

# Unit 8

## Linearity (with solution)

# Question 1: Vector Space

Consider the set of all **binary**  $n$ -vectors,  $\{0, 1\}^n$

- Addition of two vectors is defined by

$$(x_1, \dots, x_n) + (y_1, \dots, y_n) = (x_1 + y_1, \dots, x_n + y_n),$$

where the addition of two bits is defined by modulo-2 addition (i.e., logical XOR).

- Scalar multiplication is defined by

$$c(x_1, \dots, x_n) = (cx_1, \dots, cx_n), \quad \text{for } c \in \{0, 1\},$$

where multiplication of two bits is defined by usual multiplication (i.e.,  $0 \cdot 0 = 0 \cdot 1 = 0$  and  $1 \cdot 1 = 1$ ).

Is it a vector space?

## Q.1 (solution)

- ❑ Commutative and associative conditions are satisfied because of the property of XOR.
- ❑ Zero condition is satisfied since  $x + \mathbf{0} = x$ .
- ❑ Inverse condition is satisfied since  $x + x = \mathbf{0}$ .
- ❑ Associative and Unitarity conditions for scale multiplication are satisfied due to the property of usual multiplication.
- ❑ It is straightforward to check that the two distributive conditions are also satisfied.

## Question 2: Subspace

The set of all real polynomials (with usual addition and scalar multiplication) is a vector space.

- The degree of a polynomial is the highest of the degrees of its monomials (individual terms) with ***non-zero*** coefficients.

Is each of the following sets its subspaces? Why?

- a) The set of all real polynomials with degree **less than**  $n$ ;
- b) The set of all real polynomials with degree **equal** to  $n$ .

## Q.2 (solution)

- a) The set consists of all real polynomials in the form of  $p = a_0 + a_1x + \cdots + a_{n-1}x^{n-1}$ .

(Note: some coefficients  $a_i$  may be zero)

□ Closed under addition:

$p + q = (a_0 + b_0) + (a_1 + b_1)x + \cdots + (a_{n-1} + b_{n-1})x^{n-1}$   
is still in the set.

□ Closed under scalar multiplication:

$cp = (ca_0 + ca_1x + \cdots + ca_{n-1}x^{n-1})$  is still in the set.

□ Therefore, it is a subspace.

## Q.2 (solution)

b) The set consists of all real polynomials in the form of  $p = a_0 + a_1x + \cdots + a_nx^n$ ,  $a_n \neq 0$ .

□ Not closed under addition if  $a_n = -b_n$ :

$$\begin{aligned} p + q &= (a_0 + b_0) + (a_1 + b_1)x + \cdots + (a_n + b_n)x^n \\ &= (a_0 + b_0) + (a_1 + b_1)x + \cdots + (a_{n-1} - b_{n-1})x^{n-1}, \end{aligned}$$

whose degree is at most  $n - 1$ .

□ Not closed under scalar multiplication if  $c = 0$ :

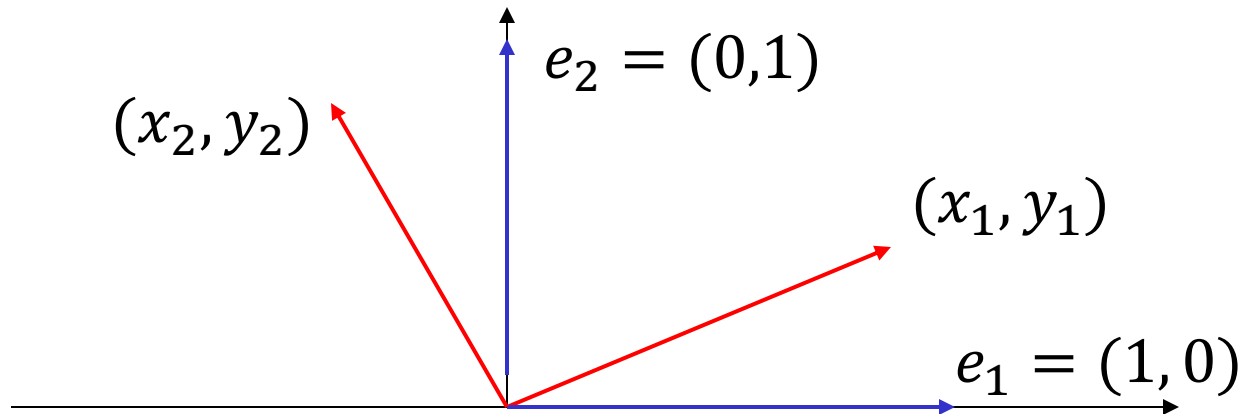
$$0p = 0, \text{ whose degree is } 0.$$

□ Therefore, it is **not** a subspace.

## Additional Explanation on Q.2(b)

- ❑ To better understand the solution (which applies to any value of  $n$ ), you may consider a concrete example, say,  $n = 2$ .
- ❑ The set of all polynomials with degree equal to 2 is  $\{ax^2 + bx + c : a > 0\}$ .
  - Note that  $a$  must be positive, for otherwise the degree of the polynomial is less than 2.
- ❑ Consider  $x^2$  and  $-x^2$ , which are both in the above set. The set is **not closed under addition** because  $x^2 + (-x^2) = 0$ , which has degree 0.
- ❑ It can also be proved that the set is **not closed under scalar multiplication** by choosing the scalar to be 0.

