

Programming with MicroBit

Overview on Hardware Features

Sensors and Actuators

Part II

Micro:Bit OLED Display

What is OLED?

OLED is an abbreviation of **O**rganic **L**ight **E**mitting **D**iode

- A flat light emitting technology
- Use organic materials that emit light when electric current is applied

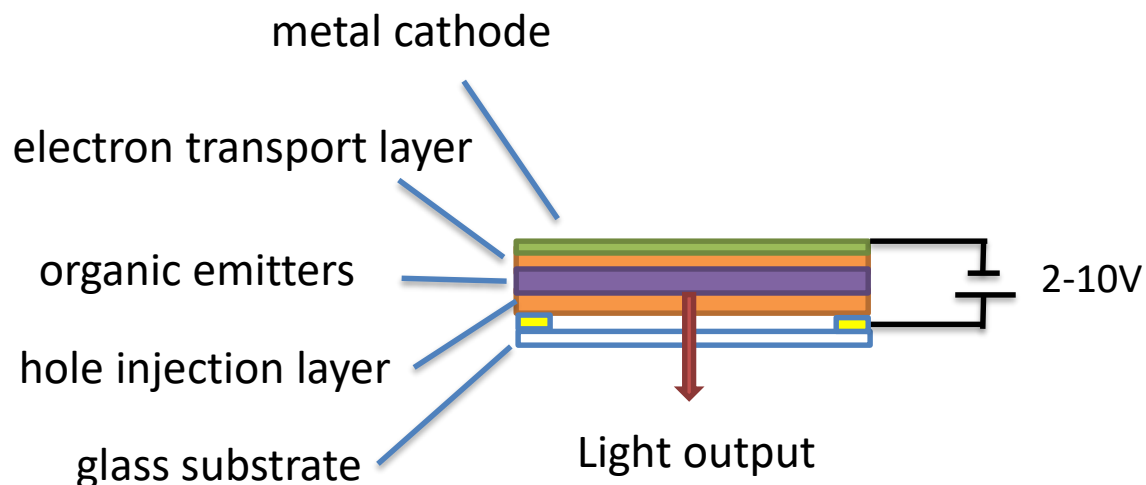
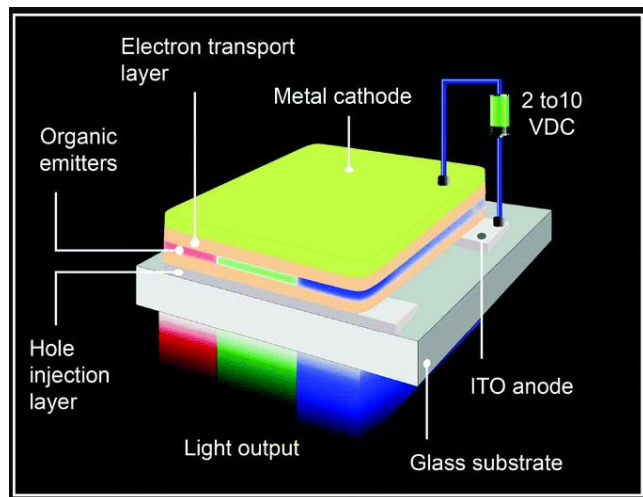
Introduction to OLED:

1) https://www.youtube.com/watch?time_continue=201&v=ZcTxI4QoGAo

2) <https://www.oled-info.com/introduction>

Basic Design of OLED

- Like a sandwich
- Place a series of organic thin films between two conductors.
- When electrical current is applied, a bright light is emitted.



Advanced Applications



Flexible display

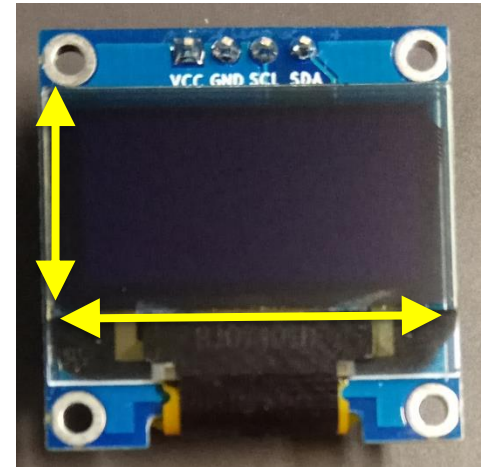


Transparent display

OLED Used in Project

- Passive OLED
- Key features
 - Dimension: 0.96 inch
 - Resolution: 128 x 64 (dots)
- Location specified by (x,y) co-ordinates
- Text and simple shape can be made by dots
- Control via **I2C** bus
- Optional display for mini-project

64 dots



128 dots

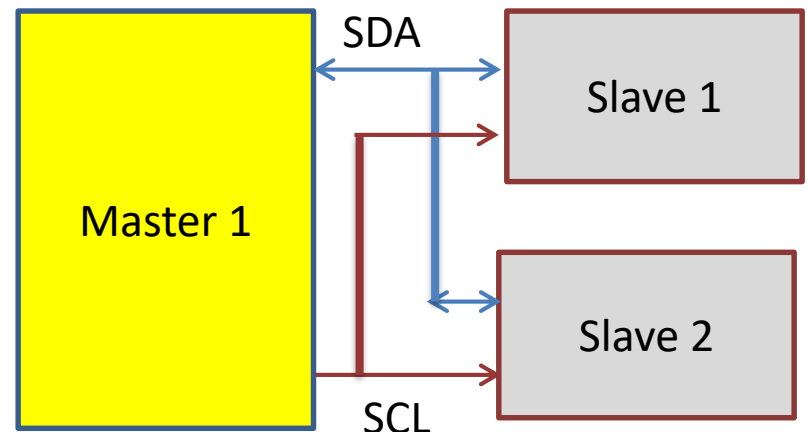
What is I²C (I Square C)?

- I2C : Inter-Integrated Circuit
- A **synchronous serial communication**, multi-master, multi-slave, wired communications
- Only required two signal wires: SCL (Serial Clock) and SDA (Serial Data)
 - SCL is the clock signal, and SDA is the data signal.

