

Tree Algorithms

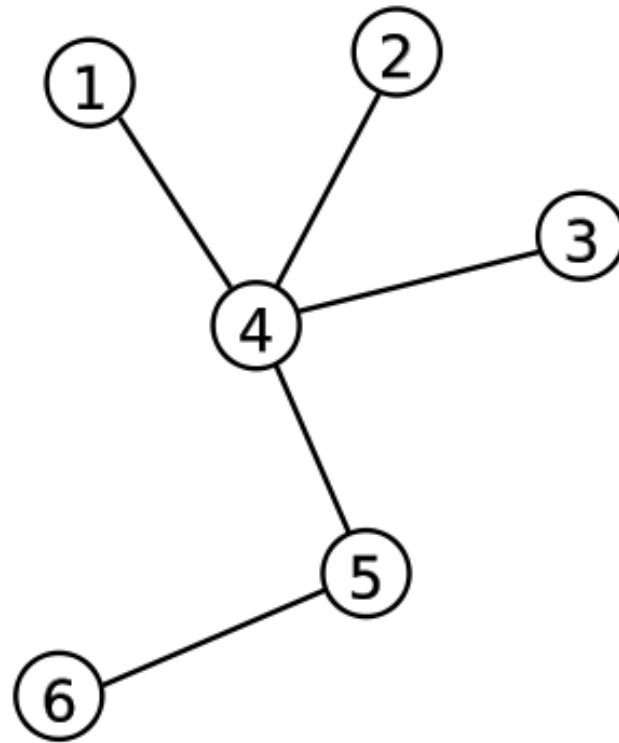
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Outline

- Introduction
- Euler Tour Technique
- Lowest Common Ancestor
- Heavy-Light Decomposition
- Centroid Decomposition

Introduction

What is a Tree?



Storing a Tree

Treat it as general graph

```
// node numbered from 1 ~ n
// store their adjacency list
vector< Edge > adj[ N ] ;

// traverse neighbors of u
for ( Edge e : adj[ u ] ) {
    int v = e.node ;
    // do anything...
}
```

Trees in Competitive Programming

- DFS Tree, BFS Tree
- Tree Data Structures, e.g. Segment Tree, Treap...
- Minimum Spanning Tree, Shortest Path Tree, Dominator Tree
- Dynamic Programming on Trees
- Update/Query on Trees

Problem (Tree Game)

You are playing a game with Alice.

Given a tree T , initially node i has a value A_i on it. Now you put a token on node u , and you move alternatively. Each step, you decrement the value of the current node, and then move the token to a neighbor node. When it's your turn and the current value is 0 , you lose. You go first, who will win?

What we will cover:

Mostly *Update/Query Problems*, some *dynamic programming*.

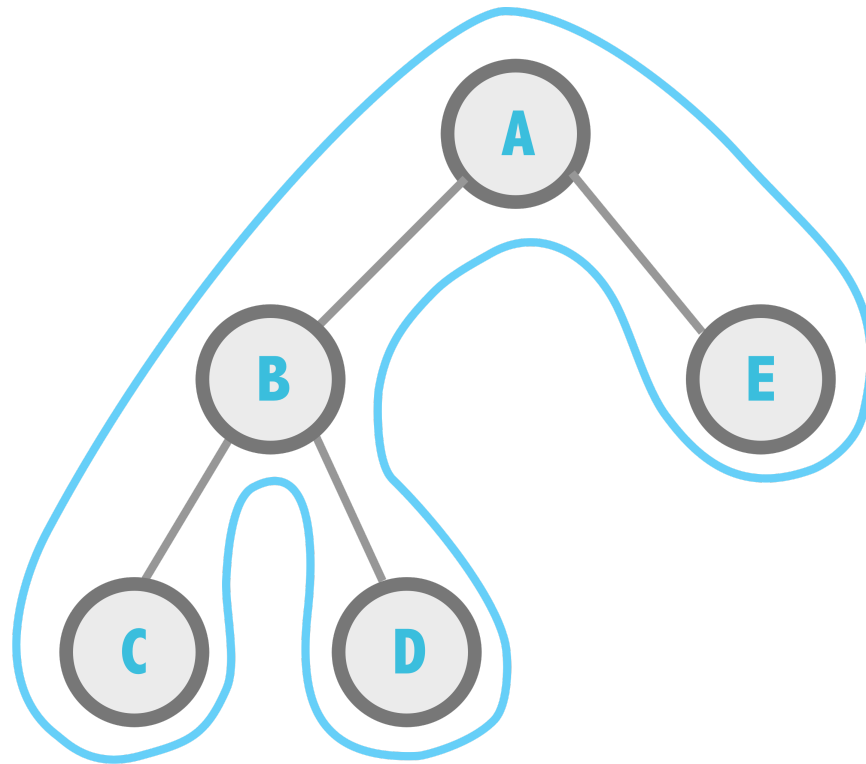
In these problems, we usually care about *Path* and *Subtree*...

Euler Tour Technique

Depth-First Search

```
void dfs( int now , int p ) {  
    for ( int nxt : adj[ now ] ) if ( nxt != p ) {  
        dfs( nxt , now ) ;  
    }  
}  
  
// start from root  
dfs( root , -1 ) ;
```

Euler Tour from DFS



ABCDBA EA

Time Stamp

Store the time *in* and *out* of a node

```
int timer = 0 ;  
  
void dfs( int u , int p ) {  
    time_in[ u ] = ++ timer ;  
    for ( int v : adj[ u ] ) if( v != p )  
        dfs( v , u ) ;  
    time_out[ u ] = ++ timer ;  
}  
  
dfs( root , -1 ) ;
```

Time Stamp Properties

- Decide if "x" is ancestor of "y" in $O(1)$

```
bool anc( int x , int y ) {  
    return time_in[ x ] <= time_in[ y ]  
        && time_out[ y ] <= time_out[ x ];  
}
```

- Any *subtree* is a *segment* - make the tree a *sequence*!!

