

Help

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#include "bs2d_std2d.h"
#include "error_msg.h"
#define PRECISION 1.0e-7 /*Precision for the localization
    of FD methods*/

static int howard_amer2(double s1,double s2,NumFunc_2 *p,
    double t,double r,double divid1,double divid2,double sigma1,
    double sigma2,double rho,int N, int M,double epsilon,double *pt
    price,double *ptdelta1,double *ptdelta2)
{
    double k,h,x1,x2,sigma11,sigma21,sigma22,m1,m2,trend1,trend2,limit,aa,bb,error,error2,temp,g0,g1;
    double **P,**Obst,**G,**R,**A,**B,**Q;
    int Index,TimeIndex,i,j;
    int **pp;

    /*Memory Allocation*/
    P=(double **)calloc(N+1,sizeof(double *));
    if (P==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
    {
        P[i]=(double *)calloc(N+1,sizeof(double));
        if (P[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    R=(double **)calloc(N+1,sizeof(double *));
    if (R==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
    {
        R[i]=(double *)calloc(N+1,sizeof(double));
        if (R[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }
}

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Obst=(double **)calloc(N+1,sizeof(double *));
if (Obst==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    Obst[i]=(double *)calloc(N+1,sizeof(double));
    if (Obst[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}
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pp=(int **)calloc(N+1,sizeof(int *));
if (pp==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    pp[i]=(int *)calloc(N+1,sizeof(int));
    if (pp[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}
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G=(double **)calloc(N+1,sizeof(double *));
if (G==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    G[i]=(double *)calloc(N+1,sizeof(double));
    if (G[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}
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A=(double **)calloc(N+1,sizeof(double *));
if (A==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    A[i]=(double *)calloc(N+1,sizeof(double));
    if (A[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}
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B=(double **)calloc(N+1,sizeof(double *));
if (B==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    B[i]=(double *)calloc(N+1,sizeof(double));
    if (B[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

Q=(double **)calloc(N+1,sizeof(double *));
if (Q==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    Q[i]=(double *)calloc(N+1,sizeof(double));
    if (Q[i]==NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

/*Covariance Matrix*/
sigma11=sigma1;
//sigma12=0.0;
sigma21=rho*sigma2;
sigma22=sigma2*sqrt(1.0-SQR(rho));

m1=(r-divid1)-SQR(sigma11)/2.0;
m2=(r-divid2)-(SQR(sigma21)+SQR(sigma22))/2.0;

/*Space Localisation*/
limit=sqrt(t)*sqrt(log(1/PRECISION));
h=2*limit/(double)N;

/*Time Step*/
k=t/(double)M;
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/*Terminal Values*/
x1=log(s1);
x2=log(s2);
trend1=exp(x1+m1*t);
trend2=exp(x2+m2*t);

for (i=1;i<N;i++)
    for (j=1;j<N;j++)
    {
P[i][j]=(p->Compute)(p->Par,trend1*exp(sigma11*(-limit+
    h*(double)j)),trend2*exp(sigma21*(-limit+h*(double)j)+sigma
    22*(limit-h*(double)i)));
    }

/*Homegenous Dirichlet Conditions*/
for(i=0;i<=N;i++)
{
    P[i][0]=0.;
    P[i][N]=0.;
    P[0][i]=0.;
    P[N][i]=0.;
}

/*Factor*/
aa=1+2.*k/(h*h)+r*k;
bb=-0.5*k/(h*h);

/*Finite Difference Cycle*/
for (TimeIndex=1;TimeIndex<M+1;TimeIndex++)
{
    trend1=exp(x1+m1*(t-TimeIndex*k));
    trend2=exp(x2+m2*(t-TimeIndex*k));

    for (i=1;i<N;i++)
for (j=1;j<N;j++)
    Obst[i][j]=(p->Compute)(p->Par,trend1*exp(sigma11*(-    limit+h*(double)j)),
    sigma22*(limit-h*(double)i)));

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        /*Init pp and R*/
        for (i=0;i<=N;i++)
for (j=0;j<=N;j++)
    {
        pp[i][j]=0;
        R[i][j]=-P[i][j];
    }
    /*Howard Cycle*/
    do
{
    error=0.;

    for (i=1;i<N;i++)
        for (j=1;j<N;j++)
            {
                Q[i][j]=P[i][j];
                g0=P[i][j]*aa+(P[i+1][j]+P[i-1][j]+P[i][j+1]+P[i][j-1])
                *bb+R[i][j];
                g1=P[i][j]-Obst[i][j];
                if (g0<g1) pp[i][j]=0;else pp[i][j]=1;
            }

    for (i=1;i<N;i++)
        for (j=1;j<N;j++)
            {
                if (pp[i][j]==0)
                {
                    G[i][j]=-R[i][j];A[i][j]=aa;B[i][j]=bb;
                }
                else {G[i][j]=Obst[i][j];A[i][j]=1;B[i][j]=0.;}
            }