Master and Slave in I²C

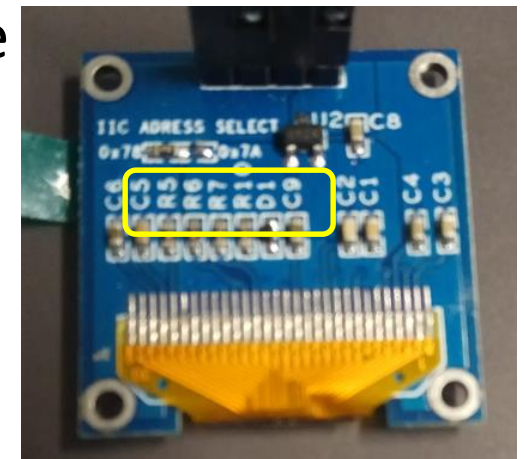
- The device that initiates a transaction on the I²C bus is called the master. The master controls the clock signal. A device being addressed by the master is called a slave.
- Using just 2 lines (SDA and SCL), a master can connect to multiple slaves (up to 1008)
- We can also have multiple masters / multiple slaves.

Example of 1 master and 2 slaves



Address of Slave Devices

- How to differentiate different devices if they connected to same master?
 - Each I²C-compatible hardware slave device comes with a **predefined device address**. Eg. our OLED is 60_d
 - To allow multiple identical devices connecting to one I2C bus, user can alter some lower bits of the address.
 - For example, our OLED's address can be modified by re-soldering a resistor at the back.
(Address will then be changed to 61_d)

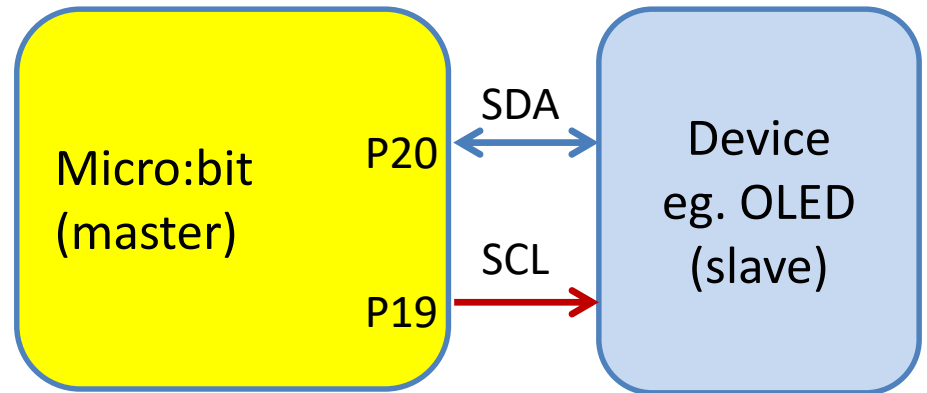


How I²C Works?

- The master transmits the device address of the intended slave at the beginning of every transaction.
- Each slave is responsible for monitoring the bus, but only the slave with that address will respond.

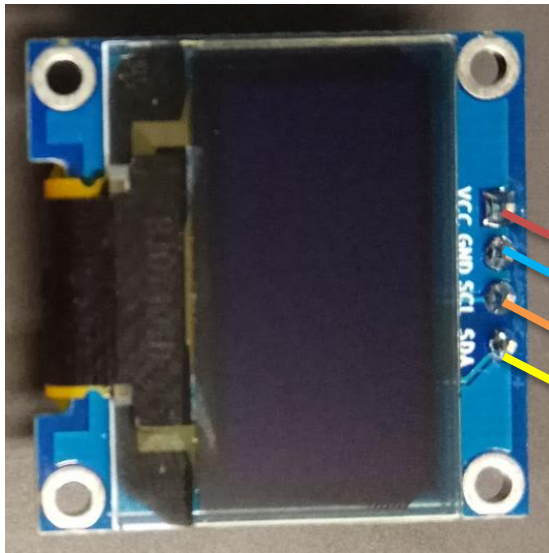
Connecting OLED to Micro:bit

- I²C requires two wires
 - SCL: clock signal
 - SDA: data signal



- Micro:bit uses P19 and P20 for I2C
- Connections
 - 3V for supply
 - Pin 19 of micro:bit → Slave device's SCL
 - Pin 20 of micro:bit → Slave device's SDA
 - Common ground

