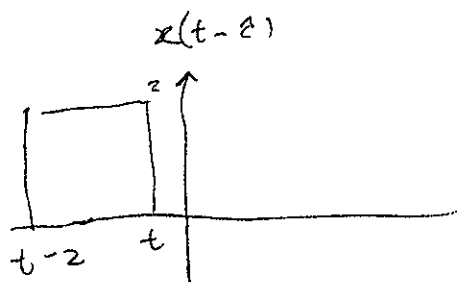
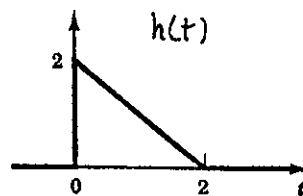
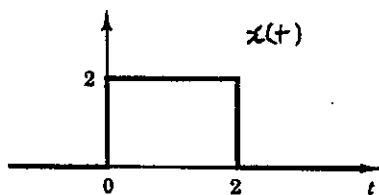


1. (10 pts) Determine if the following statements or equations are true or false. It suffices to just provide an answer. You do not need to justify it.
- (i) The series connection of two LTI systems is a LTI system.
 - (ii) The parallel connection of two LTI systems is a LTI system.
 - (iii) If the input to a LTI system is periodic, then the output is also periodic.
 - (iv) If $h(t)$ is the impulse response of a LTI system and $h(t)$ is periodic and nonzero, then the system is unstable.
 - (v) If a LTI system is causal, then it is stable.
 - (vi) If $y(t) = x(t) * h(t)$, then $y(2t) = 2x(2t) * h(2t)$.
 - (vii) If $x(t)$ and $h(t)$ are odd, then $y(t) = x(t) * h(t)$ is even.

2. (5 pts) The impulse response of a LTI system and an input signal applied to the system are shown in the following figure. Determine the output response.



$$h(t) = \begin{cases} 2 - t & 0 \leq t \leq 2 \\ 0 & \text{otherwise} \end{cases}$$

Integral limits: 1
Integrand: 1

1. $t < 0$, $y(t) \equiv 0$.

2. $0 < t < 2$, $y(t) = \int_0^t (2 - \tau) 2 d\tau = 4t - t^2$

2. $2 < t < 4$, $y(t) = \int_{t-2}^2 (2 - \tau) 2 d\tau = 4(2 - t + 2) - (2^2 - (t-2)^2)$

$$= 16 - 4t - 4 + t^2 - 4t + 4$$

$$= 16 - 8t + t^2$$

$t > 4$, $y(t) \equiv 0$

3. (6 pts) Let $x(t)$ be a periodic signal with period T . Suppose that its Fourier coefficients are given by

$$c_k = \begin{cases} 2, & k = 0 \\ (1/2)^{|k|}, & k \neq 0 \end{cases}$$

Answer and justify the following questions: (1) Is $x(t)$ real? (2) Is $x(t)$ even? (3) Calculate

$$\frac{1}{T} \int_T |x(t)|^2 dt.$$

3

3

1. Solution: (1) $x(t)$ is real, since

$$1. \quad x(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk \frac{2\pi}{T} t} = 2 + \sum_{k=1}^{\infty} 2 \left(\frac{1}{2}\right)^k \cos k \frac{2\pi}{T} t$$

1. (2) $x(t)$ is even, $x(t) = x(-t)$

(3)

$$1. \quad \frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{\infty} |c_k|^2$$

$$1. \quad = 2^2 + 2 \sum_{k=1}^{\infty} \left(\frac{1}{2}\right)^{2k}$$

$$= 2^2 - 2 + 2 \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^{2k}$$

$$= 2 + 2 \sum_{k=0}^{\infty} \left(\frac{1}{4}\right)^k$$

$$= 2 + 2 \cdot \frac{1}{1 - \frac{1}{4}}$$

$$1. \quad = 2 + \frac{8}{3} = \frac{16}{3}$$

4. (7 pts) (1) A LTI system has an impulse response $h(t) = e^t u(-t)$, where $u(t)$ is the unit step signal. (a) Give a differential equation description for the system. (b) Suppose that an input signal is given as $x(t) = e^{-t} u(t)$. Determine the output response.

Solution. Let $f(t) = e^{-t} u(t)$, $\Rightarrow h(t) = f(-t)$

$$1. \quad H(\omega) = F(-\omega) = \frac{1}{1-j\omega} = \frac{Y(\omega)}{X(\omega)}$$

$$1. \quad (a) \quad -\frac{dy(t)}{dt} + y(t) = x(t), \quad \text{or} \quad \frac{dy(t)}{dt} - y(t) = -x(t)$$

$$1. \quad (b) \quad X(\omega) = \frac{1}{1+j\omega}, \quad Y(\omega) = \frac{1}{(1-j\omega)(1+j\omega)}$$

$$Y(\omega) = \frac{A}{1-j\omega} + \frac{B}{1+j\omega}, \quad A = (1-s)Y(s)|_{s=1} = \frac{1}{2}$$

$$B = (1+s)Y(s)|_{s=-1} = \frac{1}{2}$$

$$1. \quad = \frac{1}{2} \frac{1}{1-j\omega} + \frac{1}{2} \frac{1}{1+j\omega}$$

$$1. \quad y(t) = \frac{1}{2} \left[e^t u(-t) + e^{-t} u(t) \right]$$

- (2) Let $F(\omega)$ be the Fourier transform of $f(t)$. Show that

$$\int_{-\infty}^{\infty} \left| \frac{df(t)}{dt} \right|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} \omega^2 |F(\omega)|^2 d\omega.$$