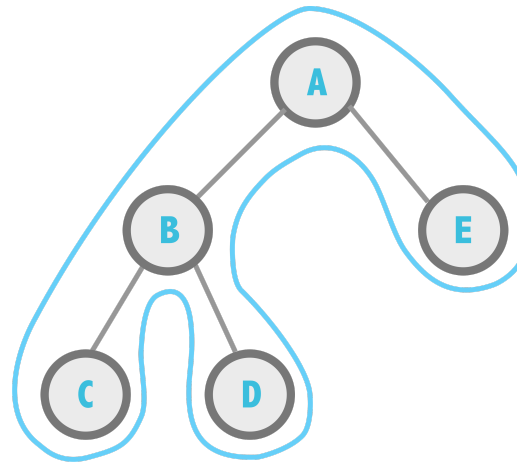
A(1, 10) B(2, 7) C(3, 4) D(5, 6) E(8, 9)

In sequence:

A B C C D D B E E A

or

A B C D E



Exercise

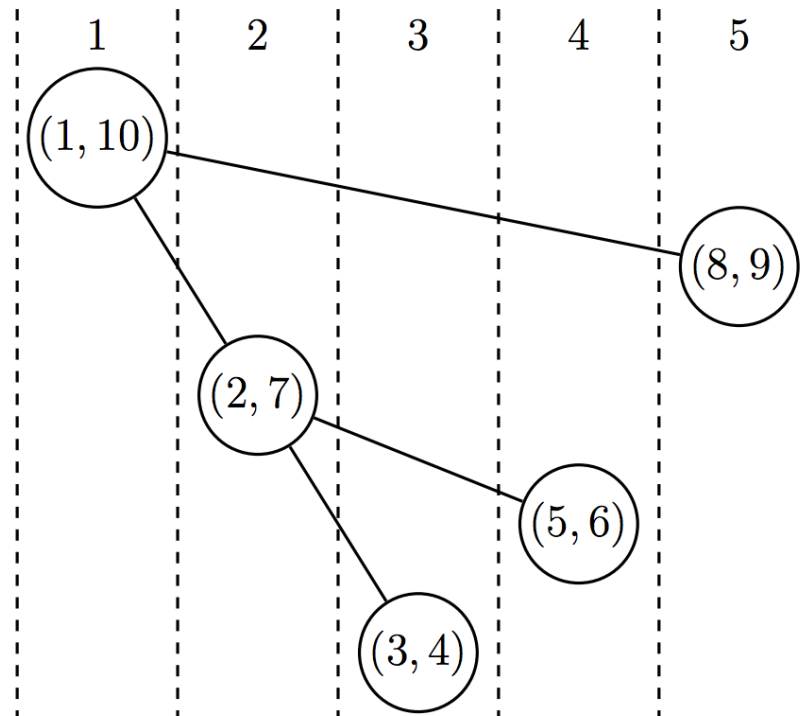
Given tree T , r is the root.

Make the following operations work in $O(\log N)$.

- Add v to all nodes in a subtree
- Query the current value of a node
- Query the sum of a subtree

Time Stamp in 2D

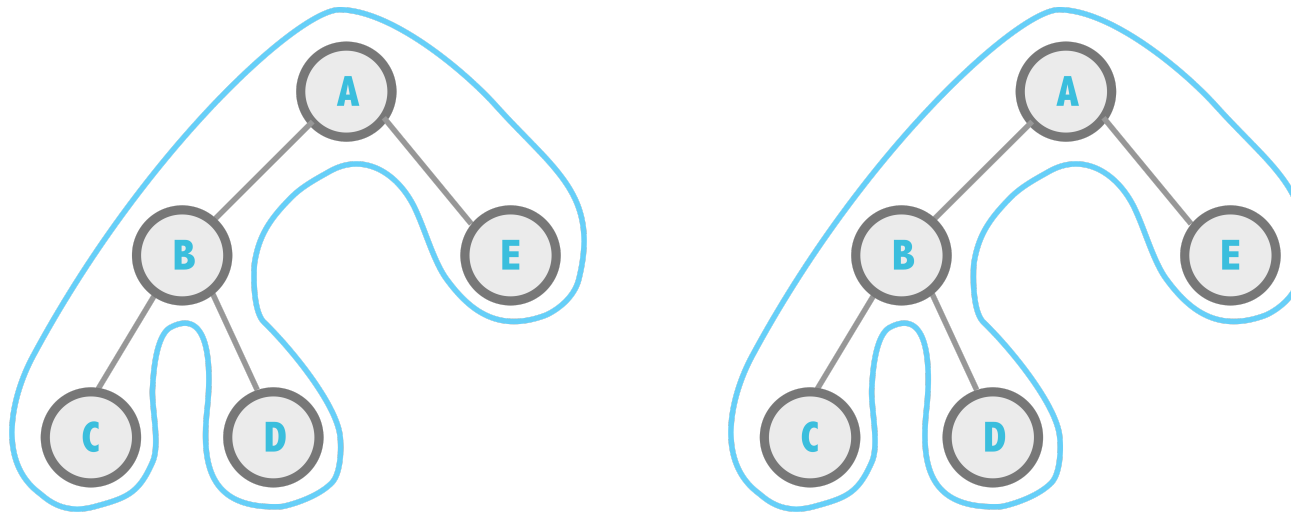
Every path between a node and its ancestors is in a rectangle.



