# 3. Data link layer

- \* reliable data transfer
  - peer-to-peer protocols
  - error detection
  - Automatic Repeat Request (ARQ)
  - flow control
- \* data link control
  - framing
  - point-to-point protocol (PPP)
  - high-level data link control (HDLC)

application

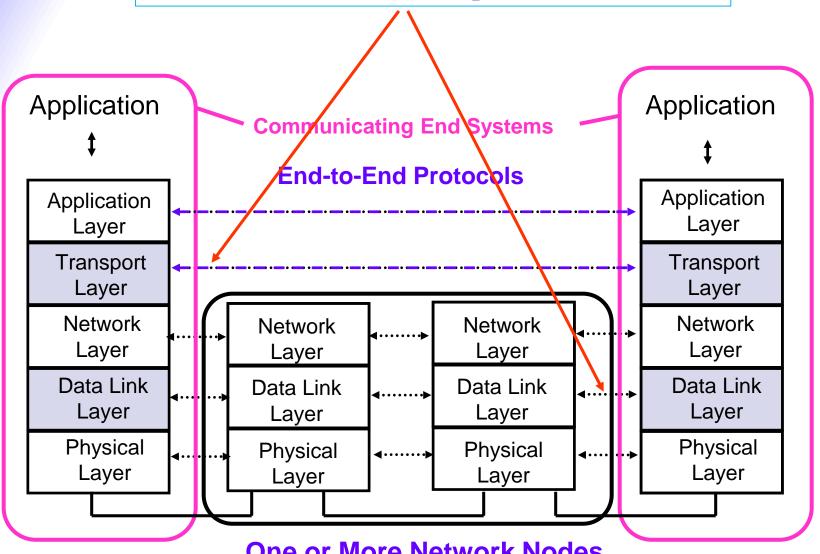
transport

network

link

physical

# Peer-to-Peer protocols



**One or More Network Nodes** 

• each layer provides a service to the layer above

• executes a peer-to-peer protocol that uses the services of the layer below

• how a protocol layer provides a reliable data transfer service across unreliable networks

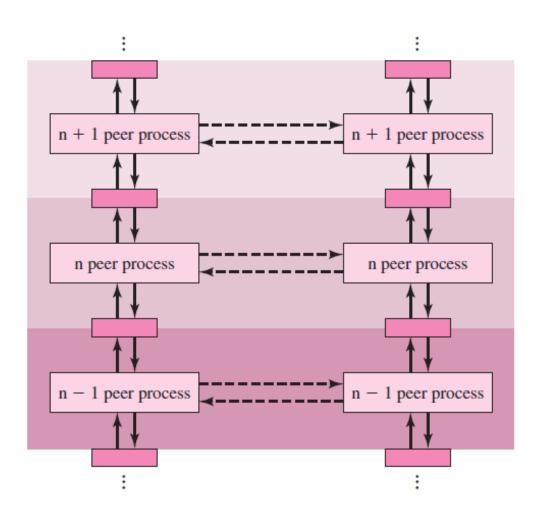
what data link layer protocols can be used

# 3.1 Peer-to-peer protocols

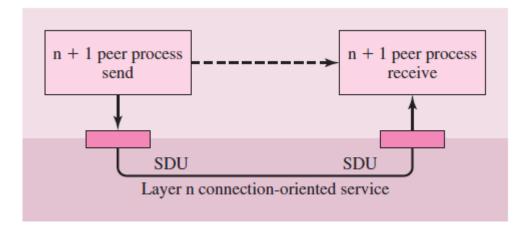
- layer *n*+1 requests a transfer of a service data unit (SDU)
- layer *n* peer processes construct protocol data units (PDUs)

Transport layer PDU is segment

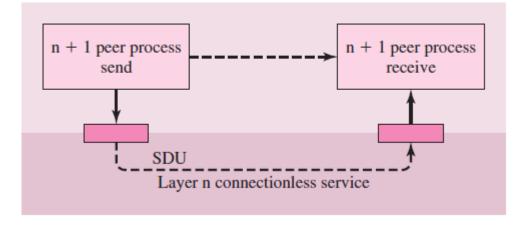
- layer n protocol uses the services of layer n-1
- peer-to-peer protocol involves the interaction of two or more processes or entities through the exchange of messages (PDUs)
- SDU is delivered to the destination layer n+1



#### Two categories of service models



State information



Self-contained information, no acknowledgment

#### Examples of services:

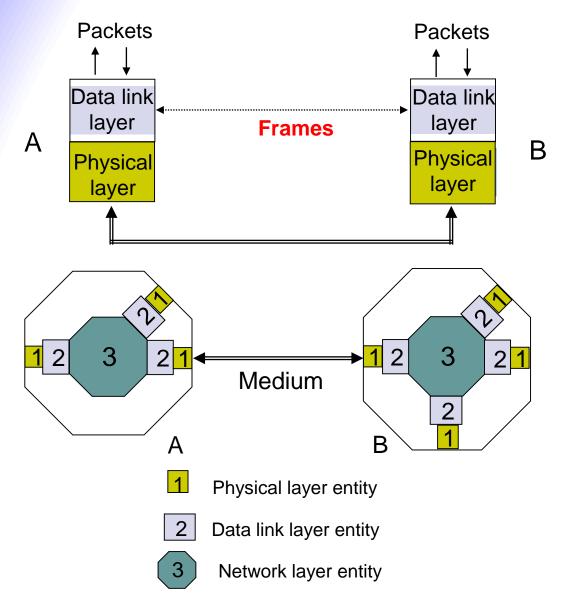
- *reliability*: are messages or information stream delivered error-free and without loss or duplication?
- sequencing: are messages or information stream delivered in order?
- how does a peer-to-peer protocol provide the service?
- you will learn some examples
- ARQ protocols combine error detection, retransmission, and sequence numbering to provide reliability & sequencing
- flow control Transmission Control Protocol (TCP)
- data link layer protocol High-Level Data Link Control (HDLC)

With error-detection, automatic retransmission, and sequence numbering, it is possible to obtain protocols that can provide reliable and sequenced communication service over unreliable networks.

# 2 basic settings: End-to-End vs. Hop-by-Hop

- A service feature can be provided by implementing a protocol
  - end-to-end across the network
  - across every hop in the network
- Example:
  - perform error control at every hop in the network or only between the source and destination
  - perform flow control between every hop in the network or only between source & destination
- consider the tradeoffs between the two approaches ...

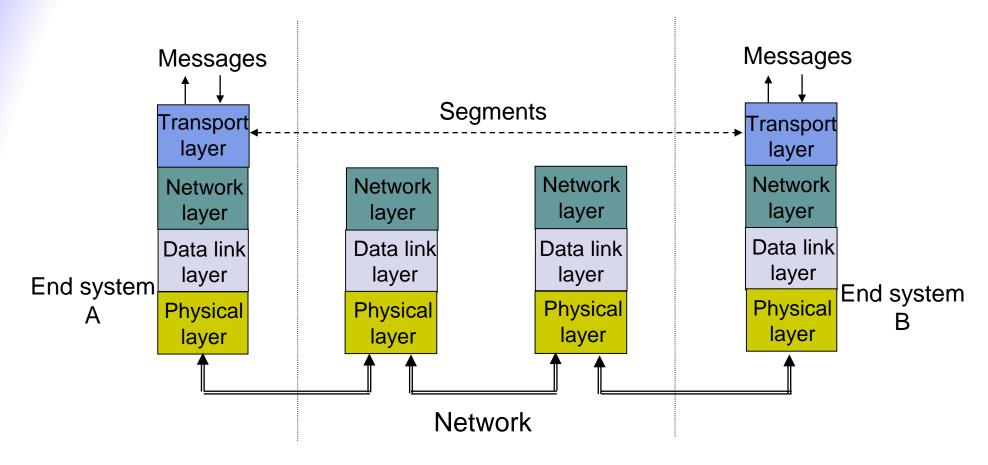
### **Error control in Data Link Layer**



- Data link operates over wire-like, directlyconnected systems
- Frames can be corrupted or lost, but arrive in order
- Data link performs error-checking & retransmission
- Ensures error-free packet transfer between two systems

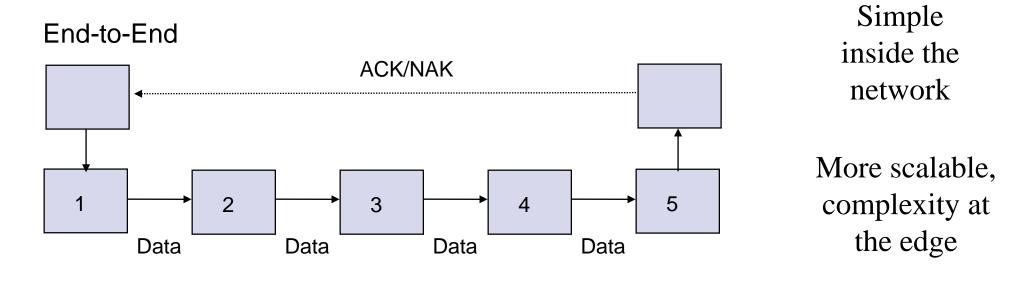
#### **Error control in Transport Layer**

- Transport layer protocol (e.g. TCP) sends segments across network and performs end-to-end error checking & retransmission
- Underlying network is assumed to be unreliable



Segments can experience long delays, can be lost, or arrive out-of-order because packets can follow different paths across network End-to-End error control protocol C more difficult **End System** End System 3 Medium Network Network layer entity Transport layer entity

#### Hop-by-Hop Faster recovery Data Data Data Data 2 3 4 5 ACK/ ACK/ ACK/ ACK/ NAK NAK NAK NAK



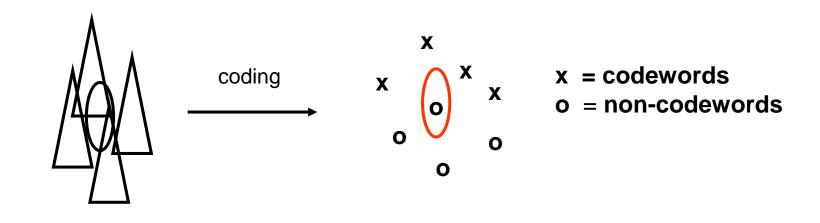
#### 3.2 Error detection

- digital transmission systems introduce errors depend on physical media
- applications require certain reliability level bit error rate acceptability
  - data applications require error-free transfer
  - voice & video applications tolerate some errors
- error control used when transmission system does *not* meet application requirement
- error control ensures a data stream is transmitted to a certain level of accuracy despite errors
- two basic approaches:
  - error detection & ARQ (with return channel, waste bandwidth)
  - error detection & forward error *correction* (FEC) (no return channel or inefficient to retransmit, need more redundancy, not covered in this course)

- all transmitted data blocks ("codewords") satisfy a pattern
- if received block doesn't satisfy pattern, it is in error

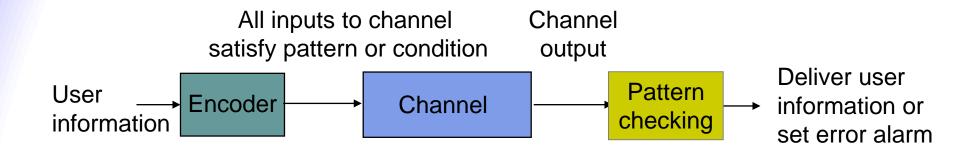
2-bit data blocks

• redundancy: only a subset of all possible blocks can be codewords, e.g. data block length = 2 bits, 1 bit redundancy



