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Help
#include <stdlib.h>
#include "mer1d_std.h"
#include "enums.h"
#if defined(PremiaCurrentVersion) && PremiaCurrentVersion <</pre>
     (2007+2) //The "#else" part of the code will be freely av
    ailable after the (year of creation of this file + 2)
static int CHK_OPT(FD_AndersenAndreasen)(void *Opt, void *
    Mod)
{
  return NONACTIVE;
int CALC(FD_AndersenAndreasen)(void *Opt, void *Mod, Pricing
    Method *Met)
{
  return AVAILABLE_IN_FULL_PREMIA;
}
#else
static int asym_1d(int am, PARAM p, DENSITY g, MESH m, WEIGHT
     w, IMESH Im, NumFunc_1 *p_func, int bound, double *pt
    price, double *ptdelta)
{
  int j,i,ii;
  unsigned long n2;
  double dum, *data, *sol_a, *sol_b, *p1, *p2, *p3, *tnoto, *bounda
    ry,*ftg,*fftg,*Obst;
  n2 = m.N << 1;
  /* vector allocation */
  sol a = malloc((m.N+1)*sizeof(double));
  if (sol_a==NULL) return MEMORY_ALLOCATION_FAILURE;
  memset(sol a,0,(m.N+1)*sizeof(double));
  Obst= malloc((m.N+1)*sizeof(double));
  if (Obst==NULL) return MEMORY_ALLOCATION_FAILURE;
  memset(Obst,0,(m.N+1)*sizeof(double));
  sol b = malloc((m.N+1)*sizeof(double));
  if (sol b==NULL) return MEMORY ALLOCATION FAILURE;
  memset(sol_b,0,(m.N+1)*sizeof(double));
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tnoto = malloc((n2+1)*sizeof(double));
if (tnoto==NULL) return MEMORY ALLOCATION FAILURE;
memset(tnoto,0,(n2+1)*sizeof(double));
p1= malloc((m.N+1)*sizeof(double));
if (p1==NULL) return MEMORY ALLOCATION FAILURE;
memset(p1,0,(m.N+1)*sizeof(double));
p2= malloc((m.N+1)*sizeof(double));
if (p2==NULL) return MEMORY ALLOCATION FAILURE;
memset(p2,0,(m.N+1)*sizeof(double));
p3= malloc((m.N+1)*sizeof(double));
if (p3==NULL) return MEMORY ALLOCATION FAILURE;
memset(p3,0,(m.N+1)*sizeof(double));
data = malloc((m.N+3)*sizeof(double));
if (data==NULL) return MEMORY ALLOCATION FAILURE;
memset(data,0,(m.N+3)*sizeof(double));
boundary = malloc((m.N)*sizeof(double));
if (boundary==NULL) return MEMORY ALLOCATION FAILURE;
memset(boundary,0,(m.N)*sizeof(double));
fftg = malloc((n2+1)*sizeof(double));
if (fftg==NULL) return MEMORY ALLOCATION FAILURE;
memset(fftg,0,(n2+1)*sizeof(double));
ftg = malloc((m.N+3)*sizeof(double));
if (ftg==NULL) return MEMORY ALLOCATION FAILURE;
memset(ftg,0,(m.N+3)*sizeof(double));
g.d = malloc((m.N+1)*sizeof(double));
if (g.d==NULL) return MEMORY ALLOCATION FAILURE;
for (j=1; j \le m.N; j++) ftg[j]=(g.d)[j]=1.0/(sqrt(2.0*M PI*
  g.par2))*exp(-SQR(g.zmin+(j-1)*m.h-g.par1)/(2.0*g.par2));
/* FFT of the density function */
drealft(ftg,m.N,1);
/*Terminal Values*/
for (j=1; j \le m.N; j++) {
  boundary[j-1]=sol a[j] = (p func->Compute)(p func->Par,
  \exp(m.xmin+(j-1)*m.h));
  Obst[j]=sol_a[j];
/* boundary */
set_boundaryAA(bound,m,p,Im,boundary,boundary);
