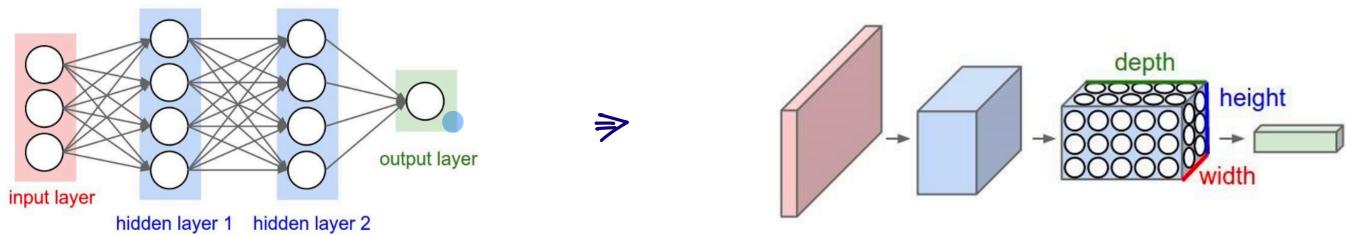


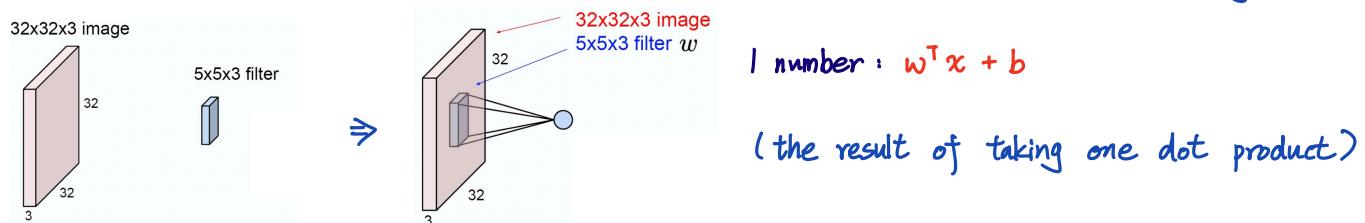
## Ch 8. Convolutional Neural Networks

### A1. Convolutional Layers

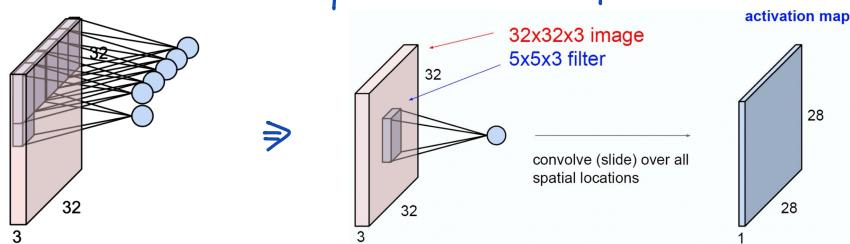
~ arrange its neurons in 3 dimensions (3D output tensor)



Given a  $32 \times 32 \times 3$  image and a  $5 \times 5 \times 3$  filter  $\Rightarrow$  Convolve the filter with the image

