```
Help
#include "merhes1d std.h"
#include "pnl/pnl_mathtools.h"
#if defined(PremiaCurrentVersion) && PremiaCurrentVersion <</pre>
     (2008+2) //The "#else" part of the code will be freely av
    ailable after the (year of creation of this file + 2)
static int CHK OPT(FD MertonHeston)(void *Opt, void *Mod)
  return NONACTIVE;
}
int CALC(FD MertonHeston) (void *Opt, void *Mod, Pricing
    Method *Met)
{
return AVAILABLE_IN_FULL_PREMIA;
#else
#include "math/highdim_solver/cps_function.h"
#include "math/highdim solver/cps pde.h"
#include "math/highdim solver/cps pde term.h"
#include "math/highdim_solver/cps_pde_integral_term.h"
#include "math/highdim solver/cps pde problem.h"
#include "math/highdim solver/cps grid.h"
#include "math/highdim solver/cps grid node.h"
#include "math/highdim solver/cps grid tuner.h"
#include "math/highdim solver/cps stencil operator.h"
#include "math/highdim_solver/cps_boundary_description.h"
#include "math/highdim solver/cps assertions.h"
#include "math/highdim_solver/cps_debug.h"
#include "math/highdim solver/cps utils.h"
typedef struct bates_model_t {
  double T;
  double theta, sigma, delta, r, rho, Ks;
  double E,K;
  double S0, V0, X0, Y0;
  double alpha, lambda, m;
  unsigned int Ns, Nv;
} bates_model;
```

```
/* functions */
double cps_func_zero(const function *f, const grid_node *gn
    ){
  REQUIRE("function_not_null", f != NULL);
  REQUIRE("grid node not null", gn != NULL);
  return 0.0;
}
/* public methods */
static int cps_function_create(function **f){
  STANDARD CREATE(f, function);
  (*f)->body = cps_func_zero;
  return OK;
}
static int cps_function_destroy(function **f){
  STANDARD DESTROY(f);
  return OK;
}
static int cps_function_set_body(function *f, double (*bo
    dy)(const function *, const grid_node *)){
  /* set body of function */
  REQUIRE("function_not_null", f != NULL);
  REQUIRE("body not null", body != NULL);
  f \rightarrow body = body;
  return OK;
}
static int cps function set args(function *f, const void *
    args){
  /* set function arguments */
```

```
REQUIRE("function not null", f != NULL);
 REQUIRE("args not null", args != NULL);
 f->args = args;
 return OK;
}
/* tuning functions */
static int focus_rescaler_proc(grid_tuner *tuner, grid *
    grid){
  bates model *m;
  /* rescale grid around focus */
 REQUIRE("tuner_not_null", tuner != NULL);
 REQUIRE("grid_not_null", grid != NULL);
 m = (bates_model *)tuner->argument;
  if(!(grid->ticks[X DIM] % 2))
    grid->ticks[X DIM]++;
  if(!(grid->ticks[Y_DIM] % 2))
    grid->ticks[Y_DIM]++;
  grid->min_value[X_DIM] = 0.0;
  grid->max value[X DIM] = 1.;
  grid->min value[Y DIM] = 0.0;
  grid->max_value[Y_DIM] = grid->min_value[Y_DIM] + 8.0 *
   m->VO;
 grid->focus[X DIM] = 0.5;
  grid->focus_tick[Y_DIM] = (int)floor((m->VO-grid->min_val
    ue[Y_DIM])*(grid->ticks[Y_DIM])/(grid->max_value[Y_DIM]-
