```
Help
#include <stdlib.h>
#include "optype.h"
#include "linsys.h"
#include "jump.h"
#include "pnl/pnl_mathtools.h"
#include <math.h>
#include <stdio.h>
#include "error_msg.h"
#define PRECISION 1.0e-7
int Gaussian data(double mu, double gamma2, DENSITY *g)
{
  g->par1=mu;
  g->par2=gamma2;
  g\rightarrow Eu = exp(mu+0.5*gamma2)-1.;
  g->zmin = mu - sqrt(2.0*gamma2*log(1.0/(PRECISION*sqrt(2.
    0*M PI*gamma2))));
  g->zmax = mu + sqrt(2.0*gamma2*log(1.0/(PRECISION*sqrt(2.
    0*M_PI*gamma2))));
  return RETURNOK;
}
int Gaussian_vect(int 1, int u, double h, DENSITY *g){
  int j;
  g->d = malloc((u-1)*sizeof(double));
  if (g->d==NULL) return MEMORY_ALLOCATION_FAILURE;
  memset(g->d,0,(u-1)*sizeof(double));
  for (j=1; j<u; j++) (g->d)[j]=1.0/(sqrt(2.0*M_PI*g->par2))*
    \exp(-SQR(g\rightarrow zmin+j*h-g\rightarrow par1)/(2.0*g\rightarrow par2));
  return RETURNOK;
}
/* ----- */
void freeDensity(DENSITY *g)
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if (g->d!=NULL){
   free(g->d);
    g->d=NULL;
  }
}
int set_parameter(double s, double K, double t, double r,
    double sigma, double divid, double lambda, double Eu, PARAM *p){
 p->s = s;
 p->K = K;
 p->T = t;
 p->r = r;
 p->sigma = sigma;
 p->divid = divid;
 p->lambda = lambda;
 p \rightarrow Eu = Eu;
 return RETURNOK;
}
int equation(PARAM p, EQ *eq){
  eq->dif = 0.5*SQR(p.sigma);
  eq->adv = -(p.r-p.divid-p.lambda*p.Eu-eq->dif);
  eq->lin = p.r+p.lambda;
 return RETURNOK;
int set mesh(EQ eq, int N, MESH *m){
 m->h = (m->xmax-m->xmin)/(double)(N-1);
  if ((m->h*fabs(eq.adv)) \le eq.dif) {
    m->upwind_alphacoef=0.5;
  }else{
    if (eq.adv>0.) m->upwind alphacoef=0.0;
    else if (eq.adv<=0.) m->upwind_alphacoef=1.0;
  }
```

```
return RETURNOK;
}
int set weights espl(double T, EQ eq, MESH *m, WEIGHT *w)
{
  m->k=SQR(m->h)/(eq.lin*SQR(m->h)+2.*eq.dif+eq.adv*m->h*(1)
     .0-2.*m->upwind alphacoef));
  m\rightarrow M=(int) (T/m\rightarrow k);
  w\rightarrow p1=eq.dif/(SQR(m\rightarrow h))+eq.adv/m\rightarrow h*(1.0-m\rightarrow upwind_alpha)
    coef);
  w\rightarrow p2=2.*eq.dif/SQR(m\rightarrow h)+eq.adv/m\rightarrow h*(1.0-2.0*m\rightarrow upwind_
    alphacoef) + eq.lin;
  w->p3=eq.dif/(SQR(m->h))-eq.adv/m->h*m->upwind_alphacoef;
  return RETURNOK;
}
int set weights impl(int M, double T, EQ eq, MESH *m, WEIGHT
      *w){
  m->k= T/((double) M);
  m->M = M;
  w\rightarrow p1=eq.dif/(SQR(m\rightarrow h))+eq.adv/m\rightarrow h*(1.0-m\rightarrow upwind alpha
  w \rightarrow p2=2.*eq.dif/SQR(m \rightarrow h)+eq.adv/m \rightarrow h*(1.0-2.0*m \rightarrow upwind)
    alphacoef)+eq.lin;
  w->p3=eq.dif/(SQR(m->h))-eq.adv/m->h*m->upwind_alphacoef;
  return RETURNOK;
}
int initgrid 1Dbis(PARAM p, DENSITY g, EQ eq, int N, MESH *
    m, IMESH *Im){
  double 1;
  /* Space localization */
  1=2.*p.sigma*sqrt(p.T)*sqrt(log(1.0/PRECISION))+fabs(eq.