Connecting OLED to Micro:bit

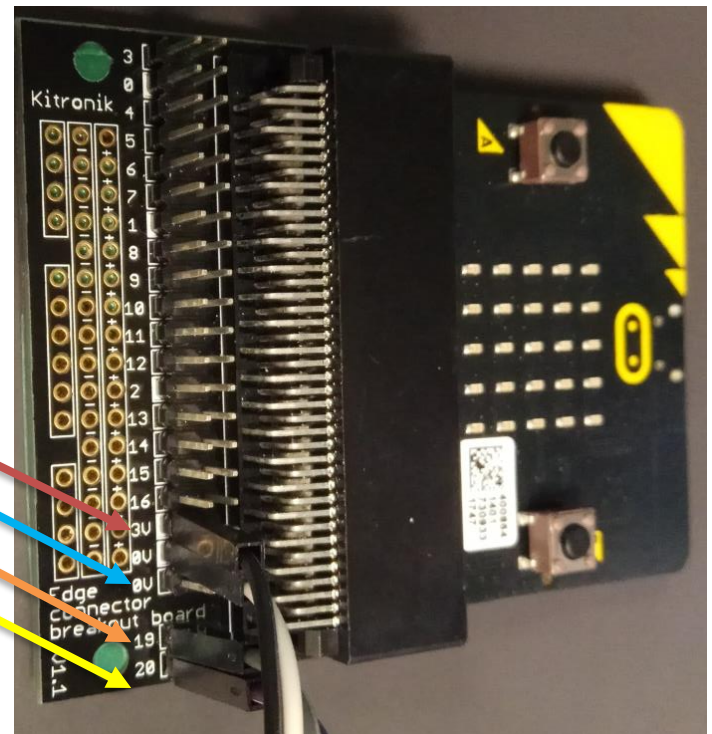


VCC ↔ 3V

GND ↔ 0V

SCL ↔ 19

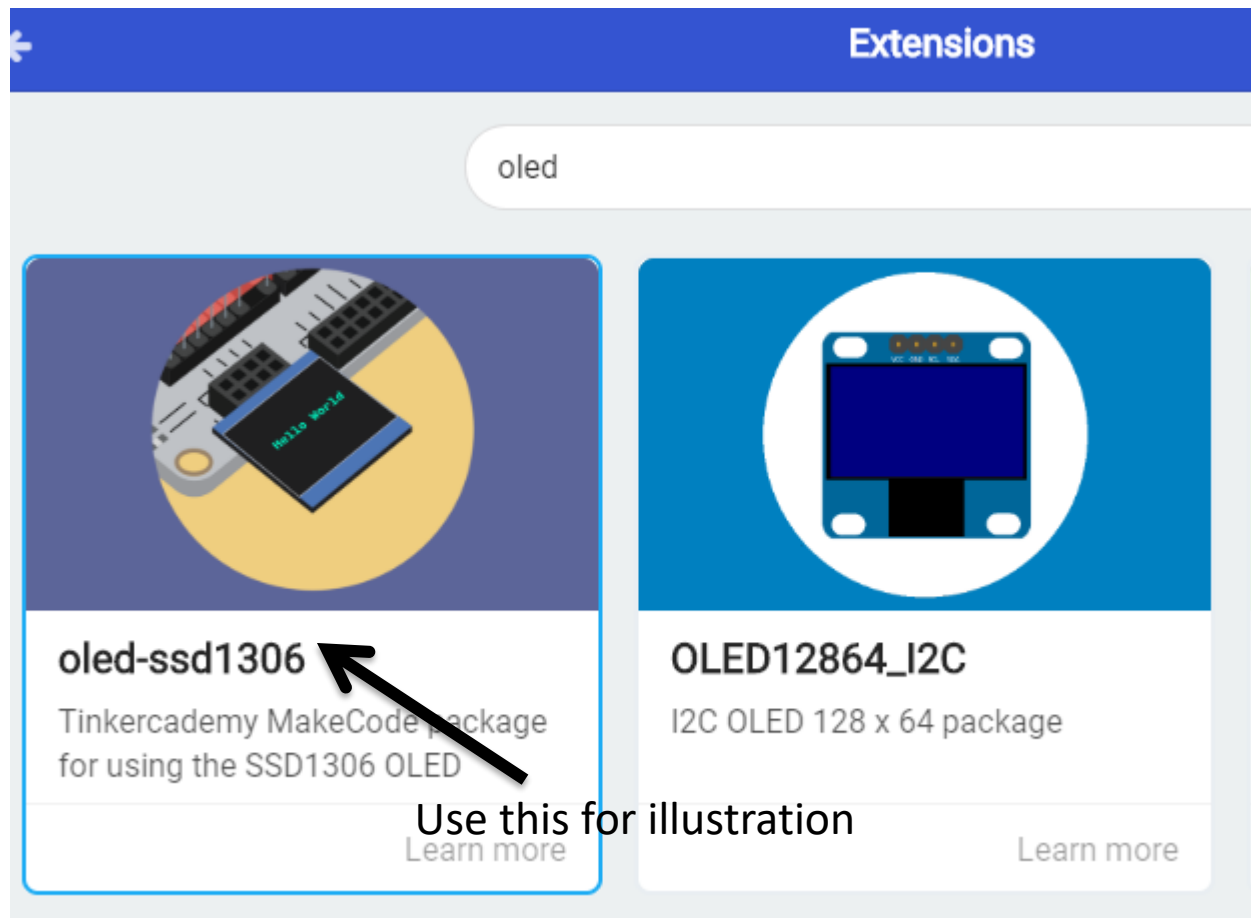
SDA ↔ 20



You may need to solder the connector for pin 19 and Pin 20, if you can't find in your breakout board.

Programming of OLED

- You will need to add an extension to program the module. (search “OLED”)



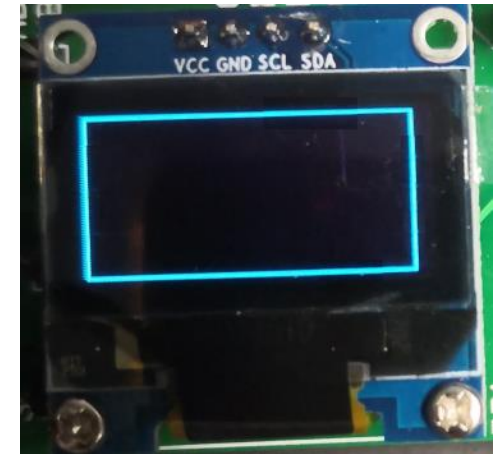
What can an OLED display?



Text



Geometric shapes

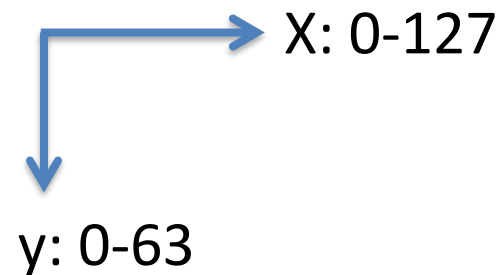
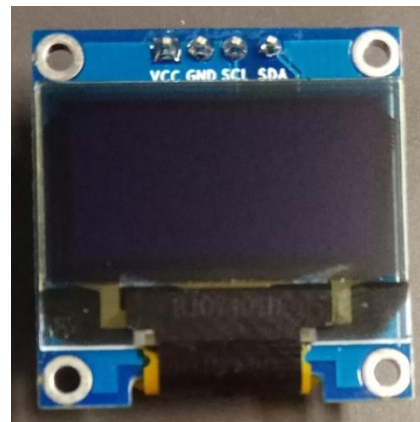


Graphics and Image

- 1) <https://blog.adafruit.com/2019/12/13/a-simple-python-game-with-microbit-and-oled-display-oled-gaming-python-microbit-blogmywiki/>
- 2) https://github.com/fizban99/microbit_ssd1306

Size of Display Area

- The size of display area is 64 x 128 (dots)



