```
Help
#include "nig1d pad.h"
#include "pnl/pnl_cdf.h"
#include"pnl/pnl random.h"
#include"pnl/pnl specfun.h"
#include"pnl/pnl mathtools.h"
#include"pnl/pnl_random.h"
#include"pnl/pnl specfun.h"
#include"pnl/pnl_mathtools.h"
#if defined(PremiaCurrentVersion) && PremiaCurrentVersion <</pre>
     (2011+2) //The "#else" part of the code will be freely av
    ailable after the (year of creation of this file + 2)
static int CHK OPT(MC Nig Floating)(void *Opt, void *Mod)
{
  return NONACTIVE;
}
int CALC(MC_Nig_Floating)(void*Opt,void *Mod,PricingMethod
    *Met)
{
  return AVAILABLE IN FULL PREMIA;
}
#else
//Compute the positive or negative jump size between the sm
    allest and the biggest value of cdf_jump_points of the NIG
    process
static double jump generator NIG(double* cdf jump vect,
    double* cdf_jump_points,int cdf_jump_vect_size,double alpha,
    double beta, int generator)
{
   double z, v, y;
   int test,temp,l,j,q;
   test=0;
   v=pnl_rand_uni(generator);
   y=cdf jump vect[cdf jump vect size]*v;
   l=cdf_jump_vect_size/2;
   j=cdf_jump_vect_size;
   z=0;
   if(cdf jump vect[1]>y)
   {
    1=0;
```

```
j=cdf_jump_vect_size/2;
   if(v==1)
   {
     z=cdf_jump_points[cdf_jump_vect_size];
   }
   if(v==0)
   {
    z=cdf_jump_points[0];
   if(v!=1 \&\& v!=0)
   {
    while(test==0)
     if(cdf_jump_vect[l+1]>y)
      q=1;
      test=1;
     }
     else
      temp=(j-l-1)/2+1;
      if(cdf_jump_vect[temp]>y)
      {
       j=temp;
       1=1+1;
      }
      else
      {
       l=temp*(temp>l)+(l+1)*(temp<=l);</pre>
      }
     }
    z=pow(1./cdf_jump_points[q]-(y-cdf_jump_vect[q])*exp(-
    beta*cdf_jump_points[q])/(pnl_bessel_k(1.,alpha*cdf_jump_po
    ints[q])*cdf_jump_points[q]),-1.);
   }
return z;
}
static int NIG_Mc_Floating(double s_maxmin,NumFunc_2*P,
```

```
double SO, double T, double r, double divid, double sigma, double th
    eta, double kappa, int generator, int n points, long n paths,
    double *ptprice,double *ptdelta,double *priceerror,double *delt
    aerror)
{
    double eps,s,s1,s2,s3,s4,s5,s6,sup,inf,infS,supS,payo
    ff,control,proba,discount, drift,err;
    double sigma0, lambda p, control expec, lambda m, cdf jump
    bound,pas,*t,cov_payoff_control,var_payoff,var_control;
    double cor_payoff_control,control_coef,var_proba,*cdf_
    jump_points,*cdf_jump_vect_p,*cdf_jump_vect_m,*X,tau;
    double *jump time vect p,*jump time vect m,*W,sO,alpha,
    beta,delta,beta1;
    int i,j,k,jump_number_p,jump_number_m,m1,m2,cdf_jump_
    vect_size,*N_p,*N_m,n_int;
    n int=10000;
    discount=exp(-r*T);
    err=1E-16;
    eps=0.1;
    beta1=0.5826;
    cdf jump vect size=100000;
    X=malloc((n points+1)*sizeof(double));
    W=malloc((n points+1)*sizeof(double));
    t=malloc((n points+1)*sizeof(double));
    N p=malloc((n points+1)*sizeof(int));
    N m=malloc((n points+1)*sizeof(int));
    X[0]=0;
    W[0] = 0;
    pas=T/n points;
    for(i=0;i<=n_points;i++)</pre>
      t[i]=i*pas;
    }
    N p[0]=0;
    N m[O]=O;
    control expec=exp((r-divid)*T);
    s=0;
    s1=0;
    s2=0;
    s3=0;
    s4=0;
```

```
s5=0;
   s6=0;
   alpha=sqrt(theta*theta+sigma*sigma/kappa)/(sigma*sigma)
   beta=theta/(sigma*sigma);
   delta=sigma/sqrt(kappa);
   if(alpha-fabs(beta)<1)</pre>
    printf("Function NIG Mc Floating: invalid parameters.
