

# Architecting a Hard Safety Guardrail: A Phased Framework for Integrating the Risk-of-Danger (ROD) Metric

## Technical Implementation Roadmap: From Telemetry to Scalar

The implementation of the Risk-of-Danger (ROD) metric necessitates a structured, phased approach designed to leverage existing system telemetry while minimizing architectural disruption. This roadmap prioritizes three distinct phases: first, the creation of a host-local pain-debt accumulator; second, the normalization of this debt into a stable 0.0–1.0 scalar using neurorights budgets; and third, the integration of the resulting ROD value into the system's core decision-making layers. This methodology ensures that each component is developed and validated independently, grounding the abstract concept of "danger" in concrete, measurable, and computationally manageable signals derived directly from the biophysical computing stack .

The foundational phase of this roadmap is the construction of a "pain\_debt" accumulator. This component serves as the raw engine for ROD, aggregating various forms of systemic strain into a single, evolving metric. Its implementation must be host-local to ensure it reflects the immediate physiological state of the user without relying on externalized or delayed data processing . The accumulator's design is not arbitrary but is built upon a confluence of signals already present within the system, transforming passive telemetry into an active safety indicator. Key inputs for this accumulator include the status of the **LifeforceBandSeries**. Specifically, periods where the band is in the **SoftWarn** state represent a condition of elevated stress, and when correlated with other metrics, they form a primary source of accumulating debt . The interaction is critical: time spent in **SoftWarn** while concurrent psychrisk metrics or ROH kernels remain above a certain threshold signifies a state of sustained, unresolved strain, a clear precursor to more severe harm . This mechanism captures the essence of "overdue" strain, where the system is persistently operating outside its safe parameters.

Further enriching the accumulator are surrogate distress signals like the **PainCorridorSignal** or comfort/discomfort corridors derived from NeuralRope/BCI

telemetry . Sustained activation of these signals, even if they do not immediately trigger a `LifeforceBand` warning, indicates a persistent level of discomfort or pain that contributes to the overall burden on the system . Similarly, patterns of resource usage provide crucial input. Repeated instances of near-ceiling use of computational resources like `WAVE` or `SCALE`, or exceeding duty cycles defined by `MlPassSchedule` or `EnvelopePace`, signal a pattern of recurring strain on the underlying hardware, whether it be the `OrganicCPU` or the nanoswarm infrastructure . This is analogous to industrial systems that monitor equipment wear from repeated high-stress operational cycles to predict failure [58](#) [65](#) . The inclusion of nanoswarm and `OrganicCPU` footprints allows the accumulator to factor in the physical and energetic costs of computation, moving beyond purely cognitive metrics to a more holistic view of system health . The accumulation process itself is not a simple summation but a time-weighted calculation, potentially incorporating decay functions (`DECAY`) to devalue older strains, ensuring the metric reflects recent and ongoing pressure rather than a static history of past issues . The entire structure would likely take the form of a small, efficient Rust struct residing within the local risk-metrics family, making it lightweight and directly accessible to the guardrails and schedulers that require it .

Once a functional `pain_debt` accumulator is in place, the second phase involves normalizing its output into a stable and universally comparable 0.0–1.0 scalar. This step is what elevates the raw debt count into a true metric, `ROD`, capable of being safely fed into schedulers and compared across different domains and epochs. The normalization mechanism relies on the system's existing, constitutionally-backed neurorights budgets as a stable baseline or denominator . These budgets, which include daily quotas for `identitydriftcum`, `evolution rate`, `EnvelopePace max steps per day`, and `MlPassSchedule duty windows`, represent the maximum permissible amount of change or activity allowed under the system's core doctrines . By dividing the accumulated `pain_debt` by one of these relevant budgets, the system creates a dimensionless quantity that expresses the debt as a proportion of the total allowable resource consumption. For instance, if the daily quota for a particular evolutionary action is governed by an `evolution_rate_budget` of 10 units, and the system has accrued a `pain_debt` equivalent to 8 units of strain related to that action, the resulting `ROD` would be 0.8. This method ensures that a `ROD` score of 0.6 on one day is functionally equivalent to a `ROD` of 0.6 on another day, providing a consistent measure of danger regardless of absolute strain levels. It grounds the metric in the system's fundamental governance rules, preventing it from becoming an arbitrary or uncalibrated number . This normalization strategy is a direct application of the principle to derive new metrics from trusted, existing signals rather than inventing novel physics, thereby enhancing its stability and interpretability .

