

Contents

1	Basic	1
1.1	/.vimrc	1
1.2	default code	1
1.3	debug list	1
2	Flow	1
2.1	Dinic	1
2.2	Gomory Hu	2
2.3	min cost flow	2
3	Geometry	2
3.1	2D Point Template	2
3.2	外心 Circumcentre	3
3.3	Convex Hull	3
3.4	半平面交	3
3.5	圖交	3
3.6	線段交	3
3.7	Smallest Covering Circle	3
4	Mathmatics	4
4.1	ax+by=gcd(a,b)	4
4.2	BigInt	4
4.3	FFT	5
4.4	FWHT	5
4.5	GaussElimination	6
4.6	Inverse	6
4.7	LinearPrime	6
4.8	Miller Rabin	6
4.9	Pollard's rho	6
4.10	數論基本工具	6
4.11	Mobius	6
4.12	Simplex	6
4.13	SG	7
4.14	Theorem	8
5	Graph	8
5.1	BCC	8
5.2	Dijkstra	9
5.3	Theorm - Domination	9
5.4	Strongly Connected Component(SCC)	9
5.5	DominatorTree	9
5.6	Manhattan MST	10
5.7	Hungarian	11
5.8	KM	11
5.9	Theorm - Matching	11
5.10	Maximum General Matching	12
5.11	Minimum General Weighted Matching	12
5.12	Maximum Clique	13
5.13	Steiner Tree	13
5.14	最小平均環	13
5.15	SchreierSims	14
5.16	Tarjan	14
5.17	2-SAT	15
6	Data Structure	15
6.1	2D Range Tree	15
6.2	ext heap	16
6.3	KD tree	16
6.4	Link Cut tree	16
6.5	Sparse Table	17
6.6	Treap Lin	17
7	String	18
7.1	AC 自動機	18
7.2	KMP	19
7.3	迴文字動機	19
7.4	Suffix Automaton	19
7.5	smallest rotation	20
7.6	Suffix Array	20
7.7	Z-value	20
8	Dark Code	20
8.1	輸入優化	20
9	Search	21
10	Others	21
10.1	矩陣數定理	21
10.2	CYK	21
10.3	數位統計	22
10.4	1D/1D dp 優化	22
10.5	Theorm - DP optimization	23
10.6	Stable Marriage	23
10.7	Mo's algorithm	23
10.8	parser	24
10.9	python 小抄	24
11	Persistence	25

Basic

/.vimrc

```

set nu ai si cin ts=4 sw=4 sts=4 expandtab

nmap #2 :! gedit %<.in %<*.in &<CR>
nmap #4 :! date > %<.pt; cat -n % > %<.pt; lpr %<.pt <
CR>
nmap #9 :! clear ; g++ -std=c++11 -O2 -D AC -o %<.out %
; for i in %<*.in; do echo $i; ./%<.out < $i; echo
""; done <CR>
nmap #0 :! clear ; g++ -std=c++11 -O2 -D AC -o %<.out %
; ./%<.out <CR>
nmap <C-I> :! read -p "CASE:" CASE; gedit %<_$CASE.in <
CR>

```

default code

```

#include <bits/stdc++.h>
using namespace std;

int main(){
#ifdef AC
freopen("", "r", stdin);
#endif
ios_base::sync_with_stdio(0);
cin.tie(0);
}

```

debug list

模板要記得 init
 priority_queue 要清空
 把邊界條件都加入測資
 邊界條件 (過程溢位, 題目數據範圍), 會不會爆 long long
 是否讀錯題目, 想不到時可以自己讀一次題目
 環狀 or 凸包問題一定要每種都算 n 次
 比較容易有問題的地方換人寫
 注意公式有沒有推錯或抄錯
 精度誤差 sqrt(大大的東西) + EPS
 測試 %lld or %I64d
 喇分 random_shuffle 隨機演算法

Flow

Dinic

(a) Bounded Maxflow Construction:
 1. add two node ss, tt
 2. add_edge(ss, tt, INF)
 3. for each edge u -> v with capacity [l, r]:
 add_edge(u, tt, l)
 add_edge(ss, v, l)
 add_edge(u, v, r-l)
 4. see (b), check if it is possible.
 5. answer is maxflow(ss, tt) + maxflow(s, t)

 (b) Bounded Possible Flow:
 1. same construction method as (a)
 2. run maxflow(ss, tt)
 3. for every edge connected with ss or tt:
 rule: check if their rest flow is exactly 0
 4. answer is possible if every edge do satisfy the rule
 ;
 5. otherwise, it is NOT possible.

```

(c) Bounded Minimum Flow:
1. same construction method as (a)
2. answer is maxflow(ss, tt)
-----
(d) Bounded Minimum Cost Flow:
* the concept is somewhat like bounded possible flow.
1. same construction method as (a)
2. answer is maxflow(ss, tt) + ( $\sum$  1 * cost for every edge)
-----
(e) Minimum Cut:
1. run maxflow(s, t)
2. run cut(s)
3. ss[i] = 1: node i is at the same side with s.
-----

const long long INF = 1LL<<60;
struct Dinic { //O(VVE), with minimum cut
    static const int MAXN = 5003;
    struct Edge{
        int u, v;
        long long cap, rest;
    };

    int n, m, s, t, d[MAXN], cur[MAXN];
    vector<Edge> edges;
    vector<int> G[MAXN];

    void init(){
        edges.clear();
        for ( int i = 0 ; i < MAXN ; i++ ) G[i].clear();
    }

    // min cut start
    bool side[MAXN];
    void cut(int u) {
        side[u] = 1;
        for ( int i : G[u] ) {
            if ( !side[ edges[i].v ] && edges[i].rest )
                cut(edges[i].v);
        }
    }
    // min cut end

    void add_edge(int u, int v, long long cap){
        edges.push_back( {u, v, cap, cap} );
        edges.push_back( {v, u, 0, 0LL} );
        m = edges.size();
        G[u].push_back(m-2);
        G[v].push_back(m-1);
    }

    bool bfs(){
        memset(d, -1, sizeof(d));
        queue<int> que;
        que.push(s); d[s]=0;
        while (!que.empty()){
            int u = que.front(); que.pop();
            for (int ei : G[u]){
                Edge &e = edges[ei];
                if (d[e.v] < 0 && e.rest > 0){
                    d[e.v] = d[u] + 1;
                    que.push(e.v);
                }
            }
        }
        return d[t] >= 0;
    }

    long long dfs(int u, long long a){
        if ( u == t || a == 0 ) return a;
        long long flow = 0, f;
        for ( int &i=cur[u]; i < (int)G[u].size() ; i++ ) {
            Edge &e = edges[ G[u][i] ];
            if ( d[u] + 1 != d[e.v] ) continue;

```

```

        f = dfs(e.v, min(a, e.rest) );
        if ( f > 0 ) {
            e.rest -= f;
            edges[ G[u][i]^1 ].rest += f;
            flow += f;
            a -= f;
            if ( a == 0 ) break;
        }
    }
    return flow;
}

long long maxflow(int s, int t){
    this->s = s, this->t = t;
    long long flow = 0, mf;
    while ( bfs() ){
        memset(cur, 0, sizeof(cur));
        while ( (mf = dfs(s, INF)) ) flow += mf;
    }
    return flow;
}
} dinic;

```

Gomory Hu

Construct of Gomory Hu Tree

1. make sure the whole graph is clear
2. set node 0 as root, also be the parent of other nodes.
3. for every node $i > 0$, we run maxflow from i to $parent[i]$
4. hence we know the weight between i and $parent[i]$
5. for each node $j > i$, if j is at the same side with i , make the parent of j as i

```

int e[MAXN][MAXN];
int p[MAXN];

Dinic D; // original graph

void gomory_hu() {
    fill(p, p+n, 0);
    fill(e[0], e[n], INF);
    for ( int s = 1 ; s < n ; s++ ) {
        int t = p[s];
        Dinic F = D;
        int tmp = F.max_flow(s, t);

        for ( int i = 1 ; i < s ; i++ )
            e[s][i] = e[i][s] = min(tmp, e[t][i]);

        for ( int i = s+1 ; i <= n ; i++ )
            if ( p[i] == t && F.side[i] ) p[i] = s;
    }
}

```

min cost flow

```

// long long version
typedef pair<long long, long long> pll;
struct CostFlow {
    static const int MAXN = 350;
    static const long long INF = 1LL<<60;
    struct Edge {
        int to, r;
        long long rest, c;
    };
    int n, pre[MAXN], preL[MAXN]; bool inq[MAXN];
    long long dis[MAXN], fl, cost;

```

```

vector<Edge> G[MAXN];
void init() {
    for ( int i = 0 ; i < MAXN ; i++) G[i].clear();
}
void add_edge(int u, int v, long long rest, long long c) {
    G[u].push_back({v, (int)G[v].size() , rest, c});
    G[v].push_back({u, (int)G[u].size()-1, 0, -c});
}
pll flow(int s, int t) {
    fl = cost = 0;
    while (true) {
        fill(dis, dis+MAXN, INF);
        fill(inq, inq+MAXN, 0);
        dis[s] = 0;
        queue<int> que;
        que.push(s);
        while ( !que.empty() ) {
            int u = que.front(); que.pop();
            inq[u] = 0;
            for ( int i = 0 ; i < (int)G[u].size() ; i++) {
                int v = G[u][i].to;
                long long w = G[u][i].c;
                if ( G[u][i].rest > 0 && dis[v] >
                    dis[u] + w ) {
                    pre[v] = u; preL[v] = i;
                    dis[v] = dis[u] + w;
                    if (!inq[v]) {
                        inq[v] = 1;
                        que.push(v);
                    }
                }
            }
        }

        if (dis[t] == INF) break;
        long long tf = INF;
        for (int v = t, u, l ; v != s ; v = u ) {
            u = pre[v]; l = preL[v];
            tf = min(tf, G[u][l].rest);
        }
        for (int v = t, u, l ; v != s ; v = u ) {
            u = pre[v]; l = preL[v];
            G[u][l].rest -= tf;
            G[v][G[u][l].r].rest += tf;
        }
        cost += tf * dis[t];
        fl += tf;
    }
    return {fl, cost};
}
} flow;

```

Geometry

2D Point Template

```

typedef double Double;
struct Point {
    Double x,y;

    bool operator < (const Point &b)const{
        //return tie(x,y) < tie(b.x,b.y);
        //return atan2(y,x) < atan2(b.y,b.x);
        assert(0 && "choose compare");
    }
    Point operator + (const Point &b)const{
        return (Point){x+b.x,y+b.y};
    }
    Point operator - (const Point &b)const{
        return (Point){x-b.x,y-b.y};
    }
}

```

```

Point operator * (const Double &d)const{
    return Point(d*x,d*y);
}
Double operator * (const Point &b)const{
    return x*b.x + y*b.y;
}
Double operator % (const Point &b)const{
    return x*b.y - y*b.x;
}
friend Double abs2(const Point &p){
    return p.x*p.x + p.y*p.y;
}
friend Double abs(const Point &p){
    return sqrt( abs2(p) );
}
};
typedef Point Vector;

struct Line{
    Point P; Vector v;
    bool operator < (const Line &b)const{
        return atan2(v.y,v.x) < atan2(b.v.y,b.v.x);
    }
};

```

外心 Circumcentre

```

#include "2Dpoint.cpp"

Point circumcentre(Point &p0, Point &p1, Point &p2){
    Point a = p1-p0;
    Point b = p2-p0;
    Double c1 = abs2(a)*0.5;
    Double c2 = abs2(b)*0.5;
    Double d = a % b;
    Double x = p0.x + ( c1*b.y - c2*a.y ) / d;
    Double y = p0.y + ( c2*a.x - c1*b.x ) / d;
    return {x,y};
}

```

Convex Hull

```

#include "2Dpoint.cpp"

// return H, 第一個點會在 H 出現兩次
void ConvexHull(vector<Point> &P, vector<Point> &H){
    int n = P.size(), m=0;
    sort(P.begin(),P.end());
    H.clear();

    for (int i=0; i<n; i++){
        while (m>=2 && (P[i]-H[m-2]) % (H[m-1]-H[m-2])
            <0)H.pop_back(), m--;
        H.push_back(P[i]), m++;
    }

    for (int i=n-2; i>=0; i--){
        while (m>=2 && (P[i]-H[m-2]) % (H[m-1]-H[m-2])
            <0)H.pop_back(), m--;
        H.push_back(P[i]), m++;
    }
}

```

半平面交

```

bool OnLeft(const Line& L,const Point& p){
    return Cross(L.v,p-L.P)>0;
}
Point GetIntersection(Line a,Line b){
    Vector u = a.P-b.P;
    Double t = Cross(b.v,u)/Cross(a.v,b.v);
}

```

```

    return a.P + a.v*t;
}
int HalfplaneIntersection(Line* L,int n,Point* poly){
    sort(L,L+n);

    int first,last;
    Point *p = new Point[n];
    Line *q = new Line[n];
    q[first=last=0] = L[0];
    for(int i=1;i<n;i++){
        while(first < last && !OnLeft(L[i],p[last-1])) last
            --;
        while(first < last && !OnLeft(L[i],p[first])) first
            ++;
        q[++last]=L[i];
        if(fabs(Cross(q[last].v,q[last-1].v))<EPS){
            last--;
            if(OnLeft(q[last],L[i].P)) q[last]=L[i];
        }
        if(first < last) p[last-1]=GetIntersection(q[last-1],q[last]);
    }
    while(first<last && !OnLeft(q[first],p[last-1])) last
        --;
    if(last-first<=1) return 0;
    p[last]=GetIntersection(q[last],q[first]);

    int m=0;
    for(int i=first;i<=last;i++) poly[m++]=p[i];
    return m;
}

