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#include "bs2d_std2d.h"
#include "error_msg.h"
#define PRECISION 1.0e-7 /*Precision for the localization
    of FD methods*/

static void init(double **g,double **u,double alpha,double
    beta,double gam,int flag,int N)
{
    int i,j;

    if (flag==1)
    {
        for(i=1;i<N;i++)
        for(j=1;j<N;j++)
            g[i][j]=alpha*u[i][j-1]+beta*u[i][j]+gam*u[i][j+1];
    }
    else
    {
        for(i=1;i<N;i++)
        for(j=1;j<N;j++)
            g[j][i]=alpha*u[j-1][i]+beta*u[j][i]+gam*u[j+1][i];
    }

    return;
}

static void swap(double **u,double **g,int N)
{
    int i,j;

    for(i=1;i<N;i++)
        for(j=1;j<N;j++)
            u[i][j]=g[i][j];

    return;
}

static int tri(double **g,double alpha,double beta,double
    gam,int flag,int N)
{
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int i,j,z;
double *c,*a,*b;

/*Memory Allocation*/
a=(double *)calloc(N+1,sizeof(double));
if (a==NULL)
    return MEMORY_ALLOCATION_FAILURE;
b=(double *)calloc(N+1,sizeof(double));
if (b==NULL)
    return MEMORY_ALLOCATION_FAILURE;
c=(double *)calloc(N+1,sizeof(double));
if (c==NULL)
    return MEMORY_ALLOCATION_FAILURE;

/*Gauss Algorithm*/
b[N-1]=beta;
for(i=N-2;i>=1;i--) b[i]=beta-gam*alpha/b[i+1];
for(i=1;i<=N-1;i++) a[i]=alpha/b[i];
for(i=1;i<N-1;i++) c[i]=gam/b[i+1];
if (flag==1) {
    for(j=1;j<N;j++)
    {
for(z=N-2;z>=1;z--)
    g[z][j]=g[z][j]-g[z+1][j]*c[z];

g[1][j]=g[1][j]/b[1];

for (z=2;z<N;z++)
    g[z][j]=(g[z][j]/b[z]-g[z-1][j]*a[z]);
    }
} else {
    for(j=1;j<N;j++)
    {
for(z=N-2;z>=1;z--)
    g[j][z]=g[j][z]-g[j][z+1]*c[z];

g[j][1]=g[j][1]/b[1];

for (z=2;z<N;z++)
    g[j][z]=(g[j][z]/b[z]-g[j][z-1]*a[z]);
    }
}

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    }
    /*Memory Desallocation*/
    free(a);
    free(b);
    free(c);

    return OK;
}

static int Adi(int am,double s1,double s2,NumFunc_2 *p,
    double t,double r,double divid1,double divid2,double sigma1,
    double sigma2,double rho,int N,int M, double *ptprice,double *pt
    delta1,double *ptdelta2)
{
    int i,j,TimeIndex,Index,flag;
    double x1,x2,sigma11,sigma21,sigma22,k,limit,h,m1,m2,trend
        nd1,trend2;
    double a1,b1,a2,b2,scan1,scan2,iv;
    double **P,**G,**temp2,*temp1;

    /*Memory Allocation*/
    P=(double**)calloc(N+1,sizeof(double*));
    if (P==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
    {
        P[i]=(double *)calloc(N+1,sizeof(double));
        if (P[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    G=(double**)calloc(N+1,sizeof(double*));
    if (G==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<N+1;i++)
    {
        G[i]=(double *)calloc(N+1,sizeof(double));
        if (G[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }
}

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temp2=(double**)calloc(N+1,sizeof(double*));
if (temp2==NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i=0;i<N+1;i++)
{
    temp2[i]=(double*)calloc(N+1,sizeof(double));
    if (temp2[i]==NULL)
return MEMORY_ALLOCATION_FAILURE;
}

temp1=(double*)calloc(N+1,sizeof(double));
if (temp1==NULL)
    return MEMORY_ALLOCATION_FAILURE;

/*Covariance Matrix*/
sigma11=sigma1;
//sigma12=0.0;
sigma21=rho*sigma2;
sigma22=sigma2*sqrt(1.0-SQR(rho));
m1=(r-divid1)-SQR(sigma11)/2.0;
m2=(r-divid2)-(SQR(sigma21)+SQR(sigma22))/2.0;

/*Space Localisation*/
limit=sqrt(t)*sqrt(log(1/PRECISION));
h=2.*limit/(double)N;

/*Time Step*/
k=t/(2.*(double)M);

/*Rhs Factor of first step*/
b1=1.-k*(1./SQR(h)+r/2.0);
a1=k/(2.0*SQR(h));