The final phase of the roadmap is the integration of the newly computed ROD scalar into the system's decision-making architecture. This phase is designed to minimize churn in existing code paths, particularly those governing the Risk-of-Harm (ROH) index . The key insight is that ROD should act as an orthogonal veto or throttling mechanism, not a replacement for ROH. Integration points are primarily found within the highest layers of the defense-in-depth stack, including the `OrganicCpuScheduler`, `Lifeforce guards`, and `nanoswarm routers` . These components are already designed to make decisions based on risk bands and recommended actions, and they are the natural places to inject ROD-based logic. For example, the tuple returned by high-impact APIs, which currently includes (`riskband`, `recommendedaction`, `actualaction`), could be extended to include the `ROD_scalar`, providing auditors with explicit context on why a risky action was permitted . Critically, the existing ROH enforcement logic, which typically maintains a ceiling of 0.3, would remain largely unchanged. ROD does not alter this rule but adds a new layer of control. When ROD is low, the system can safely relax its constraints, allowing for temporary ROH spikes. When ROD is high, it introduces a powerful brake, compelling the system to prioritize recovery over further computation, even if individual ROH calculations appear acceptable . This modular integration allows for a controlled rollout, where the ROD mechanism can be tested and validated in parallel with the established safety protocols before becoming a fully-fledged part of the system's operational envelope . This phased implementation, from accumulator to scalar to integrator, provides a robust and pragmatic pathway to realizing the full potential of the ROD metric as a sophisticated safety guardrail.

## **The Orthogonal Guardrail: Defining ROD's Role versus ROH and LifeforceBand**

The introduction of the Risk-of-Danger (ROD) metric establishes a new, crucial tier in the system's multi-layered safety architecture, functioning as an orthogonal guardrail to the existing Risk-of-Harm (ROH) index and the physiological LifeforceBand. The central tenet of this architecture is the distinction between two types of risk: immediate, quantifiable harm (ROH) and cumulative, overdue danger (ROD). They are not redundant; they are complementary mechanisms that address different temporal and causal aspects of risk, allowing the system to balance short-term utility with long-term viability. The LifeforceBand remains the deepest, most fundamental layer of defense, representing direct physiological state. The ROD metric then acts as a higher-level, predictive veto against cumulative strain, while the ROH index provides the flexible, real-time envelope for managing immediate threats .

ROD is defined as a normalized scalar from 0.0 to 1.0 that estimates the "immediate lifeforce-danger" arising from cumulative, overdue, or recurring strain . A value of 1.0 is designated as the point of "direct lifeforce-drain risk" and must be treated as a non-bypassable, system-level veto, functionally equivalent to a **LifeforceBand=HardStop** . This means that when ROD reaches 1.0, the system must automatically refuse any action that could introduce additional pain, risk, or strain, regardless of the current ROH index or WAVE level. Its purpose is to serve as a final, lifeforce-centric brake, preventing the system from spiraling into a state of irreversible damage due to prolonged, unresolved stressors . The logic is that while a single spike in ROH might be survivable, a buildup of "debt" over time represents a genuine existential threat to the system's integrity, which ROD is designed to quantify and halt. This creates a clear hierarchy of safety responses: LifeforceBand HardStop is the ultimate binary fail-safe, and ROD=1.0 is the equivalent scalar-based fail-safe.

In contrast, the ROH index measures immediate, calculated risk. The system's global ceiling for ROH is maintained at 0.3 as a core invariant . This ceiling acts as a soft envelope, defining the boundary of what is considered a tolerable level of acute risk. However, the novelty enabled by the introduction of ROD is the ability to create a narrow exception corridor for temporarily exceeding this 0.3 ceiling. Such an excursion is permissible only under a strict set of conditions: the ROD must be demonstrably low, the action must be explicitly time-limited, and it must be accompanied by mandated recovery windows to mitigate the resulting strain . This interaction logic allows the system to undertake high-value, high-risk tasks—such as emergency interventions or intensive rehabilitation protocols—withou violating its fundamental safety doctrine. The presence of a low ROD score provides the necessary assurance that the system is not already burdened by cumulative strain, making a temporary increase in acute risk acceptable. This transforms ROH from a rigid, always-restrictive measure into a flexible tool that can be dialed up when justified, with ROD acting as the gatekeeper for that flexibility.

