

Time-to-detection occupancy models

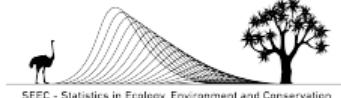
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20 August 2020



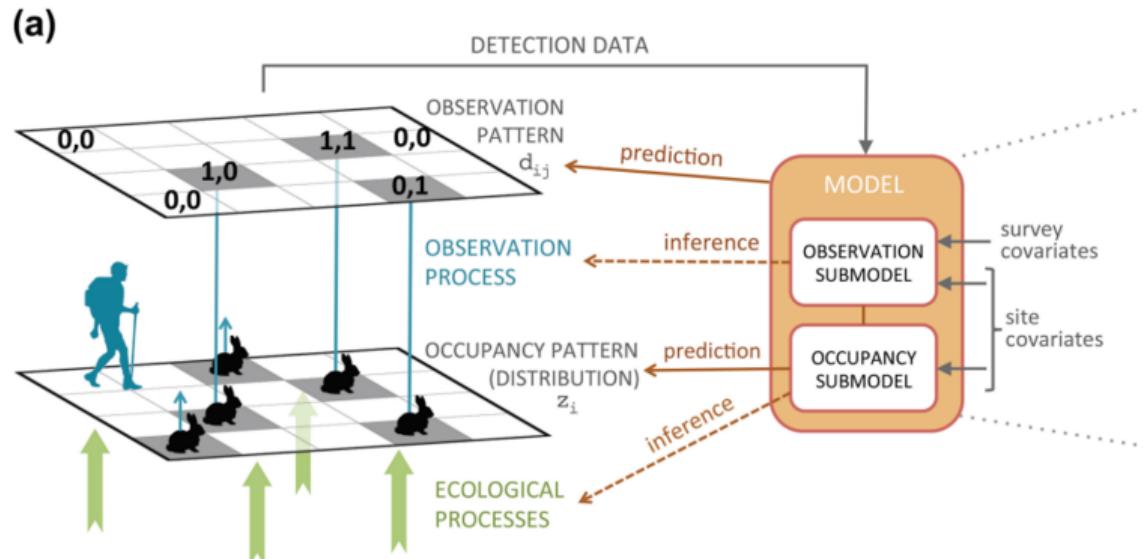
Occupancy models - previous toolboxes

Species	Temporal	Spatial AC	Data	Framework	URL
Single	Static	No	Detection/non-detection	ML	Talk 1
Single	Static	No	Detection/non-detection	Bayesian	Talk 2
Single	Dynamic	No	Detection/non-detection	ML	Talk 3
Single	Static	Yes	Detection/non-detection	Bayesian	Talk 4
Multi	Static	No	Continuous time	Bayesian	Talk 5

Outline of toolbox

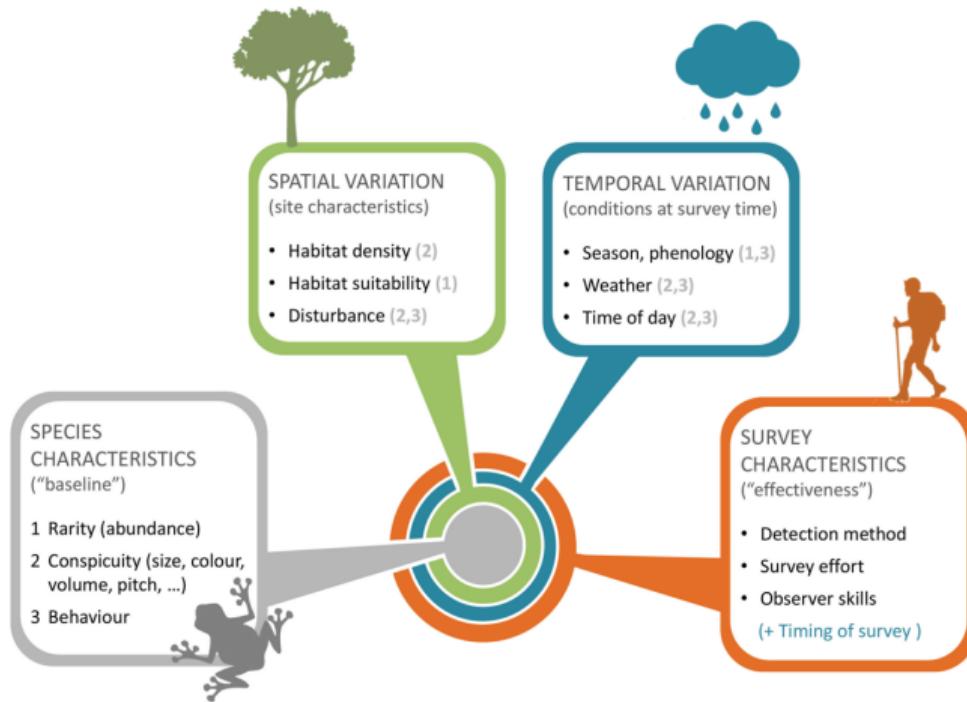
- Background of TTD models
- Single species TTD model (simulated data)
- Data processing (field data)
- Multi-species TTD model
- Plotting parameters and predictions

Occupancy models



Guillera-Arriota, G. 2016. *Ecography* 39: 1-15

Factors that influence detection



Guillera-Arriota, G. 2016. *Ecography* 39: 1-15

Data requirements



Guillera-Arriota, G. 2016. *Ecography* 39: 1-15

Origins of TTD



Austral Ecology (2008) 33, 986–998

When have we looked hard enough? A novel method for setting minimum survey effort protocols for flora surveys

