Biodiversity data analysis workshop – Day 2

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science & technology
Department:
Science and Technology
REPUBLIC OF SOUTH AFRICA

NRF National Research Foundation

SANBI
Biodiversity for Life
South African National Biodiversity Institute

31st October 2019

Programme – Day 2

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08h30 – 10h00	Session 1 – Introduction to R, RStudio, basics of programming
10h00 – 10h30	Tea break
10h30 – 12h15	Session 2 – Data wrangling with the tidyverse
12h15 – 13h30	Lunch
13h30 – 15h00	Session 3 – Data visualisation using ggplot2
15h00 – 15h30	Tea break
15h30 – 17h00	Session 4 – Handling spatial data in R

Spatial data types

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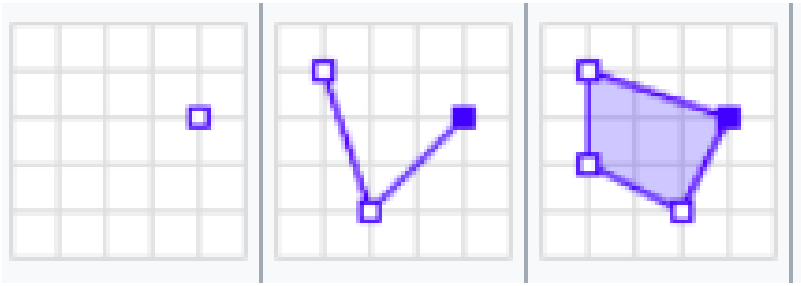
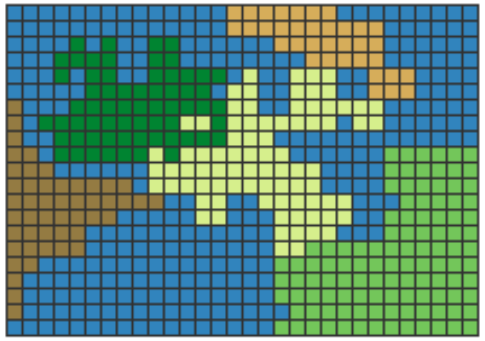
Vector

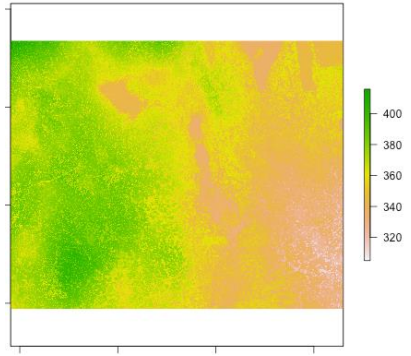
- Points, vertices and paths, polygons



Raster

- A grid with uniformly sized pixels
- Data are discrete or continuous





Vector data

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Points

- X and Y, easting and northing, or longitude and latitude
- Within a spatial reference frame
- e.g., species occurrence observations

Lines

- Connect each vertex (point where two lines meet) with paths
- e.g., rivers, roads, railway lines

Polygons

- Closed path of connected vertices
- Provides a measure of area
- e.g., habitat patch, lake

