

1. Let  $A = \begin{bmatrix} 1 & 1 & 5 & 0 & 3 \\ 1 & 1 & 5 & 1 & 4 \\ 2 & 0 & 6 & 1 & 5 \\ 1 & 0 & 3 & 0 & 2 \end{bmatrix}$ .

a. Find a basis for the image of  $A$  and find a basis for the kernel of  $A$ .

We find that  $\text{rref}(A) = \begin{bmatrix} 1 & 0 & 3 & 0 & 2 \\ 0 & 1 & 2 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ . By identifying the pivot

columns of  $A$  and using the Solution Algorithm we determine that

a basis for  $\text{im}(A)$  is  $(\vec{v}_1, \vec{v}_2, \vec{v}_3) = \left( \begin{bmatrix} 1 \\ 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right)$ , and

a basis for  $\text{ker}(A)$  is  $(\vec{w}_1, \vec{w}_2) = \left( \begin{bmatrix} 3 \\ 2 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \\ -1 \end{bmatrix} \right)$ ,

b. Use your results in part a to describe all vectors  $\vec{b}$  for which the linear equation  $A\vec{x} = \vec{b}$  has a solution.

$\vec{b}$  must be in  $\text{im}(A)$ , so  $\vec{b} = a_1 \vec{v}_1 + a_2 \vec{v}_2 + a_3 \vec{v}_3 \quad \forall \quad a_1, a_2, a_3 \in \mathbf{R}$ .

c. If  $\vec{x}_1$  and  $\vec{x}_2$  are any solutions of the linear equation  $A\vec{x} = \vec{b}$ , use your results in part a to describe the vector  $\vec{x}_1 - \vec{x}_2$ .

$\vec{x}_1 - \vec{x}_2$  must belong to  $\text{ker}(A)$ , so  $\vec{x}_1 - \vec{x}_2 = c_1 \vec{w}_1 + c_2 \vec{w}_2 \quad \forall \quad c_1, c_2 \in \mathbf{R}$ .

2. Let  $P = \frac{1}{9} \begin{bmatrix} 5 & 4 & -2 \\ 4 & 5 & 2 \\ -2 & 2 & 8 \end{bmatrix}$  and let  $W = \text{im}(P)$  and let  $W^\perp$  be the subset

of  $\mathbf{R}^3$  consisting of all vectors in  $\mathbf{R}^3$  orthogonal to all vectors in  $W$ .

a. What algebraic properties of  $P$  verify that  $P$  is a projection matrix?  
 $P^2 = P^T = P$ .

b. Demonstrate that  $W^\perp$  is a subspace of  $\mathbf{R}^4$ .  
 $W^\perp$  is the set of all vectors in  $\mathbf{R}^4$  that are orthogonal to all the vectors in

$W$ . We have to show that  $W^\perp$  is nonempty and it is closed under vector addition and multiplication by scalars.  $\vec{0}$  is in  $W^\perp$  since  $\vec{0}$  is orthogonal to every vector. Next, suppose that  $\vec{y}_1$  and  $\vec{y}_2$  are both in  $W^\perp$ . Then each is orthogonal to any  $\vec{w}$  in  $W$ . Take any linear combination of  $\vec{y}_1$  and  $\vec{y}_2$ , say  $a_1 \vec{y}_1 + a_2 \vec{y}_2$ . We obtain  $\vec{w} \cdot (a_1 \vec{y}_1 + a_2 \vec{y}_2) = a_1 \vec{w} \cdot \vec{y}_1 + a_2 \vec{w} \cdot \vec{y}_2 = a_1 0 + a_2 0 = 0 + 0 = 0$ . So, we have shown that  $a_1 \vec{y}_1 + a_2 \vec{y}_2$  is also orthogonal to any vector in  $W$ .

c. Determine the matrix  $P^\perp$  for projection onto the subspace  $W^\perp$ . Projection onto  $W^\perp$  is what remains after removing projection onto  $W$ , i.e.

$$P^\perp = I - P = \frac{1}{9} \begin{bmatrix} 4 & -4 & 2 \\ -4 & 4 & -2 \\ 2 & -2 & 1 \end{bmatrix}.$$

d. Calculate the smallest value for the expression  $\|\vec{v} - \vec{w}\|$  if  $\vec{v} = \begin{bmatrix} 9 \\ 9 \\ 9 \end{bmatrix}$  and

$\vec{w}$  is any vector in  $W$ .