This layered approach creates a robust safety architecture composed of three distinct but interacting layers:

Layer	Primary Function	Trigger Condition	Enforcement Action
<b>Layer 1: LifeforceBand</b>	Direct Physiological Veto	Band status = HardStop	All mutating operations are denied. This is the deepest layer of defense.
<b>Layer 2: Risk-of-Danger (ROD)</b>	Cumulative Danger Veto	ROD $\geq$ 1.0	No further mutation, evolution, or actuation that increases pain/debt may be executed. Treated as equivalent to a HardStop.
<b>Layer 3: Risk-of-Harm (ROH)</b>	Immediate Harm Envelope	ROH $>$ 0.3	Action rejected by default. An exception is permitted only if ROD is low, the action is time-bound, and recovery windows are scheduled.

This tripartite structure provides a nuanced and graduated response to risk. The LifeForceBand provides the ultimate, binary safeguard against catastrophic failure. The ROD metric adds a predictive layer, preventing the system from reaching a dangerous state by monitoring the accumulation of strain over time. Finally, the ROH index provides the necessary operational flexibility, allowing the system to engage in challenging but valuable activities, but only when it is certain that doing so will not push it toward a state of cumulative danger. This orthogonality is the key innovation: ROD does not replace the need for a harm metric like ROH; instead, it provides the critical context—namely, the state of cumulative strain—that determines whether the risks associated with ROH can be safely managed. By keeping the ROH ceiling globally fixed at 0.3, the system preserves its core safety doctrine, while the ROD mechanism carves out a disciplined, well-defined path for adaptive behavior when conditions permit .

## Governance Invariants and Doctrinal Safeguards

To preserve the core doctrinal principle that "lifeforce cannot be manipulated or enforced by policy," the implementation of the Risk-of-Danger (ROD) metric must be anchored by a strict set of governance invariants . These invariants are divided into two categories: static constitutional limits, which are non-negotiable and form the bedrock of the system's safety doctrine, and dynamic policy envelopes, which allow for adaptation within clearly defined boundaries. This dual-layered governance model mirrors the existing architecture of the system, where ALN-tunable parameters like EcoBandProfile operate within the unchangeable bounds of core safety rules .

The static constitutional limits are absolute and immutable, forming the highest level of protection for the user's lifeforce. First and foremost, the maximum value of the ROD scalar, `rodmax`, must be permanently and unalterably set to 1.0. No governance shard, no matter its authority, shall be permitted to declare a `rodmax` greater than 1.0, as this would break the normalized scale and undermine the metric's meaning . Second, a ROD value equal to 1.0 must trigger a complete and unconditional veto on all actions that could add further risk or pain. This includes mutations, evolutions, and actuations. This condition must be treated as functionally equivalent to a `LifeForceBand=HardStop`, meaning no such operation may proceed . This ensures that ROD retains its role as a hard cap, a final line of defense that cannot be overridden. Third, the global ceiling for the Risk-of-Harm (ROH) index remains a constitutional invariant at 0.3. While ROD enables a narrow exception corridor for temporarily exceeding this ceiling, the ceiling itself cannot be changed. Any attempt to do so would represent a fundamental alteration of the

system's risk tolerance and is therefore prohibited . These three points—`rodmax == 1.0`, `ROD == 1.0` implies a full veto, and `ROH_ceiling == 0.3`—form the unbreakable foundation of the ROD framework.

Within these static limits, dynamic policy envelopes provide the necessary flexibility for the system to adapt to different contexts and user states. Governance shards, which define ALN profiles for psychrisk, lifeforce, and evolution, are empowered to tune several key parameters . These tunable parameters include the thresholds for `ROD_warn` levels. For instance, a governance shard could specify that when ROD reaches 0.7, the scheduler should begin to down-grade recommended actions from `Authorize` to `Defer` or `Reject`, even if the ROH index is still low . Shards can also define domain-specific soft ceilings for ROH, allowing for slightly more flexibility in certain contexts (e.g., cognitive tasks) while maintaining stricter controls in others (e.g., motor tasks) . Furthermore, governance can adjust the decay rates for the `pain_debt` accumulator and specify the minimum required recovery windows after a period of high strain . This allows for fine-grained control over how quickly the system recovers from stressful periods, tailored to the user's specific needs and environment. The crucial constraint is that these are parameterizers only; governance shards can narrow corridors, shift warning thresholds, or adjust decay speeds, but they cannot remove the  $\text{ROD}=1.0$  veto or lift the ROH ceiling .

