
            {

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        if (CurrentVStar[i][j]>current_value)
        {
            if ((n==(N_Hedge-1)) && (i==0))
                alphaStar=alpha;
            CurrentVStar[i][j]=current_value;
        }
        else CurrentVStar[i][j]=current_value;
    } /*End j*/
    alpha+=alpha_step;
}/*End k*/

for (i=N-n-1;i>=0;i--)
    for (j=0;j<=i;j++)
        PrevVStar[i][j]=CurrentVStar[i][j];
}/*End n*/

}
}

if (PrevVStar[0][0]<1.0e-7)
    alphaStar=alphaStar0;

*ptprice=Price[0][0];
*ptdelta=alphaStar;
*ptvariance=CurrentVStar[0][0];
*pthedge!=(iStar==0); /*pthedge=0 means it's optimal to
    hedge*/

DESALLOC_1D(SqrSpot,N);
DESALLOC_1D(SqrPrice,N);
DESALLOC_1D(SpotPrice,N);
DESALLOC_1D(CurrentV,N);

DESALLOC_2D(Spot,N);
DESALLOC_2D(Price,N);
DESALLOC_2D(CurrentVStar,N);

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    DESALLOC_2D(PrevVStar,N);

    return 0;
}

int CALC(TR_Patry)(void *Opt,void *Mod,PricingMethod *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid,alphamin,alphamax;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid=log(1.+ptMod->Divid.Val.V_DOUBLE/100.);

    alphamin=-1.;
    alphamax=1.;

    return CoxPatry_98(ptMod->S0.Val.V_PDOUBLE,
        ptOpt->PayOff.Val.V_NUMFUNC_1,ptOpt->Maturity.
        Val.V_DATE-ptMod->T.Val.V_DATE,
        r,divid,ptMod->Sigma.Val.V_PDOUBLE,
        Met->Par[0].Val.V_INT2,Met->Par[1].Val.V_INT,
        Met->Par[3].Val.V_INT2,
        alphamin,alphamax,
        &(Met->Res[2].Val.V_DOUBLE),&(Met->Res[0].Val.V_
        DOUBLE),
        &(Met->Res[1].Val.V_DOUBLE),&(Met->Res[3].Val.V_
        BOOL),
        Met->Par[2].Val.V_DOUBLE);
}

static int CHK_OPT(TR_Patry)(void *Opt,void *Mod)
{
    Option* ptOpt=(Option*)Opt;
    TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

    if ((opt->EuOrAm). Val.V_BOOL==EURO)
        return OK;
}

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    return  WRONG;
}

static int MET(Init)(PricingMethod *Met,Option *Opt)
{
    if ( Met->init == 0)
    {
        Met->init=1;

        Met->Par[0].Val.V_INT2=100; /*stepnumber*/
        Met->Par[1].Val.V_INT=10;    /*hedgenumber*/
        Met->Par[2].Val.V_DOUBLE=0.; /*currentdelta*/

        Met->Par[3].Val.V_INT2=100; /*hedgesampling*/

        Met->Res[0].Val.V_DOUBLE=0.; /*optimaldelta*/
        Met->Res[1].Val.V_DOUBLE=0.; /*variance*/
        Met->Res[2].Val.V_DOUBLE=0.; /*optimalprice*/
        Met->Res[3].Val.V_BOOL=0;    /*hedgenow*/

    }

    return OK;
}

PricingMethod MET(TR_Patry)=
{
    "TR_Patry",
    {
        {"StepNumber",INT2,{100},ALLOW},
        {"HedgeNumber",INT, {10},ALLOW},
        {"CurrentDelta",DOUBLE, {10},IRRELEVANT},
        {"HedgeSampling",INT2,{100},ALLOW},

        {" ",PREMIA_NULLTYPE,{0},FORBID}},
    CALC(TR_Patry),
    {
        {"OptimalDelta",DOUBLE,{100},FORBID} ,
        {"Variance",DOUBLE,{100},FORBID},
    }
}

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    {"OptimalPrice",DOUBLE,{100},FORBID} ,  
    {"HedgeNow",BOOL,{0},FORBID} ,  
    {" ",PREMIA_NULLTYPE,{0},FORBID}},  
    CHK_OPT(TR\_Patry),  
    CHK_tree,  
    MET(Init)  
};
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## References