```
Help
#include<stdlib.h>
#include<math.h>
#include"pnl/pnl random.h"
#include"pnl/pnl specfun.h"
#include"pnl/pnl mathtools.h"
#include "nig1d_pad.h"
#if defined(PremiaCurrentVersion) && PremiaCurrentVersion <</pre>
     (2011+2) //The "#else" part of the code will be freely av
    ailable after the (year of creation of this file + 2)
static int CHK OPT(MC NIG FloatingAsian)(void *Opt, void *
    Mod)
{
  return NONACTIVE;
int CALC(MC NIG FloatingAsian)(void*Opt,void *Mod,Pricing
    Method *Met)
  return AVAILABLE IN FULL PREMIA;
}
//Compute the positive or negative jump size between the sm
    allest and the biggest value of cdf jump points of the NIG
    process
static double jump generator NIG(double* cdf jump vect,
    double* cdf jump points, int cdf jump vect size, double alpha,
    double beta, int generator)
{
   double z, v, y;
   int test,temp,l,j,q;
   test=0;
   v=pnl rand uni(generator);
   y=cdf_jump_vect[cdf_jump_vect_size]*v;
   l=cdf_jump_vect_size/2;
   j=cdf_jump_vect_size;
   z=0;
   if(cdf_jump_vect[1]>y)
   {
    1=0;
    j=cdf_jump_vect_size/2;
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```
}
                if(v==1)
                {
                           z=cdf_jump_points[cdf_jump_vect_size];
                }
                if(v==0)
                     z=cdf_jump_points[0];
                if(v!=1 \&\& v!=0)
                     while(test==0)
                           if(cdf_jump_vect[l+1]>y)
                               q=1;
                               test=1;
                           }
                           else
                           {
                               temp=(j-1-1)/2+1;
                                if(cdf_jump_vect[temp]>y)
                                    j=temp;
                                    1=1+1;
                                }
                                else
                                     l=temp*(temp>l)+(l+1)*(temp<=l);</pre>
                               }
                           }
                     z = pow(1./cdf_jump_points[q] - (y-cdf_jump_vect[q]) * exp(-df_jump_vect[q]) * exp(-df_jump_vect[q])
                     beta*cdf\_jump\_points[q])/(pnl\_bessel\_k(1.,alpha*cdf\_jump\_po
                     ints[q])*cdf_jump_points[q]),-1.);
                }
    return z;
//(\exp(x)-1)/x
static double p_func(double x)
{
```

}

```
double s;
 int i,n;
 n=1;
 s=0;
 for(i=0;i<=n;i++)
   s+=pow(x,i)/pnl_fact(i+1);
 return s;
//(4\exp(x)+(2x-3)\exp(2x)-1)/x^3
static double var func(double x)
{
 double s;
 int i,n;
 n=1;
 s=0;
 for(i=0;i<=n;i++)
   s+=4*pow(x,i)/pnl_fact(i+3)-3*pow(2.,i+3)*pow(x,i)/pnl_
    fact(i+3)+pow(2.,i+3)*pow(x,i)/pnl fact(i+2);
 return s;
//\exp(x)/x-(\exp(x)-1)/x^2
static double cov func(double x)
{
 double s;
 int i,n;
 n=1;
 s=0;
 for(i=0;i<=n;i++)
   s+=pow(x,i)*(1./pnl_fact(i+1)-1./pnl_fact(i+2));
 return s;
}
static int NIG_Mc_FloatingAsian(NumFunc_2*P,double S0,double
T, double r, double divid, double sigma, double theta, double ka
    ppa,int generator,int n_paths,double *ptprice,double *
    priceerror,double *ptdelta,double *deltaerror)
```

```
{
    double eps,s,s1,s2,s3,s4,s5,s6,payoff,dpayoff,control,
    discount,w1,w2,drift,err,u,u0,z,sigma0;
    double lambda p, control expec, lambda m, cdf jump bound,