/*Lhs Factor of second step*/
b2=1.+k*(1./SQR(h)+r/2.0);
a2=-k/(2.0*SQR(h));

/*Terminal Values*/
x1=log(s1);
x2=log(s2);
trend1=exp(x1+m1*t);

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trend2=exp(x2+m2*t);
for (j=0;j<=N;j++)
    temp1[j]=exp(sigma11*(-limit+h*(double)j));
for(i=1;i<N;i++)
{
    for (j=1;j<N;j++)
    {
        temp2[i][j]=exp(sigma21*(-limit+h*(double)j)+sigma22*(limit-h*(double)i)
        P[i][j]= (p->Compute)(p->Par, trend1*temp1[j],trend2*
        temp2[i][j]);
    }
}

/*Homegenous Dirichlet Conditions*/
for(i=0;i<=N;i++)
{
    P[i][0]=0.;
    P[i][N]=0.;
    P[0][i]=0.;
    P[N][i]=0.;
}

/*Finite Difference Cycle */
scan1=exp(-m1*2.*k);
scan2=exp(-m2*2.*k);
for (TimeIndex=1;TimeIndex<=M;TimeIndex++)
{
    trend1*=scan1;
    trend2*=scan2;

    /*First Step*/
    flag=1;

    /*Init Rhs*/
    init(G,P,a1,b1,a1,flag,N);

    /*Gauss Algorithm*/
    tri(G,a2,b2,a2,flag,N);
    swap(P,G,N);

    /*Second Step*/

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    flag=2;

    /*Init Rhs*/
    init(G,P,a1,b1,a1,flag,N);

    /*Gauss Algorithm*/
    tri(G,a2,b2,a2,flag,N);
    swap(P,G,N);

    /*Splitting for the american case */
    if (am)
    {
        for(i=1;i<N;i++)
        {
            for(j=1;j<N;j++)
            {
                iv=(p->Compute)(p->Par,trend1*temp1[j],trend2*temp2
                [i][j]);
                P[i][j]=MAX(iv,P[i][j]);
            }
        }
    }

    Index=(int) ((double)N/2.0);

    /*Price*/
    *ptprice=P[Index][Index];

    /*Deltas*/
    *ptdelta2=(P[Index-1][Index]-P[Index+1][Index])/(2.*s2*h*
    sigma22);
    *ptdelta1=((P[Index][Index+1]-P[Index][Index-1])/(2.*s1*
    h)-sigma21*(s2/s1)*(ptdelta2))/sigma11;

    /*Memory desallocation*/
    for (i=0;i<N+1;i++)
        free(P[i]);
    free(P);

    for (i=0;i<N+1;i++)

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    free(G[i]);
    free(G);

    for (i=0;i<N+1;i++)
        free(temp2[i]);
    free(temp2);

    free(temp1);

    return OK;
}

int CALC(FD_Adi)(void *Opt,void *Mod,PricingMethod *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid1,divid2;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid1=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.);
    divid2=log(1.+ptMod->Divid2.Val.V_DOUBLE/100.);

    return Adi(ptOpt->EuOrAm.Val.V_BOOL,ptMod->S01.Val.V_PD0
        UBLE,ptMod->S02.Val.V_PD0UBLE,ptOpt->PayOff.Val.V_NUMFUNC_2
        ,
        ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.V_DATE,r,
        divid1,divid2,
        ptMod->Sigma1.Val.V_PD0UBLE,ptMod->Sigma2.Val.V_PD0
        UBLE,ptMod->Rho.Val.V_RGDOUBLE,
        Met->Par[0].Val.V_INT,Met->Par[1].Val.V_INT,
        &(Met->Res[0].Val.V_DOUBLE),&(Met->Res[1].Val.V_
        DOUBLE),&(Met->Res[2].Val.V_DOUBLE) );
}

static int CHK_OPT(FD_Adi)(void *Opt, void *Mod)
{
    return OK;
}

static int MET(Init)(PricingMethod *Met,Option *Opt)
{

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if ( Met->init == 0)
{
    Met->init=1;

    Met->Par[0].Val.V_INT2=100;
    Met->Par[1].Val.V_INT2=100;

}

return OK;
}

PricingMethod MET(FD_Adi)=
{
    "FD_Adi",
    {"SpaceStep",INT2,{100},ALLOW},{"TimeStep",INT2,{100},
    ALLOW} ,{" ",PREMIA_NULLTYPE,{0},FORBID}},
    CALC(FD_Adi),
    {"Price",DOUBLE,{100},FORBID},{"Delta1",DOUBLE,{100},FO
    RBID} ,{"Delta2",DOUBLE,{100},FORBID} ,
    {" ",PREMIA_NULLTYPE,{0},FORBID}},
    CHK_OPT(FD_Adi),
    CHK_ok,
    MET(Init)
};

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References