

Computer Vision (CSI4116)

Introduction

Lecture 01

<https://www.youtube.com/watch?v=eQLcDmfmGB0>

Today

- Course overview
- Course requirements
- Introduction to computer vision

Course Overview (1)

- Instructor:
Seon Joo Kim (seonjookim@yonsei.ac.kr)
- Office hours:
By appointment, RM 723 (Eng4)
- Textbooks (reference):
 - Richard Szeliski,
Computer Vision: Algorithms and Applications
(draft available online)
 - Forsyth & Ponce, *Computer Vision: A Modern Approach*
 - Hartley & Zisserman, *Multiview Geometry*
- Class webpage: LearnUs

Course Overview (2)

- Grading
 - 3 projects : 40%
 - Midterm/Final Exams : 60%
 - Attendance
 - * -1% per missed class.
(-2% for 2hour classes)

* All projects will involve implementation (python).

Collaboration policy

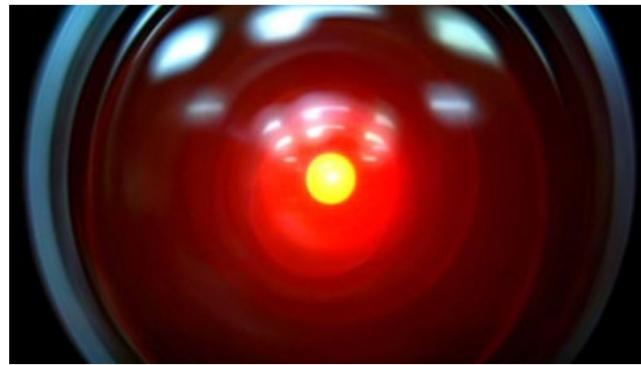
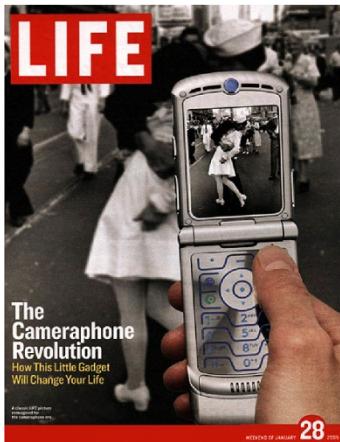
- Feel free to discuss assignments with each other, but coding must be done individually
- Feel free to incorporate code or tips you find on the Web, provided this doesn't make the assignment trivial and you explicitly acknowledge your sources
- Remember: I can Google too .

I can use ChatGPT too

Course Requirements

- Mathematical Background
 - Linear Algebra
(http://cseweb.ucsd.edu/classes/wi05/cse252a/linear_algebra_review.pdf)
 - Probability
(http://cseweb.ucsd.edu/classes/wi05/cse252a/random_var_review.pdf)
- Programming Skills
 - python

Computer Vision



The goal of computer vision

- To bridge the gap between pixels and “meaning”



La Gare Montparnasse, 1895

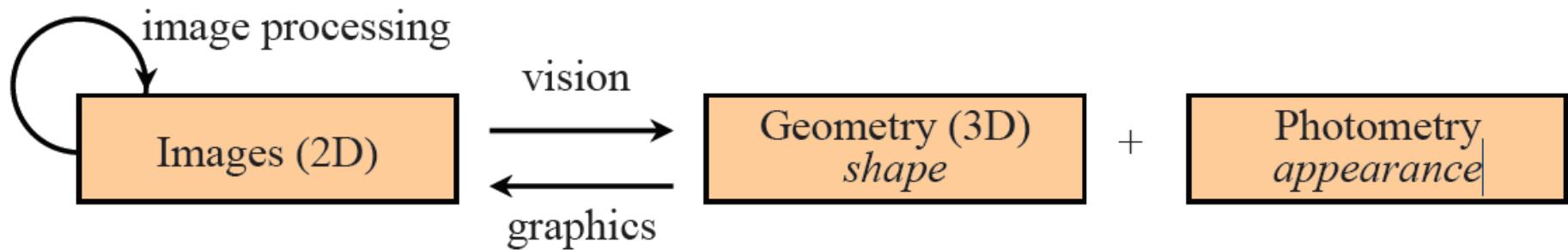
What we see

0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

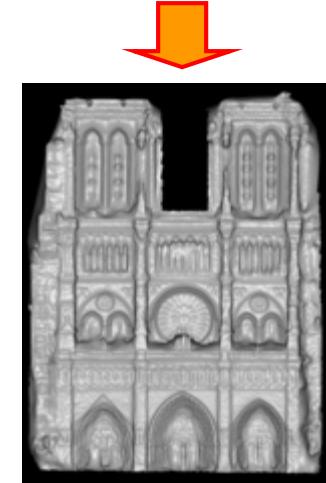
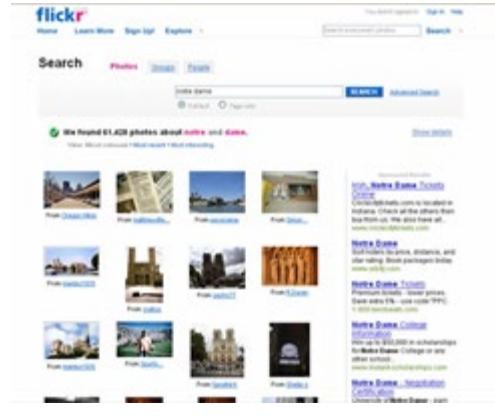
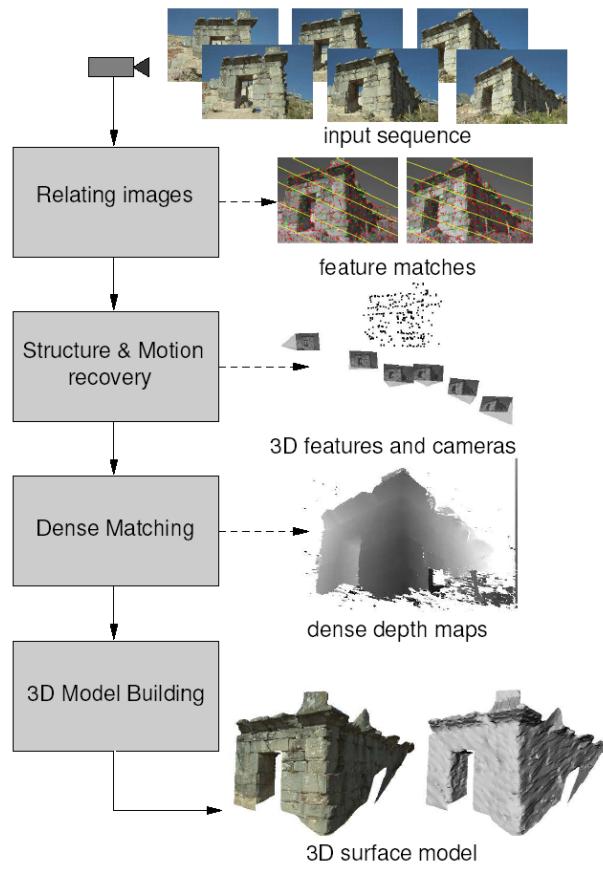
What a computer sees

What kind of information can we extract from an image?

