

EE 5410 Signal Processing

Semester A 2017-2018

Assignment 1

Due Date: 10 October 2017

1. Find the **Fourier series coefficients** for the following continuous-time signal:

$$x(t) = \begin{cases} 2, & 2 > t > 0 \\ 1, & 4 > t > 2 \end{cases}$$

with fundamental period of $T = 4$.

2. The impulse response of a RL circuit which corresponds to a continuous-time linear time-invariant (LTI) system, is given as:

$$h(t) = e^{\frac{-t}{L/R}} u(t)$$

where R and L represent the values of resistor and inductor, respectively. Find the **Fourier transform** of $h(t)$. Then determine its **magnitude**, **phase**, **real part** and **imaginary part** of $H(j\Omega)$.

3. Consider a **continuous-time LTI system** with **continuous-time** input $x(t)$ and **impulse response** $h(t) = -2\delta(t-2) + \delta(t-10)$. Determine the system continuous-time output $y(t)$ in terms of $x(t)$. Is the **system stable**? Is the system **causal**? Is the **system memoryless**?

4. Given a **discrete-time system** with input $x[n]$ and output $y[n]$:

$$y[n] = T(x[n]) = x[n] + \frac{1}{x[n]}$$

Determine whether the system is **memoryless**, **stable**, **causal**, **linear**, and/or **time-invariant**.

5. Consider **two discrete-time signals** $x[n] = u[-1-n]$ and $h[n] = (0.5)^n u[n]$.

- (a) Compute $y[n] = x[n] \otimes h[n]$ using the **convolution formula**.
(b) Compute $y[n] = x[n] \otimes h[n]$ using **z transform**.

6. Given a continuous-time signal:

$$x(t) = 2 \sin\left(\frac{\pi}{2}t + \frac{\pi}{5}\right)$$

We sample it with a **sampling period** $T = 1$ sec. to produce the discrete-time signal $x[n]$. Find $x[1]$, $x[2]$, $x[3]$, $x[4]$ and $x[5]$. Is $x[n]$ a **periodic signal**?

7. Figure 1 shows a discrete-time system which consists of an interconnection of four LTI systems with impulse responses $h_1[n]$, $h_2[n]$, $h_3[n]$ and $h_4[n]$.

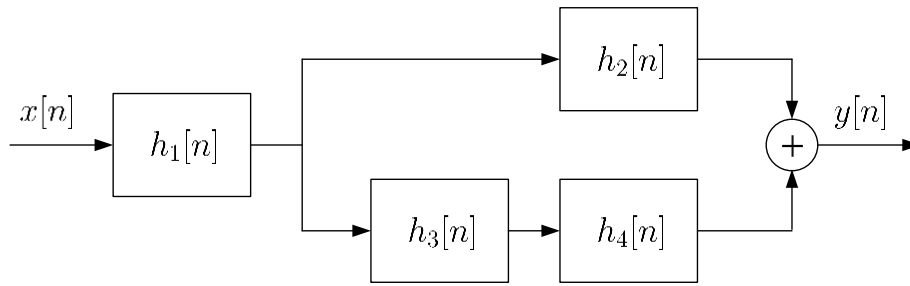


Figure 1

- (a) Determine the **overall impulse response** of the system, $h[n]$, in terms of $h_1[n]$, $h_2[n]$, $h_3[n]$ and $h_4[n]$.

- (b) Determine $h[n]$ when

$$h_1[n] = \delta[n] + \delta[n - 1]$$

$$h_2[n] = h_3[n] = u[n]$$

and

$$h_4[n] = \delta[n - 2]$$

- (c) Determine $y[n]$ in (b) if the input has the form of

$$x[n] = \delta[n + 2] + 3\delta[n - 1]$$

8. Determine the convolution of the following two discrete-time signals:

$$x[n] = \begin{cases} n^2 - 1, & -2 \leq n \leq 2 \\ 0, & \text{otherwise} \end{cases} \quad \text{and} \quad h[n] = \begin{cases} n - 4, & 0 \leq n \leq 3 \\ 0, & \text{otherwise} \end{cases}$$

9. When the input to a discrete-time LTI system is

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n - 1]$$

The corresponding output is

$$y[n] = 6 \left(\frac{1}{2}\right)^n u[n] - 6 \left(\frac{3}{4}\right)^n u[n]$$

- (a) Find the **system function** $H(z)$ of the system and specify its **region of convergence** (ROC).
 (b) Determine the **pole(s)** and **zero(s)** of $H(z)$.
 (c) Find the **impulse response** $h[n]$ of the system.
 (d) Determine the **discrete-time Fourier transform** (DTFT) of $h[n]$.
 (e) Write a **difference equation** which relates $x[n]$ and $y[n]$.
 (f) Is the system **stable**? Why?
 (g) Is the system **causal**? Why?