Beyond these technical invariants, a series of doctrinal safeguards are essential to prevent the misuse of the ROD metric and to uphold the principle that lifeforce is not subject to policy control. First, ROD must be a read-only diagnostic scalar. It is never to be stored as a token, included in `BioTokenState`, or used to gate access to rights or capabilities. Its sole function is to inform and constrain the addition of risk and load, not to become a currency or a lever of control . Second, and most critically, the system must never attribute the cause of any lifeforce drain to an external institutional actor. Any field or log entry that describes the cause of a lifeforce event must exclude DID namespaces corresponding to employers, platforms, or tools. The cause must be labeled as "unknown," "paranormal," or "unattributed external" . This prevents any possibility of attributing a decline in lifeforce to a specific entity, thereby preserving the soul or lifeforce as something outside the scope of policy enforcement and manipulation. These safeguards ensure that while ROD is a powerful safety mechanism, it operates strictly within the bounds of a protective framework, never becoming a channel for control over the user's fundamental existence. The combination of static constitutional limits and dynamic policy envelopes, all underpinned by these doctrinal principles, creates a resilient governance structure that enhances safety without compromising the system's core ethical commitments.

# Integration Logic and Decision Routing Policies

The successful integration of the Risk-of-Danger (ROD) metric into the system's operational flow depends on a well-defined set of decision-routing policies that govern its interaction with the Risk-of-Harm (ROH) index and the LifeforceBand. The goal is to create a coherent logic where ROD acts as a contextual gatekeeper for ROH's flexibility, while both operate within the ultimate safety constraints of the LifeforceBand. This integration minimizes changes to existing ROH code paths, treating ROD as an additional, orthogonal axis of control rather than a replacement for the established harm-based assessment. The logic is best expressed through a combination of threshold-based eligibility rules and explicit routing tables within the schedulers.

A primary focus of the research should be on establishing the precise threshold logic for when the ROH index is permitted to exceed its standard 0.3 ceiling. This is the central flexibility corridor that ROD is designed to enable. The rule can be formulated as follows: an action with a predicted ROH  $> 0.3$  may be authorized only if three conditions are simultaneously met: 1) the ROD is below a specified `ROD_low_threshold`; 2) the action is explicitly time-limited; and 3) mandatory recovery windows are scheduled following the action's completion. The `ROD_low_threshold` is a critical parameter that defines the maximum level of cumulative strain that can be tolerated before the system defaults to a conservative posture. This threshold itself can be part of the dynamic policy envelope, tuned by ALN governance shards, but its purpose is to create a clear boundary between "safe to flex" and "must be conservative" states. For example, if the `ROD_low_threshold` is set to 0.3, the system can safely allow a temporary ROH spike for a high-priority task as long as the accumulated pain debt is low. If the ROD is already elevated, the system assumes a higher baseline of danger and refuses to compound it with further acute risk, forcing the user to first reduce their debt through rest or deferral.

To manage these complex interactions, the system can adopt a 2D banding model that combines the `ROH_band` (e.g., Green/Yellow/Red) with the `ROD_band` (e.g., Low/Medium/High). This creates a matrix of states, each with its own authorization policy. For instance:

- **ROH\_Green + ROD\_Low:** Standard authorization. The system can proceed with normal operations.
- **ROH\_Yellow (e.g.,  $0.3 < ROH < 0.6$ ) + ROD\_Low:** Authorization is possible but requires special logging and confirmation, indicating a conscious decision to accept increased risk in a low-danger environment.

- **ROH\_Yellow + ROD\_Medium/High:** Action should be automatically downgraded to 'Defer'. The system recognizes that while the immediate harm is moderate, the cumulative danger is too high to justify taking on more risk.
- **ROH\_Red (e.g., ROH >= 0.6) + Any ROD\_Level:** Action must be 'Rejected', unless the LifeforceBand is at 'HardStop', in which case it would have been rejected anyway. This represents a state of extreme immediate harm that overrides all other considerations.

