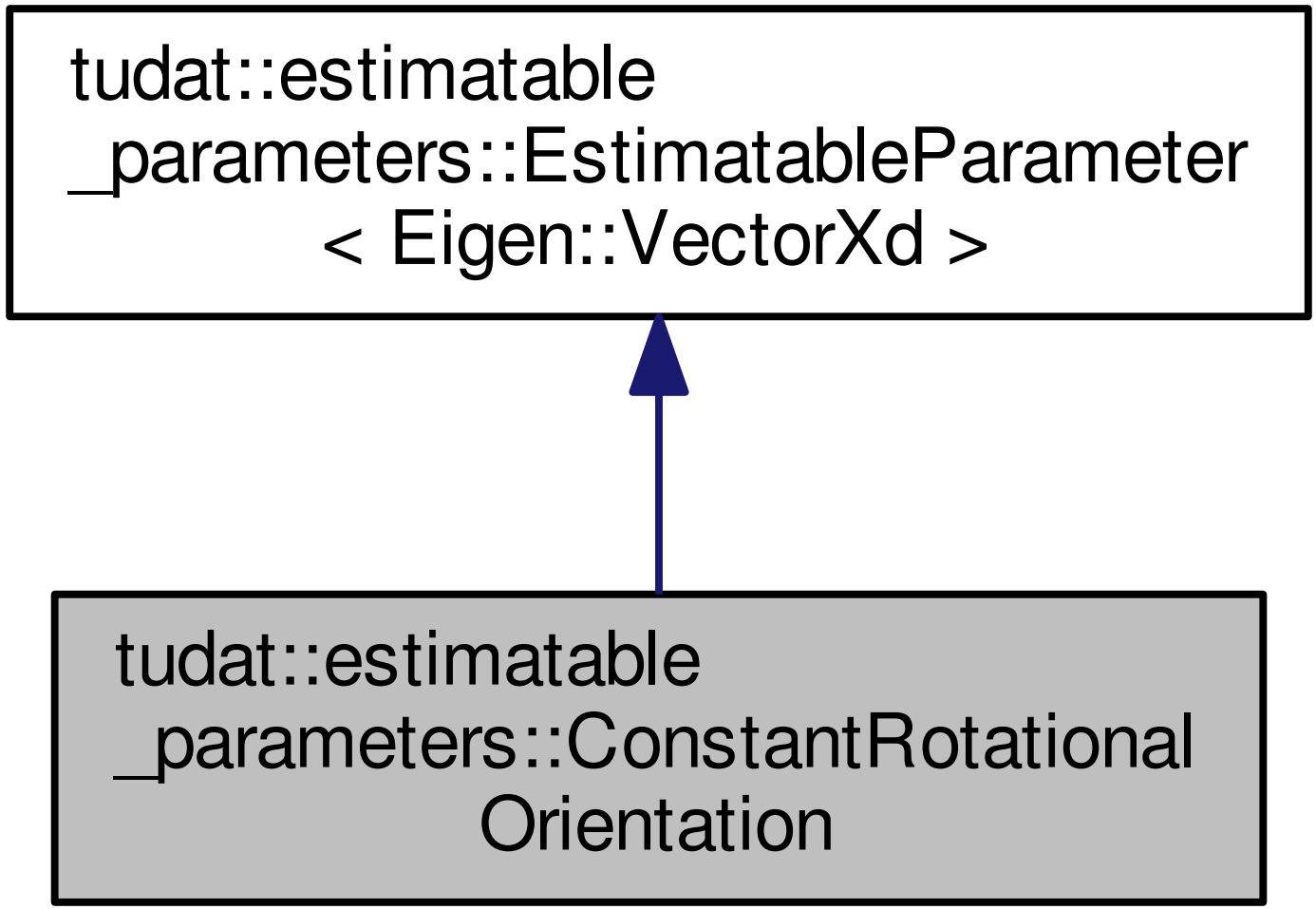
tudat::estimatable
_parameters::EstimatableParameter
< Eigen::VectorXd >
tudat::estimatable
_parameters::ConstantRotational
Orientation