2-bit data, 1 bit redundancy

blindspot: when channel transforms a codeword into another codeword



#### 3.2.1 single parity check code

• append an overall parity check to *k* information bits

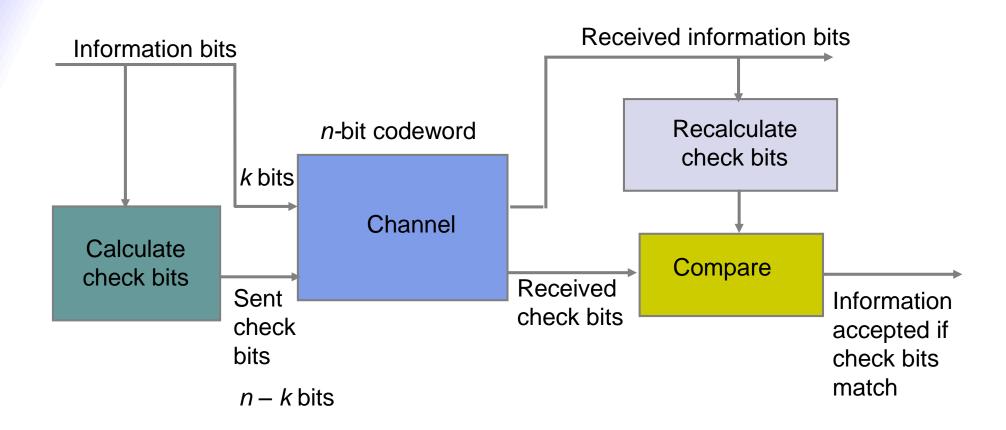
information bits: 
$$b_1, b_2, b_3, ..., b_k$$
  
check bit:  $b_{k+1} = b_1 + b_2 + b_3 + ... + b_k$  modulo 2  
codeword:  $(b_1, b_2, b_3, ..., b_k, b_{k+1})$ 

- all codewords have even number of 1s
- receiver checks to see if number of 1s is even
  - all error patterns that change an odd number of 1s are detectable
  - all error patterns with even number of 1s are *undetectable*
- example: ASCII code (7 bits for character + 1 parity bit)

#### Example

- information (7 bits): (0, 1, 0, 1, 1, 0, 0)
- parity bit:  $b_8 = 0 + 1 + 0 + 1 + 1 + 0 + 0 = 1$
- codeword (8 bits): (0, 1, 0, 1, 1, 0, 0, 1)
- if single error in bit 3: (0, 1, 1, 1, 1, 0, 0, 1)
  - number of 1s = 5, odd
  - error detected
- if errors in bits 3 and 5: (0, 1, 1, 1, 0, 0, 0, 1)
  - number of 1s = 4, even
  - error not detected

# **Error Detection System**



# How good is the single parity check code?

- Redundancy: single parity check code adds 1 redundant bit per k information bits, overhead = 1/(k+1)
- Coverage: all error patterns with odd number of errors can be detected
  - an error pattern is a binary (k + 1)-tuple with 1s where errors occur and 0's elsewhere
  - of  $2^{k+1}$  binary (k+1)-tuples, ½ are odd, so 50% of error patterns can be detected
- Is it possible to detect more errors if we add more check bits?
- Yes, with the right codes

- many transmission channels introduce bit errors at random, independently of each other, and with probability *p*
- some error patterns are more probable than others

$$P[10000000] = p(1-p)^7 = (1-p)^8 \left(\frac{p}{1-p}\right)$$
 and 
$$P[11000000] = p^2(1-p)^6 = (1-p)^8 \left(\frac{p}{1-p}\right)^2$$

- in any worthwhile channel p < 0.5, and so (p/(1-p)) < 1
- it follows that patterns with 1 error are more likely than patterns with 2 errors and so forth
- What is the probability that an undetectable error pattern occurs?

• undetectable error pattern if even number of bit errors:

P[error detection failure] = P[undetectable error pattern]= P[error patterns with even number of 1s]

$$= \binom{n}{2} p^2 (1-p)^{n-2} + \binom{n}{4} p^4 (1-p)^{n-4} + \dots$$

• example: evaluate above for n = 32,  $p = 10^{-3}$ 

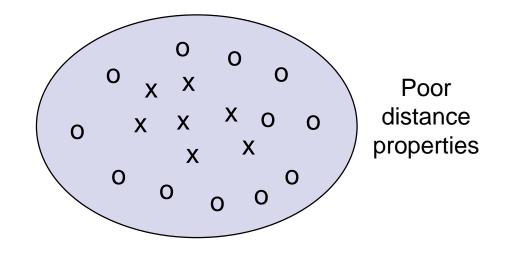
$$P[\text{undetectable error}] = {32 \choose 2} (10^{-3})^2 (1 - 10^{-3})^{30} + {32 \choose 4} (10^{-3})^4 (1 - 10^{-3})^{28} + \dots$$

$$\approx 496 (10^{-6}) + 35960 (10^{-12}) \approx 4.96 (10^{-4})$$

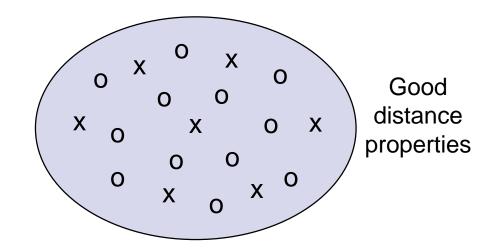
• roughly 1 in 2000 error patterns is undetectable

# What is a good code?

- many channels have preference for error patterns that have fewer number of errors
- these error patterns map transmitted codeword to nearby *n*-tuple
- if codewords close to each other then detection failures will occur
- good codes should maximize separation between codewords



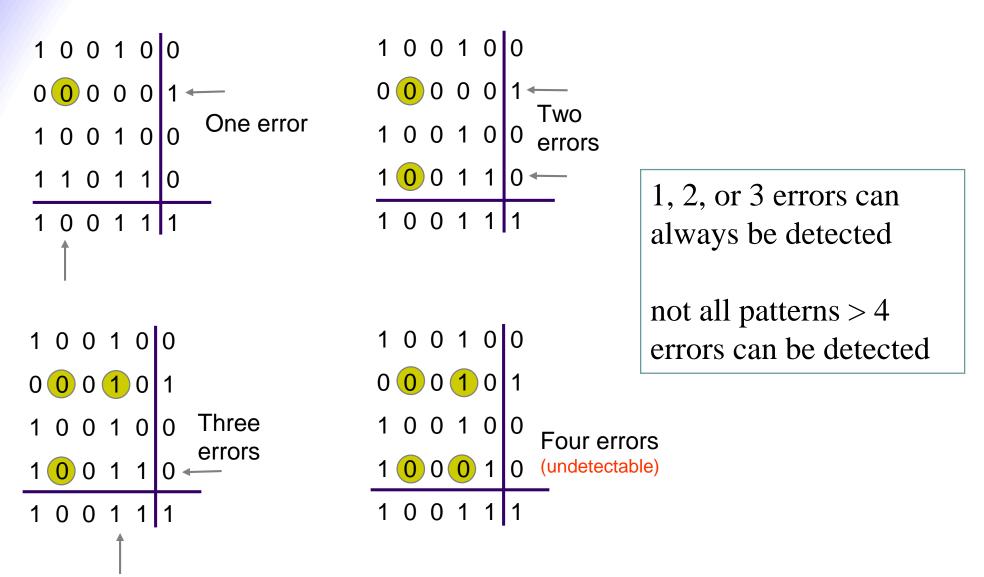
x = codewords
o = non-codewords



#### 3.2.2 two-dimensional parity check

- more parity bits to improve coverage
- arrange information as columns
- add single parity bit to each column
- add a final "parity" column
- used in early error control systems

Bottom row consists of check bit for each column

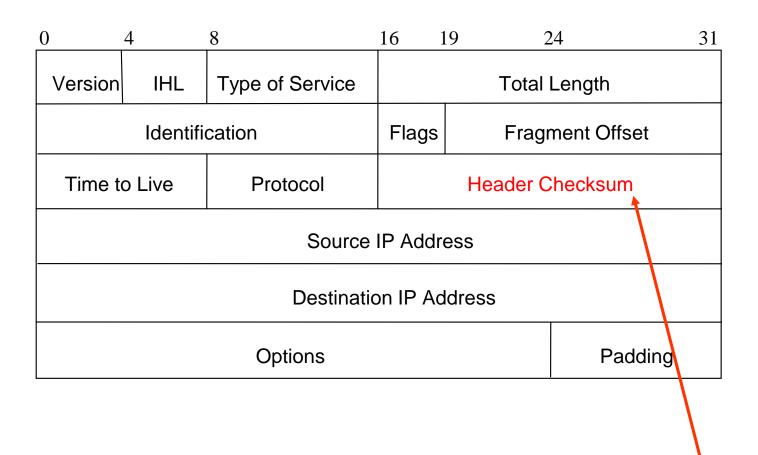


Arrows indicate failed check bits

- many applications require very low error rate
- need codes that detect the vast majority of errors
- single parity check codes do not detect enough errors
- two-dimensional parity check codes require too many check bits
- the following error detecting codes used in practice:
  - Internet checksum
  - polynomial codes also called cyclic redundancy check (CRC)

#### 3.2.3 Internet checksum

used in some Internet protocols, e.g. TCP, IP, ...



how to calculate this?

- IP header uses check bits to detect errors in the *header*
- a checksum is calculated for header contents
- checksum recalculated at every router, so algorithm selected for ease of implementation in software
- let header consists of L 16-bit words,  $\mathbf{b}_0$ ,  $\mathbf{b}_1$ ,  $\mathbf{b}_2$ , ...,  $\mathbf{b}_{L-1}$
- the algorithm appends a 16-bit *checksum*  $\mathbf{b}_{L}$
- for each received header, the router calculate

$$0 = \mathbf{b}_0 + \mathbf{b}_1 + \mathbf{b}_2 + \mathbf{b}_{L-1} + \mathbf{b}_L \text{ modulo } 2^{16} - 1$$

# **Example**

For simplicity, assuming 4-bit words

#### Use modulo arithmetic

- use modulo 2<sup>4</sup>-1 arithmetic
- $\underline{b}_0 = 1100 = 12$
- $\underline{b}_1 = 1010 = 10$
- $\underline{b}_0 + \underline{b}_1 = 12 + 10 = 22$
- 22 modulo 15 = 7
- $\underline{b}_2 = -7 = 8 \mod 15$
- checksum  $b_2 = 1000$

#### Use binary arithmetic

- $16 = 1 \mod 15$
- 10000 = 0001 modulo 15
- leading bit wraps around

$$b_0 + b_1 = 1100 + 1010$$
  
= 10110  
= 10000 + 0110  
= 0001 + 0110  
= 0111  
= 7

Take 1s complement  $b_2 = -0111 = 1000$ 

#### 3.2.4 polynomial codes

- polynomials instead of vectors for codewords
- polynomial arithmetic instead of checksum
- implemented using shift-register circuits
- most data communication standards use polynomial codes for error detection
- polynomial code is also basis for powerful error-correction methods