- Metric 3D information
- Semantic information



Vision as measurement device



Vision as a source of semantic information

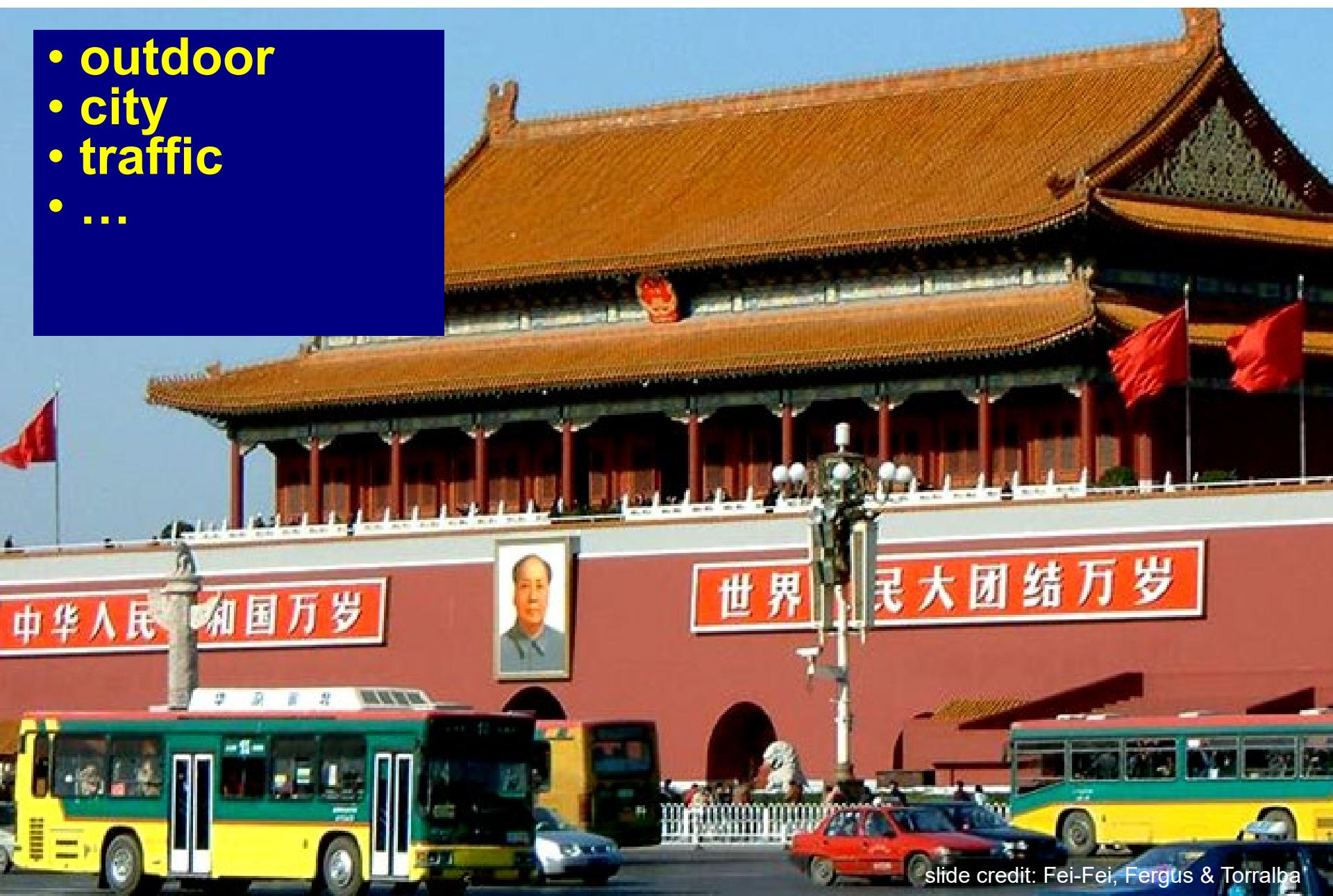


Object categorization

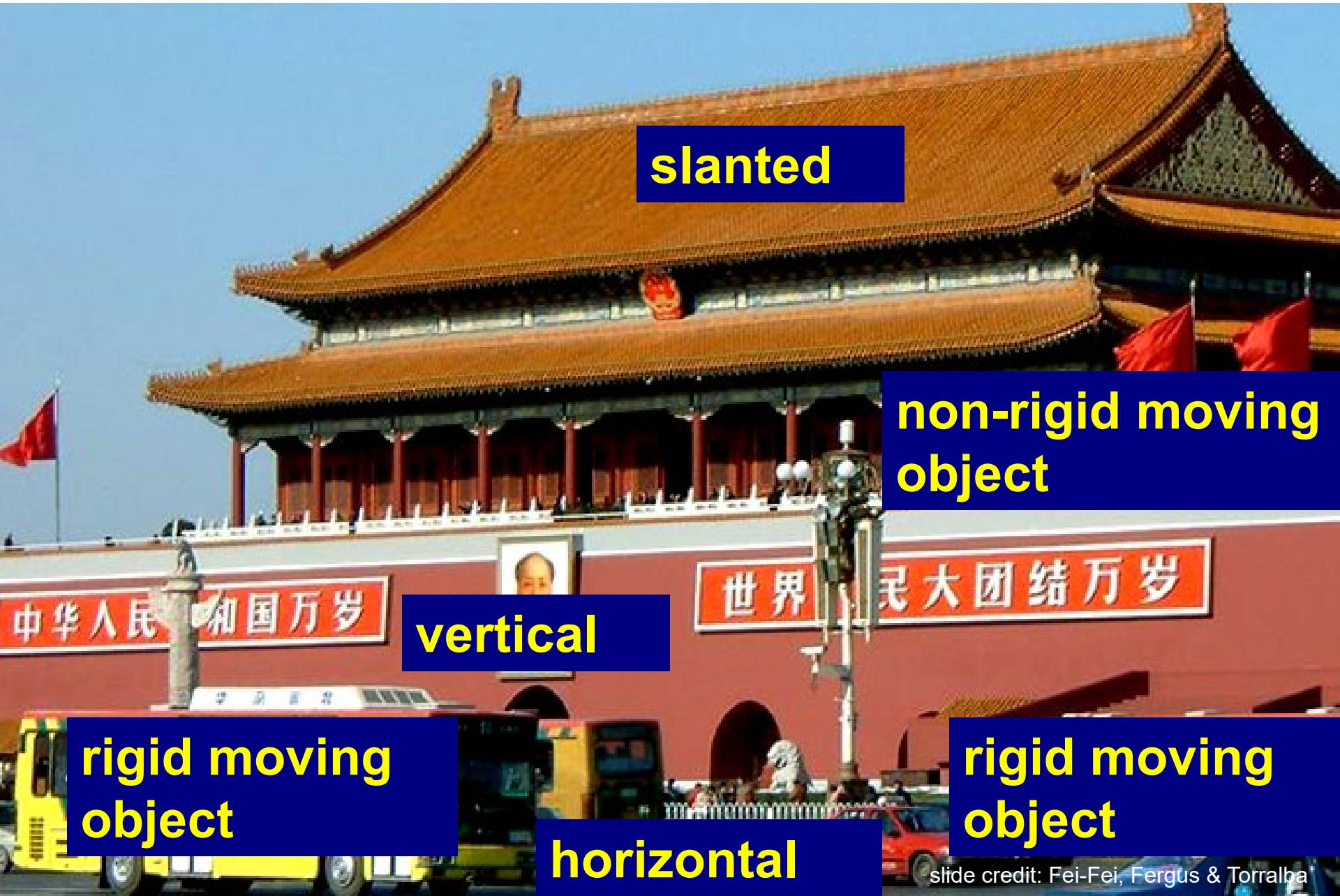


Scene and context categorization

- **outdoor**
- **city**
- **traffic**
- ...



Qualitative spatial information



rigid moving
object

rigid moving
object

horizontal

Why study computer vision?

- Vision is useful: Images and video are everywhere!