- Max: 8 rows and 21 characters on one screen; if more, it scrolls up

https://github.com/fizban99/microbit_ssd1306

OLED Display

**Crossy Road / Frogger
game on a micro:bit
with OLED display**

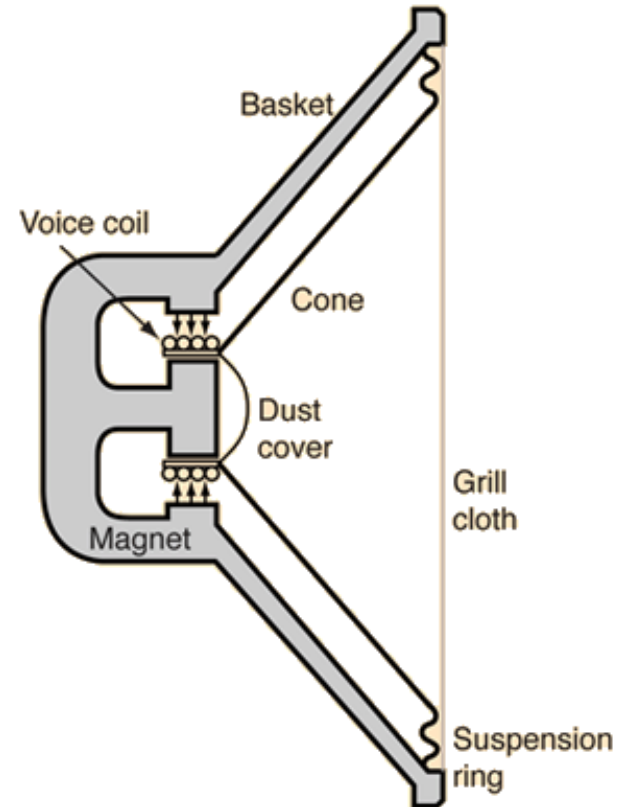
blogmywiki
edTech / micro:bit / reading / writing



Speakers

Loudspeaker

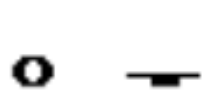
- **Loudspeaker** reproduces sound based on electromechanical process.
- When voltage is applied, the voice core generates magnetic field, and together with the fixed magnet, the cone will move accordingly (attraction and repulsion).
- As a result, it vibrates and generates sound according to the signal.



Music Notes



- Music Notes and Rest notes (no sound) for different durations



whole note
semibreve

4 beats



half note
minim

2 beats



quarter note
crotchet

1 beat



eighth note
quaver

$\frac{1}{2}$ beat



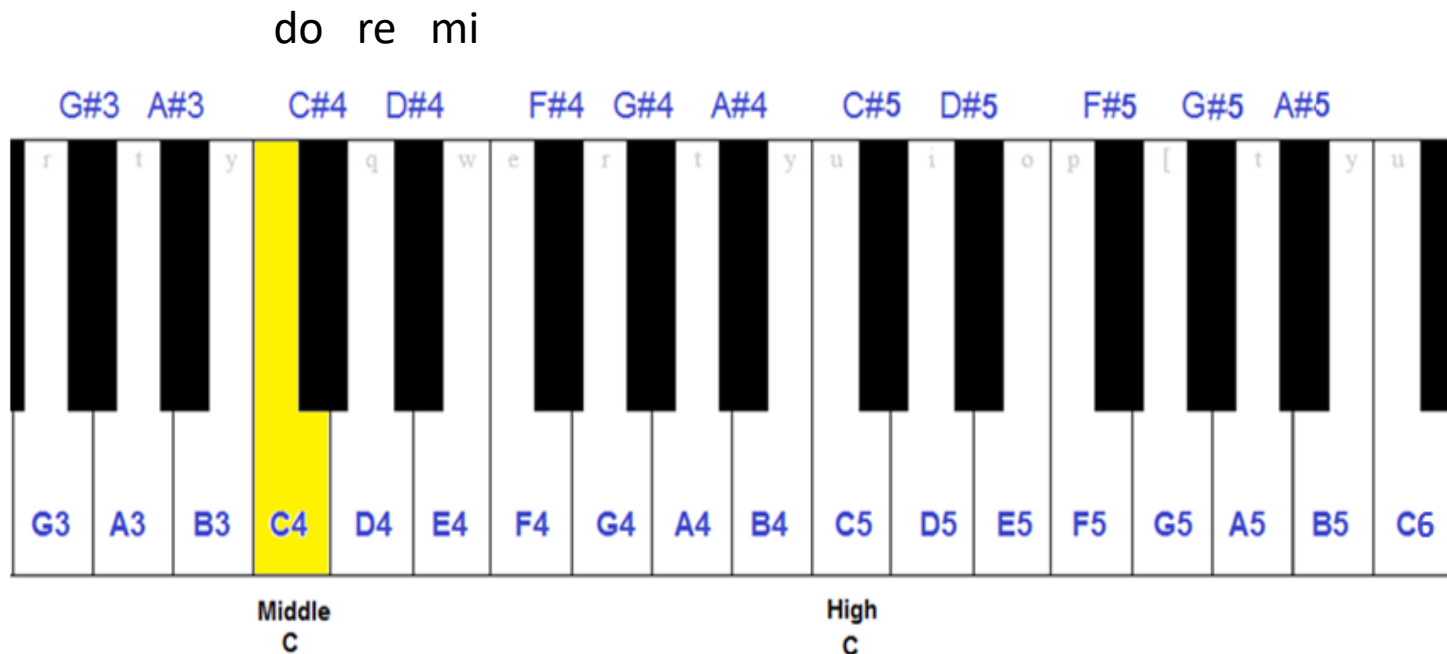
sixteenth note
semiquaver

$\frac{1}{4}$ beat

- The actual time duration of a note depends on the tempo of the song, which is in a unit of beats per minute (bpm).
- Eg. 1 beat in a tempo with 96bpm lasts for
$$60\text{sec}/96 = 0.625\text{sec} = 625 \text{ ms}$$

Pitch of a sound

- Pitch of sound is characterized by frequency
- The keyboard of a piano:



Frequency and pitch

Pitch	G3	G#3	A3	A#3	B3	C4	C#4	D4
Freq(Hz)	196	208	220	233	247	262	277	294

Pitch	D#4	E4	F4	F#4	G4	G#4	A4	A#4
Freq(Hz)	311	330	349	370	392	415	440	466

Pitch	B4	C5	C#5	D5	D#5	E5	F5
Freq(Hz)	494	523	554	587	622	659	698

Pitch	F#5	G5	G#5	A5	A#5	B5	C6
Freq(Hz)	740	784	831	880	932	988	1047

Generating a music

- Specify the tempo (x Beats per minute)
- Generating the wave with specific frequency (the pitch f) and last for certain number of beats (y beats) time (the duration or the number of beats).
- Number of cycles to generate $N = 60fy/x$