```

圓交

```

vector<Double> interCircle(Double o1, Double r1, Double
    o2, Double r2) {
    Double d2 = abs2(o1 - o2);
    Double d = sqrt(d2);
    if (d < fabs(r1-r2) || r1+r2 < d) return {};
    Double u = 0.5*(o1+o2) + ((r2*r2-r1*r1)/(2.0*d2))*(o1
        -o2);
    Double A = sqrt((r1+r2+d) * (r1-r2+d) * (r1+r2-d) *
        (-r1+r2+d));
    Double v = A / (2.0*d2) * Double(o1.S-o2.S, -o1.F+o2.
        F);
    return {u+v, u-v};
}

```

線段交

```

Point interPnt(Point p1, Point p2, Point q1, Point q2,
    bool &res){
    Double f1 = cross(p2, q1, p1);
    Double f2 = -cross(p2, q2, p1);
    Double f = (f1 + f2);

    if(fabs(f) < EPS) {
        res = false;
        return {};
    }

    res = true;
    return (f2 / f) * q1 + (f1 / f) * q2;
}

```

Smallest Covering Circle

```

#include "circumcentre.cpp"
pair<Point,Double> SmallestCircle(int n, Point _p[]){
    Point *p = new Point[n];
    memcpy(p,_p,sizeof(Point)*n);
}

```

```

    random_shuffle(p,p+n);

    Double r2=0;
    Point cen;
    for (int i=0; i<n; i++){
        if ( abs2(cen-p[i]) <= r2)continue;
        cen = p[i], r2=0;
        for (int j=0; j<i; j++){
            if ( abs2(cen-p[j]) <= r2)continue;
            cen = (p[i]+p[j])*0.5;
            r2 = abs2(cen-p[i]);
            for (int k=0; k<j; k++){
                if ( abs2(cen-p[k]) <= r2)continue;
                cen = circumcentre(p[i],p[j],p[k]);
                r2 = abs2(cen-p[k]);
            }
        }
    }

    delete[] p;
    return {cen,r2};
}
// auto res = SmallestCircle();

```

Mathmatics

$ax+by=\gcd(a,b)$

```

typedef pair<int, int> pii;
pii extgcd(int a, int b){
    if(b == 0) return make_pair(1, 0);
    else{
        int p = a / b;
        pii q = extgcd(b, a % b);
        return make_pair(q.second, q.first - q.second * p);
    }
}

```

BigInt

```

struct BigInt{
    static const int LEN = 60;
    static const int BIGMOD = 10000;
    int s;
    int v1, v[LEN];
    // vector<int> v;
    BigInt() : s(1) { v1 = 0; }
    BigInt(long long a) {
        s = 1; v1 = 0;
        if (a < 0) { s = -1; a = -a; }
        while (a) {
            push_back(a % BIGMOD);
            a /= BIGMOD;
        }
    }
    BigInt(string str) {
        s = 1; v1 = 0;
        int stPos = 0, num = 0;
        if (!str.empty() && str[0] == '-') {
            stPos = 1;
            s = -1;
        }
        for (int i=SZ(str)-1, q=1; i>=stPos; i--) {
            num += (str[i] - '0') * q;
            if ((q *= 10) >= BIGMOD) {
                push_back(num);
                num = 0; q = 1;
            }
        }
        if (num) push_back(num);
    }
    int len() const { return v1; /* return SZ(v); */ }
}

```

```

bool empty() const { return len() == 0; }
void push_back(int x) { v[vl++] = x; /* v.PB(x); */ }
void pop_back() { vl--; /* v.pop_back(); */ }
int back() const { return v[vl-1]; /* return v.back()
    ; */ }
void n() { while (!empty() && !back()) pop_back(); }
void resize(int nl) {
    vl = nl; fill(v, v+vl, 0);
    // v.resize(nl); // fill(ALL(v), 0);
}
void print() const {
    if (empty()) { putchar('0'); return; }
    if (s == -1) putchar('-');
    printf("%d", back());
    for (int i=len()-2; i>=0; i--) printf("%.4d",v[i]);
}
friend ostream& operator << (ostream& out,
    const Bigint &a) {
    if (a.empty()) { out << "0"; return out; }
    if (a.s == -1) out << "-";
    out << a.back();
    for (int i=a.len()-2; i>=0; i--) {
        char str[10];
        snprintf(str, 5, "%.4d", a.v[i]);
        out << str;
    }
    return out;
}
int cp3(const Bigint &b) const {
    if (s != b.s) return s > b.s ? 1 : -1;
    if (s == -1) return -(*this).cp3(-b);
    if (len() != b.len()) return len()>b.len()?1:-1;
    for (int i=len()-1; i>=0; i--)
        if (v[i]!=b.v[i]) return v[i]>b.v[i]?1:-1;
    return 0;
}
bool operator < (const Bigint &b) const { return cp3(b)
    ==-1; }
bool operator <= (const Bigint &b) const { return cp3(b)
    <=0; }
bool operator >= (const Bigint &b) const { return cp3(b)
    >=0; }
bool operator == (const Bigint &b) const { return cp3(b)
    ==0; }
bool operator != (const Bigint &b) const { return cp3(b)
    !=0; }
bool operator > (const Bigint &b) const { return cp3(b)
    ==1; }
Bigint operator - () const {
    Bigint r = (*this);
    r.s = -r.s;
    return r;
}
Bigint operator + (const Bigint &b) const {
    if (s == -1) return -(*this)+(-b);
    if (b.s == -1) return (*this)-(-b);
    Bigint r;
    int nl = max(len(), b.len());
    r.resize(nl + 1);
    for (int i=0; i<nl; i++) {
        if (i < len()) r.v[i] += v[i];
        if (i < b.len()) r.v[i] += b.v[i];
        if (r.v[i] >= BIGMOD) {
            r.v[i+1] += r.v[i] / BIGMOD;
            r.v[i] %= BIGMOD;
        }
    }
    r.n();
    return r;
}
Bigint operator - (const Bigint &b) const {
    if (s == -1) return -(*this)-(-b);
    if (b.s == -1) return (*this)+(-b);
    if ((*this) < b) return -(b-(*this));
    Bigint r;
    r.resize(len());
    for (int i=0; i<len(); i++) {

```

```

        r.v[i] += v[i];
        if (i < b.len()) r.v[i] -= b.v[i];
        if (r.v[i] < 0) {
            r.v[i] += BIGMOD;
            r.v[i+1]--;
        }
    }
    r.n();
    return r;
}
Bigint operator * (const Bigint &b) {
    Bigint r;
    r.resize(len() + b.len() + 1);
    r.s = s * b.s;
    for (int i=0; i<len(); i++) {
        for (int j=0; j<b.len(); j++) {
            r.v[i+j] += v[i] * b.v[j];
            if (r.v[i+j] >= BIGMOD) {
                r.v[i+j+1] += r.v[i+j] / BIGMOD;
                r.v[i+j] %= BIGMOD;
            }
        }
    }
    r.n();
    return r;
}
Bigint operator / (const Bigint &b) {
    Bigint r;
    r.resize(max(1, len()-b.len()+1));
    int oriS = s;
    Bigint b2 = b; // b2 = abs(b)
    s = b2.s = r.s = 1;
    for (int i=r.len()-1; i>=0; i--) {
        int d=0, u=BIGMOD-1;
        while(d<u) {
            int m = (d+u+1)>>1;
            r.v[i] = m;
            if((r*b2) > (*this)) u = m-1;
            else d = m;
        }
        r.v[i] = d;
    }
    s = oriS;
    r.s = s * b.s;
    r.n();
    return r;
}
Bigint operator % (const Bigint &b) {
    return (*this)-(*this)/b*b;
}
};

```

FFT

```

const double pi = atan(1.0)*4;
struct Complex {
    double x,y;
    Complex(double _x=0,double _y=0)
        :x(_x),y(_y) {}
    Complex operator + (Complex &tt) { return Complex(x
        +tt.x,y+tt.y); }
    Complex operator - (Complex &tt) { return Complex(x
        -tt.x,y-tt.y); }
    Complex operator * (Complex &tt) { return Complex(x
        *tt.x-y*tt.y,x*tt.y+y*tt.x); }
};
void fft(Complex *a, int n, int rev) {
    // n是大于等于相乘的两个数组长度的2的幂次
    // 从0开始表示长度，对a进行操作
    // rev==1进行DFT，==-1进行IDFT
    for (int i = 1, j = 0; i < n; ++ i) {
        for (int k = n>>1; k > (j^=k); k >>= 1);
        if (i<j) std::swap(a[i],a[j]);
    }
    for (int m = 2; m <= n; m <= 1) {

```

```

    Complex wm(cos(2*pi*rev/m),sin(2*pi*rev/m));
    for (int i = 0; i < n; i += m) {
        Complex w(1.0,0.0);
        for (int j = i; j < i+m/2; ++ j) {
            Complex t = w*a[j+m/2];
            a[j+m/2] = a[j] - t;
            a[j] = a[j] + t;
            w = w * wm;
        }
    }
    if (rev== -1) {
        for (int i = 0; i < n; ++ i) a[i].x /= n, a[i].y
            /= n;
    }
}

```

FWHT

```

// FWHT template

const int MAXN = 1<<20;

void FWHT(int a[], int l=0, int r=MAXN-1){
    if (l==r)return;

    int mid = (l+r)>>1+1, n = r-l+1;
    FWHT(a,l,mid-1);
    FWHT(a,mid,r);

    for (int i=0; i<(n>>1); i++){
        int a1=a[l+i], a2=a[mid+i];
        a[l+i] = a1+a2;
        a[mid+i] = a1-a2;
    }
}

```

GaussElimination

```

// by bcw_codebook

const int MAXN = 300;
const double EPS = 1e-8;

int n;
double A[MAXN][MAXN];

void Gauss() {
    for(int i = 0; i < n; i++) {
        bool ok = 0;
        for(int j = i; j < n; j++) {
            if(fabs(A[j][i]) > EPS) {
                swap(A[j], A[i]);
                ok = 1;
                break;
            }
        }
        if(!ok) continue;

        double fs = A[i][i];
        for(int j = i+1; j < n; j++) {
            double r = A[j][i] / fs;
            for(int k = i; k < n; k++) {
                A[j][k] -= A[i][k] * r;
            }
        }
    }
}

```

Inverse

```

int inverse[100000];
void invTable(int b, int p) {
    inverse[1] = 1;
    for( int i = 2; i <= b; i++) {
        inverse[i] = (long long)inverse[p%i] * (p-p/i) % p;
    }
}

int inv(int b, int p) {
    return b == 1 ? 1 : ((long long)inv(p % b, p) * (p-p/
        b) % p);
}

```

LinearPrime

```

const int MAXP = 100; //max prime
vector<int> P; // primes
void build_prime(){
    static bitset<MAXP> ok;
    int np=0;
    for (int i=2; i<MAXP; i++){
        if (ok[i]==0)P.push_back(i), np++;
        for (int j=0; j<np && i*P[j]<MAXP; j++){
            ok[ i*P[j] ] = 1;
            if ( i%P[j]==0 )break;
        }
    }
}

```

Miller Rabin

```

typedef long long LL;

inline LL bin_mul(LL a, LL n,const LL& MOD){
    LL re=0;
    while (n>0){
        if (n&1) re += a;
        a += a; if (a>=MOD) a-=MOD;
        n>>=1;
    }
    return re%MOD;
}

inline LL bin_pow(LL a, LL n,const LL& MOD){
    LL re=1;
    while (n>0){
        if (n&1) re = bin_mul(re,a,MOD);
        a = bin_mul(a,a,MOD);
        n>>=1;
    }
    return re;
}

bool is_prime(LL n){
    //static LL sprp[3] = { 2LL, 7LL, 61LL};
    static LL sprp[7] = { 2LL, 325LL, 9375LL,
        28178LL, 450775LL, 9780504LL,
        1795265022LL };
    if (n==1 || (n&1)==0 ) return n==2;
    int u=n-1, t=0;
    while ( (u&1)==0 ) u>>=1, t++;
    for (int i=0; i<3; i++){
        LL x = bin_pow( sprp[i]%n, u, n);
        if (x==0 || x==1 || x==n-1)continue;

        for (int j=1; j<t; j++){
            x=x*x%n;
            if (x==1 || x==n-1)break;
        }
        if (x==n-1)continue;
        return 0;
    }
    return 1;
}

```

Pollard's rho

```
// from PEC
// does not work when n is prime
Int f(Int x, Int mod){
    return add(mul(x, x, mod), 1, mod);
}
Int pollard_rho(Int n) {
    if ( !(n & 1) ) return 2;
    while (true) {
        Int y = 2, x = rand()%(n-1) + 1, res = 1;
        for ( int sz = 2 ; res == 1 ; sz *= 2 ) {
            for ( int i = 0 ; i < sz && res <= 1 ; i++) {
                x = f(x, n);
                res = __gcd(abs(x-y), n);
            }
            y = x;
        }
        if ( res != 0 && res != n ) return res;
    }
}
```

數論基本工具

```
Int POW(Int a, Int n, Int mod){
    Int re=1;
    while (n>0){
        if (n&1LL) re = re*a%mod;
        a = a*a%mod;
        n>>=1;
    }
    return re;
}
Int C(Int n, Int m){
    if (m<0 || m>n) return 0;
    return J[n] * inv(J[m]*J[n-m]%MOD) %MOD;
}
```

