

ARBITRAGE FREE SABR

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Abstract. Smile risk is often managed using the explicit implied volatility formulas developed for the SABR model [1]. These asymptotic formulas are not exact, and this can lead to arbitrage for low strike options. Here we provide an alternate method for pricing options under the SABR model: We use asymptotic techniques to reduce the SABR model from two dimensions to one dimension. This leads to an effective one dimensional forward equation for the probability density which has the same asymptotic order of accuracy as the explicit implied volatility formulas. We obtain arbitrage free option prices by numerically solving this PDE. The implied volatilities obtained from the numerical solutions closely match the explicit implied volatility curves, apart from a boundary layer at very low rates. For very low rate environments, or for very low strikes, the implied absolute (normal) volatility dips downwards, closely matching market observations. We also show how negative rates can be accommodated by replacing the F^β factor with $(F + a)^\beta$.

1. The SABR model. European option prices are often quoted by using the normal model. In this model the forward asset price $\tilde{F}(t)$ follows the process

$$(1.1a) \quad d\tilde{F} = \sigma_N d\tilde{W},$$

where σ_N denotes the implied normal volatility (*aka* absolute volatility or basis points per year volatility), and the (forward) price of European calls and puts works out to be

$$(1.1b) \quad V_{call}^N = [f - K] N\left(\frac{f - K}{\sigma_N \sqrt{\tau_{ex}}}\right) + \sigma_N \sqrt{\tau_{ex}} G\left(\frac{f - K}{\sigma_N \sqrt{\tau_{ex}}}\right),$$

$$(1.1c) \quad V_{put}^N = [K - f] N\left(\frac{K - f}{\sigma_N \sqrt{\tau_{ex}}}\right) + \sigma_N \sqrt{\tau_{ex}} G\left(\frac{f - K}{\sigma_N \sqrt{\tau_{ex}}}\right).$$

Here $N(\cdot)$ is the cumulative normal distribution and $G(\cdot)$ is the Gaussian density. Both V_{call}^N and V_{put}^N are increasing functions of the volatility σ_N . Consequently, European option prices can be quoted by stating the implied normal volatility, which is the unique value of σ_N that yields the option's dollar price when substituted into these formulas.

Alternatively, in Black's model the forward asset price is modeled by

$$(1.2) \quad d\tilde{F} = \sigma_B \tilde{F} d\tilde{W}.$$

Here, too, there is a one-to-one relation between the European option price and the Black (log normal) volatility σ_B , so option prices can be quoted in terms of σ_B . Implied Black volatilities σ_B and implied normal volatilities σ_N are equivalent, and the mapping between σ_B and σ_N is well understood, so in this article we focus on the normal volatilities σ_N .

If the normal model correctly described the asset price, then the same implied volatility σ_N would correctly price options with different strikes K and times-to-expiry τ_{ex} . In practice, matching market prices requires substantially different implied volatilities for options with different strikes and expiries, $\sigma_N = \sigma_N(K, \tau_{ex})$. For a given expiry τ_{ex} , the implied volatility σ_N as a function of K is the options's "smile," or "skew." Handling the smile judiciously is critical to an options desk, since the risks of options at all different strikes K have to be consolidated before they can be hedged efficiently. Although offsetting risks of options

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with different expiries is less common, handling the volatility surface (the dependence of σ_N on both K and τ_{ex}) is also important for correctly pricing path dependent options.

The need for handling smile risk effectively led to the development of the SABR models [1], [2]. These are models of the form

$$\begin{aligned} (1.3a) \quad & d\tilde{F} = \tilde{A}C(\tilde{F})d\tilde{W}_1, \\ (1.3b) \quad & d\tilde{A} = \nu\tilde{A}d\tilde{W}_2, \\ (1.3c) \quad & d\tilde{W}_1d\tilde{W}_2 = \rho dt, \end{aligned}$$

where most commonly $C(F)$ is taken to be F^β . In [1], singular perturbation techniques were used to analyze this class of models in the small volatility regime. To carry out the expansion systematically, a small parameter ε was introduced,

$$\begin{aligned} (1.4a) \quad & d\tilde{F} = \varepsilon\tilde{A}C(\tilde{F})d\tilde{W}_1, \\ (1.4b) \quad & d\tilde{A} = \varepsilon\nu\tilde{A}d\tilde{W}_2, \\ (1.4c) \quad & d\tilde{W}_1d\tilde{W}_2 = \rho dt. \end{aligned}$$

The model was analyzed in the limit $\varepsilon \ll 1$, and then ε was set to 1 in the final result¹. This analysis was used to obtain explicit formulas for the implied volatilities of European options under the SABR model. There are now several variants of these formulas [1] - [7], all correct through $O(\varepsilon^2)$, but our favorite is

$$(1.5a) \quad \sigma_N(K) = \frac{\varepsilon\alpha(f-K)}{\int_K^f \frac{df'}{C(f')}} \cdot \left(\frac{\zeta}{x(\zeta)} \right) \cdot \left\{ 1 + \left[g\alpha^2 + \frac{1}{4}\rho\nu\alpha \frac{C(f)-C(K)}{f-K} + \frac{2-3\rho^2}{24}\nu^2 \right] \varepsilon^2\tau_{ex} + \dots \right\}.$$

Here $f = \tilde{F}(0)$, $\alpha = \tilde{A}(0)$ are today's values of the forward price and the volatility, τ_{ex} is the time to exercise,

$$(1.5b) \quad \zeta = \frac{\nu}{\alpha} \int_K^f \frac{df'}{C(f')}, \quad x(\zeta) = \log \left(\frac{\sqrt{1-2\rho\zeta+\zeta^2} - \rho + \zeta}{1-\rho} \right),$$

and the geometric factor is

$$(1.5c) \quad g = \log \left(\frac{1}{f-K} \int_K^f \frac{\sqrt{C(f)C(K)}}{C(f')} df' \right) \bigg/ \left(\int_K^f \frac{1}{C(f')} df' \right)^2.$$

Although there are simpler formulas, this one seems to be the most robust.

The classic SABR model is the special case $C(F) = F^\beta$. For this case the implied volatility formula reduces to

$$(1.6a) \quad \sigma_N(K) = \frac{\varepsilon\alpha(1-\beta)(f-K)}{f^{1-\beta}-K^{1-\beta}} \cdot \left(\frac{\zeta}{x(\zeta)} \right) \cdot \left\{ 1 + \left[g\alpha^2 + \frac{1}{4}\rho\nu\alpha \frac{f^\beta-K^\beta}{f-K} + \frac{2-3\rho^2}{24}\nu^2 \right] \varepsilon^2\tau_{ex} + \dots \right\},$$

where

$$(1.6b) \quad \zeta = \frac{\nu}{\alpha} \frac{f^{1-\beta}-K^{1-\beta}}{1-\beta}, \quad x(\zeta) = \log \left(\frac{\sqrt{1-2\rho\zeta+\zeta^2} - \rho + \zeta}{1-\rho} \right),$$

¹ Although this appears inconsistent, we can non-dimensionalize the problem via $t^{new} = t/\tau_{ex}$, $\hat{A}^{new} = \hat{A}/A_0$, and $\nu^{new} = \nu/A_0$, where A_0 is the typical size of the volatility. This yields $d\tilde{F} = \varepsilon\tilde{A}C(\tilde{F})d\tilde{W}_1$ and $d\tilde{A} = \varepsilon\nu\tilde{A}d\tilde{W}_2$ in the new variables, with $\varepsilon = A_0\tau_{ex}^{1/2}$. After analyzing the problem in the $\varepsilon \ll 1$ regime, setting ε to 1 is equivalent to re-writing the answer in terms of the original, dimensioned variables. The $\varepsilon \ll 1$ assumption is based on the observation that long dated options usually have small volatilities, while short dated options have small τ_{ex} .

and

$$(1.6c) \quad g = \frac{(1-\beta)^2}{(f^{1-\beta} - K^{1-\beta})^2} \log \left((fK)^{\beta/2} \frac{f^{1-\beta} - K^{1-\beta}}{(1-\beta)(f-K)} \right).$$

Two problems have developed using these explicit implied volatility formulas. First, for some low strike, long dated options, the explicit implied volatility formulas can lead to arbitrageable prices; this is discussed in the next section. Second, the SABR model has a barrier wherever $C(F) = 0$; this is at $F = 0$ in the classical SABR model. There is an $O(\varepsilon)$ thick boundary layer next to this barrier, a region in which the original asymptotic analysis does not pertain. In the current, ultra-low rate environment, this region has a substantial influence on pricing, especially with the advent of zero strike options.

In this article we address both problems. We use singular perturbation methods to show that the *reduced density*,

$$(1.7) \quad Q(T, F) dF = \text{Prob} \left\{ F < \tilde{F}(T) < F + dF \mid \tilde{F}(t) = f, \tilde{A}(t) = \alpha \right\},$$

satisfies the *effective forward equation*

$$(1.8a) \quad Q_T^c = \frac{1}{2} \varepsilon^2 \alpha^2 \left[(1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) e^{\varepsilon^2 \rho \nu \alpha \Gamma [T-t]} C^2(F) Q^c \right]_{FF} \quad \text{for } T > t.$$

Here $z(F)$ is given by

$$(1.8b) \quad z(F) \equiv \frac{1}{\varepsilon \alpha} \int_f^F \frac{df'}{C(f')},$$

and $e^{\varepsilon^2 \rho \nu \alpha \Gamma [T-t]}$ is a very tiny correction factor with $\Gamma(F)$ given by

$$(1.8c) \quad \Gamma(F) \equiv \frac{C(F) - C(f)}{F - f}.$$

In general, this reduction is not exact², but it is accurate through $O(\varepsilon^2)$, the same accuracy as the explicit implied volatility formulas. By solving the PDE numerically, we obtain the probability density $Q(\tau_{ex}, F)$ at the exercise date τ_{ex} ; the call and put prices are then obtained by integrating to find the expected value of the payoffs. As we shall see, these option prices are arbitrage free.

To simplify notation, let

$$(1.9) \quad D(F) = \sqrt{1 + 2\varepsilon \rho \nu z(F) + \varepsilon^2 \nu^2 z^2(F)} e^{\frac{1}{2} \varepsilon^2 \rho \nu \alpha \Gamma [T-t]} C(F).$$

Then the effective forward equation is

$$(1.10a) \quad Q_T^c = \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F) Q^c]_{FF} \quad \text{for } T > t.$$

Note that $D(F) = 0$ where, and only where, $C(F) = 0$.

Solving the problem numerically requires a finite domain, $F_{\min} < F < F_{\max}$. The appropriate lower boundary F_{\min} is usually at the barrier, where $C(F_{\min}) = 0$, and thus $D(F_{\min}) = 0$. In some situations it can make sense to use other boundaries. For example, one may wish to assume that the forward $\tilde{F}(T)$ cannot go below zero, in which case the boundary has to be set at $F_{\min} = 0$, regardless of whether $C(0) = 0$. Or the barrier may be more than 5 or 6 standard deviations below the forward, so there is no reason to extend

²The reduction is exact when $C(F)$ is constant; i.e., for stochastic normal models. See appendix A.

the grid all the way to the barrier. The upper boundary F_{\max} simply needs to be large enough so that there is a negligible probability of reaching or exceeding F_{\max} ; usually this is 4 to 6 standard deviations above the current forward f . See Appendix D, which gives F in terms of the number of standard deviations above or below f .

The appropriate boundary conditions are investigated in Appendix B. There it is found that we must use absorbing boundary conditions,

$$(1.10b) \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+, \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\max}^-,$$

in order for $\tilde{F}(T)$ to remain a martingale. The appropriate initial condition is

$$(1.10c) \quad Q^c(T, F) \rightarrow \delta(F - f) \quad \text{as } T \rightarrow t.$$

Equations 1.10a - 1.10c form a well posed problem for the density $Q^c(T, F)$. Since the boundaries are absorbing, the probability density will develop δ -functions at the boundaries F_{\min} , F_{\max} in addition to the continuous density $Q^c(T, F)$. Crudely speaking,

$$(1.11) \quad Q(T, F) = \begin{cases} Q^L(T)\delta(F - F_{\min}) & \text{at } F = F_{\min} \\ Q^c(T, F) & \text{for } F_{\min} < F < F_{\max} \\ Q^R(T)\delta(F - F_{\max}) & \text{at } F = F_{\max} \end{cases}.$$

Probability accumulates at F_{\min} and F_{\max} according to the flux reaching the boundaries:

$$(1.12a) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q^c]_F,$$

$$(1.12b) \quad \frac{dQ^R}{dT} = - \lim_{F \rightarrow F_{\max}^-} \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q^c]_F,$$

with the initial condition

$$(1.12c) \quad Q^L(T) \rightarrow 0, \quad Q^R(T) \rightarrow 0 \quad \text{as } T \rightarrow t.$$

This will ensure that the combined probability in $Q^L(T)$, $Q^c(T, F)$, and $Q^R(T)$ totals 1 for all T . Of course, if the upper boundary probability $Q^R(T)$ is significant, F_{\max} can always be increased.

At first glance, the delta function at F_{\min} looks unusual. However, consider a hypothetical situation in which $C(F)$ has been replaced by

$$(1.13) \quad \tilde{C}(F) \equiv \begin{cases} C(F) & \text{for } F > \eta \\ C(F_0)F/\eta & \text{for } 0 < F < \eta \end{cases}$$

to prevent F from becoming negative. This situation is analyzed in Appendix B. We find that for $\eta \ll 1$, there is a thin boundary layer in $0 < F < \eta$ which has very high densities $Q(T, F)$. In the limit $\eta \rightarrow 0$, the total probability in $0 < F < \eta$ is $Q^L(T)$. Moreover, we find that $C^2(F)Q(T, F)$ goes to zero as we approach η from above:

$$(1.14) \quad \lim_{F \rightarrow \eta^+} C^2(F)Q(T, F) \rightarrow 0, \quad \int_0^\eta Q(T, F)dF \rightarrow Q^L(T) \quad \text{as } \eta \rightarrow 0.$$

In the limit $\eta \rightarrow 0$ we recover the absorbing boundary condition and delta function $Q^L(T)\delta(F - F_{\min})$.