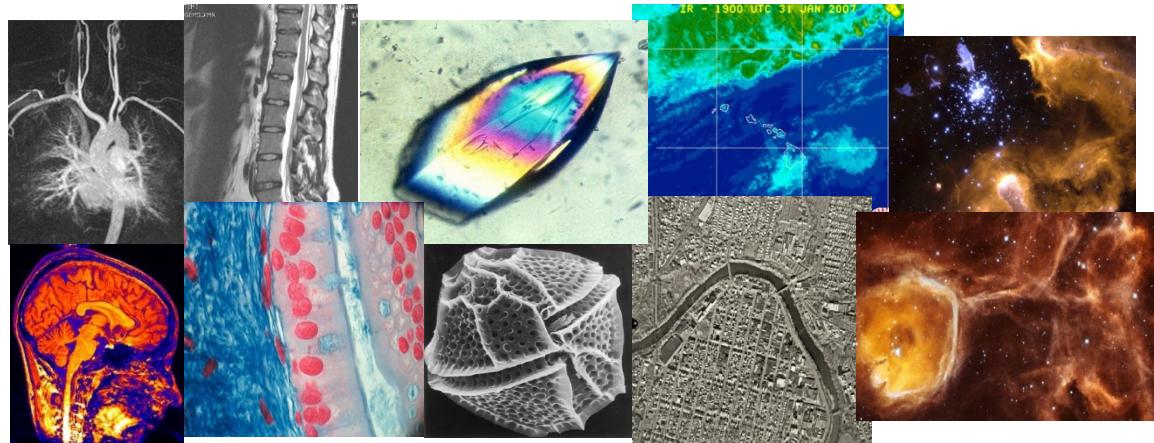
Personal photo albums



Movies, news, sports



Surveillance and security

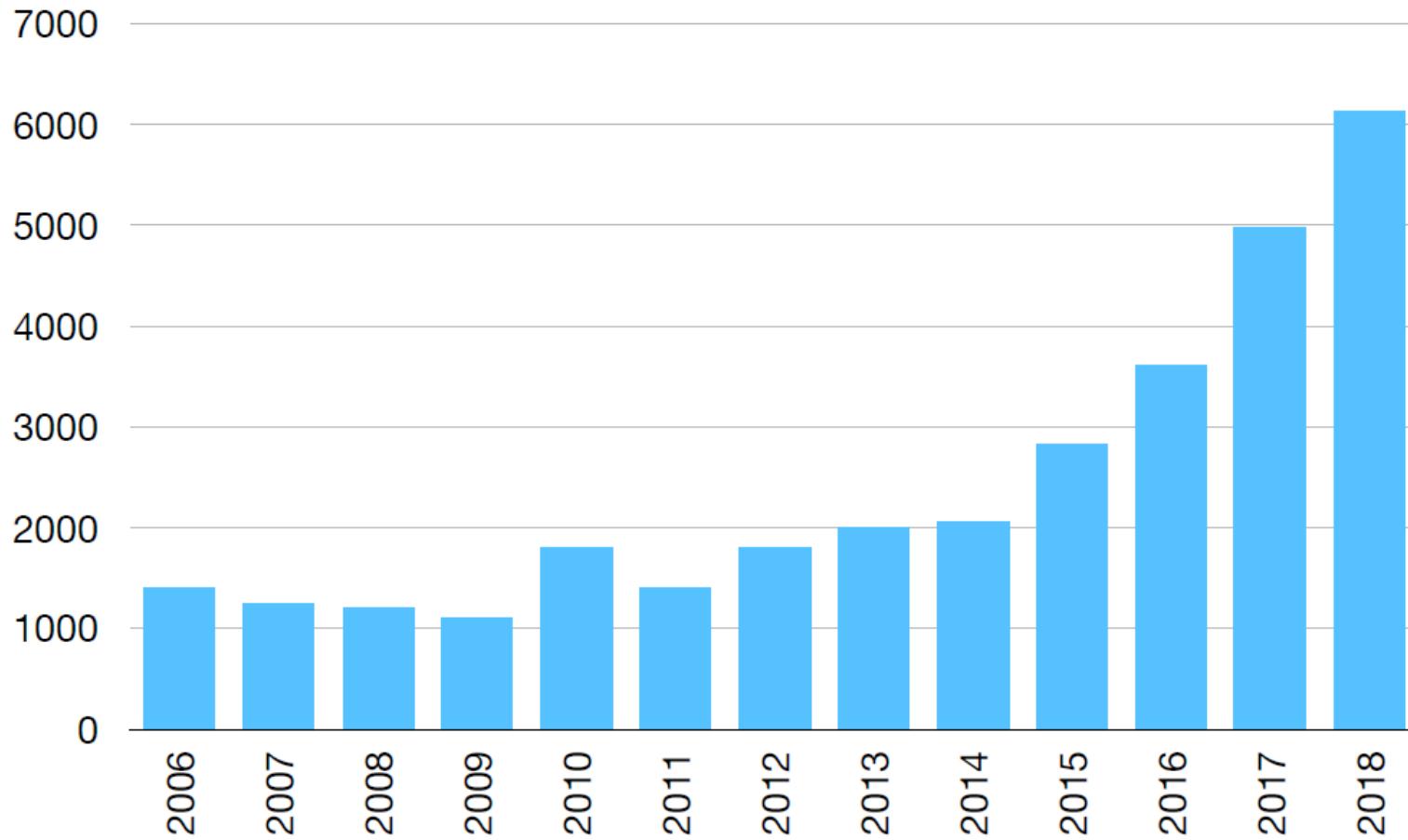


Medical and scientific images

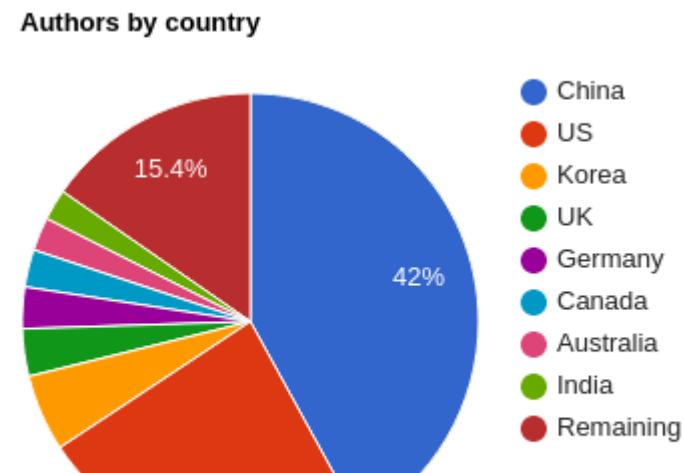
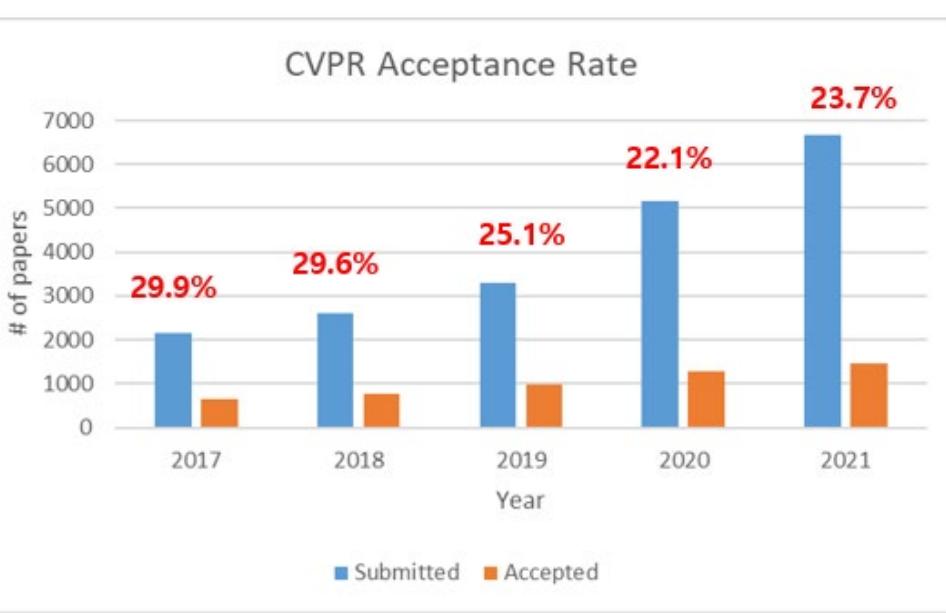
Why study computer vision?

- Vision is useful
- Vision is interesting
- Vision is difficult
 - Half of primate cerebral cortex is devoted to visual processing
- Vision is hot! (mainly due to the advance in machine,..., well deep learning techniques)