Mobius

```
void mobius() {
    fill(isPrime, isPrime + MAXN, 1);
    mu[1] = 1, num = 0;
    for (int i = 2; i < MAXN; ++i) {
        if (isPrime[i]) primes[num++] = i, mu[i] = -1;
        static int d;
        for (int j = 0; j < num && (d = i * primes[j])
            < MAXN; ++j) {
            isPrime[d] = false;
            if (i % primes[j] == 0) {
                mu[d] = 0; break;
            } else mu[d] = -mu[i];
        }
    }
}
```

Simplex

```
// Two-phase simplex algorithm for solving linear
// programs of the form
//
//      maximize      c^T x
//      subject to    Ax <= b
//                   x >= 0
//
// INPUT: A -- an m x n matrix
//        b -- an m-dimensional vector
//        c -- an n-dimensional vector
```

```
//      x -- a vector where the optimal solution will
//           be stored
//
// OUTPUT: value of the optimal solution (infinity if
//        unbounded
//        above, nan if infeasible)
//
// To use this code, create an LPSolver object with A,
// b, and c as
// arguments. Then, call Solve(x).
```

```
#include <iostream>
#include <iomanip>
#include <vector>
#include <cmath>
#include <limits>
```

```
using namespace std;
```

```
typedef long double DOUBLE;
typedef vector<DOUBLE> VD;
typedef vector<VD> VVD;
typedef vector<int> VI;
```

```
const DOUBLE EPS = 1e-9;
```

```
struct LPSolver {
    int m, n;
    VI B, N;
    VVD D;
```

```
LPSolver(const VVD &A, const VD &b, const VD &c) :
    m(b.size()), n(c.size()), N(n + 1), B(m), D(m + 2,
    VD(n + 2)) {
    for (int i = 0; i < m; i++) for (int j = 0; j < n;
    j++) D[i][j] = A[i][j];
    for (int i = 0; i < m; i++) { B[i] = n + i; D[i][n]
    = -1; D[i][n + 1] = b[i]; }
    for (int j = 0; j < n; j++) { N[j] = j; D[m][j] = -
    c[j]; }
    N[n] = -1; D[m + 1][n] = 1;
}
```

```
void Pivot(int r, int s) {
    double inv = 1.0 / D[r][s];
    for (int i = 0; i < m + 2; i++) if (i != r)
        for (int j = 0; j < n + 2; j++) if (j != s)
            D[i][j] -= D[r][j] * D[i][s] * inv;
    for (int j = 0; j < n + 2; j++) if (j != s) D[r][j]
        *= inv;
    for (int i = 0; i < m + 2; i++) if (i != r) D[i][s]
        *= -inv;
    D[r][s] = inv;
    swap(B[r], N[s]);
}
```

```
bool Simplex(int phase) {
    int x = phase == 1 ? m + 1 : m;
    while (true) {
        int s = -1;
        for (int j = 0; j <= n; j++) {
            if (phase == 2 && N[j] == -1) continue;
            if (s == -1 || D[x][j] < D[x][s] || D[x][j] ==
                D[x][s] && N[j] < N[s]) s = j;
        }
        if (D[x][s] > -EPS) return true;
        int r = -1;
        for (int i = 0; i < m; i++) {
            if (D[i][s] < EPS) continue;
            if (r == -1 || D[i][n + 1] / D[i][s] < D[r][n +
                1] / D[r][s] ||
                (D[i][n + 1] / D[i][s]) == (D[r][n + 1] / D[r]
                    [s]) && B[i] < B[r]) r = i;
        }
        if (r == -1) return false;
        Pivot(r, s);
    }
}
```



```

}

DOUBLE Solve(VD &x) {
    int r = 0;
    for (int i = 1; i < m; i++) if (D[i][n + 1] < D[r][n + 1]) r = i;
    if (D[r][n + 1] < -EPS) {
        Pivot(r, n);
        if (!Simplex(1) || D[m + 1][n + 1] < -EPS) return -numeric_limits<DOUBLE>::infinity();
        for (int i = 0; i < m; i++) if (B[i] == -1) {
            int s = -1;
            for (int j = 0; j <= n; j++)
                if (s == -1 || D[i][j] < D[s][j] || D[i][j] == D[s][j] && N[j] < N[s]) s = j;
            Pivot(i, s);
        }
    }
    if (!Simplex(2)) return numeric_limits<DOUBLE>::infinity();
    x = VD(n);
    for (int i = 0; i < m; i++) if (B[i] < n) x[B[i]] = D[i][n + 1];
    return D[m][n + 1];
}

int main() {
    const int m = 4;
    const int n = 3;
    DOUBLE _A[m][n] = {
        { 6, -1, 0 },
        { -1, -5, 0 },
        { 1, 5, 1 },
        { -1, -5, -1 }
    };
    DOUBLE _b[m] = { 10, -4, 5, -5 };
    DOUBLE _c[n] = { 1, -1, 0 };

    VVD A(m);
    VD b(_b, _b + m);
    VD c(_c, _c + n);
    for (int i = 0; i < m; i++) A[i] = VD(_A[i], _A[i] + n);

    LPSolver solver(A, b, c);
    VD x;
    DOUBLE value = solver.Solve(x);

    cerr << "VALUE: " << value << endl; // VALUE: 1.29032
    cerr << "SOLUTION:"; // SOLUTION: 1.74194 0.451613 1
    for (size_t i = 0; i < x.size(); i++) cerr << " " << x[i];
    cerr << endl;
    return 0;
}

```

SG

Anti Nim (取走最後一個石子者敗)

先手必勝 if and only if

- 「所有」堆的石子數都為 1 且遊戲的 SG 值為 0。
- 「有些」堆的石子數大於 1 且遊戲的 SG 值不為 0。

Anti-SG (決策集合為空的遊戲者贏)

定義 SG 值為 0 時，遊戲結束，

則先手必勝 if and only if

- 遊戲中沒有單一遊戲的 SG 函數大於 1 且遊戲的 SG 函數為 0。
- 遊戲中某個單一遊戲的 SG 函數大於 1 且遊戲的 SG 函數不為 0。

Sprague-Grundy

- 雙人、回合制
- 資訊完全公開
- 無隨機因素
- 可在有限步內結束
- 沒有和局
- 雙方可採取的行動相同

SG(S) 的值為 0：後手(P)必勝

不為 0：先手(N)必勝

```

int mex(set S) {
    // find the min number >= 0 that not in the S
    // e.g. S = {0, 1, 3, 4} mex(S) = 2
}

state = []
int SG(A) {
    if (A not in state) {
        S = sub_states(A)
        if (len(S) > 1) state[A] = reduce(operator.xor, [SG(B) for B in S])
        else state[A] = mex(set(SG(B) for B in next_states(A)))
    }
    return state[A]
}

```

Theorem

/*
 Lucas's Theorem
 For non-negative integer n,m and prime P,
 $C(m,n) \bmod P = C(m/M,n/M) * C(m \% M, n \% M) \bmod P$
 $= \text{mult_i} (C(m_i, n_i))$
 where m_i is the i-th digit of m in base P.

Pick's Theorem
 $A = i + b/2 - 1$

Kirchhoff's theorem
 $A_{\{ii\}} = \deg(i), A_{\{ij\}} = (i,j) \in E ? -1 : 0$
 Deleting any one row, one column, and cal the det(A)

Nth Catalan recursive function:
 $C_0 = 1, C_{n+1} = C_n * 2(2n + 1)/(n+2)$

Mobius Formula
 $u(n) = 1$, if $n = 1$
 $(-1)^m$, 若 n 無平方數因數，且 $n = p_1 * p_2 * p_3 * \dots * p_k$
 0 , 若 n 有大於 1 的平方數因數

- Property

- (積性函數) $u(a)u(b) = u(ab)$
- $\sum_{d|n} u(d) = [n == 1]$

Mobius Inversion Formula

if $f(n) = \sum_{d|n} g(d)$
 then $g(n) = \sum_{d|n} u(n/d)f(d)$
 $= \sum_{d|n} u(d)f(n/d)$

- Application

the number/power of gcd(i, j) = k

- Trick

分塊, $O(\sqrt{n})$

Chinese Remainder Theorem (m_i 兩兩互質)

```

x = a_1 (mod m_1)
x = a_2 (mod m_2)
....
x = a_i (mod m_i)

```


construct a solution:

```

Let  $M = m_1 * m_2 * m_3 * \dots * m_n$ 
Let  $M_i = M / m_i$ 

 $t_i = 1 / M_i$ 
 $t_i * M_i = 1 \pmod{m_i}$ 

solution  $x = a_1 * t_1 * M_1 + a_2 * t_2 * M_2 + \dots$ 
 $+ a_n * t_n * M_n + k * M$ 
 $= k * M + \sum a_i * t_i * M_i$ ,  $k$  is positive integer.

under mod  $M$ , there is one solution  $x = \sum a_i * t_i * M_i$ 
-----
Burnside's lemma
 $|G| * |X/G| = \sum (|X^g|)$  where  $g$  in  $G$ 
總方法數：每一種旋轉下不動點的個數總和 除以 旋轉的方法數
*/

```

Graph

BCC

邊雙連通

任意兩點間至少有兩條不重疊的路徑連接，找法：

1. 標記出所有的橋
2. 對全圖進行 DFS，不走橋，每一次 DFS 就是一個新的邊雙連通

// from BCW

```

struct BccEdge {
    static const int MXN = 100005;
    struct Edge { int v, eid; };
    int n, m, step, par[MXN], dfn[MXN], low[MXN];
    vector<Edge> E[MXN];
    DisjointSet djs;
    void init(int _n) {
        n = _n; m = 0;
        for (int i=0; i<n; i++) E[i].clear();
        djs.init(n);
    }
    void add_edge(int u, int v) {
        E[u].PB({v, m});
        E[v].PB({u, m});
        m++;
    }
    void DFS(int u, int f, int f_eid) {
        par[u] = f;
        dfn[u] = low[u] = step++;
        for (auto it:E[u]) {
            if (it.eid == f_eid) continue;
            int v = it.v;
            if (dfn[v] == -1) {
                DFS(v, u, it.eid);
                low[u] = min(low[u], low[v]);
            } else {
                low[u] = min(low[u], dfn[v]);
            }
        }
    }
}

void solve() {
    step = 0;
    memset(dfn, -1, sizeof(int)*n);
    for (int i=0; i<n; i++) {
        if (dfn[i] == -1) DFS(i, i, -1);
    }
    djs.init(n);
    for (int i=0; i<n; i++) {
        if (low[i] < dfn[i]) djs.uni(i, par[i]);
    }
}

```

```

    }
}
}graph;

```

Dijkstra

```

typedef struct Edge{
    int v; long long len;
    bool operator > (const Edge &b) const { return len>b.len; }
} State;

const long long INF = 1LL<<60;

void Dijkstra(int n, vector<Edge> G[], long long d[],
    int s, int t=-1){
    static priority_queue<State, vector<State>, greater<State>> pq;
    while ( pq.size() )pq.pop();
    for (int i=1; i<=n; i++)d[i]=INF;
    d[s]=0; pq.push( (State){s,d[s]} );
    while ( pq.size() ){
        auto x = pq.top(); pq.pop();
        int u = x.v;
        if (d[u]<x.len)continue;
        if (u==t)return;
        for (auto &e:G[u]){
            if (d[e.v] > d[u]+e.len){
                d[e.v] = d[u]+e.len;
                pq.push( (State){e.v,d[e.v]} );
            }
        }
    }
}

```

Theorm - Domination

```

Maximum Independent Set
General: [NPC] maximum clique of complement of G
Tree: [P] Greedy
Bipartite Graph: [P] Maximum Cardinality Bipartite Matching
-----
Minimum Dominating Set
General: [NPC]
Tree: [P] DP
Bipartite Graph: [NPC]
-----
Minimum Vertex Cover
General: [NPC] (?)maximum clique of complement of G
Tree: [P] Greedy, from leaf to root
Bipartite Graph: [P] Maximum Cardinality Bipartite Matching
-----
Minimum Edge Cover
General: [P] V - Maximum Matching
Bipartite Graph: [P] Greedy, strategy: cover small degree node first.
(Min/Max)Weighted: [P]: Minimum/Minimum Weight Matching

```

Strongly Connected Component(SCC)

DominatorTree

```

// PEC VER

// idom[n] is the unique node that strictly dominates n
// but does
// not strictly dominate any other node that strictly
// dominates n.