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/* "Probabilities" associated to points */
for (j=1; j \le Im.min; j++) {
 p1[j] = 0.;
 p2[j] = 1.0;
 p3[j] = 0.;
}
for (j=Im.min; j \le Im.max; j++){
  p1[j] = -m.k/2.0*w.p1;
  p2[j] = 1.0+m.k/2.0*w.p2;
  p3[j] = -m.k/2.0*w.p3;
  /*
      p1[j] = -m.k*w.p1;
      p2[j] = 1.0+m.k*w.p2;
      p3[j] = -m.k*w.p3;
  */
}
for (j=Im.max+1; j <= m.N; j++){}
  p1[j] = 0.;
 p2[j] = 1.0;
 p3[j] = 0.;
}
/* Finite Difference Cycle */
for (i=1; i \le m.M; i++){
  /* step 1 */
  for (j=1; j \le Im.min; j++) \{ data[j] = boundary[j-1]; \}/* boun
  dary */
  for (j=Im.max+1; j \le m.N; j++) \{ data[j]=boundary[j-1]; \}/*
  boundary */
  for (j=Im.min; j<Im.max; j++){
    data[j] = sol a[j];
  }
  /* okcorrel=dcorrel(data,g.d,m.N,tnoto);
     if (okcorrel != RETURNOK) return okcorrel; */
  /* -- */
  drealft(data,m.N,1);
  for (ii=2;ii<=m.N+2;ii+=2) {
    tnoto[ii-1]=(data[ii-1]*(dum=ftg[ii-1])+data[ii]*ftg[
  ii])/(m.N/2);
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tnoto[ii] = (data[ii] *dum-data[ii-1] *ftg[ii])/(m.N/2);
tnoto[2] = tnoto[m.N+1];
drealft(tnoto,m.N,-1);
for (j=1; j \le Im.min; j++) \{ data[j] = boundary[j-1]; \}/* boun
dary */
for (j=Im.max; j \le m.N; j++) \{ data[j]=boundary[j-1]; \}/* bo
undary */
/* -- */
for (j=Im.min; j<Im.max; j++){</pre>
  data[j]=m.k/2.*w.p1*sol a[j-1]+(1.0-m.k/2.*w.p2)*sol
a[j]+m.k/2.*w.p3*sol_a[j+1]+m.k*p.lambda*m.h*tnoto[j-Im.mi]
n+1];
  /* data[j]=sol_a[j]+m.k/2.0*p.lambda*m.h*tnoto[j-Im.
min+1]; */
/* tridiagonal system */
tridiag bis(p1,p2,p3,data,sol b,m.N);
/* step 2 */
/*
    data[0]=boundary[0];
    for (j=1; j \le m.N-1; j++){
    data[j]=m.k/2.*w.p1*sol b[j-1]+(1.0-m.k/2.*w.p2)*
sol b[j]+m.k/2.*w.p3*sol b[j+1];
    data[m.N-1] = boundary[m.N-1];
    dtwofft(data-1,g.d-1,tnoto-1,fftg-1,m.N);
    for (j=1; j \le m.N+2; j+=2){
    r = tnoto[j-1]*(1-m.k/2.*p.lambda*fftg[j-1])-tnoto[
j]*m.k/2.*p.lambda*fftg[j];
    im = tnoto[j-1]*m.k/2.*p.lambda*fftg[j]+tnoto[j]*(1
-m.k/2.*p.lambda*fftg[j-1]);
    den = SQR(1-m.k/2.*p.lambda*fftg[j-1])+SQR(m.k/2.*
p.lambda*fftg[j]);
    fftg[j-1] = r/(den);
    fftg[j] = im/(den);
    }
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fftg[1]=fftg[m.N];
        drealft(fftg-1,m.N,-1);
    */
    for (j=0; j < m.N; j++)
        sol_a[j]=sol_b[j];
        /* sol_a[j]=2.0/m.N*fftg[j]; */
          sol_a[j]=MAX(Obst[j],sol_a[j]);
      }
  }
  /* Price */
  *ptprice=sol_a[m.Index+1];
  /*Delta*/
  *ptdelta = (sol a[m.Index+1]-sol a[m.Index-1])/(2.0*p.s*
   m.h);
  /* Memory Desallocation */
  free(sol a);
  free(sol_b);
  free(p1);
  free(p2);
  free(p3);
  free(tnoto);
  free(data);
  free(boundary);
  free(g.d);
  free(fftg);
  free(ftg);
  free(Obst);
 return RETURNOK;
static int AndersenAndreasen(int am,double s,NumFunc 1 *p