CVPR Attendance



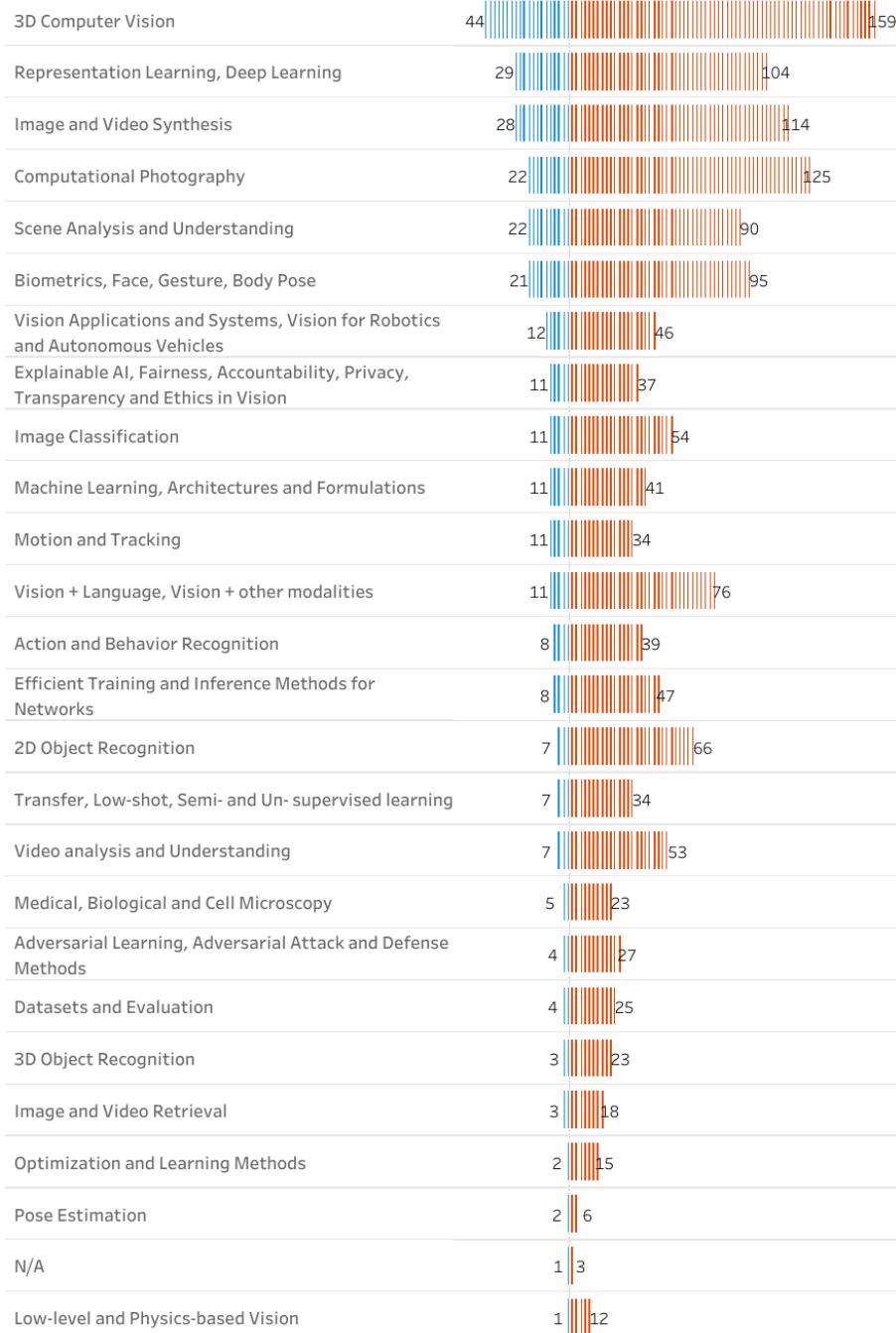
CVPR 2021 (1663 papers, 23.6%)



CVPR 2021

click an area ▼ to filter paper list

▼ Oral Poster



Why is computer vision difficult?