    adv*p.T);
```

```
m\rightarrow xmin = log(p.s)-l+ MIN(0.0,g.zmin);
 m\rightarrow xmax = log(p.s)+l+ MAX(0.0,g.zmax);
  set_mesh(eq,N,m);
  Im->min = (int) floor ((double)(fabs(MIN(0.0,g.zmin))/m->
    h));
  Im->max = N-(int) floor ((double) (MAX(0.0,g.zmax)/m->h))
  Im->N = Im->min+(int) floor ((double) (MAX(0.0,g.zmax)/m-
    >h));
 m->N = N;
 m \rightarrow Index = 0;
  while ((m->min+m->Index*m->h)<log(p.s)) m->Index++;
 m->Index--;
 return RETURNOK;
}
int set boundaryAA(int bound, MESH m, PARAM p, IMESH Im,
    double *in,double *out){
  int j,i,N,M;
  double ex_l,ex_u,gl,gu,hl,hu,*p1,*p2,*p3,*tnoto,*b2,*b1;
  PARAM pbs;
  EQ eqbs;
  MESH mbs;
 WEIGHT wbs;
 N = m.N;
  if (bound == 0) {
    for (j=0; j<N; j++) out[j]=in[j];
  }else{
    set_parameter(p.s,p.K,p.T,p.r,p.sigma,p.divid,0.0,0.0,&
    pbs);
    equation(pbs, &eqbs);
    M = m.N;
    mbs.xmin=m.xmin;
```

```
mbs.xmax=m.xmax;
set mesh(eqbs,N,&mbs);
set_weights_impl(M,p.T,eqbs,&mbs,&wbs);
b1 = malloc(N*sizeof(double));
if (b1==NULL) return MEMORY ALLOCATION FAILURE;
memset(b1,0,N*sizeof(double));
b2 = malloc(N*sizeof(double));
if (b2==NULL) return MEMORY ALLOCATION FAILURE;
memset(b2,0,N*sizeof(double));
tnoto = malloc(N*sizeof(double));
if (tnoto==NULL) return MEMORY ALLOCATION FAILURE;
memset(tnoto,0,N*sizeof(double));
p1 = malloc(N*sizeof(double));
if (p1==NULL) return MEMORY ALLOCATION FAILURE;
memset(p1,0,N*sizeof(double));
p2 = malloc(N*sizeof(double));
if (p2==NULL) return MEMORY_ALLOCATION_FAILURE;
memset(p2,0,N*sizeof(double));
p3 = malloc(N*sizeof(double));
if (p3==NULL) return MEMORY ALLOCATION FAILURE;
memset(p3,0,N*sizeof(double));
for (j=0;j<N;j++) b1[j]=in[j];
p1[0] = 0.;
p2[0] = 1.0;
p3[0] = 0.;
for (j=1; j<N-1; j++){
  p1[j] = -mbs.k/2.*wbs.p1;
  p2[j] = 1.0 + mbs.k/2.*wbs.p2;
  p3[j] = -mbs.k/2.*wbs.p3;
p1[N-1] = 0.;
p2[N-1] = 1.0;
p3[N-1] = 0.;
for (i=1; i \le M; i++){
  tnoto[0]=in[0];
  for (j=1; j<N-1; j++) tnoto[j]=mbs.k/2.*wbs.p1*b1<math>[j-1]+
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```
(1.0-mbs.k/2.*wbs.p2)*b1[j]+mbs.k/2.*wbs.p3*b1[j+1];
     tnoto [N-1] = in [N-1];
     /* tridiagonal system */
     tridiagsystem(p1,p2,p3,tnoto,b2,N);
     for (j=0; j<N; j++) b1[j]=b2[j];
   }
   ex l = \exp(m.xmin+Im.min*m.h)-\exp(m.xmin);
   ex u = exp(m.xmax)-exp(m.xmin+Im.max*m.h);
   gl = (b2[Im.min]-b2[0])/ex_1;
   gu = (b2[m.N-1]-b2[Im.max])/ex u;
   hl = (exp(m.xmin+Im.min*m.h)*b2[0]-exp(m.xmin)*b2[Im.mi]
   hu = (exp(m.xmax)*b2[Im.max]-exp(m.xmin+Im.max*m.h)*b2[
   m.N-1])/ex_u;
   for (j=0; j<Im.min; j++) out[j]=gl*exp(m.xmin+j*m.h)+hl;
   for (j=Im.min; j<Im.max; j++) out[j]=0.0;</pre>
   for (j=Im.max; j< m.N; j++) out [j]=gu*exp(m.xmin+j*m.h)+