# Binary polynomial arithmetic

binary vectors map to polynomials

$$(i_{k-1}, i_{k-2}, \dots, i_2, i_1, i_0) \rightarrow i_{k-1}x^{k-1} + i_{k-2}x^{k-2} + \dots + i_2x^2 + i_1x + i_0$$

addition:

$$(x^7 + x^6 + 1) + (x^6 + x^5) = x^7 + x^6 + x^6 + x^5 + 1$$
  
=  $x^7 + (1+1)x^6 + x^5 + 1$   
=  $x^7 + x^5 + 1$  since  $1+1=0$  modulo 2

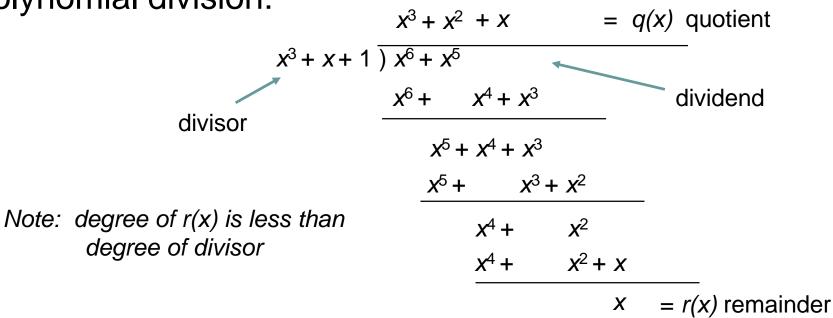
multiplication:

$$(x+1) (x^2 + x + 1) = x(x^2 + x + 1) + 1(x^2 + x + 1)$$
$$= (x^3 + x^2 + x) + (x^2 + x + 1)$$
$$= x^3 + 1$$

#### division with decimal numbers:

divisor 
$$\frac{34}{35}$$
 quotient dividend = quotient x divisor + remainder  $\frac{35}{105}$   $\frac{105}{172}$  dividend  $\frac{105}{140}$  remainder

#### polynomial division:



### **Polynomial coding**

• code has binary generator polynomial of degree n - k

$$g(x) = x^{n-k} + g_{n-k-1}x^{n-k-1} + \dots + g_2x^2 + g_1x + 1$$

• k information bits define polynomial of degree k-1

$$i(x) = i_{k-1}x^{k-1} + i_{k-2}x^{k-2} + \dots + i_2x^2 + i_1x + i_0$$

• find remainder polynomial of at most degree n - k - 1

$$g(x) \overline{) x^{n-k} i(x)}$$

$$x^{n-k} i(x) = q(x)g(x) + r(x)$$

$$r(x)$$

• define the *codeword polynomial* of degree n-1

$$b(x) = x^{n-k}i(x) + r(x)$$
n bits

k bits

n-k bits

# Example: k = 4, n - k = 3

generator polynomial:  $g(x)=x^3+x+1$ information: (1,1,0,0)  $i(x)=x^3+x^2$ encoding:  $x^3i(x)=x^6+x^5$ 

transmitted codeword:

$$b(x) = x^6 + x^5 + x$$

$$b = (1,1,0,0,0,1,0)$$

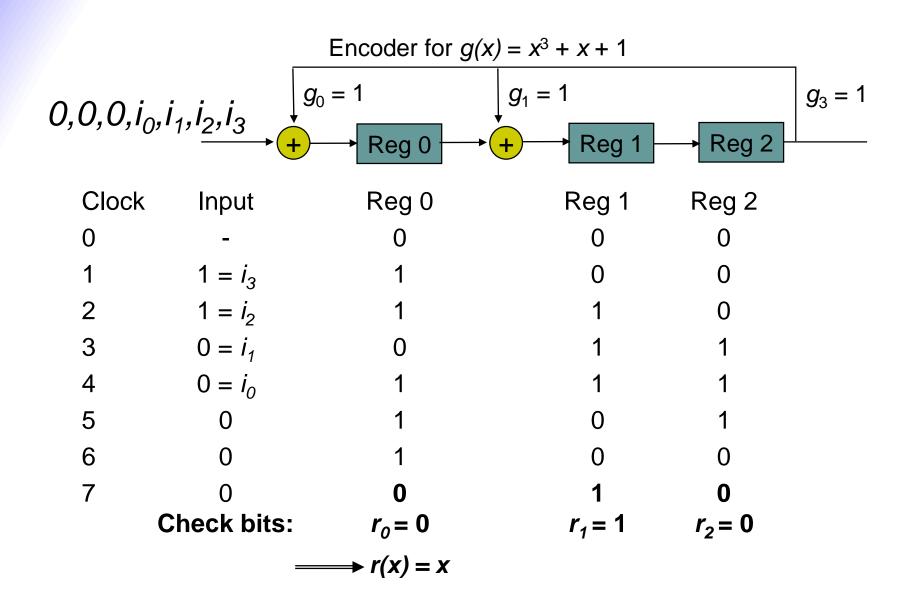
• all codewords satisfy the following **pattern**:

$$b(x) = x^{n-k}i(x) + r(x) = q(x)g(x) + r(x) + r(x) = q(x)g(x)$$

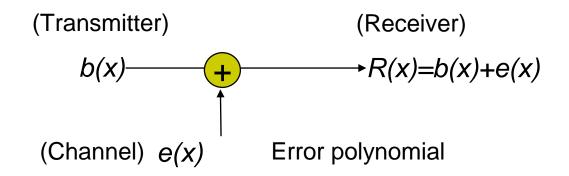
- all codewords are a multiple of g(x)!
- receiver should divide received n-tuple by g(x) and check if remainder is zero
- if remainder is non-zero, then received *n*-tuple is not a codeword

# **Implementation**

- 1. accept information bits  $i_{k-1}, i_{k-2}, ..., i_2, i_1, i_0$
- 2. append n k zeros to information bits
- 3. feed sequence to shift-register circuit that performs polynomial division
- 4. after *n* shifts, the shift register contains the remainder



## Undetectable error patterns



- e(x) has 1s in error locations & 0s elsewhere
- receiver divides the received polynomial R(x) by g(x)
- blindspot: if e(x) is a multiple of g(x), that is, e(x) is a non-zero codeword, then

$$R(x) = b(x) + e(x) = q(x)g(x) + q'(x)g(x)$$

- the set of undetectable error polynomials is the set of non-zero code polynomials
- choose the generator polynomial so that selected error patterns can be detected

## Designing good polynomial codes

- select generator polynomial so that likely error patterns are not multiples of g(x)
- detecting single errors
  - $e(x) = x^i$  for error in location i + 1
  - if g(x) has more than 1 term, it cannot divide  $x^i$
- detecting double errors
  - $e(x) = x^i + x^j = x^i(x^{j-i}+1)$  where j > i
  - if g(x) has more than 1 term, it cannot divide  $x^i$
  - if g(x) is a primitive polynomial, it cannot divide  $x^m + 1$  for all  $m < 2^{n-k} 1$  (need to keep codeword length less than  $2^{n-k} 1$ )
  - primitive polynomials can be found by consulting coding theory books

- detecting odd number of errors
  - for odd number of errors, e(x) evaluated at x = 1 is 1, therefore (x + 1) is not a factor of e(x)
  - suppose all codeword polynomials have an even number of 1s, b(x) evaluated at x = 1 is zero because b(x) has an even number of 1s
  - this implies x + 1 must be a factor of all b(x)
  - pick g(x) = (x + 1) p(x) where p(x) is primitive

## Standard generator polynomials

$$= x^8 + x^2 + x + 1$$

$$= x^{16} + x^{15} + x^2 + 1$$
  
=  $(x + 1)(x^{15} + x + 1)$ 

$$= x^{16} + x^{12} + x^5 + 1$$

$$= X^{32} + X^{26} + X^{23} + X^{22} + X^{16} + X^{12} + X^{11} + X^{10} + X^{8} + X^{7} + X^{5} + X^{4} + X^{2} + X + 1$$

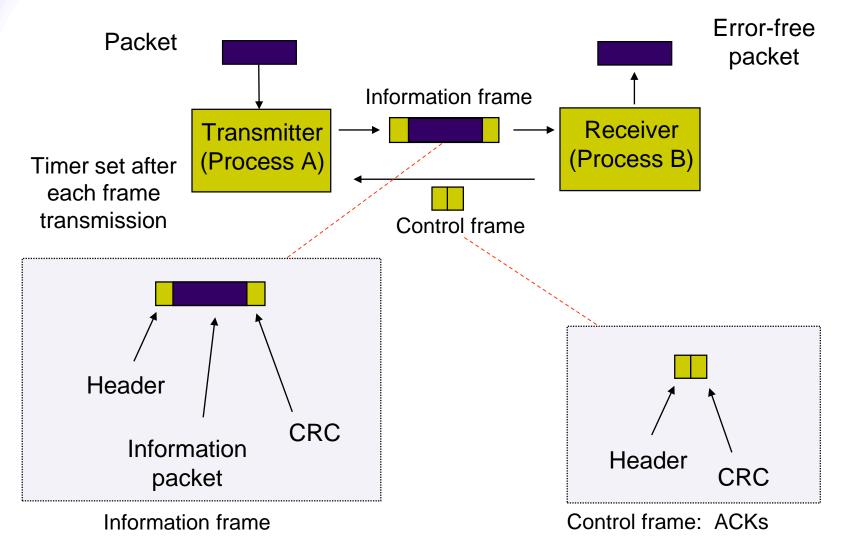
## 3.3 Automatic Repeat Request (ARQ)

#### Purpose:

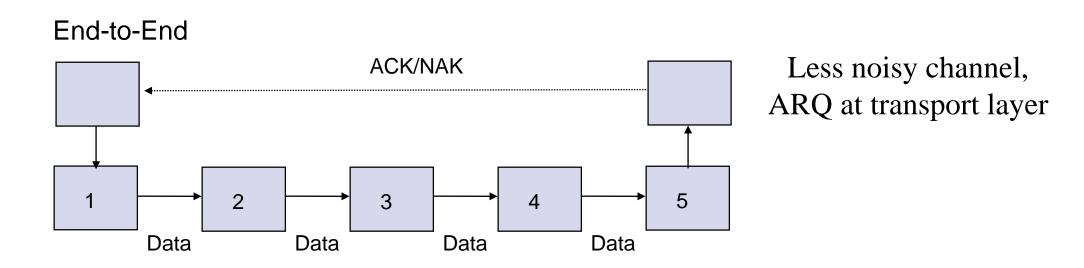
to ensure a sequence of information packets is delivered in order and without errors or duplications despite transmission errors and losses

- We will look at:
  - Stop-and-Wait ARQ
  - Go-Back N ARQ
  - Selective Repeat ARQ
- Basic elements of ARQ:
  - error-detecting code with high error coverage
  - ACKs (positive acknowledgments)
  - NAKs (negative acknowledgments)
  - timeout mechanism, and ....

