# SE 3XA3: MIS OpenCameraRefined

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Table 1: Revision History

Date	Version	Notes
March 14, 2020	1.0	Initial document
April 4, 2020	2.0	Initial document

# Gesture Controller Module

# Module

Gesture Controller

# Uses

TensorflowObjectDetectionAPI ClassifierConstants CameraController Filter Classifier

# **Syntax**

### **Exported Constants**

N/A

# **Exported Types**

GestureController = ?

# **Exported Access Programs**

Routine name	In	Out	Exceptions
GestureController		GestureController	classifier_initialize_failure
processImage			
setFrame	byte[]		
captureImage			
showFilter			

# **Semantics**

#### State Variables

image Frame: byte[]~# current camera frame classifier: Classifier~# Tensfor Flow model

filter: Filter

recognition: Recognition[] # classification on the current frame

#### **Environment Variables**

None

#### State Invariant

None

#### Assumptions

• The mathematical operator \ represents integer division. For example  $8 \setminus 5 = 1$ .

#### **Access Routine Semantics**

GestureController():

- transition: classifier, filter := Classifier(ClassifierConstants.getInferenceName(), ClassifierConstants.getLabelName()), Filter()
- $\bullet$  output: out := self
- exception:  $exc := ((ClassifierConstants.getInferenceName() == null| ClassifierConstants.getLabelName() == null) <math>\Rightarrow classifier\_initialize\_failure)$

processImage():

- transition:  $recognition := classifier.recognizeImage(bitmapFromByte(imageFrame)) \Rightarrow (recognition.title == ClassifierConstants.Smile <math>\rightarrow captureImage()|recognition.title == ClassifierConstants.Thumb \rightarrow filter.changeFilter())$
- output: None
- exception: None

setFrame(byte[] data):

• transition: imageFrame:= data

- output: None
- exception: None

# captureImage():

- $\bullet \ \ transition: \ Camera Controller. capture Image()$
- output: None
- exception: None

# showFilter():

- transition: None
- output: None
- exception: None

# **Local Functions**

bitmapFromByte(byte[] data):

- $\bullet \ \ transition: \ Matrix \ mat := ImageUtils.convertYUV420SPToARGB8888(data)$
- $\bullet$  output: out := mat
- exception: None

# Recognition Module

# Module

Recognition

# Uses

RectF

# **Syntax**

# **Exported Constants**

N/A

# **Exported Types**

Recognition =?

#### **Exported Access Programs**

Routine name	In	Out	Exceptions
Recognition	$String, String, \mathbb{Q}, RectF$	Recognition	
getID		String	
getTitle		String	
getConfidence		Q	
getLocation	Bitmap	RectF	

# **Semantics**

#### State Variables

id: String # unique id assignment since multiple recognitions possible

title: String # label of the recognition

confidence:  $\mathbb{Q}$  # confidence level of the classification location: RectF # pixel location of the recognition

#### **Environment Variables**

#### **State Invariant**

None

#### Assumptions

• Invalid arguments will not be provided into the Recognition and getLocation routines.

#### **Access Routine Semantics**

Recognition(id, title, confidence, location):

- transition: id, title, confidence, location := id, title, confidence, location
- output: out := self
- exception:None

# getID():

- transition: None
- output: out := id
- exception: None

### getTitle():

- transition: None
- output: out := title
- exception: None

# getConfidence():

• transition: None

 $\bullet \ \text{output:} \ out := confidence \\$ 

• exception: None

# getLocation():

• transition: None

• output: location

• exception: None

# **Local Functions**

# Classifier Module

# Module

Classifier

# Uses

Recognition ClassifierConstants Bitmap TF

# **Syntax**

**Exported Constants** 

N/A

# **Exported Types**

None

# **Exported Access Programs**

Routine name	In	Out	Exceptions
Classifier	$String, String, (\mathbb{Z}, \mathbb{Z})$	Classifier	classifier_initialize_failure
recognizeImage	Bitmap	Recognition	

# **Semantics**

#### State Variables

model Filename: String # link to the model inference label Filename: String # link to the model labels

input Size: ( $\mathbb{Z}$ ,  $\mathbb{Z}$ ) # size of model input

 $model: \ TF.model \# \ stored \ model$ 

#### **Environment Variables**

None

#### **State Invariant**

None

### Assumptions

• Invalid arguments will not be provided to the Classifier and recognizeImage routines.