We believe that this is representative of the general situation: when the forward $\tilde{F}(T)$ is near enough to the boundary, other mechanisms come into play; after all, there must be some reason that $\tilde{F}(T)$ doesn't

cross the boundary. For example, interest rates in near zero and even slightly negative rate environments, can be expected to behave differently than rates in more moderate regimes. If we put in a detailed model for these boundary mechanisms, and looked on a fine enough scale, then the delta functions should be resolved into structured boundary layers. Yet, independent of the detailed model, the total probability in the layer should match $Q^L(T)$, as this is required by conservation, and we expect that as we move away from the boundary, $Q(T, F)$ should transition into the solution of 1.10a with the absorbing boundary condition 1.10b, as this is required for $\tilde{F}(T)$ to be a martingale.

We use a moment-preserving Crank-Nicholson scheme [8] to solve the PDE 1.10a - 1.10c numerically for $t < T < \tau_{ex}$, while simultaneously integrating the ODE's 1.12a - 1.12c. See Appendix C. Once we have obtained $Q^L(\tau_{ex})$, $Q^c(\tau_{ex}, F)$, and $Q^R(\tau_{ex})$, the option prices for all strikes K are obtained from:

$$(1.15a) \quad V_{call}(\tau_{ex}, K) = \int_K^{F_{\max}} (F - K) Q^c(\tau_{ex}, F) dF + (F_{\max} - K) Q^R(\tau_{ex}),$$

$$(1.15b) \quad V_{put}(\tau_{ex}, K) = (K - F_{\min}) Q^L(\tau_{ex}) + \int_{F_{\min}}^K (K - F) Q^c(\tau_{ex}, F) dF.$$

If we wish, we can then find the implied normal volatility that matches these prices at each K . That is, by solving the PDE once for $0 < T < \tau_{ex}$, we obtain the smile for all K at τ_{ex} .

The implied volatilities obtained from these numerical solutions closely match the implied volatility given by the explicit formulas 1.5a - 1.5c, apart from low strikes K and low forwards f . For low strikes and forwards, the implied absolute (normal) volatility dips downwards, closely matching market behavior. We can also accomodate negative rates by, for example, using $C(F) = (F + b)^\beta$ to move the barrier below zero. For this special case, the effective forward equation is

$$(1.16a) \quad Q_T^c = \frac{1}{2} \varepsilon^2 \alpha^2 \left[(1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) e^{\varepsilon^2 \rho \nu a \Gamma T} (F + b)^{2\beta} Q^c \right]_{FF} \quad \text{for } -b < F < F_{\max},$$

for $0 < T < \tau_{ex}$, where

$$(1.16b) \quad z(F) \equiv \frac{(F + b)^{1-\beta} - (f + b)^{1-\beta}}{\varepsilon \alpha (1 - \beta)}, \quad \Gamma(F) \equiv \frac{(F + b)^\beta - (f + b)^\beta}{F - f}.$$

The boundary conditions are

$$(1.16c) \quad (F + b)^{2\beta} Q^c \rightarrow 0 \quad \text{as } F \rightarrow -b^+ \quad (F + b)^{2\beta} Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\max}^-,$$

and delta functions at $-b$ and F_{\max} accumulate probability according to

$$(1.16d) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow -a^+} \frac{1}{2} \varepsilon^2 \alpha^2 \left[(1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) e^{\varepsilon^2 \rho \nu a \Gamma T} (F + b)^{2\beta} Q^c \right]_F,$$

$$(1.16e) \quad \frac{dQ^R}{dT} = - \lim_{F \rightarrow F_{\max}^-} \frac{1}{2} \varepsilon^2 \alpha^2 \left[(1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) e^{\varepsilon^2 \rho \nu a \Gamma T} (F + b)^{2\beta} Q^c \right]_F.$$

Finally, we briefly discuss hedging under the SABR model.

We believe that other research groups are actively investigating approaches similar to the approach presented here [9] - [12].

2. Arbitrage using the explicit formulas for the SABR model. The explicit implied volatility formulas make the SABR model easy to implement, calibrate, and use. *These implied volatility formulas are usually treated as if they are exactly correct*, even though they are derived from an expansion which requires

that $\varepsilon\alpha\sqrt{\tau_{ex}} \ll 1$, $\varepsilon\nu\sqrt{\tau_{ex}} \ll 1$, and $|F - K|/\varepsilon\alpha\sqrt{\tau_{ex}} = O(1)$. The unstated argument is that *instead of treating these formulas as an accurate approximation to the SABR model, they should be treated as the exact solution to some other model which is well approximated by the SABR model.*

This is a valid viewpoint as long as the option prices obtained using the explicit formulas for $\sigma_N(K)$ are arbitrage free. There are two key requirements for this [13], [14]. The first is put-call parity, which holds automatically since we are using the same implied volatility $\sigma_N(K)$ for both calls and puts. The second is that the probability density implied by the call and put prices needs to be positive. To explore this, note that call and put prices can be written quite generally as

$$(2.1) \quad V_{call}(\tau_{ex}, K) = \int_K^\infty (F - K) Q(\tau_{ex}, F) dF, \quad V_{put}(K) = \int_{-\infty}^K (K - F) Q(\tau_{ex}, F) dF,$$

where $Q(\tau_{ex}, F)$ is the risk-neutral probability density at the exercise date (including any delta functions). Clearly,

$$(2.2) \quad \frac{\partial^2}{\partial K^2} V_{call}(K) = \frac{\partial^2}{\partial K^2} V_{put}(K) = Q(\tau_{ex}, F) \geq 0.$$

So the explicit implied volatility formulas 1.5a - 1.5c can represent an arbitrage-free model only if

$$(2.3) \quad \frac{\partial^2}{\partial K^2} V_{call}^N(f, K, \sigma_N(K), \tau_{ex}) = \frac{\partial^2}{\partial K^2} V_{put}^N(f, K, \sigma_N(K), \tau_{ex}) \geq 0 \quad \text{for all } K.$$

That is, there cannot be a “butterfly arbitrage.”

It is not terribly uncommon for this requirement to be violated for very low strike options for sufficiently large τ_{ex} . The problem does not appear to be the quality of the call and put prices obtained from the explicit implied volatility formulas, because these usually remain quite accurate. Rather, the problem seems to be that implied volatility curves are not a robust representation of option prices for low strikes. It is very easy to find nearly identical, reasonable looking, volatility curves $\sigma_N(K)$, for which some of the curves are arbitrage free and others violate the arbitrage-free constraint of eq. 2.3.

This is illustrated in Figure 2.1. There the smile $\sigma_N(K)$ obtained from the explicit formula 1.5a - 1.5c is graphed (*explicit*) along with a very similar smile (*arb free*) obtained from the arbitrage-free procedure. These two smiles look very similar, and lead to nearly identical option prices, as shown in Figure 2.2. Differentiating these prices with respect to the strike K yields the probability densities shown in Figure 2.3. The explicit smile $\sigma_N(K)$ leads to negative probabilities for ultra low strikes, and so is not arbitrage free, whilst the second curve shows that the probabilities obtained from the arbitrage-free approach are strictly positive.

Using implied Black (log normal) volatilities $\sigma_B(K)$ instead of implied normal volatilities does not help. Figure 2.4 compares the implied Black volatilities obtained from the explicit formulas for $\sigma_N(K)$ with those obtained from the arbitrage-free approach. There is no obvious way to discern that one curve leads to arbitrage-free prices, while the other does not.

3. Arbitrage free pricing.

3.1. The effective forward equation. Here we present a pricing approach which is arbitrage free and retains the $O(\varepsilon^2)$ accuracy of the original SABR analysis. We believe that similar approaches are being investigated by other research groups [9] - [12].

Consider the probability density at $\tilde{F}(T) = F$, $\tilde{A}(T) = A$ at time T , given that $\tilde{F}(t) = f$ and $\tilde{A}(t) = \alpha$ at time t :

$$(3.1a) \quad p(t, f, \alpha; T, F, A) dF dA = \text{Prob} \left\{ F < \tilde{F}(T) < F + dF, A < \tilde{A}(T) < A + dA \mid \tilde{F}(t) = f, \tilde{A}(t) = \alpha \right\}.$$

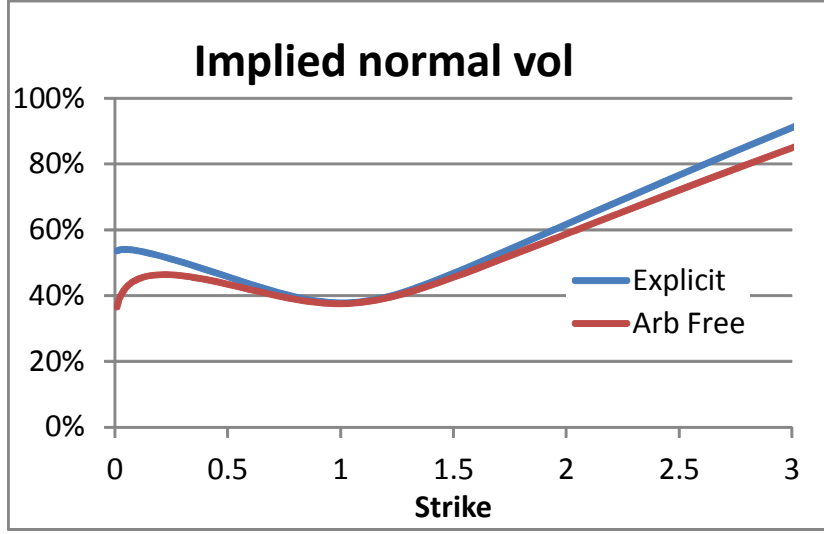


FIG. 2.1. The implied normal volatility for the SABR model for $\alpha = 35\%$, $\beta = 0.25$, $\rho = -10\%$, and $\nu = 100\%$. Shown are the curves $\sigma_N(K)$ from the explicit formula and the arbitrage-free approach for $\tau_{ex} = 1\text{yr}$.

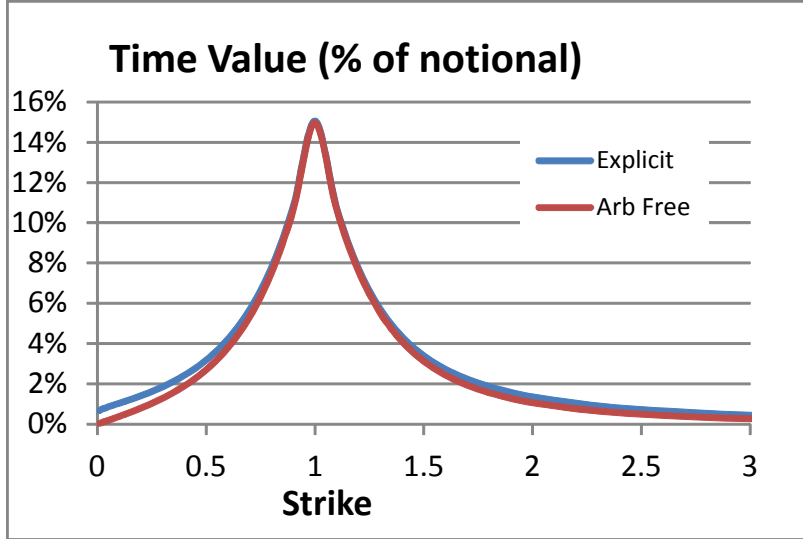


FIG. 2.2. Call prices (for $K < f$) and put prices (for $K > f$) from the SABR model for $\alpha = 35\%$, $\beta = 0.25$, $\rho = -10\%$, $\nu = 100\%$ for $\tau_{ex} = 1\text{yr}$. Shown are the prices from the explicit formulas for $\sigma_N(K)$ and from the arbitrage-free approach.

This density p satisfies the Fokker-Planck equation (the forward Kolmogorov equation),

$$(3.1b) \quad p_T = \frac{1}{2}\varepsilon^2 A^2 [C^2(F)p]_{FF} + \varepsilon^2 \rho \nu [A^2 C(F)p]_{FA} + \frac{1}{2}\varepsilon^2 \nu^2 [A^2 p]_{AA} \quad \text{for } T > t.$$

In Appendix A we define the reduced (marginal) probability density,

$$(3.2) \quad Q(T, F) = \int_0^\infty p(t, f, \alpha; T, F, A) dA,$$

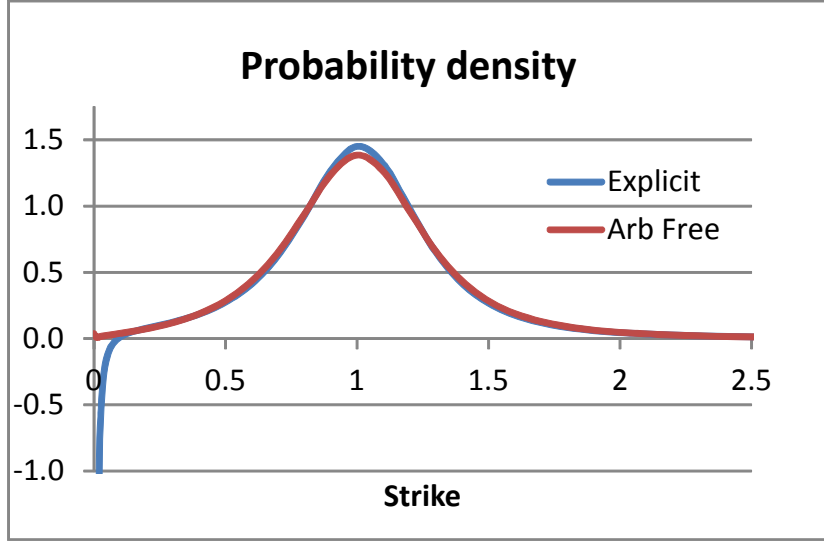


FIG. 2.3. Probability density for the SABR model for $\alpha = 35\%$, $\beta = 0.25$, $\rho = -10\%$, and $\nu = 100\%$. Shown are the densities obtained from the explicit formulas for $\sigma_N(K)$ and from the arbitrage-free approach for $\tau_{ex} = 1yr$.