    pas,cov payoff control,var payoff,var control;
    double cor payoff control, control coef, var dpayoff, *cdf
    _jump_points,*cdf_jump_vect p;
    double *cdf jump vect m,*Xg,*Xd,tau,*jump time vect,*
    jump_time_vect_p,*jump_time_vect_m;
    double alpha,beta,delta,var_temp,cov_temp,*vect_temp,g_
    temp;
    int i,j,k,jump number p,jump number m,jump number,m1,m2
    ,cdf_jump_vect_size,n_int,k1,k2;
    n_int=10000;
    discount=exp(-r*T);
    err=1E-16;
    eps=0.1;
    cdf_jump_vect_size=100000;
    if(r-divid!=0)
     control expec=S0*(exp((r-divid)*T)-1)/((r-divid)*T);
    else
     control_expec=S0;
    s=0;
    s1=0;
    s2=0;
    s3=0;
    s4=0;
    s5=0;
    s6=0;
    alpha=sqrt(theta*theta+sigma*sigma/kappa)/(sigma*sigma)
    beta=theta/(sigma*sigma);
    delta=sigma/sqrt(kappa);
    if(alpha-fabs(beta)<1)
    printf("Function NIG Mc FloatingAsian: invalid para
    meters. We must have sqrt(kappa)*(2*fabs(theta)+sigma*sigma)<
    =1{n''};
    while(delta*exp(-fabs(beta)*eps)/(M PI*eps)<10)</pre>
      eps=eps*0.9;
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```
cdf_jump_bound=1;
   //Computation of the biggest jump that we tolerate
   while(2*sqrt(alpha/(2*M PI))*delta*exp(-(alpha-fabs(bet
   a))*cdf jump bound)/((alpha-fabs(beta))*pow(cdf jump bound,
   1.5))>err)
     cdf jump bound++;
   pas=(cdf_jump_bound-eps)/cdf_jump_vect_size;
   cdf_jump_points=malloc((cdf_jump_vect_size+1)*sizeof(
   double));
   cdf jump vect p=malloc((cdf jump vect size+1)*sizeof(
   double));
   cdf jump vect m=malloc((cdf jump vect size+1)*sizeof(
   double));
   cdf_jump_points[0]=eps;
   cdf jump vect p[0]=0;
   cdf jump vect m[0]=0;
   //computation of the cdf of the positive and negative
   jumps at some points
   for(i=1;i<=cdf jump vect size;i++)</pre>
    cdf_jump_points[i]=i*pas+eps;
    cdf jump vect p[i]=cdf jump vect p[i-1]+exp(beta*cdf
   jump_points[i-1])*cdf_jump_points[i-1]*pnl_bessel_k(1.,alpha*
   cdf jump points[i-1])*(1/cdf jump points[i-1]-1/cdf jump po
   ints[i]);
    cdf_jump_vect_m[i] = cdf_jump_vect_m[i-1] + exp(-beta*cdf_
   jump points[i-1])*cdf jump points[i-1]*pnl bessel k(1.,alpha*
   cdf_jump_points[i-1])*(1/cdf_jump_points[i-1]-1/cdf_jump_po
   ints[i]);
   }
   lambda_p=cdf_jump_vect_p[cdf_jump_vect_size]*alpha*delt
   lambda m=cdf jump vect m[cdf jump vect size]*alpha*delt
   a/M PI;
sigma0=0;
   for(i=1;i<=n int;i++)</pre>
    sigma0+=(eps*i/n_int)*cosh(beta*i*eps/n_int)*pnl_bess
   el_k(1.,alpha*i*eps/n_int)*eps/n_int;
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```
sigma0=sqrt(sigma0*alpha*delta*2/M PI);
   drift=0:
   for(i=1;i<=n int;i++)</pre>
    drift+=sinh(beta*i*eps/n int)*pnl bessel k(1.,alpha*i*
   eps/n int)*eps/n int;
  drift=drift*alpha*delta*2/M PI+(r-divid)-delta*(sqrt(alp
   ha*alpha-beta*beta)-sqrt(alpha*alpha-(beta+1)*(beta+1)));
m1=(int)(1000*lambda p*T);
   m2=(int)(1000*lambda m*T);
   jump time vect p=malloc((m1)*sizeof(double));
   jump time vect m=malloc((m2)*sizeof(double));
   jump time vect=malloc((m1+m2)*sizeof(double));
   vect temp=malloc((m1+m2)*sizeof(double));
   jump_time_vect_p[0]=0;
   jump_time_vect_m[0]=0;
   jump time vect[0]=0;
   vect temp[0]=0;
   Xg=malloc((m1+m2)*sizeof(double));//left value of X at
   jump times