Raster data

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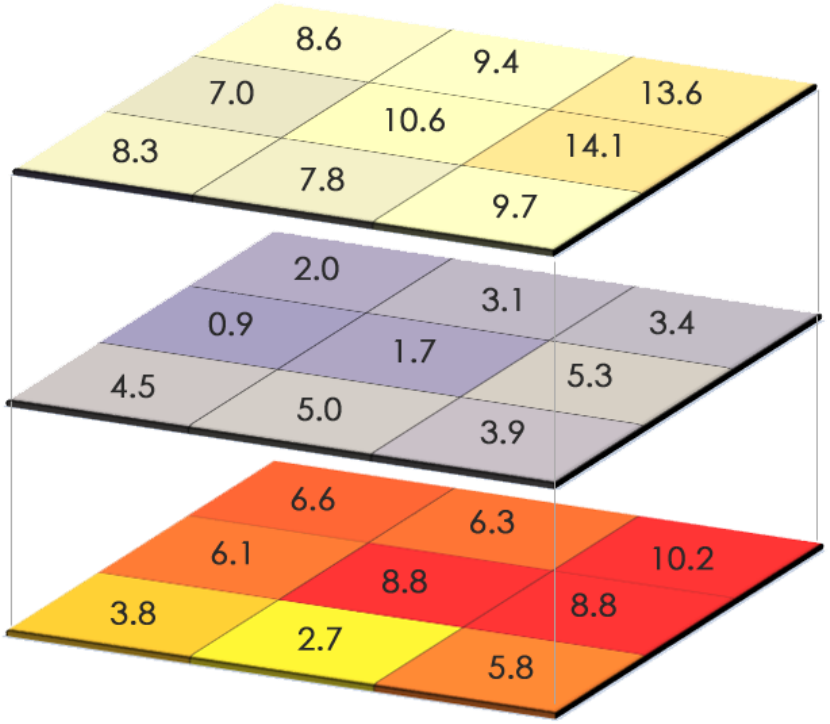
- Made up of pixels (grid cells)
- Each pixel has its own value
- Continuous surface
  - Elevation
  - Rainfall
  - NDVI
  - Remotely sensed (satellite) data
- Discrete (categorical) surface
  - Land cover
  - Vegetation type
- Ability to stack raster surfaces and perform map algebra



Coordinate reference systems (CRS)

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Map projections

- Portray the earth's surface (or part thereof) onto a flat plane
- Spherical shape (3D) to a planar shape (2D)

CRS

- Defines how real places on earth relate to 2D projected map (using a mathematical model)
- Type depends on regional extent and global position of data
- Necessary to calculate distances and areas accurately
- Tells mapping software where the data are and what method should be used to project the data in geographic space

Coordinate reference systems (CRS)

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Components of CRS

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Datum

- Model of the shape of the earth (angular units where starting point [0,0] is defined so that angles can reference meaningful spot)
- Most common WGS84

Projection

- Mathematical transformation of angular measurements
- Units are usually meters or feet

Additional parameters

- Definition of the center of the map and others

Components of CRS

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Datum

Projection

Describing CRS

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Several formats

- EPSG
- PROJ.4 (widely used in R, but *sf* is moving towards using EPSG)

A PROJ4 string includes the following information:

- **proj=**: the projection of the data
- **zone=**: the zone of the data (unique UTM projection)
- **datum=**: the datum use
- **units=**: the units for the coordinates of the data
- **ellps=**: the ellipsoid (how the earth's roundness is calculated) for the data

Comprehensive library - https://spatialreference.org and https://proj.org/operations/projections/index.html

Universal Transverse Mercator (UTM)