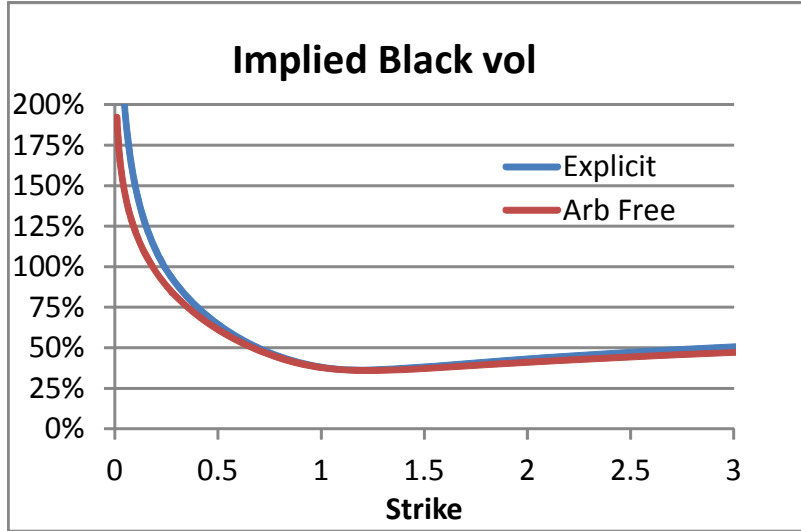


FIG. 2.4. The implied log normal volatility from the SABR model at $\tau_{ex} = 1yr$ for $\alpha = 35\%$, $\beta = 25\%$, $\rho = -10\%$, $\nu = 100\%$. Shown are the implied volatilities from the explicit $\sigma_N(K)$, and from the arbitrage-free approach.

which is the probability density that $\tilde{F}(T) = F$ at time T , regardless of the value of $\tilde{A}(T)$. Although Q is also a function of the backward variables t, f, α , we have omitted explicitly showing this dependence for clarity.

In appendix A we use singular perturbation techniques to analyze the Fokker-Planck equation, 3.1b. This analysis shows that the marginal density satisfies the PDE

$$(3.3a) \quad Q_T^c = \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q^c]_{FF} \quad \text{for } T > t,$$

through $O(\varepsilon^2)$, where

$$(3.3b) \quad D^2(F) = [1 + 2\varepsilon\rho\nu z(F) + \varepsilon^2\nu^2 z^2(F)] e^{\varepsilon^2\rho\nu a\Gamma(F)(T-t)} C^2(F),$$

and where $z(F)$ and $\Gamma(F)$ are defined by

$$(3.3c) \quad z(F) \equiv \frac{1}{\varepsilon\alpha} \int_f^F \frac{df'}{C(f')}, \quad \Gamma(F) \equiv \frac{C(F) - C(f)}{F - f}.$$

This effective forward equation reduces the dimensionality from two space dimensions (F and A) to one space dimension (F only), while retaining the same order of accuracy as the original SABR analysis [1], [2]. In particular, the factor $e^{\varepsilon^2\rho\nu a\Gamma(F)(T-t)}$ generally makes a very tiny, but non-negligible correction. We have added a c superscript to denote that this is the continuous part of the density.

For the special case $C(F) = F^\beta$, we have

$$(3.4) \quad z(F) \equiv \frac{F^{1-\beta} - f^{1-\beta}}{\varepsilon\alpha(1-\beta)}, \quad \Gamma(F) \equiv \frac{F^\beta - f^\beta}{F - f}.$$

3.2. Boundary conditions. The SABR model has an innate barrier where $C(F) = 0$, or, equivalently, where $D(F) = 0$. Traditionally this barrier is at $F = 0$, as it is for $C(F) = F^\beta$, but currently there is an active debate over whether rates can be negative, and if so, how negative they can become. Appendix E explores an alternative model, $C(F) = (F + b)^\beta$, which puts the barrier at $-b$.

We solve the PDE numerically, which requires a finite domain $F_{\min} < F < F_{\max}$. It is natural to place the lower boundary at the barrier, but not essential, and there may well be situations in which a different boundary makes more sense. So we do not assume that F_{\min} is necessarily at the barrier. F_{\max} should be chosen to be large enough so that the boundary doesn't affect the pricing appreciably.

Boundary conditions are examined in Appendix B. Since there may be a net flow of probability into the boundaries, and since we are not considering models in which the forward $\tilde{F}(T)$ can leave the domain, we need to allow for probability to accumulate at the boundaries. That is, we need to allow δ -functions in the probability density,

$$(3.5) \quad Q(T, F) = \begin{cases} Q^L(T)\delta(F - F_{\min}) & \text{at } F = F_{\min} \\ Q^c(T, F) & \text{for } F_{\min} < F < F_{\max} \\ Q^R(T)\delta(F - F_{\max}) & \text{at } F = F_{\max} \end{cases}.$$

Here, the superscript c is used to denote the continuous part of the density.

The total probability has to be 1 for all T ,

$$(3.6) \quad Q^L(T) + \int_{F_{\min}}^{F_{\max}} Q^c(T, F) dF + Q^R(T) = 1.$$

so

$$(3.7) \quad \frac{d}{dT} \left\{ Q^L(T) + \int_{F_{\min}}^{F_{\max}} Q^c(T, F) dF + Q^R(T) \right\} = 0.$$

Substituting 3.3a for Q_T^c and integrating leads to

$$(3.8) \quad \frac{dQ^L}{dT} + \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q^c]_F \Big|_{F_{\min}}^{F_{\max}} + \frac{dQ^R(T)}{dT} = 0.$$

Thus, conservation of probability requires that

$$(3.9a) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_F,$$

$$(3.9b) \quad \frac{dQ^R}{dT} = \lim_{F \rightarrow F_{\max}^-} -\frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_F.$$

Similarly, for $\tilde{F}(T)$ to be a martingale, its expected value must be fixed:

$$(3.10) \quad \begin{aligned} E \left\{ \tilde{F}(T) \middle| \tilde{F}(t) = f, \tilde{A}(t) = \alpha \right\} \\ = F_{\min} Q_L(T) + \int_{F_{\min}}^{F_{\max}} F Q^c(T, F) dF + F_{\max} Q^R(T) = f. \end{aligned}$$

Therefore,

$$(3.11) \quad F_{\min} \frac{dQ_L(T)}{dT} + \int_{F_{\min}}^{F_{\max}} F Q_T^c(T, F) dF + F_{\max} \frac{dQ^R(T)}{dT} = 0.$$

Substituting 3.3a for Q_T^c , integrating by parts twice, and using equations 3.9a, 3.9b leads to

$$(3.12) \quad D^2(F)Q^c|_{F_{\min}}^{F_{\max}} = 0.$$

So we must require absorbing boundary conditions,

$$(3.13a) \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+,$$

$$(3.13b) \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\max}^-,$$

to ensure that $\tilde{F}(T)$ is a martingale.

In summary, we solve

$$(3.14a) \quad Q_T^c = \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_{FF} \quad \text{for } F_{\min} < F < F_{\max},$$

with the boundary condition

$$(3.14b) \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+, \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\max}^-,$$

for $t < T < \tau_{ex}$. The probabilities at the boundary are given by

$$(3.14c) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_F,$$

$$(3.14d) \quad \frac{dQ^R}{dT} = \lim_{F \rightarrow F_{\max}^-} -\frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_F,$$

and the initial conditions are

$$(3.14e) \quad Q^L(0) = 0, \quad Q^c(T, F) \rightarrow \delta(F - f) \quad Q^R(0) = 0, \quad \text{as } T \rightarrow t^+.$$

3.3. Option pricing. In Appendix C we sketch out a Crank-Nicholson scheme [8] for solving 3.14a - 3.14e for $Q^c(T, F)$, $Q^L(T)$, and $Q^R(T)$. This scheme conserves probability and the expected value of $\tilde{F}(T)$, so equations 3.6 and 3.10 remain exactly true for the numerical solution. Once we have solved these equations, the call and put prices are obtained by integrating:

$$(3.15a) \quad V_{call}(\tau_{ex}, K) = f - K \quad \text{for } K < F_{\min},$$

$$(3.15b) \quad V_{call}(\tau_{ex}, K) = \int_K^{F_{\max}} (F - K) Q^c(\tau_{ex}, F) dF + (F_{\max} - K) Q^R(\tau_{ex}) \quad \text{for } F_{\min} < K < F_{\max},$$

$$(3.15c) \quad V_{call}(\tau_{ex}, K) = 0 \quad \text{for } K > F_{\max},$$

$$(3.15d) \quad V_{put}(\tau_{ex}, K) = 0 \quad \text{for } K < F_{\min},$$

$$(3.15e) \quad V_{put}(\tau_{ex}, K) = \int_{F_{\min}}^K (K - F) Q^c(\tau_{ex}, F) dF + (K - F_{\min}) Q^L(\tau_{ex}) \quad \text{for } F_{\min} < K < F_{\max},$$

$$(3.15f) \quad V_{put}(\tau_{ex}, K) = K - f \quad \text{for } K > F_{\max}.$$

The conservation of probability 3.6 and martingale property 3.10 show that put-call parity holds exactly for the numerical solution:

$$(3.16) \quad V_{call}(\tau_{ex}, K) - V_{put}(\tau_{ex}, K) = f - K.$$

The maximum principle for parabolic equations [15] guarantees that $Q^c(T, F) \geq 0$ for $F_{\min} < F < F_{\max}$, and that $Q^L(T)$ and $Q^R(T)$ are increasing, and hence positive. For fine enough grids, the numerical solutions will also be non-negative. Thus, the numerical option prices are exactly arbitrage free [13], [14].

The effective forward equation has only one space dimension, so solving the PDE is essentially instantaneous. Solving these equations for $t < T < \tau_{ex}$ yields the option prices for all strikes K . Thus the implied normal volatilities $\sigma_N(K)$ for all strikes K can be obtained by solving the PDE once.

4. Discussion.

4.1. Results. Singular perturbation techniques can be used to analyze the effective forward equation,

$$(4.1a) \quad Q_T^c = \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F) Q^c]_{FF} \quad \text{for } T > t,$$

where

$$(4.1b) \quad D(F) = (1 + 2\varepsilon \rho \nu z(F) + \varepsilon^2 \nu^2 z^2(F)) e^{\varepsilon^2 \rho \nu a \Gamma(F)(T-t)} C^2(F),$$

with

$$(4.1c) \quad z(F) \equiv \frac{1}{\varepsilon \alpha} \int_f^F \frac{df'}{C(f')}, \quad \Gamma(F) \equiv \frac{C(F) - C(f)}{F - f}.$$

From this analysis we can obtain explicit option prices, and these prices can be used to find explicit formulas for the implied volatility $\sigma_N(K)$. Away from the boundaries F_{\min} and F_{\max} , this analysis leads to the same explicit implied volatility formulas 1.5a-1.5c as before, at least if we continue to work through $O(\varepsilon^2)$. Thus, away from the boundaries, the “arbitrage-free” implied volatility obtained by numerically solving the effective forward equation should match the explicit implied volatility formulas to within $O(\varepsilon^2)$. This is indeed our experience. Even in relatively extreme cases, such as Figure 2.1, the “arbitrage-free” and explicit implied volatilities match closely, except when the strike K or the forward f is too close to the boundary F_{\min} .

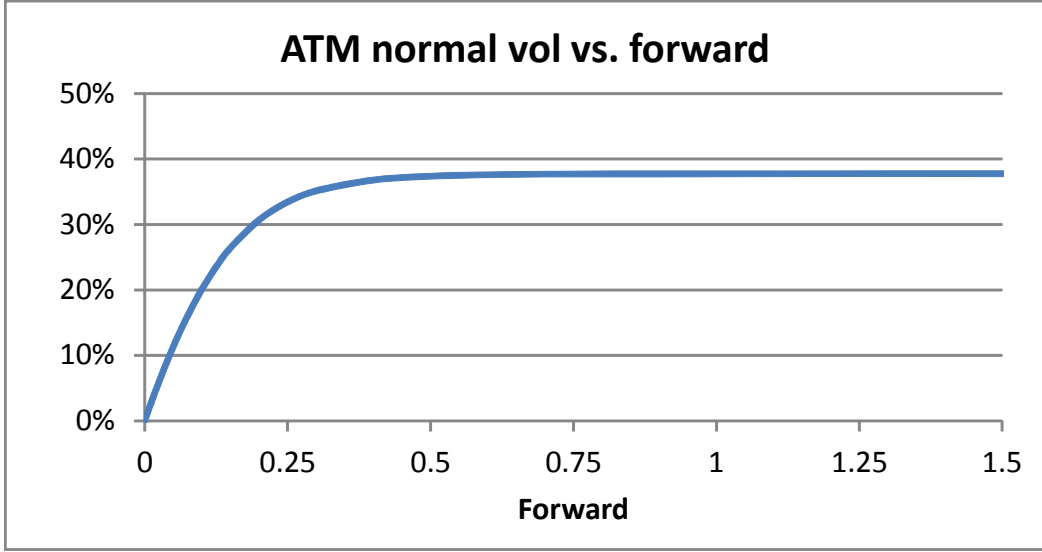


FIG. 4.1. The at-the-money implied normal volatility $\sigma_N(f)$ at $\tau_{ex} = 1\text{yr}$ for the arbitrage-free SABR model with $\alpha = 35\%$, $\beta = 0$, $\rho = 0$, and $\nu = 100\%$.

