```
Help
#include <stdlib.h>
#include "bs2d_std2d.h"
#include "error_msg.h"
#include "math/mc am.h"
#include "enums.h"
static double *Mesh=NULL;
static long *Weights=NULL;
static double *Path=NULL, *Mean_Cell=NULL, *Price=NULL, *
    Transition=NULL, *PathAux=NULL;
static double *PathAuxPO=NULL, *Aux BS=NULL, *Sigma=NULL, *Aux
    _Stock=NULL;
static int BaMa_Allocation(int AL_PO_Size,int BS_Dimension,
         int OP_Exercise_Dates)
{
  if (Mesh==NULL)
    Mesh= malloc(OP_Exercise_Dates*(AL_PO_Size+1)*sizeof(
    double));
  if (Mesh==NULL) return MEMORY ALLOCATION FAILURE;
  if (Path==NULL)
    Path= malloc(OP Exercise Dates*BS Dimension*sizeof(
    double));
  if (Path==NULL)
    return MEMORY ALLOCATION FAILURE;
  if (Weights == NULL)
    Weights= malloc(OP_Exercise_Dates*AL_PO_Size*sizeof(lon
    g));
  if (Weights == NULL)
    return MEMORY_ALLOCATION_FAILURE ;
  if (Mean_Cell==NULL)
    Mean_Cell= malloc(OP_Exercise_Dates*AL_PO_Size*sizeof(
    double));
  if (Mean_Cell==NULL) return MEMORY_ALLOCATION_FAILURE;
```

```
if (Price==NULL)
 Price= malloc(OP_Exercise_Dates*AL_PO_Size*sizeof(
 double));
if (Price==NULL)
 return MEMORY ALLOCATION FAILURE;
if (Transition==NULL)
  Transition= malloc((OP_Exercise_Dates-1)*AL_PO_Size*AL_
 PO Size*sizeof(double));
if (Transition==NULL)
  return MEMORY ALLOCATION FAILURE;
if (PathAux==NULL)
 PathAux= malloc(AL_PO_Size*2*BS_Dimension*sizeof(
  double));
if (PathAux==NULL)
  return MEMORY_ALLOCATION_FAILURE;
if (PathAuxPO==NULL)
  PathAuxPO= malloc((AL PO Size+1)*sizeof(double));
if (PathAuxPO==NULL)
  return MEMORY_ALLOCATION_FAILURE;
if (Aux BS==NULL)
  Aux BS= malloc(BS Dimension*sizeof(double));
if (Aux BS==NULL)
  return MEMORY ALLOCATION FAILURE;
if (Aux Stock==NULL)
 Aux_Stock= malloc(BS_Dimension*sizeof(double));
if (Aux Stock==NULL)
 return MEMORY_ALLOCATION_FAILURE;
if (Sigma==NULL)
  Sigma= malloc(BS_Dimension*BS_Dimension*sizeof(double))
if (Sigma==NULL)
  return MEMORY_ALLOCATION_FAILURE;
```

```
return OK;
static void BaMa_Liberation()
  if (Mesh!=NULL) {
    free(Mesh);
    Mesh=NULL;
  if (Path!=NULL) {
    free(Path);
    Path=NULL;
  }
  if (Weights!=NULL) {
    free(Weights);
    Weights=NULL;
  if (Mean_Cell!=NULL) {
    free(Mean_Cell);
    Mean_Cell=NULL;
  if (Price!=NULL) {
    free(Price);
    Price=NULL;
  }
  if (Transition!=NULL) {
    free(Transition);
    Transition=NULL;
  }
  if (PathAux!=NULL) {
    free(PathAux);
    PathAux=NULL;
  }
  if (PathAuxPO!=NULL) {
```

```
free(PathAuxPO);
    PathAuxPO=NULL;
  }
  if (Aux BS!=NULL) {
    free(Aux BS);
    Aux_BS=NULL;
  }
  if (Aux_Stock!=NULL) {
    free(Aux_Stock);
    Aux Stock=NULL;
  }
  if (Sigma!=NULL) {
    free(Sigma);
    Sigma=NULL;
  }
}
/*Black-Sholes Step*/
static void BS_Forward_Step(int generator,double *Stock,
    double *Initial_Stock, int BS_Dimension,double Step,double Sqrt_
    Step)
{
  int j,k;
  double Aux;
  for (j=0;j<BS_Dimension;j++){</pre>
    Aux_Stock[j]=Sqrt_Step*pnl_rand_normal(generator);
  for (j=0;j<BS Dimension;j++){</pre>
