SI231 - Matrix Computations, Fall 2020-21

Homework Set #1

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Acknowledgements:

- 1) Deadline: 2020-09-27 23:59:59
- 2) No handwritten is accepted. You need to use LATEX. (If you have difficulty in using LATEX, you are allowed to use Word for the first and the second homework to accommodate yourself.)
- 3) Do use the given template.

I. Understanding rank, range space and null space

Problem 1. (4 points \times 5)

- 1) For matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, prove that $\mathbb{R}^n = \mathcal{N}(\mathbf{A}) \oplus \mathcal{R}(\mathbf{A}^T)^{-1}$. **Hint:** $\dim(\mathcal{N}(\mathbf{A})) + \dim(\mathcal{R}(\mathbf{A}^T)) = n$.
- 2) For matrices $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{B} \in \mathbb{R}^{m \times n}$, prove that $\operatorname{rank}(\mathbf{A} + \mathbf{B}) \leq \operatorname{rank}(\mathbf{A}) + \operatorname{rank}(\mathbf{B})$.
- 3) For matrices $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{B} \in \mathbb{R}^{n \times p}$, prove that $rank(\mathbf{AB}) \leq min\{rank(\mathbf{A}), rank(\mathbf{B})\}$ and $rank(\mathbf{AB}) = n$ only when ${\bf A}$ has full-column rank and ${\bf B}$ has full-row rank.
- 4) For matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{B} \in \mathbb{R}^{m \times p}$, prove that $\mathcal{R}(\mathbf{A}|\mathbf{B}) = \mathcal{R}(\mathbf{A}) + \mathcal{R}(\mathbf{B})^2$
- 5) For matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{B} \in \mathbb{R}^{m \times p}$, prove that

$$\mathsf{rank}(\mathbf{A}|\mathbf{B}) = \mathsf{rank}(\mathbf{A}) + \mathsf{rank}(\mathbf{B}) - \dim(\mathcal{R}(\mathbf{A}) \cap \mathcal{R}(\mathbf{B})).$$

Hint: Recall the result in 4).

¹Let \mathcal{S}_1 and \mathcal{S}_2 be two subspaces of \mathbb{R}^n , if $\mathcal{S}_1 \cap \mathcal{S}_2 = \{\mathbf{0}\}$ and $\mathcal{S}_1 + \mathcal{S}_2 = \mathbb{R}^n$, we define the **direct sum** $\mathbb{R}^n = \mathcal{S}_1 \oplus \mathcal{S}_2$.

²Here
$$\mathbf{A}|\mathbf{B}$$
 denotes a new matrix combined by \mathbf{A} and \mathbf{B} . For example, $\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$, $\mathbf{B} = \begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix}$, then $\mathbf{A}|\mathbf{B} = \begin{bmatrix} a_{11} & a_{12} & b_{11} \\ a_{21} & a_{22} & b_{21} \end{bmatrix}$.

II. UNDERSTANDING SPAN, SUBSPACE

Problem 1. (10 points) For a set of vectors $\mathcal{S} = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$, prove that span(\mathcal{S}) is the intersection of all subspaces that contain \mathcal{S} , i.e., prove that span(\mathcal{S}) = \mathcal{M} where $\mathcal{M} := \bigcap_{s \subseteq \mathcal{V}} \mathcal{V}$ is the intersection of all subspaces that contain \mathcal{S} and \mathcal{V} denotes the subspace containing \mathcal{S} .

Hint: Prove that $span(\mathcal{S})\subseteq\mathcal{M}$ and $\mathcal{M}\subseteq span(\mathcal{S}).$

III. BASIS, DIMENSION AND PROJECTION

Problem 1. (2 points \times 2) Determine the dimension of each of the following vector spaces:

- 1) The space of polynomials having degree n or less;
- 2) The space of $n \times n$ symmetric matrices.

Problem 2. Some Important linear transformations

- 1) Rotations. (6 points) A rotation matrix $\mathbf{R} \in \mathbb{R}^{n \times n}$ is an orthogonal matrix $(\mathbf{R}\mathbf{R}^T = \mathbf{I})$ such that $\det(\mathbf{R}) = 1$.
 - According to above definition, find all rotation matrix in $\mathbb{R}^{2\times 2}$.
 - Geometrically, if $\mathbf{R} \in \mathbb{R}^{2 \times 2}$, then $\mathbf{R}\mathbf{x}$ means we rotate the vector $\mathbf{x} \in \mathbb{R}^2$ from some angle $\theta \in [0, 2\pi]$ in anti-clockwise direction. For $\mathbf{x} = [\cos(\pi/4), \sin(\pi/4)]^T$, compute $\mathbf{R}\mathbf{x}$, where \mathbf{R} represents the matrix that rotating \mathbf{x} by $7/12\pi$ in anti-clockwise direction.

Hint: draw a plot of x and Rx.

