CMPS 101 Homework 2

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Question 1

Heaps naturally lead to a sorting algorithm, Heapsort. Starting from array A, build it into a min-heap. Repeatly called Extract-Min to get the elements of A in sorted order. Give pseudocode for Heapsort and show that it is not stable.

Pseudo Code

The Pseudo Code below makes use of an extractMin(Array) method that

- 1) Returns and swaps the root element with the last element.
- 2) Decrements the size of the Heap.
- 3) Restores the Minimum Heap property.

Algorithm 1 Pseudo Code for Heap Sort

```
buildMinHeap(Array)
for all i in Array do
Array[i] \leftarrow \mathbf{extractMin}(Array)
end for
return Array
```

Heap Sort stability

Heap Sort is not a stable sorting algorithm, although it can be implemented to be stable. For the purpose of the question we will show that the Heap Sort Implementation in $Introduction\ to\ Algorithms$, $3rd\ Edition$ which uses a Max Heap and builds the array from the largest index to the smallest by inserting the largest element in the heap in the largest unsorted index in the array is not stable. With the following example we can show that Heap Sort is not stable: Consider the Array $\{56, 33, 31, 29, 13_1, 13_2, 7, 2, 0\}$. Note that 13_1 and 13_2 both have value 13, the subscript merely keeps track of their order. Heap Sort will insert the largest value in the Heap in the largest unsorted the index so our sorted Array will look like this: $\{0, 2, 7, 13_2, 13_1, 29, 31, 33, 56\}$. We can clearly see that 13_1 and 13_2 switched order, therefore Heap Sort is not stable.

Question 2

Given an input array A of length n and a positive integer k>0, design an algorithm that outputs the largest k elements in sorted order. Provide pseudocode and give a time-complexity analysis. You will get full credit if the time-complexity is $O(n+k\log k)$.

Pseudo Code

Heap Sort k times

Algorithm 2 Pseudo Code to find the k largest elements in sorted order

```
kLargest(Array, k)

SortedK \leftarrow new \ Array[k]

buildMaxHeap(Array)

for i \leftarrow k-1, i >= 0, i - - do

SortedK[i] \leftarrow extractMax(Array)

end for

return SortedK
```

Time Complexity Analysis

The time complexity of building a Max Heap out of an array with n elements is O(n). The time complexity of extractMax which also restores the heap property is $O(\log n)$ and is executed k times so overall Time Copmplexity is $O(n+k\log n)$.

Question 3

Prove that the number of keys stored in a 2-3 tree of height h is $\Omega(2^h)$ and $O(3^h)$.

Proof that the number of keys is $\Omega(2^h)$

Proof. To prove this statement we will use Induction.

Basis Step: Let the height of the 2-3 tree h=0, then number of keys stored $k=2^0=1$. $1\geq 1$ so $1=\Omega(2^0)$ meaning that our Base Case holds.

Inductive Hypothesis: $k = \Omega(2^h)$, so our number of keys $k \geq 2^h$.

Inductive Step: Assume that our Hypothesis holds up to h. Prove for h+1. Let l be the number of keys in a 2-3 tree oh height h

+ 1. A 2-3 tree of height h+1 is a 2-3 tree of height h where at least one of the leaf nodes has an additional subtree of height 1 as a child which by definition of a 2-3 tree stores at least 2 keys. By the Inductive Hypothesis $l \geq 2 \cdot k \geq 2 \cdot 2^h \geq 2^{h+1}$.

Proof that the number of keys is $O(3^h)$

Proof. To prove this statement we will use Induction.

Basis Step: Let the height of the 2-3 tree h=0, then number of keys stored $k=3^0=1$. $1 \le 1$ so $1=O(3^0)$ meaning that our Base Case holds.

Inductive Hypothesis: $k = O(3^h)$, so our number of keys $k \le 3^h$.

Inductive Step: Assume that our Hypothesis holds up to h. Prove for h+1. Let l be the number of keys in a 2-3 tree of height h+1. A 2-3 tree of height h+1 is a 2-3 tree of height h+1 where at most all of the leaf nodes have an additional subtree of height 1 as a child which by definition of a 2-3 tree stores at most 3 keys. By the Inductive Hypothesis $l \leq 3 \cdot k \leq 3 \cdot 3^h \leq 3^{h+1}$.

Question 4

Suppose you are given two 2-3 trees T1, T2 and a value x such that all keys in T1 are less than x, and all keys in T2 are greater than x. Give an algorithm that constructs a single new T 0 that has the union of keys in T1, T2, and x. Give a running time analysis.