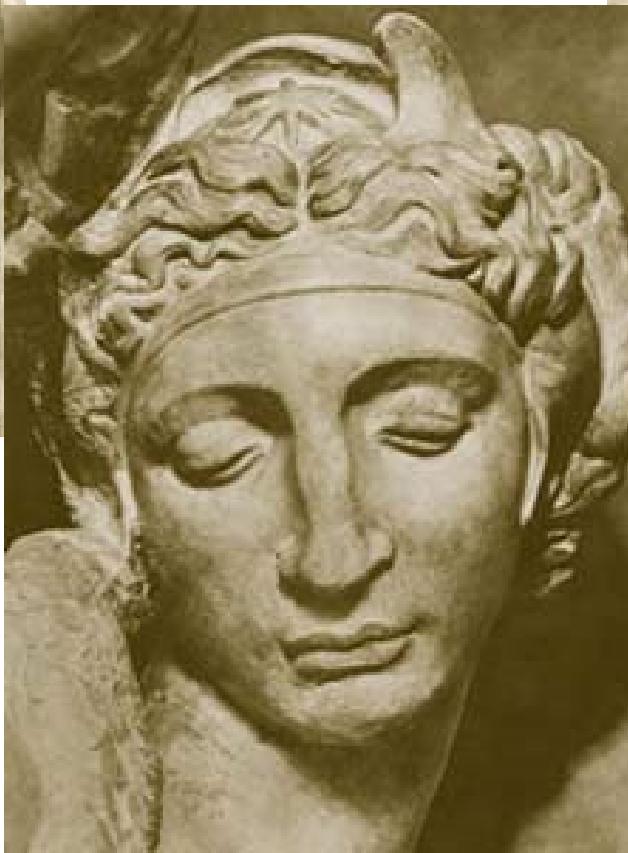
Alpha-Go vs. Image Recognition



Difficulty



Challenges: viewpoint variation



Michelangelo 1475-1564

slide credit: Fei-Fei, Fergus & Torralba

Challenges: illumination

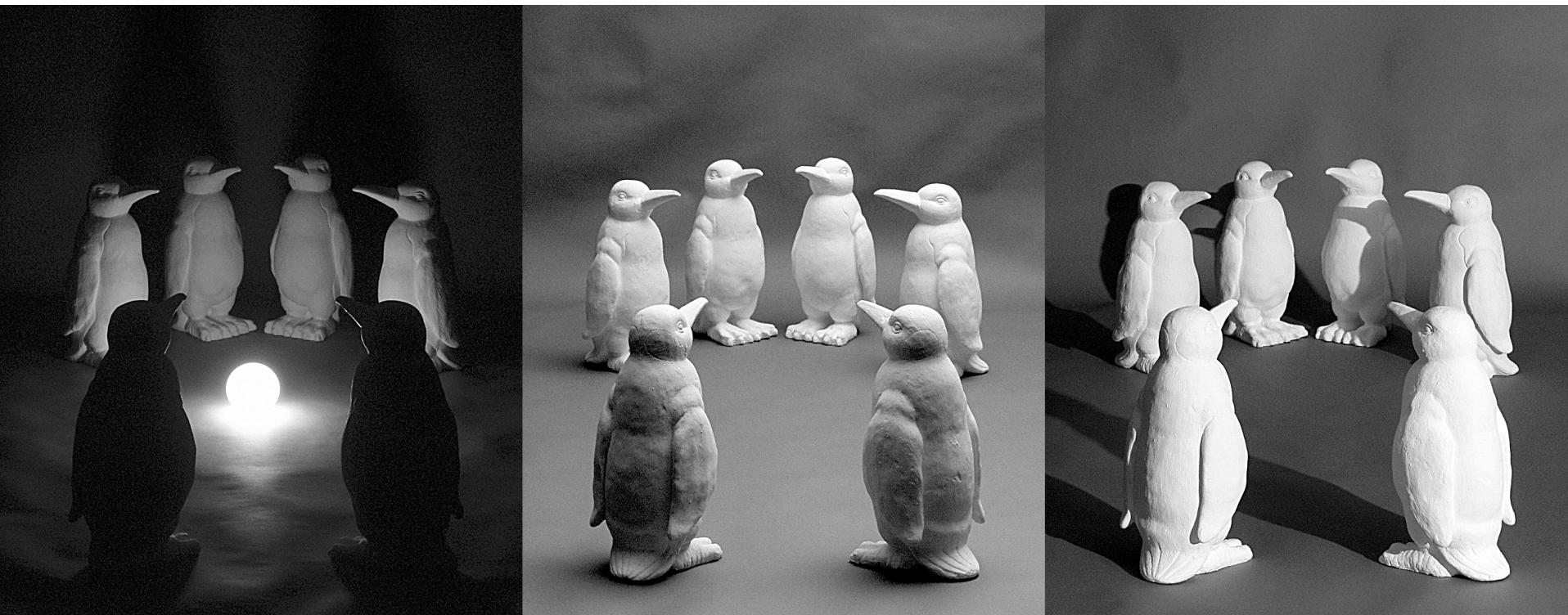


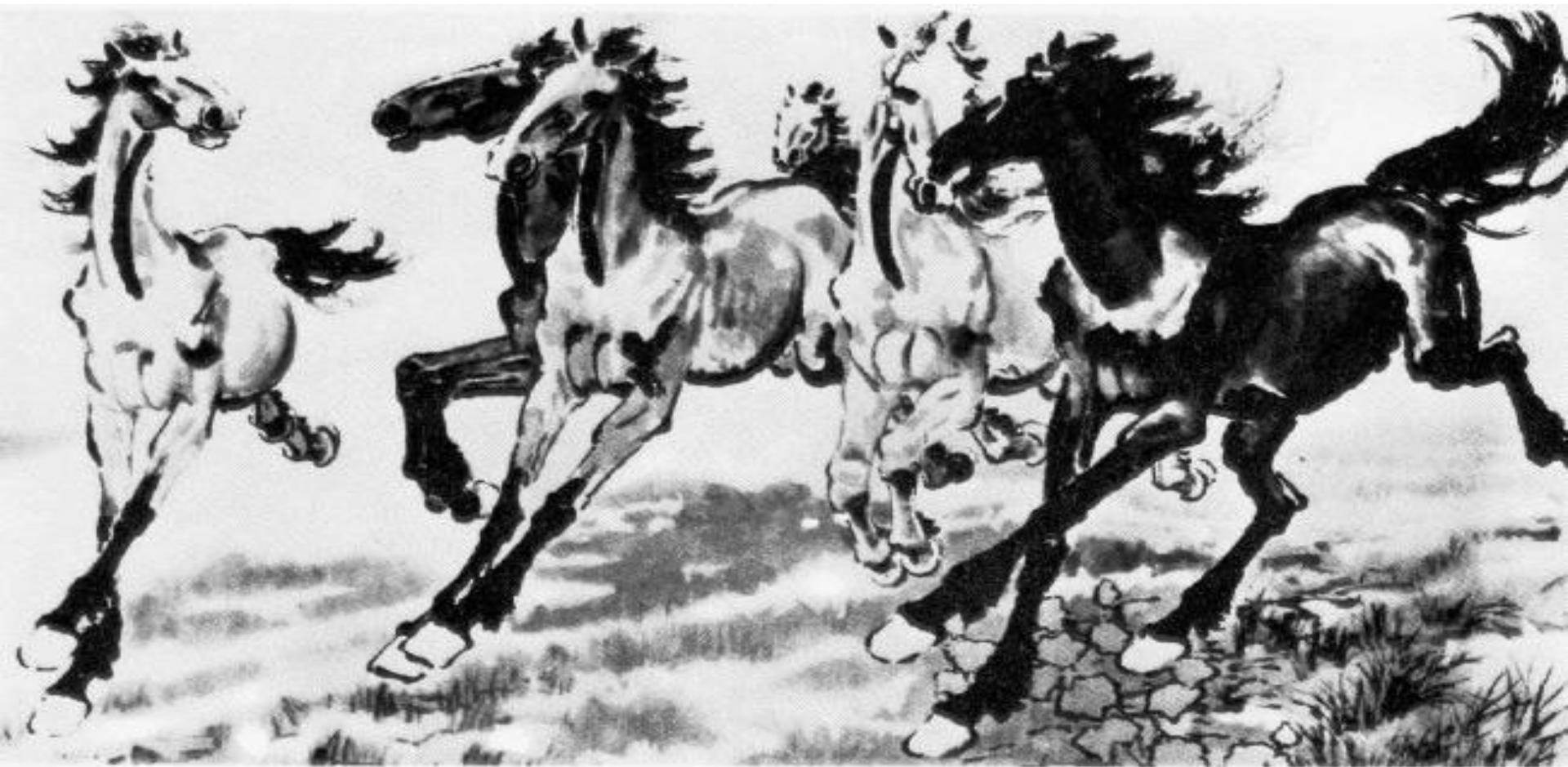
image credit: J. Koenderink

Challenges: scale



slide credit: Fei-Fei, Fergus & Torralba

Challenges: deformation



Xu, Beihong 1943

Challenges: occlusion



Magritte, 1957

slide credit: Fei-Fei, Fergus & Torralba

Challenges: background clutter



Emperor shrimp and commensal crab on a sea cucumber in Fiji
Photograph by Tim Laman

NATIONAL
GEOGRAPHIC

Challenges: Motion



Challenges: object intra-class variation



slide credit: Fei-Fei, Fergus & Torralba

Challenges or opportunities?

- Images are confusing, but they also reveal the structure of the world through numerous cues
- Our job is to interpret the cues!