Euler Tour Tree

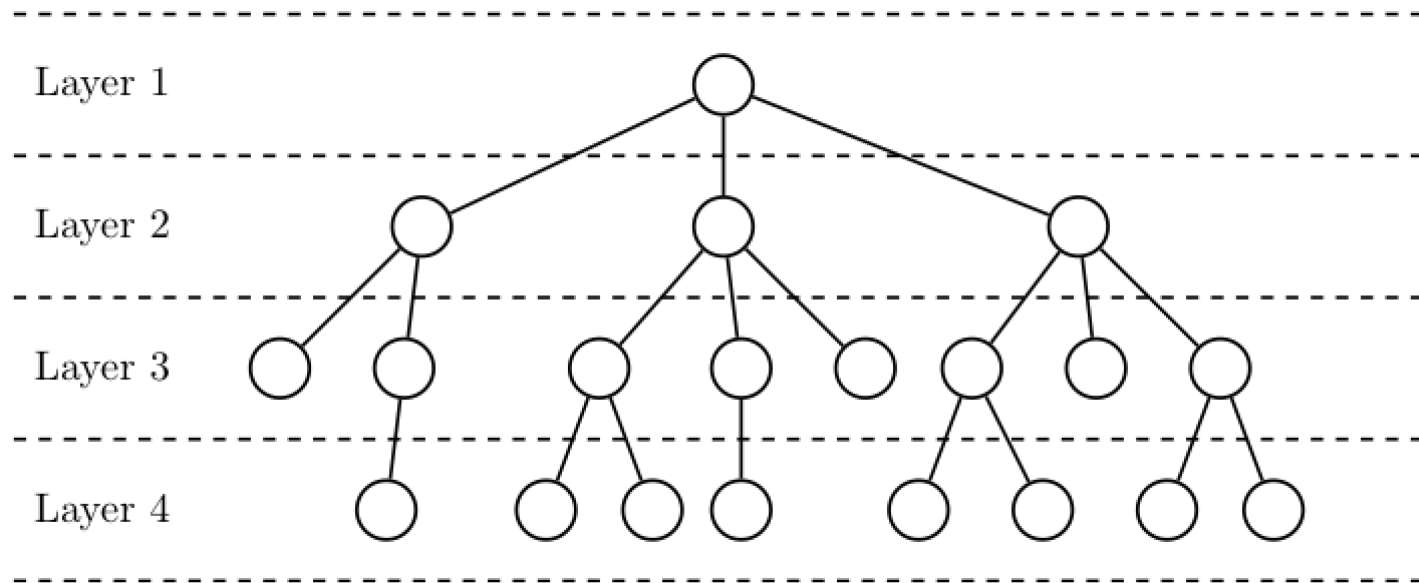
Represent the tree with the Euler Tour sequence. We can *cut an edge* / *link two trees* / *change root* easily. Solves *dynamic connectivity* problem on trees.

Implement with BST or Treap.



Lowest Common Ancestor

Definition



How fast can we compute LCA?

Method	Precompute	Query
Brute force	$O(1)$	$O(N)$
樹壓平	$O(N)$	$O(1)/O(\log N)$
倍增法	$O(N \log N)$	$O(\log N)$

倍增法（預處理）

```
// adj[ u ] : adjacency list of u
// par[ u ][ i ] : (2^i)-th parent of u
int timer = 0 ;

void dfs( int u , int p ) {
    par[ u ][ 0 ] = p ;
    time_in[ u ] = ++ timer ;
    for ( int v : adj[ u ] ) if( v != p )
        dfs( v , u ) ;
    time_out[ u ] = ++ timer ;
}

int main() {
    int root = 1 ; // set root node
    dfs( root , root ) ;

    for ( int j = 1 ; j <= LOG ; j ++ ) {
        for ( int i = 1 ; i <= n ; i ++ ) {
            par[ i ][ j ] = par[ par[ i ][ j - 1 ] ][ j - 1 ] ;
        }
    }
}
```

倍增法（查詢）

```
int LOG = 20 ;
bool anc( int x , int y ) {
    return time_in[ x ] <= time_in[ y ]
        && time_out[ y ] <= time_out[ x ];
}

int lca( int x , int y ) {
    if ( anc( y , x ) ) return y;
    for ( int j = LOG ; j >= 0 ; j -- )
        if ( !anc( par[ y ][ j ], x ) ) y = par[ y ][ j ] ;
    return par[ y ][ 0 ] ;
}
```

Exercise

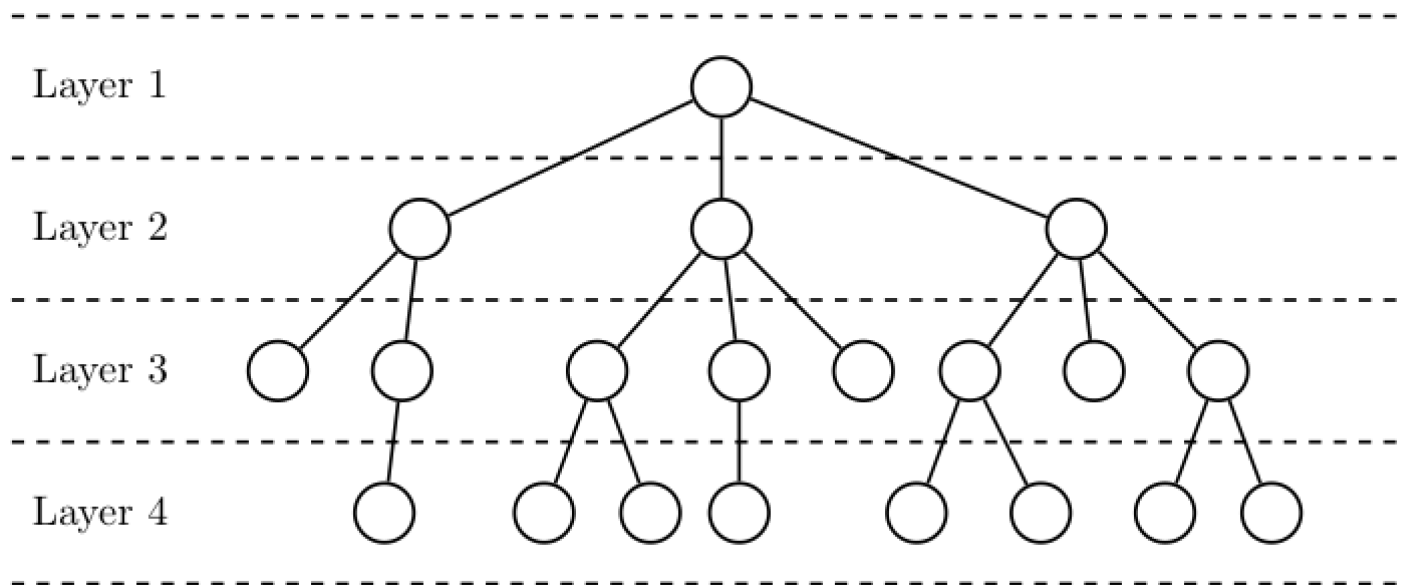
Given a tree T and an empty set \mathcal{S} .

