

DATA STRUCTURE AND ALGORITHM

CLASS 1

Seongjin Lee

Updated: 2021-02-01
DSA_2017_01

insight@gnu.ac.kr
<http://resourceful.github.io>
Systems Research Lab.
GNU



Table of contents

1. Miscellanea
2. Basic Concepts
3. Algorithm Specification
4. Recursive Algorithms
5. Data Abstraction
6. Performance Analysis
 - 6.1 Time Complexity
 - 6.2 Asymptotic Notation
 - 6.3 Practical Complexities

MISCELLANEA

Fundamentals of Data Structure in C, 2nd Ed.

by Horowitz, Sahni, and Anderson-Freed

<http://www.cise.ufl.edu/~sahni/fdsc2ed/>

Presentations are uploaded in

- https://github.com/resourceful/lecture_dsa2017-1

Contact

E-mail: insight@gnu.ac.kr

Room: 407-314

Visiting Hour: Monday and Wednesday 14:00 - 16:00

Evaluation

- Midterm - 20%
- Final - 30%
- Assignments - 40%
- Attendance - 10%

BASIC CONCEPTS



Overview: System Life Cycle

Requirements

- describe informations(input, output, initial)

Analysis

- bottom-up, top-down

Design

- data objects and operations performed on them

Coding

- choose representations for data objects and write algorithms for each operation

Overview: System Life Cycle Cnt'd

Verification

- **correctness proofs:** select algorithms that have been proven correct
- **testing:** working code and sets of test data
- **error removal:** If done properly, the correctness proofs and system test indicate erroneous code

ALGORITHM SPECIFICATION



Algorithm Specification

Definition

- a finite set of instructions - accomplish a particular task

Criteria

- zero or more inputs
- at least one output
- definiteness(clear, unambiguous)
- finiteness(terminates after a finite number of steps)

Algorithm Specification: Selection Sort

Ex Selection Sort: Sort n ($n \geq 1$) integers

- From those integers that are currently unsorted, find the smallest and place it next in the sorted list

```
for (i=0; i<n; i++) {  
    Examine list[i] to list[n-1] and suppose  
    that the smallest integer is at list[min];  
  
    Interchange list[i] and list[min];  
}
```

Algorithm Specification: Selection Sort

finding the smallest integer

- assume that minimum is `list[i]`
- compare current minimum with `list[i+1]` to `list[n-1]` and find smaller number and make it the new minimum

interchanging minimum with `list[i]`

- **function:** `swap(&a,&b)`
- **macro:** `swap(x,y,t)`
- The function's code is easier to read than that of the macro but the macro works with any data type

Algorithm Specification: Selection Sort

○ **function:** swap(&a,&b)

```
void swap(int *x, int *y){  
    int temp = *x;  
  
    *x = *y;  
  
    *y = temp;  
}
```

○ **macro:** swap(x,y,t)

```
#define SWAP(x,y,t) ((t) = (x), (x) = (y), (y) = (t))
```

Algorithm Specification: Binary Search

assumption

- sorted $n(1)$ distinct integers stored in the array list

return

- index i (if $i, \text{list}[i] = \text{searchnum}$)
- or -1 (otherwise)

Algorithm Specification: Binary Search

denote left and right

- left and right ends of the list to be searched
- initially, left=0 and right=n-1

let $\text{middle} = (\text{left} + \text{right}) / 2$ middle position in the list

compare $\text{list}[\text{middle}]$ with the searchnum and adjust left or right

| | | | | | | | | | |
|----------|------|---|---|---|--------|----|----|----|-------|
| value | 1 | 5 | 7 | 8 | 13 | 19 | 20 | 23 | 29 |
| index | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| variable | left | | | | middle | | | | right |

assume searchnum is 23

Algorithm Specification: Binary Search

compare `list[middle]` with `searchnum`

1. `searchnum < list[middle]` set `right` to `middle-1`
2. `searchnum = list[middle]` return `middle`
3. `searchnum > list[middle]` set `left` to `middle+1`

| | | | | | | | | | |
|----------|---|---|---|---|----|------|----|----|-------|
| value | 1 | 5 | 7 | 8 | 13 | 19 | 20 | 23 | 29 |
| index | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| variable | | | | | | left | | | right |