Example

```
from microbit import *  
import music
```

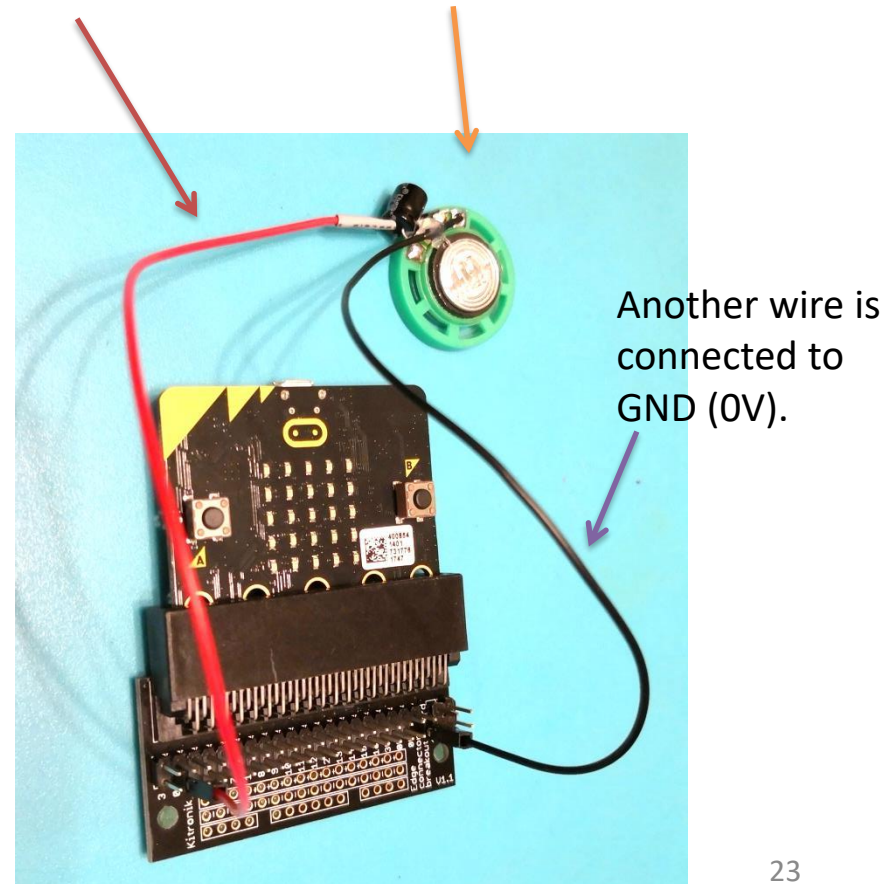
```
tune = ["c4:4", "d4:4",  
        "e4:4", "c4:4", "c4:4",  
        "d4:4", "e4:4", "c4:4",  
        "e4:4", "f4:4", "g4:8",  
        "e4:4", "f4:4", "g4:8"]
```

```
music.play(tune)
```

For low power speaker, it can be connected directly to an I/O pin

The wire with a capacitor is + and it is connected to P0

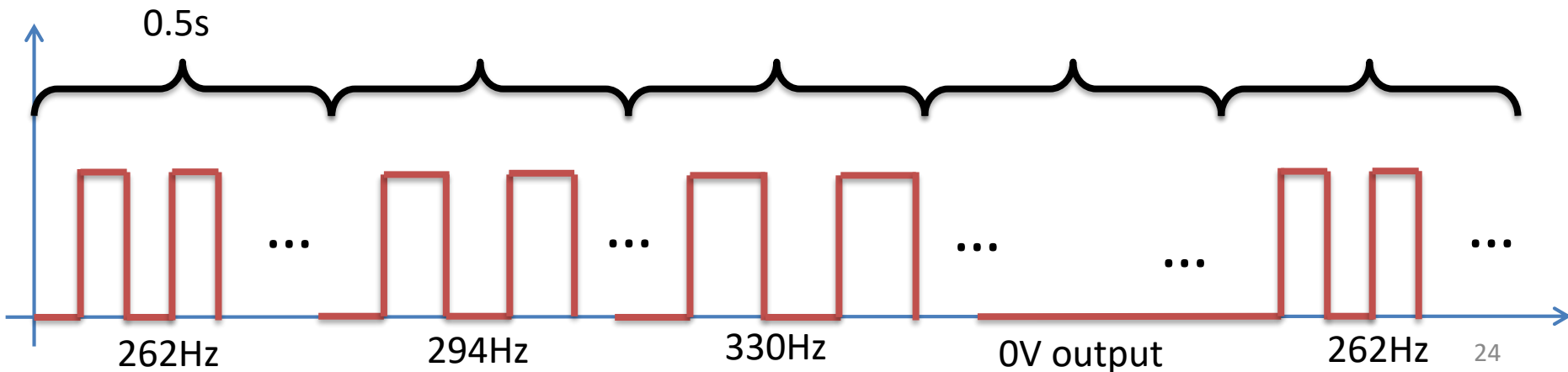
A capacitor (for ac coupling)



Another wire is connected to GND (0V).

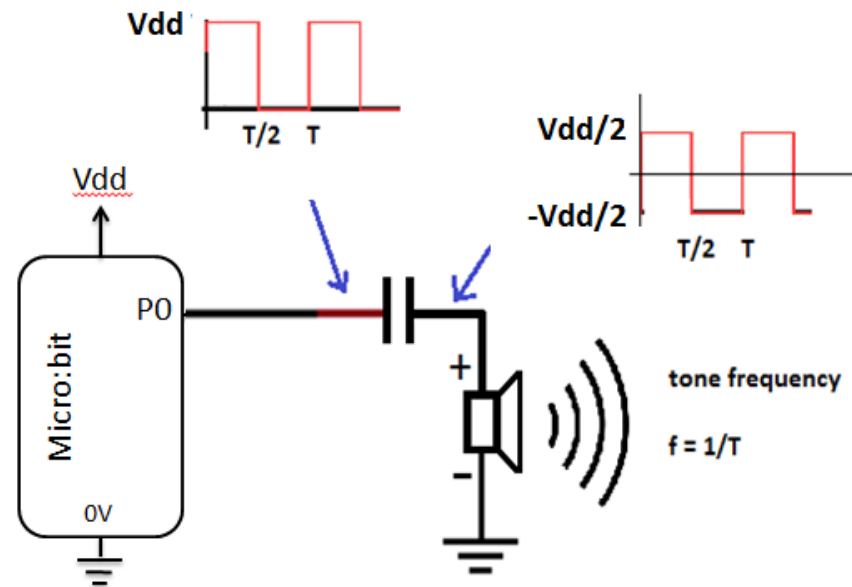
Timing

- 120bpm: 1 beat lasts 0.5sec
- Frequency
 - Middle C: 262Hz
 - Middle D: 294Hz
 - Middle E: 330Hz