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Origins of TTD

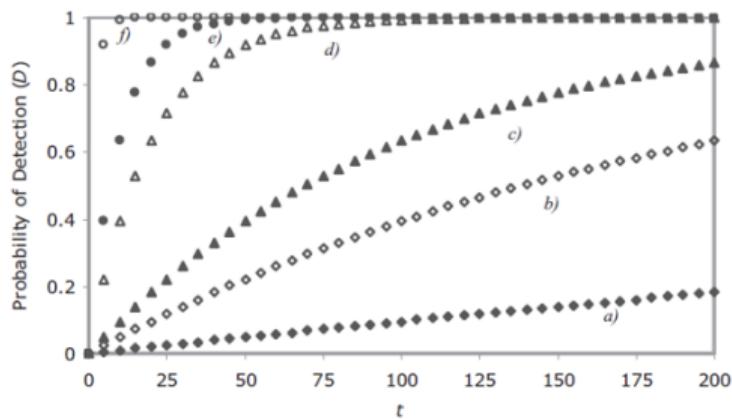


Fig. 5. Detectability curves for species with single time step detection probabilities (λ) of: (a) 0.001, (b) 0.005, (c) 0.01, (d) 0.05, (e) 0.1 and (f) 0.5. Curves like these can be used to determine the length of time an observer would need to spend looking for a species to achieve a specified level of certainty of detecting it if it is present at a site. For example, for a species which has an average detection time $\bar{t} = 100$ ($\lambda = 0.01$, curve c), an observer would need to spend around 165 time steps to achieve a probability of detection of 0.80.

Detection curves

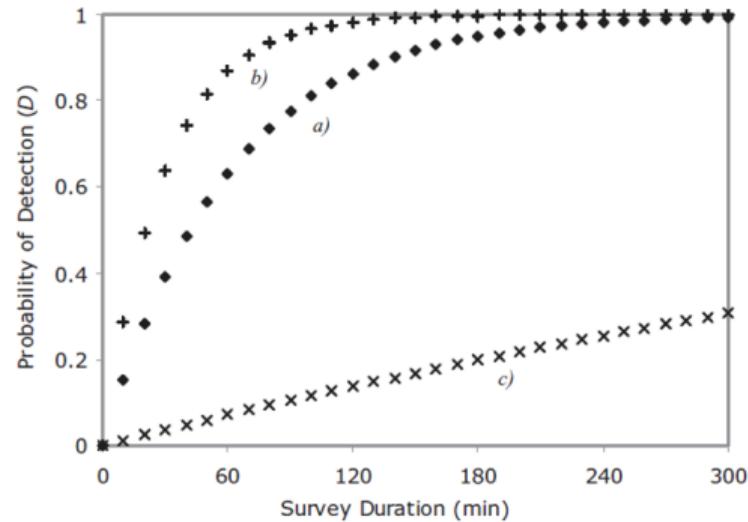


Fig. 6. Detectability curves for *Calocephalus citreus*, a plant found in Melbourne's Western (Basalt) Plains Grassland, under (a) average conditions; (b) best-case conditions; and (c) worst-case conditions.



Time-to-detection models

State process

$$z_{ik} \sim \text{Bernoulli}(\psi_{ik}) \quad (1)$$

Observation process

$$y_{ijk} | z_{ik} \sim \text{Exponential}(\lambda_{ijk}) C(T_{max_{ij}}) \quad (2)$$

Detection probability after survey duration d

$$p = 1 - e^{-\lambda_k * d} \quad (3)$$

Notation: site i , survey j , species k

Censoring of data

Model for occurrence

$$z_{ik} \sim \text{Bernoulli}(\psi_{ik})$$

Model for censoring of data

$$d(T\max_{ij}) = z_{ik} * I(y_{ijk} > T\max_{ij}) + (1 - z_{ik})$$

Model for observed data of data

$$\begin{aligned} y_{ijk} | z_{ik} &\sim \text{Exponential}(\lambda_{ijk}) && \text{if } d_{ijk} = 0 \\ y_{ijk} &= NA && \text{if } d_{ijk} = 1 \end{aligned}$$

Weibull distribution

Generalisation of the exponential distribution

Detection rate can vary over time (e.g., decrease as surveys progress)

Shape parameter (k) governs the change in rate

- $k = 1$ exponential with constant rate
- $0 < k < 1$ detection rate decreases over time
- $k > 1$ detection rate increases over time

Read: Medina-Romero, et al. 2019. Ecography 42(9): 1514-1522.

Can we reduce sampling effort?

Methods in Ecology and Evolution



Methods in Ecology and Evolution 2014, 5, 433–442

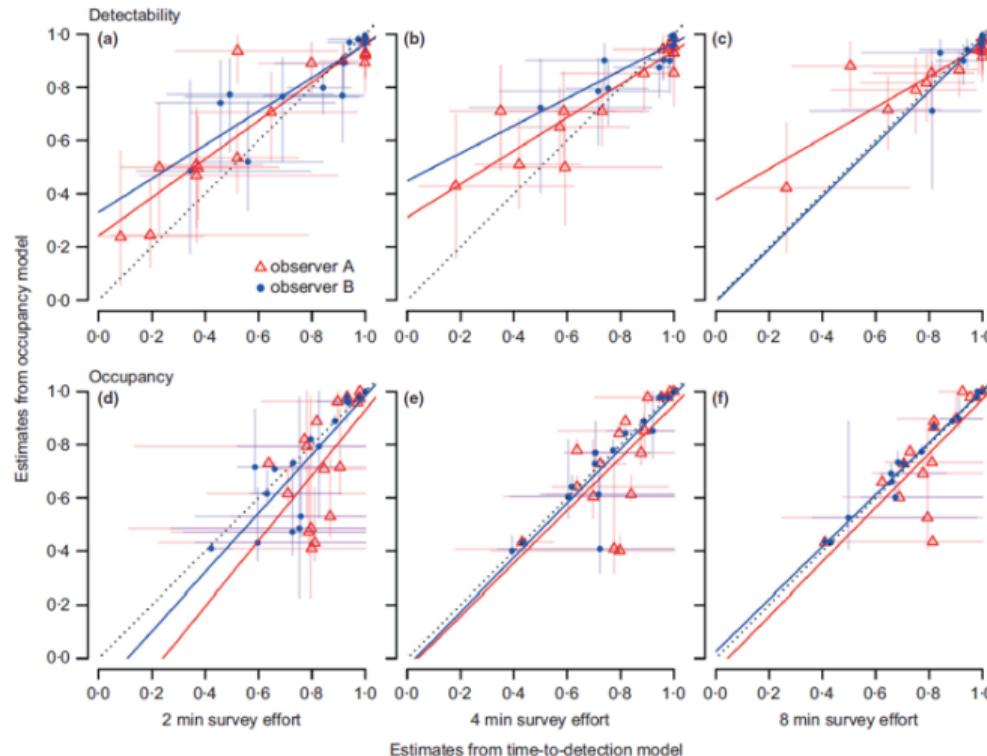
doi: 10.1111/2041-210X.12171

Hide-and-seek in vegetation: time-to-detection is an efficient design for estimating detectability and occurrence

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Can we reduce sampling effort?



