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EXERCISE 3 DUE 30.11.2015, 12:15 PM

Question 1 (5 Points)

Transformations.

Give the transformation matrix T that rotates a point around another point R=(1,2,3) by 35° around the z-axis and *afterwards* scales it by a factor of 2 with the center of scaling at point S=(2,2,2).

It is sufficient to give the translation, rotation and scale matrices and the correct concatination of them. For example, for translating a point by (1,1,1) and then rotating it by 45° around the y-axis, this would look like this:

$$M_t = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix}, M_r = \begin{pmatrix} \cos(45^\circ) & 0 & \sin(45^\circ) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(45^\circ) & 0 & \cos(45^\circ) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, T = M_t \cdot M_r$$

Question 2 (5 Points)

Give 5 reasons why the visual perception of the real world is different from the one in a virtual reality under consideration of the currently available hardware and software!

Question 3 (4 Points)

We want to draw four rectangles into a window sized 4×4 pixels using z-buffering. The rectangles are defined as follows (higher z-value means closer to the viewer):

1.
$$(0,1,1), (2,1,1), (2,3,1), (0,3,1)$$

2.
$$(2,0,2),(3,0,2),(3,1,2),(2,1,2)$$

4.
$$(0,2,0),(1,2,0),(1,3,0),(0,3,0)$$