    grid->min value[Y DIM]));
  grid->max_value[Y_DIM] = grid->min_value[Y_DIM] + ((
    double)(grid->ticks[Y_DIM]-1))*(m->VO-grid->min_value[Y_DIM])/((
    double)grid->focus tick[Y DIM]);
 grid->delta[X_DIM] = (grid->max_value[X_DIM] - grid->min_
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value[X DIM])/((double)(grid->ticks[X DIM]-1));
 grid->delta[Y DIM] = (grid->max value[Y DIM] - grid->min
   value[Y_DIM])/((double)(grid->ticks[Y_DIM]-1));
 grid->focus[Y DIM] = grid->min value[Y DIM] + ((double)
   grid->focus_tick[Y_DIM]) * grid->delta[Y_DIM];
 grid->focus tick[X DIM] = (int)floor(0.5*(grid->ticks[X
   DIM]));
 //xmin = grid->min value[X DIM];
 //ymin = grid->min_value[Y_DIM];
 //xmax = grid->min_value[X_DIM] + ((double)(grid->ticks[X
   _DIM] - 1)) * grid->delta[X_DIM];
 //ymax = grid->min_value[Y_DIM] + ((double)(grid->ticks[
   Y DIM] - 1)) * grid->delta[Y DIM];
 return OK;
}
static int explicit_tuner_proc(grid_tuner *tuner, grid *
   grid){
 /* tuning procedure for explicit part */
 bates model *model = (bates model *)tuner->argument;
 double dx ;
 double rx = 0.03125;
 double dy;
 double ry = 0.5;
 double bx ;
 double by;
 dx = grid->delta[X_DIM];
 dy = grid->delta[Y_DIM];
 bx = POW(dx, 2.0)/(0.5*rx);
 by = POW(dy,2.0)/(0.5*ry*POW(model->sigma,2.0));
 REQUIRE("tuner_not_null", tuner != NULL);
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REQUIRE("grid not null", grid != NULL);
  REQUIRE("grid_is_rescaled", grid->is_rescaled);
  grid->delta[T_DIM] = 0.1 * MIN(bx,by);
  grid->ticks[T DIM] = (int)floor((grid->max value[T DIM] -
     grid->min value[T DIM])/grid->delta[T DIM]) + 1;
  grid->delta[T_DIM] = (grid->max_value[T_DIM] - grid->min_
    value[T DIM])/((double)grid->ticks[T DIM] - 1.0);
 ENSURE("tmax accurate", APPROX EQUAL(grid->max value[T
    DIM],
         (grid->min value[T DIM] + ((double)grid->ticks[T
    DIM] - 1.0)* grid->delta[T DIM]),1e-8));
 return OK;
}
static int implicit tuner proc(grid tuner *tuner, grid *
    grid){
 /* tuning procedure for implicit part */
  REQUIRE("tuner not null", tuner != NULL);
  REQUIRE("grid not null", grid != NULL);
  grid->current_value[T_DIM] -= grid->delta[T_DIM]; /* ret
    urn to last step computed */
  grid->delta[T_DIM] = sqrt(grid->delta[T_DIM]);
    * rescale dt */
  grid->delta[T DIM]=MIN(grid->delta[X DIM],grid->delta[Y
   DIM]);
  grid->min_value[T_DIM] = grid->current_value[T_DIM] +
    grid->delta[T DIM]; /* compute next starting value */
  grid->ticks[T_DIM] = (unsigned int)floor((grid->max_value)
    [T_DIM] - grid->min_value[T_DIM])/grid->delta[T DIM]) + 1;
  grid->delta[T DIM] = (grid->max value[T DIM] - grid->min
    value[T_DIM])/((double)grid->ticks[T_DIM] - 1.0);
  ENSURE("tmax accurate", APPROX EQUAL(grid->max value[T
    DIM],
         (grid->min_value[T_DIM] + ((double)grid->ticks[T_
```