How well do these models perform?

Received: 4 October 2019

Accepted: 7 February 2020

DOI: 10.1111/2041-210X.13379

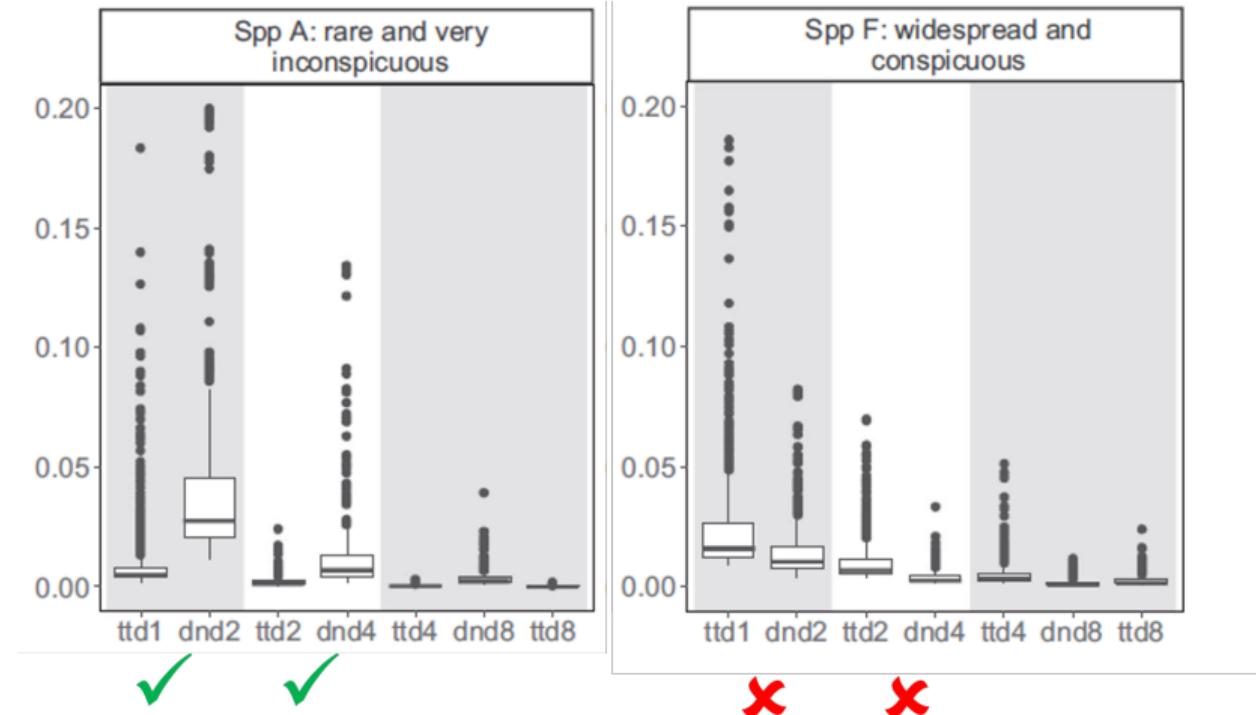
RESEARCH ARTICLE

Methods in Ecology and Evolution 

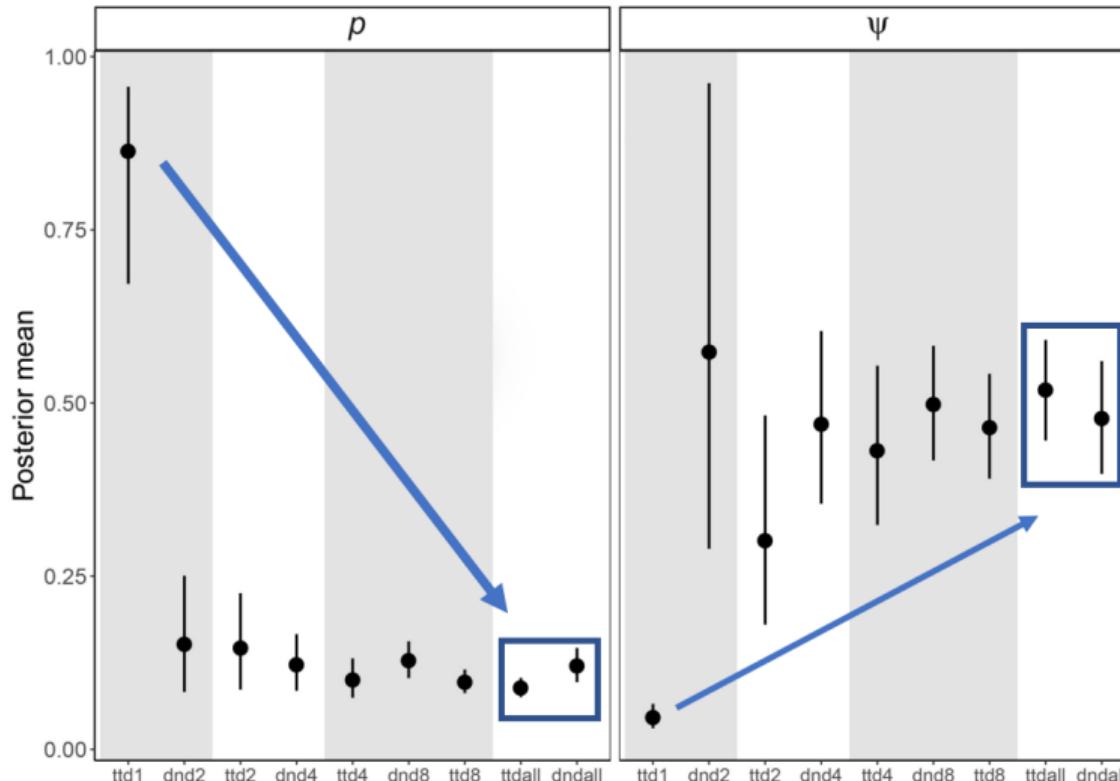
Can time-to-detection models with fewer survey replicates provide a robust alternative to traditional site-occupancy models?

