

## Solution

1.(a)

Taking the DTFT on both sides yields

$$Y(e^{j\omega}) (1 - ae^{-j\omega}) = X(e^{j\omega}) \left(1 - \frac{1}{a}e^{-j\omega}\right) \Rightarrow H(e^{j\omega}) = \frac{1 - \frac{1}{a}e^{-j\omega}}{1 - ae^{-j\omega}}$$

1.(b)

$$\begin{aligned} |H(e^{j\omega})|^2 &= H(e^{j\omega})H^*(e^{j\omega}) = \frac{1 - \frac{1}{a}e^{-j\omega}}{1 - ae^{-j\omega}} \cdot \frac{1 - \frac{1}{a}e^{j\omega}}{1 - ae^{j\omega}} = \frac{1 + \frac{1}{a^2} - \frac{2}{a}\cos(\omega)}{1 + a^2 - 2a\cos(\omega)} \\ &= \frac{1}{a^2} \end{aligned}$$

Hence we have:

$$|H(e^{j\omega})| = \frac{1}{|a|}$$

2.(a)

The impulse response is **not** a finite-duration sequence.

2.(b)

The system is **not causal**. It is because  $h[n] \neq 0$  for  $n < 0$ .

2.(c)

The system is **not stable**. It is because  $\sum_{n=-\infty}^{\infty} |h[n]| \rightarrow \infty$ .

2.(d)

By making use of

$$a^n u[-n-1] \leftrightarrow -\frac{1}{1-az^{-1}}, \quad |z| < |a|$$

and the time-shifting property, we get

$$(0.5)(0.5)^{n-1}u[-n] \leftrightarrow -\frac{0.5z^{-1}}{1 - 0.5z^{-1}}, \quad |z| < 0.5$$

2.(e)

$$H(z) = \frac{1}{1 - 2z}$$

Hence there is no zero but only one pole at  $z = 0.5$ .

2.(f)

$$\begin{aligned} H(z) &= \frac{Y(z)}{X(z)} = -\frac{0.5z^{-1}}{1 - 0.5z^{-1}} \\ \Rightarrow Y(z) (1 - 0.5z^{-1}) &= -0.5z^{-1}X(z) \\ \Rightarrow y[n] - 0.5y[n-1] &= -0.5x[n-1] \end{aligned}$$

2.(g)

The  $z$  transform of  $x[n] = \delta[n] - 0.5\delta[n - 1]$  is:

$$X(z) = 1 - 0.5z^{-1}, \quad |z| > 0$$

Hence  $Y(z)$  is:

$$Y(z) = H(z)X(z) = -0.5z^{-1}, \quad |z| > 0$$

$$\Rightarrow y[n] = -0.5\delta[n - 1]$$

3.

$$H(z) = \frac{3 + 3z^{-1}}{1 + 2.5z^{-1} + z^{-2}} = \frac{3z(z + 1)}{(z + 0.5)(z + 2)} = \frac{1}{1 + 0.5z^{-1}} + \frac{2}{1 + 2z^{-1}}$$

Since the system is stable, its ROC must include the unit circle and hence it is  $0.5 < |z| < 2$ . Hence  $h[n]$  is:

$$h[n] = (-0.5)^n u[n] - 2(-2)^n u[-n - 1]$$

4.(a)

There are only two frequency components in  $x(t)$ : 100 and 200. Apparently, the fundamental frequency is 100.

4.(b)

According to sampling theorem, the sampling frequency must exceed 400 (or  $200/\pi$  in Hz).

4.(c)

$$x[n] = x(t)|_{t=nT} = \sin(5n + 1) + 2 \cos(10n + 2)$$

4.(d)

$x[n]$  is not periodic as there is no integer  $N$  which satisfies  $x[n] = x[n + N]$ .

5.

Since the system is **causal**, the ROC should be  $|z| > |a_0|$ . As a result, the impulse response of the system is:

$$h[n] = b_0(-a_0)^n u[n] + b_1 \delta[n]$$

When the input is  $x[n] = \delta[n]$ ,  $y[n] = h[n]$ . Hence we have the following equations:

$$y[0] = b_0 + b_1 = 4$$

$$y[1] = b_0(-a_0) = -a_0 b_0 = 3$$

$$y[2] = b_0(-a_0)^2 = a_0^2 b_0 = 2$$

From the last two equations, we get

$$a_0 = -\frac{2}{3}$$

$$b_0 = 4.5$$

From the first equation, we then get

$$b_1 = -0.5$$



## 6. Investigating

$$x[n] = (0.5)^{3n}u[3n - 3]$$

for different  $n$ :

$$x[0] = 0$$

$$x[1] = (0.5)^3 = 0.125$$

$$x[2] = (0.5)^6 = (0.125)^2$$

Hence we can re-express  $x[n]$  as:

$$x[n] = \begin{cases} 0, & n \leq 0 \\ (0.125)^n, & n \geq 1 \end{cases}$$

Taking  $z$  transform on  $x[n]$ , we have:

$$\begin{aligned} X(z) &= \sum_{n=1}^{\infty} (0.125z^{-1})^n, \quad |0.125z^{-1}| < 1 \Rightarrow |z| > 0.125 \\ &= \frac{0.125z^{-1}}{1 - 0.125z^{-1}} \end{aligned}$$

The ROC is  $|z| > 0.125$ .