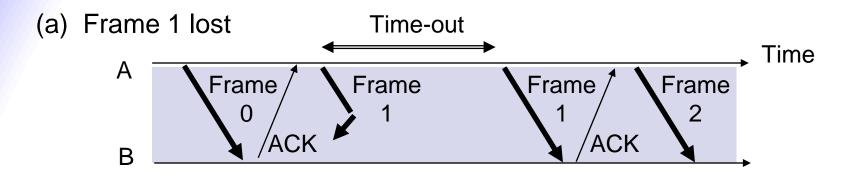
### Transmit a frame, wait for ACK

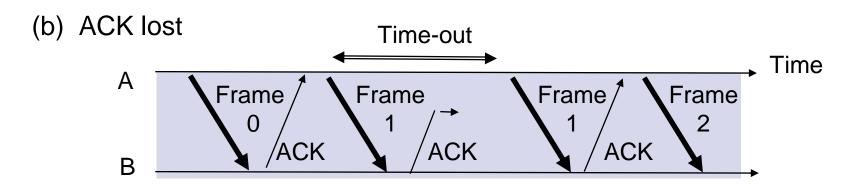


#### Hop-by-Hop Data Data Data Data Noisy channel, 2 3 4 5 ARQ across each ACK/ ACK/ ACK/ ACK/ NAK NAK NAK NAK single hop



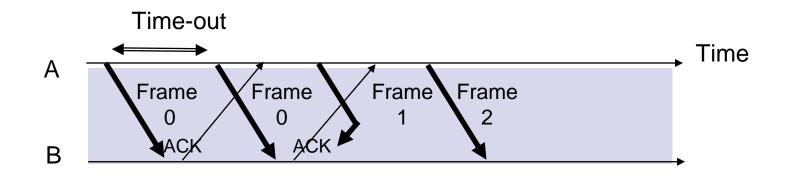
### 3.3.1 Stop-and-Wait ARQ (SW)





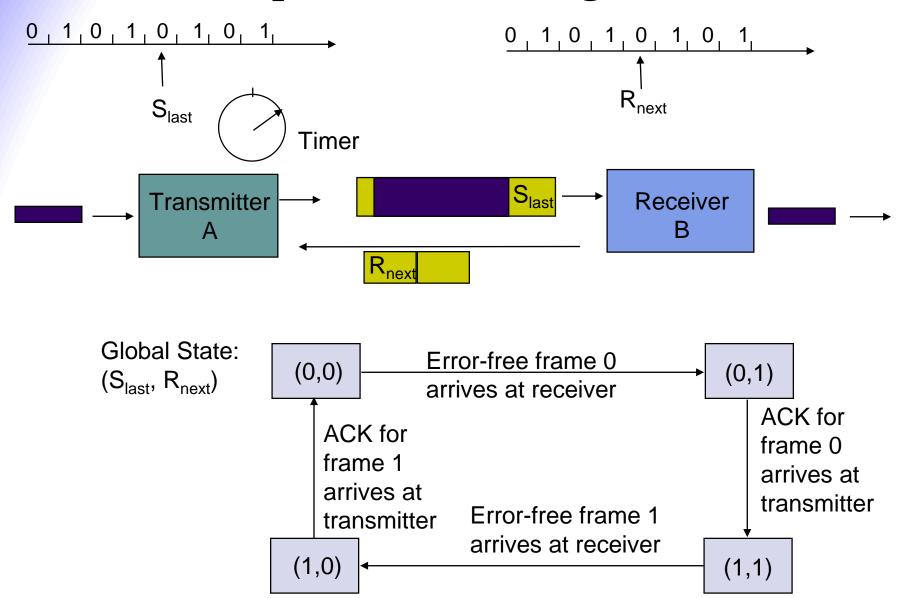
- In cases (a) & (b) the transmitting station A acts the same way
- But in case (b) the receiving station B accepts frame 1 twice
- Question: How is the receiver to know the second frame is also frame 1?
- Answer: **Add frame sequence number in header**
- S<sub>last</sub> is sequence number of most recent transmitted frame

#### (c) Premature Time-out



- The transmitting station A misinterprets duplicate ACKs
- Incorrectly assumes second ACK acknowledges Frame 1
- Question: How is the transmitter to know second ACK is for frame 0?
- Answer: Add frame sequence number in ACK header
- R<sub>next</sub> is sequence number of next frame expected by the receiver
- Implicitly acknowledges receipt of all prior frames

## 1-bit sequence numbering



## protocol

#### **Transmitter**

#### Ready state

- Await request from higher layer for packet transfer
- When request arrives, transmit frame with updated S<sub>last</sub> and CRC
- Go to Wait State

#### Wait state

- Wait for ACK or timer to expire; block requests from higher layer
- If timeout expires
  - retransmit frame and reset timer
- If ACK received:
  - If sequence number is incorrect or if errors detected: ignore ACK
  - If sequence number is correct (R<sub>next</sub> = S<sub>last</sub> +1): accept frame, go to Ready state

#### Receiver

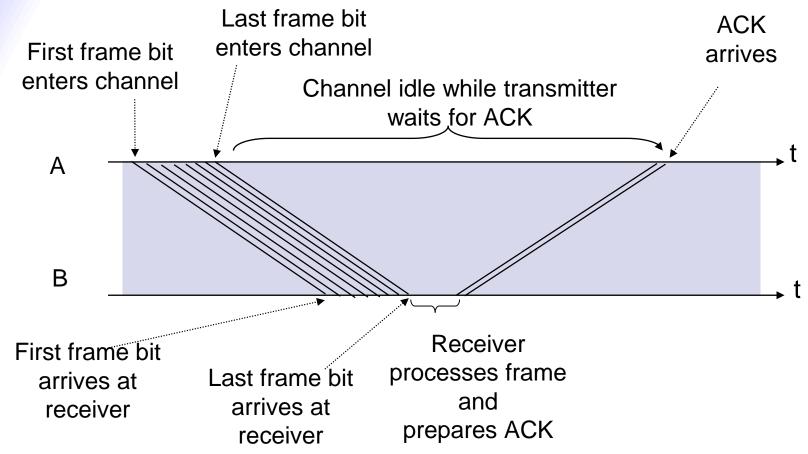
#### Always in Ready State

- Wait for arrival of new frame
- When frame arrives, check for errors
- If no errors detected and sequence number is correct (S<sub>last</sub>=R<sub>next</sub>), then
  - accept frame,
  - update R<sub>next</sub>,
  - send ACK frame with R<sub>next</sub>,
  - deliver packet to higher layer
- If no errors detected and wrong sequence number
  - discard frame
  - send ACK frame with R<sub>next</sub>
- If errors detected
  - discard frame

## applications

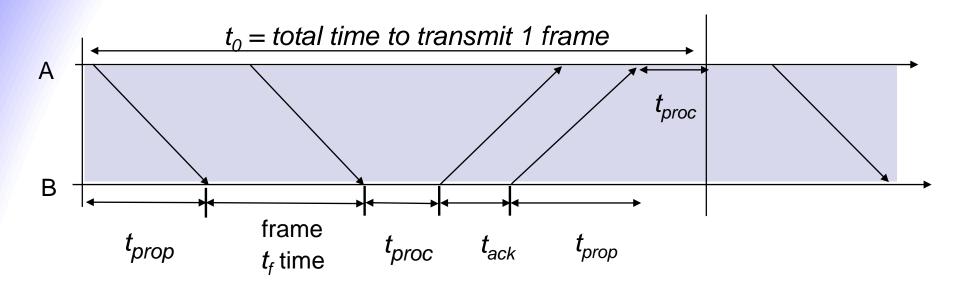
- IBM Binary Synchronous Communications protocol (Bisync): character-oriented data link control
- Xmodem: modem file transfer protocol
- Trivial File Transfer Protocol (RFC 1350): simple protocol for file transfer over User Datagram Protocol (UDP)

## efficiency



- 10000 bit frame @ 1 Mbps takes 10 ms to transmit
- If wait for ACK = 1 ms, then efficiency = 10/11 = 91%
- If wait for ACK = 20 ms, then efficiency = 10/30 = 33%

## delay components



$$t_0 = 2t_{prop} + 2t_{proc} + t_f + t_{ack} \qquad \text{bits/info frame}$$
 
$$= 2t_{prop} + 2t_{proc} + \frac{n_f}{R} + \frac{n_a}{R} \qquad \text{bits/ACK frame}$$

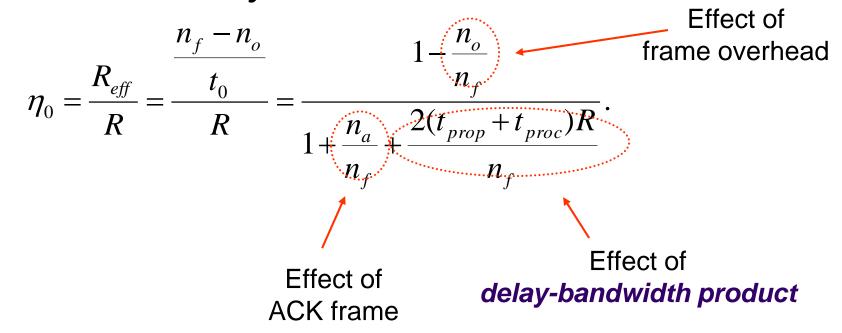
channel transmission rate

## efficiency on error-free channel

#### Effective transmission rate:

$$R_{eff}^{0} = \frac{\text{number of informatio n bits delivered to destinatio n}}{\text{total time required to deliver the informatio n bits}} = \frac{n_f - n_o}{t_0},$$

### Transmission efficiency:



## impact of delay-bandwidth product

 $n_f$ =1250 bytes = 10000 bits,  $n_a$ = $n_o$ =25 bytes = 200 bits

2xDelayxBW Efficiency	1 ms	10 ms	100 ms	1 sec
	200 km	2,000 km	20,000 km	200,000 km
1 Mbps	10 <sup>3</sup>	104	10 <sup>5</sup>	10 <sup>6</sup>
	88%	49%	9%	1%
1 Gbps	10 <sup>6</sup>	10 <sup>7</sup>	108	10 <sup>9</sup>
	1%	0.1%	0.01%	0.001%

Stop-and-Wait does not work well for very high speeds or long propagation delays

## efficiency in channel with errors

- Let  $1 P_f =$  probability frame arrives without errors
- Average number of transmissions to first correct arrival is then  $1/(1-P_f)$
- "If 1-in-10 get through without error, then average 10 tries to success"
- Average total time per frame is then  $t_0/(1 P_f)$  (a proper derivation is given in next two slides)

$$\eta_{SW} = \frac{\frac{n_f - n_o}{t_o}}{R} = \frac{\frac{1 - \frac{n_o}{t_o}}{1 - P_f}}{R} = \frac{1 - \frac{n_o}{n_f}}{1 + \frac{n_a}{n_f} + \frac{2(t_{prop} + t_{proc})R}{n_f}} (1 - P_f)$$

Effect of frame loss

• Let X be a random variable assuming the values of  $x_1$ ,  $x_2$ ,... with corresponding probabilities  $p_1$ ,  $p_2$ ,.... The mean or *expected* value of X is defined by:

$$E(X) = \sum_{i} p_{i} x_{i}$$

• e.g.  $x_1 = 1$ ,  $x_2 = 2$ ,  $x_3 = 3$ , each with probability of 1/3 E(X) = 1/3 + 2/3 + 3/3 = (1+2+3)/3 = 2, which is the simple average formula when X takes each value with equal probability

1 successful transmission 
$$i-1 \text{ unsuccessful transmissions}$$
 
$$E[t_{total}] = t_0 + \sum_{i=1}^{\infty} (i-1)t_{out}P[n_t = i]$$
 
$$= t_0 + \sum_{i=1}^{\infty} (i-1)t_{out}P_f^{i-1}(1-P_f)$$
 
$$= t_0 + \frac{t_{out}P_f}{1-P_f} = t_0 + \frac{1}{1-P_f}.$$

#### **Efficiency:**

$$\eta_{SW} = \frac{\frac{n_f - n_o}{E[t_{total}]}}{R} = (1 - P_f) \frac{1 - \frac{n_o}{n_f}}{1 + \frac{n_a}{n_f} + \frac{2(t_{prop} + t_{proc})R}{n_f}} = (1 - P_f)\eta_0.$$