Dominic A. W. Henry^{1,2}  | Alan T. K. Lee^{3,4} | Res Altwegg^{1,5} 

How well do these models perform?



How well do these models perform?



What are our options for TTD modelling?

Maximum likelihood

- unmarked::occuTTD
- Pros: Built-in functions, fast, easy to use, single & multi-season
- Cons: Single species, not customisable

What are our options for TTD modelling?

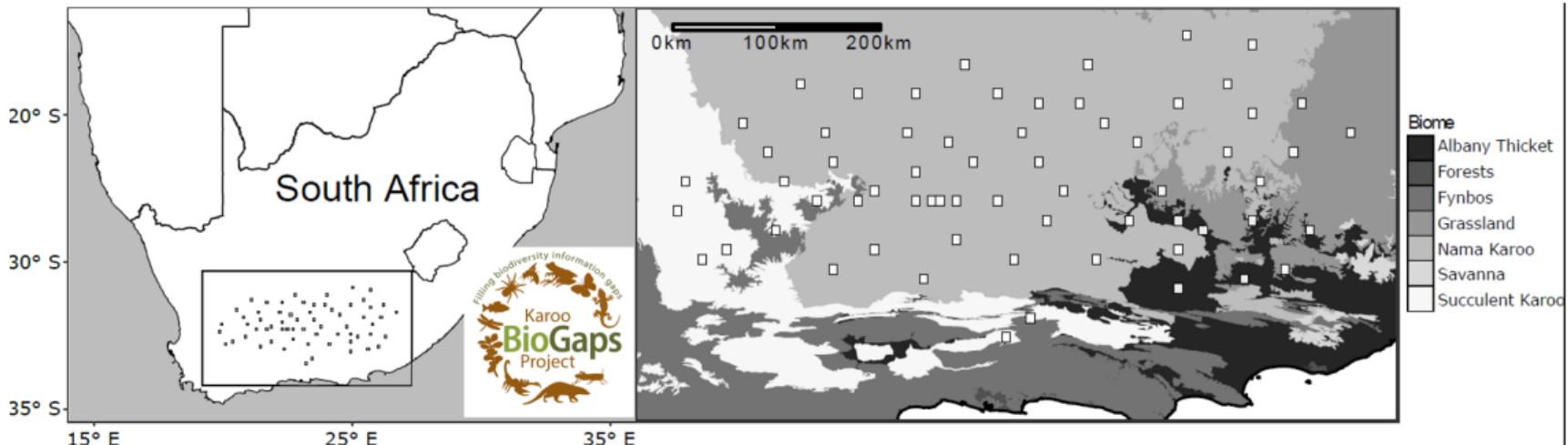
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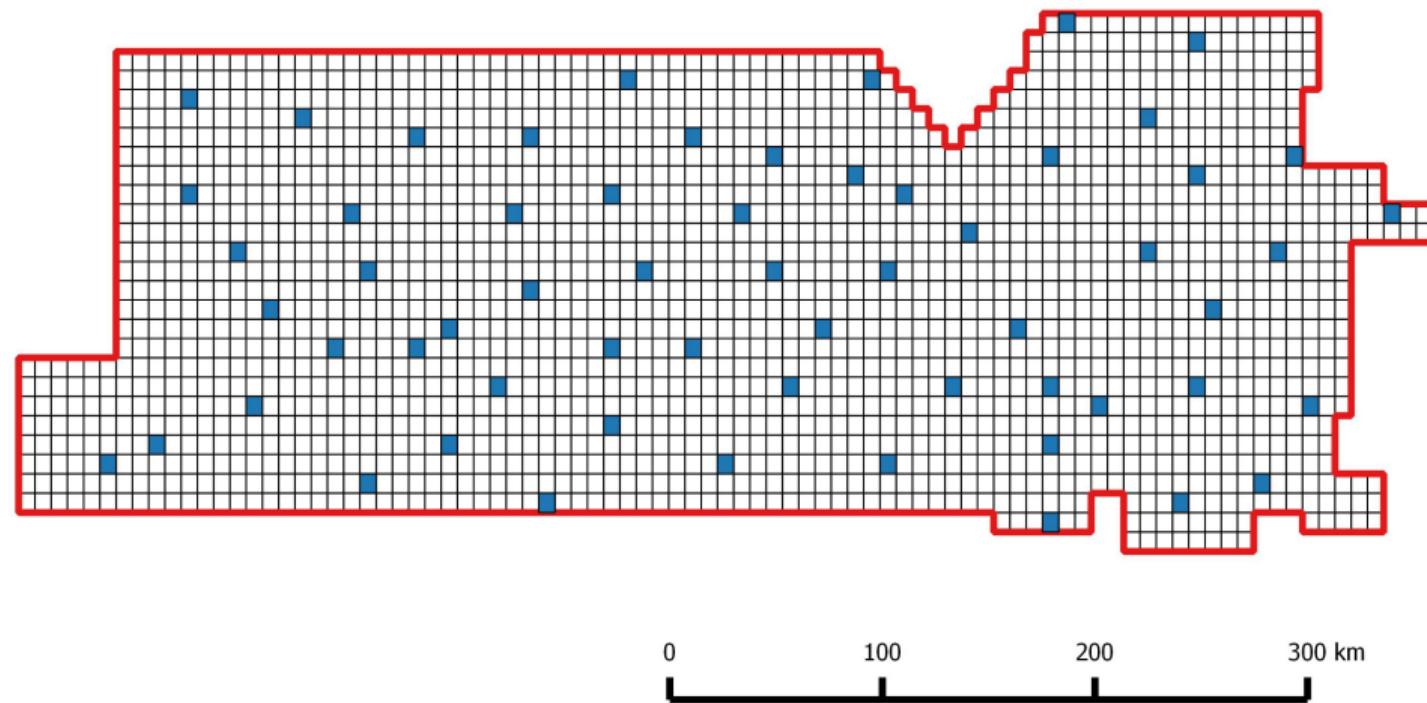
Bayesian