```

```
// idom[n] = 0 if n is entry or the entry cannot reach
// n.
struct DominatorTree{
    static const int MAXN = 200010;
    int n,s;
    vector<int> g[MAXN],pred[MAXN];
    vector<int> cov[MAXN];
    int dfn[MAXN],nfd[MAXN],ts;
    int par[MAXN];
    int sdom[MAXN],idom[MAXN];
    int mom[MAXN],mn[MAXN];

    inline bool cmp(int u,int v) { return dfn[u] < dfn[v]
    }; }

    int eval(int u) {
        if(mom[u] == u) return u;
        int res = eval(mom[u]);
        if(cmp(sdom[mn[mom[u]]],sdom[mn[u]]))
            mn[u] = mn[mom[u]];
        return mom[u] = res;
    }

    void init(int _n, int _s) {
        n = _n;
        s = _s;
        REP1(i,1,n) {
            g[i].clear();
            pred[i].clear();
            idom[i] = 0;
        }
    }

    void add_edge(int u, int v) {
        g[u].push_back(v);
        pred[v].push_back(u);
    }

    void DFS(int u) {
        ts++;
        dfn[u] = ts;
        nfd[ts] = u;
        for(int v:g[u]) if(dfn[v] == 0) {
            par[v] = u;
            DFS(v);
        }
    }

    void build() {
        ts = 0;
        REP1(i,1,n) {
            dfn[i] = nfd[i] = 0;
            cov[i].clear();
            mom[i] = mn[i] = sdom[i] = i;
        }
        DFS(s);
        for (int i=ts; i>=2; i--) {
            int u = nfd[i];
            if(u == 0) continue;
            for(int v:pred[u]) if(dfn[v]) {
                eval(v);
                if(cmp(sdom[mn[v]],sdom[u])) sdom[u] = sdom[mn[v]];
            }
            cov[sdom[u]].push_back(u);
            mom[u] = par[u];
            for(int w:cov[par[u]]) {
                eval(w);
                if(cmp(sdom[mn[w]],par[u])) idom[w] = mn[w];
                else idom[w] = par[u];
            }
            cov[par[u]].clear();
        }
        REP1(i,2,ts) {
            int u = nfd[i];
            if(u == 0) continue;
            if(idom[u] != sdom[u]) idom[u] = idom[idom[u]];
        }
    }
}dom;
```

```
#define MXN 100005
#define PB push_back
#define FZ(s) memset(s,0,sizeof(s))

struct Scc{
    int n, nScc, vst[MXN], bln[MXN];
    vector<int> E[MXN], rE[MXN], vec;
    void init(int _n){
        n = _n;
        for (int i=0; i<MXN; i++){
            E[i].clear();
            rE[i].clear();
        }
    }
    void add_edge(int u, int v){
        E[u].PB(v);
        rE[v].PB(u);
    }
    void DFS(int u){
        vst[u]=1;
        for (auto v : E[u])
            if (!vst[v]) DFS(v);
        vec.PB(u);
    }
    void rDFS(int u){
        vst[u] = 1;
        bln[u] = nScc;
        for (auto v : rE[u])
            if (!vst[v]) rDFS(v);
    }
    void solve(){
        nScc = 0;
        vec.clear();
        FZ(vst);
        for (int i=0; i<n; i++)
            if (!vst[i]) DFS(i);
        reverse(vec.begin(),vec.end());
        FZ(vst);
        for (auto v : vec){
            if (!vst[v]){
                rDFS(v);
                nScc++;
            }
        }
    }
};
```

Manhattan MST

```
#include <bits/stdc++.h>
using namespace std;

const int MAXN = 100005;
const int OFFSET = 2000; // y-x may < 0, offset it, if
// y-x too large, please write a unique function
const int INF = 0xFFFFFFFF;
int n;
int x[MAXN], y[MAXN], p[MAXN];

typedef pair<int, int> pii;
pii bit[MAXN]; // [ val, pos ]

struct P {
    int x, y, id;
    bool operator<(const P&b) const {
        if ( x == b.x ) return y > b.y;
        else return x > b.x;
    }
};
vector<P> op;

struct E {
    int x, y, cost;
    bool operator<(const E&b) const {
        return cost < b.cost;
    }
};
```

```

};
vector<E> edges;

int find(int x) {
    return p[x] == x ? x : p[x] = find(p[x]);
}

void update(int i, int v, int p) {
    while ( i ) {
        if ( bit[i].first > v ) bit[i] = {v, p};
        i -= i & (-i);
    }
}

pii query(int i) {
    pii res = {INF, INF};
    while ( i < MAXN ) {
        if ( bit[i].first < res.first ) res = {bit[i].first, bit[i].second};
        i += i & (-i);
    }
    return res;
}

void input() {
    cin >> n;
    for ( int i = 0 ; i < n ; i++ ) cin >> x[i] >> y[i]
        , op.push_back((P) {x[i], y[i], i});
}

void mst() {
    for ( int i = 0 ; i < MAXN ; i++ ) p[i] = i;
    int res = 0;
    sort(edges.begin(), edges.end());
    for ( auto e : edges ) {
        int x = find(e.x), y = find(e.y);
        if ( x != y ) {
            p[x] = y;
            res += e.cost;
        }
    }
    cout << res << endl;
}

void construct() {
    sort(op.begin(), op.end());
    for ( int i = 0 ; i < n ; i++ ) {
        pii q = query(op[i].y - op[i].x + OFFSET);
        update(op[i].y - op[i].x + OFFSET, op[i].x + op[i].y, op[i].id);
        if ( q.first == INF ) continue;
        edges.push_back((E) {op[i].id, q.second, abs(x[op[i].id]-x[q.second]) + abs(y[op[i].id]-y[q.second]) }));
    }
}

void solve() {
    // [-45 ~ 0 deg]
    for ( int i = 0 ; i < MAXN ; i++ ) bit[i] = {INF, INF};
    construct();

    // [0 ~ 45 deg]
    for ( int i = 0 ; i < MAXN ; i++ ) bit[i] = {INF, INF};
    for ( int i = 0 ; i < n ; i++ ) swap(op[i].x, op[i].y);
    construct();
    for ( int i = 0 ; i < n ; i++ ) swap(op[i].x, op[i].y);

    // [-90 ~ -45 deg]
    for ( int i = 0 ; i < MAXN ; i++ ) bit[i] = {INF, INF};
    for ( int i = 0 ; i < n ; i++ ) op[i].y *= -1;

```

```

construct();

// [-45 ~ 0 deg]
for ( int i = 0 ; i < MAXN ; i++ ) bit[i] = {INF, INF};
for ( int i = 0 ; i < n ; i++ ) swap(op[i].x, op[i].y);
construct();

// mst
mst();
}

int main () {
    input();
    solve();
    return 0;
}

```

Hungarian

// Maximum Cardinality Bipartite Matching

```

struct Graph {
    static const int MAXN = 5005;
    vector<int> G[MAXN];
    int n;
    int match[MAXN]; // Matching Result
    int vis[MAXN];

    void init(int _n) {
        n = _n;
        for ( int i = 0 ; i < n ; i++ ) G[i].clear();
    }

    bool dfs(int u) {
        for ( auto v:G[u] ) {
            if (!vis[v]) {
                vis[v] = true;
                if (match[v] == -1 || dfs(match[v])) {
                    match[v] = u;
                    match[u] = v;
                    return true;
                }
            }
        }
        return false;
    }

    int solve() {
        int res = 0;
        memset(match, -1, sizeof(match));
        for (int i = 0; i < n; i++) {
            if (match[i] == -1) {
                memset(vis, 0, sizeof(vis));
                if (dfs(i)) res += 1;
            }
        }
        return res;
    }
} graph;

```

KM

Detect non-perfect-matching:
 1. set all edge[i][j] as INF
 2. if solve() >= INF, it is not perfectmatching.

 // Maximum Weight Perfect Bipartite Matching
 // allow negative weight!

typedef long long Int;

```

struct KM {
    static const int MAXN = 1050;
    static const int INF = 1LL<<60;
    int n, match[MAXN], vx[MAXN], vy[MAXN];
    Int edge[MAXN][MAXN], lx[MAXN], ly[MAXN], slack[
        MAXN];
    void init(int _n){
        n = _n;
        for ( int i = 0 ; i < n ; i++ )
            for ( int j = 0; j < n ; j++ )
                edge[i][j] = 0;
    }
    void add_edge(int x, int y, Int w){
        edge[x][y] = w;
    }
    bool DFS(int x){
        vx[x] = 1;
        for ( int y = 0 ; y < n ; y++ ) {
            if ( vy[y] ) continue;
            if ( lx[x] + ly[y] > edge[x][y] ) {
                slack[y] = min(slack[y], lx[x] + ly[y]
                    - edge[x][y]);
            } else {
                vy[y] = 1;
                if ( match[y] == -1 || DFS(match[y]) ) {
                    match[y] = x;
                    return true;
                }
            }
        }
        return false;
    }
    Int solve() {
        fill(match, match + n, -1);
        fill(lx, lx + n, -INF);
        fill(ly, ly + n, 0);
        for ( int i = 0; i < n; i++ )
            for ( int j = 0; j < n; j++ )
                lx[i] = max(lx[i], edge[i][j]);
        for ( int i = 0 ; i < n; i++ ) {
            fill(slack, slack + n, INF);
            while (true){
                fill(vx, vx + n, 0);
                fill(vy, vy + n, 0);
                if ( DFS(i) ) break;
                Int d = INF;
                for ( int j = 0 ; j < n ; j++ )
                    if ( !vy[j] ) d = min(d, slack[j]);
                for ( int j = 0 ; j < n ; j++ ) {
                    if ( vx[j] ) lx[j] -= d;
                    if ( vy[j] ) ly[j] += d;
                    else slack[j] -= d;
                }
            }
        }
        Int res = 0;
        for ( int i = 0 ; i < n ; i++ ) {
            res += edge[ match[i] ][i];
        }
        return res;
    }
} graph;

```

Theorm - Matching

最大匹配 + 最小邊覆蓋 = V

最大獨立集 + 最小點覆蓋 = V

最大匹配 = 最小點覆蓋

最小路徑覆蓋數 = V - 最大匹配數

Maximum General Matching

// Maximum Cardinality Matching

```

struct Graph {
    vector<int> G[MAXN];
    int pa[MAXN], match[MAXN], st[MAXN], S[MAXN], vis[
        MAXN];
    int t, n;

    void init(int _n) {
        n = _n;
        for ( int i = 1 ; i <= n ; i++ ) G[i].clear();
    }
    void add_edge(int u, int v) {
        G[u].push_back(v);
        G[v].push_back(u);
    }
    int lca(int u, int v){
        for ( ++t ; ; swap(u, v) ) {
            if ( u == 0 ) continue;
            if ( vis[u] == t ) return u;
            vis[u] = t;
            u = st[ pa[ match[u] ] ];
        }
    }
    void flower(int u, int v, int l, queue<int> &q) {
        while ( st[u] != 1 ) {
            pa[u] = v;
            if ( S[ v = match[u] ] == 1 ) {
                q.push(v);
                S[v] = 0;
            }
            st[u] = st[v] = 1;
            u = pa[v];
        }
    }
    bool bfs(int u){
        for ( int i = 1 ; i <= n ; i++ ) st[i] = i;
        memset(S, -1, sizeof(S));
        queue<int> q;
        q.push(u);
        S[u] = 0;
        while ( !q.empty() ) {
            u = q.front(); q.pop();
            for ( int i = 0 ; i < (int)G[u].size(); i++ ) {
                int v = G[u][i];
                if ( S[v] == -1 ) {
                    pa[v] = u;
                    S[v] = 1;
                    if ( !match[v] ) {
                        for ( int lst ; u ; v = lst, u = pa[v] ) {
                            lst = match[u];
                            match[u] = v;
                            match[v] = u;
                        }
                        return 1;
                    }
                    q.push(match[v]);
                    S[ match[v] ] = 0;
                } else if ( !S[v] && st[v] != st[u] ) {
                    int l = lca(st[v], st[u]);
                    flower(v, u, l, q);
                    flower(u, v, l, q);
                }
            }
        }
        return 0;
    }
    int solve(){
        memset(pa, 0, sizeof(pa));
        memset(match, 0, sizeof(match));
        int ans = 0;
        for ( int i = 1 ; i <= n ; i++ )
            if ( !match[i] && bfs(i) ) ans++;
        return ans;
    }
} graph;

```

Minimum General Weighted Matching

```
// Minimum Weight Perfect Matching (Perfect Match)

struct Graph {
    static const int MAXN = 105;
    int n, e[MAXN][MAXN];
    int match[MAXN], d[MAXN], onstk[MAXN];
    vector<int> stk;
    void init(int _n) {
        n = _n;
        for( int i = 0 ; i < n ; i ++ )
            for( int j = 0 ; j < n ; j ++ )
                e[i][j] = 0;
    }
    void add_edge(int u, int v, int w) {
        e[u][v] = e[v][u] = w;
    }
    bool SPFA(int u){
        if (onstk[u]) return true;
        stk.push_back(u);
        onstk[u] = 1;
        for ( int v = 0 ; v < n ; v++ ) {
            if (u != v && match[u] != v && !onstk[v] )
            {
                int m = match[v];
                if ( d[m] > d[u] - e[v][m] + e[u][v] )
                {
                    d[m] = d[u] - e[v][m] + e[u][v];
                    onstk[v] = 1;
                    stk.push_back(v);
                    if (SPFA(m)) return true;
                    stk.pop_back();
                    onstk[v] = 0;
                }
            }
        }
        onstk[u] = 0;
        stk.pop_back();
        return false;
    }
    int solve() {
        for ( int i = 0 ; i < n ; i += 2 ) {
            match[i] = i+1;
            match[i+1] = i;
        }
        while (true){
            int found = 0;
            for ( int i = 0 ; i < n ; i++ )
                onstk[ i ] = d[ i ] = 0;
            for ( int i = 0 ; i < n ; i++ ) {
                stk.clear();
                if ( !onstk[i] && SPFA(i) ) {
                    found = 1;
                    while ( stk.size() >= 2 ) {
                        int u = stk.back(); stk.
                            pop_back();
                        int v = stk.back(); stk.
                            pop_back();
                        match[u] = v;
                        match[v] = u;
                    }
                }
            }
            if (!found) break;
        }
        int ret = 0;
        for ( int i = 0 ; i < n ; i++ )
            ret += e[i][match[i]];
        ret /= 2;
        return ret;
    }
} graph;
```