Pseudo Code

Algorithm 3 Pseudo Code for merging 2-3 Trees

```
T0 \leftarrow new \text{ 2-3 Tree}
if T1.height == T2.height then
  T0.root \leftarrow x
  T0.left \leftarrow T1
  T0.right \leftarrow T2
else if T1.height > T2.height then
  T2.\mathbf{insert}(x)
  currentNode \leftarrow T1.root
  for i \leftarrow 0, i < T1.height - T2.height, i++ do
     currentNode \leftarrow currentNode.right
  end for
  currentNode.right \leftarrow T2
  if currenNode.right.numOfKeys > 3 then
     fixOverall(currentNode)
  end if
  T0.root \leftarrow T1.root
else if T1.height < T2.height then
  T1.\mathbf{insert}(x)
  currentNode \leftarrow T2.root
  for i \leftarrow 0, i < T2.height - T2.height, i++ do
     currentNode \leftarrow currentNode.right
  end for
  currentNode.right \leftarrow T1
  if currenNode.right.numOfKeys > 3 then
     fixOverall(currentNode)
  end if
  T0.root \leftarrow T2.root
end if
```

Runtime Analysis

This alorithm constructs a single new 2-3 Tree T0 that has the union of keys in T1, T2, and x in time $O(\log n)$. The algorithm needs to consider three cases: First, T1 and T2 are of equal height. Here, the algorithm will construct T0 in constant time O(1) by making x the root Node and storing the subtree T1 which contains all keys smaller than x as the left child of the root, and storing the subtree T2 which contains all keys greaterthan x as the right child of the root. The next 2 cases are that either T1 or T2 are bigger. If this is the case, the algorithm will find the h1 - h2th largest node and insert T2 as a subtree of T1 if the height of T1 is bigger or find the h2 - h1th smallest node and insert T1 as a subtree of T2. If necessary, the algorithm will then restore the 2-3 Tree

property, Giving us a total runtime of $O(\log n)$.

Question 5

Consider a binary search tree where keys are positive integers. Augment the tree to answer Range queries of the form: "how many elements have key in the range [a, b]"? Thus, such a query is called by the function Range(a, b). Provide pseudocode for Insert, Delete, and Range queries. Provide a running time analysis for all these queries, in terms on n (the number of nodes in the tree) and D (the maximum depth). (Hint: you might want to maintain subtree sizes at the nodes.)

BST Insertion

Algorithm 4 Pseudo Code for inserting a key k in a BST node

```
if node == null then
  node.data \leftarrow k
  node.left \leftarrow null
  node.right \leftarrow null
  node.treeSize \leftarrow 0
  return
else if node != null then
  if k < node.data then
     node.treeSize + +
     node.left \leftarrow \mathbf{insert}(node.left, k)
  else if k > node.data then
     node.treeSize + +
     node.right \leftarrow \mathbf{insert}(node.right, k)
  end if
end if
return
```

Time Complexity Analysis:

The insert algorithm runs in worst case O(n) and O(D). If the tree becomes very unbalanced it effectively functions as a linked list and the time compelxity of inserting at the last node in a Linked List is O(n).

BST Deletion

Algorithm 5 Pseudo Code for deleting a node with key k in a BST node

```
if node! = null then
  if k < node.data then
     node.treeSize--
     node.left \leftarrow \mathbf{delete}(node.left, k)
  else if k > node.data then
     node.treeSize--
     node.right \leftarrow \mathbf{delete}(node.right, k)
  else
     if node.right == null and node.left == null then
       node \leftarrow null
     else if node.right == null and node.left! = null then
       node \leftarrow node.left
     else if node.right != null and node.left == null then
       node \leftarrow node.right
     else
       smallestRightChild \leftarrow node.right.data
       tempNode \leftarrow node.right
       while tempNode.left! = null do
          smallestRightChild \leftarrow tempNode.left.data
          tempNode \leftarrow tempNode.left
       end while
       node.data \leftarrow smallestRightChild
       node.right \leftarrow \mathbf{delete}(node.right, node.data)
     end if
  end if
end if
```

Time Analysis:

The delete algorithm runs in worst case O(n) and O(D). If the tree becomes very unbalanced it effectively functions as a linked list and the time compelxity of deleting the last node in a Linked List is O(n).

BST Range Query

Time Complexity Analysis:

The Range Query Algorithm runs in O(n) and O(D). Such a runtime occurs in the case that the tree is a linked list where the key at the root is equal to a and the key at the rightmost child of the tree is equal to b.

Algorithm 6 Pseudo Code for num of keys in Range [a,b] of a BST node

```
if node == null then
  return 0
else if node.data < a then
  \mathbf{Range}(node.right, a, b)
else if node.data > b then
  \mathbf{Range}(node.left, a, b)
else
  leftNode \leftarrow node.left
  leftCount \leftarrow 0
  while leftNode.left! = null and leftNode.data > a do
    if leftNode.right! = null then
       leftCount += leftNode.right.treeSize
    end if
    leftCount + +
    leftNode \leftarrow leftNode.left
  end while
  if leftNode.left ! = null and leftNode.left.right.data ! = null and
  leftNode.left.right.data > a then
    leftCount += \mathbf{Range}(leftNode.left.right, a, b)
  end if
  rightNode \leftarrow node.right
  rightCount \leftarrow 0
  while rightNode.right. ! = null and rightNode.data < b do
    if rightNode.left != null then
       rightCount \mathrel{+}= rightNode.left.treeSize
    end if
    rightCount + +
    rightNode \leftarrow rightNode.right
  end while
  if rightNode.right! = null and rightNode.righ.left.data! = null and
  righttNode.right.left.data < b  then
    rightCount += \mathbf{Range}(rightNode.right.left, a, b)
  end if
  return 1 + rightCount + leftCount
end if
```