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DIM] - 1.0)* grid->delta[T DIM]),1e-8));
 return OK;
}
/* model functions */
static double func_call_payoff(const function *f, const
    grid node *node){
  bates_model *model = (bates_model *)f->args;
  double x = node->value[X DIM];
  double K = model->K;
  double S0 = model->S0;
  double result = MAX(x * (S0 + K)/S0 - K/S0,0.);
  REQUIRE("function_not_null", f != NULL);
 REQUIRE("node not null", node != NULL);
 return result;
/*
static double func_put_payoff(const function *f, const
    grid_node *node){
  REQUIRE("function_not_null", f != NULL);
  REQUIRE("node_not_null", node != NULL);
 bates model *model = (bates model *)f->args;
  double x = node->value[X_DIM];
  double K = model->K;
  double S0 = model->S0;
 double result = max((K/S0 * (1.0 - x) - x), 0.0);
 return result;
}
*/
```

```
static double func call boundary(const function *f, const
    grid node *node){
  bates model *model = (bates model *)f->args;
  double x = node->value[X DIM];
  double t = node->value[T DIM];
  double K = model->K;
  double r = model -> r;
  double S0 = model->S0;
 double result = MAX(x * (SO + K * exp(-r * t))/SO - K *
    \exp(-r * t)/S0,0.);
  REQUIRE("function_not_null", f != NULL);
 REQUIRE("node not null", node != NULL);
  return result;
}
static double func_put_boundary(const function *f, const
    grid_node *node){
  REQUIRE("function_not_null", f != NULL);
  REQUIRE("node_not_null", node != NULL);
  bates_model *model = (bates_model *)f->args;
  double x = node->value[X_DIM];
  double t = node->value[T DIM];
  double K = model->K;
  double r = model -> r;
  double S0 = model->S0;
  double result = \max(K * \exp(-r*t)*(1.0 - x)/S0 - x, 0.0);
 return result;
}
*/
```

```
static double func uxx(const function *f, const grid node *
    node){
  double x = node->value[X DIM];
  double y = node->value[Y_DIM];
 double result = 0.5 * y * POW(x * (1.0 - x), 2.0);
  REQUIRE("function_not_null", f != NULL);
 REQUIRE("node_not_null", node != NULL);
 return result;
}
static double func_uxy(const function *f, const grid_node *
   node){
 bates_model *model = (bates_model *)f->args;
 double x = node->value[X DIM];
 double y = node->value[Y_DIM];
  double rho = model->rho;
 double sigma = model->sigma;
 double result = rho * sigma * y * x * (1.0-x);
  REQUIRE("function not null", f != NULL);
 REQUIRE("node_not_null", node != NULL);
 return result;
static double func uyy(const function *f, const grid node *
   node){
 bates model *model;
 double y ;
 double sigma;
 double result;
  REQUIRE("function_not_null", f != NULL);
  REQUIRE("node_not_null", node != NULL);
```

```
model = (bates model *)f->args;
 y = node->value[Y_DIM];
 sigma = model->sigma;
 result = 0.5 * POW(sigma, 2.) * y;
 return result;
}
static double func_ux(const function *f, const grid_node *
    node){
  bates_model *model;
  double x;
 double r;
  double a;
  double m;
  double delta;
  double lambda;
  double result;
 REQUIRE("function_not_null", f != NULL);
 REQUIRE("node_not_null", node != NULL);
 model = (bates model *)f->args;
 x = node->value[X DIM];
 r = model -> r;
  a = model->alpha;
 m = model -> m;
 delta = model->delta;
 lambda = model->lambda;
  result = (r - delta - lambda*(exp(0.5*POW(a,2.0) + m) - 1
    (0)) * x * (1.0 - x);
 return result;
static double func_uy(const function *f, const grid_node *
    node){
```

```
bates_model *model = (bates_model *)f->args;
  double x = node->value[X DIM];
  double y = node->value[Y DIM];
  double Ks = model->Ks;
  double theta = model->theta;
  double rho = model->rho;
  double sigma = model->sigma;
  double result = rho * sigma * y * x + Ks * (theta - y);
 REQUIRE("function not null", f != NULL);
  REQUIRE("node_not_null", node != NULL);
  return result;
}
static double func_u(const function *f, const grid_node *
    node){
  bates_model *model = (bates_model *)f->args;
  double x = node->value[X_DIM];
  double r = model -> r;
  double delta = model->delta;
  double a = model->alpha;
  double m = model -> m;
  double lambda = model->lambda;
  double result = (r - delta - lambda * (exp(0.5 * POW(a, 2.
    0) + m) - 1.0)) * x - r - lambda;
  REQUIRE("function not null", f != NULL);
  REQUIRE("node_not_null", node != NULL);
 return result;
}
/* public interface */
int FDMertonHeston(double St0, NumFunc_1 *p, double T,
    double r, double divid, double VO, double kappa, double theta,
```

```
double sigmav, double rho, double lambda, double m0, double v, int
   N1, int N2, double *ptprice, double *ptdelta)
{
 bates model model;
 double K=p->Par[0].Val.V_DOUBLE;
 grid
                          *grid;
 grid_tuner
                          *tuner;
 boundary_description
                         *boundary;
 pde_problem
                         *problem;
 pde
                          *equation;
 pde_term
                         *pterm;
 pde_integral_term
                         *iterm;
 stencil_operator
                         *stnop;
 function
                         *f_uxx, *f_uxy, *f_uyy, *f_ux, *
   f uy, *f u;
 function
                         *f_payoff,*f_boundary;
 /**************
       MODEL
 **********************
 model.T = T;
 model.rho = rho;
 model.sigma = sigmav;
 model.theta = theta;
 model.r = r;
 model.K = K;
 model.Ks = kappa;
 model.delta = divid;
 model.S0 = St0;
 model.V0 = V0;
 model.alpha = sqrt(v); /* CHECK THIS !!! */
 model.m = m0;
 model.lambda = lambda;
 model.Ns = N1;
 model.Nv = N2;
 /**************
       GRID and TUNER
```