## impact of bit error rate

 $n_f$ =1250 bytes = 10000 bits,  $n_a$ = $n_o$ =25 bytes = 200 bits Find efficiency for random bit errors with p = 0, 10<sup>-6</sup>, 10<sup>-5</sup>, 10<sup>-4</sup>

$$1 - P_f = (1 - p)^{n_f} \approx e^{-n_f p}$$
 for large  $n_f$  and small  $p$ 

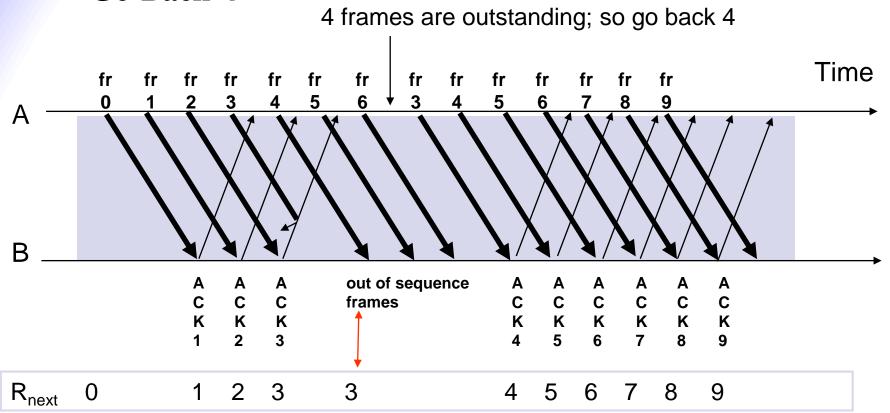
1 – $P_f$ Efficiency	0	10 <sup>-6</sup>	10 <sup>-5</sup>	10-4
1 Mbps	1	0.99	0.905	0.368
& 1 ms	88%	86.6%	79.2%	32.2%

bit error impact performance as  $n_f p$  approach 1

### 3.3.2 Go-Back-N ARQ (GBN)

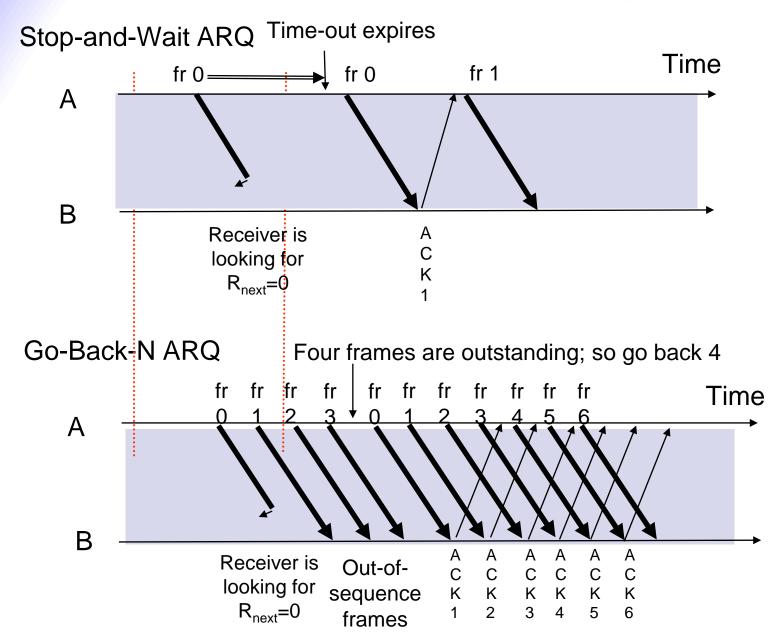
- Improve Stop-and-Wait by not waiting!
- Keep channel busy by continuing to send frames
- Allow a window of up to  $W_s$  outstanding frames
- Use *m*-bit sequence numbering
- Primitive version
  - If ACK for oldest frame arrives before window is exhausted, we can continue transmitting
  - If window is exhausted, pull back and retransmit all outstanding frames

#### Go-Back-4



- Frame transmission are *pipelined* to keep the channel busy
- Frame with errors and subsequent out-of-sequence frames are ignored
- Transmitter is forced to go back when window of 4 is exhausted

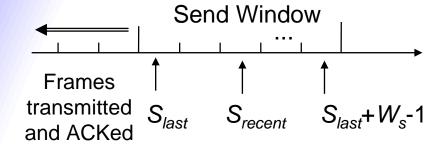
### Window size long enough to cover round trip time



### Alternative: use timeout

- Problem with the primitive Go-Back-N as presented:
  - If frame is lost and source does not have frame to send, then window will not be exhausted and recovery will not commence
- Use a timeout with each frame
  - When timeout expires, resend all outstanding frames

#### **Transmitter**



#### **Buffers**



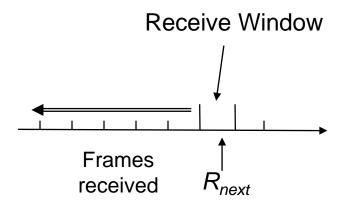


most recent transmission

...



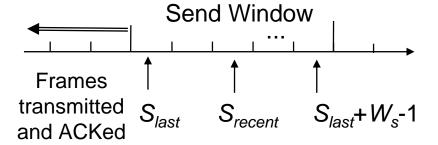
#### Receiver



Receiver will only accept a frame that is error-free and that has sequence number  $R_{next}$ 

When such frame arrives  $R_{next}$  is incremented by one, so the receive window slides forward by one

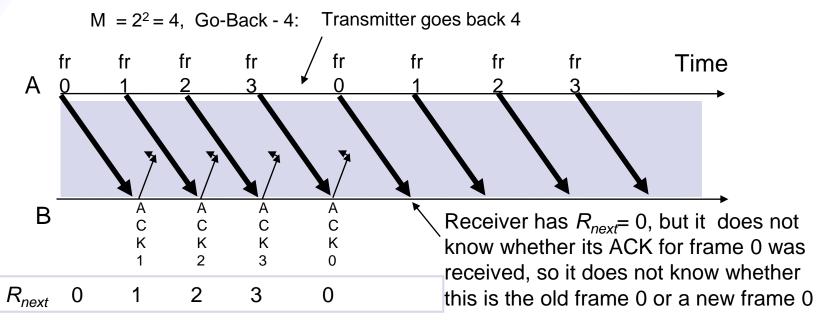
#### Transmitter

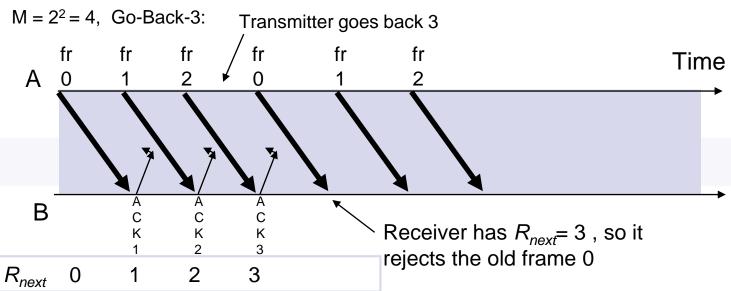


Transmitter waits for error-free ACK frame with sequence number  $S_{last}$ 

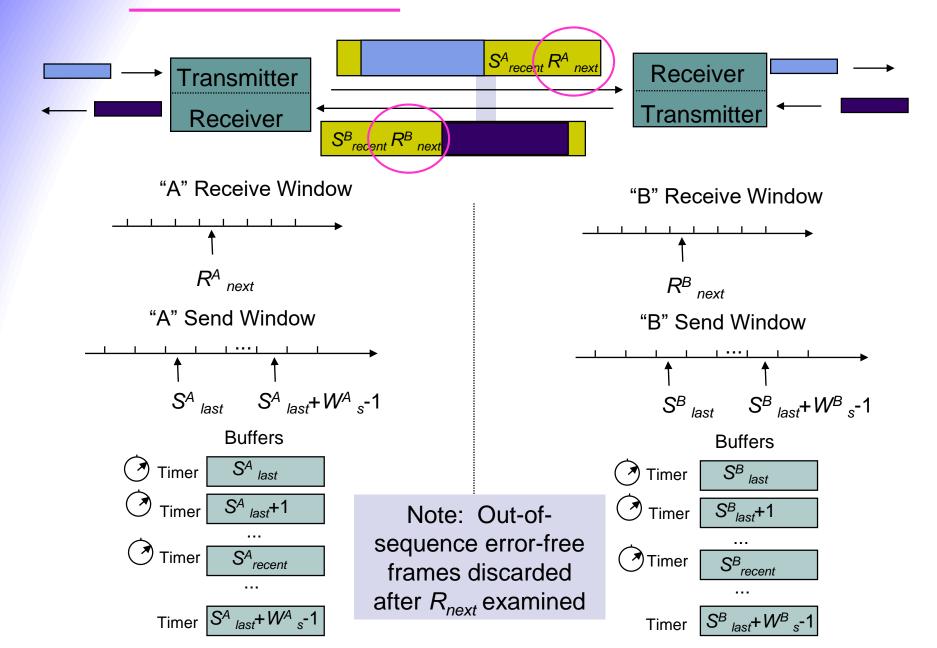
When such ACK frame arrives,  $S_{last}$  is incremented by one, and the send window slides forward by one

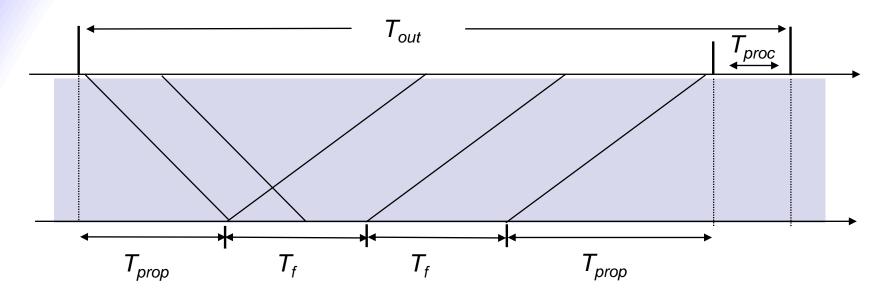
### Maximum Allowable Window Size is $W_s = 2^m-1$





## **ACK Piggybacking in bidirectional GBN**





- Timeout value should allow for:
  - Two propagation times + 1 processing time: 2  $T_{prop}$  +  $T_{proc}$
  - A frame that begins transmission right before our frame arrives  $T_f$
  - Next frame carries the ACK,  $T_f$
- $W_s$  should be large enough to keep channel busy for  $T_{out}$

## applications

- High-Level Data Link Control (HDLC): bit-oriented data link control
- V.42 modem: error control over telephone modem links

# performance

Frame = 1250 bytes = 10,000 bits, $R = 1$ Mbps					
$2(T_{prop} + T_{proc})$	2 x Delay x BW	Window			
1 ms	1000 bits	1			
10 ms	10,000 bits	2			
100 ms	100,000 bits	11			
1 second	1,000,000 bits	101			