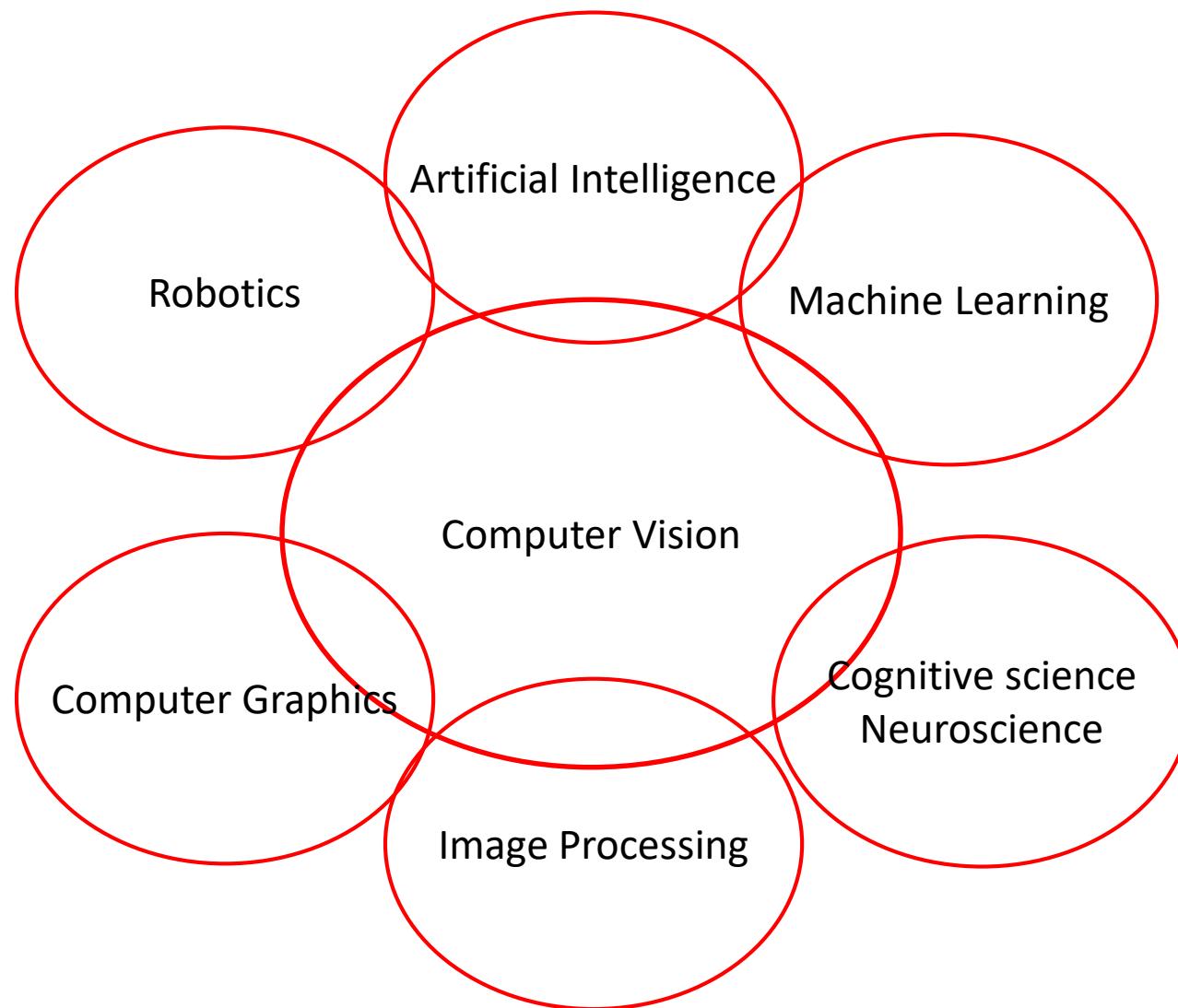
Bottom line

- Perception is an inherently ambiguous problem
 - Many different 3D scenes could have given rise to a particular 2D picture



- Possible solutions
 - Bring in more constraints (more images)
 - Use prior knowledge about the structure of the world
- Need a combination of different methods