Make the following operations work in $O(\log N)$.

- Insert the path from u to v into \mathcal{S}
- Given u and v , how many paths in \mathcal{S} intersects with the path from u to v ?

Key Insight

- $path(u,v)$ intersects with $path(p,q)$ if and only if $lca(u,v)$ is on $path(p,q)$ or $lca(p,q)$ is on $path(u,v)$



Heavy-Light Decomposition

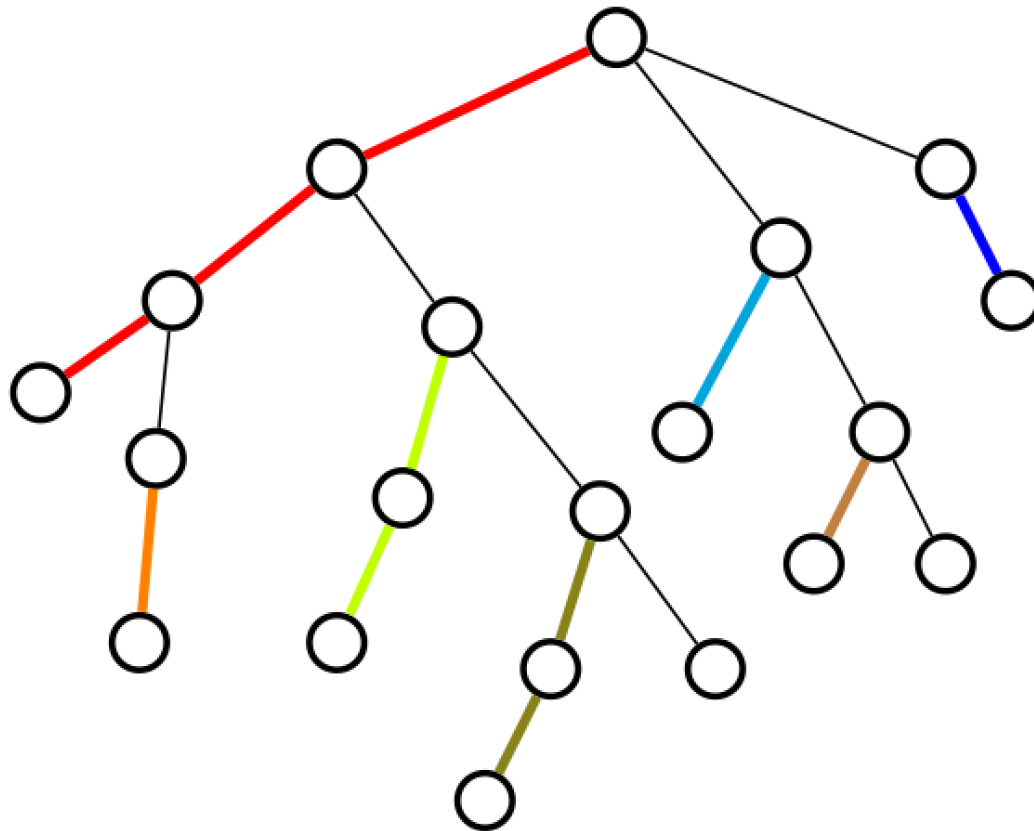
Problem (QTREE)

Given a tree T , make the following operations efficient.

- Update the weight of some edge
- Given u and v , which edge has the maximum weight on *$path(u,v)$*