- WinBUGS, JAGS, NIMBLE, STAN, Greta
- Pros: Multi-species, random effects, custom distributions, sky is the limit
- Cons: manual model formulations, runtime, unhelpful error messages, computationally intensive

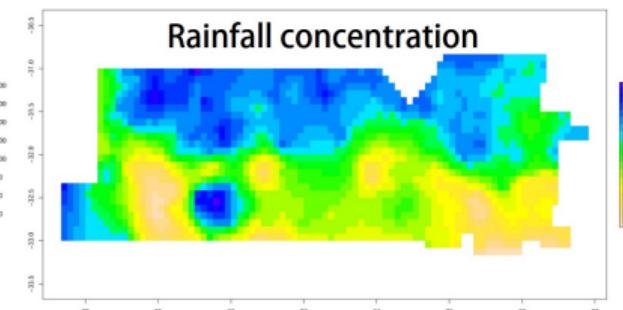
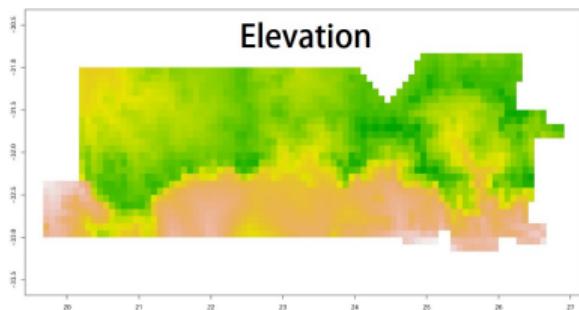
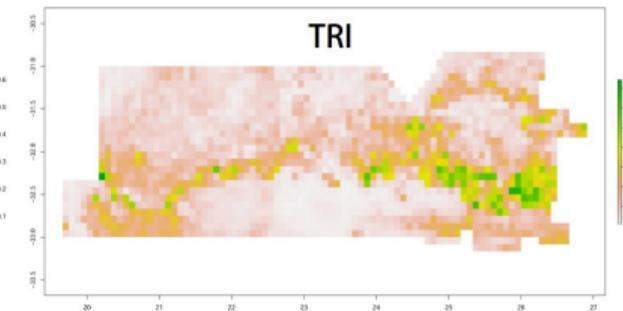
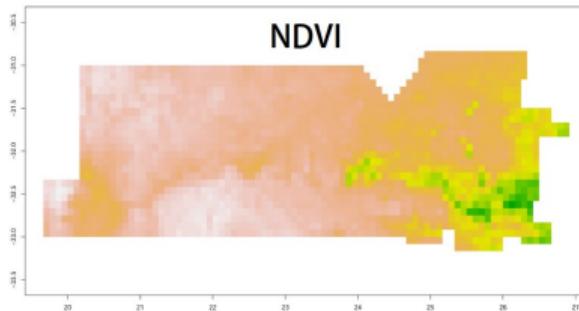
Multi-species TTD models of Karoo avifauna



Survey layout



Covariates



Detection covariates: Wind, cloud, temperature, Julian day, time of day

TTD model formulation

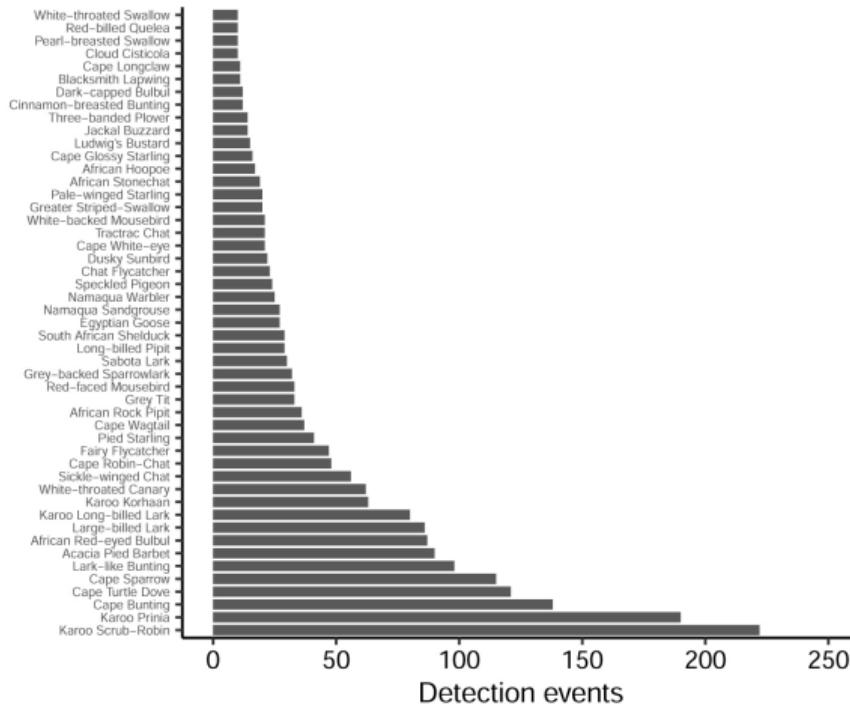
Occurrence

$$\text{logit}(\Psi_{ik}) = \beta_{0k} + \beta_{1k} \times \text{NDVI}_i + \beta_{2k} \times \text{PCI}_i + \beta_{3k} \times \text{elev}_i + \beta_{4k} \times \text{TRI} \quad (4)$$