   Xd=malloc((m1+m2)*sizeof(double));//right value of X
   at jump times
   Xg[0]=0;
   Xd[0]=0;
pnl_rand_init(generator,1,n_paths);
   /*Call Case*/
   if((P->Compute)==&Call StrikeSpot2)
      for(i=0;i<n_paths;i++)</pre>
       {
        //simulation of the positive jump times and number
        tau=-(1/lambda p)*log(pnl rand uni(generator));
        jump number p=0;
        while(tau<T)</pre>
         jump_number_p++;
         jump_time_vect_p[jump_number_p]=tau;
         tau+=-1/(lambda p)*log(pnl rand uni(generator));
        //simulation of the negative jump times and numb
```

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er
                               tau=-(1/lambda m)*log(pnl rand uni(generator));
                               jump_number_m=0;
                              while(tau<T)</pre>
                                  jump_number_m++;
                                  jump_time_vect_m[jump_number_m]=tau;
                                  tau+=-1/(lambda m)*log(pnl rand uni(generator));
                               jump_time_vect_p[jump_number_p+1]=T;
                               jump_time_vect_m[jump_number_m+1]=T;
                               jump number=jump number p+jump number m;
//
                               //computation of Xg and Xd
                       k1=1;
                       k2=1:
                       u0=0;
                              u=0;
                       for(k=1;k<=jump number;k++)</pre>
                           w1=jump_time_vect_p[k1];
                           w2=jump_time_vect_m[k2];
                           if(w1<w2)
                           {
                              u=w1;
                              k1++;
                                     z=jump_generator_NIG(cdf_jump_vect_p,cdf_jump_po
             ints,cdf_jump_vect_size,alpha,beta,generator);
                           else
                           {
                              u=w2;
                              k2++;
                              z=-jump_generator_NIG(cdf_jump_vect_m,cdf_jump_po
             ints,cdf_jump_vect_size,alpha,-beta,generator);
                           }
                                  g_temp=pnl_rand_normal(generator);
                                  if(fabs(drift*(u-u0))<1e-4)</pre>
                                  {
                                     var_temp=(u-u0)*(u-u0)*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(drift*(u-u0)*var_func(dri
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```
u0))/2;
                              cov temp=(u-u0)*(u-u0)*cov func(drift*(u-u0));
                           }
                           else
                           {
                              var_temp=(4*exp(drift*(u-u0))+(2*drift*(u-u0)-3)
           *exp(2*drift*(u-u0))-1)/(2*drift*drift*drift);
                              cov temp=(u-u0)*exp(drift*(u-u0))/drift-(exp(dr
          ift*(u-u0))-1)/(drift*drift);
                           }
                      jump time vect[k]=u;
                           vect_temp[k]=cov_temp*g_temp/(sqrt(u-u0))+sqrt(
          var_temp-cov_temp*cov_temp/(u-u0))*pnl_rand_normal(generator);
                      Xg[k]=drift*(u-u0)+sigma0*g_temp*sqrt(u-u0)+Xd[k-1]
          ];