Maximum Clique

```
const int MAXN = 105;
int best;
int m, n;
int num[MAXN];
// int x[MAXN];
int path[MAXN];
int g[MAXN][MAXN];

bool dfs( int *adj, int total, int cnt ){
    int i, j, k;
    int t[MAXN];
    if( total == 0 ){
        if( best < cnt ){
            // for( i = 0; i < cnt; i++) path[i] = x[i];
            best = cnt; return true;
        }
        return false;
    }
    for( i = 0; i < total; i++){
        if( cnt+(total-i) <= best ) return false;
        if( cnt+num[adj[i]] <= best ) return false;
        // x[cnt] = adj[i];
        for( k = 0, j = i+1; j < total; j++ )
            if( g[ adj[i] ][ adj[j] ] )
                t[ k++ ] = adj[j];
        if( dfs( t, k, cnt+1 ) ) return true;
    }
    return false;
}

int MaximumClique(){
    int i, j, k;
    int adj[MAXN];
    if( n <= 0 ) return 0;
    best = 0;
    for( i = n-1; i >= 0; i-- ){
        // x[0] = i;
        for( k = 0, j = i+1; j < n; j++ )
            if( g[i][j] ) adj[k++] = j;
        dfs( adj, k, 1 );
        num[i] = best;
    }
    return best;
}
```

Steiner Tree

```
// Minimum Steiner Tree
//  $O(V^3 T + V^2 2^T)$ 
struct SteinerTree{
#define V 33
#define T 8
#define INF 1023456789
    int n, dst[V][V], dp[1 << T][V], tdst[V];
    void init( int _n ){
        n = _n;
        for( int i = 0 ; i < n ; i ++ ){
            for( int j = 0 ; j < n ; j ++ )
                dst[ i ][ j ] = INF;
            dst[ i ][ i ] = 0;
        }
    }
    void add_edge( int ui, int vi, int wi ){
        dst[ ui ][ vi ] = min( dst[ ui ][ vi ], wi );
        dst[ vi ][ ui ] = min( dst[ vi ][ ui ], wi );
    }
    void shortest_path(){
        for( int k = 0 ; k < n ; k ++ )
            for( int i = 0 ; i < n ; i ++ )
                for( int j = 0 ; j < n ; j ++ )
                    dst[ i ][ j ] = min( dst[ i ][ j ],
                        dst[ i ][ k ] + dst[ k ][ j ] );
    }
    int solve( const vector<int>& ter ){
        int t = (int)ter.size();
        for( int i = 0 ; i < ( 1 << t ) ; i ++ )
            for( int j = 0 ; j < n ; j ++ )
```

```

    dp[ i ][ j ] = INF;
    for( int i = 0 ; i < n ; i ++ )
        dp[ 0 ][ i ] = 0;
    for( int msk = 1 ; msk < ( 1 << t ) ; msk ++ ){
        if( msk == ( msk & (-msk) ) ){
            int who = __lg( msk );
            for( int i = 0 ; i < n ; i ++ )
                dp[ msk ][ i ] = dst[ ter[ who ] ][ i ];
            continue;
        }
        for( int i = 0 ; i < n ; i ++ )
            for( int submsk = ( msk - 1 ) & msk ; submsk ;
                submsk = ( submsk - 1 ) & msk )
                dp[ msk ][ i ] = min( dp[ msk ][ i ],
                    dp[ submsk ][ i ] +
                    dp[ msk ^ submsk ][ i ] );
        for( int i = 0 ; i < n ; i ++ ){
            tdst[ i ] = INF;
            for( int j = 0 ; j < n ; j ++ )
                tdst[ i ] = min( tdst[ i ],
                    dp[ msk ][ j ] + dst[ j ][ i ] );
        }
        for( int i = 0 ; i < n ; i ++ )
            dp[ msk ][ i ] = tdst[ i ];
    }
    int ans = INF;
    for( int i = 0 ; i < n ; i ++ )
        ans = min( ans , dp[ ( 1 << t ) - 1 ][ i ] );
    return ans;
}
} solver;

```

最小平均環

```

// from BCW

/* minimum mean cycle */
const int MAXE = 1805;
const int MAXN = 35;
const double inf = 1029384756;
const double eps = 1e-6;
struct Edge {
    int v,u;
    double c;
};
int n,m,prv[MAXN][MAXN], prve[MAXN][MAXN], vst[MAXN];
Edge e[MAXE];
vector<int> edgeID, cycle, rho;
double d[MAXN][MAXN];
inline void bellman_ford() {
    for(int i=0; i<n; i++) d[0][i]=0;
    for(int i=0; i<n; i++) {
        fill(d[i+1], d[i+1]+n, inf);
        for(int j=0; j<m; j++) {
            int v = e[j].v, u = e[j].u;
            if(d[i][v]<inf && d[i+1][u]>d[i][v]+e[j].c) {
                d[i+1][u] = d[i][v]+e[j].c;
                prv[i+1][u] = v;
                prve[i+1][u] = j;
            }
        }
    }
}
double karp_mmc() {
    // returns inf if no cycle, mmc otherwise
    double mmc=inf;
    int st = -1;
    bellman_ford();
    for(int i=0; i<n; i++) {
        double avg=-inf;
        for(int k=0; k<n; k++) {
            if(d[n][i]<inf-eps) avg=max(avg,(d[n][i]-d[k][i])/(n-k));
            else avg=max(avg,inf);
        }
        if (avg < mmc) tie(mmc, st) = tie(avg, i);
    }
}

```

```

}
for(int i=0; i<n; i++) vst[i] = 0;
edgeID.clear(); cycle.clear(); rho.clear();
for (int i=n; !vst[st]; st=prv[i--][st]) {
    vst[st]++;
    edgeID.PB(prve[i][st]);
    rho.PB(st);
}
while (vst[st] != 2) {
    int v = rho.back(); rho.pop_back();
    cycle.PB(v);
    vst[v]++;
}
reverse(ALL(edgeID));
edgeID.resize(SZ(cycle));
return mmc;
}

```

SchreierSims

```

// time:  $O(n^2 \lg^3 |G| + t n \lg |G|)$ 
// mem :  $O(n^2 \lg |G| + tn)$ 
// t : number of generator
namespace SchreierSimsAlgorithm{
    typedef vector<int> Permu;
    Permu inv( const Permu& p ){
        Permu ret( p.size() );
        for( int i = 0 ; i < (int)p.size(); i ++ )
            ret[ p[ i ] ] = i;
        return ret;
    }
    Permu operator*( const Permu& a, const Permu& b ){
        Permu ret( a.size() );
        for( int i = 0 ; i < (int)a.size(); i ++ )
            ret[ i ] = b[ a[ i ] ];
        return ret;
    }
    typedef vector<Permu> Bucket;
    typedef vector<int> Table;
    typedef pair<int,int> pii;
    int n, m;
    vector<Bucket> bkts, bktsInv;
    vector<Table> lookup;
    int fastFilter( const Permu &g, bool addToG = 1 ){
        n = bkts.size();
        Permu p;
        for( int i = 0 ; i < n ; i ++ ){
            int res = lookup[ i ][ p[ i ] ];
            if( res == -1 ){
                if( addToG ){
                    bkts[ i ].push_back( p );
                    bktsInv[ i ].push_back( inv( p ) );
                    lookup[ i ][ p[i] ] = (int)bkts[i].size()-1;
                }
                return i;
            }
            p = p * bktsInv[i][res];
        }
        return -1;
    }
    long long calcTotalSize(){
        long long ret = 1;
        for( int i = 0 ; i < n ; i ++ )
            ret *= bkts[i].size();
        return ret;
    }
    bool inGroup( const Permu &g ){
        return fastFilter( g, false ) == -1;
    }
    void solve( const Bucket &gen, int _n ){
        n = _n, m = gen.size(); // m perm[0..n-1]s
        //clear all
        bkts.clear();
        bktsInv.clear();
        lookup.clear();
    }
}

```

```

for(int i = 0 ; i < n ; i ++ ){
    lookup[i].resize(n);
    fill(lookup[i].begin(), lookup[i].end(), -1);
}
Permu id( n );
for(int i = 0 ; i < n ; i ++ ) id[i] = i;
for(int i = 0 ; i < n ; i ++ ){
    bkts[i].push_back(id);
    bktsInv[i].push_back(id);
    lookup[i][i] = 0;
}
for(int i = 0 ; i < m ; i ++ )
    fastFilter( gen[i] );
queue< pair<pii,pii> > toUpd;
for(int i = 0; i < n; i ++ )
    for(int j = i; j < n; j ++ )
        for(int k = 0; k < (int)bkts[i].size(); k ++ )
            for(int l = 0; l < (int)bkts[j].size(); l ++ )
                toUpd.push( {pii(i,k), pii(j,l)} );
while( !toUpd.empty() ){
    pii a = toUpd.front().first;
    pii b = toUpd.front().second;
    toUpd.pop();
    int res = fastFilter(bkts[a.first][a.second] *
                        bkts[b.first][b.second]);
    if(res == -1) continue;
    pii newPair(res, (int)bkts[res].size() - 1);
    for(int i = 0; i < n; i ++ )
        for(int j = 0; j < (int)bkts[i].size(); ++j){
            if(i <= res)
                toUpd.push(make_pair(pii(i , j), newPair));
            if(res <= i)
                toUpd.push(make_pair(newPair, pii(i, j)));
        }
    }
}
}
}
}

```

Tarjan

割點

點 u 為割點 **if and only if** 滿足 1. or 2.

1. u 為樹根，且 u 有多於一個子樹。
2. u 不為樹根，且滿足存在 (u,v) 為樹枝邊（或稱父子邊，即 u 為 v 在搜索樹中的父親），使得 $DFN(u) \leq Low(v)$ 。

橋

一條無向邊 (u,v) 是橋 **if and only if** (u,v) 為樹枝邊，且滿足 $DFN(u) < Low(v)$ 。

// 0 base

```

struct TarjanSCC{
    static const int MAXN = 1000006;
    int n, dfn[MAXN], low[MAXN], scc[MAXN], scn, count;
    vector<int> G[MAXN];
    stack<int> stk;
    bool ins[MAXN];

    void tarjan(int u){
        dfn[u] = low[u] = ++count;
        stk.push(u);
        ins[u] = true;

        for(auto v:G[u]){
            if(!dfn[v]){
                tarjan(v);
                low[u] = min(low[u], low[v]);
            }else if(ins[v]){
                low[u] = min(low[u], dfn[v]);
            }
        }

        if(dfn[u] == low[u]){

```

```

int v;
do {
    v = stk.top();
    stk.pop();
    scc[v] = scn;
    ins[v] = false;
} while(v != u);
scn++;
}
}

void getSCC(){
    memset(dfn,0,sizeof(dfn));
    memset(low,0,sizeof(low));
    memset(ins,0,sizeof(ins));
    memset(scc,0,sizeof(scc));
    count = scn = 0;
    for(int i = 0 ; i < n ; i ++ ){
        if(!dfn[i]) tarjan(i);
    }
}
}SCC;

```

SchreierSims.cpp

2-SAT

```

const int MAXN = 2020;

struct TwoSAT{
    static const int MAXv = 2*MAXN;
    vector<int> GO[MAXv],BK[MAXv],stk;
    bool vis[MAXv];
    int SC[MAXv];

    void imply(int u,int v){ // u imply v
        GO[u].push_back(v);
        BK[v].push_back(u);
    }

    int dfs(int u,vector<int>*G,int sc){
        vis[u]=1, SC[u]=sc;
        for (int v:G[u])if (!vis[v])
            dfs(v,G,sc);
        if (G==GO)stk.push_back(u);
    }

    int scc(int n=MAXv){
        memset(vis,0,sizeof(vis));
        for (int i=0; i<n; i++)if (!vis[i])
            dfs(i,GO,-1);
        memset(vis,0,sizeof(vis));
        int sc=0;
        while (!stk.empty()){
            if (!vis[stk.back()])
                dfs(stk.back(),BK,sc++);
            stk.pop_back();
        }
    }
}SAT;

int main(){
    SAT.scc(2*n);
    bool ok=1;
    for (int i=0; i<n; i++){
        if (SAT.SC[2*i]==SAT.SC[2*i+1])ok=0;
    }
    if (ok){
        for (int i=0; i<n; i++){
            if (SAT.SC[2*i]>SAT.SC[2*i+1]){
                cout << i << endl;
            }
        }
    }
    else puts("NO");
}

```


Data Structure

2D Range Tree

```
// remember sort x !!!!!
typedef int T;
const int LGN = 20;
const int MAXN = 100005;

struct Point{
    T x, y;
    friend bool operator < (Point a, Point b){
        return tie(a.x,a.y) < tie(b.x,b.y);
    }
};
struct TREE{
    Point pt;
    int toleft;
}tree[LGN][MAXN];
struct SEG{
    T mx, Mx;
    int sz;
    TREE *st;
}seg[MAXN*4];

vector<Point> P;

void build(int l, int r, int o, int deep){
    seg[o].mx = P[l].x;
    seg[o].Mx = P[r].x;
    seg[o].sz = r-l+1;

    if(l == r){
        tree[deep][r].pt = P[r];
        tree[deep][r].toleft = 0;
        seg[o].st = &tree[deep][r];
        return;
    }
    int mid = (l+r)>>1;
    build(l,mid,o+o,deep+1);
    build(mid+1,r,o+o+1,deep+1);

    TREE *ptr = &tree[deep][l];
    TREE *pl = &tree[deep+1][l], *nl = &tree[deep+1][mid+1];
    TREE *pr = &tree[deep+1][mid+1], *nr = &tree[deep+1][r+1];

    int cnt = 0;
    while(pl != nl && pr != nr) {
        *(ptr) = pl->pt.y <= pr->pt.y ? cnt++, *(pl++):
            *(pr++);
        ptr -> toleft = cnt; ptr++;
    }
    while(pl != nl) *(ptr) = *(pl++), ptr -> toleft = ++cnt, ptr++;
    while(pr != nr) *(ptr) = *(pr++), ptr -> toleft = cnt, ptr++;
}

int main(){
    int n; cin >> n;
    for(int i = 0 ; i < n; i++){
        T x,y; cin >> x >> y;
        P.push_back((Point){x,y});
    }
    sort(P.begin(),P.end());
    build(0,n-1,1,0);
}
```

ext heap

```
#include <bits/extc++.h>
typedef __gnu_pbds::priority_queue<int> heap_t;
```

```
heap_t a,b;

int main() {
    a.clear();
    b.clear();
    a.push(1);
    a.push(3);
    b.push(2);
    b.push(4);
    assert(a.top() == 3);
    assert(b.top() == 4);
    // merge two heap
    a.join(b);
    assert(a.top() == 4);
    assert(b.empty());

    return 0;
}
```