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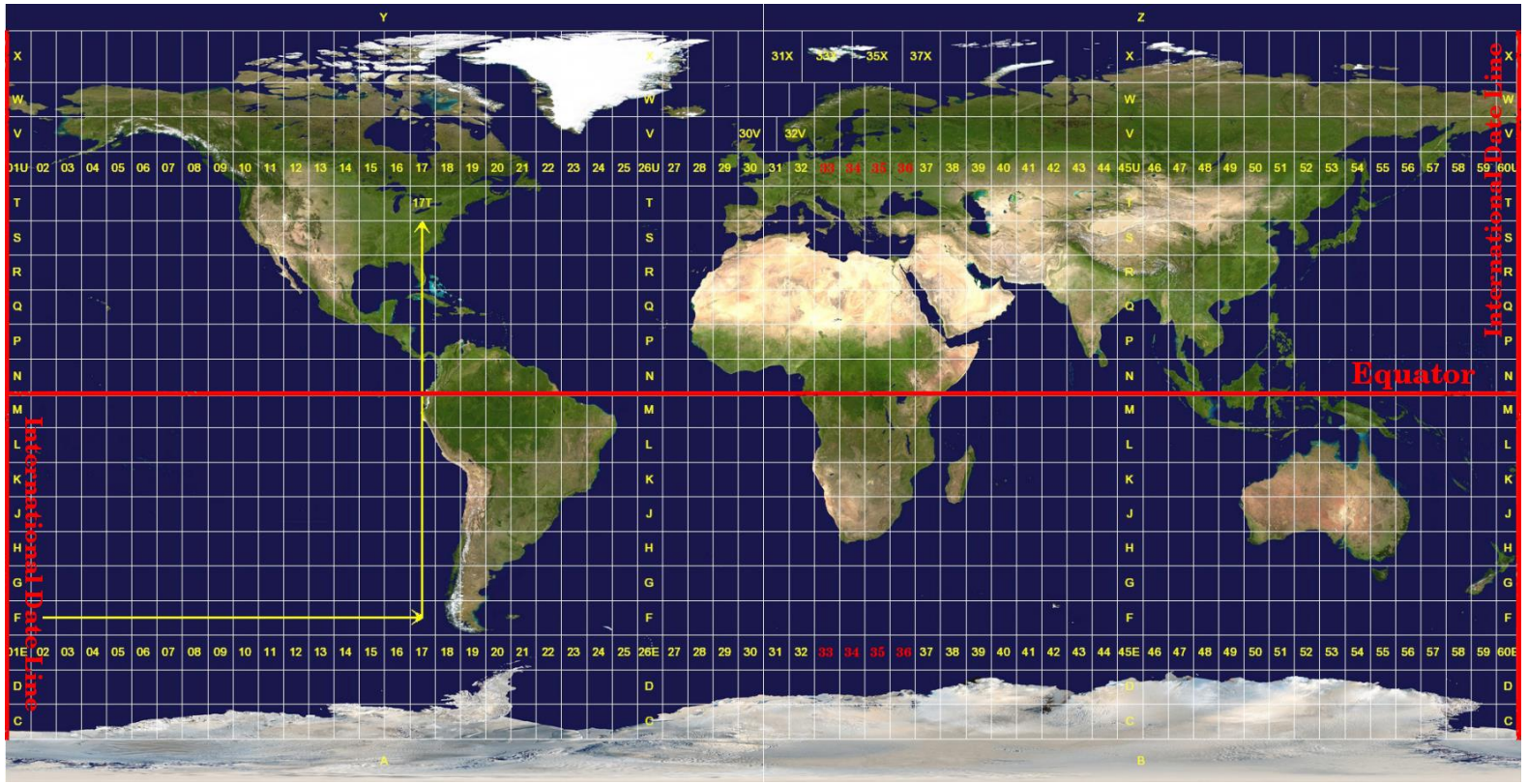
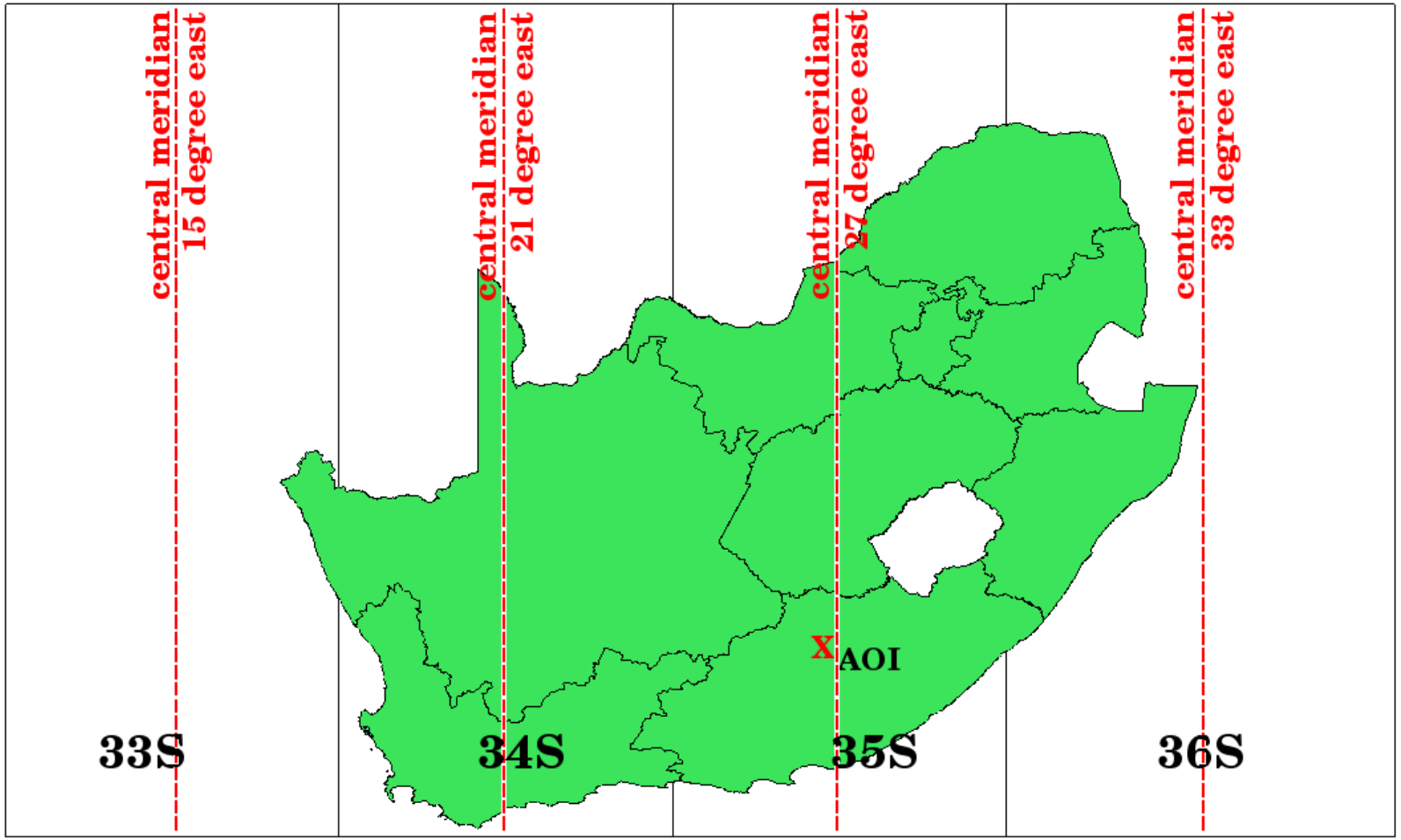
UTM is a global map projection and to avoid distortion the world is divided into 60 equal zones (6 degrees wide)