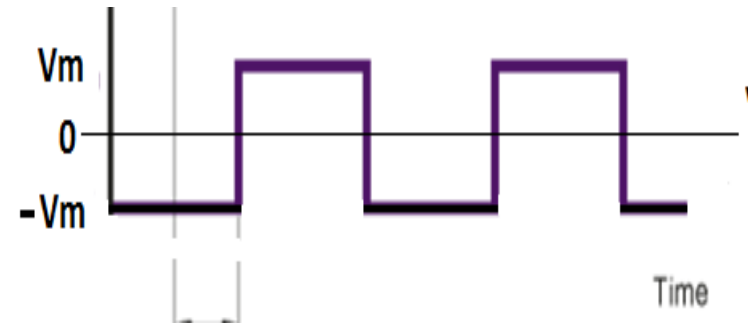
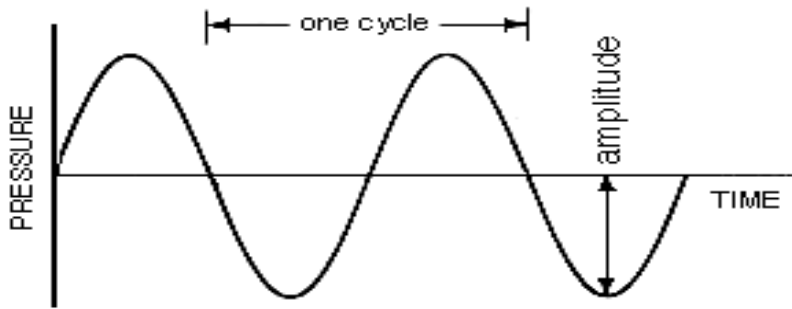
Remark 1: DC Problem

- Output of an I/O pin: 0V – LOW; Vdd (3V) – HIGH
- The generated square wave has a DC shift which may damage a loudspeaker
- Solution:
 - Add ac-coupling capacitor in series as shown
 - The capacitor will block the dc components, but let the ac components go through



Limitation

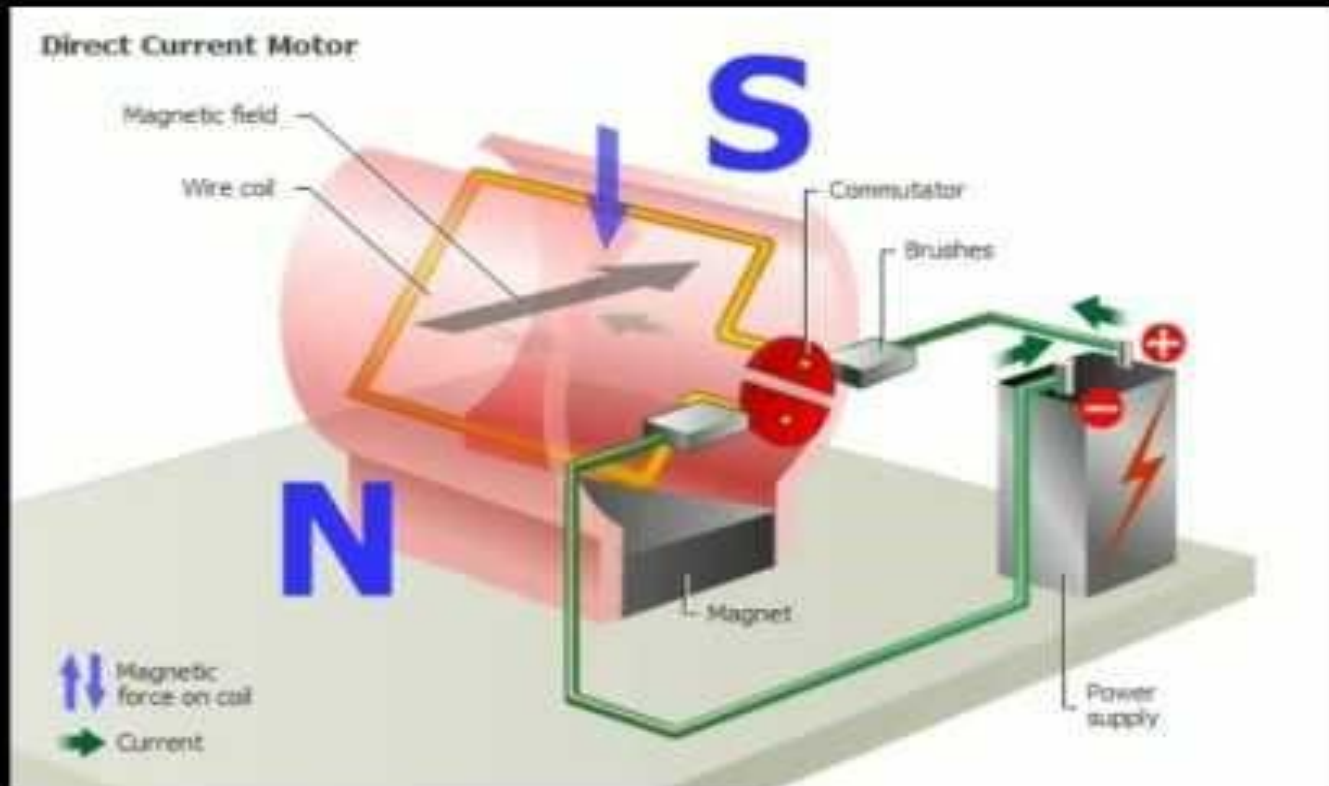
- Loudness depends on the amplitude of the wave V_m



- Voltage level of I/O pin cannot be modified to different level (Note: even PWM only modify the duty cycle, not the peak of amplitude of the square wave)

Motor

Basic Principle



A collage of various types of actuators, including DC motors, servos, solenoids, and pneumatic cylinders. The image displays a wide variety of mechanical components used for converting electrical energy into motion. The components include: several small DC motors in different sizes and colors (blue, silver, black); a larger black DC motor with a blue label; a black servo motor with a blue horn; a transparent servo motor showing internal gears; a black solenoid with a blue coil; a silver pneumatic cylinder; a black pneumatic cylinder with a black tire-like tread; and a yellow solenoid. The actuators are arranged in a grid-like fashion on a white background.