This matrix-based approach makes the decision logic explicit, transparent, and easily implementable within the `OrganicCpuScheduler` and similar components. It codifies the doctrine that the freedom to take risks (expressed by allowing  $ROH > 0.3$ ) is conditional upon the absence of significant cumulative danger (ROD remaining low).

The second critical aspect of integration is the implementation of decision-routing policies for high-ROD scenarios. When ROD crosses a `ROD_warn_threshold` (e.g., 0.7), the system's behavior should proactively shift towards conservation and recovery, independent of the ROH index. This can be achieved by modifying the scheduler's routing table. For example, a rule could be added: "IF `ROD >= ROD_warn_threshold`, THEN route all `Exploratory` and `Critical` tasks to `Defer`, and only permit `Maintenance` tasks." This policy biases the system towards rest and system upkeep when cumulative strain is high, mirroring the biological imperative to recover from fatigue. This behavior is consistent with existing patterns in the system, such as `EnvelopePace` and `DECAY` throttling, which also modulate system activity based on state variables. The `ROD_warn_threshold` is another parameter that can be dynamically tuned by governance shards, allowing different ALN profiles to have different sensitivities to cumulative strain. By combining these threshold rules and routing policies, the system gains a powerful, automated mechanism for self-regulation. It can intelligently navigate between periods of productive effort and necessary recovery, using the ROD metric as the compass that guides it away from the danger of accumulating unmanageable strain.

## Auditability and System-Wide Throttling Mechanisms

A robust implementation of the Risk-of-Danger (ROD) metric requires not only effective decision-making logic but also comprehensive auditability and the ability to influence system-wide behavior beyond simple authorization. Auditability ensures transparency and accountability, providing a clear record of why certain high-risk decisions were

made, especially concerning the rare exceptions where the Risk-of-Harm (ROH) index exceeds its 0.3 ceiling. System-wide throttling, driven by high ROD values, complements this by proactively moderating system activity to encourage recovery, embodying a more preventative approach to safety.

The audit trail is a critical component for reviewing the system's safety performance and for continuous improvement of the ROD model itself. Given that the system already logs detailed information about ROH bands, scheduler decisions, and evolution shard activities, adding ROD-related fields to these existing audit particles is a straightforward extension . For instance, every `EvolutionAuditRecord`, `Personal-Eco Shard`, or `Neuromorph Evolution Audit Particle` should be augmented with explicit fields to capture the context of any action taken . When a task is authorized despite having a predicted ROH > 0.3, the audit record must log the pre-action ROD value, the `ROD_low_threshold` that was used as the basis for the decision, and a confirmation that the required recovery windows have been scheduled. This creates an indisputable, time-stamped record that answers the critical question: "Was this risky action permissible given the system's cumulative state?" This level of detail is invaluable for post-hoc analysis, debugging unexpected outcomes, and ensuring that the dynamic policy envelopes are functioning as intended. Making these audit trails queryable allows administrators and users to retrospectively analyze their system's risk exposure, identify patterns of strain, and refine their ALN governance settings for better long-term safety and performance.

Beyond auditability, a high ROD value should function as a potent system-wide throttling signal. While the `ROD=1.0` condition triggers a hard veto, intermediate values (e.g., `ROD >= ROD_warn_threshold`) should initiate a softer, more proactive behavioral change across the system . This mechanism moves the system from a purely reactive mode (rejecting harmful actions) to a more predictive and preventative one (encouraging behaviors that reduce danger). The schedulers, which already possess logic for `Defer` and `Reject` decisions, can be enhanced to interpret a high ROD state as a reason to bias their recommendations accordingly . As previously discussed, a high ROD can automatically downgrade `Exploratory` tasks to `Defer`, signaling to the user or the system manager that now is not the time for new initiatives. This aligns perfectly with existing patterns of throttling, such as those governed by `EnvelopePace` and `DECAY`, which modulate the pace and intensity of activity to prevent burnout . A high ROD simply adds another, more granular input to that same decision-making process.