    Aux=0.;
    for (k=0; k \le j; k++){
      Aux+=Sigma[j*BS Dimension+k]*Aux Stock[k];
    Aux-=Step*Aux_BS[j];
    Stock[j]=Initial_Stock[j]*exp(Aux);
  }
}
```

```
/*Cell Number in the mesh*/
static int Number Cell(double x, int Instant, int AL PO Si
             ze)
{
       int min=0,max=AL PO Size,j;
      do {
             j=(\max+\min)/2;
             if (x>=Mesh[Instant*(AL_PO_Size+1)+j]) {
                   min=j;
             } else {
                    max=j;
       } while (!((x>=Mesh[Instant*(AL_PO_Size+1)+j])\&\&(x<=Mesh[Instant*(AL_PO_Size+1)+j])\&\&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])&&(x<=Mesh[Instant*(AL_PO_Size+1)+j])
             Instant*(AL_PO_Size+1)+j+1])));
      return j;
}
/*Black-Sholes Path*/
static void ForwardPath(double *Path, double *Initial Stock
              , int Initial_Time,int Number_Dates,int generator,int BS_
             Dimension, double Step, double Sqrt_Step)
{
       int i,j,k;
       double aux;
       double *SigmapjmBS Dimensionpk;
       for (j=0; j<BS_Dimension; j++) Path[Initial_Time*BS_Dimens
             ion+j]=Initial_Stock[j];
       for (i=Initial Time+1;i<Initial Time+Number Dates;i++){</pre>
             for (j=0;j<BS Dimension;j++){</pre>
                    Aux Stock[j]=Sqrt_Step*pnl_rand_normal(generator);
             SigmapjmBS_Dimensionpk=Sigma;
             for (j=0; j<BS Dimension; j++){</pre>
                    aux=0.;
                    for (k=0; k<=j; k++){
```

```
aux+=(*SigmapjmBS Dimensionpk)*Aux Stock[k];
  SigmapjmBS Dimensionpk++;
      }
      SigmapjmBS_Dimensionpk+=BS_Dimension-j-1;
      aux-=Step*Aux BS[j];
      Path[i*BS Dimension+j]=Path[(i-1)*BS Dimension+j]*exp
    (aux);
    }
  }
}
static void Init Cells(int generator, NumFunc 2 *p,int BS
    Dimension, int OP_Exercise_Dates, int AL_MonteCarlo_Iteratio
    ns,int AL_PO_Size, double *BS_Spot,double Step, double Sq
    rt_Step)
{
  double auxop1,auxop2;
  int i,j,k,auxcell1,auxcell2;
  for (i=0;i<OP Exercise Dates-1;i++)</pre>
    for (j=0;j<AL PO Size;j++)</pre>
      for (k=0;k<AL_PO_Size;k++) Transition[i*AL_PO_Size*
    AL_PO_Size+j*AL_PO_Size+k]=0;
  for (i=0;i<OP_Exercise_Dates;i++)</pre>
    for (j=0;j<AL_PO_Size;j++) Mean_Cell[i*AL_PO_Size+j]=0;</pre>
  for (i=0;i<OP Exercise Dates;i++)</pre>
    for (j=0;j<AL PO Size;j++) Price[i*AL PO Size+j]=0;</pre>
  for (i=0;i<OP_Exercise_Dates;i++)</pre>
    for (j=0;j<AL_PO_Size;j++) Weights[i*AL_PO_Size+j]=0;</pre>
  for (k=0;k<AL MonteCarlo Iterations;k++){</pre>
    ForwardPath(Path,BS_Spot,0,OP_Exercise_Dates,
                                                     generator,BS_Dimension,Step
    auxop2=(p->Compute)(p->Par,*Path,*(Path+1));
    auxcell2=Number Cell(auxop2,0,AL PO Size);
    for (i=0;i<OP_Exercise_Dates-1;i++){</pre>
      auxcell1=auxcell2;
      auxop1=auxop2;
      auxop2=(p->Compute)(p->Par,*(Path+(i+1)*BS_Dimension)
```

```
,*(Path+(i+1)*BS Dimension+1));
      auxcell2=Number Cell(auxop2,i+1,AL PO Size);
      Weights[i*AL_PO_Size+auxcell1]++;
