

[Help](#)

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#include <stdlib.h>
#include "cir1d_std.h"
#include "error_msg.h"

/*Product*/
static double dt,dr,r_min,r_max;
static double *r_vect;
static double *V,*Vp,*Ps;
static double *beta,*alpha_r,*beta_r,*gamma_r,*alpha_l,*
    beta_l,*gamma_l;
static int Nt0;
/* static int j_max; */
/* static double c01,c02,c03,c11,c12,c13, cn1,cn2,cn3,cnm1,
    cnm2,cnm3;*/

/*Memory Allocation*/
static int memory_allocation(int Nt,int Ns)
{
    r_vect= malloc((Ns+1)*sizeof(double));
    if (r_vect==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    V= malloc((Ns+1)*sizeof(double));
    if (V==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    Vp= malloc((Ns+1)*sizeof(double));
    if (Vp==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    Ps= malloc((Ns+1)*sizeof(double));
    if (Ps==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    beta= malloc((Ns+1)*sizeof(double));
    if (beta==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    alpha_l= malloc((Ns+1)*sizeof(double));
    if (alpha_l==NULL)
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    return MEMORY_ALLOCATION_FAILURE;

    beta_l= malloc((Ns+1)*sizeof(double));
    if (beta_l==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    gamma_l= malloc((Ns+1)*sizeof(double));
    if (gamma_l==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    alpha_r= malloc((Ns+1)*sizeof(double));
    if (alpha_r==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    beta_r= malloc((Ns+1)*sizeof(double));
    if (beta_r==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    gamma_r_= malloc((Ns+1)*sizeof(double));
    if (gamma_r_==NULL)
        return MEMORY_ALLOCATION_FAILURE;

    return OK;
}

/*Memory Desallocation*/
static void free_memory(int Nt)
{
    free(beta);
    free(alpha_r);
    free(beta_r);
    free(gamma_r_);
    free(alpha_l);
    free(beta_l);
    free(gamma_l);

    free(r_vect);

    free(V);
    free(Vp);
    free(Ps);
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    return;
}

/*Zero Coupon Bond Computation*/
static int zcb_cir(int Nt,int Ns)
{
    int i,TimeIndex;

    /*Maturity conditions for pure discount Bond*/
    for(i=0;i<=Ns;i++)
        Ps[i]=1.;

    /*Finite Difference Cycle*/
    for(TimeIndex=Nt-1;TimeIndex>=0;TimeIndex--)
    {
        /*Right factor*/
        V[0]=beta_r[0]*Ps[0]+gamma_r_[0]*Ps[1];
        for (i=1;i<Ns;i++)
            V[i]=alpha_r[i]*Ps[i-1]+beta_r[i]*Ps[i]+gamma_r_[i]*Ps[
                i+1];

        /*Backward Steps*/
        Vp[Ns-1]=V[Ns-1];
        beta[Ns-1]=beta_l[Ns-1];
        for(i=Ns-2;i>=0;i--)
        {
            beta[i]=beta_l[i]-gamma_l[i]*alpha_l[i+1]/beta[i+1];
            Vp[i]=V[i]-gamma_l[i]*Vp[i+1]/beta[i+1];
        }

        /*Forward Steps*/
        Ps[0]=Vp[0]/beta[0];
        for (i=1;i<Ns;i++)
            Ps[i]=(Vp[i]-alpha_l[i]*Ps[i-1])/beta[i];
        }

    return 1.;
}

/*Zero Bond Computation*/

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static int zbond_cir1d(double r0,double k,double t0,
    double sigma,double theta,double T,double t,NumFunc_1 *p,int am,
    int Nt,int Ns,double cn_theta,double *price)
{
    int i,j;
    double val,val1,sigma2;

    /*Space Localisation*/
    memory_allocation(Nt,Ns);
    sigma2=SQR(sigma);
    dt=(T-t0)/(double)Nt;
    r_min=0.;
    r_max=2.;
    dr=(r_max-r_min)/(double)Ns;
    r_vect[0]=r_min;
    for(i=0;i<=Ns;i++)
        r_vect[i]=r_min+(double)i*dr;

    /*Boundary*/
    /*Computation of Rhs coefficients*/
    alpha_r[0]=0.;
    beta_r[0]=(1.-cn_theta)*(1-k*theta*(dt/dr));
    gamma_r_[0]=(1.-cn_theta)*(k*theta*(dt/dr));