   We must have sqrt(kappa)*(2*fabs(theta)+sigma*sigma)<=1{n")
   }
   while(delta*exp(-fabs(beta)*eps)/(M PI*eps)<17)</pre>
     eps=eps*0.9;
cdf jump bound=1;
   //Computation of the biggest jump that we tolerate
   while(2*sqrt(alpha/(2*M_PI))*delta*exp(-(alpha-fabs(bet
   a))*cdf_jump_bound)/((alpha-fabs(beta))*pow(cdf_jump_bound,
   1.5))>err)
     cdf jump bound++;
   pas=(cdf_jump_bound-eps)/cdf_jump_vect_size;
   cdf jump points=malloc((cdf jump vect size+1)*sizeof(
   double));
   cdf jump vect p=malloc((cdf jump vect size+1)*sizeof(
   double));
   cdf jump vect m=malloc((cdf jump vect size+1)*sizeof(
   double));
   cdf_jump_points[0] = eps;
   cdf jump vect p[0]=0;
   cdf jump vect m[0]=0;
   //computation of the cdf of the positive and negative
   jumps at some points
   for(i=1;i<=cdf jump vect size;i++)</pre>
    cdf_jump_points[i]=i*pas+eps;
    cdf_jump_vect_p[i]=cdf_jump_vect_p[i-1]+exp(beta*cdf_
   jump_points[i-1])*cdf_jump_points[i-1]*pnl_bessel k(1.,alpha*
   cdf jump points[i-1])*(1/cdf jump points[i-1]-1/cdf jump po
   ints[i]);
```

```
cdf jump vect m[i]=cdf jump vect m[i-1]+exp(-beta*cdf
   jump_points[i-1])*cdf_jump_points[i-1]*pnl bessel k(1.,alpha*
   cdf_jump_points[i-1])*(1/cdf_jump_points[i-1]-1/cdf_jump_po
   ints[i]);
lambda_p=cdf_jump_vect_p[cdf_jump_vect_size]*alpha*delt
   a/M PI;
   lambda m=cdf jump vect m[cdf jump vect size]*alpha*delt
   a/M PI;
   sigma0=0;
   for(i=1;i<=n int;i++)</pre>
    sigma0+=(eps*i/n int)*cosh(beta*i*eps/n int)*pnl bess
   el k(1.,alpha*i*eps/n int)*eps/n int;
   sigma0=sqrt(sigma0*alpha*delta*2/M_PI);
   drift=0;
   for(i=1;i<=n int;i++)</pre>
    drift+=sinh(beta*i*eps/n int)*pnl bessel k(1.,alpha*i*
   eps/n_int)*eps/n int;
  drift=drift*alpha*delta*2/M PI+(r-divid)-delta*(sqrt(alp
   ha*alpha-beta*beta)-sqrt(alpha*alpha-(beta+1)*(beta+1)));
m1=(int)(1000*lambda p*T);
   m2=(int)(1000*lambda m*T);
   jump time vect p=malloc((m1)*sizeof(double));
   jump time vect m=malloc((m2)*sizeof(double));
   jump time vect p[0]=0;
   jump time vect m[0]=0;
pnl_rand_init(generator,1,n_paths);
 //Call options case
 if ((P->Compute)==&Call StrikeSpot2)
       s maxmin=exp(beta1*sigma0*sqrt(T/n points))*s maxmi
   n;//shifting the predetermine minimum in order to approxima
   te the continuous price
       for(i=0;i<n_paths;i++)</pre>
        //simulation of the positive jump times and number
        tau=-1/(lambda p)*log(pnl rand uni(generator));
        jump_number p=0;
```

```
while(tau<T)</pre>
          jump_number_p++;
          jump_time_vect_p[jump_number_p]=tau;
          tau+=-1/(lambda p)*log(pnl rand uni(generator));
         //simulation of the negative jump times and numb
   er