Algorithm Specification: Binary Search

if searchnum has not been found and there are more integers to check

- recalculate middle and continue search
- determining if there are any elements left to check

| | | | | | | | | | |
|----------|---|---|---|---|----|------|--------|----|-------|
| value | 1 | 5 | 7 | 8 | 13 | 19 | 20 | 23 | 29 |
| index | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| variable | | | | | | left | middle | | right |

- handling the comparison (through a function or a macro)

| | | | | | | | | | |
|----------|---|---|---|---|----|----|----|------|-------|
| value | 1 | 5 | 7 | 8 | 13 | 19 | 20 | 23 | 29 |
| index | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| variable | | | | | | | | left | right |

Algorithm Specification: Binary Search

- **function:** compare(int x, int y)

```
int compare(int x, int y){  
    if (x < y) return -1;  
    else if (x == y) return 0;  
    else return 1;  
}
```

- **macro:** COMPARE(x, y)

```
#define COMPARE(x,y) (((x) < (y) ? -1: (x) == (y)) ? 0: 1)
```

Algorithm Specification: Binary Search

```
int binsearch(int list[],int searchnum,
              int left,int right) {
    int middle;
    while(left <= right) {
        middle = (left + right) / 2;
        switch(COMPARE(list[middle],searchnum)) {
            // COMPARE() returns -1, 0, or 1
            case -1: left = middle + 1;
                    break;
            case 0: return middle;
            case 1: right = middle - 1;
        }
    }
    return -1;
}
```

RECURSIVE ALGORITHMS

Recursive Algorithms

direct recursion

- call themselves

indirect recursion

- call other function that invoke the calling function again

recursive mechanism

- extremely powerful
- allows us to express a complex process in very clear terms

any function that we can write using assignment, if-else, and while statements can be written recursively

Recursive Algorithms: Binary Search

transform iterative version of a binary search into a recursive one

- establish boundary condition that terminate the recursive call
 1. success: `list[middle]=searchnum`
 2. failure: left & right indices cross
- implement the recursive calls so that each call brings us one step closer to a solution

Recursive Algorithms: Binary Search

```
int binsearch(int list[],int searchnum,int left,int right) {  
    int middle;  
    if(left <= right) {  
        middle=(left+right)/2;  
        switch(COMPARE(list[middle], searchnum)) {  
            case -1 : return  
                binsearch(list,searchnum,middle+1,right);  
            case 0 : return middle  
            case 1 : return  
                binsearch(list,searchnum,left,middle-1);  
        }  
    }  
    return -1;  
}
```


Recursive Algorithms: Permutations

given a set of $n(> 1)$ elements

- print out all possible permutations of this set

eg) if set a,b,c is given,

- then set of permutations is
(a,b,c), (a,c,b), (b,a,c), (b,c,a), (c,a,b), (c,b,a)

Recursive Algorithms: Permutations

if look at the set a,b,c,d, the set of permutations are

1. a followed by all permutations of (b,c,d)
2. b followed by all permutations of (a,c,d)
3. c followed by all permutations of (a,b,d)
4. d followed by all permutations of (a,b,c)

“followed by all permutations” : clue to the recursive solution

Recursive Algorithms: Permutations

```
void perm(char *list,int i,int n) {
    int j,temp;
    if(i==n) {
        for(j=0;j<=n;j++)
            printf("%c", list[j]);
        printf(" ");
    }
    else {
        for(j=i;j<=n;j++) {
            SWAP(list[i],list[j],temp);
            perm(list,i+1,n);
            SWAP(list[i],list[j],temp);
        }
    }
}
```

initial function call is **perm(list,0,n-1);**

recursively generates permutations **until i=n**

DATA ABSTRACTION



Data Abstraction: Data Type

definition

- a collection of objects and
- a set of operations that act on those objects
- basic data type
 - char, int, float, double
- composite data type
 - array, structure
- user-defined data type
- pointer data type