#### **Access Routine Semantics**

Classifier(modelFilename, labelFilename, inputSize):

- transition: model := newTF.model(modelFilename, labelFilename)
- output: out := self
- exception:  $exc := newTF.model(modelFilename, labelFilename) == null \Rightarrow (classifier\_initialize\_failure)$

### recognizeImage(b):

- transition: None
- output: out := model.detect(b)
- exception: None

#### **Local Functions**

# Classifier Constants Module

# Module

ClassifierConstants

Uses

**Syntax** 

**Exported Constants** 

 $\begin{array}{ll} \text{inferenceName: } String \\ \text{labelName: } String \end{array}$ 

**Exported Types** 

None

### **Exported Access Programs**

Routine name	In	Out	Exceptions
getInferenceName		String	
getLabelName		String	

# **Semantics**

State Variables

**Environment Variables** 

None

State Invariant

None

Assumptions

# **Access Routine Semantics**

# getInferenceName():

- transition: None
- $\bullet$  output: out := inferenceName
- exception: None

# getLabelName():

- transition: None
- $\bullet$  output: out := labelName
- exception: None

# **Local Functions**

# Filter Module

#### Module

Filter

# Uses

Filter Constants

# **Syntax**

**Exported Constants** 

N/A

**Exported Types** 

N/A

#### **Exported Access Programs**

Routine name	In	Out	Exceptions
changeFilter			
getFilter		$\mathbb{Z}$	
setFrame	byte[]		
processImage			
getFiltered		Bitmap	

#### **Semantics**

#### **State Variables**

 $filterIndex: \mathbb{Z} \# Which \ index \ in \ the \ FILTERS \ constant \ from \ the \ filters \ module \ is \ selected$ 

imageFrame: byte[] # current camera frame

rgb Frame<br/>Bitmap: Bitmap~#bit Map version of camera frame

filtered: Bitmap # Filtered version of rgbFrameBitmap

#### **Environment Variables**

preview: # Android Camera Preview object

#### State Invariant

```
filterIndex < |FILTERS|
```

#### Assumptions

The % operator represents the mathematical modulus operator

#### **Access Routine Semantics**

```
changeFilter():
```

- transition: filterIndex := (filterIndex + 1)%|FILTERS + 1|
- output: None

### getFilter():

- transition: None
- output: out := filterIndex

### setFrame(byte[] data):

- transition: imageFrame:= data
- output: None
- exception: None

#### processImage():

• transition:

```
filterIndex = 0 \implies filtered := null
filterIndex = 0 \implies filtered := setFiltered(rgbFrameBitmap)
```

- output: None
- exception: None

#### getFiltered():

- transition: None
- output: out := filtered

# Filter Constants Module

#### Module

Constants

#### Uses

OpenCV

# **Syntax**

#### **Exported Constants**

 $\begin{array}{l} \operatorname{GRAYSCALE:} & (\mathbb{Z}[], \mathbb{Z}[]) & \operatorname{ColorMatrixColorFilter} \\ \operatorname{RED\_FILTER:} & (\mathbb{Z}[], \mathbb{Z}[]) & \operatorname{ColorMatrixColorFilter} \\ \operatorname{BLUE\_FILTER:} & (\mathbb{Z}[], \mathbb{Z}[]) & \operatorname{ColorMatrixColorFilter} \\ \end{array}$ 

# The values of the filters will be obtained from the OpenCV lookup tables. They are 2xN matrices which # The values of the filters are obtained from code snippets found online, the type Color-

MatrixColorFilter is a type built into android

FILTERS = [GRAYSCALE, RED\_FILTER, BLUE\_FILTER]

#### **Exported Types**

None

#### **Exported Access Programs**

None

#### **Semantics**

State Variables

None

#### **State Invariant**