KD tree

```
// from BCW

const int MXN = 100005;

struct KDTree {
    struct Node {
        int x,y,x1,y1,x2,y2;
        int id,f;
        Node *L,*R;
    }tree[MXN];
    int n;
    Node *root;

    long long dis2(int x1, int y1, int x2, int y2) {
        long long dx = x1-x2;
        long long dy = y1-y2;
        return dx*dx+dy*dy;
    }
    static bool cmpx(Node& a, Node& b){ return a.x<b.x; }
    static bool cmpy(Node& a, Node& b){ return a.y<b.y; }
    void init(vector<pair<int,int>> ip) {
        n = ip.size();
        for (int i=0; i<n; i++) {
            tree[i].id = i;
            tree[i].x = ip[i].first;
            tree[i].y = ip[i].second;
        }
        root = build_tree(0, n-1, 0);
    }
    Node* build_tree(int L, int R, int dep) {
        if (L>R) return nullptr;
        int M = (L+R)/2;
        tree[M].f = dep%2;
        nth_element(tree+L, tree+M, tree+R+1, tree[M].f ?
            cmpy : cmpx);
        tree[M].x1 = tree[M].x2 = tree[M].x;
        tree[M].y1 = tree[M].y2 = tree[M].y;

        tree[M].L = build_tree(L, M-1, dep+1);
        if (tree[M].L) {
            tree[M].x1 = min(tree[M].x1, tree[M].L->x1);
            tree[M].x2 = max(tree[M].x2, tree[M].L->x2);
            tree[M].y1 = min(tree[M].y1, tree[M].L->y1);
            tree[M].y2 = max(tree[M].y2, tree[M].L->y2);
        }

        tree[M].R = build_tree(M+1, R, dep+1);
        if (tree[M].R) {
            tree[M].x1 = min(tree[M].x1, tree[M].R->x1);
            tree[M].x2 = max(tree[M].x2, tree[M].R->x2);
            tree[M].y1 = min(tree[M].y1, tree[M].R->y1);
            tree[M].y2 = max(tree[M].y2, tree[M].R->y2);
        }

        return tree+M;
    }
}
```

```

}
int touch(Node* r, int x, int y, long long d2){
    long long dis = sqrt(d2)+1;
    if (x<r->x1-dis || x>r->x2+dis || y<r->y1-dis || y>
        r->y2+dis)
        return 0;
    return 1;
}
void nearest(Node* r, int x, int y, int &mID, long
    long &md2) {
    if (!r || !touch(r, x, y, md2)) return;
    long long d2 = dis2(r->x, r->y, x, y);
    if (d2 < md2 || (d2 == md2 && mID < r->id)) {
        mID = r->id;
        md2 = d2;
    }
    // search order depends on split dim
    if ((r->f == 0 && x < r->x) ||
        (r->f == 1 && y < r->y)) {
        nearest(r->L, x, y, mID, md2);
        nearest(r->R, x, y, mID, md2);
    } else {
        nearest(r->R, x, y, mID, md2);
        nearest(r->L, x, y, mID, md2);
    }
}
int query(int x, int y) {
    int id = 1029384756;
    long long d2 = 102938475612345678LL;
    nearest(root, x, y, id, d2);
    return id;
}
}tree;

```

Link Cut tree

// from bcw codebook

```

const int MXN = 100005;
const int MEM = 100005;

struct Splay {
    static Splay nil, mem[MEM], *pmem;
    Splay *ch[2], *f;
    int val, rev, size;
    Splay () : val(-1), rev(0), size(0) {
        f = ch[0] = ch[1] = &nil;
    }
    Splay (int _val) : val(_val), rev(0), size(1) {
        f = ch[0] = ch[1] = &nil;
    }
    bool isr() {
        return f->ch[0] != this && f->ch[1] != this;
    }
    int dir() {
        return f->ch[0] == this ? 0 : 1;
    }
    void setCh(Splay *c, int d) {
        ch[d] = c;
        if (c != &nil) c->f = this;
        pull();
    }
    void push() {
        if (rev) {
            swap(ch[0], ch[1]);
            if (ch[0] != &nil) ch[0]->rev ^= 1;
            if (ch[1] != &nil) ch[1]->rev ^= 1;
            rev=0;
        }
    }
    void pull() {
        size = ch[0]->size + ch[1]->size + 1;
        if (ch[0] != &nil) ch[0]->f = this;
        if (ch[1] != &nil) ch[1]->f = this;
    }
}

```

```

} Splay::nil, Splay::mem[MEM], *Splay::pmem = Splay::
    mem;
Splay *nil = &Splay::nil;

void rotate(Splay *x) {
    Splay *p = x->f;
    int d = x->dir();
    if (!p->isr()) p->f->setCh(x, p->dir());
    else x->f = p->f;
    p->setCh(x->ch[!d], d);
    x->setCh(p, !d);
    p->pull(); x->pull();
}

vector<Splay*> splayVec;
void splay(Splay *x) {
    splayVec.clear();
    for (Splay *q=x;; q=q->f) {
        splayVec.push_back(q);
        if (q->isr()) break;
    }
    reverse(begin(splayVec), end(splayVec));
    for (auto it : splayVec) it->push();
    while (!x->isr()) {
        if (x->f->isr()) rotate(x);
        else if (x->dir()==x->f->dir()) rotate(x->f), rotate
            (x);
        else rotate(x), rotate(x);
    }
}

Splay* access(Splay *x) {
    Splay *q = nil;
    for (;x!=nil;x=x->f) {
        splay(x);
        x->setCh(q, 1);
        q = x;
    }
    return q;
}

void evert(Splay *x) {
    access(x);
    splay(x);
    x->rev ^= 1;
    x->push(); x->pull();
}

void link(Splay *x, Splay *y) {
    // evert(x);
    access(x);
    splay(x);
    evert(y);
    x->setCh(y, 1);
}

void cut(Splay *x, Splay *y) {
    // evert(x);
    access(y);
    splay(y);
    y->push();
    y->ch[0] = y->ch[0]->f = nil;
}

int N, Q;
Splay *vt[MXN];

int ask(Splay *x, Splay *y) {
    access(x);
    access(y);
    splay(x);
    int res = x->f->val;
    if (res == -1) res=x->val;
    return res;
}

int main(int argc, char** argv) {
    scanf("%d%d", &N, &Q);
    for (int i=1; i<=N; i++)
        vt[i] = new (Splay::pmem++) Splay(i);
    while (Q--) {

```

```

char cmd[105];
int u, v;
scanf("%s", cmd);
if (cmd[1] == 'i') {
    scanf("%d%d", &u, &v);
    link(vt[v], vt[u]);
} else if (cmd[0] == 'c') {
    scanf("%d", &v);
    cut(vt[1], vt[v]);
} else {
    scanf("%d%d", &u, &v);
    int res=ask(vt[u], vt[v]);
    printf("%d\n", res);
}
}
return 0;
}

```

Sparse Table

```

const int MAXN = 200005;
const int lgN = 20;

struct SP{ //sparse table
    int Sp[MAXN][lgN];
    function<int(int,int)> opt;
    void build(int n, int *a){ // 0 base
        for (int i=0 ;i<n; i++) Sp[i][0]=a[i];

        for (int h=1; h<lgN; h++){
            int len = 1<<(h-1), i=0;
            for (; i+len<n; i++)
                Sp[i][h] = opt( Sp[i][h-1] , Sp[i+len][h-1] );
            for (; i<n; i++)
                Sp[i][h] = Sp[i][h-1];
        }
    }
    int query(int l, int r){
        int h = __lg(r-l+1);
        int len = 1<<h;
        return opt( Sp[l][h] , Sp[r-len+1][h] );
    }
};

```

Treap Lin

```

#include <cstdio>
#include <cstdlib>
#include <algorithm>
#include <string.h>
using namespace std;
const int INF = 999999999;
int ran(){
    static unsigned x = 20170928;
    return x = 0xdefaced*x+1;
}
struct Treap{
    Treap *l,*r;
    int num,m,sz,tag,ra,ad;
    Treap(int a){
        l=r=NULL;
        num=m=a;
        sz=1;
        tag=ad=0;
        ra = ran();
    }
}*head,*tp;

int size(Treap *a){
    return a ? a->sz : 0;
}
int min(Treap *a){

```

```

    return a ? a->m+a->ad : INF;
}
int add(Treap *a){
    return a ? a->ad : 0;
}
void push(Treap *a){
    if(!a) return;
    if(a->tag){
        swap(a->l,a->r);
        if(a->l)a->l->tag ^= 1;
        if(a->r)a->r->tag ^= 1;
        a->tag=0;
    }
    if(a->l)a->l->ad += a->ad;
    if(a->r)a->r->ad += a->ad;
    a->num += a->ad;
    a->m += a->ad;
    a -> ad = 0;
}
void pull(Treap *a){
    if(!a) return;
    a->sz=1+size(a->l)+size(a->r);
    a->m = min( a->num, min( min(a->l), min(a->r) ) );
}

Treap* merge(Treap *a, Treap *b){
    if(!a || !b) return a ? a : b;
    if(a->ra > b->ra){
        push(a);
        a->r = merge(a->r,b);
        pull(a);
        return a;
    }else{
        push(b);
        b->l = merge(a,b->l);
        pull(b);
        return b;
    }
}

void split (Treap *o, Treap *&a, Treap *&b,int k){
    if(!k) a=NULL, b=o;
    else if(size(o)==k) a=o, b=NULL;
    else{
        push(o);
        if(k <= size(o->l)){
            b = o;
            split(o->l, a, b->l,k);
            pull(b);
        }else{
            a = o;
            split(o->r, a->r, b, k-size(o->l)-1);
            pull(a);
        }
    }
}

int main(){
    int n,tmp;
    scanf("%d",&n);
    for(int i = 0 ;i < n ;i++){
        scanf("%d",&tmp);
        tp = new Treap(tmp);
        head = merge(head,tp);
    }
    int Q;
    scanf("%d\n",&Q);
    char ss[50];
    int a, b, c;
    Treap *ta, *tb, *tc, *td;
    while(Q--){
        scanf("%s",ss);
        if(strcmp(ss,"ADD")==0){
            scanf("%d %d %d",&a,&b,&c);
            split(head,tb,tc,b);
            split(tb,ta,tb,a-1);
            tb -> ad += c;
            head = merge(ta, merge(tb, tc));
        }else if(strcmp(ss,"REVERSE")==0){

```

```

        scanf("%d %d",&a,&b);
        split(head,tb,tc,b);
        split(tb,ta,tb,a-1);
        tb -> tag ^= 1;
        head = merge(ta, merge(tb, tc));
    }else if(strcmp(ss,"REVOLVE")==0){
        scanf("%d %d %d",&a,&b,&c);
        split(head,tb,tc,b);
        split(tb,ta,tb,a-1);
        int szz = size(tb);
        c %= szz;
        split(tb,tb,td,szz-c);
        tb=merge(td,tb);
        head = merge(ta, merge(tb, tc));
    }else if(strcmp(ss,"INSERT")==0){
        scanf("%d %d",&a,&b);
        split(head,ta,tc,a);
        tb = new Treap(b);
        head = merge(ta, merge(tb, tc));
    }else if(strcmp(ss,"DELETE")==0){
        scanf("%d",&a);
        split(head,ta,tc,a-1);
        split(tc,tb,tc,1);
        delete tb;
        head = merge(ta,tc);
    }else if(strcmp(ss,"MIN")==0){
        scanf("%d %d",&a,&b);
        split(head,tb,tc,b);
        split(tb,ta,tb,a-1);
        printf("%d\n",min(tb));
        head = merge(ta, merge(tb, tc));
    }
}
}
}

```

String

AC 自動機

```

// remember make_fail() !!!
// notice MLE

const int sigma = 62;
const int MAXC = 200005;

inline int idx(char c){
    if ('A' <= c && c <= 'Z') return c - 'A';
    if ('a' <= c && c <= 'z') return c - 'a' + 26;
    if ('0' <= c && c <= '9') return c - '0' + 52;
}

struct ACautomaton{
    struct Node{
        Node *next[sigma], *fail;
        int cnt; // dp
        Node(){
            memset(next,0,sizeof(next));
            fail=0;
            cnt=0;
        }
    } buf[MAXC], *bufp, *ori, *root;

    void init(){
        bufp = buf;
        ori = new (bufp++) Node();
        root = new (bufp++) Node();
    }

    void insert(int n, char *s){
        Node *ptr = root;
        for (int i=0; s[i]; i++){
            int c = idx(s[i]);
            if (ptr->next[c]==NULL)
                ptr->next[c] = new (bufp++) Node();