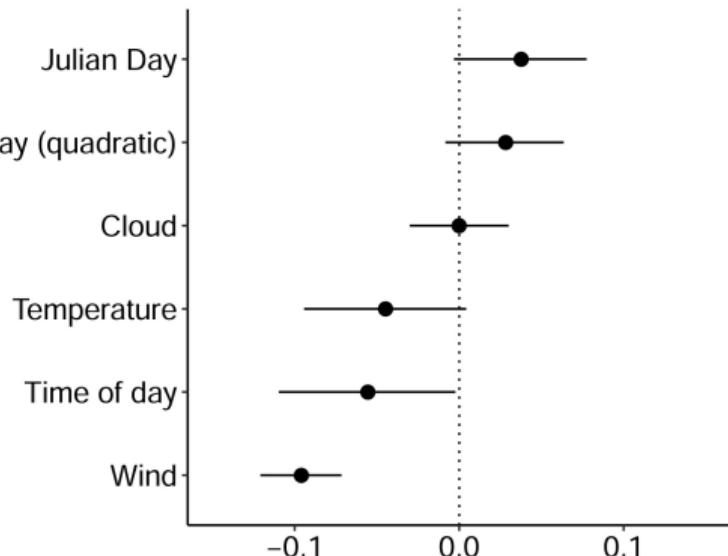
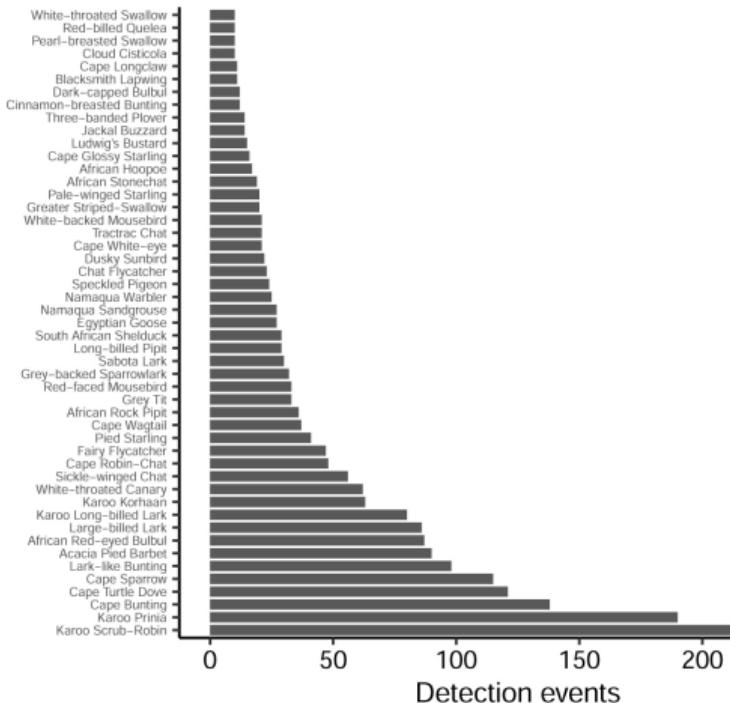
Detection

$$\begin{aligned} \log(\lambda_{ijk}) = & \alpha_{0k} + \alpha_1 \times \text{JulianDay}_{ij} + \alpha_2 \times \text{TOD}_{ij} + \alpha_3 \times \text{TOD}_{ij}^2 + \\ & \alpha_4 \times \text{temp}_{ij} + \alpha_5 \times \text{wind}_{ij} + \alpha_6 \times \text{cloud}_{ij} \end{aligned} \quad (5)$$