Data Abstraction: Abstract Data Type (ADT)

definition

- **data type** that is organized in such a way that
- **the specification** of the objects and **the specification** of the operations on the objects is separated from
- **the representation** of the objects and **the implementation** of the operations

specification

- names of every function
- type of its arguments
- type of its result
- description of what the function does

classify the function of data type

- **creator/constructor:** These functions create a new instance of the designated type.
- **transformers:** These functions also create an instance of the designated type, generally by using one or more other instance.
- **observers/reporters:** These functions provide information about an instance of the type, but they do not change the instance.

Data Abstraction: Abstract Data Type

```
structure Natural_Number(Nat_No) is
  objects: an ordered subrange of the integers
            starting at zero and ending at the max.
            integer on the computer
  functions: for all x, y in Natural_Number;
              TRUE, FALSE in Boolean,
              and where +, -, <, and == are
              the usual integer operations,

  Nat_No Zero() ::= 0
  Nat_No Add(x,y) ::= if ((x+y)<=INT_MAX) return x+y
                     else return INT_MAX
  Nat_No Subtract(x,y) ::= if (x<y) return 0
                          else return x-y
  Boolean Equal(x,y) ::= if (x==y) return TRUE
                       else return FALSE
  Nat_No Successor(x) ::= if (x==INT_MAX) return x
                        else return x+1
  Boolean Is_Zero(x) ::= if (x) return FALSE
                      else return TRUE
end Natural_Number
```

Data Abstraction

objects and **functions** are two main sections in the definition

function Zero is a **constructor**

function Add, Subtractor, Successor are **transformers**

function Is_Zero and Equal are **reporters**

PERFORMANCE ANALYSIS



Performance Analysis

Performance evaluation

- performance analysis: machine independent complexity theory
- performance measurement: machine dependent

space complexity

- the amount of memory that it needs to run to completion

time complexity

- the amount of computer time that it needs to run to completion

Performance Analysis: Space Complexity

fixed space requirements

- don't depend on the number and size of the program's inputs and outputs
- eg) instruction space

variable space requirement

- the space needed by *structured variable* whose size depends on the particular instance, I , of the problem being solved

Performance Analysis: Space Complexity

total space requirement $S(Program)$

$$S(Program) = c + Sp(I)$$

c :

- constant representing the fixed space requirements

$S_p(I)$:

- function of some characteristics of the instance I
- variable space requirements for program ' p '

Performance Analysis: Space Complexity

```
float calculation(float a, float b, float c) {  
    return a+b+b*c+(a+b-c)/(a+b)+4.00;  
}
```

- input - three simple variables
- output - a simple variable
- There is no variable space requirement, fixed space requirements only
- $S_{calculation}(I) = o$

Performance Analysis: Space Complexity

Iterative Version

```
float sum(float list[], int n) {  
    float tempsum = 0;  
    int i;  
    for(i = 0; i < n; i++)  
        tempsum += list[i];  
    return tempsum;  
}
```

- input - an array variable
- output - a simple variable

Performance Analysis: Space Complexity

Pascal pass arrays **by value**

- entire array is copied into temporary storage before the function is executed
- $S_{sum}(I) = S_{sum}(n) = n$

C pass arrays **by pointer**

- passing *the address of the first element* of the array
- $S_{sum}(n) = 0$

Performance Analysis: Space Complexity

Recursive Version

```
float rsum(float list[],int n) {  
    if(n) return rsum(list,n-1) + list[n-1];  
    return 0;  
}
```

handled recursively

- compiler must save
 - the parameters
 - the local variables
 - the return address
- for each recursive call

Although Recursive version allows to express very clear, it has a greater overhead than its iterative counterpart