- GBN is completely efficient, if W<sub>s</sub> large enough to keep channel busy, and if channel is error-free
- Assume P<sub>f</sub> frame loss probability, then time to deliver a frame is:
  - $t_f$  if first frame transmission succeeds  $(1 P_f)$
  - $t_f + W_s t_f / (1-P_f)$  if the first transmission does not succeed  $P_f$

$$t_{GBN} = t_f (1 - P_f) + P_f \{t_f + \frac{W_s t_f}{1 - P_f}\} = t_f + P_f \frac{W_s t_f}{1 - P_f}$$
 and

$$\frac{n_f - n_o}{t_{GBN}} = \frac{1 - \frac{n_o}{n_f}}{R} = \frac{1 - (N_o - 1)P_f}{1 + (N_o - 1)P_f} (1 - N_f)$$

Delay-bandwidth product determines  $W_s$ 

1 successful transmission 
$$i-1 \text{ unsuccessful transmissions}$$
 
$$E[t_{total}] = t_f + \sum_{i=1}^{\infty} (i-1)W_s t_f P[n_t = i]$$
 
$$= t_f + W_s t_f \sum_{i=1}^{\infty} (i-1)P_f^{i-1}(1-P_f)$$
 
$$= t_f + \frac{W_s t_f P_f}{1-P_f} = t_f \frac{1+(W_s-1)P_f}{1-P_f}.$$

#### **Efficiency:**

$$\eta_{GBN} = \frac{\frac{n_f - n_o}{E[t_{total}]}}{R} = (1 - P_f) \frac{1 - \frac{n_o}{n_f}}{1 + (W_s - 1)P_f}.$$

## impact of bit error rate

 $n_f$ =1250 bytes = 10000 bits,  $n_a$ = $n_o$ =25 bytes = 200 bits compare SW with GBN efficiency for random bit errors with p=0,  $10^{-6}$ ,  $10^{-5}$ ,  $10^{-4}$  and R=1 Mbps and 100 ms

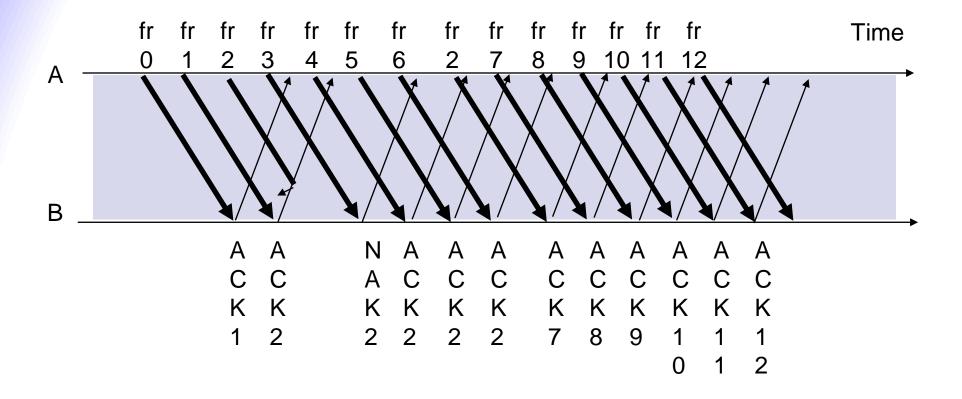
1 Mbps x 100 ms = 100,000 bits = 10 frames  $\rightarrow$  Use  $W_s = 11$ 

Efficiency	0	10 <sup>-6</sup>	10 <sup>-5</sup>	10 <sup>-4</sup>
SW	8.9%	8.8%	8.0%	3.3%
GBN	98%	88.2%	45.4%	4.9%

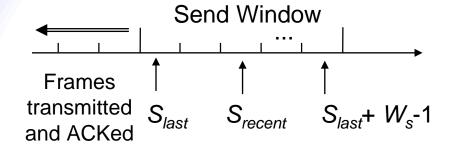
- Go-Back-N significant improvement over Stop-and-Wait for large delay-bandwidth product
- Go-Back-N becomes inefficient as error rate increases

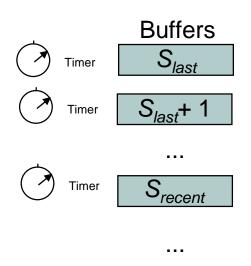
### 3.3.3 Selective Repeat ARQ (SR)

- Go-Back-N ARQ inefficient because *multiple* frames are resent when errors or losses occur
- Selective Repeat ARQ retransmits only an individual frame
  - Timeout causes individual corresponding frame to be resent
  - NAK causes retransmission of oldest un-acked frame
- Receiver maintains a *receive window* of sequence numbers that can be accepted
  - Error-free, but out-of-sequence frames with sequence numbers within the receive window are buffered
  - Arrival of frame with  $R_{next}$  causes window to slide forward by 1 or more



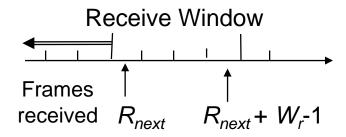
#### Transmitter





 $S_{last} + W_s - 1$ 

#### Receiver



$$R_{next}$$
+ 2

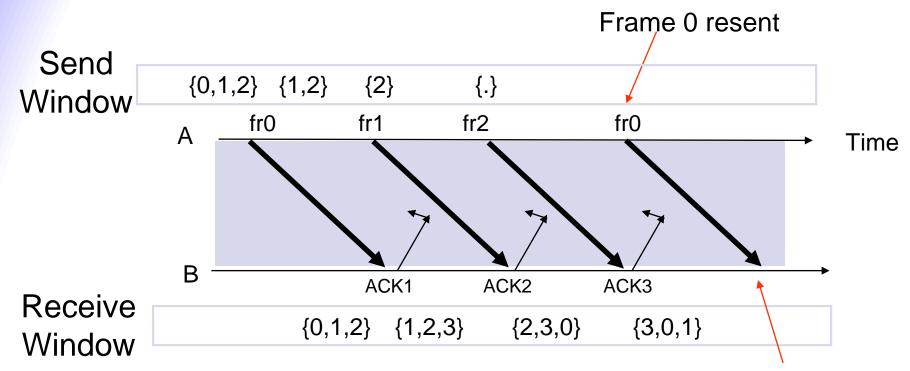
...

$$R_{next}$$
+  $W_r$ - 1

maximum sequence number accepted

# What size $W_s$ and $W_r$ allowed?

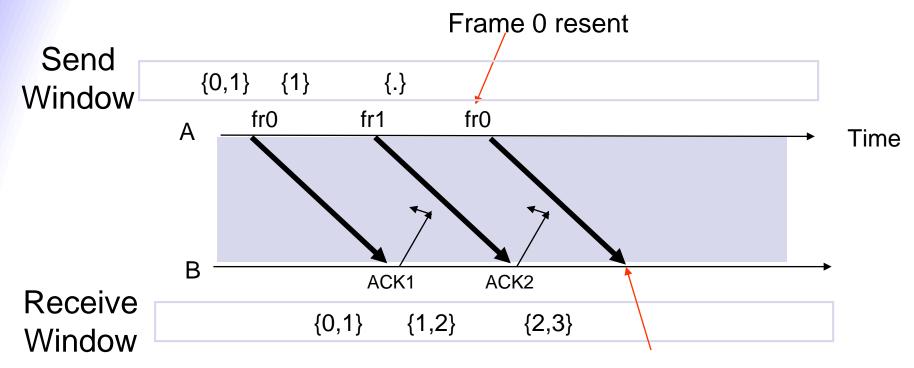
Example:  $M=2^2=4$ ,  $W_s=3$ ,  $W_r=3$ 



Old frame 0 accepted as a new frame because it falls in the receive window

# $W_s + W_r = 2^m$ is maximum allowed

Example:  $M=2^2=4$ ,  $W_s=2$ ,  $W_r=2$ 



Old frame 0 rejected because it falls outside the receive window

Why 
$$W_s + W_r = 2^m$$
 works?

- Transmitter sends frames 0 to W<sub>s</sub>-1; send window empty
- All arrive at receiver
- All ACKs lost
- Transmitter resends frame 0

- Receiver window starts at {0, ..., W<sub>r</sub>-1}
- Window slides forward to  $\{W_s, ..., W_s + W_r 1\}$
- Receiver rejects frame 0 because it is outside receive window

## applications

- Transmission Control Protocol (TCP): transport layer protocol uses variation of selective repeat to provide reliable stream service
- Service Specific Connection Oriented Protocol: error control for signaling messages in asynchronous transfer mode (ATM) networks

## performance

- Assume  $P_f$  frame loss probability, then number of transmissions required to deliver a frame is:
  - $t_f/(1-P_f)$

$$\eta_{SR} = \frac{\frac{n_f - n_o}{t_f / (1 - P_f)}}{R} = (1 - \frac{n_o}{n_f})(1 - P_f)$$

## impact of bit error rate

 $n_f$ =1250 bytes = 10000 bits,  $n_a$ = $n_o$ =25 bytes = 200 bits compare SW, GBN and SR efficiency for random bit errors with p=0, 10<sup>-6</sup>, 10<sup>-5</sup>, 10<sup>-4</sup> and R = 1 Mbps and 100 ms

Efficiency	0	10 <sup>-6</sup>	10 <sup>-5</sup>	10-4
SW	8.9%	8.8%	8.0%	3.3%
GBN	98%	88.2%	45.4%	4.9%
SR	98%	97%	89%	36%

 SR outperforms GBN and SW, but efficiency drops as error rate increases Assume  $n_a$  and  $n_o$  are negligible relative to  $n_f$ , and  $L = 2(t_{prop} + t_{proc})R/n_f = (W_s-1)$ , then

Selective Repeat:

$$\eta_{SR} = (1-P_f)(1-\frac{n_o}{n_f}) \approx (1-P_f)$$
 Go-Back-N:

For *P*<sub>₹</sub>0, SR and GBN same

$$\eta_{GBN} = \frac{1 - P_f}{1 + (W_S - 1)P_f} = \frac{1 - P_f}{1 + LP_f}$$

Stop-and-Wait:

For  $P_f \rightarrow 1$ , GBN and SW same

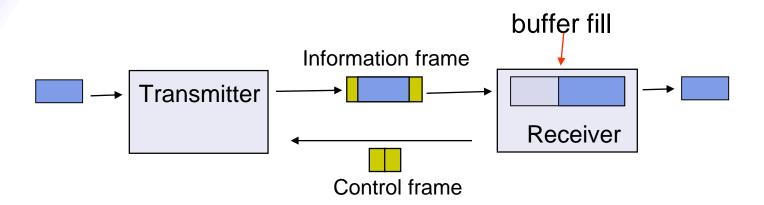
$$\eta_{SW} = \frac{(1 - P_f)}{1 + \frac{n_a}{n_f} + \frac{2(t_{prop} + t_{proc})R}{n_f}} \approx \frac{1 - P_f}{1 + L}$$



delay-bandwidth product = 10, 100 frames

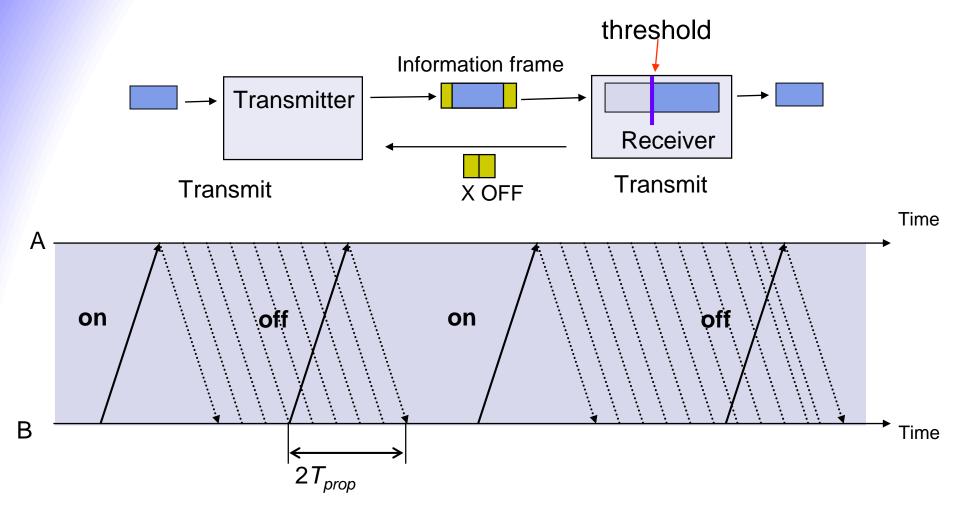
#### 3.4 Flow control

- Messages can be lost if receiving system does not have sufficient buffering to store arriving messages
- If destination layer-(n+1) does not retrieve its information fast enough, destination layer-n buffers may overflow
- Pacing and flow control provide backpressure mechanisms that control transfer according to availability of buffers at the destination
- Examples: TCP and HDLC