Proof: $\mathcal{F} \left\{ \frac{df(t)}{dt} \right\} = j\omega F(\omega)$

$$\Rightarrow \int_{-\infty}^{\infty} \left| \frac{df(t)}{dt} \right|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |j\omega F(\omega)|^2 d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \omega^2 |F(\omega)|^2 d\omega$$

5. (9 pts) Consider the LTI system with frequency response

$$H(\omega) = \frac{j\omega + 1}{(j\omega)^2 + 7j\omega + 12}$$

- (1) Find the impulse response of this system.
- (2) Determine a differential equation that describes the system.
- (3) Find a block diagram realization (of any kind) consisting of adders, integrators, and coefficient multipliers for this system.
- (4) Suppose that an input signal $x(t) = e^{-2t}u(t)$ is applied. Determine the output response.

Solution

(1) $H(\omega) = \frac{j\omega + 1}{(j\omega + 3)(j\omega + 4)}$

$$H(s) = \frac{s+1}{(s+3)(s+4)} = \frac{A}{s+3} + \frac{B}{s+4} = -\frac{2}{s+3} + \frac{3}{s+4}$$

2. $A = (s+3) \frac{s+1}{(s+3)(s+4)} \Big|_{s=-3} = -2$

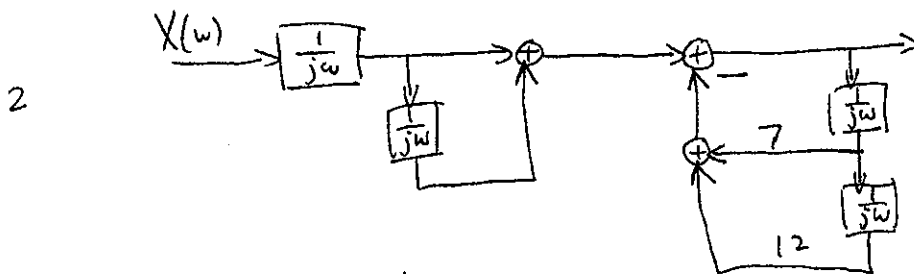
$$B = (s+4) \frac{s+1}{(s+3)(s+4)} \Big|_{s=-4} = 3$$

$$h(t) = [-2e^{-3t} + 3e^{-4t}] u(t)$$

(2) $\frac{Y(j\omega)}{X(j\omega)} = H(\omega) = \frac{j\omega + 1}{(j\omega)^2 + 7j\omega + 12}$

2. $\frac{d^2 y(t)}{dt^2} + 7 \frac{dy(t)}{dt} + 12 y(t) = \frac{dx(t)}{dt} + x(t)$

(3) $Y(\omega) = \frac{1}{j\omega} X(\omega) + \frac{1}{(j\omega)^2} X(\omega) - \frac{7}{j\omega} Y(\omega) - \frac{12}{(j\omega)^2} Y(\omega)$



(4) $X(\omega) = \frac{1}{j\omega + 2}$

3 $Y(\omega) = H(\omega) X(\omega) = \frac{j\omega + 1}{(j\omega + 2)(j\omega + 3)(j\omega + 4)}$

$$Y(s) = \frac{s+1}{(s+2)(s+3)(s+4)} = \frac{A}{s+2} + \frac{B}{s+3} + \frac{C}{s+4}$$

$$A = \cancel{(s+2)} \frac{s+1}{\cancel{(s+2)}(s+3)(s+4)} \Big|_{s=-2} = -\frac{1}{2}$$

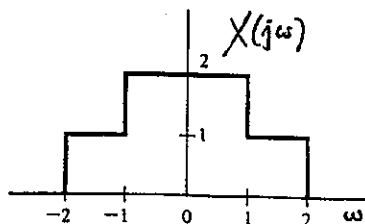
$$B = \cancel{(s+3)} \frac{s+1}{(s+2)\cancel{(s+3)}(s+4)} \Big|_{s=-3} = 2$$

$$C = \cancel{(s+4)} \frac{s+1}{(s+2)(s+3)\cancel{(s+4)}} \Big|_{s=-4} = -\frac{3}{2}$$

$$\Rightarrow Y(\omega) = -\frac{1}{2} \frac{1}{j\omega+2} + 2 \frac{1}{j\omega+3} - \frac{3}{2} \frac{1}{j\omega+4}$$

$$y(t) = \left[-\frac{1}{2} e^{-2t} + 2 e^{-3t} - \frac{3}{2} e^{-4t} \right] u(t)$$

6. (5 pts) The Fourier transform of a certain signal $x(t)$ is given in the following figure. Find $x(t)$ without performing any integration.



Solution :

$$X(j\omega) = Y_1(\omega) + Y_2(\omega)$$

$$2. \quad Y_1(\omega) = \begin{cases} 1 & |\omega| < 2 \\ 0 & |\omega| > 2 \end{cases} \Rightarrow y_1(t) = \frac{\sin 2t}{\pi t}$$

$$2. \quad Y_2(\omega) = \begin{cases} 1 & |\omega| < 1 \\ 0 & |\omega| > 1 \end{cases} \Rightarrow y_2(t) = \frac{\sin t}{\pi t}$$

$$\begin{aligned} \Rightarrow 1. \quad x(t) &= y_1(t) + y_2(t) = \frac{\sin 2t}{\pi t} + \frac{\sin t}{\pi t} \\ &= \frac{\sin t}{\pi t} (1 + 2 \cos t) \end{aligned}$$