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tr_vellekoop_heston

This model is given by,

$$dS_t = rS_t dt + \sqrt{v_t} S_t dW_t^1,$$

$$dv_t = k(\theta - v_t) dt + \sigma \sqrt{v_t} dW_t^2,$$

where W^1 and W^2 are two correlated brownian motions with $\langle W^1, W^2 \rangle_t = \rho t$, and k, θ and σ are constants. Description of the algorithm is given in there

References