                     Xd[k]=Xg[k]+z;
                     u0=u;
                   }
                        g temp=pnl rand normal(generator);
                        if(fabs(drift*(T-u0))<1e-4)</pre>
                           var temp=(T-u0)*(T-u0)*(T-u0)*var func(drift*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u0)*(T-u
          u0))/2;
                           cov_temp=(T-u0)*(T-u0)*cov_func(drift*(T-u0));
                         }
                        else
                           var temp=(4*exp(drift*(T-u0))+(2*drift*(T-u0)-3)*
          exp(2*drift*(T-u0))-1)/(2*drift*drift*drift);
                           cov temp=(T-u0)*exp(drift*(T-u0))/drift-(exp(drif
          t*(T-u0))-1)/(drift*drift);
                   jump_time_vect[jump_number+1]=T;
                        vect temp[jump number+1]=cov temp*g temp/(sqrt(T-
          u0))+sqrt(var_temp-cov_temp*cov_temp/(T-u0))*pnl_rand_nor
          mal(generator);
                   Xg[jump_number+1]=drift*(T-u0)+sigma0*g_temp*sqrt(
          T-u0)+Xd[jump number];
                   Xd[jump_number+1] = Xg[jump_number+1];
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//computation of the payoff
     payoff=0;
     for(j=1;j<=jump number+1;j++)</pre>
      if(fabs(drift*(jump time vect[j]-jump time vect[
j-1]))<1e-4)
       payoff+=exp(Xd[j-1])*(p func(drift*(jump time v
ect[j]-jump_time_vect[j-1]))*(jump_time_vect[j]-jump_time_v
ect[j-1])+sigma0*vect_temp[j]);
      else
       payoff+=exp(Xd[j-1])*((exp(drift*(jump time vec
t[j]-jump_time_vect[j-1]))-1)/drift+sigma0*vect_temp[j]);
     control=S0*payoff/T;
     dpayoff=discount*(exp(Xd[jump number+1])-payoff/T)
*(payoff/T<exp(Xd[jump_number+1]));
     payoff=discount*(S0*exp(Xd[jump_number+1])-S0*payo
ff/T)*(payoff/T<exp(Xd[jump number+1]));</pre>
     s1+=payoff;
     s+=payoff*payoff;
     s2+=control;
     s3+=control*control;
     s4+=control*payoff;
     s5+=dpayoff;
     s6+=dpayoff*dpayoff;
    cov payoff control=s4/n paths-s1*s2/((double)n
paths*n paths);
    var payoff=(s-s1*s1/((double)n paths))/(n paths-1);
    var control=(s3-s2*s2/((double)n paths))/(n paths-1
);
    cor_payoff_control=cov_payoff_control/(sqrt(var pay
off)*sqrt(var control));
    control coef=cov payoff control/var control;
    var_dpayoff=(s6-s5*s5/((double)n_paths))/(n_paths-1
);
    *ptprice=(s1/n paths-control coef*(s2/n paths-contr
ol_expec));
    *priceerror=1.96*sqrt(var_payoff*(1-cor_payoff_
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```
control*cor payoff control))/sqrt(n paths);
       *ptdelta=s5/(n paths);
       *deltaerror=1.96*sqrt(var_dpayoff)/sqrt(n_paths);
      }
  /*Put case*/
   if((P->Compute) ==&Put_StrikeSpot2)
      for(i=0;i<n paths;i++)</pre>
       {
        //simulation of the positive jump times and number
        tau=-(1/lambda p)*log(pnl rand uni(generator));
        jump number p=0;
        while(tau<T)
        {
         jump_number_p++;
         jump_time_vect_p[jump_number_p]=tau;
         tau+=-1/(lambda_p)*log(pnl_rand_uni(generator));
        //simulation of the negative jump times and numb
   er
        tau=-(1/lambda_m)*log(pnl_rand_uni(generator));
        jump number m=0;
        while(tau<T)
         jump_number_m++;
         jump time vect m[jump number m]=tau;