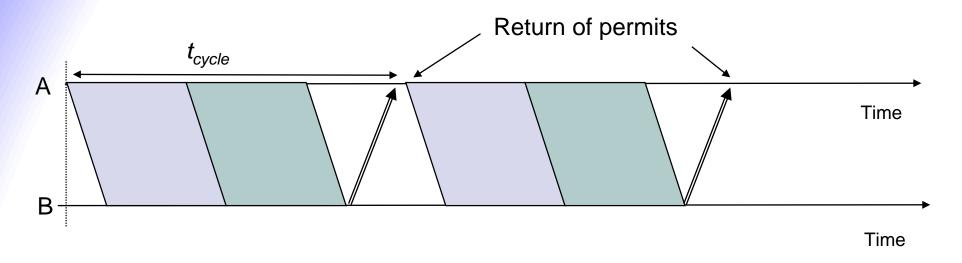
- Receiver has limited buffering to store arriving frames
- Several situations cause buffer overflow
  - Mismatch between sending rate and rate at which user can retrieve data
  - Surges in frame arrivals
- Flow control prevents buffer overflow by regulating rate at which source is allowed to send information

### **ON-OFF** flow control



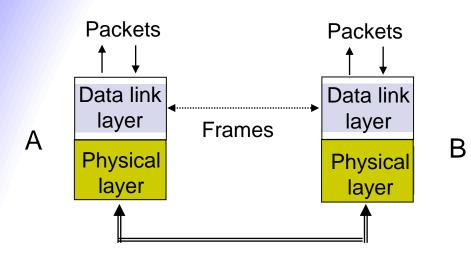
Threshold must activate OFF signal while  $2 T_{prop} R$  bits still remain in buffer

## Sliding window flow control



- Sliding window ARQ method with  $W_s$  equal to buffer available
  - Transmitter can never send more than  $W_s$  frames
- ACKs that slide window forward can be viewed as permits to transmit more
- Can also pace ACKs as shown above
  - Return permits (ACKs) at end of cycle regulates transmission rate

#### **Data Link Protocols**



- Directly connected, wire-like
- Losses & errors, but no out-ofsequence frames
- Applications: Direct Links; LANs; Connections across WANs

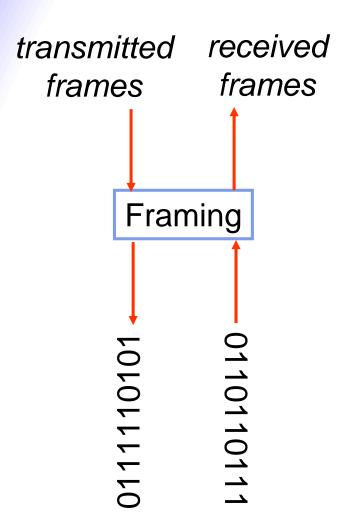
#### **Data Links Services**

- Framing
- Error control
- Flow control
- Multiplexing
- Link Maintenance
- Security: Authentication & Encryption

#### **Examples**

- PPP
- HDLC
- Ethernet LAN
- IEEE 802.11 (Wi Fi) LAN

## 3.5 Framing



- Mapping stream of physical layer bits into frames
- Mapping frames into bit stream
- Frame boundaries can be determined using:
  - character counts
  - control characters
  - flags
  - CRC checks

## byte stuffing

Data to be sent

A DLE B ETX DLE STX E

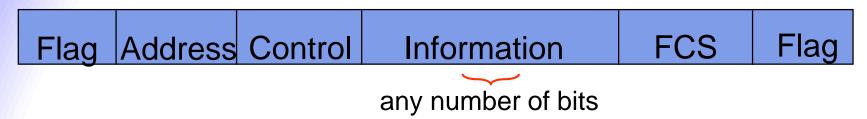
After stuffing and framing

DLE STX A DLE DLE B ETX DLE DLE STX E DLE ETX

- Frames consist of integer number of bytes
  - Asynchronous transmission systems using ASCII to transmit printable characters
  - Octets with HEX value < 20 are nonprintable</li>
- Special 8-bit patterns used as control characters
  - STX (start of text) = 0x02; ETX (end of text) = 0x03
- Byte used to carry non-printable characters in frame
  - DLE (data link escape) = 0x10
  - DLE STX (DLE ETX) used to indicate beginning (end) of frame
  - Insert extra DLE in front of occurrence of DLE in frame byte stuffing
  - All DLEs occur in pairs except at frame boundaries

# bit stuffing

**HDLC** frame



- Frame delineated by flag character
- HDLC uses bit stuffing to prevent occurrence of flag 01111110 inside the frame
- Transmitter inserts extra 0 after each consecutive five 1s inside the frame
- Receiver checks for five consecutive 1s
  - if next bit = 0, it is removed
  - if next two bits are 10, then flag is detected
  - If next two bits are 11, then frame has errors

## **Example**

(a) Data to be sent

011011111111100

After stuffing and framing

*01111110*011011111<u>0</u>000*01111110* 

(b) Data received

01111110000111011111011111011001111110

After destuffing and deframing

\*000111011111-11111-110\*

## 3. Data link layer

- \* reliable data transfer
  - peer-to-peer protocols
  - error detection
  - Automatic Repeat Request (ARQ)
  - flow control
- \* data link control
  - framing
  - point-to-point protocol (PPP)
  - high-level data link control (HDLC)

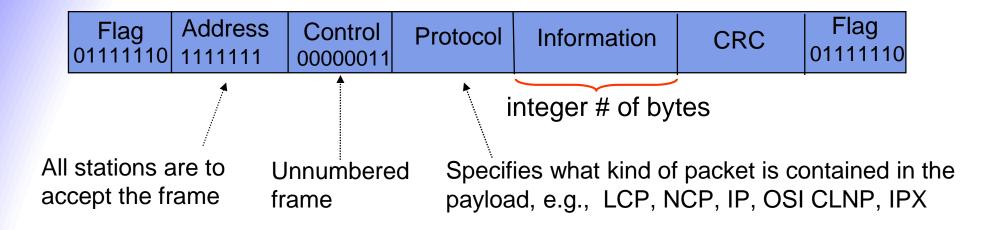
## 3.6 Point-to-point protocol (PPP)

- Data link protocol for point-to-point lines in Internet
  - Router-router; dial-up to router
- 1. Provides framing and error detection
  - Character-oriented HDLC-like frame structure
- 2. Link control protocol (LCP)
  - Bringing up, testing, bringing down lines, negotiating options
  - Authentication: key capability in ISP access
- 3. A family of Network Control Protocols (NCP) specific to different network layer protocols
  - IP, OSI network layer, IPX (Novell), Appletalk

## applications

PPP used in many point-to-point applications

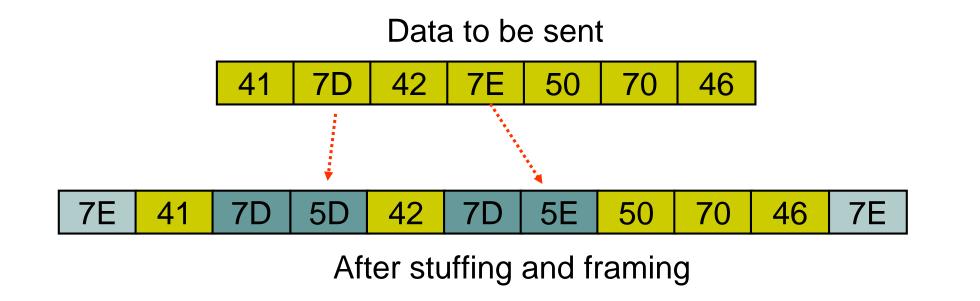
- Telephone Modem Links 30 Kbps
- Packet over Synchronous Optical Network (SONET) 600 Mbps to 10 Gbps
  - $IP \rightarrow PPP \rightarrow SONET$
- PPP is also used over shared links such as Ethernet to provide LCP, NCP, and authentication features
  - PPP over Ethernet (RFC 2516)
  - Used over DSL



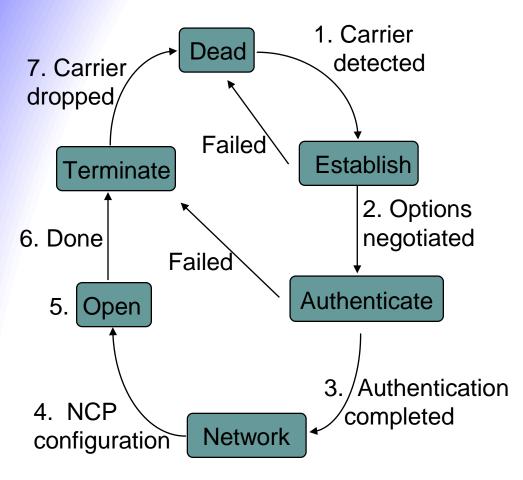
- PPP uses similar frame structure as HDLC, except
  - Protocol type field
  - Payload contains an integer number of bytes
- PPP uses the same flag, but uses byte stuffing

- PPP is character-oriented version of HDLC
- Flag is 0x7E (01111110)
- Control escape 0x7D (01111101)
- Any occurrence of flag or control escape inside of frame is replaced with 0x7D followed by

original octet XORed with 0x20 (00100000)



# PPP phase diagram



#### Home PC to Internet Service Provider

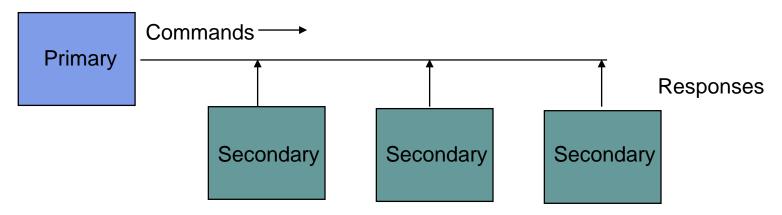
- 1. PC calls router via modem
- 2. PC and router exchange LCP packets to negotiate PPP parameters
- 3. Check on identities
- 4. NCP packets exchanged to configure the network layer, e.g. TCP/IP (requires IP address assignment)
- 5. Data transport, e.g. send/receive IP packets
- 6. NCP used to tear down the network layer connection (free up IP address); LCP used to shut down data link layer connection
- 7. Modem hangs up