Performance Analysis: Space Complexity

space needed for one recursive call


- number of bytes required for the two parameters and the return address
- 12 bytes needed on Intel-i7 (depends on the architecture)
 - 4 bytes for pointer list[]
 - 4 bytes for integer n
 - 4 bytes for return address

assume array has $n = \text{MAX_SIZE}$ numbers,

total variable space $S_{rsum}(\text{MAX_SIZE})$

- $S_{rsum}(\text{MAX_SIZE}) = 12 * \text{MAX_SIZE}$

PERFORMANCE ANALYSIS : TIME COMPLEXITY



Performance Analysis: Time Complexity

The time $T(P)$, taken by a program P ,

- is the sum of its compile time and its run(or execution) time
- We really concerned only with the program's execution time, T_p

count the number of operations the program performs

- give a machine-independent estimation

Performance Analysis: Time Complexity

Iterative summing of a list of numbers

```
float sum(float list[], int n) {  
    float tempsum=0;  
    \textbf{count}++; /* for assignment */  
    int i;  
    for(i = 0; i < n; i++) {  
        \textbf{count}++; /* for the for loop */  
        tempsum += list[i];  
        \textbf{count}++; /*for assignment*/  
    }  
    \textbf{count}++; /* last execution of for */  
    \textbf{count}++; /* for return */  
    return tempsum;  
}
```

Performance Analysis: Time Complexity

eliminate most of the program statements from Program to obtain a simpler program that **computes the same value for count**

```
float sum(float list[], int n) {  
    float tempsum=0;  
    int i;  
    for(i = 0; i < n; i++)  
        count += 2;  
    count += 3;  
    return tempsum;  
}
```

for one time execution **sum** function

- `count += 2` in for loop n time : $2n$
- `count += 3` : 3
- **total $2n + 3$ steps**

Performance Analysis: Time Complexity

Recursive summing of a list of numbers

```
float rsum(float list[], int n) {  
    count++;  
    if(n) {  
        count++;  
        return rsum(list,n-1)+list[n-1];  
    }  
    count++;  
    return 0;  
}
```


Performance Analysis: Time Complexity

when $n=0$ only the if conditional and the second return statement are executed (termination condition)

- step count for $n = 0 : 2$
- each step count for $n > 0 : 2$

total step count for function : $2n + 2$

- less step count than iterative version, but
- take more time than those of the iterative version

Performance Analysis: Time Complexity

Matrix Addition determine the step count for a function that adds two-dimensional arrays(rows and cols)

```
void add(int a[][M_SIZE],int b[][M_SIZE],int c[][M_SIZE],
        int rows,int cols) {
    int i, j;
    for(i = 0; i < rows; i++)
        for(j = 0; j < cols; j++)
            c[i][j] = a[i][j] + b[i][j];
}
```

Performance Analysis: Time Complexity

apply step counts to add function

```
void add(int a[][M_SIZE],int b[][M_SIZE], int c[][M_SIZE],
        int rows,int cols) {
    int i,j;
    for(i = 0; i < rows; i++) {
        count++;
        for(j = 0; j < cols; j++) {
            count++;
            c[i][j] = a[i][j] + b[i][j];
            count++;
        }
        count++;
    }
    count++;
}
```

Performance Analysis: Time Complexity

combine counts

```
void add(int a[][M_SIZE],int b[][M_SIZE],int c[][M_SIZE],
        int rows,int cols) {
    int i, j;
    for(i = 0; i < rows; i++) {
        for(j = 0; j < cols; j++)
            count += 2;
        count += 2;
    }
    count++;
}
```

- initially count = 0;
- total step count on termination : $2 \cdot \text{rows} \cdot \text{cols} + 2 \cdot \text{rows} + 1$;
- In this case, If the number of rows is more than the number of columns, swaping rows and columns will take fewer steps

Performance Analysis: Time Complexity

Tabular Method

construct a step count table

1. first determine the step count for each statement
 - $\text{steps}/\text{execution}(s/e)$
2. next figure out the number of times that each statement is executed
 - frequency
3. total steps for each statement
 - $(\text{total steps}) = (s/e) * \text{frequency}$