    /*Solve the system*/
    do
    {
        error2=0.;
        for (i=1;i<N;i++)
for (j=1;j<N;j++)
        {
            temp=P[i][j];

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        P[i][j]=(-(P[i+1][j]+P[i-1][j]+P[i][j+1]+P[i][j-1]
    ]) * B[i][j] + G[i][j]) / A[i][j];
        error2 += fabs(P[i][j] - temp);
    }
}
while (error2 > epsilon);

for (i=1; i<N; i++)
    for (j=1; j<N; j++)
        error += fabs(P[i][j] - Q[i][j]);

}
while (error > epsilon);
/*End Howard Cycle*/
}
/*End Finite Difference Cycle*/

Index = (int)((double)N/2.0);

/*Price*/
*ptprice = P[Index][Index];

/*Deltas*/
*ptdelta2 = (P[Index-1][Index] - P[Index+1][Index]) / (2.*s2*h*
    sigma22);
*ptdelta1 = ((P[Index][Index+1] - P[Index][Index-1]) / (2.*s1*
    h) - sigma21 * (*ptdelta2)) / sigma11;

/*Memory desallocation*/
for (i=0; i<N+1; i++)
    free(P[i]);
free(P);

for (i=0; i<N+1; i++)
    free(R[i]);
free(R);

for (i=0; i<N+1; i++)
    free(Obst[i]);

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    free(Obst);

    for (i=0;i<N+1;i++)
        free(pp[i]);
    free(pp);

    for (i=0;i<N+1;i++)
        free(G[i]);
    free(G);

    for (i=0;i<N+1;i++)
        free(Q[i]);
    free(Q);

    for (i=0;i<N+1;i++)
        free(A[i]);
    free(A);

    for (i=0;i<N+1;i++)
        free(B[i]);
    free(B);

    return OK;
}

int CALC(FD_Howard)(void *Opt,void *Mod,PricingMethod *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid1,divid2;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid1=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.);
    divid2=log(1.+ptMod->Divid2.Val.V_DOUBLE/100.);

    return howard_amer2(ptMod->S01.Val.V_PDOUBLE,ptMod->S02.

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Val.V_PDDOUBLE,ptOpt->PayOff.Val.V_NUMFUNC_2,
    ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.V_DATE,
r,divid1,divid2,
    ptMod->Sigma1.Val.V_PDDOUBLE,ptMod->Sigma2.Val.
V_PDDOUBLE,ptMod->Rho.Val.V_RGDOUBLE,
    Met->Par[0].Val.V_INT,Met->Par[1].Val.V_INT,
Met->Par[2].Val.V_RGDOUBLE,
    &(Met->Res[0].Val.V_DOUBLE),&(Met->Res[1].Val.
V_DOUBLE),&(Met->Res[2].Val.V_DOUBLE) );
}

```

```

static int CHK_OPT(FD_Howard)(void *Opt, void *Mod)
{
    Option* ptOpt=(Option*)Opt;
    TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);

    if ((opt->EuOrAm). Val.V_BOOL==AMER)
        return OK;

    return WRONG;
}

```

```

static int MET(Init)(PricingMethod *Met,Option *Opt)
{
    if ( Met->init == 0)
    {
        Met->init=1;

        Met->Par[0].Val.V_INT2=80;
        Met->Par[1].Val.V_INT2=80;
        Met->Par[2].Val.V_RGDOUBLE=0.000001;

    }

    return OK;
}

```



```

PricingMethod MET(FD_Howard)=
{
    "FD_Howard2d",
    {"SpaceStep",INT2,{100},ALLOW},{"TimeStep",INT2,{100},
        ALLOW}, {"Epsilon",RGDOUBLE,{100},ALLOW} ,{" ",PREMIA_NULLT
        YPE,{0},FORBID}},
    CALC(FD_Howard),
    {"Price",DOUBLE,{100},FORBID},{"Delta1",DOUBLE,{100},FO
        RBID} ,{"Delta2",DOUBLE,{100},FORBID} ,
        {" ",PREMIA_NULLTYPE,{0},FORBID}},
    CHK_OPT(FD_Howard),
    CHK_ok,
    MET(Init)
};

```

References