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Source | Model Presentation

scott1d

1 Description

This model is given by,

$$dS_t = rS_t dt + exp(v_t)S_t dW_t^1,$$

$$dv_t = k(\theta - v_t)dt + \sigma dW_t^2,$$

where W^1 and W^2 are two correlated brownian motions with $\langle W^1, W^2 \rangle_t = \rho t$, and k, θ and σ are constants.

2 Code Implementation

```
#ifndef _SCOTT1D_H
#define _SCOTT1D_H

#include "optype.h"
#include "var.h"

#define TYPEMOD SCOTT1D

/*1D SCOTT World*/
typedef struct TYPEMOD{
   VAR T;
   VAR SO;
   VAR Divid;
   VAR R;
   VAR SigmaO;
   VAR MeanReversion;
   VAR LongRunVariance;
   VAR Sigma;
```

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```
VAR Rho;
} TYPEMOD;
#endif
```

References