```

```

        ptr = ptr->next[c];
    }
    ptr->cnt++;
}

Node* trans(Node *o, int c){
    while (o->next[c]==NULL) o = o->fail;
    return o->next[c];
}

void make_fail(){
    static queue<Node*> que;

    for (int i=0; i<sigma; i++)
        ori->next[i] = root;
    root->fail = ori;

    que.push(root);
    while ( ! que.empty() ){
        Node *u = que.front(); que.pop();
        for (int i=0; i<sigma; i++){
            if (u->next[i]==NULL) continue;
            u->next[i]->fail = trans(u->fail,i);
            que.push(u->next[i]);
        }
        u->cnt += u->fail->cnt;
    }
}
} ac;

```

KMP

```

template<typename T>
void build_KMP(int n, T *s, int *f){ // 1 base
    f[0]=-1, f[1]=0;
    for (int i=2; i<=n; i++){
        int w = f[i-1];
        while (w>0 && s[w+1]!=s[i]) w = f[w];
        f[i]=w+1;
    }
}

template<typename T>
int KMP(int n, T *a, int m, T *b){
    build_KMP(m,b,f);
    int ans=0;

    for (int i=1, w=0; i<=n; i++){
        while ( w>0 && b[w+1]!=a[i] ) w = f[w];
        w++;
        if (w==m){
            ans++;
            w=f[w];
        }
    }
    return ans;
}

```

迴文字動機

```

// remember init() !!!
// remember make_fail() !!!
// insert s need 1 base !!!
// notice MLE

const int sigma = 62;
const int MAXC = 1000006;
inline int idx(char c){
    if ('a' <= c && c <= 'z') return c - 'a';
    if ('A' <= c && c <= 'Z') return c - 'A'+26;
    if ('0' <= c && c <= '9') return c - '0'+52;
}

struct PalindromicTree{
    struct Node{

```

```

    Node *next[sigma], *fail;
    int len, cnt; // for dp
    Node(){
        memset(next,0,sizeof(next));
        fail=0;
        len = cnt = 0;
    }
} buf[MAXC], *bufp, *even, *odd;

void init(){
    bufp = buf;
    even = new (bufp++) Node();
    odd = new (bufp++) Node();
    even->fail = odd;
    odd->len = -1;
}

void insert(char *s){
    Node* ptr = even;
    for (int i=1; s[i]; i++){
        ptr = extend(ptr,s+i);
    }
}

Node* extend(Node *o, char *ptr){
    int c = idx(*ptr);
    while ( *ptr != *(ptr-1-o->len) )o=o->fail;
    Node *&np = o->next[c];
    if (!np){
        np = new (bufp++) Node();
        np->len = o->len+2;
        Node *f = o->fail;
        if (f){
            while ( *ptr != *(ptr-1-f->len) )f=f->fail;
            np->fail = f->next[c];
        }
        else {
            np->fail = even;
        }
        np->cnt = np->fail->cnt;
    }
    np->cnt++;
    return np;
}
} PAM;

```

Suffix Automaton

```

// par : fail link
// val : a topological order ( useful for DP )
// go[x] : automata edge ( x is integer in [0,26) )

struct SAM{
    struct State{
        int par, go[26], val;
        State () : par(0), val(0){ FZ(go); }
        State (int _val) : par(0), val(_val){ FZ(go); }
    };
    vector<State> vec;
    int root, tail;

    void init(int arr[], int len){
        vec.resize(2);
        vec[0] = vec[1] = State(0);
        root = tail = 1;
        for (int i=0; i<len; i++)
            extend(arr[i]);
    }
    void extend(int w){
        int p = tail, np = vec.size();
        vec.PB(State(vec[p].val+1));
        for ( ; p && vec[p].go[w]==0; p=vec[p].par)
            vec[p].go[w] = np;
        if (p == 0){
            vec[np].par = root;

```

```

        } else {
            if (vec[vec[p].go[w]].val == vec[p].val+1){
                vec[np].par = vec[p].go[w];
            } else {
                int q = vec[p].go[w], r = vec.size();
                vec.PB(vec[q]);
                vec[r].val = vec[p].val+1;
                vec[q].par = vec[np].par = r;
                for ( ; p && vec[p].go[w] == q; p=vec[p].par)
                    vec[p].go[w] = r;
            }
        }
        tail = np;
    }
};

```

smallest rotation

```

string mcp(string s){
    int n = s.length();
    s += s;
    int i=0, j=1;
    while (i<n && j<n){
        int k = 0;
        while (k < n && s[i+k] == s[j+k]) k++;
        if (s[i+k] <= s[j+k]) j += k+1;
        else i += k+1;
        if (i == j) j++;
    }
    int ans = i < n ? i : j;
    return s.substr(ans, n);
}

```

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Suffix Array

*/*he[i]保存了在后缀数组中相邻两个后缀的最长公共前缀长度
 *sa[i]表示的是字典序排名为i的后缀是谁（字典序越小的排名越靠前）
 *rk[i]表示的是后缀我所对应的排名是多少 */*

```

const int MAX = 1020304;
int ct[MAX], he[MAX], rk[MAX];
int sa[MAX], tsa[MAX], tp[MAX][2];
void suffix_array(char *ip){
    int len = strlen(ip);
    int alp = 256;
    memset(ct, 0, sizeof(ct));
    for(int i=0;i<len;i++) ct[ip[i]+1]++;
    for(int i=1;i<alp;i++) ct[i]+=ct[i-1];
    for(int i=0;i<len;i++) rk[i]=ct[ip[i]];
    for(int i=1;i<len;i*=2){
        for(int j=0;j<len;j++){
            if(j+i>len) tp[j][1]=0;
            else tp[j][1]=rk[j+i]+1;
            tp[j][0]=rk[j];
        }
        memset(ct, 0, sizeof(ct));
        for(int j=0;j<len;j++) ct[tp[j][1]+1]++;
        for(int j=1;j<len+2;j++) ct[j]+=ct[j-1];
        for(int j=0;j<len;j++) tsa[ct[tp[j][1]]+1]=j;
        memset(ct, 0, sizeof(ct));
        for(int j=0;j<len;j++) ct[tp[j][0]+1]++;
        for(int j=1;j<len+1;j++) ct[j]+=ct[j-1];
        for(int j=0;j<len;j++){
            sa[ct[tp[tsa[j]][0]]+1]=tsa[j];
            rk[sa[0]]=0;
            for(int j=1;j<len;j++){
                if( tp[sa[j]][0] == tp[sa[j-1]][0] &&
                    tp[sa[j]][1] == tp[sa[j-1]][1] )
                    rk[sa[j]] = rk[sa[j-1]];
                else

```

```

        rk[sa[j]] = j;
    }
}
for(int i=0,h=0;i<len;i++){
    if(rk[i]==0) h=0;
    else{
        int j=sa[rk[i]-1];
        h=max(0,h-1);
        for(;ip[i+h]==ip[j+h];h++);
    }
    he[rk[i]]=h;
}
}
}

```

Z-value

```

z[0] = 0;
for ( int bst = 0, i = 1; i < len ; i++ ) {
    if ( z[bst] + bst <= i ) z[i] = 0;
    else z[i] = min(z[i - bst], z[bst] + bst - i);
    while ( str[i + z[i]] == str[z[i]] ) z[i]++;
    if ( i + z[i] > bst + z[bst] ) bst = i;
}

// 回文版

void Zpal(const char *s, int len, int *z) {
    // Only odd palindrome len is considered
    // z[i] means that the longest odd palindrom
    // centered at
    // i is [i-z[i] .. i+z[i]]
    z[0] = 0;
    for (int b=0, i=1; i<len; i++) {
        if (z[b] + b >= i) z[i] = min(z[2*b-i], b+z[b]-i);
        else z[i] = 0;
        while (i+z[i]+1 < len and i-z[i]-1 >= 0 and
            s[i+z[i]+1] == s[i-z[i]-1]) z[i] ++;
        if (z[i] + i > z[b] + b) b = i;
    }
}

```

Dark Code

輸入優化

```

#include <stdio.h>

char getc(){
    static const int bufsize = 1<<16;
    static char B[bufsize], *S=B, *T=B;
    return (S==T&&(T=(S=B)+fread(B,1,bufsize,stdin),S==T)
        ?0:*S++);
}

template <class T>
bool input(T& a){
    a=(T)0;
    register char p;
    while ((p = getc()) < '-')
        if (p==0 || p==EOF) return false;
    if (p == '-')
        while ((p = getc()) >= '0') a = a*10 - (p^'0');
    else {
        a = p ^ '0';
        while ((p = getc()) >= '0') a = a*10 + (p^'0');
    }
    return true;
}

template <class T, class... U>
bool input(T& a, U&... b){

```

```

    if (!input(a)) return false;
    return input(b...);
}

```

Search

Others

矩陣數定理

新的方法介绍

下面我们介绍一种新的方法——Matrix-Tree定理(Kirchhoff矩阵-树定理)。

Matrix-Tree定理是解决生成树计数问题最有力的武器之一。它首先于1847年被Kirchhoff证明。在介绍定理之前，我们首先明确几个概念：

- 1、G的度数矩阵D[G]是一个n*n的矩阵，并且满足：当i≠j时，dij=0；当i=j时，dij等于vi的度数。
- 2、G的邻接矩阵A[G]也是一个n*n的矩阵，并且满足：如果vi、vj之间有边直接相连，则aij=1，否则为0。

我们定义G的Kirchhoff矩阵(也称为拉普拉斯算子)C[G]为C[G]=D[G]-A[G]，

则Matrix-Tree定理可以描述为：G的所有不同的生成树的个数等于其Kirchhoff矩阵C[G]任何一个n-1阶主子式的行列式的绝对值。

所谓n-1阶主子式，就是对于r(1≤r≤n)，将C[G]的第r行、第r列同时去掉后得到的新矩阵，用Cr[G]表示。

生成树计数

算法步骤：

- 1、构建拉普拉斯矩阵

```

Matrix[i][j] =
degree(i) , i==j
-1 , i-j有边
0 , 其他情况

```

- 2、去掉第r行，第r列 (r任意)

- 3、计算矩阵的行列式

```

/* *****
MYID      : Chen Fan
LANG      : G++
PROG      : Count_Spaning_Tree_From_Kuangbin
***** */

#include <stdio.h>
#include <string.h>
#include <algorithm>
#include <iostream>
#include <math.h>
using namespace std;
const double eps = 1e-8;
const int MAXN = 110;
int sgn(double x)
{
    if(fabs(x) < eps)return 0;
    if(x < 0)return -1;
    else return 1;
}
double b[MAXN][MAXN];
double det(double a[][MAXN],int n)
{
    int i, j, k, sign = 0;
    double ret = 1;
    for(i = 0; i < n; i++)
        for(j = 0; j < n; j++) b[i][j] = a[i][j];
    for(i = 0; i < n; i++)
    {
        if(sgn(b[i][i]) == 0)
        {
            for(j = i + 1; j < n; j++)

```

```

        if(sgn(b[j][i]) != 0) break;
        if(j == n) return 0;
        for(k = i; k < n; k++) swap(b[i][k], b[j][k]);
        sign++;
    }
    ret *= b[i][i];
    for(k = i + 1; k < n; k++) b[i][k] /= b[i][i];
    for(j = i + 1; j < n; j++)
        for(k = i + 1; k < n; k++) b[j][k] -= b[j][i] * b[i][k];
    }
    if(sign & 1) ret = -ret;
    return ret;
}
double a[MAXN][MAXN];
int g[MAXN][MAXN];
int main()
{
    int T;
    int n, m;
    int u, v;
    scanf("%d", &T);
    while(T--)
    {
        scanf("%d%d", &n, &m);
        memset(g, 0, sizeof(g));
        while(m--)
        {
            scanf("%d%d", &u, &v);
            u--; v--;
            g[u][v] = g[v][u] = 1;
        }
        memset(a, 0, sizeof(a));
        for(int i = 0; i < n; i++)
            for(int j = 0; j < n; j++)
                if(i != j && g[i][j])
                {
                    a[i][i]++;
                    a[i][j] = -1;
                }
        double ans = det(a, n - 1);
        printf("%.01f\n", ans);
    }
    return 0;
}

```

CYK

```
// 2016 NCPC from sunmoon
```

```
// 轉換
```

```

#define MAXN 55
struct CNF{
    int s, x, y; // s->xy | s->x, if y== -1
    int cost;
    CNF(){}
    CNF(int s, int x, int y, int c): s(s), x(x), y(y), cost(c){}
};
int state; // 規則數量
map<char, int> rule; // 每個字元對應到的規則，小寫字母為終端字符
vector<CNF> cnf;
inline void init(){
    state = 0;
    rule.clear();
    cnf.clear();
}
inline void add_to_cnf(char s, const string &p, int cost)
{
    if(rule.find(s) == rule.end()) rule[s] = state++;
    for(auto c: p) if(rule.find(c) == rule.end()) rule[c] = state++;
    if(p.size() == 1){
        cnf.push_back(CNF(rule[s], rule[p[0]], -1, cost));
    }
}