         tau=-1/(lambda_m)*log(pnl_rand_uni(generator));
         jump_number_m=0;
         while(tau<T)</pre>
          jump_number_m++;
          jump_time_vect_m[jump_number_m]=tau;
         tau+=-1/(lambda_m)*log(pnl_rand_uni(generator));
         jump_time_vect_p[jump_number_p+1]=0;
         jump_time_vect_m[jump_number_m+1]=0;
// simulation of one NIG path
  for(k=1;k<=n points;k++)</pre>
  {
   \label{lem:wk} \begin{tabular}{ll} $W[k]=sigma0*pnl\_rand\_normal(generator)*sqrt(t[k]-t[k-1]) \\ \end{tabular}
   ])+drift*(t[k]-t[k-1])+W[k-1];
   N p[k]=N p[k-1];
   j=N_p[k-1]+1;
   while(jump_time_vect_p[j]<=t[k] && j<=jump_number_p)</pre>
    N_p[k]++;
    j++;
   s0=0;
   for(j=N p[k-1]+1; j \le N p[k]; j++)
      s0+=jump_generator_NIG(cdf_jump_vect_p,cdf_jump_po
   ints,cdf_jump_vect_size,alpha,beta,generator);
   N_m[k] = N_m[k-1];
   j=N m[k-1]+1;
   while(jump_time_vect_m[j]<=t[k] && j<=jump_number_m)</pre>
   {
```

```
N m[k]++;
     j++;
   }
   for(j=N m[k-1]+1;j<=N m[k];j++)
   s0-=jump generator NIG(cdf jump vect m,cdf jump points
   ,cdf jump vect size,alpha,-beta,generator);
   X[k]=X[k-1]+(W[k]-W[k-1])+s0;
//computation of the supremum and the infimum of
   the CGMY path
        inf=X[0];
        \sup=X[0];
        for(j=1;j<=n_points;j++)</pre>
          if(inf>X[j])
           inf=X[j];
          if(sup<X[j])</pre>
           sup=X[j];
        }
        proba=0;
        infS=S0*exp(inf);
        if(infS>s maxmin)
         infS=s maxmin;
        proba=1;
        payoff=infS;
        infS=S0*exp(X[n_points]-sup);//antithetic variab
   le associated with the exponential of the Levy infimum
        if(infS>s maxmin)
         infS=s_maxmin;
         proba+=1.;
        proba=proba/2;
        payoff=discount*(payoff+infS)/2;
        control=exp(X[n points]);
        s+=control;
        s1+=payoff;
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```
s2+=payoff*payoff;
       s3+=control*payoff;
       s4+=control*control;
       s5+=proba;
       s6+=proba*proba;
      }
      cov_payoff_control=s3/n_paths-s1*s/((double)n_paths
  *n paths);
      var_payoff=(s2-s1*s1/((double)n_paths))/((double)n_
  paths-1);
      var_control=(s4-s*s/((double)n_paths))/((double)n_
  paths-1);
      cor_payoff_control=cov_payoff_control/(sqrt(var_pay
  off)*sqrt(var control));
      control_coef=cov_payoff_control/var_control;
      var_proba=(s6-s5*s5/((double)n_paths))/((double)n_
  paths-1);
      *ptprice=-exp(-beta1*sigma0*sqrt(T/n_points))*(s1/(
  double)n_paths-control_coef*(s/n_paths-control_expec))+S0*exp(-
  divid*T):
*priceerror=exp(-beta1*sigma0*sqrt(T/n points))*1.96*sq
  rt(var_payoff*(1-cor_payoff_control*cor_payoff_control))/sq
  rt((double)n paths);