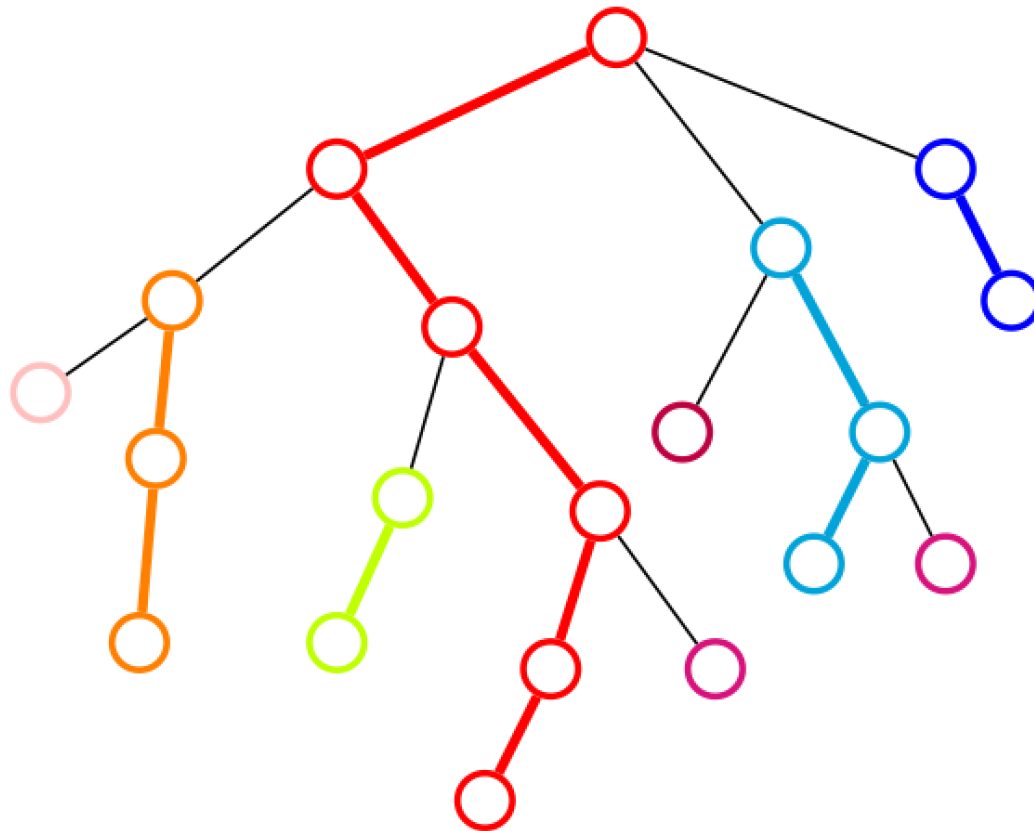
Sequence?

- Path does not form a continuous segment
- Still OK sometimes



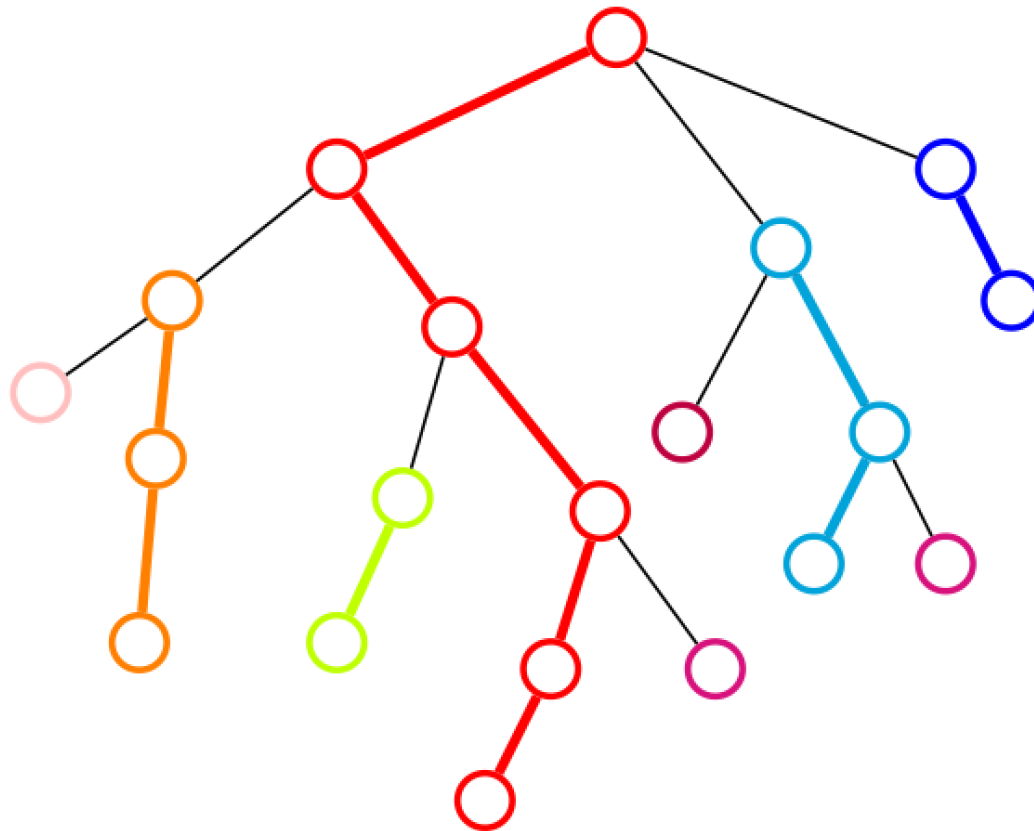
Partition to Chains

- Find some good partitions
- What partitions are good?