## Question 3: Rotation

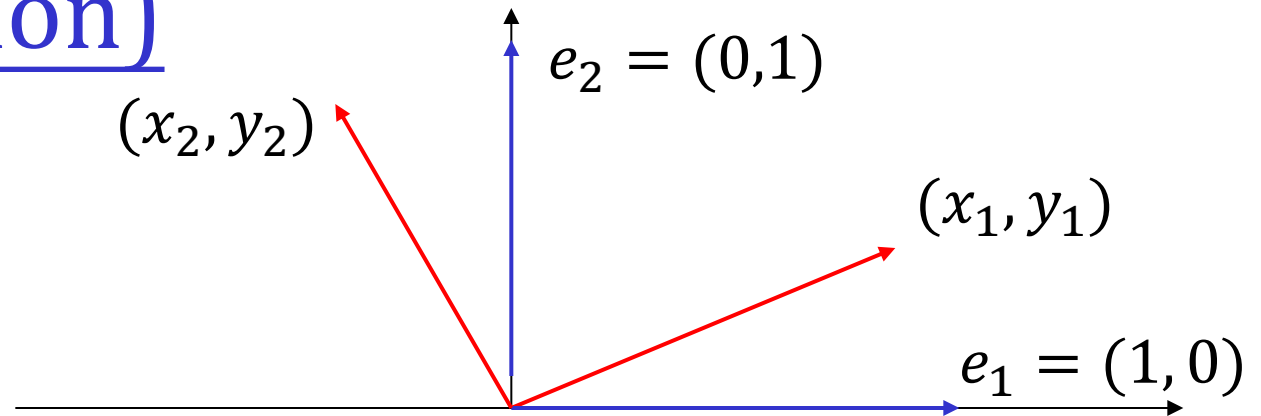


Consider anti-clockwise rotations of  $e_1$  and  $e_2$  by  $30^\circ$ .

- a) Find  $(x_1, y_1)$  and  $(x_2, y_2)$ .
- b) Consider an arbitrary vector  $v = (x, y)$ . Express  $v$  as a linear combination of  $e_1$  and  $e_2$ .
- c) What is the resultant vector after rotating  $v$  by  $30^\circ$ ?
- d) What is the corresponding rotation matrix?



## Q.3 (solution)



- a)  $(x_1, y_1) = \left(\frac{\sqrt{3}}{2}, \frac{1}{2}\right), (x_2, y_2) = \left(-\frac{1}{2}, \frac{\sqrt{3}}{2}\right)$
- b)  $v = xe_1 + ye_2$
- c)  $v' = x\left(\frac{\sqrt{3}}{2}, \frac{1}{2}\right) + y\left(-\frac{1}{2}, \frac{\sqrt{3}}{2}\right)$  (by linearity)  
 $= \left(\frac{\sqrt{3}}{2}x - \frac{1}{2}y, \frac{1}{2}x + \frac{\sqrt{3}}{2}y\right)$
- d)  $A = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$

## Question 4: Projection

Consider the straight line  $y = \frac{x}{2}$  in the 2-dimensional space.

- a) Find the matrix that projects any vector to the above line.
- b) Hence, find the projection of  $(3, 2)$  onto the above line.

## Q.4 (solution)

- a) The slope is  $\frac{1}{2}$ . Consider a right-angled triangle with base 2, height 1, and hypotenuse  $\sqrt{5}$ .  
Therefore,  $\cos \theta = \frac{2}{\sqrt{5}}$  and  $\sin \theta = \frac{1}{\sqrt{5}}$ .

The projection matrix is

$$P = \begin{bmatrix} c^2 & cs \\ cs & s^2 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix}.$$

- b) The vector after projection is

$$\frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 16 \\ 8 \end{bmatrix}.$$

## Question 5: Geometric Transformations

- ❑ Consider the vector  $(3, 17, 12)$ . First, it is reflected across the  $y$ - $z$  plane. Next, it is projected onto the  $x$ - $y$  plane. Lastly, it is rotated anti-clockwise by  $60^\circ$  on the  $x$ - $y$  plane. What is the  $x$ -component of the resultant vector? Round your answer to 2 decimal places.

## Q5. Solution

### □ Solution:

- Reflection across the  $y$ - $z$  plane:  $(-3, 17, 12)$ .
- Projection onto the  $x$ - $y$  plane:  $(-3, 17, 0)$ .
- Rotation anti-clockwise by  $60^\circ$  on the  $x$ - $y$  plane:
$$\begin{bmatrix} \cos 60^\circ & -\sin 60^\circ \\ \sin 60^\circ & \cos 60^\circ \end{bmatrix} \begin{bmatrix} -3 \\ 17 \end{bmatrix} = \begin{bmatrix} -16.22 \\ 5.90 \end{bmatrix}.$$
- Hence, the  $x$ -component is  $-16.22$ .