Nowadays Motor's Applications



Flight devices



Automation



Robotics



Smart Appliance



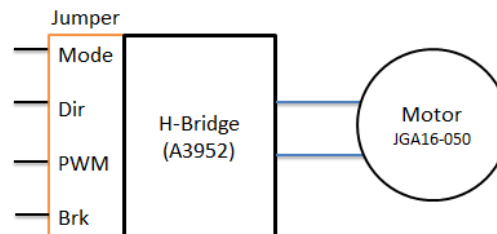
Security devices



Transportation

Driving Circuit

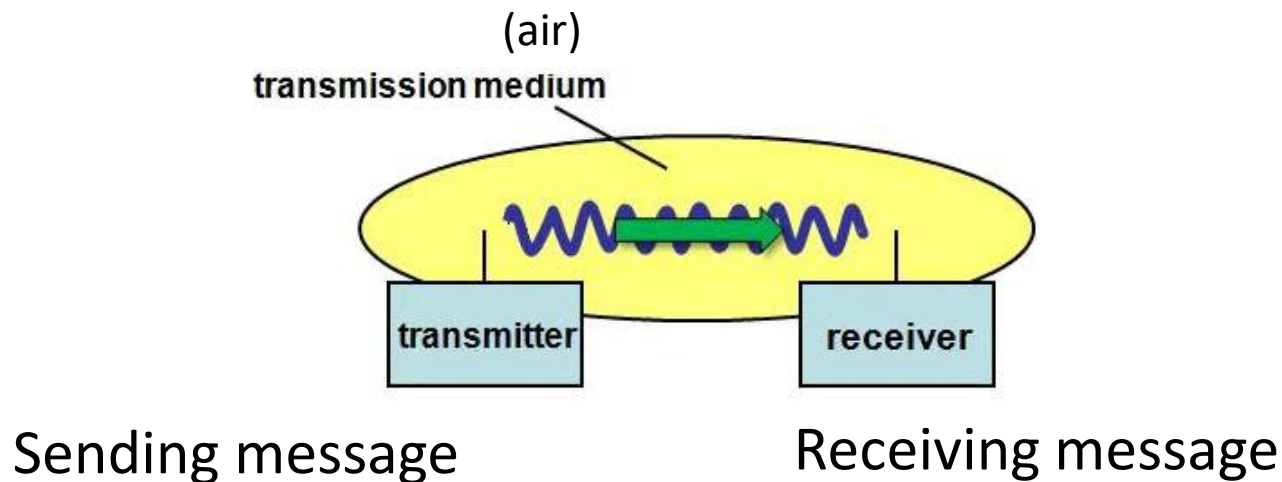
- Some motors need high voltage and high current
 - E.g. Motor (JGA16-050) needs 1A current, too large for micro:bit;
 - It also needs 6V but micro:bit can only output 3V (Vdd).
- Solution: Driving circuit is needed
 - e.g. to drive JGA16-050, a H-Bridge Motor Driver is needed



Wired and Wireless Communications

WIRED and WIRELESS

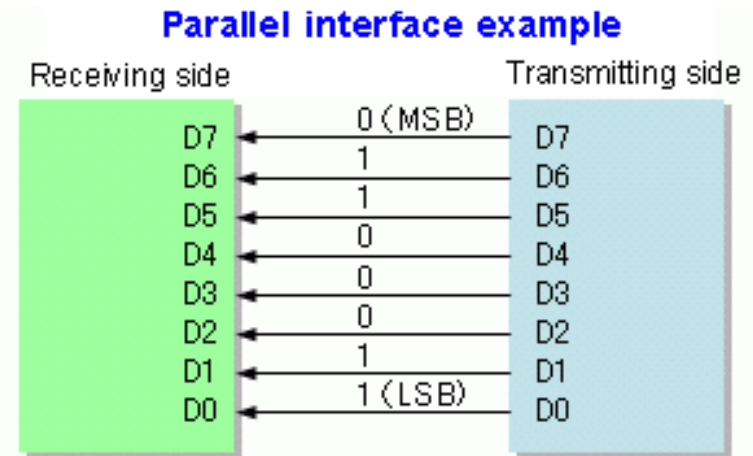
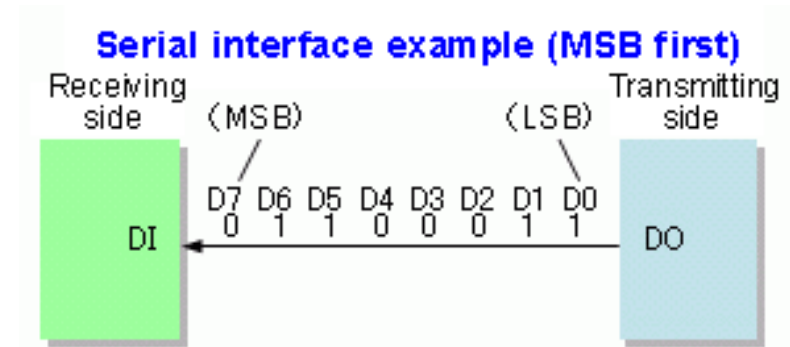
- Communications between units via a medium
- **Wired Communication**: Transfer of information between two or more points that are connected by an electrical conductor (wire)
- **Wireless Communication**: not via any physical wire



WIRED COMMUNICATION

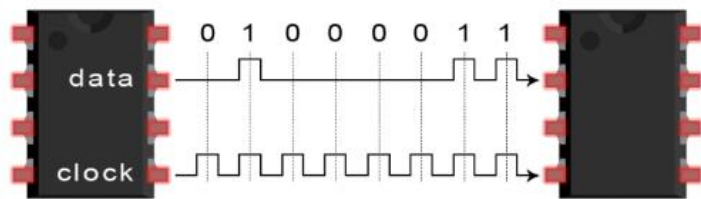
Serial and Parallel Communication

- Data in bytes (1 byte = 8 bits)
- Serial communication
 - Disadv: Bits are sent one by one (eg. 8 bits need 8 cycles), hence slow
 - Adv: Require very few pins (wires) for communications
- Parallel communication
 - Adv: Several bits (eg. a word of 8 bits) are sent in one cycle, hence fast
 - Disadv: Require many pins/wires