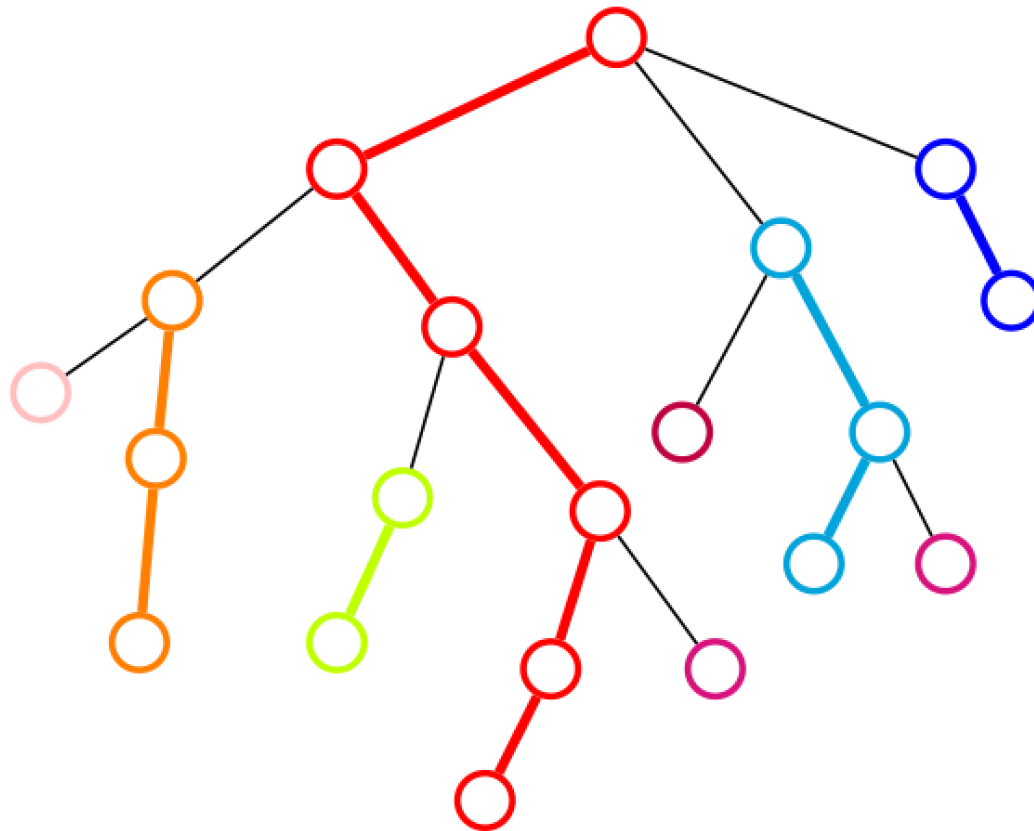
Heavy-Light Decomposition

- Heavy edges and light edges
- Heavy edges form heavy chains



So what?

- A path is composed of at most $\log N$ chains
- Subtree can still be a segment!



Implementation (precompute subtree size)

```
void dfssz( int u, int p ) {  
    // precompute the size of each subtree  
    par[ u ][ 0 ] = p ;  
    sz[ u ] = 1 ;  
    head[ u ] = u ;  
    for( int v : g[ u ] ) if( v != p ) {  
        dep[ v ] = dep[ u ] + 1 ;  
        dfssz( v , u ) ;  
        sz[ u ] += sz[ v ] ;  
    }  
}  
  
// inside main()  
int root = 1 ; // set root node  
dep[ root ] = 1 ;  
dfssz( root , root ) ;
```

Implementation (heavy-light decomposition)

```
void dfshl( int u ){
    tin[ u ] = ++ ts ;
    sort( g[ u ].begin() , g[ u ].end() ,
        [&]( int a , int b ){ return sz[ a ] > sz[ b ] ; } ) ;
    bool flag = 1 ;
    for ( int v : g[ u ] ) if ( v != par[ u ][ 0 ] ) {
        if ( flag ) head[ v ] = head[ u ] , flag = 0 ;
        dfshl( v ) ;
    }
    tout[ u ] = ts ;
}

// inside main()
ts = 0 ;
dfshl( root ) ;
```

Implementation (decompose a path)

```
vector< ii > getPath( int u , int v ) {  
    // u must be ancestor of v  
    // returns a list of intervals from v to u  
    vector< ii > res ;  
    while( tin[ u ] < tin[ head[ v ] ] ) {  
        res.push_back( ii( tin[ head[ v ] ] , tin[ v ] ) ) ;  
        v = par[ head[ v ] ][ 0 ] ;  
    }  
    if ( tin[ u ] + 1 <= tin[ v ] )  
        res.push_back( ii( tin[ u ] + 1 , tin[ v ] ) ) ;  
    return res ;  
}
```


Implementation (answer querys)

```
// query operation
int vx[ 2 ] ;
scanf( "%d%d" , &vx[ 0 ] , &vx[ 1 ] ) ;
int z = lca( vx[ 0 ] , vx[ 1 ] ) ;
int ans = -INF ;
vector< ii > path ;
for ( int u : vx ) {
    path = getPath( z , u ) ;
    for ( ii pr : path ) {
        if ( pr.first > pr.second ) swap( pr.first , pr.second ) ;
        ans = max( ans , query( 1 , 1 , n , pr.first , pr.second ) ) ;
    }
}
printf( "%d\n" , ans ) ;
```

Centroid Decomposition

Problem

Given a tree T , all nodes are white initially, make the following operations efficient.