For values of F within $O(\varepsilon)$ of the lower boundary F_{\min} , a non-negligible percentage of paths that would have reached F hit the boundary. This creates an $O(\varepsilon)$ thick boundary layer at F_{\min} , in which the explicit implied volatility formulas do not pertain. Instead, as the strike approaches F_{\min} , the implied normal volatility $\sigma_N(K)$ bends towards zero. See Figure 2.1

Figure 4.1 shows the effect of the boundary layer on the normal volatility of *at-the-money* options. As today's forward f decreases to within $O(\varepsilon)$ of F_{\min} , an increasing percentage of the paths reach the boundary before the expiry date, which reduces the ATM volatility. This creates a “knee” in the graph, which makes it appear that the market switches from a normal to a log normal regime when the forward is sufficiently small. This is an illusion; this graph comes from the SABR model with $\beta = 0$ and $\rho = 0$, which is a stochastic *normal* model. The reduction is caused solely by the boundary layer. Figure 4.2 shows the smiles $\sigma_N(K)$ obtained for different values of the forward f , using the same SABR parameters.

Market data for at-the-money swaption volatilities exhibit this “knee.” Historical studies comparing ATM normal volatilities with forward rates show that when the forward rate is above a critical value, the ATM normal volatilities are reasonably constant; for forward rates below the critical value, the ATM volatilities decrease linearly with the rate. See figure 4.3.

This knee is often explained as the market switching from normal to log normal behavior in ultra-low rate environments. This belief is often reinforced by using the explicit implied volatility formulas to calibrate the SABR model. Calibrating the explicit formulas to observed smiles can lead to relatively high values of β and/or ρ for low forward rates. Since high values of β and ρ push up the high strike volatilities, this can create significant mispricing for instruments which are sensitive to *high* strikes, like constant maturity caps, floors, and swaps. To counter this, some groups have chosen to use

$$(4.2) \quad C(F) = \begin{cases} F & \text{for } F < F_0 \\ F_0 & \text{for } F > F_0 \end{cases}$$

in place of F^β . We believe that our approach provides a more natural explanation, since the knee occurs automatically, without requiring gross changes between the SABR parameters for low and moderate rate environments.

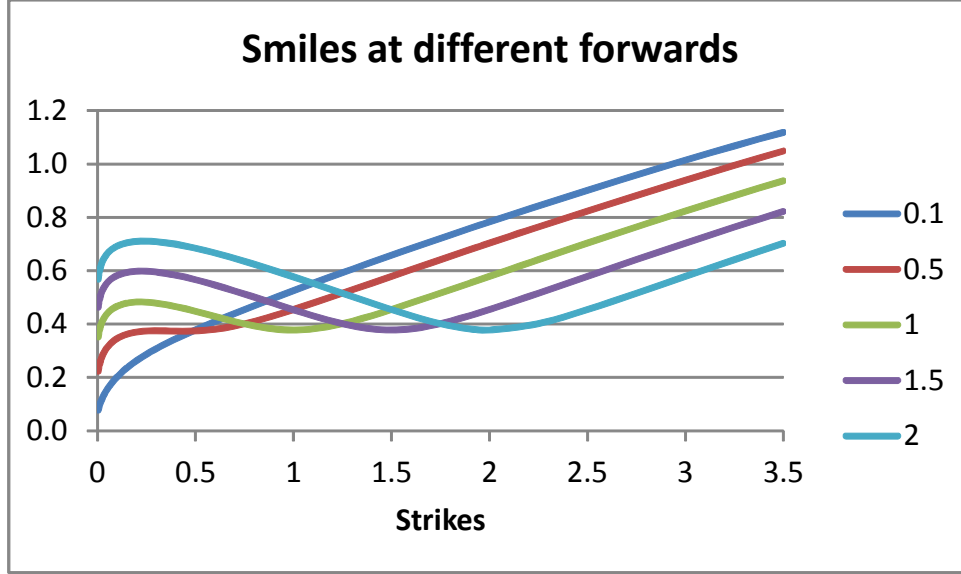


FIG. 4.2. The smiles $\sigma_N(K)$ at $\tau_{ex} = 1\text{yr}$ for different values of the forward f for the SABR model with $\alpha = 35\%$, $\beta = 0$, $\rho = 0\%$, and $\nu = 100\%$.

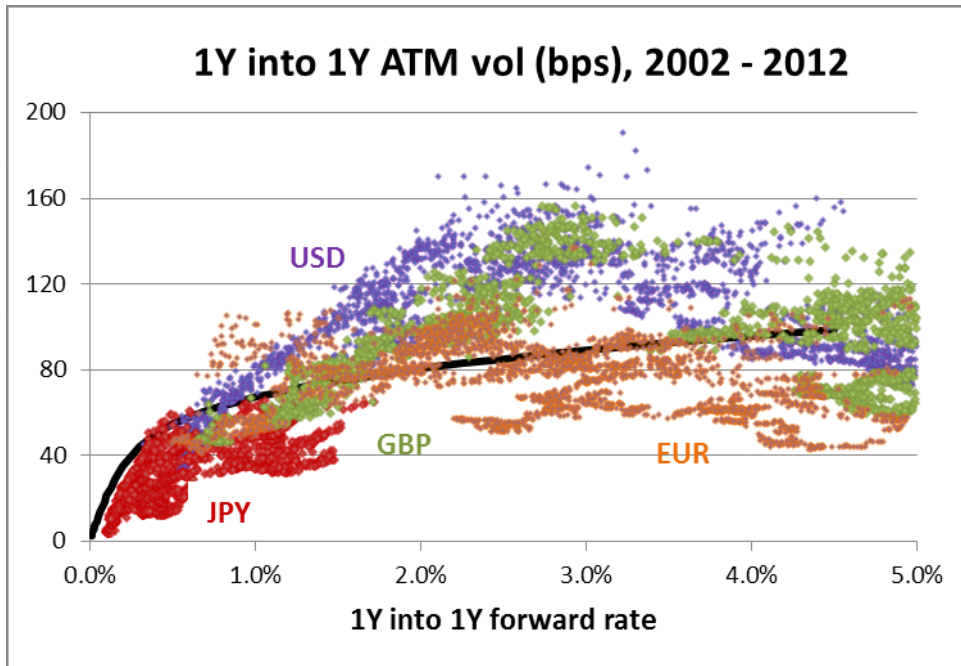


FIG. 4.3. The normal volatilities for 1Y into 1Y at-the-money swaptions vs. the forward swap rate. Shown are the historic data for 2002 through 2012 for USD, GBP, EUR, and JPY swaptions. Also shown is the implied volatility obtained from the SABR model for $\alpha = 65\%$, $\beta = 0.25$, $\rho = 0\%$, and $\nu = 75\%$. Data courtesy of Bloomberg LP and AVM LP.

4.2. No local volatility model. The coefficients in the effective forward equation 4.1a - 4.1c depend on the current forward f as well as F . This means that

- there is no obvious “effective backward equation” equivalent to the effective forward equation;
- the effective forward equation is *not* the Fokker-Planck equation (forward Kolmogorov equation) for a one dimensional Itô process.

That is, *there is not an effective one dimensional local volatility model* corresponding to the effective forward equation. This should have been anticipated as the SABR model was created because of perceived shortcomings of local volatility models [1].

4.3. Hedging. When the SABR model is calibrated to market data, it is very difficult to distinguish between β and ρ ; both control the skew. If we fix β , say, and calibrate the rest of the parameters, the quality of the fit is often fairly independent of the particular value of β chosen. This is illustrated in Figure 4.4. There we have chosen $\beta = 0, \frac{1}{2}$, and 1, and calibrated the SABR model to the same market data for all three cases. This yields the following set of SABR parameters:

α	31.8%	32.9%	35.1%
β	0	0.5	1
ρ	-18.3%	-45.5%	-64.4%
ν	0.777	0.867	0.985

Although the tails of the smiles are somewhat different, all three sets of parameters seem to fit the actual market data.

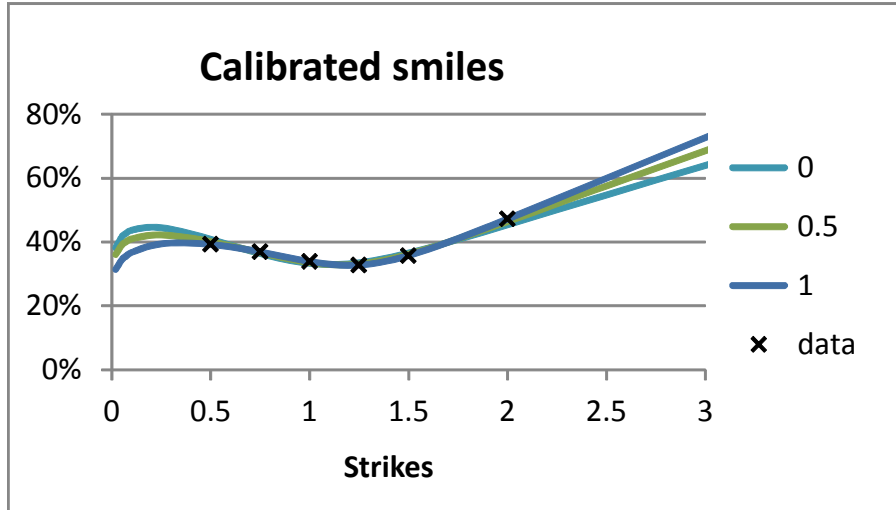


FIG. 4.4. The SABR model calibrated to the same market data for $\beta = 0$, $\beta = \frac{1}{2}$, and $\beta = 1$. Because ρ can largely compensate for β , all three fits are well within market noise.

The conventional delta risk is calculated by shifting the current forward f and keeping the current volatility α fixed:

$$(4.3) \quad f \rightarrow f + \Delta f, \quad \alpha \rightarrow \alpha.$$

If the delta risk is calculated in the conventional way, then delta depends on the particular value of β used. This is shown in Figure 4.5. There we have calculated the conventional delta of a call option as a function

of the strike K for the same three sets of SABR parameters. Even though all three sets lead to essentially the same smile (especially for strikes which are not too extreme), we see that the different choices of β have led to different values of delta. This means that if we hedge our positions using the conventional delta, choosing a poor β may lead to a poor hedge, even though it may lead to a superb fit of the market data.

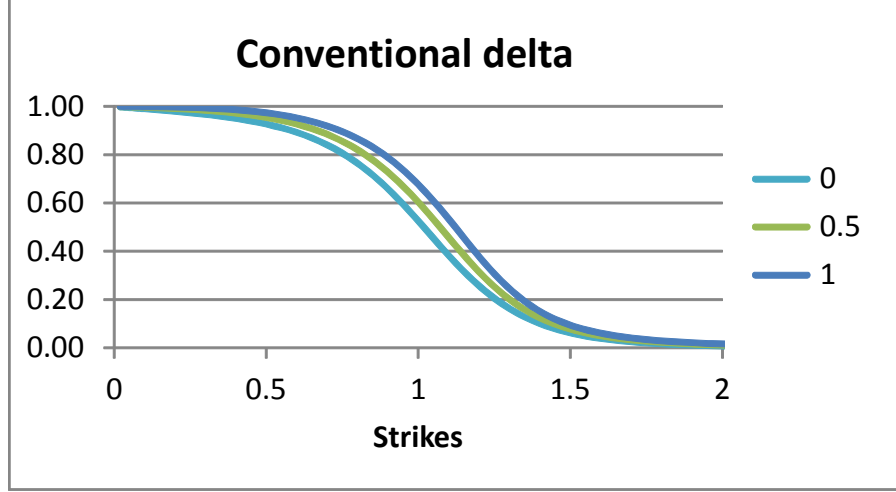


FIG. 4.5. The conventional delta, $\partial V / \partial F$, as a function of the strike K for $\beta = 0$, $\beta = \frac{1}{2}$, and $\beta = 1$. For each β , the other three parameters α , ρ , and ν are chosen to match the arbitrage-free SABR smile to the market data.