         tau+=-1/(lambda m)*log(pnl rand uni(generator));
        jump_time_vect_p[jump_number_p+1]=T;
        jump time vect m[jump number m+1]=T;
        jump number=jump number p+jump number m;
//computation of Xg and Xd
      k1=1;
      k2=1;
      u0=0;
        u=0;
      for(k=1;k<=jump number;k++)</pre>
      {
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```
w1=jump time vect p[k1];
            w2=jump time vect m[k2];
             if(w1<w2)
             {
                u=w1;
               k1++;
                       z=jump_generator_NIG(cdf_jump_vect_p,cdf_jump_po
ints,cdf jump vect size,alpha,beta,generator);
             }
             else
             {
                u=w2;
                k2++;
                z=-jump_generator_NIG(cdf_jump_vect_m,cdf_jump_po
ints,cdf_jump_vect_size,alpha,-beta,generator);
                   g temp=pnl rand normal(generator);
                    if(fabs(drift*(u-u0))<1e-4)</pre>
                      var temp=(u-u0)*(u-u0)*(u-u0)*var func(drift*(u-u0)*var func(dri
u0))/2;
                      cov_temp=(u-u0)*(u-u0)*cov_func(drift*(u-u0));
                    }
                   else
                    {
                       var temp=(4*exp(drift*(u-u0))+(2*drift*(u-u0)-3)
*exp(2*drift*(u-u0))-1)/(2*drift*drift*drift);
                       cov temp=(u-u0)*exp(drift*(u-u0))/drift-(exp(dr
ift*(u-u0))-1)/(drift*drift);
                   }
             jump time vect[k]=u;
                    vect_temp[k]=cov_temp*g_temp/(sqrt(u-u0))+sqrt(
var_temp-cov_temp*cov_temp/(u-u0))*pnl_rand_normal(generator);
            Xg[k]=drift*(u-u0)+sigma0*g_temp*sqrt(u-u0)+Xd[k-1]
];
            Xd[k]=Xg[k]+z;
            u0=u;
         }
                g_temp=pnl_rand_normal(generator);
                if(fabs(drift*(T-u0))<1e-4)</pre>
```

```
{
                          var temp=(T-u0)*(T-u0)*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(drift*(T-u0)*var_func(dri
          u0))/2;
                          cov temp=(T-u0)*(T-u0)*cov func(drift*(T-u0));
                        }
                       else
                          var temp=(4*exp(drift*(T-u0))+(2*drift*(T-u0)-3)*
          exp(2*drift*(T-u0))-1)/(2*drift*drift*drift);
                          cov_temp=(T-u0)*exp(drift*(T-u0))/drift-(exp(drif
          t*(T-u0))-1)/(drift*drift);
                        }
                  jump time vect[jump number+1]=T;
                        vect_temp[jump_number+1] = cov_temp*g_temp/(sqrt(T-
          u0))+sqrt(var_temp-cov_temp*cov_temp/(T-u0))*pnl_rand_nor
          mal(generator);
                  Xg[jump number+1]=drift*(T-u0)+sigma0*g temp*sqrt(
          T-u0)+Xd[jump number];
                  Xd[jump_number+1] = Xg[jump_number+1];
//computation of the payoff
                       pavoff=0;
                       for(j=1;j<=jump number+1;j++)</pre>
                          if(fabs(drift*(jump time vect[j]-jump time vect[
          j-1]))<1e-4)
                            payoff+=exp(Xd[j-1])*(p func(drift*(jump time v
          ect[j]-jump_time_vect[j-1]))*(jump_time_vect[j]-jump_time_v
          ect[j-1])+sigma0*vect_temp[j]);
                          else
                            payoff+=exp(Xd[j-1])*((exp(drift*(jump time vec
          t[j]-jump_time_vect[j-1]))-1)/drift+sigma0*vect_temp[j]);