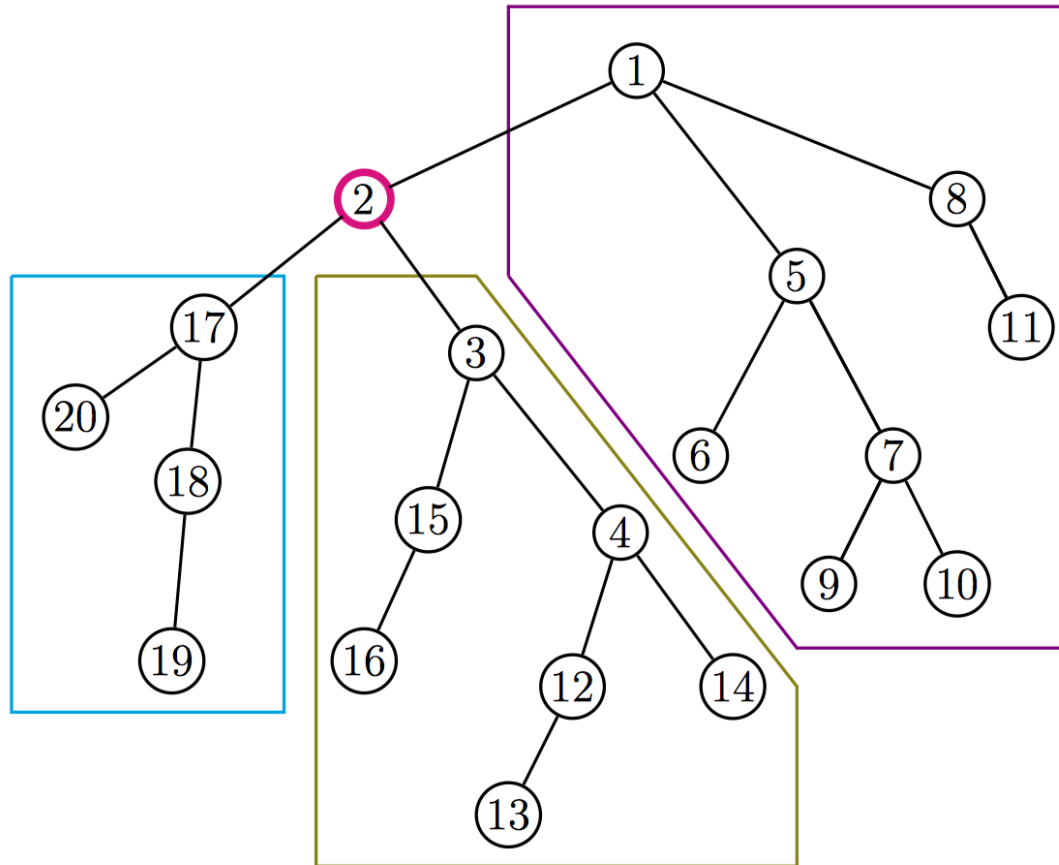
- Color a node black
- Given u , calculate the sum of distance from node u to all black nodes.

What's wrong with brute force?

- Each update takes constant time $O(1)$
- For each query, there is $O(N)$ other nodes, so need to consider $O(N)$ paths