      Transition[i*AL PO Size*AL PO Size+auxcell1*AL PO Si
    ze+auxcell2]++;
      Mean Cell[i*AL PO Size+auxcell1]+=auxop1;
    auxop1=(p->Compute) (p->Par,*(Path+(OP Exercise Dates-1
    )*BS Dimension),
       *(Path+(OP Exercise_Dates-1)*BS_Dimension+1));
    auxcell1=Number_Cell(auxop1,OP_Exercise_Dates-1,AL_PO_
    Size);
    Weights[(OP Exercise Dates-1)*AL PO Size+auxcell1]++;
    Mean_Cell[(OP_Exercise_Dates-1)*AL_PO_Size+auxcell1]+=
    auxop1;
  }
}
static void InitMesh(NumFunc_2 *p,int generator,int AL_PO_
    Size, long Al PO Init, int BS Dimension, int OP Exercise Da
    tes, double *BS Spot, double Step, double Sqrt Step)
{
  int i,j,k,l;
  for (i=0;i<OP Exercise Dates*(AL PO Size+1);i++)</pre>
    Mesh[i]=0;
  for (i=0;i<Al PO Init;i++){
    for (j=0;j<AL_PO_Size;j++){</pre>
      for (k=0;k<BS Dimension;k++){</pre>
  PathAux[j*2*BS Dimension+k]=BS Spot[k];
    }
    for (j=1;j<OP Exercise Dates;j++){</pre>
      for (k=0;k<AL_PO_Size;k++){
  BS_Forward_Step(generator, PathAux+k*2*BS_Dimension+BS_
    Dimension, PathAux+k*2*BS Dimension, BS Dimension, Step, Sqrt
    Step);
      }
```

```
for (k=1;k<AL_PO_Size+1;k++){
PathAuxPO[k] = (p->Compute)(p->Par,*(PathAux+(k-1)*2*BS_
  Dimension+BS_Dimension),*(PathAux+(k-1)*2*BS_Dimension+BS_
  Dimension+1));
    }
    Sort(AL_PO_Size,PathAuxPO);
    for (k=1;k<AL_PO_Size+1;k++){
Mesh[j*(AL_PO_Size+1)+k]+=PathAuxPO[k];
    }
    for (1=0;1<AL_PO_Size;1++){
for (k=0;k<BS_Dimension;k++){</pre>
  PathAux[1*2*BS_Dimension+k] = PathAux[(1*2+1)*BS_Dimens
  ion+k];
}
    }
  }
}
for (j=1;j<OP_Exercise_Dates;j++){</pre>
  for (k=1;k<AL PO Size+1;k++){
    Mesh[j*(AL_PO_Size+1)+k]/=(double)Al_PO_Init;
  }
}
for (j=1;j<OP_Exercise_Dates;j++){</pre>
  Mesh[j*(AL_PO_Size+1)]=0;
  Mesh[(j+1)*(AL PO Size+1)-1]=DBL MAX;
  for (k=1;k<AL PO Size-1;k++)
    Mesh[j*(AL_PO_Size+1)+k] = (Mesh[j*(AL_PO_Size+1)+k]+
      Mesh[j*(AL_PO_Size+1)+k+1])*0.5;
Mesh[AL PO Size] = DBL MAX;
for (k=0; k<AL_PO_Size; k++)
  Mesh[k]=0;
```

}

```
static void BaMa(double *AL BPrice, long AL MonteCarlo Itera
    tions, NumFunc 2 *p,int AL PO Size,int AL PO Init,int AL Shut
    tingDown,int generator,int OP_Exercise_Dates,double *BS Spo
    t, double BS Maturity, double BS Interest Rate, double *div
    id, double *sigma,int gj flag)
{
  double aux,Step,Sqrt_Step,DiscountStep;
  int i, j, k;
  int BS Dimension;
  BS Dimension=2;
  /*Memory Allocation*/
  BaMa_Allocation(AL_PO_Size,BS_Dimension,OP_Exercise_Da
    tes);
  *AL BPrice=0.;
  Step=BS Maturity/(double)(OP Exercise Dates-1);
  Sqrt Step=sqrt(Step);
  DiscountStep=exp(-BS_Interest_Rate*Step);
  /*Black-Sholes initalization parameters*/
  Sigma[0] = sigma[0];
  Sigma[1]=sigma[1];
  Sigma[2] = sigma[2];
  Sigma[3]=sigma[3];
  Aux BS[0]=0.5*(SQR(sigma[0])+SQR(sigma[1]))-BS Interest
    Rate+divid[0];
  Aux BS[1]=0.5*(SQR(sigma[2])+SQR(sigma[3]))-BS Interest
    Rate+divid[1];
  /* Cells Weights and Transitions probabilities for the
    payoff mesh */
  InitMesh(p,generator,AL_PO_Size,AL_PO_Init,BS_Dimension,
