# SE 3XA3: MIS
# OpenCameraRefined

Team #211, CAMERACREW
Faisal Jaffer, jaffem1
Dominik Buszowiecki, buszowid
Pedram Yazdinia, yazdinip
Zayed Sheet, sheetz

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Table 1: **Revision History**

| **Date** | **Version** | **Notes** |
|---|---|---|
| March 14, 2020 | 1.0 | Initial document |

# Gesture Controller Module

## Module

GestureController

## Uses

TensorflowObjectDetectionAPI
ClassifierConstants
CameraController
Filter
Classifier

## Syntax

### Exported Constants

N/A

### Exported Types

GestureController = ?

### Exported Access Programs

| Routine name | In | Out | Exceptions |
|---|---|---|---|
| GestureController | | GestureController | classifier_initialize_failure |
| processImage | | | |
| setFrame | *byte*[] | | |
| captureImage | | | |
| showFilter | | | |

## Semantics

### State Variables

imageFrame: *byte*[] # current camera frame
classifier: $Classifier$ # TensforFlow model
filter: $Filter$

recognition: *Recognition*[] # classification on the current frame

### Environment Variables

None

### State Invariant

None

### Assumptions

- The mathematical operator \ represents integer division. For example $8 \backslash 5 = 1$.

### Access Routine Semantics

GestureController():

- transition: $classifier, filter := Classifier(ClassifierConstants.getInferenceName(), ClassifierConstants.getLabelName()), Filter()$
- output: $out := self$
- exception: $exc := ((ClassifierConstants.getInferenceName() == null | ClassifierConstants.getLabelName() == null) \Rightarrow classifier\_initialize\_failure)$

processImage():

- transition: $recognition := classifier.recognizeImage(bitmapFromByte(imageFrame)) \Rightarrow (recognition.title == ClassifierConstants.Smile \rightarrow captureImage() | recognition.title == ClassifierConstants.Thumb \rightarrow filter.changeFilter())$
- output: None
- exception: None

setFrame(*byte*[] data):

- transition: imageFrame:= data

- output: None
- exception: None

captureImage():

- transition: *CameraController.captureImage*()
- output: None
- exception: None

showFilter():

- transition: None
- output: None
- exception: None

## Local Functions

bitmapFromByte(*byte*[] data):

- transition: Matrix mat := ImageUtils.convertYUV420SPToARGB8888(data)
- output: *out* := mat
- exception: None

# Recognition Module

## Module

Recognition

## Uses

RectF

## Syntax

### Exported Constants

N/A

### Exported Types

Recognition = ?

### Exported Access Programs

| Routine name | In | Out | Exceptions |
|---|---|---|---|
| Recognition | $String, String, \mathbb{Q}, RectF$ | Recognition | |
| getID | | $String$ | |
| getTitle | | $String$ | |
| getConfidence | | $\mathbb{Q}$ | |
| getLocation | $Bitmap$ | $RectF$ | |

## Semantics

### State Variables

id: $String$ # unique id assignment since multiple recognitions possible
title: $String$ # label of the recognition
confidence: $\mathbb{Q}$ # confidence level of the classification
location: RectF # pixel location of the recognition

### Environment Variables

None

**State Invariant**

None

**Assumptions**

- Invalid arguments will not be provided into the Recognition and getLocation routines.

**Access Routine Semantics**

Recognition(id, title, confidence, location):

- transition: $id, title, confidence, location := id, title, confidence, location$
- output: $out := self$
- exception:None

getID():

- transition: None
- output: $out := id$
- exception: None

getTitle():

- transition: None
- output: $out := title$
- exception: None

getConfidence():

- transition: None
- output: $out := confidence$
- exception: None

getLocation():

- transition: None
- output: $location$
- exception: None

## Local Functions

None

# Classifier Module

## Module

Classifier

## Uses

Recognition
ClassifierConstants
Bitmap
TF

## Syntax

### Exported Constants

N/A

### Exported Types

None

### Exported Access Programs

| Routine name | In | Out | Exceptions |
|---|---|---|---|
| Classifier | $String, String, (\mathbb{Z}, \mathbb{Z})$ | Classifier | classifier_initialize_failure |
| recognizeImage | *Bitmap* | *Recognition* | |

## Semantics

### State Variables

modelFilename: *String* # link to the model inference
labelFilename: *String* # link to the model labels
inputSize: $(\mathbb{Z}, \mathbb{Z})$ # size of model input
model: TF.model# stored model

### Environment Variables

None

### State Invariant

None

### Assumptions

- Invalid arguments will not be provided to the Classifier and recognizeImage routines.

### Access Routine Semantics

Classifier(modelFilename, labelFilename, inputSize):

- transition: $model := newTF.model(modelFilename, labelFilename)$
- output: $out := self$
- exception: $exc := newTF.model(modelFilename, labelFilename) == null \Rightarrow (classifier\_initialize\_failure)$

recognizeImage(b):

- transition: None
- output: $out := model.detect(b)$
- exception: None

## Local Functions

None

# Classifier Constants Module

## Module

ClassifierConstants

## Uses

## Syntax

### Exported Constants

inferenceName: *String*
labelName: *String*

### Exported Types

None

### Exported Access Programs

| Routine name | In | Out | Exceptions |
|---|---|---|---|
| getInferenceName | | *String* | |
| getLabelName | | *String* | |

## Semantics

### State Variables

### Environment Variables

None

### State Invariant

None

### Assumptions

None

**Access Routine Semantics**

getInferenceName():

- transition: None
- output: *out* := inferenceName
- exception: None

getLabelName():

- transition: None
- output: *out* := labelName
- exception: None

## Local Functions

None

# Filter Module

## Module

Filter

## Uses

Filter Constants

## Syntax

### Exported Constants

N/A

### Exported Types

N/A

### Exported Access Programs

| Routine name | In | Out | Exceptions |
|---|---|---|---|
| changeFilter | | | |
| getFilter | | $\mathbb{Z}$ | |

## Semantics

### State Variables

filterIndex : $\mathbb{Z}$ *#Which index in the FILTERS constant from the filters module is selected*

### Environment Variables

None

### State Invariant

filterIndex $< |FILTERS|$

### Assumptions

The % operator represents the mathematical modulus operator

**Access Routine Semantics**

changeFilter():

- transition: filterIndex := (filterIndex + 1)%$|FILTERS|$
- output: None

getFilter():

- transition: None
- output: *out* := filterIndex

# Filter Constants Module

## Module

Constants

## Uses

OpenCV

## Syntax

### Exported Constants

GRAYSCALE: ($\mathbb{Z}$[], $\mathbb{Z}$[])
RED_FILTER: ($\mathbb{Z}$[], $\mathbb{Z}$[])
BLUE_FILTER: ($\mathbb{Z}$[], $\mathbb{Z}$[])
*# The values of the filters will be obtained from the OpenCV lookup tables. They are 2xN matrices which map a source colour of a pixel to a final colour after applying a filter. The value of N depends on the total number of possible colours*
FILTERS = [GRAYSCALE, RED_FILTER, BLUE_FILTER]

### Exported Types

None

### Exported Access Programs

None

## Semantics

### State Variables

None

### State Invariant

None