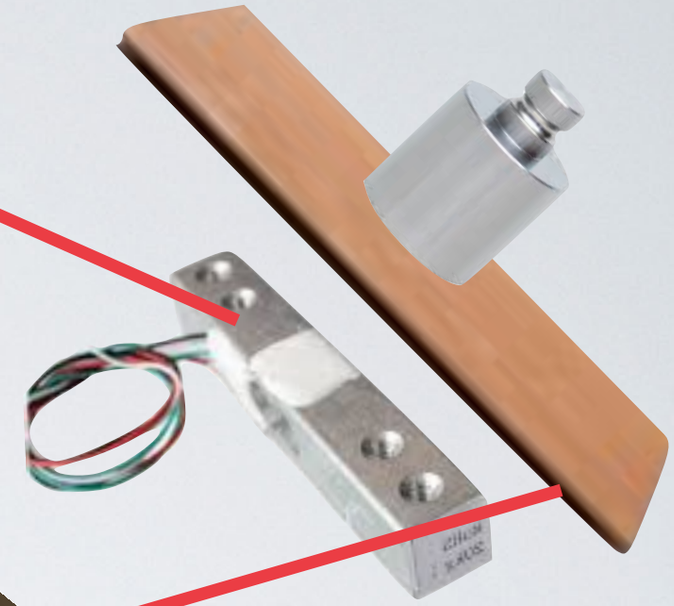
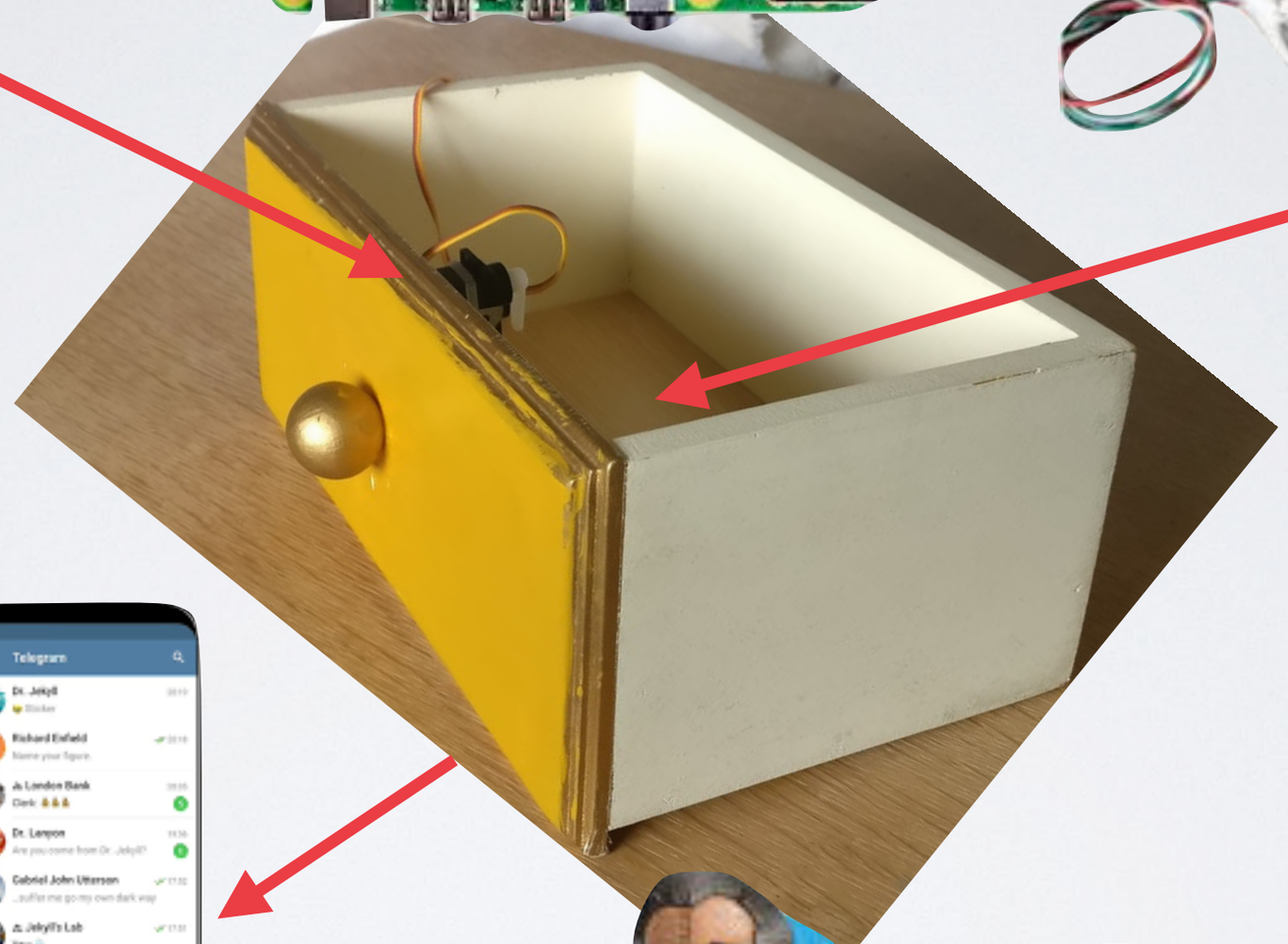
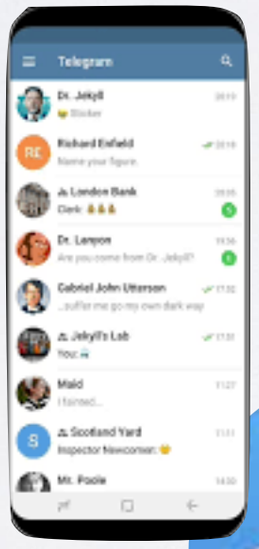
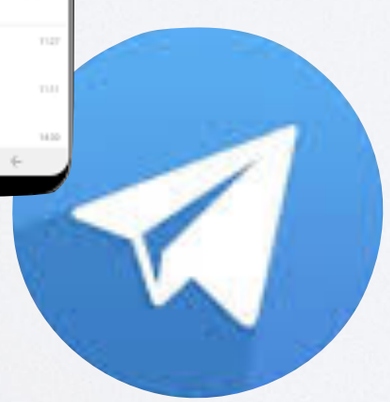


1. The first function is opening and closing the drawer with the help of a servo motor and the raspberry pi. Python is used for communication , a library called "telepot" is used to use the telegram API and communicate with the bot.



2. The second function of the drawer is to sense if anything has gone into the drawer and report to the user via the telegram bot.



3. The communication is made through a telegram bot created with BotFather and communicates with the raspberry pi.