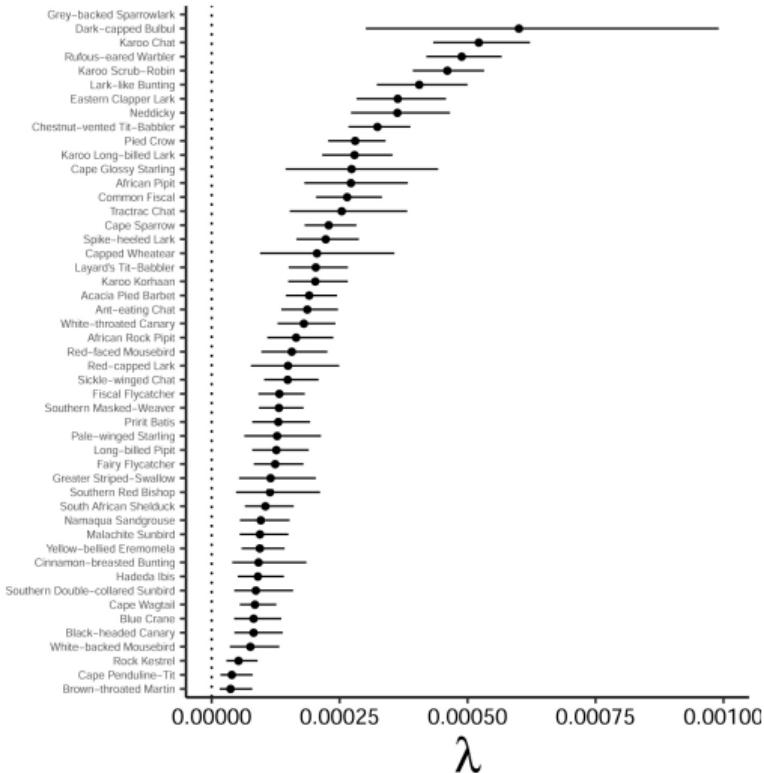
Results - detection



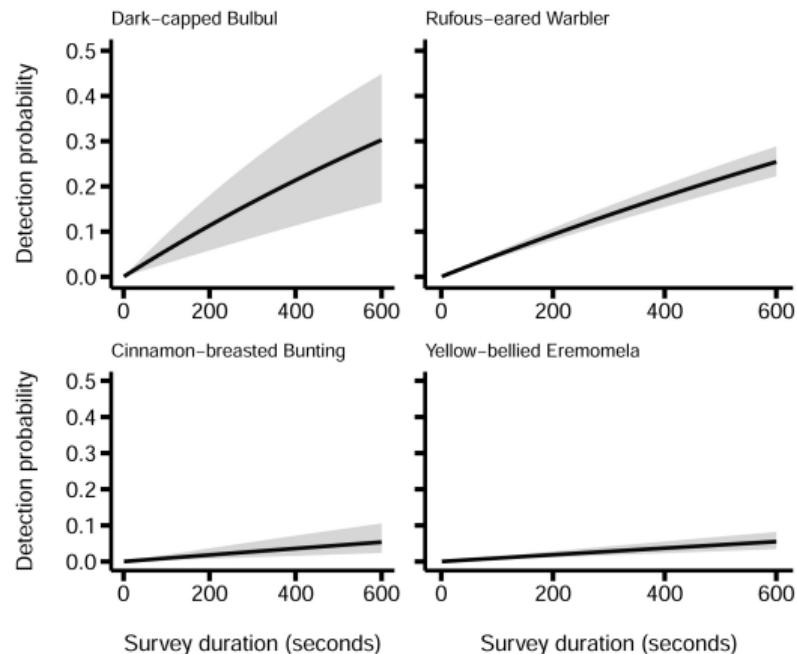
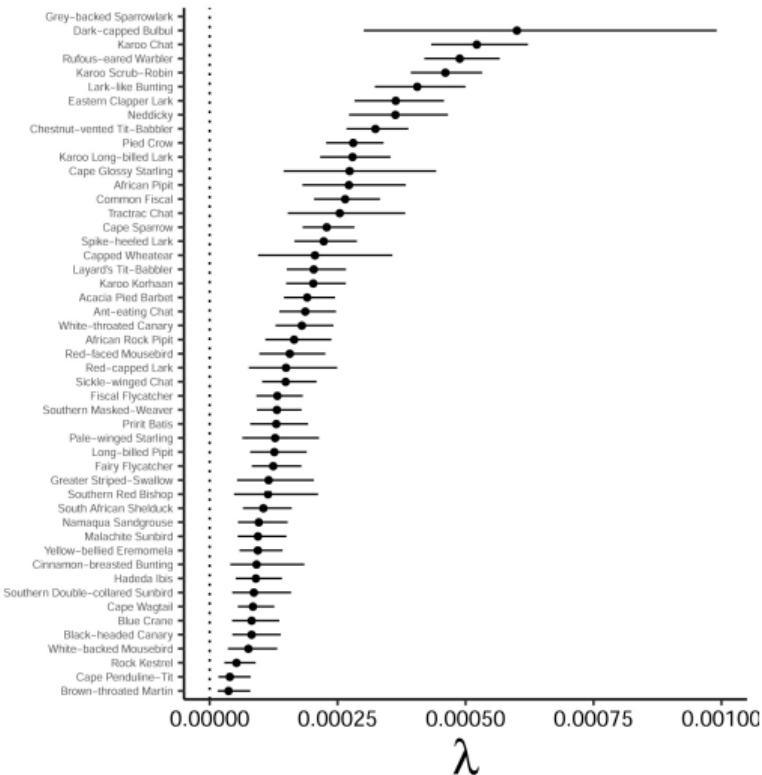
Results - detection



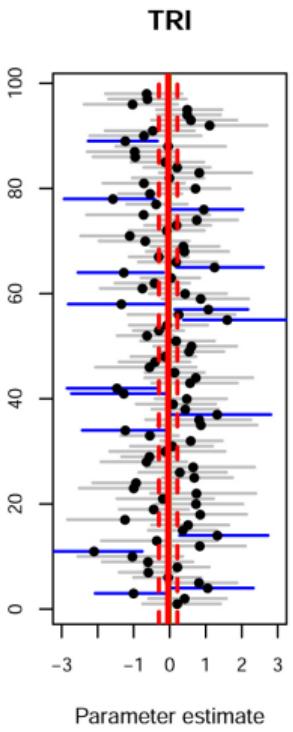
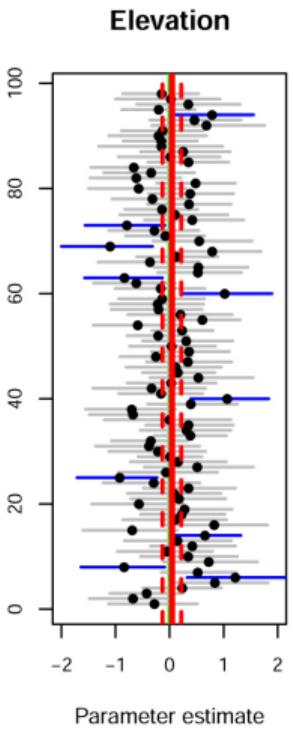
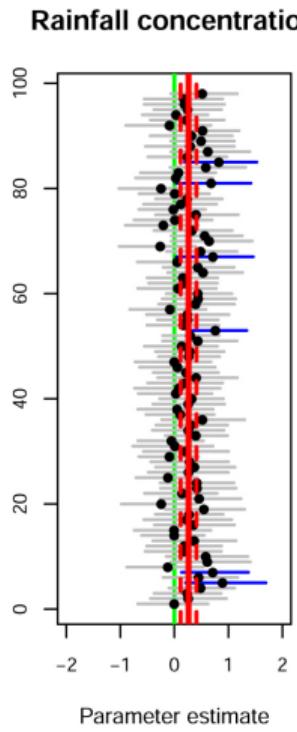
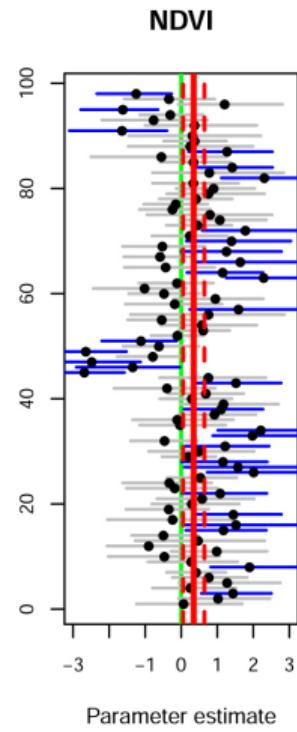
Results - detection