                       control=S0*payoff/T;
                        dpayoff=discount*(exp(Xd[jump_number+1])-payoff/T)
          *(payoff/T<exp(Xd[jump_number+1]));
                       payoff=discount*(S0*exp(Xd[jump_number+1])-S0*payo
          ff/T)*(payoff/T<exp(Xd[jump number+1]));</pre>
                        s1+=payoff;
```

```
s+=payoff*payoff;
      s2+=control;
      s3+=control*control;
      s4+=control*payoff;
      s5+=dpayoff;
      s6+=dpayoff*dpayoff;
     cov payoff control=s4/n paths-s1*s2/((double)n
 paths*n paths);
     var_payoff=(s-s1*s1/((double)n_paths))/(n_paths-1);
     var control=(s3-s2*s2/((double)n paths))/(n paths-1
 );
     cor_payoff_control=cov_payoff_control/(sqrt(var_pay
 off)*sqrt(var control));
     control_coef=cov_payoff_control/var_control;
     var_dpayoff=(s6-s5*s5/((double)n_paths))/(n_paths-1
 );
     if(r!=divid)
      *ptprice=(s1/n_paths-control_coef*(s2/n_paths-
 control expec))-S0*exp(-divid*T)+S0*(exp(-divid*T)-exp(-r*T))/
 ((r-divid)*T);
     else
      *ptprice=(s1/n_paths-control_coef*(s2/n_paths-
 control expec))-S0*exp(-divid*T)+S0*exp(-r*T);
     *priceerror=1.96*sqrt(var payoff*(1-cor payoff
 control*cor payoff control))/sqrt(n paths);
     if(r!=divid)
      *ptdelta=s5/(n paths)-exp(-divid*T)+(exp(-divid*T)
 -\exp(-r*T))/((r-divid)*T);
      *ptdelta=s5/(n paths)-exp(-divid*T)+exp(-r*T);
     *deltaerror=1.96*sqrt(var dpayoff)/sqrt(n paths);
}
    free(Xd);
    free(Xg);
    free(cdf_jump_points);
    free(cdf_jump_vect_p);
    free(cdf jump vect m);
    free(jump_time_vect_p);
    free(jump_time_vect_m);
```

```
free(jump time vect);
      free(vect temp);
   return OK;
}
int CALC(MC NIG FloatingAsian)(void*Opt,void *Mod,Pricing
   Method *Met)
  TYPEOPT* ptOpt=(TYPEOPT*)Opt;
  TYPEMOD* ptMod=(TYPEMOD*)Mod;
  double r, divid;
  r=log(1.+ptMod->R.Val.V DOUBLE/100.);
  divid=log(1.+ptMod->Divid.Val.V DOUBLE/100.);
  return NIG_Mc_FloatingAsian(ptOpt->PayOff.Val.V_NUMFUNC_
   2,ptMod->S0.Val.V PDOUBLE,ptOpt->Maturity.Val.V DATE-pt
   Mod->T.Val.V_DATE,r,divid,ptMod->Sigma.Val.V_PDOUBLE,ptMod->
   Theta.Val.V_DOUBLE,ptMod->Kappa.Val.V_SPDOUBLE,Met->Par[0].
   Val.V ENUM.value, Met->Par[1].Val.V LONG, & (Met->Res[0].Val.V
   DOUBLE),&(Met->Res[1].Val.V_DOUBLE),&(Met->Res[2].Val.V_DOUBLE),
   &(Met->Res[3].Val.V_DOUBLE));
}
static int CHK_OPT(MC_NIG_FloatingAsian)(void *Opt, void *
   Mod)
  if ((strcmp(((Option*)Opt)->Name, "AsianCallFloatingEuro")
   return OK;
 return WRONG;
}
#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met,Option *Mod)
  if (Met->init == 0)
   {
     Met->init=1;
     Met->Par[0].Val.V_ENUM.value=0;
     Met->Par[0].Val.V_ENUM.members=&PremiaEnumMCRNGs;
```

```
Met->Par[1].Val.V_LONG=100000;
}
return OK;
}

PricingMethod MET(MC_NIG_FloatingAsian)=
{
    "MC_NIG_AsianFloating",
    {{"RandomGenerator",ENUM,{100},ALLOW}, {"N iterations",
        LONG,{100},ALLOW},{" ",PREMIA_NULLTYPE,{0},FORBID}}, CALC(
        MC_NIG_FloatingAsian),
    {{"Price",DOUBLE,{100},FORBID},{"Delta",DOUBLE,{100},FORB
        ID},{"Price Error",DOUBLE,{100},FORBID},{"Delta Error",
        DOUBLE,{100},FORBID},{" ",PREMIA_NULLTYPE,{0},FORBID}},
        CHK_OPT(MC_NIG_FloatingAsian),
        CHK_ok,
        MET(Init)
};
```

References