The expression is smallest when  $\vec{w}$  is the projection of  $\vec{v}$  onto  $W$ , i.e. for

$$\|\vec{v} - \vec{w}\| = \|\vec{v} - P\vec{v}\| = \|(I - P)\vec{v}\| = \|P^\perp \vec{v}\| = \left\| \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} \right\| = 3.$$

3. Consider the list  $\mathcal{B} = (\vec{v}_1, \vec{v}_2, \vec{v}_3) = \left( \begin{bmatrix} 2 \\ 3 \\ 6 \end{bmatrix}, \begin{bmatrix} 6 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 11 \\ -1 \\ 5 \end{bmatrix} \right)$  and notice that the

first two entries are orthogonal.  $\mathcal{B}$  is a basis for  $\mathbf{R}^3$ .

a. Use the Gram-Schmidt process to determine, from  $\mathcal{B}$ , an orthonormal basis  $\mathcal{C} = (\hat{u}_1, \hat{u}_2, \hat{u}_3)$  for  $\mathbf{R}^3$ .

The first two vectors in  $\mathcal{C}$  are found by normalization and the third by the

usual G-S process. We have  $\hat{u}_1 = \vec{v}_1 / \|\vec{v}_1\| = \frac{1}{7} \begin{bmatrix} 2 \\ 3 \\ 6 \end{bmatrix}$  and  $\hat{u}_2 = \vec{v}_2 / \|\vec{v}_2\| = \frac{1}{7} \begin{bmatrix} 6 \\ 2 \\ -3 \end{bmatrix}$ .

Then,  $\vec{v}_3^\perp = \vec{v}_3 - (\vec{v}_3 \cdot \hat{u}_1)\hat{u}_1 - (\vec{v}_3 \cdot \hat{u}_2)\hat{u}_2 = \vec{v}_3 - 7\hat{u}_1 - 7\hat{u}_2 = \begin{bmatrix} 11 \\ -1 \\ 5 \end{bmatrix} - \begin{bmatrix} 2 \\ 3 \\ 6 \end{bmatrix} - \begin{bmatrix} 6 \\ 2 \\ -3 \end{bmatrix}$

$$= \begin{bmatrix} 3 \\ -6 \\ 2 \end{bmatrix}. \text{ So, } \hat{u}_3 = \vec{v}_3^\perp / \|\vec{v}_3^\perp\| = \frac{1}{7} \begin{bmatrix} 3 \\ -6 \\ 2 \end{bmatrix}.$$

b. Determine the coordinate vector  $\begin{bmatrix} 7 \\ 7 \\ 7 \end{bmatrix}_{\mathcal{C}}$  for  $\begin{bmatrix} 7 \\ 7 \\ 7 \end{bmatrix}$  by using the

orthonormality of  $\mathcal{C}$ .

The coefficients  $c_1$ ,  $c_2$ , and  $c_3$  in  $\vec{w} = \begin{bmatrix} 7 \\ 7 \\ 7 \end{bmatrix} = c_1 \hat{u}_1 + c_2 \hat{u}_2 + c_3 \hat{u}_3$  are the

components of the coordinate vector. By taking the inner product of both sides of this equation with  $\hat{u}_k$  and using the orthonormality of  $\mathcal{C}$ , we find

$$c_k = \vec{w} \cdot \hat{u}_k. \text{ So, } \begin{bmatrix} 7 \\ 7 \\ 7 \end{bmatrix}_{\mathcal{C}} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 11 \\ 5 \\ -1 \end{bmatrix}.$$

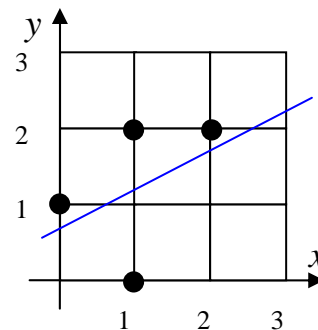
c. Let  $Q = [\hat{u}_1 | \hat{u}_2 | \hat{u}_3]$ . Suppose  $\vec{w}_1$  and  $\vec{w}_2$  are vectors in  $\mathbf{R}^3$  with magnitudes 1 and 2, respectively, and the angle between  $\vec{w}_1$  and  $\vec{w}_2$  is  $\pi/3$ , calculate the angle between  $Q\vec{w}_1$  and  $Q\vec{w}_2$ .

