

[Help](#)

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#include "bs2d_std2d.h"
#include "error_msg.h"

static int KamradRitchken_91(int am,double s1,double s2,
    NumFunc_2 *p,double t,double r,double divid1,double divid2,
    double sigma1,double sigma2,double rho,int N,double lambda,
    double *ptprice,double *ptdelt
    a1,double *ptdelta2)
{
    int npoints,i,j,k;
    double h,m1,m2,u1,u2,d1,d2,lowerstock1,lowerstock2,puu,
        pud,pdu,pdd,pm,stock1,stock2;
    double **iv,**P;

    /*Memory Allocation*/
    iv=(double **)calloc(2*N+1,sizeof(double *));
    if (iv==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<2*N+1;i++)
    {
        iv[i]=(double *)calloc(2*N+1,sizeof(double));
        if (iv[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    P=(double **)calloc(2*N+1,sizeof(double *));
    if (P==NULL)
        return MEMORY_ALLOCATION_FAILURE;
    for (i=0;i<2*N+1;i++)
    {
        P[i]=(double *)calloc(2*N+1,sizeof(double));
        if (P[i]==NULL)
            return MEMORY_ALLOCATION_FAILURE;
    }

    /*Up and Down factors*/
    h=t/(double)N;
    u1=exp(lambda*sigma1*sqrt(h));
    d1= 1.0/u1;
    u2=exp(lambda*sigma2*sqrt(h));
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d2= 1.0/u2;

/*Risk-Neutral Probabilities*/
m1=(r-divid1)-SQR(sigma1)/2.0;
m2=(r-divid2)-SQR(sigma2)/2.0;

puu=exp(-r*h)*(1./SQR(lambda)+(sqrt(h)/lambda)*(m1/sigma1
+m2/sigma2)+rho/SQR(lambda))/4.;
pud=exp(-r*h)*(1./SQR(lambda)+(sqrt(h)/lambda)*(m1/sigma1
-m2/sigma2)-rho/SQR(lambda))/4.;
pdu=exp(-r*h)*(1./SQR(lambda)+(sqrt(h)/lambda)*(-m1/sigma
1+m2/sigma2)-rho/SQR(lambda))/4.;
pdd=exp(-r*h)*(1./SQR(lambda)+(sqrt(h)/lambda)*(-m1/sigma
1-m2/sigma2)+rho/SQR(lambda))/4.;
pm=exp(-r*h)*(1.-1./SQR(lambda));

/*Terminal Values*/
lowerstock1=s1;lowerstock2=s2;
for(i=0;i<N;i++)
{
    lowerstock1*=d1;
    lowerstock2*=d2;
}

stock1=lowerstock1;stock2=lowerstock2;
for (i=0;i<=2*N;i++,stock1*=u1,stock2=lowerstock2)
    for (j=0;j<=2*N;j++,stock2*=u2)
    {
        iv[i][j]=(p->Compute)(p->Par,stock1,stock2);
        P[i][j]=iv[i][j];
    }

/*Backward Cycle*/
npoints=2*N;
for (k=1;k<=N-1;k++)
{
    npoints-=2;
    for(i=0;i<=npoints;i++)
for(j=0;j<=npoints;j++)
{
    P[i][j]=pdu*P[i][j+2]+puu*P[i+2][j+2]+pdd*P[i][j]+

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        pud*P[i+2][j]+pm*P[i+1][j+1];
        if (am)
            P[i][j]= MAX(iv[k+i][k+j],P[i][j]);
    }

}

/*Deltas*/
MOD_OPT(Delta_Operator)(u1,d1,u2,d2,s1,s2,P[2][2],P[2][0],
P[0][2],P[0][0],ptdelta1,ptdelta2);

/*First Time Step*/
P[0][0]=pdu*P[0][2]+puu*P[2][2]+pdd*P[0][0]+pud*P[2][0]+
pm*P[1][1];
if (am)
    P[0][0]=MAX(iv[N][N],P[0][0]);

/*Price*/
*ptprice=P[0][0];

/*Memory desallocation*/
for (i=0;i<2*N+1;i++)
    free(iv[i]);
free(iv);

for (i=0;i<2*N+1;i++)
    free(P[i]);
free(P);

return OK;
}

int CALC(TR_KamradRitchken)(void *Opt,void *Mod,Pricing
Method *Met)
{
    TYPEOPT* ptOpt=(TYPEOPT*)Opt;
    TYPEMOD* ptMod=(TYPEMOD*)Mod;
    double r,divid1,divid2;

    r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
    divid1=log(1.+ptMod->Divid1.Val.V_DOUBLE/100.);
    divid2= log(1.+ptMod->Divid2.Val.V_DOUBLE/100.);

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return KamradRitchken_91(ptOpt->EuOrAm.Val.V_BOOL,
    ptMod->S01.Val.V_PDOUBLE,ptMod->S02.Val.V_PDOUB
    LE,
    ptOpt->PayOff.Val.V_NUMFUNC_2,ptOpt->Maturity.
    Val.V_DATE-ptMod->T.Val.V_DATE,r,divid1,divid2,
    ptMod->Sigma1.Val.V_PDOUBLE,ptMod->Sigma2.Val.
    V_PDOUBLE,ptMod->Rho.Val.V_RGDOUBLE,
    Met->Par[0].Val.V_INT,Met->Par[1].Val.V_RG
    DOUBLE,
    &(Met->Res[0].Val.V_DOUBLE),&(Met->Res[1].Val.
    V_DOUBLE),&(Met->Res[2].Val.V_DOUBLE));
}

static int CHK_OPT(TR_KamradRitchken)(void *Opt, void *Mod)
{
    return OK;
}

static int MET(Init)(PricingMethod *Met,Option *Opt)
{
    if ( Met->init == 0)
    {
        Met->init=1;

        Met->Par[0].Val.V_INT2=100;
        Met->Par[1].Val.V_RGDOUBLE12=1.22;

    }

    return OK;
}

PricingMethod MET(TR_KamradRitchken)=
{
    "TR_KamradRitchken",
    {{ "StepNumber",INT2,{100},ALLOW},{ "Lambda",RGDOUBLE12,{10
        0},ALLOW},{ " ",PREMIA_NULLTYPE,{0},FORBID}},
    CALC(TR_KamradRitchken),
    {{ "Price",DOUBLE,{100},FORBID},{ "Delta1",DOUBLE,{100},FO

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    RBID} ,{"Delta2",DOUBLE,{100},FORBID} ,  
    {" ",PREMIA_NULLTYPE,{0},FORBID}},  
    CHK_OPT(TR_KamradRitchken),  
    CHK_tree,  
    MET(Init)  
};
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## References