Performance Analysis: Time Complexity

Iterative function to sum a list of numbers

| Statement | s/e | Frequency | Total steps |
|---------------------------------|------|-----------|-------------|
| float sum(float list[],int n) { | 0 | 0 | 0 |
| float tempsum=0; | 1 | 1 | 1 |
| int i; | 0 | 0 | 0 |
| for(i=0;i<n;i++) | 1 | n+1 | n+1 |
| tempsum+=list[i]; | 1 | n | n |
| return tempsum; | 1 | 1 | 1 |
| } | 0 | 0 | 0 |
| total | 2n+3 | | |

Figure: step count table

Performance Analysis: Time Complexity

Recursive function to sum a list of numbers

| Statement | s/e | Frequency | Total steps |
|----------------------------------|-----|-----------|-------------|
| float rsum(float list[],int n) { | 0 | 0 | 0 |
| if(n) | 1 | n+1 | n+1 |
| return rsum(list,n-1)+list[n-1]; | 1 | n | n |
| return 0; | 1 | 1 | 1 |
| } | 0 | 0 | 0 |
| total | | | 2n+2 |

Figure: step count table for recursive summing function

Performance Analysis: Time Complexity

Matrix addition

| Statement | s/e | Frequency | Total steps |
|----------------------------------|-----|---------------|----------------------|
| void add(int a[][M_SIZE] ...) { | 0 | 0 | 0 |
| int i,j; | 0 | 0 | 0 |
| for(i=0;i<rows;i++) | 1 | rows+1 | rows+1 |
| for(j=0;j<cols;j++) | 1 | rows·(cols+1) | rows·cols+rows |
| c[i][j] = a[i][j] + b[i][j]; | 1 | rows·cols | rows·cols |
| } | 0 | 0 | 0 |
| total | | | 2·rows·cols+2·rows+1 |

Figure: step count table for matrix addition

Performance Analysis: Time Complexity

factors: time complexity

1. input size

- depends on size of input(n): $T(n) = ?$

2. input form

- depends on different possible input formats
 - average case: $A(n) = ?$
 - worst case: $W(n) = ?$
- concerns mostly for “worst case”
- worst case gives “upper bound”
 - exist different algorithm for the same task
 - which one is faster ?

○ The “worst case” means case that has maximum number of steps

PERFORMANCE ANALYSIS : ASYMP- TOTIC NOTATION

Performance Analysis: Asymptotic Notation

comparing time complexities

- exist different algorithms for the same task
- which one is faster ?

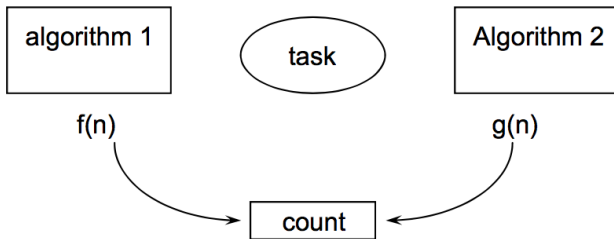


Figure: Which one is faster?

Performance Analysis: Asymptotic Notation

Big “OH”

○ **def** $f(n) = O(g(n))$

- iff (if and only if) there exist positive constants c and n_0 such that
- $f(n) \leq c \cdot g(n)$ for all n , $n \geq n_0$ (n_0 is the break even point)

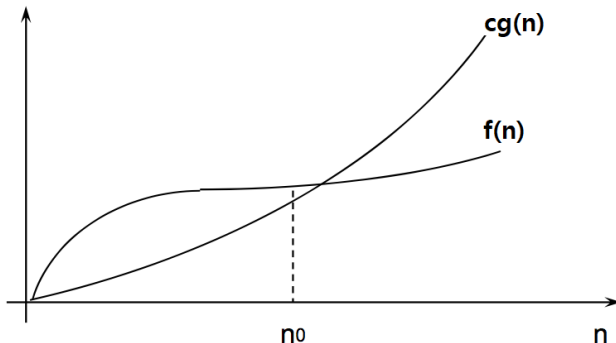


Figure: Which one is faster?

