2. **(w06_2_xxxxxxxxx.py) speed_warning[Attachment]:** Create a function named `speed_warning` that takes 2 parameters: **`density and speed`**. The function to issue warnings for a car based on the current traffic conditions. The program will monitor the car density of the traffic (measured in cars per kilometer, denoted as carDensity) and the speed of the vehicle (measured in kilometers per hour, denoted as speed).
    a. If the traffic is not heavily congested (density is less than or equal to 5 cars/km), it is safe to drive the car at speeds up to 90 km/hr. If the speed exceeds this limit, a warning should be issued.
    b. However, if the traffic is congested (density is greater than 5 cars/km), the car can only be driven at speeds up to 60 km/hr safely. If the speed exceeds this limit, a warning should be given.
    c. The function should return a Boolean value according to warning status, True for the situation that a warning should be issued and False for the safety situation.

NOTE: delete "pass" keyword before edit the function in template file

Input	**Output**
`car_density = 4` `car_speed = 80`	`False`
`car_density = 7` `car_speed = 70`	`True`
`car_density = 4` `car_speed = 100`	`True`
`car_density = 7` `car_speed = 60`	`False`