    func, double t, double r, double divid, double sigma, double lambd
    a, double mu, double gamma2, int N, int M, int bound, double *pt
    price,double *ptdelta)
{
 MESH m;
```

}

```
WEIGHT w;
  IMESH Im;
 PARAM p;
 DENSITY g;
 EQ eq;
 double K;
 K=p func->Par[0].Val.V DOUBLE;
 Gaussian_data(mu,gamma2,&g);
  set_parameter(s,K,t,r,sigma,divid,lambda,g.Eu,&p);
  equation(p, & eq);
  if (N\%2==1) N++;
  initgrid_1Dbis(p,g,eq,N,&m,&Im);
  set_weights_impl(M,p.T,eq,&m,&w);
  /* Gaussian vect(0,Im.N,m.h,&g);
                                      */
  asym_1d(am,p,g,m,w,Im,p_func,bound,ptprice,ptdelta);
  /*
        freeDensity(&g); */
 return OK;
int CALC(FD_AndersenAndreasen)(void *Opt,void *Mod,Pricing
    Method *Met)
{
  TYPEOPT* ptOpt=( TYPEOPT*)Opt;
  TYPEMOD* ptMod=( TYPEMOD*)Mod;
 double r, divid;
 r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
 divid=log(1.+ptMod->Divid.Val.V_DOUBLE/100.);
 return AndersenAndreasen(ptOpt->EuOrAm.Val.V BOOL,
                           ptMod->SO.Val.V PDOUBLE,
                           ptOpt->PayOff.Val.V_NUMFUNC_1,
                           ptOpt->Maturity.Val.V_DATE-pt
   Mod->T.Val.V DATE,
                           r,
                           divid,
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ptMod->Sigma.Val.V PDOUBLE,
                           ptMod->Lambda.Val.V PDOUBLE,
                           ptMod->Mean.Val.V_PDOUBLE,
                           ptMod->Variance.Val.V_PDOUBLE,
                           Met->Par[0].Val.V INT,
                           Met->Par[1].Val.V_INT,
                           Met->Par[2].Val.V_ENUM.value,
                           &(Met->Res[0].Val.V DOUBLE),
                           &(Met->Res[1].Val.V_DOUBLE));
}
static int CHK_OPT(FD_AndersenAndreasen)(void *Opt, void *
    Mod)
{
  /*
         Option* ptOpt=(Option*)Opt;
   * TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);
   */
  return OK;
#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met,Option *Opt)
  if (Met->init == 0)
      Met->init=1;
      Met->Par[0].Val.V_INT2=8192;
      Met->Par[1].Val.V INT2=500;
      Met->Par[2].Val.V_ENUM.value=0;
      Met->Par[2].Val.V_ENUM.members=&PremiaEnumBoundaryCon
    d;
    }
  return OK;
}
```

```
PricingMethod MET(FD_AndersenAndreasen)=
{
    "FD_AndersenAndreasen",
    {{"SpaceStepNumber MUST be an integer power of 2 (this is not checked for!)",INT2,{100},ALLOW},
    {"TimeStepNumber",INT2,{100},ALLOW},
    {"Boundary Condition",ENUM,{1},ALLOW},
    {" ",PREMIA_NULLTYPE,{0},FORBID}},
    CALC(FD_AndersenAndreasen),
    {{"Price",DOUBLE,{100},FORBID},{"Delta",DOUBLE,{100},FORB ID},{" ",PREMIA_NULLTYPE,{0},FORBID}},
    CHK_OPT(FD_AndersenAndreasen),
    CHK_split,
    MET(Init)
};
```

References