This issue led to an alternative approach for calculating delta hedges. Since \tilde{F} and \tilde{A} are correlated, when \tilde{F} changes then \tilde{A} changes as well, at least on average. It is argued that accounting for this shift should result in a better hedge [16]:

$$(4.4) \quad f \rightarrow f + \Delta f, \quad \alpha \rightarrow \alpha + \Delta \alpha.$$

To compute the amount of the α shift, we re-write the SABR model as

$$(4.5a) \quad d\tilde{F} = \varepsilon \tilde{A} C(\tilde{F}) d\tilde{W}_1,$$

$$(4.5b) \quad d\tilde{A} = \varepsilon \nu \tilde{A} \left\{ \rho d\tilde{W}_1 + \sqrt{1 - \rho^2} d\tilde{Z} \right\},$$

where $d\tilde{W}_1$ and $d\tilde{Z}$ are independent. This implies that

$$(4.6) \quad d\tilde{A} = \frac{\rho \nu}{C(\tilde{F})} d\tilde{F} + \varepsilon \sqrt{1 - \rho^2} \nu \tilde{A} d\tilde{Z}.$$

So changes in $\tilde{A}(T)$ can be split into two components, one caused by changes in $\tilde{F}(T)$, and one due to idiosyncratic changes in the volatility. Accordingly, the delta hedge should be calculated with respect to the scenario [16]

$$(4.7) \quad f \rightarrow f + \Delta f, \quad \alpha \rightarrow \alpha + \frac{\rho \nu}{C(f)} \Delta f.$$

Figure 4.6 shows this alternative delta as a function of the strike K for the same three sets of SABR parameters used above. We calculated these deltas by simply bumping the f and α values input into the

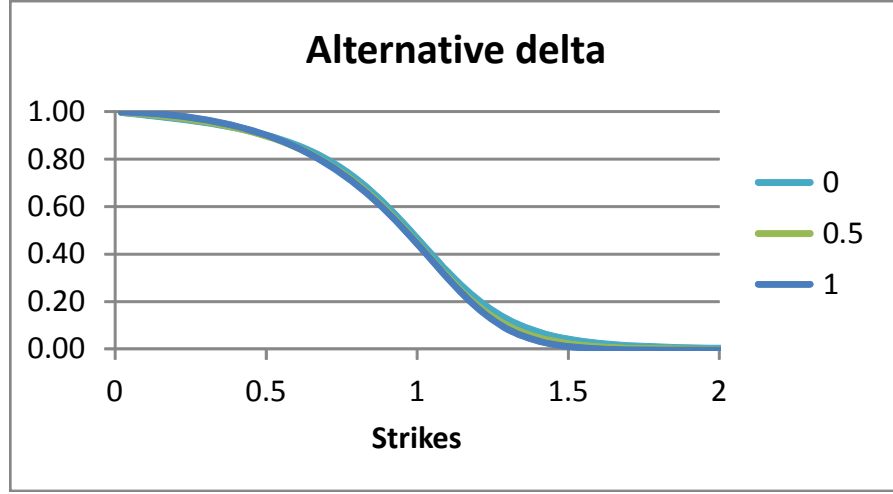


FIG. 4.6. The alternative delta, $\partial V / \partial f + [\rho \nu / C(f)] \partial V / \partial \alpha$, as a function of the strike K for $\beta = 0$, $\beta = \frac{1}{2}$, and $\beta = 1$. For each β , the other three parameters α , ρ , and ν are chosen to match the arbitrage-free SABR smile to the market data.

pricing code according to 4.7. We see that this alternative delta is nearly independent of the particular value of β chosen. This has proven true for all cases we have investigated: as long as the SABR model fits market data decently, the alternative delta is nearly independent of the particular values of β or ρ used in the fitting. Apparently this new delta depends mostly on the actual market smile, and not on how the smiles and skews are represented within the model. The alternative deltas are the same as the conventional deltas when the correlation ρ is zero. This may be why some groups prefer to set $\rho = 0$ and calibrate α , β , and ν to the market smiles.

It is generally accepted that hedges based on the alternative delta are superior to ones based on the conventional delta when a desk is only hedging delta. Which delta hedge is used, is irrelevant when a desk is hedging both delta and vega, provided one doesn't double count the vega hedge.

Appendix A. Derivation of the effective forward equation.

Here we analyze the SABR model

$$(A.1a) \quad d\tilde{F} = \varepsilon \tilde{A} C(\tilde{F}) d\tilde{W}_1,$$

$$(A.1b) \quad d\tilde{A} = \varepsilon \nu \tilde{A} d\tilde{W}_2,$$

$$(A.1c) \quad d\tilde{W}_1 d\tilde{W}_2 = \rho dt,$$

in the limit $\varepsilon \ll 1$, using singular perturbation methods to derive the effective forward equation.

Recall that $p(t, f, \alpha; T, F, A)$ is the probability density that $\tilde{F}(T) = F$, $\tilde{A}(T) = A$ at time T , given that $\tilde{F}(t) = f$ and $\tilde{A}(t) = \alpha$ at time t . Define the moments

$$(A.2a) \quad Q^{(k)}(t, f, \alpha; T, F) = \int_0^\infty A^k p(t, f, \alpha; T, F, A) dA \\ = E \left\{ A^k \delta(\tilde{F}(T) - F) \mid \tilde{F}(t) = f, \tilde{A}(t) = \alpha \right\}.$$

Clearly the zeroeth moment $Q^{(0)}$ is the probability density of being at F at time T ,

$$(A.2b) \quad Q(T, F) = Q^{(0)}(t, f, \alpha; T, F),$$

regardless of the value of $\tilde{A}(T)$.

The density p satisfies the Fokker-Planck equation

$$(A.3a) \quad p_T = \frac{1}{2}\varepsilon^2 [C^2(F)A^2p]_{FF} + \varepsilon^2 \rho \nu [C(F)A^2p]_{FA} + \frac{1}{2}\varepsilon^2 \nu^2 [A^2p]_{AA} \quad \text{for all } T > t,$$

with the initial condition

$$(A.3b) \quad p = \delta(F - f)\delta(A - \alpha) \quad \text{for all } T \rightarrow t^+.$$

Now

$$(A.4a) \quad \int_0^\infty [C(F)A^2p]_{FA} dA = [C(F)A^2p]_F \Big|_{A=0}^{A=+\infty} = 0,$$

$$(A.4b) \quad \int_0^\infty [A^2p]_{AA} dA = [A^2p]_A \Big|_{A=0}^{A=+\infty} = 0,$$

for all F . This just states that there is no probability flux across the boundaries at $A = 0$ and $A = \infty$; i.e., that probability is conserved. Integrating the Fokker-Planck equation across all A now yields

$$(A.5) \quad Q_T^{(0)} = \frac{1}{2}\varepsilon^2 [C^2(F)Q^{(2)}]_{FF} \quad \text{for } T > t,$$

showing that the evolution of the reduced density $Q^{(0)}$ depends on the second moment $Q^{(2)}$.

Under the SABR model these moments satisfy the backward Kolmogorov equation

$$(A.6a) \quad Q_t^{(k)} + \frac{1}{2}\varepsilon^2 \alpha^2 C^2(f) Q_{ff}^{(k)} + \varepsilon^2 \rho \nu \alpha^2 C(f) Q_{f\alpha}^{(k)} + \frac{1}{2}\varepsilon^2 \nu^2 \alpha^2 Q_{\alpha\alpha}^{(k)} = 0 \quad \text{for } t < T,$$

subject to the condition

$$(A.6b) \quad Q^{(k)}(t, f, \alpha; T, F) \rightarrow \alpha^k \delta(F - f) \quad \text{as } t \rightarrow T^-.$$

We will successively transform this equation order-by-order until all the α derivatives are negligibly small [17], [18]. Instead of constructing explicit asymptotic solutions to the resulting problem, as was done in the original SABR paper [1], here we seek to write $Q^{(2)}$ in terms of $Q^{(0)}$. This provides the “constitutive law” needed to close the “conservation law” A.5, which is then the effective forward equation. Throughout we work through $O(\varepsilon^2)$, neglecting higher order terms.

Since the backward equation is autonomous, the moments $Q^{(k)}$ depend only on

$$(A.7) \quad \tau = T - t,$$

and not on T or t separately. We first change independent variables from f to

$$(A.8a) \quad z = \frac{1}{\varepsilon\alpha} \int_f^F \frac{df'}{C(f')}.$$

For clarity, we also introduce

$$(A.8b) \quad B(\varepsilon\alpha z) = C(f).$$

Then

$$(A.9a) \quad \frac{\partial}{\partial f} \longrightarrow \frac{-1}{\varepsilon\alpha C(f)} \frac{\partial}{\partial z} = \frac{-1}{\varepsilon\alpha B(\varepsilon\alpha z)} \frac{\partial}{\partial z}, \quad \frac{\partial}{\partial \alpha} \longrightarrow \frac{\partial}{\partial \alpha} - \frac{z}{\alpha} \frac{\partial}{\partial z}$$

$$(A.9b) \quad \frac{\partial^2}{\partial f^2} \longrightarrow \frac{1}{\varepsilon^2 \alpha^2 B^2(\varepsilon \alpha z)} \left\{ \frac{\partial^2}{\partial z^2} - \varepsilon \alpha \frac{B'(\varepsilon \alpha z)}{B(\varepsilon \alpha z)} \frac{\partial}{\partial z} \right\},$$

$$(A.9c) \quad \frac{\partial^2}{\partial f \partial \alpha} \longrightarrow \frac{1}{\varepsilon \alpha B(\varepsilon \alpha z)} \left\{ -\frac{\partial^2}{\partial z \partial \alpha} + \frac{z}{\alpha} \frac{\partial^2}{\partial z^2} + \frac{1}{\alpha} \frac{\partial}{\partial z} \right\},$$

$$(A.9d) \quad \frac{\partial^2}{\partial \alpha^2} \longrightarrow \frac{\partial^2}{\partial \alpha^2} - \frac{2z}{\alpha} \frac{\partial^2}{\partial z \partial \alpha} + \frac{z^2}{\alpha^2} \frac{\partial^2}{\partial z^2} + \frac{2z}{\alpha^2} \frac{\partial}{\partial z},$$

and

$$(A.9e) \quad \delta(f - F) = \delta(\varepsilon \alpha z C(F)) = \frac{1}{\varepsilon \alpha B(0)} \delta(z).$$

The backward equation now becomes

$$(A.10a) \quad Q_\tau^{(k)} = \frac{1}{2} (1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) Q_{zz}^{(k)} - \frac{1}{2} \varepsilon \alpha \frac{B'(\varepsilon \alpha z)}{B(\varepsilon \alpha z)} Q_z^{(k)} \\ + (\varepsilon \rho \nu + \varepsilon^2 \nu^2 z) \left(-\alpha Q_{\alpha z}^{(k)} + Q_z^{(k)} \right) + \frac{1}{2} \varepsilon^2 \nu^2 \alpha^2 Q_{\alpha \alpha}^{(k)} \quad \text{for } \tau > 0,$$

with the initial condition

$$(A.10b) \quad Q^{(k)}(\tau, z, \alpha) \rightarrow \frac{\alpha^{k-1}}{\varepsilon B(0)} \delta(z) \quad \text{as } \tau \rightarrow 0^+.$$

Accordingly, we define $\hat{Q}^{(k)}(\tau, z, \alpha)$ by

$$(A.11) \quad Q^{(k)}(\tau, z, \alpha) = \frac{\alpha^{k-1}}{\varepsilon B(0)} \hat{Q}^{(k)}(\tau, z, \alpha).$$

Then $\hat{Q}^{(k)}(\tau, z, \alpha)$ satisfies

$$(A.12a) \quad \hat{Q}_\tau^{(k)} = \frac{1}{2} (1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) \hat{Q}_{zz}^{(k)} - \frac{1}{2} \varepsilon \alpha \frac{B'(\varepsilon \alpha z)}{B(\varepsilon \alpha z)} \hat{Q}_z^{(k)} \\ - (\varepsilon \rho \nu + \varepsilon^2 \nu^2 z) (k-2) \hat{Q}_z^{(k)} - (\varepsilon \rho \nu + \varepsilon^2 \nu^2 z) \alpha \hat{Q}_{\alpha z}^{(k)} \\ + \frac{1}{2} \varepsilon^2 \nu^2 \left\{ \alpha^2 \hat{Q}_{\alpha \alpha}^{(k)} + 2(k-1) \alpha \hat{Q}_\alpha^{(k)} + (k-1)(k-2) \hat{Q}^{(k)} \right\} \quad \text{for } \tau > 0,$$

with

$$(A.12b) \quad \hat{Q}^{(k)}(\tau, z, \alpha) \rightarrow \delta(z) \quad \text{as } \tau \rightarrow 0^+.$$

To leading order, the equation and initial condition for $\hat{Q}^{(k)}(\tau, z, \alpha)$ are

$$(A.13a) \quad \hat{Q}_\tau^{(k)} = \frac{1}{2} \hat{Q}_{zz}^{(k)}$$

$$(A.13b) \quad \hat{Q}^{(k)}(\tau, z, \alpha) \rightarrow \delta(z) \quad \text{as } \tau \rightarrow 0^+,$$

and are independent of α to leading order. Therefore, if we *were* to expand

$$(A.14) \quad \hat{Q}^{(k)}(\tau, z, \alpha) = \hat{Q}_0^{(k)}(\tau, z) + \varepsilon \hat{Q}_1^{(k)}(\tau, z, \alpha) + \varepsilon^2 \hat{Q}_2^{(k)}(\tau, z, \alpha) + \dots,$$

then the leading term $\hat{Q}_0^{(k)}(\tau, z)$ would not depend on α . Consequently, the terms $\varepsilon^2 \nu^2 z \alpha \hat{Q}_{\alpha z}^{(k)}$, $\varepsilon^2 \nu^2 \alpha^2 \hat{Q}_{\alpha\alpha}^{(k)}$, and $\varepsilon^2 \nu^2 \alpha \hat{Q}_{\alpha}^{(k)}$ are actually no larger than $O(\varepsilon^3)$. Since we are only working through $O(\varepsilon^2)$, we drop these terms, obtaining³

$$(A.15a) \quad \begin{aligned} \hat{Q}_\tau^{(k)} = \frac{1}{2} (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) \hat{Q}_{zz}^{(k)} - \frac{1}{2}\varepsilon\alpha \frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)} \hat{Q}_z^{(k)} \\ - (\varepsilon\rho\nu + \varepsilon^2\nu^2 z) (k-2) \hat{Q}_z^{(k)} - \varepsilon\rho\nu\alpha \hat{Q}_{\alpha z}^{(k)} \\ + \frac{1}{2}\varepsilon^2\nu^2 (k-1)(k-2) \hat{Q}^{(k)} \end{aligned} \quad \text{for } \tau > 0,$$

with

$$(A.15b) \quad \hat{Q}^{(k)}(\tau, z, \alpha) \rightarrow \delta(z) \quad \text{as } \tau \rightarrow 0^+.$$