Results - detection



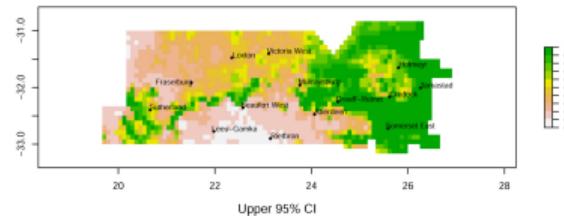
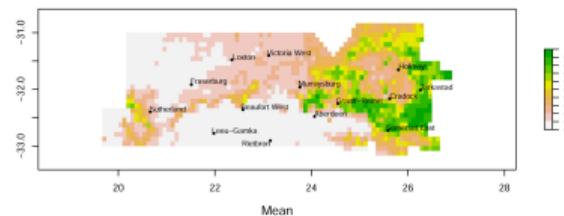
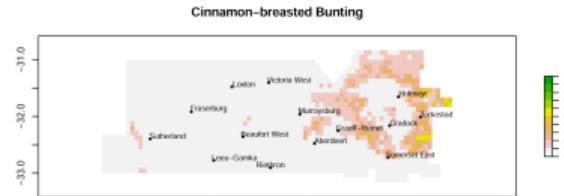
Results - occupancy



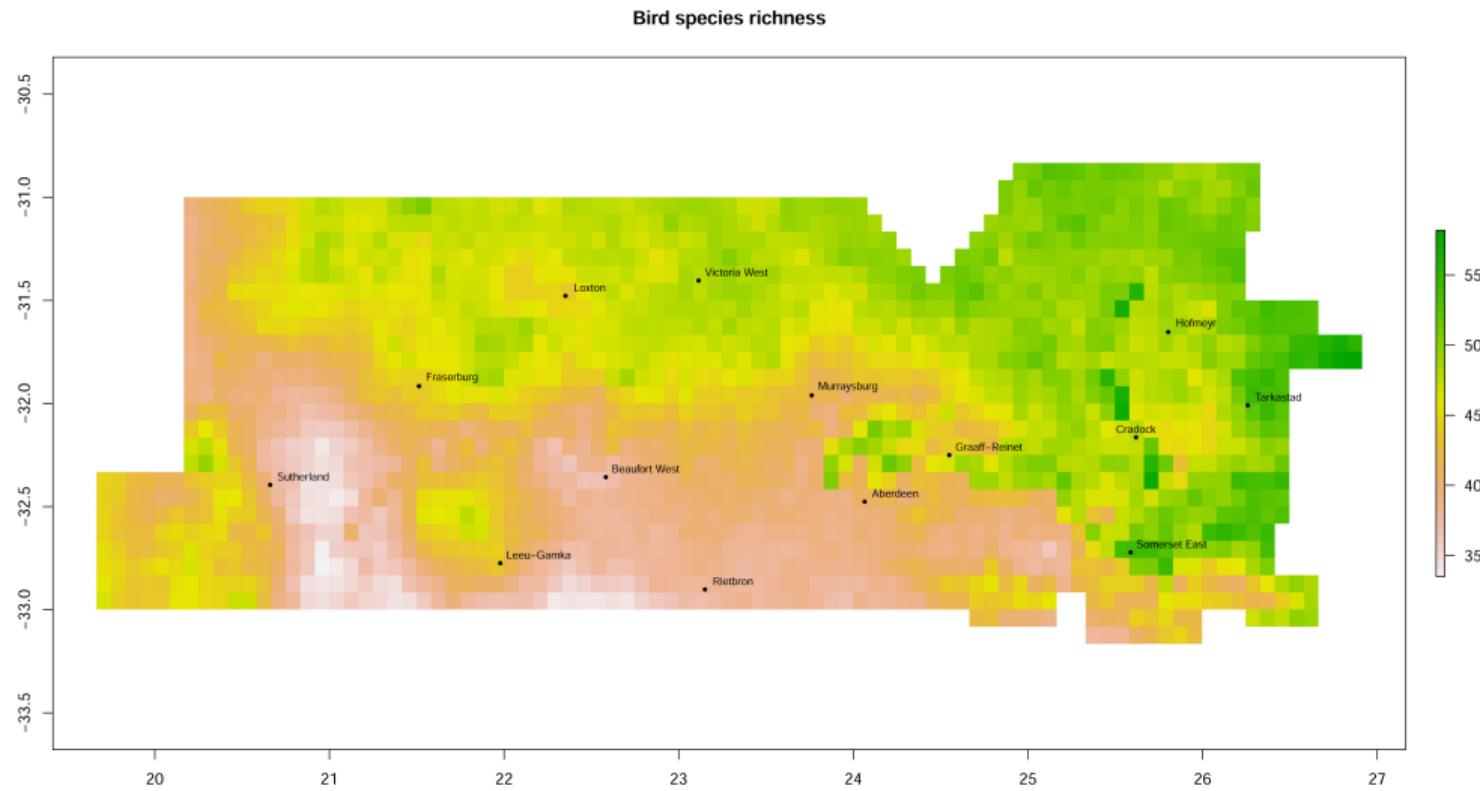
Occurrence maps



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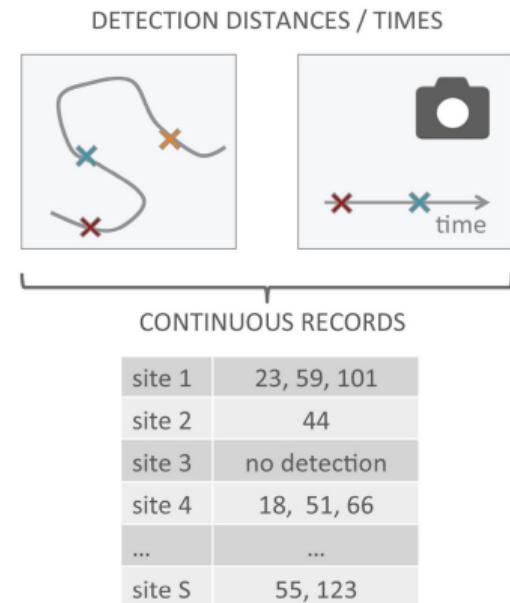


Species richness map



Recap

- Time-to-detection can provide a robust and cost effective alternative
- Detection curves as a useful by-product
- Survey replicates are still important
- Think carefully about nested set of factors that influence detection in focal species/community
- Consider whether changes in detection rate are important (Weibull)



Key references

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- GitHub page with toolbox materials: <https://github.com/DomHenry/SEEC-ttd-Toolbox>