   hu;
   free(b1);
   free(b2);
   free(tnoto);
   free(p1);
   free(p2);
   free(p3);
 }
 return RETURNOK;
/* -----
   ----- */
int tridiagsystem(double *a, double *b, double *c, double *
   r, double *u, int n){
 int j;
 double bet, *gam;
 gam = malloc(n*sizeof(double));
 if (gam==NULL) return MEMORY_ALLOCATION_FAILURE;
 memset(gam,0,n*sizeof(double));
```

```
/* if (b[0] == 0.0) nerror("Error 1 in tridiag{n",1); */
  u[0]=r[0]/(bet=b[0]);
  for (j=1; j< n; j++){
    gam[j]=c[j-1]/bet;
    bet=b[j]-a[j]*gam[j];
    /* if (bet==0.0) nerror("Error 2 in tridiag\{n, 1\}; */
   u[j]=(r[j]-a[j]*u[j-1])/bet;
  for (j=(n-2); j>=0; j--) u[j]=gam[j+1]*u[j+1];
  if (gam!=NULL){
    free(gam);
   gam=NULL;
  }
 return RETURNOK;
}
int tridiag_bis(double *a, double *b, double *c, double *r,
    double *u, unsigned long n){
  int j;
  double bet,*gam;
  gam = malloc((n+1)*sizeof(double));
  if (gam==NULL) return MEMORY ALLOCATION FAILURE;
 memset(gam,0,(n+1)*sizeof(double));
 u[1]=r[1]/(bet=b[1]);
  for (j=2; j <= (int)n; j++){}
    gam[j]=c[j-1]/bet;
    bet=b[j]-a[j]*gam[j];
   u[j]=(r[j]-a[j]*u[j-1])/bet;
  }
  for (j=(n-1);j>=1;j--) u[j]-=gam[j+1]*u[j+1];
  free(gam);
 return OK;
}
/* ----- */
double calc_int(int nodes, double *weight, double *pu){
  int i;
```

```
double somma;
  somma=0.0;
  for (i=0;i<nodes;i++, pu++)</pre>
    somma += weight[i]* *pu;
 return somma;
}
int d1_intcomp(int nodes, double h, double *weight, double *jd
    ensity,int int_method){
  int i;
  switch (int_method) {
  case TR:
    for (i=0;i<nodes-1;i++){
      int_trapez(h,&jdensity[i],&weight[i]);
    }
    break;
  case SIMP:
    for (i=0;i<nodes-2;i++){
      int_simp(h,&jdensity[i],&weight[i]);
   break;
  case NC4:
    for (i=0;i<nodes-3;i++){
      int_nc4(h,&jdensity[i],&weight[i]);
    }
    break;
  case NC6:
    for (i=0;i<nodes-5;i++){
      int nc6(h,&jdensity[i],&weight[i]);
    }
    break;
  default:
    /*nerror("Error in d1_intcomp, varible int_method not
    define{n",1);*/}
    break;
  }
 return RETURNOK;
```

```
}
/* ----- */
int int trapez(REAL h,REAL *d,REAL *p){
 *p += h/2.0* *d;
 *(p+1) += h/2.0* *(d+1);
 return RETURNOK;
int int_simp(REAL h,REAL *d,REAL *p){
  *p += h/6.0* *d;
  *(p+1) += 4.0*h/6.0* *(d+1);
  *(p+2) += h/6.0* *(d+2);
 return RETURNOK;
}
int int_nc4(REAL h,REAL *d,REAL *p){
  *p += 3.0*h/8.0* *d;
  *(p+1) += 9.0*h/8.0* *(d+1);
  *(p+2) += 9.0*h/8.0* *(d+2);
  *(p+3) += 3.0*h/8.0* *(d+3);
 return RETURNOK;
}
int int_nc6(REAL h,REAL *d,REAL *p){
  *p += 5.0*19.0*h/288.0* *d;
  *(p+1) += 5.0*75.0*h/288.0* *(d+1);
  *(p+2) += 5.0*50.0*h/288.0* *(d+2);
  *(p+3) += 5.0*50.0*h/288.0* *(d+3);
