1 HIO using Volterra-operators

Let $w: [0,T] \to \mathbb{R}^m$, $y: [0,T] \to \mathbb{R}^p$, $A \in \mathbb{R}^{n \times n}$, $D \in \mathbb{R}^{n \times m}$ and $C \in \mathbb{R}^{p \times n}$ such that

$$y(t) = \int_{0}^{t} C \exp\{A(t-\tau)\}Dw(\tau) d\tau \quad . \tag{1}$$

Due to Cayley-Hamilton

$$A^{k} = \sum_{l=0}^{n-1} c_{k,l} A^{l}$$
 (2)

with coefficients $c_{k,l}$ that in general are not unique. By choosing $N \le n$ the smallest number such that

$$A^N \in \text{span}(A^0, A^1, ..., A^{N-1})$$
 , (3)

the coefficients $c_{k,l}$ count $l=0,1,\ldots,N-1$ and are unique. Expanding the exponential function to its power series we get

$$y(t) = \sum_{l=0}^{N-1} CA^l D\Phi_l[w](t) \quad . \tag{4}$$

where

$$\Phi_{l}[w](t) := \int_{0}^{t} \sum_{k=0}^{\infty} \frac{(t-\tau)^{k}}{k!} c_{k,l} w(\tau) d\tau \quad . \tag{5}$$

Proposition 1 (Without proof). Each operator Φ_l is injective, i.e.

$$\Phi_l[w] \equiv 0 \qquad \Rightarrow \quad w \equiv 0 \quad . \tag{6}$$

Here " \equiv " denotes equality in function space and Φ_l operates component-wise on $(w_1, w_2, ..., w_m)^{\mathrm{T}} : [0, T] \to \mathbb{R}^m$.

1.1 Linearly independent HI

Consider the simple case $D = \mathbb{1}$ (m = n). Then for the μ -th column of CA^k we find

$$\left(CA^{k}\right)_{\mu} = \sum_{\omega=1}^{n} A_{\omega\mu}^{k} C_{\omega} \tag{7}$$

where $A_{\omega\mu}^k$ is the $(\omega\mu)$ component of A^k and C_{ω} is the ω -th column of C. Therefore each column of any CA^k is a linear combination of column vectors C_{ω} and thus

$$rank[C, CA, CA^2, \dots, CA^{N-1}] = rankC .$$
 (8)

Furthermore we assume the hidden inputs to be linearly independent, i.e.

$$\sum_{\mu=1}^{n} d_{\mu} w_{\mu} \equiv 0 \quad \Leftrightarrow \quad d_{\mu} w_{\mu} \equiv 0 \quad \forall \mu \quad . \tag{9}$$

1.1.1 Nilpotent dynamics

Let A be a nilpotent matrix, i.e. there is a regular $n \times n$ matrix P such that

$$A = P^{-1} A_{\triangle} P \tag{10}$$

with $A_{\triangle\omega\mu} = 0$ when $\omega \le \mu$. As a graphical condition this means, that A can be represented by a directed acyclic graph. Inserting in (4) yields

$$y(t) = \sum_{l=0}^{N-1} \underbrace{CP^{-1}}_{\text{rank }CP^{-1} = \text{rank }C} A_{\Delta}^{l} \Phi_{l} [\underbrace{Pw}_{\text{lin.indep.}}](t) \quad . \tag{11}$$

Thus without loss of generality can assume that A is strictly lower triangular and N = n. Furthermore we see that (5) reduces to

$$\Phi_{l}[w_{\mu}](t) = \int_{0}^{t} \frac{(t-\tau)^{l}}{l!} w_{\mu}(\tau) d\tau$$
 (12)

with the properties

$$\frac{d}{dt}\Phi_{l}[w_{\mu}](t) = \Phi_{l-1}[w_{\mu}](t) \quad \text{and} \quad \frac{d}{dt}\Phi_{0}[w_{\mu}](t) = w_{\mu}(t) \quad , \tag{13}$$

and equation (4) becomes

$$y(t) = \sum_{\omega=1}^{n} \underbrace{\sum_{l=0}^{\omega-1} \sum_{\mu=1}^{\omega-l} \Phi_l \left[A_{\omega\mu}^l w_{\mu} \right](t) C_{\omega}}_{:=\varphi_{\omega}(t)} . \tag{14}$$

Case: C is regular Assume the columns of C, $\{C_1, C_2, ..., C_n\}$ form a linearly independent set of \mathbb{R}^p vectors. Setting $y \equiv 0$ and equating coefficients we get

$$\propto C_1: \qquad \varphi_1 = \Phi_0[\underbrace{A_{11}^0}_{-1} w_1] \equiv 0 \qquad \Rightarrow \qquad w_1 \equiv 0 \tag{15}$$

$$\propto C_1: \qquad \varphi_1 = \Phi_0[\underbrace{A_{11}^0}_{=1} w_1] \equiv 0 \qquad \Rightarrow \qquad w_1 \equiv 0 \qquad (15)$$

$$\propto C_2: \qquad \varphi_2 = \Phi_0[\underbrace{A_{22}^0}_{=1} w_2] + \Phi_1[A_{21}^1 \underbrace{w_1}_{\equiv 0}] \equiv 0 \qquad \Rightarrow \qquad w_2 \equiv 0 \qquad (16)$$

etc.

which shows, that such a system is hidden input observable.

Example 1. Consider the system

$$A = \begin{pmatrix} 2 & -1 & -1 & 0 \\ 2 & -1 & -1 & 1/2 \\ 1 & 0 & -1/2 & -3/4 \\ -2 & 2 & 1 & -1/2 \end{pmatrix} \quad C = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad . \tag{17}$$

With the matrix

$$P = \begin{pmatrix} 1 & -1/2 & -1/2 & 1/4 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 0 & 1/2 \\ 0 & 0 & 1/2 & -1/4 \end{pmatrix}$$
 (18)

we transform the system to

$$A_{\triangle} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & 0 & -1 & 0 \end{pmatrix} \quad \hat{C} = \begin{pmatrix} 1 & 1 & 0 & 1 \\ 1 & 3 & 1 & 3 \\ 0 & 2 & 3 & 2 \\ 0 & 2 & 1 & 2 \\ 1 & 1 & 3 & 3 \end{pmatrix} \quad , \tag{19}$$

to see that this system is hidden input observable.

• To have a set $\{C_1, \dots, C_n\}$ of linear independent vectors, its crucial to have $n \le p$.

• A nilpotent matrix has only one Eigenvalue 0. Thus also tr A = 0 and $\det A = 0$ are necessary conditions.

C_Z is a linear combination