Performance Analysis: Asymptotic Notation

$$f(n) = 25 \cdot n, g(n) = 1/3 \cdot n^2$$

- $25 \cdot n = O(n^2/3)$ if let $c = 1$
- 'f of n' is 'big-oh of g of n'

| n | $f(n) = 25 \cdot n$ | $g(n) = n^2 / 3$ |
|----|---------------------|------------------|
| 1 | 25 | 1/3 |
| 2 | 50 | 4/3 |
| . | . | . |
| . | . | . |
| . | . | . |
| 75 | 1875 | 1875 |

Figure: Which one is faster?

$$|25 \cdot n| \leq 1 \cdot |n^2/3| \text{ for all } n \geq 75$$

Performance Analysis: Asymptotic Notation

$$f(n) = O(g(n))$$

- $g(n)$ is an upper bound on the value of $f(n)$ for all n , $n \geq n_0$
- but, doesn't say anything about how good this bound is
 - $n = O(n^2)$, $n = O(n^{2.5})$
 - $n = O(n^3)$, $n = O(2^n)$
- $g(n)$ should be as small a function of n as one can come up with for which $f(n) = O(g(n))$

$$f(n) = O(g(n)) \neq O(g(n)) = f(n)$$

(It is meaningless to say that $O(g(n)) = f(n)$)

Performance Analysis: Asymptotic Notation

theorem) if $f(n) = a_m n^m + \dots + a_1 n + a_0$, then $f(n) = O(n^m)$

proof)

$$\begin{aligned} f(n) &\leq |a_k| \cdot n^k + |a_{k-1}| \cdot n^{k-1} + \dots + |a_1| \cdot n + |a_0| \\ &= |a_k| + |a_{k-1}|/n + \dots + |a_1|/n^{k-1} + |a_0|/n^k \cdot n^k \\ &\leq |a_k| + |a_{k-1}| + \dots + |a_1| + |a_0| \cdot n^k \\ &= c \cdot n^k (c = |a_k| + |a_{k-1}| + \dots + |a_1| + |a_0|) = O(n^k) \end{aligned}$$

Performance Analysis: Asymptotic Notation

Omega def) $f(n) = \Omega(g(n))$

- iff there exist positive constants c and n_0 such that $f(n) \geq c \cdot g(n)$ for all $n, n \geq n_0$

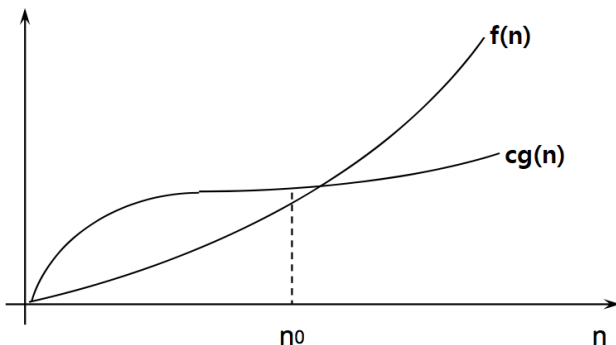


Figure: Which one is faster?

Performance Analysis: Asymptotic Notation

Omega

- $g(n)$ is a lower bound on the value of $f(n)$ for all n , $n \geq n_0$
- should be as large a function of n as possible

theorem) if $f(n) = a_m n^m + \dots + a_1 n + a_0$ and $a_m > 0$, then $f(n) = \Omega(n^m)$

Performance Analysis: Asymptotic Notation

Theta def) $f(n) = \Theta(g(n))$

- iff there exist positive constants c^1 , c^2 , and n^0 such that
- $c^1 \cdot g(n) \leq f(n) \leq c^2 \cdot g(n)$ for all n , $n \geq n^0$

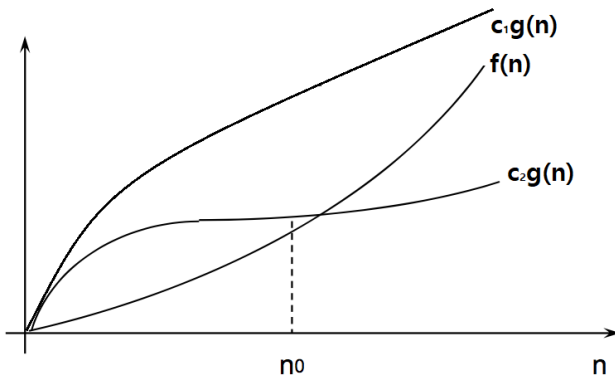


Figure: Which one is faster?