      *ptdelta=(*ptprice+discount*s maxmin*s5/(double)n
  paths)/S0;
      *deltaerror=(*priceerror+discount*s maxmin*1.96*sq
  rt(var proba)/sqrt((double)n paths))/S0;
}
else//Put
 if ((P->Compute) == &Put_StrikeSpot2)
      s maxmin=exp(-beta1*sigma0*sqrt(T/n points))*s max
  min;//shifting the predetermine maximum in order to approx
  imate the continuous price
      for(i=0;i<n paths;i++)</pre>
       //simulation of the positive jump times and number
       tau=-1/(lambda_p)*log(pnl_rand_uni(generator));
       jump number p=0;
       while(tau<T)
       {
```

```
jump_number_p++;
         jump_time_vect_p[jump_number_p]=tau;
         tau+=-1/(lambda_p)*log(pnl_rand_uni(generator));
        //simulation of the negative jump times and number
        tau=-1/(lambda_m)*log(pnl_rand_uni(generator));
        jump_number_m=0;
        while(tau<T)</pre>
        {
         jump_number_m++;
         jump_time_vect_m[jump_number_m]=tau;
         tau+=-1/(lambda_m)*log(pnl_rand_uni(generator));
        jump_time_vect_p[jump_number_p+1]=0;
        jump_time_vect_m[jump_number_m+1]=0;
// simulation of one NIG path
  for(k=1;k<=n points;k++)</pre>
   W[k] = sigma0*pnl_rand_normal(generator)*sqrt(t[k]-t[k-1
   ])+drift*(t[k]-t[k-1])+W[k-1];
   N_p[k]=N_p[k-1];
   j=N_p[k-1]+1;
   while(jump_time_vect_p[j]<=t[k] && j<=jump_number_p)</pre>
    N_p[k]++;
    j++;
   s0=0;
   for(j=N p[k-1]+1; j \le N p[k]; j++)
     s0+=jump_generator_NIG(cdf_jump_vect_p,cdf_jump_po
   ints,cdf_jump_vect_size,alpha,beta,generator);
   N m[k]=N m[k-1];
   j=N m[k-1]+1;
   while(jump_time_vect_m[j]<=t[k] && j<=jump_number_m)</pre>
     N m[k]++;
     j++;
   }
```

```
for(j=N m[k-1]+1; j \le N m[k]; j++)
   s0-=jump_generator_NIG(cdf_jump_vect_m,cdf_jump_points
   ,cdf_jump_vect_size,alpha,-beta,generator);
   X[k]=X[k-1]+(W[k]-W[k-1])+s0;
//computation of the supremum and the infimum of
   the NIG path
        inf=X[0];
        \sup=X[0];
        for(j=1;j<=n points;j++)</pre>
          if(inf>X[j])
            inf=X[j];
          if(sup<X[j])</pre>
            sup=X[j];
        }
        proba=0;
        supS=S0*exp(sup);
        if(supS<s maxmin)</pre>
         supS=s_maxmin;
         proba=1.;
        payoff=supS;
        supS=S0*exp(X[n points]-inf);//antithetic variab
   le associated with the exponential of the Levy supremum
        if(supS<s maxmin)</pre>
         supS=s_maxmin;
         proba+=1.;
        proba=proba/2;
        payoff=discount*(payoff+supS)/2;
        control=exp(X[n_points]);
        s+=control;
        s1+=payoff;
        s2+=payoff*payoff;
        s3+=control*payoff;
        s4+=control*control;
```

```
s5+=proba;
        s6+=proba*proba;
        }
        cov_payoff_control=s3/n_paths-s1*s/((double)n paths
