Tutorial	CS3103	Operating Systems	Student Name:							
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Deadlocks

Introduction

Topics to be covered in this tutorial include:

- Explore some real code that deadlocks (or avoids deadlock).
- The different versions of code correspond to different approaches to avoiding deadlock in a simplified vector_add() routine.

Acknowledgement

This tutorial was adapted from OSTEP book written by Remzi and Andrea Arpaci-Dusseau at the University of Wisconsin. This free OS book is available at http://www.ostep.org.

Getting Started

1. Logging in to the Linux server

- Start the SSH client, e.g., MobaXterm or Xshell.
- Log in to the Linux server using the following details:

Host Name: gateway.cs.cityu.edu.hk
User Name: your EID (e.g., cctom2)

as you type it, not even as a row of stars (******).

Password: your password

NOTE: The shell will always give you a prompt if it is ready to accept commands. The shell prompt normally ends in a \$ sign as we use in this tutorial. Some shell prompts end in % or > instead. Never copy/type the shell prompt used in this tutorial.

NOTE: Please don't forget to log out (use the exit command) after you finish your work.

2. Getting the real code

This tutorial lets you play around with a number of ways to implement a small, deadlock-free vector object in C. The vector object is quite limited (e.g., it only has add() and init() functions) but is just used to illustrate different approaches to avoiding deadlock.

Start by copying the codes to a directory in which you plan to do your work. For example, to copy *tutorial5* directory and its contents (10 files) to your current directory and change to it, enter:

```
$ cp -rf /public/cs3103/tutorial5 .
$ cd tutorial5
```

The last dot/period (.) indicates the current directory as destination.

Introduction of the code

Some files that you should pay attention to are as follows. They, in particular, are used by all the variants in this tutorial.

mythreads.h

The usual wrappers around many different pthread (and other) library calls, so as to ensure they are not failing silently.

vector-header.h

A simple header for the vector routines, mostly defining a fixed vector size and then a struct that is used per vector (vector t).

main-header.h

A number of global variables common to each different program.

main-common.c

Contains the main() routine (with arguments parsing) that initializes two vectors, starts some threads to access them (via a worker() routine), and then waits for the many vector_add()'s to complete.

The variants of this tutorial are found in the following files. Each takes a different approach to dealing with concurrency inside a "vector addition" routine called vector_add(); examine the code in these files to get a sense of what is going on. They all use the files above to make a complete runnable program.

vector-deadlock.c

This version blithely grabs the locks in a particular order (dst then src). By doing so, it creates an "invitation to deadlock", as one thread might call vector_add(v1, v2) while another concurrently calls vector add(v2, v1).

vector-global-order.c

This version of vector add() grabs the locks in a total order, based on address of the vector.

vector-try-wait.c

This version of vector_add() uses pthread_mutex_trylock() to attempt to grab locks; when the try fails, the code releases any locks it may hold and goes back to the top and tries it all over again.

vector-avoid-hold-and-wait.c

This version of vector_add() ensures it can't get stuck in a hold and wait pattern by using a single lock around lock acquisition.

vector-nolock.c

This version of vector_add() doesn't even use locks; rather, it uses an atomic fetch-and-add to implement the vector add() routine. Its semantics (as a result) are slightly different.

Type "make" (and read the Makefile) to build each of five executables.

\$ make

Then you can run a program by simply typing its name:

\$./vector-deadlock

Each program takes the same set of arguments (see main-common.c for details):

```
This flag turns on the ability for threads to deadlock.

When you pass -d to the program, every other thread calls vector_add() with the vectors in a different order, e.g., with two threads, and -d enabled, Thread 0 calls vector_add(v1, v2) and Thread 1 calls vector_add(v2, v1)

-p

This flag gives each thread a different set of vectors to call add() upon, instead of just two vectors. Use this to see how things perform when there isn't contention for the same set of vectors.

-n num_threads

Creates some number of threads; you need more than one to deadlock.

-1 loops

How many times should each thread call vector_add()?

-t

Turns on timing and shows how long everything took.
```

Questions

All questions should be answered on the separate answer sheet provided.

- 1. First let's make sure you understand how the programs generally work, and some of the key options. Study the code in vector-deadlock.c, as well as in main-common.c and related files. Now, run./vector-deadlock.d -n 2 -l 1 -t, which instantiates two threads (-n 2), each of which does one vector add (-l 1). Change the number of loops (-l) from 1 to higher numbers. What happens? Does the code (always) deadlock?
- 2. How does changing the number of threads (-n) change the outcome of the program? Are there any values of -n that ensure no deadlock occurs?
- 3. Now examine the code in vector-global-order.c. First, make sure you understand what the code is trying to do; do you understand why the code avoids deadlock? Also, why is there a special case in this vector_add() routine when the source and destination vectors are the same?
- 4. Now run the code with the following flags: -t -n 2 -1 100000 -d. How long does the code take to complete? How does the total time change when you increase the number of loops, or the number of threads?
- 5. What happens if you turn on the parallelism flag (-p)? How much would you expect performance to change when each thread is working on adding different vectors (which is what -p enables) versus working on the same ones?
- 6. Now let's study vector-try-wait.c. First make sure you understand the code. Is the first call to pthread_mutex_trylock() really needed? Now run the code. How fast does it run compared to the global order approach? How does the number of retries, as counted by the code, change as the number of threads increases?
- 7. Now let's look at vector-avoid-hold-and-wait.c. What is the main problem with this approach? How does its performance compare to the other versions, when running both with -p and without it?
- 8. Finally, let's look at vector-nolock.c. This version doesn't use locks at all; does it provide the exact same semantics as the other versions? Why or why not?
- 9. Now compare its performance to the other versions, both when threads are working on the same two vectors (no -p) and when each thread is working on separate vectors (-p). How does this no-lock version perform?