Performance Analysis: Asymptotic Notation

Theta

- more precise than both the “big oh” and omega notations
- $g(n)$ is both an upper and lower bound on $f(n)$

Performance Analysis: Asymptotic Notation

Complexity of matrix addition

| Statement | Asymptotic complexity |
|----------------------------------|---|
| void add(int a[][M_SIZE] ...) { | 0 |
| int i, j; | 0 |
| for(i = 0; i < rows; i++) | $\Theta(\text{rows})$ |
| for(j = 0; j < cols; j++) | $\Theta(\text{rows} \cdot \text{cols})$ |
| c[i][j] = a[i][j] + b[i][j]; | $\Theta(\text{rows} \cdot \text{cols})$ |
| } | 0 |
| Total | $\Theta(\text{rows} \cdot \text{cols})$ |

Figure: time complexity of matrix addition

PERFORMANCE ANALYSIS : PRACTICAL COMPLEXITIES

Performance Analysis: Practical Complexities

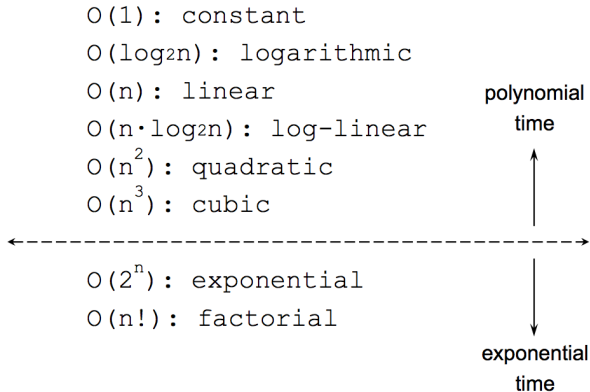


Figure: Class of time complexities

Performance Analysis: Practical Complexities

polynomial time

- tractable problem exponential time
- intractable (hard) problem

eg)

- sequential search
- binary search
- insertion sort
- heap sort
- satisfiability problem
- testing serializable scheduling

Performance Analysis: Practical Complexities

| | | instance characteristic n | | | | | |
|----------------|-------------|---------------------------|---|----|-------|----------------|------------------------|
| time | name | 1 | 2 | 4 | 8 | 16 | 32 |
| 1 | constant | 1 | 1 | 1 | 1 | 1 | 1 |
| log n | logarithmic | 0 | 1 | 2 | 3 | 4 | 5 |
| n | linear | 1 | 2 | 4 | 8 | 16 | 32 |
| n log n | log linear | 0 | 2 | 8 | 24 | 64 | 160 |
| n ² | quadratic | 1 | 4 | 16 | 64 | 256 | 1024 |
| n ³ | cubic | 1 | 8 | 64 | 512 | 4096 | 32768 |
| 2n | exponential | 2 | 4 | 16 | 256 | 65536 | 4294967296 |
| n! | factorial | 1 | 2 | 24 | 40320 | 20922789888000 | 26313×10 ³³ |

Figure: function value

Performance Analysis: Practical Complexities

If a program needs 2^n steps for execution

- $n=40$: number of steps = 1.1×10^{12} in computer systems
 - 1 billion steps/sec — 18.3 min
- $n=50$ — 13 days
- $n=60$ — 310.56 years
- $n=100$ — 4×10^{13} years

If a program needs n^{10} steps for execution

- $n=10$ — 10 sec
- $n=100$ — 3171 years