- Password Authentication Protocol (PAP)
  - Initiator must send ID and password
  - Authenticator replies with authentication success/fail
  - After several attempts, LCP closes link
  - Transmitted unencrypted, susceptible to eavesdropping
- Challenge-Handshake Authentication Protocol (CHAP)
  - Initiator and authenticator share a secret key
  - Authenticator sends a challenge (random number and ID)
  - Initiator computes cryptographic checksum of random number and ID using the shared secret key
  - Authenticator also calculates cryptographic checksum and compares to response
  - Authenticator can reissue challenge during session

## 3.7 High-level data link control (HDLC)

- Bit-oriented data link control
- Derived from IBM Synchronous Data Link Control (SDLC)
- Related to Link Access Procedure Balanced standards (LAPB)
  - LAP-Data (LAPD) in Integrated Services Digital Network (ISDN)
  - LAP-Modems (LAPM) in cellular telephone signaling

- Normal Response Mode (NRM)
  - Used in polling multidrop lines



- Asynchronous Balanced Mode (ABM)
  - Used in full-duplex point-to-point links



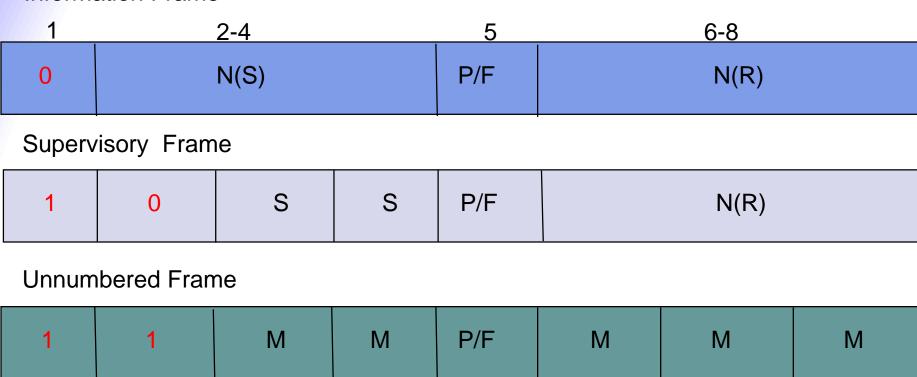
Mode is selected during connection establishment



- Control field gives HDLC its functionality
- Codes in fields have specific meanings and uses
  - Flag: delineate frame boundaries
  - Address: identify secondary station (1 or more octets)
    - In ABM mode, a station can act as primary or secondary so address changes accordingly
  - Control: purpose and functions of frame (1 or 2 octets)
  - Information: contains user data; length not standardized, but implementations impose maximum
  - Frame Check Sequence (FCS): 16- or 32-bit CRC

#### control field format





- S: Supervisory Function Bits
- N(R): Receive Sequence Number
- N(S): Send Sequence Number

- M: Unnumbered Function Bits
- P/F: Poll/Final bit used in interaction between primary and secondary

#### information frame

- Each I-frame contains sequence number N(S)
- Positive ACK piggybacked
  - N(R)=Sequence number of *next* frame expected acknowledges all frames up to and including N(R)-1
- 3 or 7 bit sequence numbering
  - Maximum window sizes 7 or 127 (SW and GBN)
- Poll/Final bit
  - NRM: Primary polls station by setting P=1; Secondary sets F=1 in *last* I-frame in response
  - Primaries and secondaries always interact via paired P/F bits

- Frames lost due to loss-of-sync or receiver buffer overflow
- Frames may undergo errors in transmission
- CRCs detect errors and such frames are treated as lost
- Recovery through ACKs, timeouts and retransmission
- Sequence numbering to identify out-of-sequence and duplicate frames
- HDLC provides for options that implement several ARQ methods

## supervisory frame

Used for error control (ACK, NAK) and flow control (Don't Send):

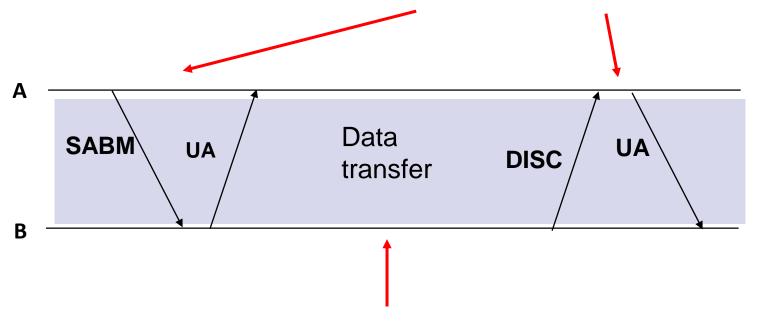
- Receive Ready (RR), SS=00
  - ACKs frames up to N(R)-1 when piggyback not available
- Reject (REJ), SS=01
  - Negative ACK indicating N(R) is first frame not received correctly.
     Transmitter must resend N(R) and later frames (GBN)
- Receive Not Ready (RNR), SS=10
  - ACKs frame N(R)-1 and requests that no more I-frames be sent (flow control)
- Selective Reject (SREJ), SS=11
  - Negative ACK for N(R) requesting that N(R) be selectively retransmitted (SR, what are the maximum send and receive window sizes?)

#### unnumbered frame

- Setting of modes with M bits:
  - set asynchronous balanced mode (SABM)
  - unnumbered acknowledgment (UA): acknowledges acceptance of mode setting commands
  - disconnect (DISC): terminates logical link connection
- Information transfer between stations
  - unnumbered information (UI)
- Recovery used when normal error/flow control fails
  - frame reject (FRMR): frame with correct FCS but impossible semantics (e.g. invalid M bits)
  - RSET: indicates sending station is resetting sequence numbers
- XID: exchange station id and characteristics

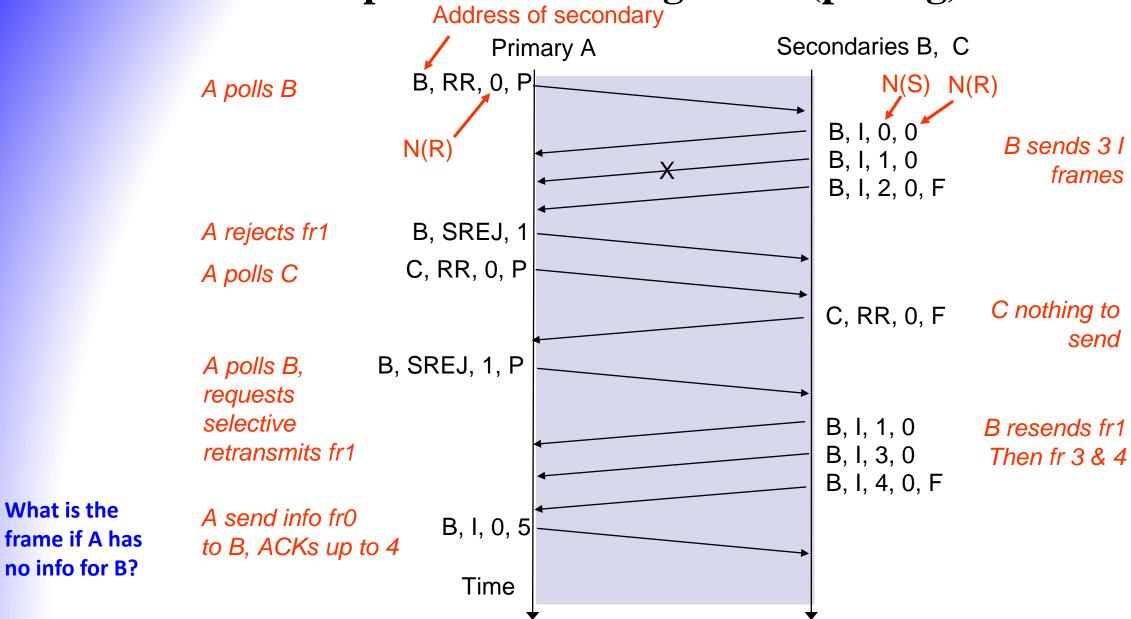
### connection establishment and release

unnumbered frames used to establish and release data link connection

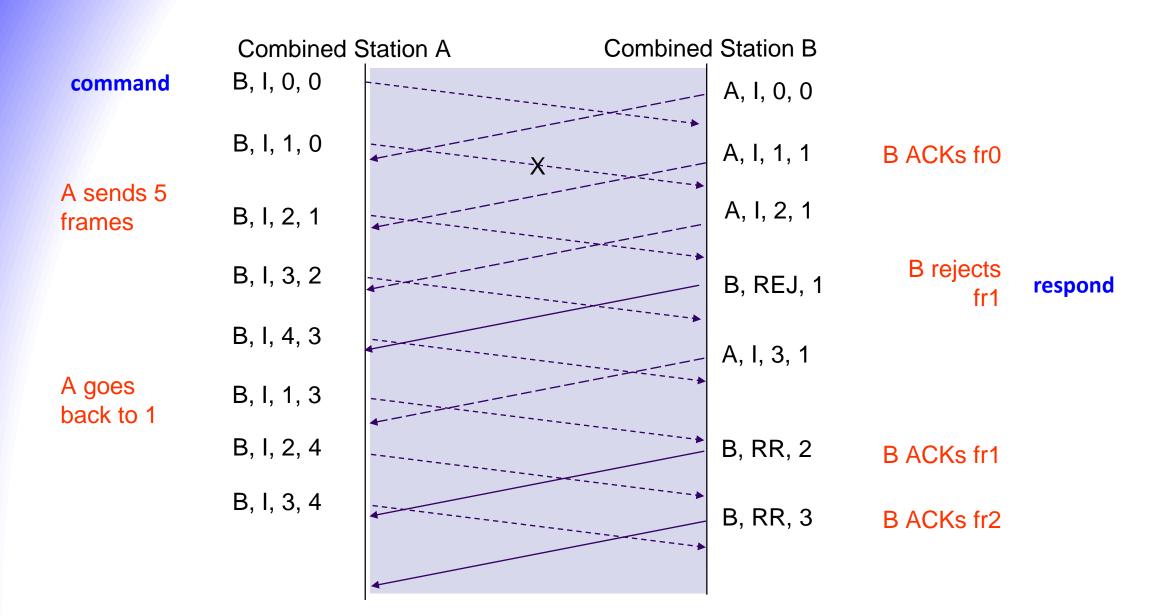


I and S frames used for data transfer

# **Example: HDLC using NRM (polling)**

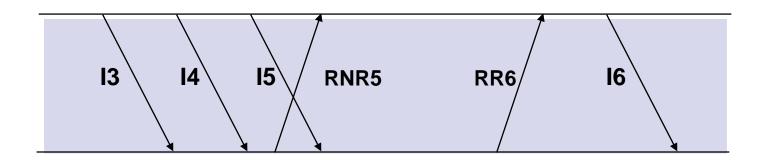


# **Example: frame exchange using ABM**



#### flow control

- Flow control is required to prevent transmitter from overrunning receiver buffers
- Receiver can control flow by delaying acknowledgement messages
- Receiver can also use supervisory frames to explicitly control transmitter
  - Receive Not Ready (RNR) and Receive Ready (RR)



# **Chapter Summary**

- ♦ peer-to-peer protocols
- ♦ reliable data transfer error detection + ARQ
- ◆ parity check, Internet checksum, polynomial codes
- ♦ SW, GBN, SR
- ♦ flow control
- **♦** framing
- ◆ PPP
- ♦ HDLC

#### Reference

Chapters 3 and 5, Communication Networks: Fundamental Concepts and Key Architectures