In [1] we continued transforming the equations until we could construct the explicit asymptotic solution to A.15a, A.15b. Here we take a different tack. We note that for $k = 2$,

$$(A.16a) \quad \hat{Q}_\tau^{(2)} = \frac{1}{2} (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) \hat{Q}_{zz}^{(2)} - \frac{1}{2}\varepsilon\alpha \frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)} \hat{Q}_z^{(2)} - \varepsilon\rho\nu\alpha \hat{Q}_{\alpha z}^{(2)},$$

whilst the equation for $k = 0$ can be written as

$$(A.16b) \quad \hat{Q}_\tau^{(0)} = \frac{1}{2} \left[(1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) \hat{Q}^{(0)} \right]_{zz} - \frac{1}{2}\varepsilon\alpha \frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)} \hat{Q}_z^{(0)} - \varepsilon\rho\nu\alpha \hat{Q}_{\alpha z}^{(0)}.$$

These equations are very similar, and both $\hat{Q}^{(2)}$ and $\hat{Q}^{(0)}$ satisfy the same initial condition:

$$(A.16c) \quad \hat{Q}^{(2)}(\tau, z, \alpha) \rightarrow \delta(z) \quad \hat{Q}^{(0)}(\tau, z, \alpha) \rightarrow \delta(z) \quad \text{as } \tau \rightarrow 0^+.$$

We now apply near-identity transformations to $\hat{Q}^{(0)}$ until the transformed quantity satisfies the equation for $\hat{Q}^{(2)}$ through $O(\varepsilon^2)$. We can then conclude that the transformed quantity must equal $\hat{Q}^{(2)}$ through $O(\varepsilon^2)$, allowing us to write the second moment in terms of $\hat{Q}^{(0)}$. This is then the relation we need to close A.5.

Define

$$(A.17) \quad \hat{U}(\tau, z, \alpha) = (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) \hat{Q}^{(0)}(\tau, z, \alpha).$$

Multiplying eq. A.16b by $(1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2)$ shows that

$$(A.18) \quad \begin{aligned} \hat{U}_\tau = \frac{1}{2} (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) \hat{U}_{zz} - \frac{1}{2}\varepsilon\alpha \frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)} \hat{U}_z - \varepsilon\rho\nu\alpha \hat{U}_{\alpha z} \\ + \varepsilon^2\rho\nu\alpha \frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)} \hat{U}, \end{aligned}$$

through $O(\varepsilon^2)$. Here we have neglected the term $2\varepsilon^2\rho^2\nu^2\alpha\hat{U}_\alpha$; since \hat{U} does not depend on α at leading order, this term can be no larger than $O(\varepsilon^3)$. Apart from the last term, this equation is identical to equation A.16a for $\hat{Q}^{(2)}$. To eliminate the last term, define

$$(A.19a) \quad U(\tau, z, \alpha) = \hat{U}(\tau, z, \alpha) e^{\varepsilon^2\rho\nu\alpha\Gamma\tau} = (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) e^{\varepsilon^2\rho\nu\alpha\Gamma\tau} \hat{Q}^{(0)}(\tau, z, \alpha),$$

³These terms are exactly zero for the special case of $C(F)$ being constant. Then $B'(\varepsilon\alpha z) \equiv 0$ and the solutions $\hat{Q}^{(k)}$ are independent of α . Consequently, the effective forward equation A.23 is exact in this case.

where

$$(A.19b) \quad \Gamma = -\frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)}.$$

Since $\varepsilon^2\Gamma_z$, $\varepsilon^2\Gamma_\alpha$, $\varepsilon^2\Gamma_{zz}$, and $\varepsilon^2\Gamma_{z\alpha}$ are all no larger than $O(\varepsilon^3)$, eq. A.18 shows that U satisfies

$$(A.20a) \quad U_\tau = \frac{1}{2} (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) U_{zz} - \frac{1}{2}\varepsilon\alpha \frac{B'(\varepsilon\alpha z)}{B(\varepsilon\alpha z)} U_z - \varepsilon\rho\nu\alpha U_{\alpha z} \quad \text{for } \tau > 0$$

through $O(\varepsilon^2)$, with

$$(A.20b) \quad U \rightarrow \delta(z) \quad \text{as } \tau \rightarrow 0^+.$$

This is identical to the PDE and initial condition for $\hat{Q}^{(2)}$, so uniqueness allows us to conclude that U and $\hat{Q}^{(2)}$ are the same through $O(\varepsilon^2)$:

$$(A.21) \quad \hat{Q}^{(2)}(\tau, z, \alpha) = (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2 + \dots) e^{\varepsilon^2\rho\nu\alpha\Gamma\tau} \hat{Q}^{(0)}(\tau, z, \alpha).$$

We now chase back through the transformations, obtaining

$$(A.22a) \quad Q^{(2)}(t, f, \alpha; T, F) = \alpha^2 \{1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2 + \dots\} e^{+\varepsilon^2\rho\nu\alpha\Gamma(T-t)} Q^{(0)}(t, f, \alpha; T, F)$$

through $O(\varepsilon^2)$, where

$$(A.22b) \quad \Gamma = -B'(\varepsilon\alpha z)/B(\varepsilon\alpha z) = C'(F).$$

Substituting equation A.22a into the conservation equation, A.5, we obtain

$$(A.23) \quad Q_T^{(0)} = \frac{1}{2}\varepsilon^2\alpha^2 \left[(1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) e^{+\varepsilon^2\rho\nu\alpha\Gamma(T-t)} C^2(F) Q^{(0)} \right]_{FF}$$

for $T > t$. This is the effective forward equation for $Q(T, F) \equiv Q^{(0)}(t, f, \alpha; T, F)$.

In the derivation we could have used $\Gamma = C'(F)$ or $C'(f)$ or even $C'([f + F]/2)$ or any other reasonable choice without losing the $O(\varepsilon^2)$ accuracy of the final result. Higher order analysis suggests that using an average value is more accurate than $C'(f)$ or $C'(F)$. This is why we have chosen

$$(A.24) \quad \Gamma = \frac{C(F) - C(f)}{F - f}$$

in the text. The examples seem to indicate that this is a good choice. Although the term $e^{+\varepsilon^2\rho\nu\alpha\Gamma(F)(T-t)}$ is generally a tiny correction, it is usually not negligible.

Appendix B. Boundary conditions.

To simplify notation, let

$$(B.1) \quad D^2(F) = (1 + 2\varepsilon\rho\nu z + \varepsilon^2\nu^2 z^2) e^{\varepsilon^2\rho\nu\alpha\Gamma(F)(T-t)} C^2(F),$$

so that the effective forward equation is

$$(B.2) \quad Q_T = \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q]_{FF} \quad \text{for } F_{\min} < F < F_{\max}.$$

Note that $C(F)$ can be zero where, and only where, $D(F) = 0$.

The change in the total probability in any interval $F_1 < F < F_2$ is

$$(B.3) \quad \frac{d}{dT} \int_{F_1}^{F_2} Q(T, F) dF = \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q]_F \Big|^{F_2} - \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q]_F \Big|^{F_1},$$

so clearly the probability flux at any point F is

$$(B.4) \quad J(F) = -\frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q]_F.$$

It is natural to place the lower boundary at the barrier, where $C(F)$, and hence $D(F)$, is zero. So let us first consider the case $D(F_{\min}) = 0$ with

$$(B.5) \quad D(F) \sim \text{const} \cdot (F - F_{\min})^\beta \quad \text{as } F \rightarrow F_{\min}.$$

Barriers have been studied extensively in stochastic processes and PDEs [19], [20]. If $0 \leq \beta < \frac{1}{2}$, it is known that F_{\min} is a regular boundary. Paths can both enter and leave the barrier, and it is theoretically possible for probability to diffuse through the barrier, reaching the “forbidden region” $F < F_{\min}$. We do not consider models which allow paths to reach the region $F < F_{\min}$. Any flux of probability from the interior $F > F_{\min}$ to the boundary F_{\min} must accumulate as a delta function at the boundary:

$$(B.6a) \quad Q(T, F) = Q^L(T) \delta(F - F_{\min}) \quad \text{at } F = F_{\min}.$$

Conservation requires that the accumulation of probability balances the flux,

$$(B.6b) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q]_F.$$

For regular boundaries we also need to prescribe a boundary condition at F_{\min} . Typically this boundary condition would be absorbing, reflecting, or mixed:

$$(B.7a) \quad D^2(F)Q(T, F) \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+ \quad (\text{absorbing}),$$

$$(B.7b) \quad [D^2(F)Q]_F \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+, \quad (\text{reflecting}),$$

$$(B.7c) \quad [D^2(F)Q]_F - \gamma D^2(F)Q(T, F) \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+ \quad (\text{mixed}).$$

To determine the correct boundary condition, note that the expected value of $\tilde{F}(T)$ is

$$(B.8) \quad E \left\{ \tilde{F}(T) \mid \tilde{F}(t) = f, \tilde{A}(t) = \alpha \right\} = F_{\min} Q^L(T) + \int_{F_{\min}}^{\infty} F Q(T, F) dF = f.$$

This expected value has to be constant for $\tilde{F}(T)$ to be a martingale, so

$$(B.9) \quad \frac{d}{dT} \left\{ F_{\min} Q^L(T) + \int_{F_{\min}}^{\infty} F Q(T, F) dF \right\} = 0.$$

Substituting B.2 for Q_T and B.6b for $Q^L(T)$, and then integrating by parts yields

$$(B.10) \quad \frac{d}{dT} \left\{ F_{\min} Q^L(T) + \int_{F_{\min}}^{\infty} F Q(T, F) dF \right\} = \lim_{F \rightarrow F_{\min}^+} -\frac{1}{2} \varepsilon^2 \alpha^2 D^2(F) Q(T, F).$$

Therefore the requirement that $\tilde{F}(T)$ be a martingale means that $Q(T, F)$ must satisfy absorbing boundary conditions at F_{\min} ,

$$(B.11) \quad \lim_{F \rightarrow F_{\min}^+} D^2(F)Q(T, F) = 0.$$

If $\frac{1}{2} < \beta < 1$, then F_{\min} is an exit boundary [19]. In this case some paths reach the barrier in finite time, but no paths leave the barrier. There is a finite amount of probability at the boundary F_{\min} ,

$$(B.12a) \quad Q(T, F) = Q^L(T)\delta(F - F_{\min}) \quad \text{at } F = F_{\min},$$

and it accumulates according to the flux,

$$(B.12b) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q]_F,$$

as before. For exit boundaries, the probability density automatically satisfies the absorbing boundary condition

$$(B.12c) \quad D^2(F)Q(T, F) \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+,$$

as is well-known. See [19] and the references cited therein. Theoretically no boundary condition is needed at F_{\min} , since the absorbing boundary condition occurs automatically. In practice, however, the absorbing boundary condition should be applied explicitly when solving the PDE numerically, since most numerical finite difference schemes create a slight amount of numerical dispersion, meaning that $D(F_{\min})$ is effectively slightly positive. Even if we could develop and employ a dispersion-free finite difference scheme, applying this boundary condition would be redundant, and not lead to any contradictions.

If $\beta \geq 1$ the barrier at F_{\min} is an *inaccessible*, or *natural*, boundary [19]. No paths can reach the boundary, and the probability and flux both go to zero as F approaches the F_{\min} ,

$$(B.13) \quad D^2(F)Q(T, F) \rightarrow 0, \quad [D^2(F)Q]_F \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+.$$

In theory, no delta function is needed at F_{\min} , since no paths reach the boundary. In practice, due to numerical dispersion, small amounts of probability reach the boundary. By incorporating a delta function at the boundary,

$$(B.14a) \quad Q(T, F) = Q^L(T)\delta(F - F_{\min}) \quad \text{at } F = F_{\min},$$

one can keep track of this probability,

$$(B.14b) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2}\varepsilon^2\alpha^2 [D^2(F)Q]_F.$$

This ensures that probability is conserved exactly. Even if we had a dispersion-free numerical scheme, it would result in $Q^L(T)$ being exactly zero, so the δ function would be redundant, but not erroneous. Similarly, we keep the absorbing boundary condition at F_{\min} , even though it should be satisfied automatically.

In summary, whenever there is a barrier at F_{\min} , we use absorbing boundary conditions

$$(B.15a) \quad D^2(F)Q(T, F) \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+,$$

and use a delta function

$$(B.15b) \quad Q(T, F) = Q^L(T)\delta(F - F_{\min}) \quad \text{at } F = F_{\min},$$

with

$$(B.15c) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q]_F,$$

in all cases.

There may be situations in which the boundary F_{\min} is placed at a point where $C(F_{\min}) \neq 0$. For example, one may wish to put the boundary at $F_{\min} = 0$, regardless of whether $C(F_{\min})$ is zero or not. Since we are not allowing any paths to go below F_{\min} , we have to allow a delta function at F_{\min} , with the probability at F_{\min} increasing according to B.15c. To preserve the martingale property, we need to use the absorbing boundary condition B.15a. Thus, in this case we must still use B.15a - B.15c at the boundary.