Universal Transverse Mercator (UTM)



Proj4 example

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Proj4 demo link - LSM

Vector data with the *sf* package

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Simple features

- Geometry describing where they are
- May also have additional attributes which describe properties of the geometries

Simple point feature

- Geometry: XY coordinate
- Attributes: species name, date, collector

Simple feature geometry types

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Type	Description
POINT	zero-dimensional geometry containing a single point
LINESTRING	sequence of points connected by straight, non-self intersecting line pieces; one-dimensional geometry
POLYGON	geometry with a positive area (two-dimensional); sequence of points form a closed, non-self intersecting ring; the first ring denotes the exterior ring, zero or more subsequent rings denote holes in this exterior ring
MULTIPOINT	set of points; a MULTIPOINT is simple if no two Points in the MULTIPOINT are equal
MULTILINESTRING	set of linestrings
MULTIPOLYGON	set of polygons
GEOMETRYCOLLECTION	set of geometries of any type except GEOMETRYCOLLECTION

Simple feature geometry types

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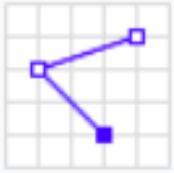
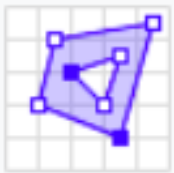
Geometry primitives (2D)

Type	Examples	
Point		`POINT (30 10)`
LineString		`LINESTRING (30 10, 10 30, 40 40)`
Polygon		`POLYGON ((30 10, 40 40, 20 40, 10 20, 30 10))`
		`POLYGON ((35 10, 45 45, 15 40, 10 20, 35 10), (20 30, 35 35, 30 20, 20 30))`

Simple feature geometry types

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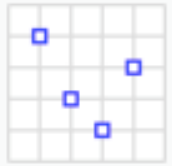
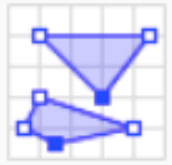
Multipart geometries (2D)

Type	Examples	
MultiPoint		`MULTIPOINT ((10 40), (40 30), (20 20), (30 10))`
		`MULTIPOINT (10 40, 40 30, 20 20, 30 10)`
MultiLineString		`MULTILINESTRING ((10 10, 20 20, 10 40), (40 40, 30 30, 40 20, 30 10))`
MultiPolygon		`MULTIPOLYGON (((30 20, 45 40, 10 40, 30 20)), ((15 5, 40 10, 10 20, 5 10, 15 5)))`
		`MULTIPOLYGON (((40 40, 20 45, 45 30, 40 40)), ((20 35, 10 30, 10 10, 30 5, 45 20, 20 35), (30 20, 20 15, 20 25, 30 20)))`

sf package

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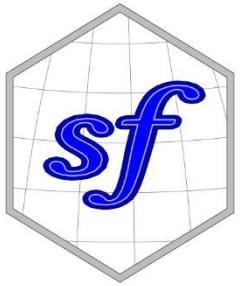
- sf represents simple features as R objects



- All functions and methods in sf that operate on spatial data are prefixed by **`st_`**, which refers to *spatial and temporal*; this makes them easily findable by command-line completion (TAB key)

- Typical use involves reading, manipulating and writing of sets of features, with attributes and geometries.

sf package

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- Attributes are typically stored in **data.frame or tbl_df** objects
- Geometry feature are also stored in **data.frame** column.
- Geometries are not single-valued and are therefore in a list-column (length equal to number of records and each element holds simple feature geometry of that feature)

The three classes used to represent simple features are:

- **sf**, the table (data.frame) with feature attributes and feature geometries, which contains
- **sfc**, the list-column with the geometries for each feature (record), which is composed of
- **sfg**, the feature geometry of an individual simple feature.