```
**********************/
grid tuner create(&tuner);
grid_tuner_set_argument(tuner,&model);
grid_tuner_set_tuner(tuner, EXPLICIT_TUNER, explicit_tune
 r proc);
grid tuner set tuner(tuner, IMPLICIT TUNER, implicit tune
 r_proc);
grid tuner set tuner(tuner, RESCALE TUNER, focus rescale
 r_proc);
grid_create(&grid);
grid set space dimensions(grid,2);
grid set tuner(grid,tuner);
grid set min value(grid,T DIM,0.0);
grid_set_max_value(grid,T_DIM,model.T);
grid_set_ticks(grid, X_DIM, model.Ns);
grid set ticks(grid,Y DIM,model.Nv);
grid_set_iterator(grid, X_DIM, ITER_PLAIN);
grid_set_iterator(grid, Y_DIM, ITER_CORE);
/* focus */
grid_set_focus(grid, X_DIM, model.S0);
grid_set_focus(grid,Y_DIM,model.V0);
grid rescale(grid);
/**************
      BOUNDARY
**********************
cps_function_create(&f_payoff);
cps function set args(f payoff,&model);
cps function create(&f boundary);
cps_function_set_args(f_boundary,&model);
cps function set body(f payoff,func call payoff);
cps_function_set_body(f_boundary,func_call_boundary);
boundary_description_create(&boundary);
boundary_description_set_left(boundary, X_DIM, f_boundary)
```

```
boundary_description_set_left(boundary,Y_DIM, f_boundary)
boundary_description_set_right(boundary, X_DIM, f_bounda
boundary description set right(boundary, Y DIM, f bounda
  ry);
boundary_description_set_initial(boundary, f_payoff);
/**************
      EQUATION
**********************
pde_create(&equation);
/* 1: Uxx */
cps_function_create(&f_uxx);
cps_function_set_body(f_uxx,func_uxx);
stencil operator create(&stnop,STENCIL OP UXX);
pde_term_create(&pterm, UXX_TERM, f_uxx, stnop);
pde_add_term(equation, pterm);
/* 2: Uxy */
cps_function_create(&f_uxy);
cps_function_set_args(f_uxy, &model);
cps_function_set_body(f_uxy, func_uxy);
stencil_operator_create(&stnop,STENCIL_OP_UXY);
pde_term_create(&pterm, UXY_TERM, f_uxy, stnop);
pde add term(equation, pterm);
/* 3: Uyy */
cps function create(&f uyy);
cps_function_set_args(f_uyy, &model);
cps_function_set_body(f_uyy, func_uyy);
stencil_operator_create(&stnop,STENCIL_OP_UYY);
pde_term_create(&pterm,UYY_TERM, f_uyy, stnop);
pde_add_term(equation,pterm);
```

```
/* 4: Ux */
cps_function_create(&f_ux);
cps_function_set_args(f_ux, &model);
cps function set body(f ux, func ux);
stencil_operator_create(&stnop,STENCIL_OP_UX);
pde term create(&pterm,UX TERM, f ux, stnop);
pde_add_term(equation,pterm);
/* 5: Uy */
cps function create(&f uy);
cps_function_set_args(f_uy, &model);
cps_function_set_body(f_uy, func_uy);
stencil_operator_create(&stnop,STENCIL_OP_UY);
pde term create(&pterm,UY TERM, f uy, stnop);
pde_add_term(equation,pterm);
/* 6: U */
cps function create(&f u);
cps_function_set_args(f_u, &model);
cps_function_set_body(f_u, func_u);
stencil_operator_create(&stnop,STENCIL_OP_U);
pde_term_create(&pterm, U_TERM, f_u, stnop);
pde_add_term(equation,pterm);
/* 7: integral term */
if(model.lambda != 0.0){
 pde_integral_term_create(&iterm);
 pde integral term set lambda(iterm, model.lambda);
 pde_integral_term_set_alpha(iterm, model.alpha);
 pde_integral_term_set_m(iterm, model.m);
 pde integral term set grid(iterm,grid);
 pde_set_integral_term(equation, iterm);
/***********
      PROBLEM
```