2) **Reflections.** (8 points) Let $\mathbf{u} \in \mathbb{R}^n$ be a unit vector, $\|\mathbf{u}\|_2 = 1$. For a given vector $\mathbf{x} \in \mathbb{R}^n$ and a hyperplane $\mathcal{H}_u = \{\mathbf{x} \in \mathbb{R}^n | \mathbf{u}^T \mathbf{x} = 0\}$. Let $\mathbf{Q} = \mathbf{I} - \mathbf{u}\mathbf{u}^T$. Then a vector $\mathbf{y} \in \mathbb{R}^n$ is said to be a *reflection* of \mathbf{x} with respect to \mathcal{H} if their projections onto the hyperplane \mathcal{H} (denoted as $\mathbf{Q}\mathbf{x}$ and $\mathbf{Q}\mathbf{y}$ respectively) satisfy

$$\mathbf{Q}\mathbf{x} = \mathbf{Q}\mathbf{y}\,,\quad \|\mathbf{x} - \mathbf{Q}\mathbf{x}\|_2 = \|\mathbf{y} - \mathbf{Q}\mathbf{y}\|_2\,.$$

See Figure.1 for visualization.

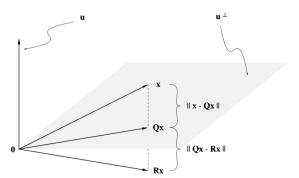


Figure 1. Reflection of x

A Householder matrix has the form $\mathbf{H} = \mathbf{I} - 2\mathbf{u}\mathbf{u}^T$. Prove that $\mathbf{H}\mathbf{x}$ is a reflection of \mathbf{x} with respect to \mathcal{H}_u .

IV. DIRECT SUM

Problem 1. (10 points) Let \mathcal{V} be a vector space, and \mathcal{B} be a basis for \mathcal{V} . Suppose that there exist subsets $\mathcal{B}_1, \mathcal{B}_2$ of \mathcal{B} , such that $\mathcal{B} = \mathcal{B}_1 \cup \mathcal{B}_2$ and $\mathcal{B}_1 \cap \mathcal{B}_2 = \emptyset$. Then show that $\mathcal{V} = \text{span}(\mathcal{B}_1) \oplus \text{span}(\mathcal{B}_2)$.

Problem 2. (10 points) Let $\mathcal V$ be a real vector space of dimension n. Let $\mathcal S$ be a subspace of $\mathcal V$ of dimension $d \leq n$. Prove that there exists a subspace $\mathcal T$ of $\mathcal V$ such that $\mathcal V = \mathcal S \oplus \mathcal T$.

V. UNDERSTANDING THE MATRIX NORM

Problem 1. (7 points \times 2) Matrix norm is induced by vector norm,

$$\|\mathbf{A}\|_p = \max_{\mathbf{x} \neq \mathbf{0}} \frac{\|\mathbf{A}\mathbf{x}\|_p}{\|\mathbf{x}\|_p} = \max_{\|\mathbf{x}\|_p = 1} \|\mathbf{A}\mathbf{x}\|_p, \quad \mathbf{A} \in \mathbb{R}^{m \times n}, \mathbf{x} \in \mathbb{R}^{n \times 1},$$

prove that

1) the matrix 1-norm

$$\|\mathbf{A}\|_1 = \max_{\|\mathbf{x}\|_1 = 1} \|\mathbf{A}\mathbf{x}\|_1 = \max_j \sum_i^m |a_{ij}|$$

= the largest absolute column sum.

2) the matrix ∞ -norm

$$\|\mathbf{A}\|_{\infty} = \max_{\|\mathbf{x}\|_{\infty}=1} \|\mathbf{A}\mathbf{x}\|_{\infty} = \max_{i} \sum_{j=1}^{n} |a_{ij}|$$

= the largest absolute row sum.

VI. UNDERSTANDING THE HÖLDER INEQUALITY

Problem 1. (6 points \times 3) Hölder inequality:

$$|\mathbf{x}^T \mathbf{y}| \leq ||\mathbf{x}||_p ||\mathbf{y}||_q$$

for any p,q such that 1/p+1/q=1, $p\geq 1$. Derive this inequality by exexcuting the following steps:

1) Consider the function $f(t)=(1-\lambda)+\lambda t-t^{\lambda}$ for $0<\lambda<1$, establish the inequality

$$\alpha^{\lambda} \beta^{1-\lambda} \le \lambda \alpha + (1-\lambda)\beta$$
,

for nonnegative real numbers α and β .

2) Let $\hat{\mathbf{x}} = \mathbf{x}/\|\mathbf{x}\|_p$ and $\hat{\mathbf{y}} = \mathbf{y}/\|\mathbf{y}|_q$, and apply the inequality of part (a) to obtain

$$\sum_{i=1}^{n} |\hat{x}_i \hat{y}_i| \le \frac{1}{p} \sum_{i=1}^{n} |\hat{x}_i|^p + \frac{1}{q} \sum_{i=1}^{n} |\hat{y}_i|^q = 1.$$

- 3) Deduce the Hölder inequality with the above results.
- 4) (Bouns question: 10 points) Prove the general form of triangle inequality

$$\|\mathbf{x} + \mathbf{y}\|_p \le \|\mathbf{x}\|_p + \|\mathbf{y}\|_p.$$

Hint: For p > 1, let q be the number such that 1/q = 1 - 1/p. Verify that for scalars α and β ,

$$|\alpha + \beta|^p = |\alpha + \beta||\alpha + \beta|^{p/q} \le |\alpha||\alpha + \beta|^{p/q} + |\beta||\alpha + \beta|^{p/q}$$

and make use of Hölder's inequality.