    OP Exercise Dates, BS Spot, Step, Sqrt Step);
  Init Cells(generator,p,BS Dimension,OP Exercise Dates,AL
    MonteCarlo_Iterations,AL_PO_Size,BS_Spot,Step,Sqrt_Step);
  /*Initialization of the price at maturity*/
  for (k=0; k<AL PO Size; k++){
    if (Weights[(OP_Exercise_Dates-1)*AL_PO_Size+k]>0){
```

```
Price[(OP Exercise Dates-1)*AL PO Size+k]=Mean Cell[(
    OP_Exercise_Dates-1)*AL_PO_Size+k]/(double)Weights[(OP_Exerc
    ise_Dates-1)*AL_PO_Size+k];
  }
  /* Dynamical programing (backward price)*/
  for (i=OP Exercise Dates-2;i>=0;i--){
    for (k=0; k<AL PO Size; k++){
      if (Weights[i*AL_PO_Size+k]>0){
      aux=0;
      for (j=0;j<AL PO Size;j++)</pre>
        aux+=Transition[i*AL_PO_Size*AL_PO_Size+k*AL_PO_Si
    ze+j]*Price[(i+1)*AL_PO_Size+j];
  aux/=(double)Weights[i*AL_PO_Size+k];
      aux*=DiscountStep;
  if((!gj_flag) || ((gj_flag)&&(i>0)))
    Price[i*AL_PO_Size+k]=MAX(Mean_Cell[i*AL_PO_Size+k]/We
    ights[i*AL_PO_Size+k],aux);
  else
    Price[k]=aux;
      }
    }
  }
  /*Backward Price*/
  *AL BPrice=Price[Number Cell((p->Compute)(p->Par,*BS Spo
    t,*(BS_Spot+1)),0,AL_PO_Size)];
  /*Memory Disallocation*/
  if (AL_ShuttingDown){
   BaMa Liberation();
}
static int MCBarraquandMartineau2D(double s1, double s2,
    NumFunc_2 *p, double t, double r, double divid1, double divid2,
    double sigma1, double sigma2, double rho, long N, int
                                                              generator, double
    double *ptprice, double *ptdelta1, double *ptdelta2)
{
```

```
double p1,p2,p3;
int simulation dim= 1,fermeture=1,init mc;
double s_vector[2];
double s_vector_plus1[2],s_vector_plus2[2];
double sigma[4];
double divid[2];
/* Covariance Matrix */
/* Coefficients of the matrix A such that A(tA)=Gamma */
sigma[0] = sigma1;
sigma[1] = 0.0;
sigma[2] = rho*sigma2;
sigma[3] = sigma2*sqrt(1.0-SQR(rho));
/*Initialisation*/
s vector[0]=s1;
s_vector[1]=s2;
s_vector_plus1[0]=s1*(1.+inc);
s vector plus1[1]=s2;
s_vector_plus2[0]=s1;
s_vector_plus2[1]=s2*(1.+inc);
divid[0]=divid1;
divid[1]=divid2;
/*MC sampling*/
init mc= pnl rand init(generator, simulation dim, N);
/* Test after initialization for the generator */
if(init mc == OK)
  {
    /*Geske-Johnson Formulae*/
    if (exercise_date_number==0) {
BaMa(&p3,N,p,size,init,fermeture,generator,4,s vector,t,
  r, divid, sigma, 1);
BaMa(&p2,N,p,size,init,fermeture,generator,3,s_vector,t,
  r, divid, sigma, 1);
BaMa(&p1,N,p,size,init,fermeture,generator,2,s vector,t,
  r, divid, sigma, 1);
*ptprice=p3+7./2.*(p3-p2)-(p2-p1)/2.;
```

```
} else {
  BaMa(ptprice, N, p, size, init, fermeture, generator, exercise
    date_number,s_vector,t,r,divid,sigma,0);
      }
      /*Delta*/
      if (exercise_date_number==0) {
  BaMa(&p1,N,p,size,init,fermeture,generator,4,s vector pl
    us1,t,r,divid,sigma,1);
 BaMa(&p2,N,p,size,init,fermeture,generator,3,s_vector_pl
    us1,t,r,divid,sigma,1);
  BaMa(&p3,N,p,size,init,fermeture,generator,2,s vector pl
    us1,t,r,divid,sigma,1);
  *ptdelta1=((p3+7./2.*(p3-p2)-(p2-p1)/2.)-*ptprice)/(s1*)