sf classes

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```
Simple feature collection with 9 features and 2 fields
geometry type:  MULTIPOLYGON
dimension:      XY
bbox:           xmin: 16.45485 ymin: -34.83304 xmax: 32.89128 ymax: -22.12595
epsg (SRID):    4326
proj4string:    +proj=longlat +datum=WGS84 +no_defs
  PR_CODE        PR_NAME                              geometry
1       1  WESTERN CAPE  MULTIPOLYGON (((17.75758 -3...
2       2  EASTERN CAPE  MULTIPOLYGON (((25.46704 -3...
3       3 NORTHERN CAPE  MULTIPOLYGON (((17.75758 -3...
4       4     FREE STATE  MULTIPOLYGON (((27.59139 -2...
5       5 KWAZULU-NATAL  MULTIPOLYGON (((31.6085 -29...
6       6     NORTH WEST  MULTIPOLYGON (((27.59139 -2...
7       7        GAUTENG  MULTIPOLYGON (((27.59322 -2...
8       8    MPUMALANGA  MULTIPOLYGON (((28.65209 -2...
9       9        LIMPOPO  MULTIPOLYGON (((26.40878 -2...
```

Simple feature (sf)

Simple feature geometry list column (sfc)

Simple feature geometry (sfg)

Reading and writing

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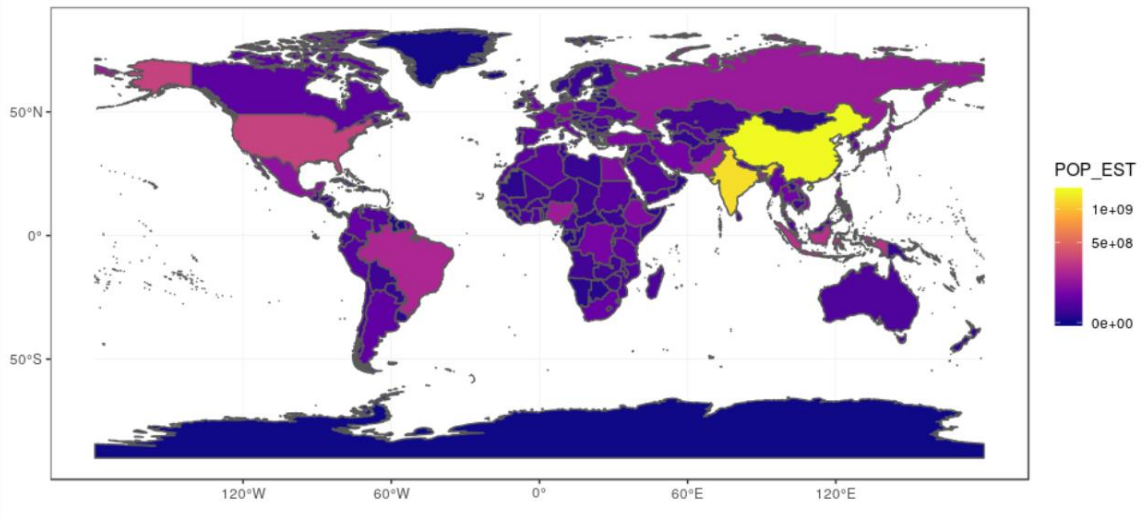
```
read_sf("input/South_Africa_prov.shp")
write_sf(RSA, "outputsouth_africa.shp")
```

Plotting sf objects

- Each attribute can be individually plotted
- Integration with ggplot2()

```
ggplot(data = world) +
    geom_sf(aes(fill = pop_est)) +
    scale_fill_viridis_c(option = "plasma", trans = "sqrt")
```



Rmd demo link - LSM

Rasters

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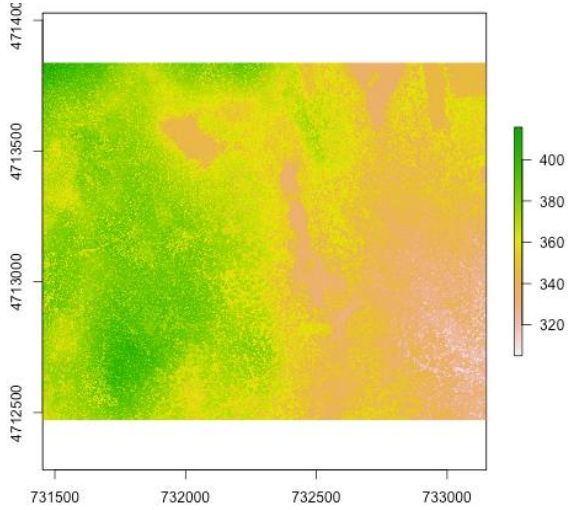
Rasters have a regular structure and are defined by:

- coordinates of its origin
- a distance or cell size in each direction
- a dimension or numbers of cells in each direction
- an array of cell values



raster package

- Major extension of spatial data classes to access large rasters and process very large files
- Object classes include **RasterLayer**, **RasterStacks** and **RasterBricks**
- Simple functions for converting among these classes, and operators for computations on the raster data.
- Vector to raster conversions are also possible

Rasters

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Rmd demo link – LSM

Rmd demo link – handling spatial data