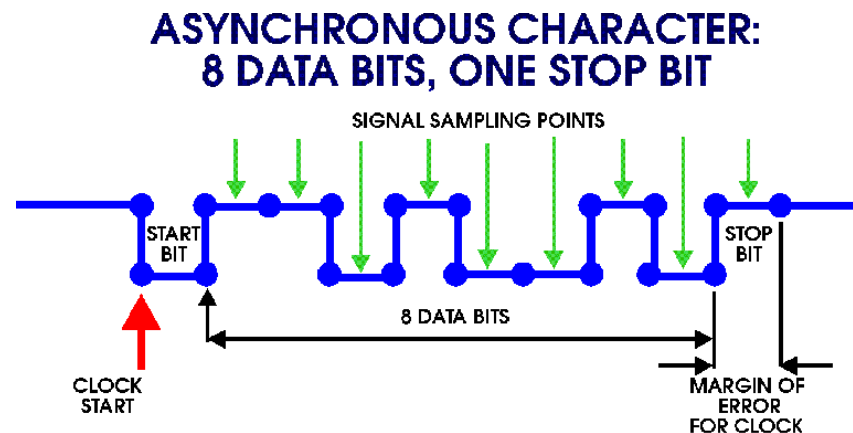


Synchronous and Asynchronous

- Serial port interface
 - Synchronous:
 - A **clock to synchronize** between transmitter and receiver so that the receiver can receive the data correctly.
 - Asynchronous:
 - No synchronous clock
 - **Start and stop bits** in the data packet being transferred to define the beginning and end of the data packet. With such, the receiver can know when to start reading the bits.

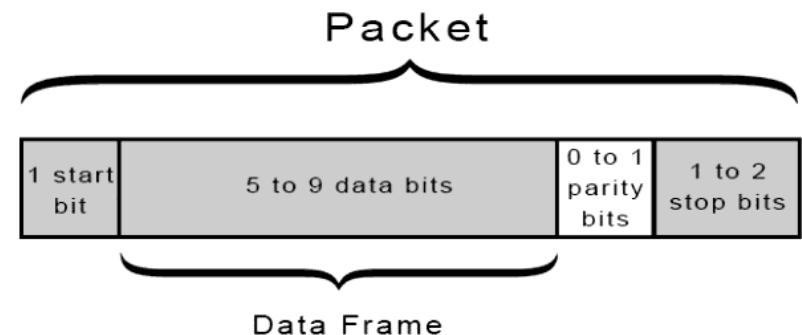
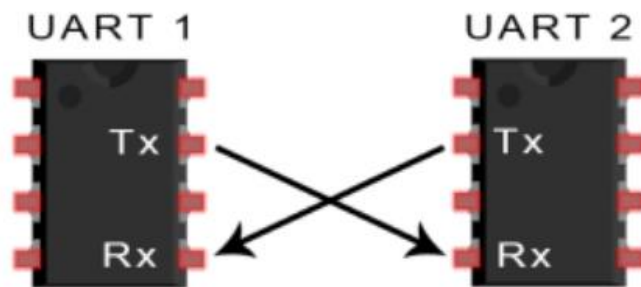


Synchronous



UART

- UART: Universal Asynchronous Receiver/Transmitter
- A kind of serial communications (Very commonly used)
- General flow:
 - 2 UARTs: one acts as transmitter and one is receiver
 - Transmitter: Data (in bytes) is firstly converted into a serial form (bits), then transmitted one by one at Tx pin.
 - Receiver: After received the serial data one-by-one from Rx pin, the receiver converts the serial data back as byte.



Serial Communication

- Useful for communicating with PC
- Connecting micro:bit to your PC using an USB cable, communications can be established (Note: not only doing programming).
- Based on Serial Communications (wired)

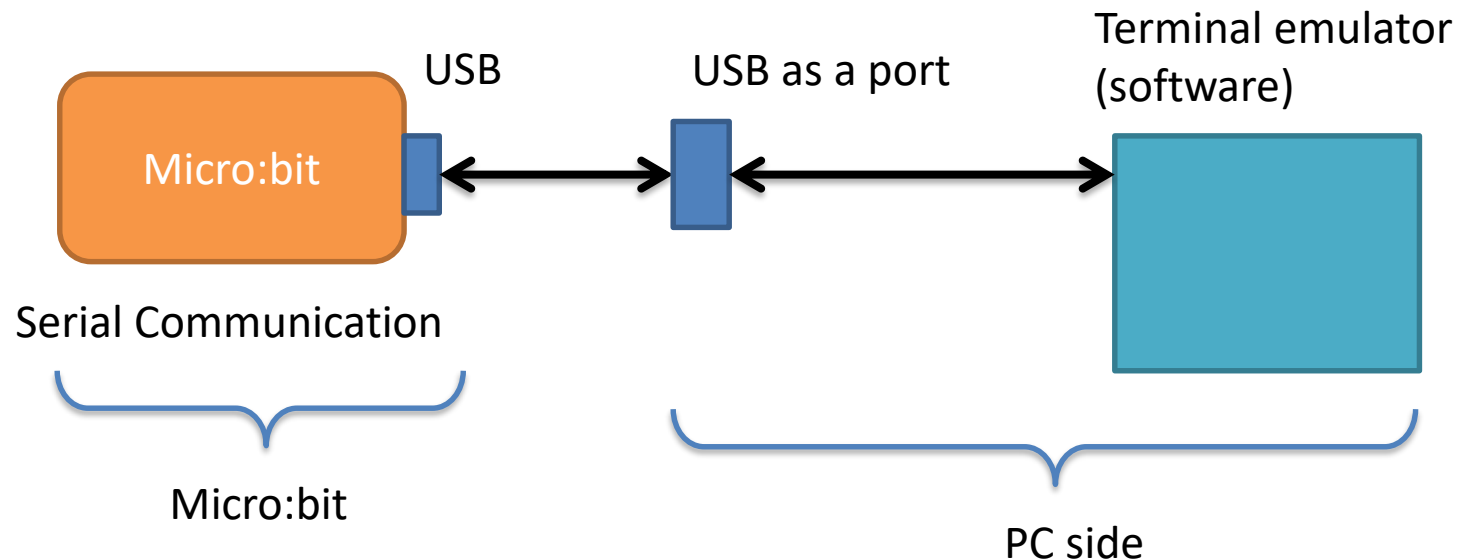


What is Needed?

- A terminal emulator is needed at PC side to communicate via the port
 - Putty, See <https://www.putty.org/>
 - CoolTerm, download from <http://freeware.the-meiers.org/> (we demonstrate this one).

Data Flow Diagram

- Data flow:
 - Terminal -> USB port -> Micro:bit **or**
Micro:bit -> USB port -> Terminal
- What are needed?
 - Program the micro:bit
 - Configure terminal emulator and the USB port



WIRELESS COMMUNICATION (BUILT-IN: RADIO COMMUNICATION)

Example of Wireless Communication