Connections to other disciplines



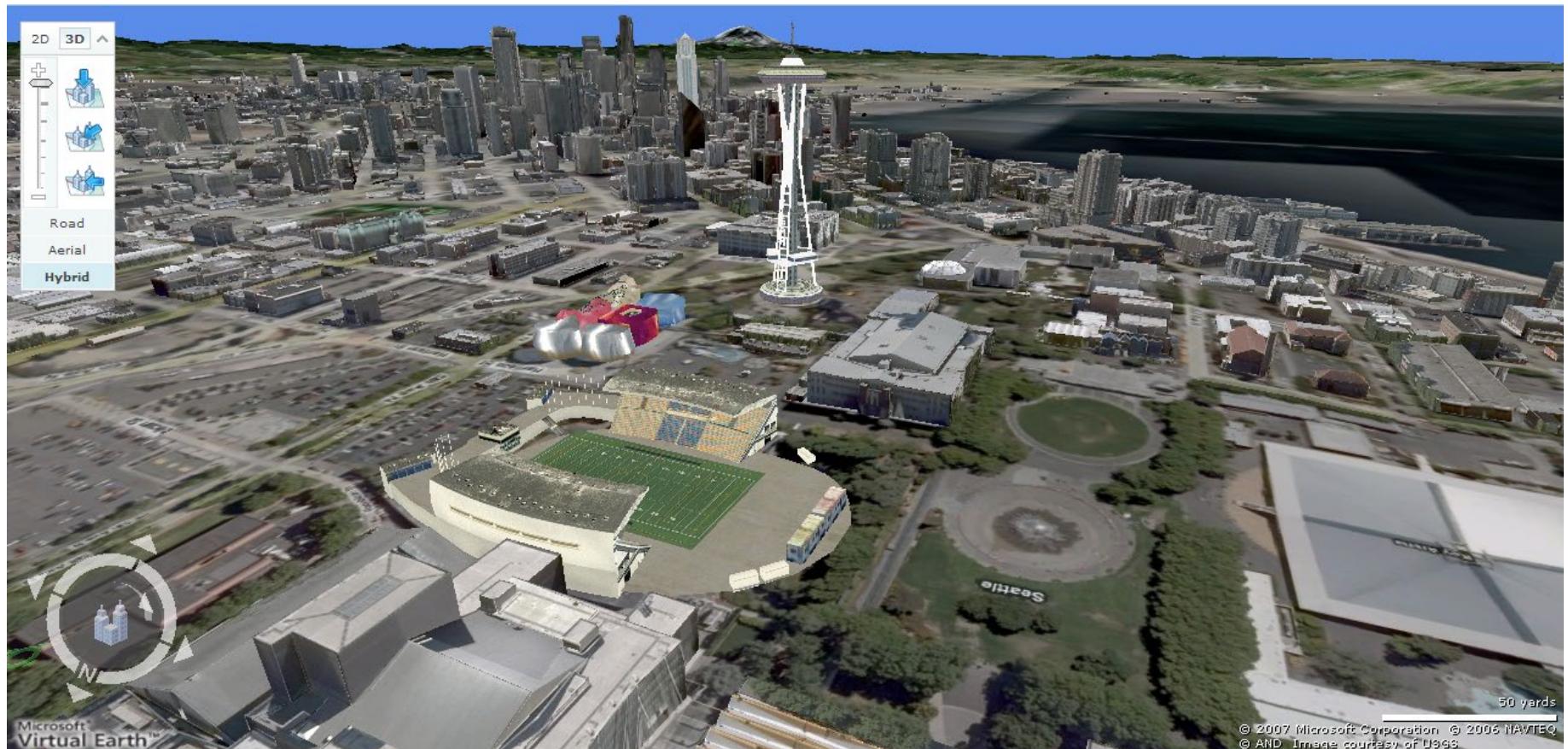
Computer Vision in the Real World

Special effects: shape and motion capture



Source: S. Seitz

3D urban modeling



Bing maps, Google Streetview

Source: S. Seitz

Face detection

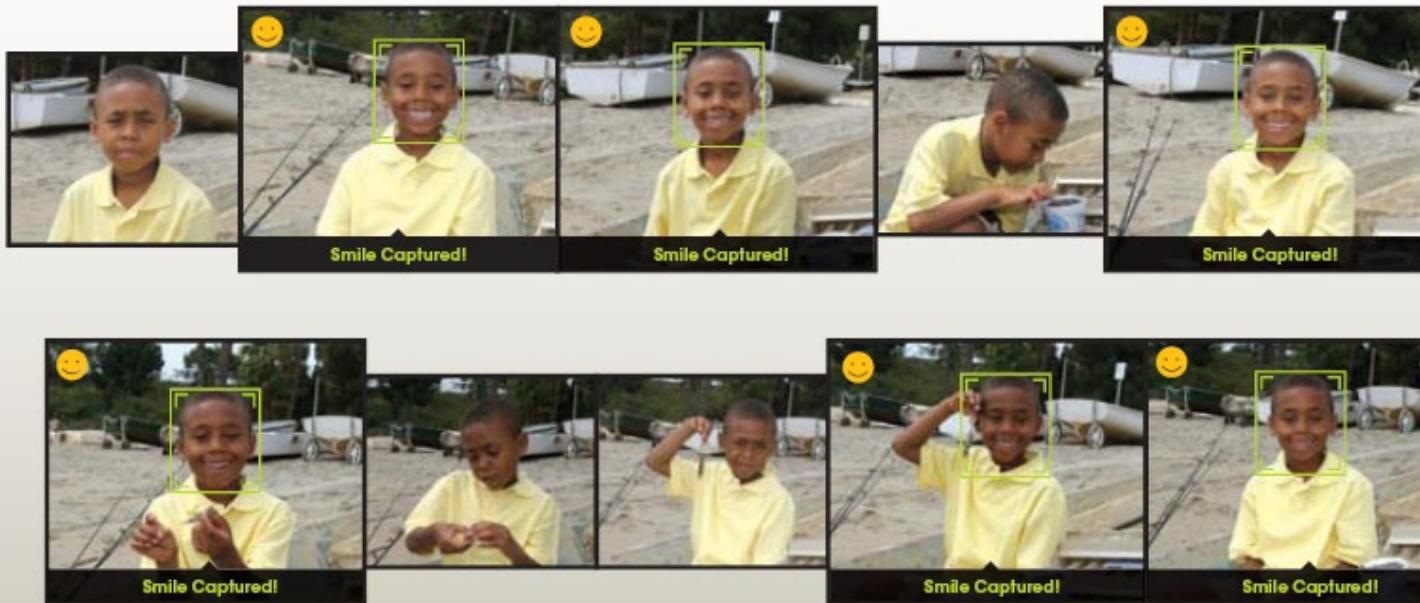


- Many new digital cameras now detect faces
 - Canon, Sony, Fuji, ...

Smile detection

The Smile Shutter flow