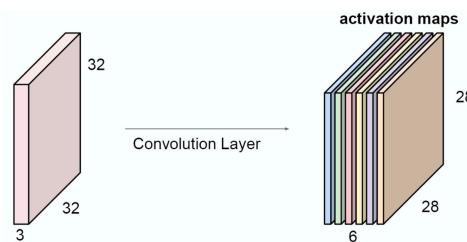


Construct the activation map based on one filter

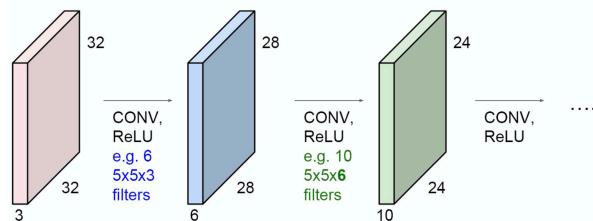


If we have more filters, we can get more separate activation maps

And we can stack them up and get a new image

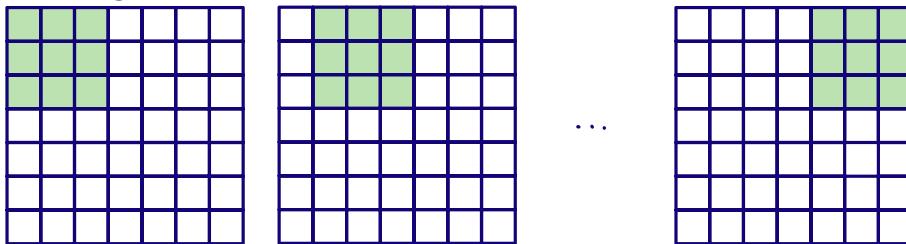


ConvNet: a sequence of Convolutional Layers, interspersed with activation function



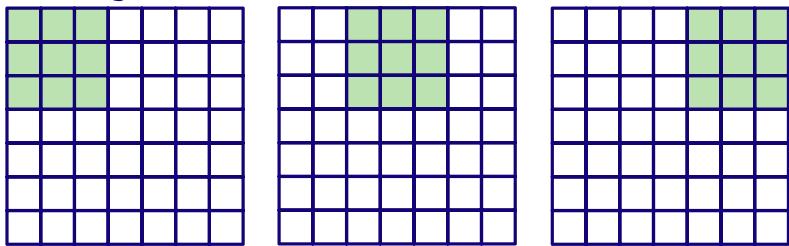
## • Spatial Dimension Analysis

Given  $7 \times 7$  image and  $3 \times 3$  filter



$\Rightarrow 5 \times 5$  outputs

Given  $7 \times 7$  image and  $3 \times 3$  filter with stride 2



$\Rightarrow 3 \times 3$  outputs

Given  $7 \times 7$  image with 1 zero padding to the border

0	0	0	0	0	0	0	0
0							0
0							0
0							0
0							0
0							0
0							0
0	0	0	0	0	0	0	0

N: Input dimension    F: Filter size    P: Width of zero-pad

$$\text{Output Size} = (N + 2P - F) / \text{stride} + 1$$

Given a 3D Volume with size  $W_1 \times H_1 \times D_1$  and 4 hyper-parameters :

# filters K, filter size F, convolution stride S, # zero padding P

$\Rightarrow$  Produce a volume with size  $W_2 \times H_2 \times D_2$  where

$$W_2 = (W_1 + 2P - F) / S + 1, \quad H_2 = (H_1 + 2P - F) / S + 1, \quad D_2 = K$$

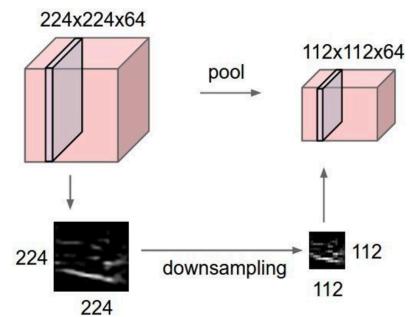
$\Rightarrow$  # parameters in the layer =  $(F \times F \times D_1) \times K + K$  (bias)

\* It has  $(F \times F \times D_1) \times K$  weights and K bias

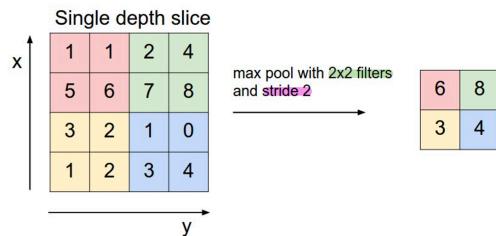
## A2. Pooling Layers

~ make the representation smaller and more manageable

↳ operate over each activation map independently



\* Max. pooling layer



EG. Input volume of size  $224 \times 224 \times 64$  is pooled with filter size 2, stride 2 into output volume of size  $112 \times 112 \times 64$

Given a 3D Volume with size  $W_1 \times H_1 \times D$  and 2 hyper-parameters :

filter size  $F$ , convolution stride  $S$

⇒ Produce a volume with size  $W_2 \times H_2 \times D$  where

$$W_2 = (W_1 - F)/S + 1, \quad H_2 = (H_1 - F)/S + 1$$

⇒ # parameters in the layer = 0