$Q$  is the matrix for an orthogonal transformation and so, it preserves angles between vectors. Therefore, the angle between  $Q\vec{w}_1$  and  $Q\vec{w}_2$  is the same as that between  $\vec{w}_1$  and  $\vec{w}_2$ , namely  $\pi/3$ .

4. Find the coefficients  $\alpha$  and  $\beta$  for the equation

$$y = \alpha x + \beta$$

of the straight line that best fits, in the least squares sense, the data points at the right.



Let  $A = \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix}$ ,  $\vec{b} = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 2 \end{bmatrix}$ ,  $\vec{x} = \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$ . Then, we seek the solution to

$A^T A \vec{x} = A^T \vec{b}$ . Since the columns of  $A$  are linearly independent, we have

$$\begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \vec{x} = (A^T A)^{-1} A^T \vec{b} = \left( \begin{bmatrix} 0 & 1 & 1 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \right)^{-1} \begin{bmatrix} 0 & 1 & 1 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 0 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 6 & 4 \\ 4 & 4 \end{bmatrix}^{-1} \begin{bmatrix} 6 \\ 5 \end{bmatrix} = \frac{1}{8} \begin{bmatrix} 4 & -4 \\ -4 & 6 \end{bmatrix} \begin{bmatrix} 6 \\ 5 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ \frac{3}{4} \end{bmatrix}. \text{ The least squares line has the equation } y = \frac{1}{2}x + \frac{3}{4}.$$

5. For each assertion below, state whether it is **TRUE** or **FALSE**. You are not asked to provide a proof or explanation. However, each correct statement earns full credit and each incorrect statement loses half credit. No credit is assigned to a statement left blank.

a.  $\|\vec{v} + \vec{w}\|^2 = \|\vec{v}\|^2 + \|\vec{w}\|^2$  for vectors in  $\mathbf{R}^n$ .

**FALSE.** The statement (Pythagorean Theorem) is true only when  $\vec{v}$  and  $\vec{w}$  are orthogonal. As a counterexample, choose nonzero vectors with  $\vec{v} = -\vec{w}$ .

b. Any list of  $n$  spanning vectors in  $\mathbf{R}^n$  is linearly independent.

**TRUE.**  $n$  spanning vectors in  $\mathbf{R}^n$  constitute a basis.

c. All matrices representing reflections across any lines through the origin in the plane are similar.

**TRUE.** Rotations change one reflection into any other.

d. The union of any two subspaces of  $\mathbf{R}^n$  is always a subspace of  $\mathbf{R}^n$ .

**FALSE.** For example, the union of two different lines through the origin in  $\mathbf{R}^2$  is not a subspace.

e. The square of an orthogonal matrix is also orthogonal.

**TRUE.** If  $Q$  is orthogonal,  $(Q^2)^T(Q^2) = Q^T Q^T Q Q = Q^T I Q = I$ .

f. If  $A$  and  $B$  are symmetric  $n \times n$  matrices,  $AB$  is also symmetric.

**FALSE.**  $(AB)^T = B^T A^T = BA \neq AB$  unless  $A$  and  $B$  commute.

g. For any matrix  $A$ ,  $(\ker(A))^{\perp} = \text{im}(A^T)$ .

**TRUE.** This follows from the identity  $(\text{im}(A))^{\perp} = \ker(A^T)$  by replacing  $A$  by  $A^T$  and taking the orthogonal complement of both sides.

h. If  $\hat{v}$  and  $\hat{w}$  are unit vectors in  $\mathbf{R}^n$ ,  $\hat{v}\hat{v}^T + \hat{w}\hat{w}^T$  is a projection matrix.

**FALSE.** This is true only if  $\hat{v}$  and  $\hat{w}$  are also orthogonal.