The upper boundary F_{\max} should be set high enough so it has no appreciable effect on option prices; typically setting F_{\max} to be 4 to 6 standard deviations above the forward suffices. This requires

$$(B.16a) \quad z(F_{\max}) = \frac{1}{\varepsilon \alpha} \int_f^{F_{\max}} \frac{dF'}{C(F')} = \frac{2}{\varepsilon \nu} \sinh \theta (\cosh \theta + \rho \sinh \theta)$$

with

$$(B.16b) \quad \theta = \frac{1}{2} \varepsilon \nu \cdot (4 \text{ to } 6) \sqrt{\tau_{ex}},$$

as shown in Appendix D. The boundary condition is irrelevant if F_{\max} is chosen large enough, but we find it cleanest to use the same boundary treatment at F_{\max} as at F_{\min} : We allow a delta function at F_{\max} ,

$$(B.17a) \quad Q(T, F) = Q^R(T) \delta(F - F_{\max}) \quad \text{at } F = F_{\max},$$

where

$$(B.17b) \quad \frac{dQ^R}{dT} = - \lim_{F \rightarrow F_{\max}^-} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q]_F.$$

This ensures that probability is conserved exactly, and by examining the size of $Q^R(T)$, we can determine whether the boundary F_{\max} needs to be increased. We also use absorbing boundary conditions,

$$(B.17c) \quad D^2(F)Q(T, F) \rightarrow 0 \quad \text{as } F \rightarrow F_{\max}^-,$$

to preserve the martingale property exactly.

To summarize, let us write the density as

$$(B.18) \quad Q(T, F) = \begin{cases} Q^L(T) \delta(F - F_{\min}) & \text{at } F = F_{\min} \\ Q^c(T, F) & \text{for } F_{\min} < F < F_{\max} \\ Q^R(T) \delta(F - F_{\max}) & \text{at } F = F_{\max} \end{cases},$$

where the superscript c is being used to denote the continuous part of the density. Then $Q^c(T, F)$ satisfies the boundary value problem

$$(B.19a) \quad Q_T^c = \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_{FF} \quad \text{for } F_{\min} < F < F_{\max},$$

with the boundary conditions

$$(B.19b) \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\min}^+,$$

$$(B.19c) \quad D^2(F)Q^c \rightarrow 0 \quad \text{as } F \rightarrow F_{\max}^-,$$

for $t < T < \tau_{ex}$, and the initial condition

$$(B.19d) \quad Q^c(T, F) \rightarrow \delta(F - f) \quad \text{as } T \rightarrow t^+.$$

The probability at the boundaries is

$$(B.19e) \quad \frac{dQ^L}{dT} = \lim_{F \rightarrow F_{\min}^+} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_F$$

$$(B.19f) \quad \frac{dQ^R}{dT} = - \lim_{F \rightarrow F_{\max}^-} \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F)Q^c]_F$$

and the initial conditions are

$$(B.19g) \quad Q^L(0) = 0, \quad Q^R(0) \rightarrow 0 \quad \text{as } T \rightarrow t^+.$$

B.1. Boundary layer analysis. We believe that the delta function $Q^L(T)$ arises because other mechanisms come into play when the forward $\tilde{F}(T)$ is near enough to the boundary. After all, there must be some reason that $\tilde{F}(T)$ doesn't cross the boundary. To show how this could come about, consider the effective forward equation

$$(B.20a) \quad Q_T = \frac{1}{2} \varepsilon^2 \alpha^2 [\tilde{D}^2(F)Q]_{FF} \quad \text{for } 0 < F < \infty,$$

$$(B.20b) \quad Q = \delta(F - f) \quad \text{at } T \rightarrow 0,$$

where $D(F)$ has been modified near the boundary:

$$(B.20c) \quad \tilde{D}(F) = \begin{cases} D(\eta) \frac{F}{\eta} & \text{for } 0 < F < \eta \\ D(F) & \text{for } F > \eta \end{cases}.$$

We will show that the absorbing boundary condition and the delta function $Q^L(T)$ are recovered in the limit $\eta \rightarrow 0$.

In the region $0 < F < \eta$, the new effective forward equation is

$$(B.21a) \quad Q_T = \frac{1}{2} \varepsilon^2 \alpha^2 (D(\eta)/\eta)^2 [F^2 Q]_{FF} \quad \text{for } 0 < F < \eta,$$

$$(B.21b) \quad Q = 0 \quad \text{at } T \rightarrow 0.$$

The boundary at $F = 0$ is an inaccessible (natural) boundary; no paths can reach the boundary, no boundary condition is required, and there is no probability flux at $F = 0$ [19]. At $F = \eta$, we require

$$(B.22a) \quad Q(T, \eta^-) = Q(T, \eta^+),$$

$$(B.22b) \quad (D(\eta)/\eta)^2 \lim_{F \rightarrow \eta^-} [F^2 Q(T, F)]_F = \lim_{F \rightarrow \eta^+} [D^2(F)Q(T, F)]_F$$

since both the probability and the flux must be continuous.

Define $Q^L(T)$ as the total amount of probability in $0 < F < \eta$,

$$(B.23) \quad Q^L(T) = \int_0^\eta Q(T, F) dF.$$

We note that

$$(B.24) \quad \begin{aligned} \frac{dQ^L(T)}{dT} &= \int_0^\eta Q_T(T, F) dF = \frac{1}{2} \varepsilon^2 \alpha^2 (D(\eta)/\eta)^2 \int_0^\eta [F^2 Q]_{FF} dF \\ &= \frac{1}{2} \varepsilon^2 \alpha^2 (D(\eta)/\eta)^2 \lim_{F \rightarrow \eta^-} [F^2 Q]_F. \end{aligned}$$

The continuity of the flux then ensures that

$$(B.25) \quad \frac{dQ^L(T)}{dT} = \frac{1}{2} \varepsilon^2 \alpha^2 \lim_{F \rightarrow \eta^+} [D^2(F) Q(T, F)]_F.$$

In the limit $\eta \rightarrow 0$, we have a finite probability $Q^L(T)$ in an infinitely thin region; i.e., a delta function:

$$(B.26a) \quad Q(T, F) = Q^L(T) \delta(F),$$

with

$$(B.26b) \quad \frac{dQ^L(T)}{dT} = \lim_{F \rightarrow 0^+} [D^2(F) Q(T, F)]_F.$$

To investigate the effective boundary condition, define the Fourier transform of Q ,

$$(B.27) \quad \hat{Q}(\lambda, F) = \int_0^\infty Q(T, F) e^{-\lambda T} dT.$$

Then

$$(B.28a) \quad \frac{A}{\eta^2} [F^2 \hat{Q}]_{FF} - \lambda \hat{Q} = 0 \quad \text{for } 0 < F < \eta,$$

where the constant A is

$$(B.28b) \quad A = \frac{1}{2} \varepsilon^2 \alpha^2 D^2(\eta) > 0.$$

The general solution to B.28a is

$$(B.29a) \quad \hat{Q}(\lambda, F) = C_1(\lambda) (F/\eta)^{\gamma_1} + C_2(\lambda) (F/\eta)^{\gamma_2},$$

where

$$(B.29b) \quad \gamma_{1,2} = \frac{-3 \pm \sqrt{1 + 4\lambda\eta^2/A}}{2}.$$

The integral

$$(B.30) \quad \int_0^\eta (F/\eta)^{\gamma_2} dF$$

is infinite when $\text{Re}\{\lambda\} \geq 0$. (From the general theory of Fourier transforms, it suffices to consider a region $\text{Re}\{\lambda\} \geq z$ for any real constant z , and then use analytic continuation. See [21].) Therefore, we must have $C_2(\lambda) = 0$ since $\hat{Q}(\lambda, F)$ must be integrable in F , and so

$$(B.31) \quad \hat{Q}(\lambda, F) = C_1(\lambda) (F/\eta)^{\gamma_1} \quad \text{for } 0 < F < \eta.$$

Since

$$(B.32) \quad \hat{Q}(\lambda, \eta^+) = \hat{Q}(\lambda, \eta^-) = C_1(\lambda),$$

and

$$(B.33) \quad \lim_{F \rightarrow \eta^+} \left[D^2(F) \hat{Q}(\lambda, F) \right]_F = D^2(\eta) C_1(\lambda) \lim_{F \rightarrow \eta^-} \left[(F/\eta)^{2+\gamma_1} \right]_F \\ = D^2(\eta) (2 + \gamma_1) C_1(\lambda) / \eta,$$

we have

$$(B.34) \quad D^2(\eta) \hat{Q}(\lambda, \eta^+) = \frac{\eta}{2 + \gamma_1} \lim_{F \rightarrow \eta^+} \left[D^2(F) \hat{Q}(\lambda, F) \right]_F.$$

In the limit that $\eta \rightarrow 0$, the right hand side goes to zero, and we obtain

$$(B.35) \quad \lim_{\eta \rightarrow 0^+} D^2(\eta) \hat{Q}(\lambda, \eta) = 0.$$

Inverting the the Fourier transform yields the absorbing boundary condition:

$$(B.36) \quad \lim_{\eta \rightarrow 0^+} D^2(\eta) Q(T, \eta) = 0.$$

Appendix C. Moment preserving finite difference schemes.

We require our numerical scheme to conserve probability and the first moment exactly, so that

$$(C.1a) \quad Q^L(T) + \int_{F_{\min}}^{F_{\max}} Q^c(T, F) dF + Q^R(T) = 1,$$

$$(C.1b) \quad F_{\min} Q^L(T) + \int_{F_{\min}}^{F_{\max}} F Q^c(T, F) dF + F_{\max} Q^R(T) = f.$$

This ensures put-call parity, and provided that $Q^c(T, F) \geq 0$ for all F , it also ensures that the numerical solution itself represents an exactly arbitrage-free model.

To simplify notation, define

$$(C.2) \quad M(T, F) = \frac{1}{2} \varepsilon^2 \alpha^2 D^2(F) = \frac{1}{2} \varepsilon^2 \alpha^2 \left[1 + 2\varepsilon \rho \nu z(F) + \varepsilon^2 \nu^2 z^2(F) \right] e^{\varepsilon^2 \rho \nu \alpha \Gamma(F) T} C^2(F),$$

We also set $t = 0$ without loss of generality.

C.1. Grid generation. We discretize F so that

$$(C.3) \quad F_{\max} = F_{\min} + Jh,$$

and define

$$(C.4) \quad F_j \equiv F_{\min} + \left(j - \frac{1}{2}\right) h \quad \text{for } j = 0, 1, \dots, J+1,$$

to be the midpoints of the intervals $(j-1)h$ to jh . In this process we adjust h slightly so that f occurs exactly at the midpoint of its interval:

$$(C.5) \quad f \equiv F_{j_0} = F_{\min} + \left(j_0 - \frac{1}{2}\right) h \quad \text{for some } j_0.$$

This will allow us to implement the initial condition in bias free manner.

Let $Q_j^n = Q^c(n\delta, F_j)$ be the probability density at $F = F_j$ at time $n\delta$. Specifically, define

$$(C.6) \quad Q_j^n = \frac{1}{h} \int_{F_{\min} + (j-1)h}^{F_{\min} + jh} Q^c(n\delta, F') dF' \quad \text{for } j = 1, \dots, J,$$

so that hQ_j^n is the total probability in the j^{th} grid cell at time step n . We usually use around 200 to 500 points for our grid, and divide $0 < T < \tau_{ex}$ into 30 to 100 time steps.

C.2. Finite difference scheme. We integrate the effective forward equation using a Crank-Nicholson scheme. This scheme averages explicit and implicit centered difference equations, is unconditionally stable, and is second order accurate in time [8]. To advance from time $n\delta$ to $(n+1)\delta$, we need to solve

$$(C.7) \quad Q_j^{n+1} - Q_j^n = \frac{\delta}{2h^2} \{M_{j+1}^{n+1}Q_{j+1}^{n+1} - 2M_j^{n+1}Q_j^{n+1} + M_{j-1}^{n+1}Q_{j-1}^{n+1}\} \\ \frac{\delta}{2h^2} \{M_{j+1}^nQ_{j+1}^n - 2M_j^nQ_j^n + M_{j-1}^nQ_{j-1}^n\} \quad \text{for } j = 1, 2, \dots, J,$$

where M_j^n is $M(T, F)$ at $T = n\delta$ and $F = F_j$. We re-write this as the system

$$(C.8a) \quad Q_j^{n+1} - \frac{\delta}{2h^2} \{M_{j+1}^{n+1}Q_{j+1}^{n+1} - 2M_j^{n+1}Q_j^{n+1} + M_{j-1}^{n+1}Q_{j-1}^{n+1}\} \\ = Q_j^n + \frac{\delta}{2h^2} \{M_{j+1}^nQ_{j+1}^n - 2M_j^nQ_j^n + M_{j-1}^nQ_{j-1}^n\} \quad \text{for } j = 1, 2, \dots, J.$$

The absorbing boundary conditions yield

$$(C.8b) \quad M_0^{n+1}Q_0^{n+1} + M_1^{n+1}Q_1^{n+1} = 0 \quad \text{at } j = 0,$$

$$(C.8c) \quad M_{J+1}^{n+1}Q_{J+1}^{n+1} + M_J^{n+1}Q_J^{n+1} = 0 \quad \text{at } j = J + 1.$$

The points $j = 0$ and $j = J + 1$ fall outside the domain; these shadow points simply enable us to obtain the correct boundary condition at the “true” boundaries $F_{\min} = F_{1/2}$ and $F_{\max} = F_{J+1/2}$.

This scheme only requires the solution of a tridiagonal system, so the computational work scales linearly with J and the number of time steps N .