    inc);
  BaMa(&p1,N,p,size,init,fermeture,generator,4,s vector pl
    us2,t,r,divid,sigma,1);
  BaMa(&p2,N,p,size,init,fermeture,generator,3,s_vector_pl
    us2,t,r,divid,sigma,1);
  BaMa(&p3,N,p,size,init,fermeture,generator,2,s vector pl
    us2,t,r,divid,sigma,1);
  *ptdelta2=((p3+7./2.*(p3-p2)-(p2-p1)/2.)-*ptprice)/(s2*
    inc);
      } else {
  BaMa(&p1,N,p,size,init,fermeture,generator,exercise da
    te number, s vector plus1, t, r, divid, sigma, 0);
  *ptdelta1=(p1-*ptprice)/(s1*inc);
  BaMa(&p2,N,p,size,init,fermeture,generator,exercise_da
    te_number,s_vector_plus2,t,r,divid,sigma,0);
  *ptdelta2=(p2-*ptprice)/(s2*inc);
    }
 return init mc;
int CALC(MC_BarraquandMartineau2D)(void *Opt, void *Mod,
    PricingMethod *Met)
  TYPEOPT* ptOpt=(TYPEOPT*)Opt;
```

}

{

```
TYPEMOD* ptMod=(TYPEMOD*)Mod;
  double r,divid1,divid2;
  r=log(1.+ptMod->R.Val.V DOUBLE/100.);
  divid1=log(1.+ptMod->Divid1.Val.V DOUBLE/100.);
  divid2=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.);
  return MCBarraquandMartineau2D(ptMod->S01.Val.V PDOUBLE,
         ptMod->S02.Val.V_PDOUBLE,
         ptOpt->PayOff.Val.V_NUMFUNC_2,
         ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.V_DA
    TE,
         r,
         divid1,
         divid2,
         ptMod->Sigma1.Val.V_PDOUBLE,
         ptMod->Sigma2.Val.V PDOUBLE,
         ptMod->Rho.Val.V_RGDOUBLE,
         Met->Par[0].Val.V_LONG,
         Met->Par[1].Val.V ENUM.value,
         Met->Par[2].Val.V_PDOUBLE,
         Met->Par[3].Val.V_INT,
         Met->Par[4].Val.V_INT,
         Met->Par[5].Val.V INT,
         &(Met->Res[0].Val.V_DOUBLE),
         &(Met->Res[1].Val.V_DOUBLE),&(Met->Res[2].Val.
    V DOUBLE));
}
static int CHK_OPT(MC_BarraquandMartineau2D)(void *Opt, voi
    d *Mod)
  Option* ptOpt=(Option*)Opt;
 TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);
  if ((opt->EuOrAm).Val.V BOOL==AMER)
    return OK;
  return WRONG;
}
```

```
static int MET(Init)(PricingMethod *Met,Option *Opt)
  if ( Met->init == 0)
    {
      Met->init=1;
      Met->Par[0].Val.V LONG=20000;
      Met->Par[1].Val.V_ENUM.value=0;
      Met->Par[1].Val.V_ENUM.members=&PremiaEnumMCRNGs;
      Met->Par[2].Val.V_PDOUBLE=0.1;
      Met->Par[3].Val.V INT=100;
      Met->Par[4].Val.V INT=300;
      Met->Par[5].Val.V INT=10;
    }
  return OK;
}
PricingMethod MET(MC BarraquandMartineau2D)=
  "MC BarraquandMartineau2d",
  {{"N iterations", LONG, {100}, ALLOW},
   {"RandomGenerator", ENUM, {100}, ALLOW},
   {"Delta Increment Rel", PDOUBLE, {100}, ALLOW},
   {"Number of Cells", INT, {100}, ALLOW},
   {"Size of grid initialising sample", INT, {100}, ALLOW},
   {"Number of Exercise Dates (0->Geske Johnson Formulae)",
    INT, {100}, ALLOW},
   {" ",PREMIA NULLTYPE, {0}, FORBID}},
  CALC(MC BarraquandMartineau2D),
  {{"Price",DOUBLE,{100},FORBID},
   {"Delta1",DOUBLE,{100},FORBID} ,{"Delta2",DOUBLE,{100},
    FORBID},
   {" ",PREMIA NULLTYPE,{0},FORBID}},
  CHK OPT(MC BarraquandMartineau2D),
  CHK_mc,
```

```
MET(Init)
};
```

## References