```
**********************/
pde problem create(&problem);
problem->max_explicit_steps = 20;
pde problem set desired accuracy(problem, 10e-8);
pde problem set equation(problem, equation);
pde problem set grid(problem, grid);
pde_problem_set_boundary(problem, boundary);
/************
          SOLUTION
**************************
pde problem setup(problem);
pde_problem_solve(problem);
pde problem get solution(problem, ptprice);
pde_problem_get_delta_x(problem, ptdelta);
 if((p->Compute) == &Call){ /* CALL EVALUATION */
   (*ptprice) *= 2.0 * model.S0;
}
else{ /* PUT EVALUATION */
   (*ptprice) *= (2.0 * model.S0);
   (*ptprice) += model.K * exp(-model.r) - model.S0;
}
/***********
         CLEANUP
***********************
pde_problem_destroy(&problem);
cps_function_destroy(&f_payoff);
cps function destroy(&f boundary);
cps function destroy(&f uxx);
cps function destroy(&f uxy);
cps_function_destroy(&f_uyy);
cps function destroy(&f ux);
cps function destroy(&f uy);
cps_function_destroy(&f_u);
return OK;
```

}

```
int CALC(FD MertonHeston)(void *Opt, void *Mod, Pricing
    Method *Met)
  TYPEOPT* ptOpt=(TYPEOPT*)Opt;
  TYPEMOD* ptMod=(TYPEMOD*)Mod;
  double r, divid;
  if(ptMod->Sigma.Val.V_PDOUBLE==0.0)
      Fprintf(TOSCREEN, "BLACK-SCHOLES MODEL{n{n{n");
      return WRONG;
    }
  else
    {
      r=log(1.+ptMod->R.Val.V_DOUBLE/100.);
      divid=log(1.+ptMod->Divid.Val.V DOUBLE/100.);
      return FDMertonHeston(ptMod->SO.Val.V_PDOUBLE,
        ptOpt->PayOff.Val.V NUMFUNC 1,
        ptOpt->Maturity.Val.V_DATE-ptMod->T.Val.V_DATE,
        divid, ptMod->SigmaO.Val.V_PDOUBLE
        ,ptMod->MeanReversion.hal.V PDOUBLE,
        ptMod->LongRunVariance.Val.V_PDOUBLE,
        ptMod->Sigma.Val.V PDOUBLE,
        ptMod->Rho.Val.V PDOUBLE,
        ptMod->Lambda.Val.V_PDOUBLE,
        ptMod->Mean.Val.V_PDOUBLE,
        ptMod->Variance.Val.V_PDOUBLE,
              Met->Par[0].Val.V_INT,Met->Par[1].Val.V_
    INT,
        &(Met->Res[0].Val.V DOUBLE),
        &(Met->Res[1].Val.V_DOUBLE));
    }
}
static int CHK OPT(FD MertonHeston)(void *Opt, void *Mod)
{
if ((strcmp(((Option*)Opt)->Name, "CallEuro")==0) || (strc
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mp( ((Option*)Opt)->Name, "PutEuro")==0) )
    return OK;
  return WRONG;
#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met,Option *Opt)
{
   if (Met->init == 0)
      Met->init=1;
      Met->Par[0].Val.V_INT2=51;
      Met->Par[1].Val.V_INT2=21;
  return OK;
PricingMethod MET(FD_MertonHeston)=
  "FD NataliniBriani MERHES",
  {{"SpaceStepNumber S",INT2,{100},ALLOW},{"SpaceStepNumb
    er V",INT2,{100},ALLOW},{" ",PREMIA_NULLTYPE,{0},FORBID}},
  CALC(FD MertonHeston),
  {{"Price",DOUBLE,{100},FORBID},
   {"Delta", DOUBLE, {100}, FORBID},
   {" ",PREMIA NULLTYPE, {0}, FORBID}},
  CHK_OPT(FD_MertonHeston),
  CHK_ok,
  MET(Init)
};
```

References