

1 HIO using Volterra-operators

Let $w : [0, T] \rightarrow \mathbb{R}^m$, $y : [0, T] \rightarrow \mathbb{R}^p$, $A \in \mathbb{R}^{n \times n}$, $D \in \mathbb{R}^{n \times m}$ and $C \in \mathbb{R}^{p \times n}$ such that

$$y(t) = \int_0^t C \exp\{A(t-\tau)\} D w(\tau) d\tau \quad . \quad (1)$$

Due to Cayley-Hamilton

$$A^k = \sum_{l=0}^{n-1} c_{k,l} A^l \quad (2)$$

with coefficients $c_{k,l}$ that in general are not unique. By choosing N the smallest number such that

$$A^N \in \text{span}(A^0, A^1, \dots, A^{N-1}) \quad , \quad (3)$$

the coefficients $c_{k,l}$ count $l = 0, 1, \dots, N-1$ and are unique. For each $k \leq N-1$ we find the Kronecker-delta

$$c_{k,l} = \delta_{k,l} \quad . \quad (4)$$

Expanding the exponential function to its power series we get

$$\begin{aligned} \exp\{A(t-\tau)\} &= \sum_{k=0}^{\infty} \frac{(t-\tau)^k}{k!} A^k \\ &= \sum_{l=0}^{N-1} A^l \underbrace{\sum_{k=0}^{\infty} \frac{(t-\tau)^k}{k!} c_{k,l}}_{\phi_l(t,\tau)} \quad . \end{aligned} \quad (5)$$

Both sums should converge absolutely since they are either finite or suppressed exponentially. Using (5) we can write (1) as

$$y(t) = \sum_{l=0}^{N-1} C A^l D \int_0^t \phi_l(t, \tau) w(\tau) d\tau \quad . \quad (6)$$

1.1 Scalar Volterra-operator

Definition 1. According to [1] or [2] the equation

$$\int_0^t K(t, s) f(s) ds = g(t) \quad (7)$$

where $f, g : [0, T] \rightarrow \mathbb{R}$ and $K : \{(t, s) \in [0, T] \times [0, T] | s < t\} \rightarrow \mathbb{R}$ is called *Volterra integral equation of the first kind (V1)* and K is called the *kernel*.

Comparing (6) and (7) we see that, if w_i denotes the i -th component of w , we get m V1 equations

$$\int_0^t \phi_l(t, \tau) w_i(\tau) d\tau = z_i(t) \quad . \quad (8)$$

Let $z(t)$ be any desired trajectory in \mathbb{R}^m and we want to solve (8).

Definition 2. Again according to [1] and [2]

$$f(s) - \int_0^t K(t, s) f(s) ds = g(t) \quad (9)$$

is called *Volterra integral equation of the second kind (V2)*.

Theorem 1 (Proof in [1] and [2]). For any admissible function g , V2 has a unique solution f that is given by the Neumann series.

Theorem 2. Let K be a continuous kernel, $K(t, t) \neq 0$ and $\frac{\partial K}{\partial t}$ continuous. Then, given an differentiable g , V1 has a unique solution f .

Proof. We follow the proof in [2].

Differentiation of V1 with respect to t yields

$$K(t, t) f(t) + \int_0^t \frac{\partial K}{\partial t}(t, s) f(s) ds = \frac{dg}{dt}(t) \quad (10)$$

Only if $K(t, t) \neq 0$ we can divide the whole equation by $K(t, t)$ and redefine the Kernel and right hand side to end up with a V2, which has a unique solution. \square

Now turning back to (8), we want to apply theorem 2 to get information about the solution. But we find that the kernels ϕ_l do not fit to the assumption since

$$\phi_l(t, t) = \sum_{k=0}^{\infty} \frac{(t-t)^k}{k!} c_{k,l} = c_{0,l} \quad (11)$$

and comparing to (4)

$$\phi_0(t, t) = 1 \quad , \quad \phi_l(t, t) = 0 \quad \text{for } l = 1, 2, \dots, N-1 \quad . \quad (12)$$

References

- [1] Harro Heuser. *Funktionalanalysis*. 1992.
- [2] Andreas Kirsch. *Lineare Integralgleichungen*. 2010.