  *(p+4) += 5.0*75.0*h/288.0* *(d+4);
  *(p+5) += 5.0*19.0*h/288.0* *(d+5);
 return RETURNOK;
}
/* ----- */
/* Numerical Recipes (p. 507) FFT */
void dfour1(double *data, unsigned long nn, int isign)
```

```
/* Replace data[1..2*nn] by its Fourier transform, if is
    ign is input as 1; or replace data[1..2*nn] by nn times its
     inverse discrete Fourier tranform, if isign is input as -
    1. data is a complex array of length nn, or, equivalently,
     a real array of length 2*nn. nn must be an integer power
    of 2 (this is not checked for!). */
{
 unsigned long n,mmax,m,j,istep,i;
  double wtemp, wr, wpr, wpi, wi, theta;
  double tempr, tempi;
  n=nn \ll 1;
  j=1;
  for (i=1;i< n;i+=2) {
    if (j > i) {
      SWAP(data[j],data[i]);
      SWAP(data[j+1],data[i+1]);
    }
    m=n \gg 1;
    while (m \ge 2 \&\& j > m) \{
      j = m;
      m >>= 1;
    j += m;
  mmax=2;
  while (n > mmax) {
    istep=mmax << 1;</pre>
    theta=isign*(6.28318530717959/mmax);
    wtemp=sin(0.5*theta);
    wpr = -2.0*wtemp*wtemp;
    wpi=sin(theta);
    wr=1.0;
    wi=0.0;
    for (m=1; m < mmax; m+=2) {
      for (i=m;i<=n;i+=istep) {</pre>
        j=i+mmax;
        tempr=wr*data[j]-wi*data[j+1];
        tempi=wr*data[j+1]+wi*data[j];
        data[j]=data[i]-tempr;
        data[j+1]=data[i+1]-tempi;
```

```
data[i] += tempr;
       data[i+1] += tempi;
      wr=(wtemp=wr)*wpr-wi*wpi+wr;
      wi=wi*wpr+wtemp*wpi+wi;
   mmax=istep;
  }
}
/* ----- */
/* Numerical Recipes (p. 543) - Convolution and Deconvolut
    ion using FFT */
void drealft(double *data, unsigned long n, int isign)
  /* Calculates the Fourier trasform of a set of n real-val
    ued data points. Replaces this data (which is stored in ar
    ray data[1..n]) by the positive frequency half of its
    complex Fourier transform. The real-valued first and last compone
    nts of the complex trasform are returned as elements data[1
    ] and data[2], respectively. n must be a power of 2. This
    routine also calculates the inverse trasformation of a
    complex data array if it is the trasform of real data. (Result
    in this case must be multiplied by 2/n) */
{
  unsigned long i,i1,i2,i3,i4,np3;
  double c1=0.5,c2,h1r,h1i,h2r,h2i;
  double wr,wi,wpr,wpi,wtemp,theta;
  theta=3.141592653589793/(double) (n>>1);
  if (isign == 1) {
    c2 = -0.5;
    dfour1(data,n>>1,1);
  } else {
    c2=0.5:
    theta = -theta;
  wtemp=sin(0.5*theta);
  wpr = -2.0*wtemp*wtemp;
  wpi=sin(theta);
```

```
wr=1.0+wpr;
  wi=wpi;
 np3=n+3;
  for (i=2; i <= (n>>2); i++) {
    i4=1+(i3=np3-(i2=1+(i1=i+i-1)));
    h1r=c1*(data[i1]+data[i3]);
    h1i=c1*(data[i2]-data[i4]);
   h2r = -c2*(data[i2]+data[i4]);