```

```

} else {
    int left = rule[s];
    int sz = p.size();
    for(int i = 0; i < sz - 2; ++i){
        cnf.push_back(CNF(left, rule[p[i]], state, 0));
        left = state++;
    }
    cnf.push_back(CNF(left, rule[p[sz - 2]], rule[p[sz - 1]], cost));
}
}

// 計算
vector<long long> dp[MAXN][MAXN];
vector<bool> neg_INF[MAXN][MAXN]; // 如果花費是負的可能會有無限小的情形
inline void relax(int l, int r, const CNF &c, long long cost, bool neg_c = 0){
    if(!neg_INF[l][r][c.s] && (neg_INF[l][r][c.x] || cost < dp[l][r][c.s])){
        if(neg_c || neg_INF[l][r][c.x]){
            dp[l][r][c.s] = 0;
            neg_INF[l][r][c.s] = true;
        } else dp[l][r][c.s] = cost;
    }
}
inline void bellman(int l, int r, int n){
    for(int k = 1; k <= state; ++k)
        for(auto c: cnf)
            if(c.y == -1) relax(l, r, c, dp[l][r][c.x] + c.cost, k == n);
}
inline void cyk(const vector<int> &tok){
    for(int i = 0; i < (int)tok.size(); ++i){
        for(int j = 0; j < (int)tok.size(); ++j){
            dp[i][j] = vector<long long>(state + 1, INT_MAX);
            neg_INF[i][j] = vector<bool>(state + 1, false);
        }
        dp[i][i][tok[i]] = 0;
        bellman(i, i, tok.size());
    }
    for(int r = 1; r < (int)tok.size(); ++r){
        for(int l = r - 1; l >= 0; --l){
            for(int k = 1; k < r; ++k)
                for(auto c: cnf)
                    if(~c.y) relax(l, r, c, dp[l][k][c.x] + dp[k + 1][r][c.y] + c.cost);
            bellman(l, r, tok.size());
        }
    }
}

```

數位統計

```

int dfs(int pos, int state1, int state2, ..., bool limit, bool zero) {
    if (pos == -1) return 是否符合條件;
    int &ret = dp[pos][state1][state2][...];
    if (ret != -1 && !limit) return ret;
    int ans = 0;
    int upper = limit ? digit[pos] : 9;
    for (int i = 0; i <= upper; i++) {
        ans += dfs(pos - 1, new_state1, new_state2, limit & (i == upper), (i == 0) && zero);
    }
    if (!limit) ret = ans;
    return ans;
}

int solve(int n) {
    int it = 0;
    for (; n; n /= 10) digit[it++] = n % 10;
    return dfs(it - 1, 0, 0, 1, 1);
}

```


1D/1D dp 優化

```
#include<bits/stdc++.h>

int t, n, L;
int p;
char s[MAXN][35];
ll sum[MAXN] = {0};
long double dp[MAXN] = {0};
int prevd[MAXN] = {0};

long double pw(long double a, int n) {
    if ( n == 1 ) return a;
    long double b = pw(a, n/2);
    if ( n & 1 ) return b*b*a;
    else return b*b;
}

long double f(int i, int j) {
    // cout << (sum[i] - sum[j]+i-j-1-L) << endl;
    return pw(abs(sum[i] - sum[j]+i-j-1-L), p) + dp[j];
}

struct INV {
    int L, R, pos;
};
INV stk[MAXN*10];
int top = 1, bot = 1;
void update(int i) {
    while ( top > bot && i < stk[top].L && f(stk[top].L, i) < f(stk[top].L, stk[top].pos) ) {
        stk[top - 1].R = stk[top].R;
        top--;
    }
    int lo = stk[top].L, hi = stk[top].R, mid, pos = stk[top].pos;
    //if ( i >= lo ) lo = i + 1;
    while ( lo != hi ) {
        mid = lo + (hi - lo) / 2;
        if ( f(mid, i) < f(mid, pos) ) hi = mid;
        else lo = mid + 1;
    }
    if ( hi < stk[top].R ) {
        stk[top + 1] = (INV) { hi, stk[top].R, i };
        stk[top++].R = hi;
    }
}

int main() {
    cin >> t;
    while ( t-- ) {
        cin >> n >> L >> p;
        dp[0] = sum[0] = 0;
        for ( int i = 1 ; i <= n ; i++ ) {
            cin >> s[i];
            sum[i] = sum[i-1] + strlen(s[i]);
            dp[i] = numeric_limits<long double>::max();
        }
        stk[top] = (INV) {1, n + 1, 0};
        for ( int i = 1 ; i <= n ; i++ ) {
            if ( i >= stk[bot].R ) bot++;
            dp[i] = f(i, stk[bot].pos);
            update(i);
            // cout << (ll) f(i, stk[bot].pos) << endl;
        }
        if ( dp[n] > 1e18 ) {
            cout << "Too hard to arrange" << endl;
        } else {
            vector<PI> as;
            cout << (ll)dp[n] << endl;
        }
    }
    return 0;
}
```

Theorm - DP optimization

Monotonicity & 1D/1D DP & 2D/1D DP

Definition xD/yD

1D/1D $DP[j] = \min(0 \leq i < j) \{ DP[i] + w(i, j) \}$; $DP[0] = k$
 2D/1D $DP[i][j] = \min(i < k \leq j) \{ DP[i][k - 1] + DP[k][j] \}$
 $+ w(i, j)$; $DP[i][i] = 0$

Monotonicity

c d

a | w(a, c) w(a, d)
 b | w(b, c) w(b, d)

Monge Condition

Concave (凹四邊形不等式): $w(a, c) + w(b, d) \geq w(a, d) + w(b, c)$

Convex (凸四邊形不等式): $w(a, c) + w(b, d) \leq w(a, d) + w(b, c)$

Totally Monotone

Concave (凹單調): $w(a, c) \leq w(b, d) \rightarrow w(a, d) \leq w(b, c)$

Convex (凸單調): $w(a, c) \geq w(b, d) \rightarrow w(a, d) \geq w(b, c)$

1D/1D DP $O(n^2) \rightarrow O(n \lg n)$

****CONSIDER THE TRANSITION POINT****

Solve 1D/1D Concave by Stack

Solve 1D/1D Convex by Deque

2D/1D Convex DP (Totally Monotone) $O(n^3) \rightarrow O(n^2)$

$h(i, j - 1) \leq h(i, j) \leq h(i + 1, j)$

Stable Marriage

// normal stable marriage problem

// input:

//3

//Albert Laura Nancy Marcy

//Brad Marcy Nancy Laura

//Chuck Laura Marcy Nancy

//Laura Chuck Albert Brad

//Marcy Albert Chuck Brad

//Nancy Brad Albert Chuck

#include<bits/stdc++.h>

using namespace std;

const int MAXN = 505;

int n;

int favor[MAXN][MAXN]; // favor[boy_id][rank] = girl_id

;

int order[MAXN][MAXN]; // order[girl_id][boy_id] = rank

;

int current[MAXN]; // current[boy_id] = rank; boy_id will pursue current[boy_id] girl.

int girl_current[MAXN]; // girl[girl_id] = boy_id;

void initialize() {

for (int i = 0 ; i < n ; i++) {

current[i] = 0;

girl_current[i] = n;

order[i][n] = n;

}

}

map<string, int> male, female;

string bname[MAXN], gname[MAXN];

int fit = 0;

void stable_marriage() {

queue<int> que;

for (int i = 0 ; i < n ; i++) que.push(i);

while (!que.empty()) {

```

int boy_id = que.front();
que.pop();

int girl_id = favor[boy_id][current[boy_id]];
current[boy_id]++;

if ( order[girl_id][boy_id] < order[girl_id][
    girl_current[girl_id]] ) {
    if ( girl_current[girl_id] < n ) que.push(
        girl_current[girl_id]); // if not the first
        time
    girl_current[girl_id] = boy_id;
} else {
    que.push(boy_id);
}
}

int main() {
    cin >> n;

    for ( int i = 0 ; i < n ; i++ ) {
        string p, t;
        cin >> p;
        male[p] = i;
        bname[i] = p;
        for ( int j = 0 ; j < n ; j++ ) {
            cin >> t;
            if ( !female.count(t) ) {
                gname[fit] = t;
                female[t] = fit++;
            }
            favor[i][j] = female[t];
        }
    }

    for ( int i = 0 ; i < n ; i++ ) {
        string p, t;
        cin >> p;
        for ( int j = 0 ; j < n ; j++ ) {
            cin >> t;
            order[female[p]][male[t]] = j;
        }
    }

    initialize();
    stable_marriage();

    for ( int i = 0 ; i < n ; i++ ) {
        cout << bname[i] << " " << gname[favor[i][current[i]
            ] - 1]] << endl;
    }
}

```

Mo's algorithm

```

int l = 0, r = 0, nowAns = 0, BLOCK_SIZE, n, m;
int ans[];
struct QUE{
    int l, r, id;
    friend bool operator < (QUE a, QUE b){
        if(a.l / BLOCK_SIZE != b.l / BLOCK_SIZE)
            return a.l / BLOCK_SIZE < b.l / BLOCK_SIZE;
        return a.r < b.r;
    }
}querys[];

inline void move(int pos, int sign) {
    // update nowAns
}

void solve() {
    BLOCK_SIZE = int(ceil(pow(n, 0.5)));

```

```

sort(querys, querys + m);
for (int i = 0; i < m; ++i) {
    const QUE &q = querys[i];
    while (l > q.l) move(--l, 1);
    while (r < q.r) move(r++, 1);
    while (l < q.l) move(l++, -1);
    while (r > q.r) move(--r, -1);
    ans[q.id] = nowAns;
}
}

```

parser

```

#include <bits/stdc++.h>
using namespace std;

typedef long long T;
bool GG;

T Eval2(char *&end) {
    T Eval0(char *&);
    T res=0;
    if ( *end=='(' ){
        res = Eval0(++end);
        if (*(end++)=='') return res;
        else { GG = true; return -1; }
    }
    else if( isdigit(*end) ){
        return strtol(end, &end, 10);
    }
    // 可改成 {strtol, strtoll, strtod}
    else { GG = true; return -1; }
}

T Evalx(char *&end){
    if(GG) return -1;
    T res = Eval2(end); if(GG) return -1;
    while (*end == '%'){
        end++;
        res = ( res % Eval2(end) );
        if(GG) return -1;
    }
    return res;
}

T Eval1(char *&end) {
    if(GG) return -1;
    T res = Evalx(end); if(GG) return -1;
    while (*end=='*' || *end == '/') {
        end++;
        if(*(end-1) == '*')res = ( res * Evalx(end) );
        else if(*(end-1) == '/')res = ( res / Evalx(end) );
        if(GG) return -1;
    }
    return res;
}

T Eval12(char *&end){
    if(GG) return -1;
    T res=1;
    if(*end == '-'){
        end++;
        res = -1;
    }
    res *= Evalx(end);
    while (*end=='*' || *end == '/') {
        end++;
        if(*(end-1) == '*')res = ( res * Evalx(end) );
        else if(*(end-1) == '/')res = ( res / Evalx(end) );
        if(GG) return -1;
    }
    return res;
}

T Eval0(char *&end) {

```

```

if(GG) return -1;
T res;
res = Eval12(end); if(GG) return -1;
while (*end=='+' || *end == '-'){
    end++;
    if(*end-1 == '+')res = ( res + Eval1(end) );
    else res = ( res - Eval1(end) );
    if(GG) return -1;
}
return res;
}

T parse(char *s){
    GG = false;
    T res = Eval0(s);
    while(*s != '\0'){
        if(*s != ' ')GG = true;
        s++;
    }
    return res;
}

int main() {
    char expr[3003];
    string str;
    int cnt = 0;
    while (getline (cin,str)){
        printf("case %d:\n",++cnt);
        strcpy(expr,str.c_str());
        T ans = parse(expr);
        if(GG) puts("syntactically incorrect\n");
        else printf("%lld\n", ans);
    }
}

/*
E0 = E1' (+-E1)*
E1 = Ex (/*Ex)*
Ex = E2 (%E2)*
E2 = (E0) or R+
E1' = Ex (/* Ex)* or -Ex (/* Ex)*
*/

```

python 小抄

```

#!/usr/bin/env python3

# 帕斯卡三角形
n = 10
dp = [ [1 for j in range(n)] for i in range(n) ]
for i in range(1,n):
    for j in range(1,n):
        dp[i][j] = dp[i][j-1] + dp[i-1][j]

for i in range(n):
    print( ' '.join( '{:5d}'.format(x) for x in dp[i] )
        )

# EOF
while True:
    try:
        n, m = map(int, input().split())
    except:
        break
    print( min(n,m), max(n,m) )

# input a sequence of number
a = [ int(x) for x in input().split() ]
a.sort()
print( ''.join( str(x)+' ' for x in a ) )

# LCS
ncase = int( input() )
for _ in range(ncase):

```

```

n, m = [int(x) for x in input().split()]
a, b = "$"+input(), "$"+input()

dp = [ [int(0) for j in range(m+1)] for i in range(
    n+1) ]

for i in range(1,n+1):
    for j in range(1,m+1):
        dp[i][j] = max(dp[i-1][j],dp[i][j-1])
        if a[i]==b[j]:
            dp[i][j] = max(dp[i][j],dp[i-1][j-1]+1)

for i in range(1,n+1):
    print(dp[i][1:])

print('a={:s}, b={:s}, |LCS(a,b)|={:d}'.format(a
    [1:],b[1:],dp[n][m]))

# Basic operator
a, b = 10, 20
a/b # 0.5
a//b # 0
a%b # 10
a**b # 10^20

# if, else if, else
if a==0:
    print('zero')
elif a>0:
    print('postive')
else:
    print('negative')

# stack # C++
stack = [3,4,5]
stack.append(6) # push()
stack.pop() # pop()
stack[-1] # top()
len(stack) # size() 0(1)

# queue # C++
from collections import deque
queue = deque([3,4,5])
queue.append(6) # push()
queue.popleft() # pop()
queue[0] # front()
len(queue) # size() 0(1)

```

Persistence