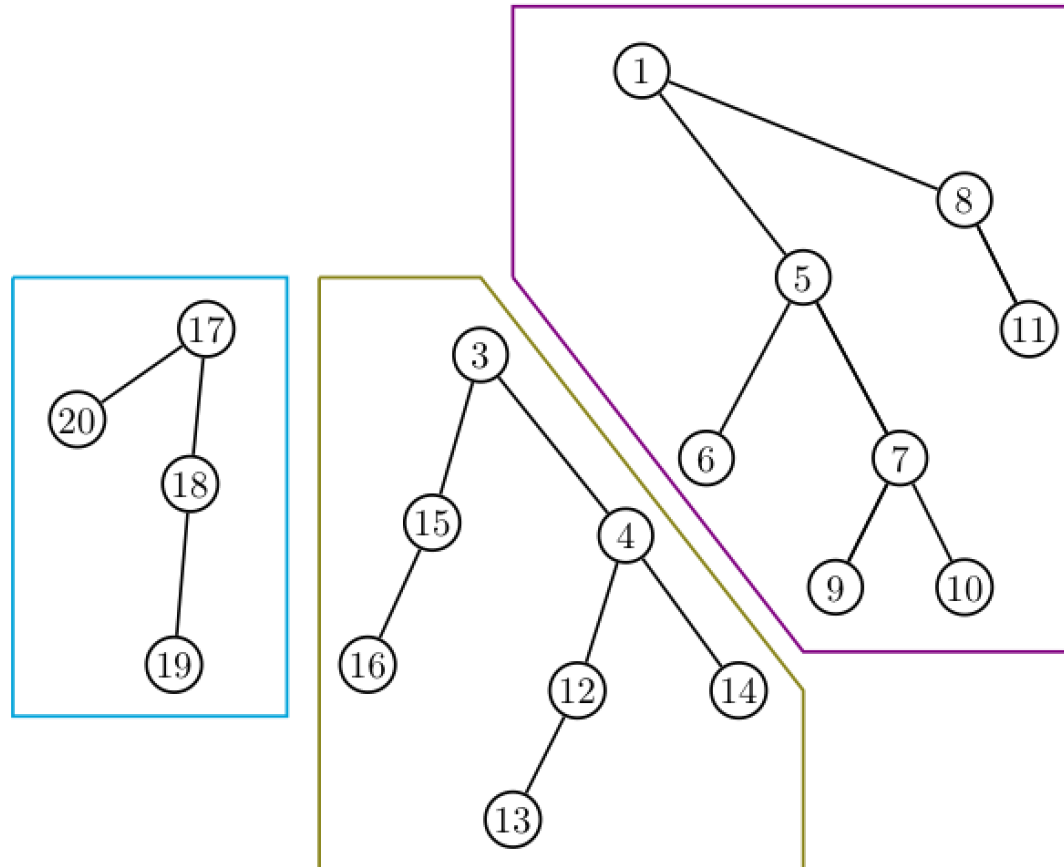
Centroid

The node such that removing it results in no tree of size $> \frac{n}{2}$



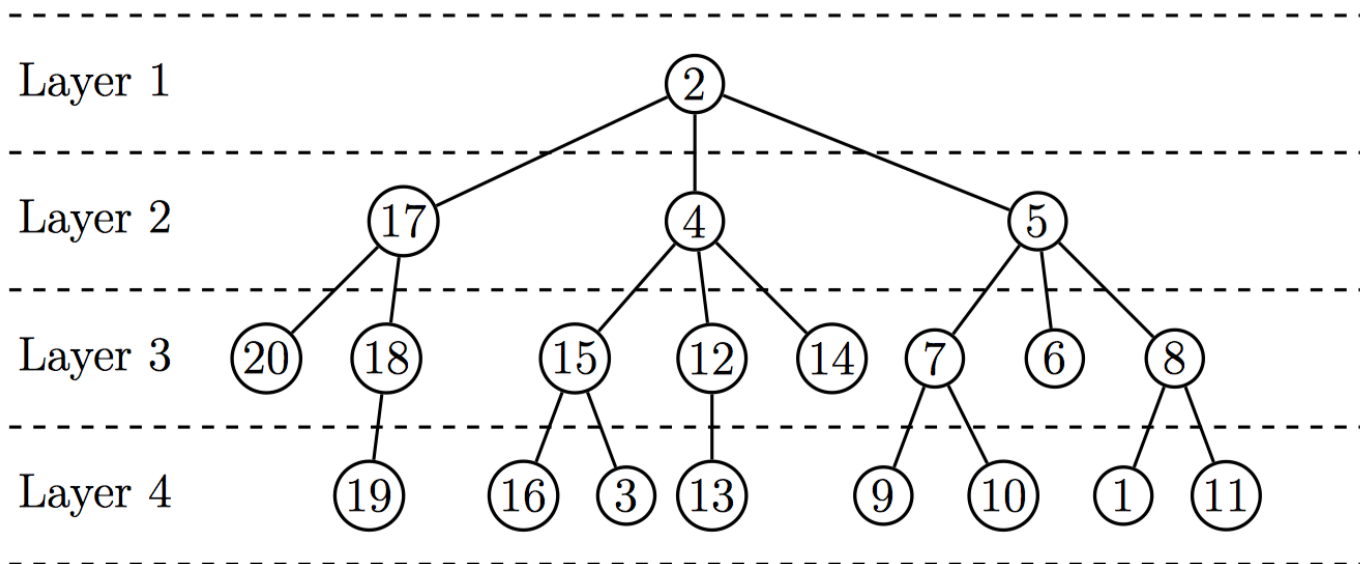
Divide and Conquer

Remove the centroid and repeat the same process on each resulting tree



Centroid Tree

Built through the process of Divide and Conquer



Properties from Divide and Conquer

- $path(u, v)$ can be partitioned into $path(u, lca(u, v))$ and $path(lca(u, v), v)$, where $lca(u, v)$ is the LCA in the Centroid Tree
- So we only care about $path(u, v)$, where u is the ancestor of v in the Centroid Tree

Properties from Centroid

- In total, we only care about $O(N \log N)$ paths, $O(\log N)$ for each node

Implementation (decomposition-1)

```
int centroidDecomp( int x ) {  
    // decompose the subtree and return the centroid  
    vector< int > q ;  
    { // bfs from arbitrary point to get bfs order for  
        // later computation of subtree size and M(u)  
        size_t pt = 0 ;  
        q.push_back( x ) ;  
        p[ x ] = -1 ;  
        while ( pt < q.size() ) {  
            int now = q[ pt ++ ] ;  
            sz[ now ] = 1 ;  
            M[ now ] = 0 ;  
            for ( auto &pr : adj[ now ] ) {  
                int nxt = pr.first ;  
                if ( !vis[ nxt ] && nxt != p[ now ] ) {  
                    q.push_back( nxt ) , p[ nxt ] = now ;  
                }  
            }  
        }  
    }  
}
```

Implementation (decomposition-2)

```
// calculate subtree size in reverse order
reverse( q.begin() , q.end() ) ;
for ( int& nd : q ) if ( p[ nd ] != -1 ) {
    sz[ p[ nd ] ] += sz[ nd ] ;
    maxify( M[ p[ nd ] ] , sz[ nd ] ) ;
}
for ( int& nd : q )
    maxify( M[ nd ] , (int)q.size() - sz[ nd ] ) ;

// find centroid
int centroid ;
for ( int &nd : q )
    if ( M[ nd ] + M[ nd ] <= (int)q.size() )
        centroid = nd ;

// path[ nd ] stores the nodes on the path from the root
// to "nd" on the centroid tree
// struct node( now , nxt , dis )
for ( int &nd : q ) {
    if ( path[ nd ].size() )
        path[ nd ].back().nxt = centroid ;
    path[ nd ].emplace_back( centroid , -1 , 0 ) ;
}
```

Implementation (decomposition-3)

```
{ // bfs from centroid to compute distance from all
  // nodes to the centroid, can also be done with LCA
  q.clear() ;
  size_t pt = 0 ;
  q.push_back( centroid ) ;
  p[ centroid ] = -1 ;
  while ( pt < q.size() ) {
    int now = q[ pt ++ ] ;
    long long ndis = path[ now ].back().dis ;
    for ( auto &pr : adj[ now ] ) {
      int nxt = pr.first ;
      long long cdis = pr.second ;
      if ( !vis[ nxt ] && nxt != p[ now ] ) {
        q.push_back( nxt ) , p[ nxt ] = now ;
        path[ nxt ].back().dis = ndis + cdis ;
      }
    }
  }
}

// decompose the tree recursively
// set vis[ centroid ] = 1 to break the tree into forest
vis[ centroid ] = 1 ;
for ( auto &pr : adj[ centroid ] ) {
  int nxt = pr.first ;
  if ( !vis[ nxt ] ) centroidDecomp( nxt ) ;
}
return centroid ;
}
```

Implementation (update & query)

Need some math to avoid counting the same path twice

```
long long sum[ N ] ;
int tot[ N ] , cnt[ N ] ;
void mark( int x ) {
    for ( auto& nd : path[ x ] ) {
        int now = nd.now , nxt = nd.nxt ;
        long long dis = nd.dis ;
        sum[ now ] += dis ;
        tot[ now ] ++ ;
        if ( nxt != -1 ) {
            sum[ nxt ] -= dis ;
            cnt[ nxt ] ++ ;
        }
    }
}

long long query( int x ) {
    long long ret = 0 ;
    for ( auto& nd : path[ x ] ) {
        int now = nd.now , nxt = nd.nxt ;
        long long dis = nd.dis ;
        ret += sum[ now ] + dis * ( tot[ now ] - cnt[ nxt ] ) ;
    }
    return ret ;
}
```

Questions?

THE END