    h2i=c2*(data[i1]-data[i3]);
    data[i1]=h1r+wr*h2r-wi*h2i;
    data[i2]=h1i+wr*h2i+wi*h2r;
    data[i3]=h1r-wr*h2r+wi*h2i;
    data[i4] = -h1i+wr*h2i+wi*h2r;
    wr=(wtemp=wr)*wpr-wi*wpi+wr;
    wi=wi*wpr+wtemp*wpi+wi;
  if (isign == 1) {
    data[1] = (h1r=data[1])+data[2];
    data[2] = h1r-data[2];
  } else {
    data[1]=c1*((h1r=data[1])+data[2]);
    data[2]=c1*(h1r-data[2]);
   dfour1(data,n>>1,-1);
}
/* ----- */
/* Numerical Recipes (p. 511) */
/* Given two real input arrays data1[1..n] and data2[1..n],
    this routin calls four1 and returns two complex output ar
    rays fft1[1..2n] and fft2[1..2n], each of complex length n
    (i.e. real lenght 2*n), which contain the discrete Fourie
    r transforms of the respective data arrays. n must be an
    integer power of 2. */
/* void dtwofft(double *data1, double *data2, double *fft1,
    double *fft2, unsigned long n)
unsigned long nn3,nn2,jj,j;
 double rep, rem, aip, aim;
```

```
nn3=1+(nn2=2+n+n);
for (j=1,jj=2;j\leq n;j++,jj+=2) {
fft1[jj-1]=data1[j];
fft1[jj]=data2[j];
dfour1(fft1,n,1);
fft2[1]=fft1[2];
fft1[2]=fft2[2]=0.0;
for (j=3; j<=n+1; j+=2) {
rep=0.5*(fft1[j]+fft1[nn2-j]);
rem=0.5*(fft1[j]-fft1[nn2-j]);
aip=0.5*(fft1[j+1]+fft1[nn3-j]);
aim=0.5*(fft1[j+1]-fft1[nn3-j]);
fft1[j]=rep;
fft1[j+1]=aim;
fft1[nn2-j]=rep;
fft1[nn3-j] = -aim;
fft2[j]=aip;
fft2[j+1] = -rem;
fft2[nn2-j]=aip;
fft2[nn3-j]=rem;
}
*/
/* ----- */
/* Numerical Recipes (p. 546) - Correlation */
/*Computes the correlation of two real data set data1[], da
   ta2[] (including any user-supplied pudding). n must be an
   integer power of two. The answer is returned as the first n po
   ints in ans[1..2*n] stored in wrap-around order, i.e.,
   correlations at increasingly negative lags are in ans[n] on down to an
   s[n/2+1], while correlations at increasingly positive lags
   are in ans[1] (zero lag) on up to ans[n/2]. Note that ans
   must be supplied in the calling program with length at lea
   st 2*n, since it is also used as working space. Sign convent
   ion of this routine: if data1 lags data2, i.e., is shifted
   to the right of it, then ans will show a peak at positive
   lags. */
/* int dcorrel(double *data1, double *data2, unsigned long
   n, double *ans)
```

```
{
unsigned long no2,i,nap;
double dum,*fft;
nap = n << 1;
fft= malloc((size_t) ((nap+1)*sizeof(double)));
if (fft==NULL) return MEMORY_ALLOCATION_FAILURE;
memset(fft,0,(nap+1)*sizeof(double));
dtwofft(data1,data2,fft,ans,n);
no2=n>>1;
for (i=2;i<=n+2;i+=2) {
ans[i-1]=(fft[i-1]*(dum=ans[i-1])+fft[i]*ans[i])/no2;
ans[i]=(fft[i]*dum-fft[i-1]*ans[i])/no2;
}
ans[2]=ans[n+1];
drealft(ans,n,-1);
free(fft);
return OK;
}
*/
```

## References