    /*Computation of Lhs coefficients*/
    alpha_l[0]=0.;
    beta_l[0]=cn_theta*(1+k*theta*(dt/dr));
    gamma_l[0]=cn_theta*(-k*theta*(dt/dr));

    /*Computation of the Matrix*/
    for(i=1;i<Ns;i++)
    {
        /*Computation of Rhs coefficients*/
        alpha_r[i]=(1.-cn_theta)*(0.5*sigma2*r_vect[i]*(dt/SQ
R(dr))-0.5*k*(theta-r_vect[i])*(dt/dr));
        beta_r[i]=1.-(1.-cn_theta)*(sigma2*r_vect[i]*(dt/SQR(
dr))+r_vect[i]*dt);
        gamma_r_[i]=(1.-cn_theta)*(0.5*sigma2*r_vect[i]*(dt/
SQR(dr))+0.5*k*(theta-r_vect[i])*(dt/dr));

        /*Computation of Lhs coefficients*/

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        alpha_1[i]=cn_theta*(-0.5*sigma2*r_vect[i]*(dt/SQR(dr
    ))+0.5*k*(theta-r_vect[i))*(dt/dr));
        beta_1[i]=1.+cn_theta*(sigma2*r_vect[i]*(dt/SQR(dr))+
    r_vect[i]*dt);
        gamma_1[i]=cn_theta*(-0.5*sigma2*r_vect[i]*(dt/SQR(dr
    ))-0.5*k*(theta-r_vect[i))*(dt/dr));
    }

    /*Number of Step for the Option*/
    Nt0=(int)ceil((t-t0)/dt);

    /*Compute Zero Coupon Prices*/
    zcb_cir(Nt,Ns);

    /*Linear Interpolation*/
    j=0;
    while(r_vect[j]<r0)
        j++;

    val= Ps[j];
    val1= Ps[j-1];

    /*Price*/
    *price=val+(val-val1)*(r0-r_vect[j])/(r_vect[j]-r_vect[j-
    1]);

    /*Memory Disallocation*/
    free_memory(Nt);

    return OK;
}

int CALC(FD_GaussZCBond)(void *Opt,void *Mod,PricingMethod
    *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;

    return zbond_cir1d(ptMod->r0.Val.V_PDOUBLE,ptMod->k.Val.

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    V_DOUBLE,ptMod->T.Val.V_DATE,ptMod->Sigma.Val.V_PDOUBLE,pt
    Mod->theta.Val.V_PDOUBLE,ptOpt->BMaturity.Val.V_DATE,ptOpt->
    OMaturity.Val.V_DATE,ptOpt->PayOff.Val.V_NUMFUNC_1,ptOpt->
    EuOrAm.Val.V_BOOL,Met->Par[0].Val.V_INT,Met->Par[1].Val.V_
    INT,Met->Par[2].Val.V_RGDOUBLE,&(Met->Res[0].Val.V_DOUBLE));
}

```

```

static int CHK_OPT(FD_GaussZCBond)(void *Opt, void *Mod)
{

    if ((strcmp(((Option*)Opt)->Name,"ZeroCouponBond")==0))
        return OK;
    else
        return WRONG;
}

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static int MET(Init)(PricingMethod *Met,Option *Opt)
{
    if ( Met->init == 0)
    {
        Met->init=1;

        Met->Par[0].Val.V_INT2=300;
        Met->Par[1].Val.V_INT2=300;
        Met->Par[2].Val.V_RGDOUBLE=0.5;

    }
    return OK;
}

```

```

PricingMethod MET(FD_GaussZCBond)=
{
    "FD_Gauss_Cir1d_ZCBond",
    {"SpaceStepNumber",INT2,{100},ALLOW },{"TimeStepNumber"
    ,INT2,{100},ALLOW},{ "Theta",RGDOUBLE051,{100},ALLOW},
    {" " ,PREMIA_NULLTYPE,{0},FORBID}},
    CALC(FD_GaussZCBond),
    {"Price",DOUBLE,{100},FORBID}/*,{"Delta",DOUBLE,{100},FO
    RBID}*/ ,{" " ,PREMIA_NULLTYPE,{0},FORBID}},
    CHK_OPT(FD_GaussZCBond),
}

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    CHK_ok,  
    MET(Init)  
} ;
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## References