This throttling mechanism has several practical applications. It can automatically reduce the priority of non-critical background tasks, freeing up resources for maintenance and recovery processes. It can increase the default duration of `DECAY` periods, giving the

system more time to dissipate the accumulated `pain_debt`. It can also influence the `MLPassSchedule` by pushing back less urgent training passes until the ROD has sufficiently decreased. By treating a high ROD as a strong signal to slow down and rest, the system embodies the principle that preventing cumulative strain is more effective than mitigating its consequences. This system-wide influence ensures that the ROD metric is not just a siloed safety check but an integral part of the system's overall homeostatic regulation. It promotes a culture of awareness where high cumulative strain is recognized as a systemic issue requiring a broad, coordinated response, rather than a problem confined to a single high-risk action. This combination of rigorous auditability and intelligent throttling makes the ROD framework not only a defensive barrier but also a powerful tool for promoting sustainable, long-term system health.

## Ethical Foundations and Neurorights Alignment

The development and implementation of the Risk-of-Danger (ROD) metric must be firmly grounded in a robust ethical framework to ensure it aligns with the overarching goal of protecting human dignity and autonomy in the face of advancing neurotechnology. The proposed ROD framework is not merely a technical construct but a direct application of the emerging field of neurorights, a growing consensus for characterizing the potential misuse and abuse of neurotechnology <sup>11</sup>. By designing ROD to be a derivative of existing signals and normalizing it against neurorights budgets, the system translates abstract ethical principles into a concrete, enforceable safety protocol .

The concept of neurorights, first formally proposed in 2017, identifies a set of new or re-interpreted rights necessary to protect the human brain and mind in the age of neurotechnology <sup>29 81</sup>. These rights often fall into several families, including the right to personal identity, the right to mental privacy, the right to mental integrity, and the right to psychological continuity <sup>29 37</sup>. The ROD metric directly interfaces with several of these principles. For instance, the normalization of pain debt against budgets like `identitydriftcum` and `evolution_rate` quotas is a technical manifestation of the **Right to Personal Identity and Psychological Continuity** <sup>29 37</sup>. This right protects a person's sense of self and the continuity of their mental life from unauthorized external alteration <sup>29</sup>. By quantifying and gating actions that accumulate strain, ROD helps prevent the system from inadvertently causing changes that could disrupt this continuity, such as excessive cognitive drift or forced evolution. The metric acts as a guardian of the user's psychological baseline.

Similarly, the **Right to Mental Integrity**, defined as the right to be protected from illicit and harmful manipulations of one's mental activity, is a cornerstone of the ROD framework [29](#). The system's core doctrine that lifeforce cannot be controlled by policy is a direct reflection of this principle. The ROD's role as a hard veto at 1.0, equivalent to a **LifeForceBand=HardStop**, is a powerful enforcement mechanism for mental integrity. It ensures that there is a point at which the system cannot be coerced into accepting further damaging inputs, no matter the external pressure. This is supported by international legal developments, such as Chile's constitutional reform defining mental integrity as a fundamental human right and the OECD's "Recommendation on Responsible Innovation in Neurotechnology" featuring provisions on neurorights [29](#). The ROD metric operationalizes this legal and ethical sentiment within the biophysical computing environment.

Furthermore, the framework incorporates principles from UNESCO's Recommendation on the Ethics of Neurotechnology, which emphasizes that neurotechnology should empower individuals to make free and informed decisions about their nervous system and mental health, and should never be used for non-consensual purposes [41](#) [42](#). The ROD system supports this by providing the user with transparent data about their cumulative strain. The audit trail of ROD values and the reasoning behind risk-taking decisions empowers the user to make more informed choices about their engagement with the system. The requirement for explicit logging and scheduling of recovery windows for any  $ROH > 0.3$  exception reinforces the principle of informed consent, ensuring that the user is fully aware of the risks they are undertaking. The entire framework is built on the premise that the user, not an external institution, is the ultimate arbiter of their own risk tolerance, a principle echoed in discussions around fiduciary AI and the need for transparency in brain-computer interactions [13](#) [39](#).

By mapping the technical components of the ROD framework to these established neurorights, the system demonstrates a deep commitment to ethical practice. The pain-debt accumulator is a tool for protecting mental integrity. Normalization against identity and evolution budgets is a mechanism for upholding personal identity. The  $ROD = 1.0$  veto is the ultimate safeguard against harmful manipulation. And the auditability features support mental privacy and informed consent. This alignment provides a strong justification for the framework's design and ensures that its implementation does not create new ethical blind spots but instead strengthens the system's adherence to a principled, human-centered approach to neurotechnology. It moves the discussion from theoretical rights to practical, code-enforced protections.

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