   *n paths);
       var_payoff=(s2-s1*s1/((double)n_paths))/(n_paths-1)
       var control=(s4-s*s/((double)n paths))/(n paths-1);
        cor_payoff_control=cov_payoff_control/(sqrt(var_pay
   off)*sqrt(var_control));
        control_coef=cov_payoff_control/var_control;
        var proba=(s6-s5*s5/((double)n paths))/(n paths-1);
        *ptprice=exp(beta1*sigma0*sqrt(T/n_points))*(s1/n_
   paths-control_coef*(s/n_paths-control_expec))-S0*exp(-divid*T)
        *priceerror=exp(beta1*sigma0*sqrt(T/n points))*1.96
   *sqrt(var_payoff*(1-cor_payoff_control*cor_payoff_control)
   )/sqrt(n_paths);
        *ptdelta=(*ptprice-discount*s maxmin*s5/n paths)/S0
        *deltaerror=(*priceerror+discount*s_maxmin*1.96*sq
   rt(var proba)/sqrt((double)n paths))/S0;
  }
  free(X);
  free(W);
  free(cdf_jump_points);
  free(cdf_jump_vect_p);
  free(cdf_jump_vect_m);
  free(jump_time_vect_p);
  free(jump_time_vect_m);
  free(t);
  free(N p);
  free(N_m);
  return OK;
int CALC(MC_Nig_Floating)(void*Opt,void *Mod,PricingMethod
   *Met)
 TYPEOPT* ptOpt=(TYPEOPT*)Opt;
```

}

{

```
TYPEMOD* ptMod=(TYPEMOD*)Mod;
  double r, divid;
  r=log(1.+ptMod->R.Val.V DOUBLE/100.);
  divid=log(1.+ptMod->Divid.Val.V DOUBLE/100.);
  return NIG_Mc_Floating((ptOpt->PathDep.Val.V_NUMFUNC_2)-
    >Par[4].Val.V_PDOUBLE,ptOpt->PayOff.Val.V_NUMFUNC_2,ptMod-
    >SO.Val.V_PDOUBLE,ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.
    V_DATE,r,divid,ptMod->Sigma.Val.V_PDOUBLE,ptMod->Theta.Val.
    V_DOUBLE,ptMod->Kappa.Val.V_SPDOUBLE,Met->Par[0].Val.V_
    ENUM.value,Met->Par[1].Val.V_PINT,Met->Par[2].Val.V_LONG,&(
    Met->Res[0].Val.V_DOUBLE),&(Met->Res[1].Val.V_DOUBLE),&(Met->
    Res[2].Val.V_DOUBLE),&(Met->Res[3].Val.V_DOUBLE));
}
static int CHK OPT(MC Nig Floating)(void *Opt, void *Mod)
  if ((strcmp(((Option*)Opt)->Name," LookBackCallFloatingEuro")==0) || (strcm
    return OK;
  return WRONG;
}
#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met,Option *Mod)
  if (Met->init == 0)
      Met->init=1;
      Met->Par[0].Val.V_ENUM.value=0;
      Met->Par[0].Val.V_ENUM.members=&PremiaEnumMCRNGs;
      Met->Par[1].Val.V PINT=100;
      Met->Par[2].Val.V_LONG=100000;
    }
 return OK;
}
PricingMethod MET(MC_Nig_Floating)=
  "MC_NIG_LookbackFloating",
  {{"RandomGenerator", ENUM, {100}, ALLOW},
```

```
{"Number of discretization steps",LONG,{100},ALLOW},{"N
   iterations",LONG,{100},ALLOW},{" ",PREMIA_NULLTYPE,{0},FORBID}
},
CALC(MC_Nig_Floating),
{"Price",DOUBLE,{100},FORBID},{"Delta",DOUBLE,{100},FORB
   ID},{"Price Error",DOUBLE,{100},FORBID},{"Delta Error",
   DOUBLE,{100},FORBID},{" ",PREMIA_NULLTYPE,{0},FORBID}},
CHK_OPT(MC_Nig_Floating),
CHK_ok,
MET(Init)
};
```

References