We also need to solve for the boundary probabilities $Q^L(T)$ and $Q^R(T)$. Let

$$(C.9) \quad Q_L^n = Q^L(n\delta), \quad Q_R^n = Q^R(n\delta).$$

At each time step, after solving for the Q_j^{n+1} , we update the values Q_L^{n+1} and Q_R^{n+1} via

$$(C.10a) \quad Q_L^{n+1} - Q_L^n = \frac{\delta}{2h} \{M_1^{n+1}Q_1^{n+1} - M_0^{n+1}Q_0^{n+1} + M_1^nQ_1^n - M_0^nQ_0^n\},$$

$$(C.10b) \quad Q_R^{n+1} - Q_R^n = -\frac{\delta}{2h} \{M_{J+1}^{n+1}Q_{J+1}^{n+1} - M_J^{n+1}Q_J^{n+1} + M_{J+1}^nQ_{J+1}^n - M_J^nQ_J^n\}.$$

Note that this too is second order accurate in the time step δ .

The appropriate initial condition is

$$(C.11) \quad Q_L^0 = 0, \quad Q_j^0 = \begin{cases} 0 & \text{for } j \neq j_0 \\ 1/h & \text{for } j = j_0 \end{cases}, \quad Q_R^0 = 0,$$

where j_0 is the cell at which f is exactly F_{j_0} :

$$(C.12) \quad f = F_{j_0} \equiv F_{\min} + (j_0 - \frac{1}{2})h.$$

C.3. Moments. The total probability is

$$(C.13) \quad Q_L^n + \int_{F_{\min}}^{F_{\max}} Q^c(t_n, F')dF' + Q_R^n \equiv Q_L^n + \sum_{j=1}^J hQ_j^n + Q_R^n.$$

Summing equation C.8a over j , and using equations C.10a, C.10b, yields

$$\begin{aligned}
(C.14) \quad \sum_{j=1}^J h (Q_j^{n+1} - Q_j^n) &= \frac{\delta}{2h} \{M_{J+1}^{n+1} Q_{J+1}^{n+1} - M_J^{n+1} Q_J^{n+1} - M_1^{n+1} Q_1^{n+1} + M_0^{n+1} Q_0^{n+1}\} \\
&\quad + \frac{\delta}{2h} \{M_{J+1}^n Q_{J+1}^n - M_J^n Q_J^n - M_1^n Q_1^n + M_0^n Q_0^n\} \\
&= - (Q_L^{n+1} - Q_L^n) - (Q_R^{n+1} - Q_R^n)
\end{aligned}$$

for each time step n . Thus

$$(C.15) \quad Q_L^{n+1} + \sum_{j=1}^J h Q_j^{n+1} + Q_R^{n+1} = Q_L^n + \sum_{j=1}^J h Q_j^n + Q_R^n \quad \text{for all timesteps } n,$$

so the total probability doesn't change from one time step to the next. Since the total probability is 1 at $n = 0$,

$$(C.16) \quad Q_L^n + \sum_{j=1}^J h Q_j^n + Q_R^n = 1 \quad \text{for all } n.$$

The first moment is

$$(C.17) \quad F_{\min} Q_L^n + \int_{F_{\min}}^{F_{\max}} F' Q^c(t_n, F') dF' + F_{\max} Q_R^n \equiv F_{\min} Q_L^n + \sum_{j=1}^J h F_j Q_j^n + F_{\max} Q_R^n.$$

We multiply eq. C.8a by F_j and sum over j . Since $F_{j+1} - 2F_j + F_{j-1} = 0$, this yields

$$\begin{aligned}
(C.18) \quad \sum_{j=1}^J h F_j (Q_j^{n+1} - Q_j^n) &= \frac{\delta}{2h} \{F_J M_{J+1}^{n+1} Q_{J+1}^{n+1} - F_0 M_1^{n+1} Q_1^{n+1} - F_{J+1} M_J^{n+1} Q_J^{n+1} + F_1 M_0^{n+1} Q_0^{n+1}\} \\
&\quad + \frac{\delta}{2h} \{F_J M_{J+1}^n Q_{J+1}^n - F_0 M_1^n Q_1^n - F_{J+1} M_J^n Q_J^n + F_1 M_0^n Q_0^n\}.
\end{aligned}$$

Using C.10a, C.10b, this becomes

$$\begin{aligned}
(C.19) \quad F_{\min} (Q_L^{n+1} - Q_L^n) + \sum_{j=1}^J h F_j (Q_j^{n+1} - Q_j^n) + F_{\max} (Q_R^{n+1} - Q_R^n) \\
= \frac{\delta}{4} (M_1^{n+1} Q_1^{n+1} + M_0^{n+1} Q_0^{n+1}) - \frac{\delta}{4} (M_{J+1}^{n+1} Q_{J+1}^{n+1} + M_J^{n+1} Q_J^{n+1}) \\
+ \frac{\delta}{4} (M_1^n Q_1^n + M_0^n Q_0^n) - \frac{\delta}{4} (M_{J+1}^n Q_{J+1}^n + M_J^n Q_J^n).
\end{aligned}$$

The absorbing boundary conditions C.8b, C.8c ensure that the right hand side is zero, so the first moment is conserved for each time step n :

$$(C.20) \quad F_{\min} Q_L^{n+1} + \sum_{j=1}^J h F_j Q_j^{n+1} + F_{\max} Q_R^{n+1} = F_{\min} Q_L^n + \sum_{j=1}^J h F_j Q_j^n + F_{\max} Q_R^n.$$

Hence,

$$(C.21) \quad F_{\min} Q_L^n + \sum_{j=1}^J h F_j Q_j^n + F_{\max} Q_R^n = h F_{j_0} Q_{j_0}^0 = f.$$

Thus the expected value of $\tilde{F}(T)$ remains exactly f for the numerical solution. This is a key reason for using a uniform mesh; if a non-uniform mesh were used, a moment preserving finite difference scheme would yield a linear problem with at least five non-zero diagonals instead of three.

C.4. Option pricing. We integrate the option prices assuming that the probability $h Q_j^N$ is spread uniformly in each cell j . This yields

$$(C.22a) \quad V_{call}(\tau_{ex}, K) = f - K \quad \text{for } K < F_{\min},$$

$$(C.22b) \quad V_{call}(\tau_{ex}, K) = \frac{1}{2} (F_{\min} + kh - K)^2 Q_k^N + \sum_{j=k+1}^J [F_{\min} + (j - \frac{1}{2})h - K] h Q_j^N + (F_{\max} - K) Q_R^N$$

for $F_{\min} + (k - 1)h < K < F_{\min} + kh$,

$$(C.22c) \quad V_{call}(\tau_{ex}, K) = 0 \quad \text{for } K > F_{\max},$$

and

$$(C.23a) \quad V_{put}(\tau_{ex}, K) = 0 \quad \text{for } K < F_{\min},$$

$$(C.23b) \quad V_{put}(\tau_{ex}, K) = (K - F_{\min}) Q_L^N + \sum_{j=1}^{k-1} [K - F_{\min} - (j - \frac{1}{2})h] h Q_j^N + \frac{1}{2} [K - F_{\min} - (k - 1)h]^2 Q_k^N$$

for $F_{\min} + (k - 1)h < K < F_{\min} + kh$,

$$(C.23c) \quad V_{put}(\tau_{ex}, K) = K - f \quad \text{for } K > F_{\max}.$$

Appendix D. Dispersion.

We would like to measure F , at least crudely, in terms of standard deviations from today's forward f . The effective forward equation can be written as

$$(D.1a) \quad Q_T = \frac{1}{2} \varepsilon^2 \alpha^2 [D^2(F) Q]_{FF} \quad \text{for } T > t,$$

$$(D.1b) \quad Q \rightarrow \delta(F - f) \quad \text{as } T \rightarrow t,$$

with

$$(D.1c) \quad D^2(F) = (1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) e^{\varepsilon^2 \rho \nu a \Gamma(F)(T-t)} C^2(F).$$

To leading order, the solution is a Gaussian density

$$(D.2a) \quad Q(T, F) \approx \frac{1}{\sqrt{2\pi(T-t)}} e^{-y^2/2(T-t)} \frac{dy}{dF}$$

with

$$(D.2b) \quad y(F) = \frac{1}{\varepsilon\alpha} \int_f^F \frac{dF'}{D(F')}.$$

Since we are working only to leading order, we can neglect the exponential factor $e^{\varepsilon^2 \rho \nu \alpha \Gamma(F)(T-t)}$ in $D(F)$. Integrating then yields

$$(D.3a) \quad y(F) = \frac{1}{\varepsilon\nu} \log \left(\frac{\sqrt{1 + 2\varepsilon\rho\nu z(F) + \varepsilon^2\nu^2 z^2(F)} + \rho + \varepsilon\nu z(F)}{1 + \rho} \right),$$

where

$$(D.3b) \quad z(F) = \frac{1}{\varepsilon\alpha} \int_f^F \frac{dF'}{C(F')}.$$

For F to be roughly N standard deviations above f on the exercise date τ_{ex} , we need y to be $+N\sqrt{\tau_{ex}-t}$. This occurs at the F where

$$(D.4a) \quad z(F) = \frac{1}{\varepsilon\alpha} \int_f^F \frac{dF'}{C(F')} = \frac{2}{\varepsilon\nu} \sinh \theta (\cosh \theta + \rho \sinh \theta)$$

with

$$(D.4b) \quad \theta = \frac{\varepsilon\nu}{2} N \sqrt{\tau_{ex} - t}.$$

Similarly, for F to be roughly N standard deviations below f on the exercise date, we need y to be $-N\sqrt{\tau_{ex}-t}$. This occurs where

$$(D.5a) \quad -z(F) = \frac{1}{\varepsilon\alpha} \int_F^f \frac{dF'}{C(F')} = \frac{2}{\varepsilon\nu} \sinh \theta (\cosh \theta - \rho \sinh \theta)$$

with

$$(D.5b) \quad \theta = \frac{\varepsilon\nu}{2} N \sqrt{\tau_{ex} - t}.$$

Appendix E. Shifted SABR model.

It is now commonly accepted that interest rates need not be strictly positive. Surely, though, if interest rates were to become too negative, then increasing amounts of money would be withdrawn from the banking system, putting a squeeze on deposits. So there should be some barrier to how negative interest rates can become, but this barrier is probably below zero. Thus, it may make more sense to use a shifted SABR model,

$$(E.1) \quad C(F) = (F + b)^\beta,$$

for some $b > 0$.

For this model, the explicit implied volatility formula is

$$(E.2a) \quad \sigma_N(K) = \frac{\varepsilon\alpha(1-\beta)(f-K)}{(f+b)^{1-\beta} - (K+b)^{1-\beta}} \cdot \left(\frac{\zeta}{x(\zeta)} \right) \cdot \left\{ 1 + \left[g\alpha^2 + \frac{1}{4}\rho\nu\alpha \frac{(f+b)^\beta - (K+b)^\beta}{f-K} + \frac{2-3\rho^2}{24}\nu^2 \right] \varepsilon^2 \tau_{ex} \right\},$$

where

$$(E.2b) \quad \zeta = \frac{\nu}{\alpha} \frac{(f+b)^{1-\beta} - (K+b)^{1-\beta}}{1-\beta}, \quad x(\zeta) = \log \left(\frac{\sqrt{1-2\rho\zeta+\zeta^2} - \rho + \zeta}{1-\rho} \right),$$

and

$$(E.2c) \quad g = \frac{(1-\beta)^2}{\left([f+b]^{1-\beta} - [K+b]^{1-\beta}\right)^2} \log \left((f+b)^{\beta/2} (K+b)^{\beta/2} \frac{[f+b]^{1-\beta} - [K+b]^{1-\beta}}{(1-\beta)(f-K)} \right).$$

Our effective forward equation is

$$(E.3a) \quad Q_T = \frac{1}{2} \varepsilon^2 \alpha^2 \left[(1 + 2\varepsilon \rho \nu z + \varepsilon^2 \nu^2 z^2) e^{\varepsilon^2 \rho \nu a \Gamma(T-t)} C^2(F) Q \right]_{FF} \quad \text{for } T > t.$$

where

$$(E.3b) \quad z(F) = \frac{(F+b)^{1-\beta} - (f+b)^{1-\beta}}{\varepsilon \alpha (1-\beta)}, \quad \Gamma = \frac{(F+b)^\beta - (f+b)^\beta}{F-f}.$$

E.1. Stochastic normal model. As $\beta \rightarrow 0$, the shifted SABR model simplifies to the stochastic normal model,

$$(E.4) \quad C(F) = 1.$$

For this model, the explicit implied volatility formula is

$$(E.5a) \quad \sigma_N(K) = \varepsilon \alpha \cdot \left(\frac{\zeta}{x(\zeta)} \right) \cdot \left\{ 1 + \frac{1}{24} (2 - 3\rho^2) \nu^2 \varepsilon^2 \tau_{ex} + \dots \right\},$$

where

$$(E.5b) \quad \zeta = \frac{\nu}{\alpha} (f-K), \quad x(\zeta) = \log \left(\frac{\sqrt{1-2\rho\zeta+\zeta^2} - \rho + \zeta}{1-\rho} \right).$$

The effective forward equation is

$$(E.6a) \quad Q_T = \frac{1}{2} \varepsilon^2 \left[\left(\alpha^2 + 2\rho \nu \alpha [F-f] + \nu^2 [F-f]^2 \right) Q \right]_{FF} \quad \text{for } T > t,$$

$$(E.6b) \quad Q(T, F) \rightarrow \delta(F-f) \quad \text{as } T \rightarrow t^+.$$

Here there is no barrier, and the placement of F_{\min} is an independent modeling decision.

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