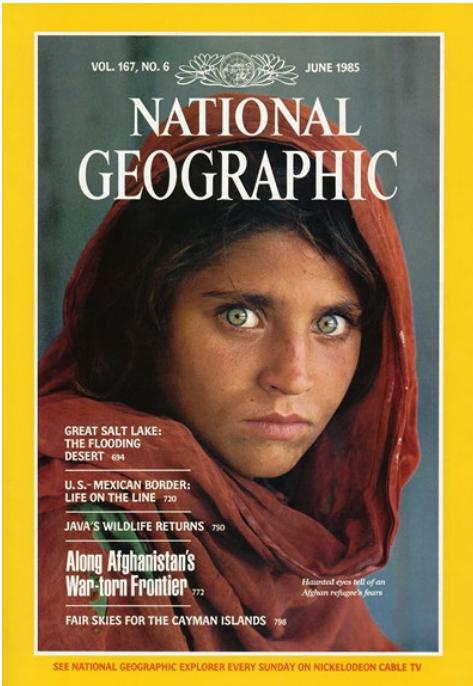
Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



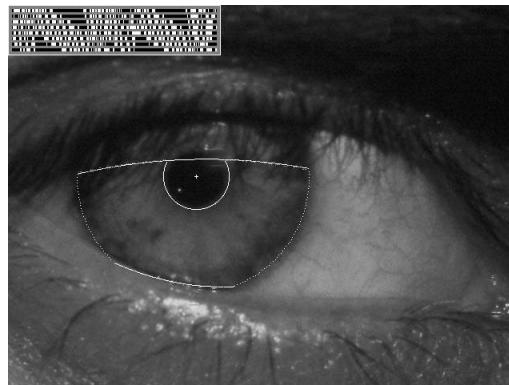
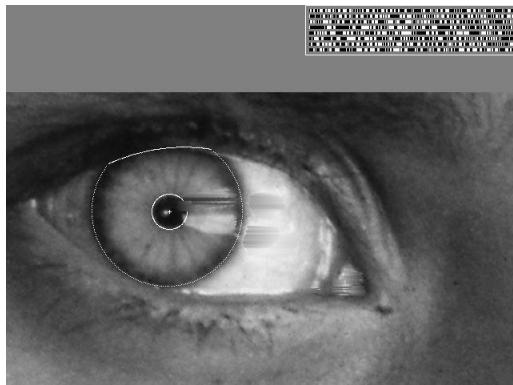
[Sony Cyber-shot® T70 Digital Still Camera](#)

Source: S. Seitz

Biometrics



How the Afghan Girl was Identified by Her Iris Patterns

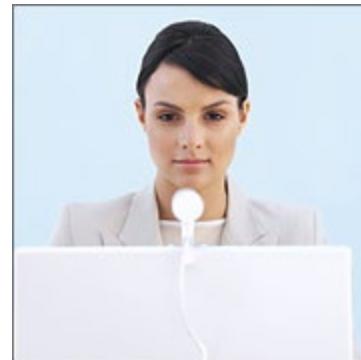


Source: S. Seitz

Biometrics



Fingerprint scanners on
many new laptops,
other devices

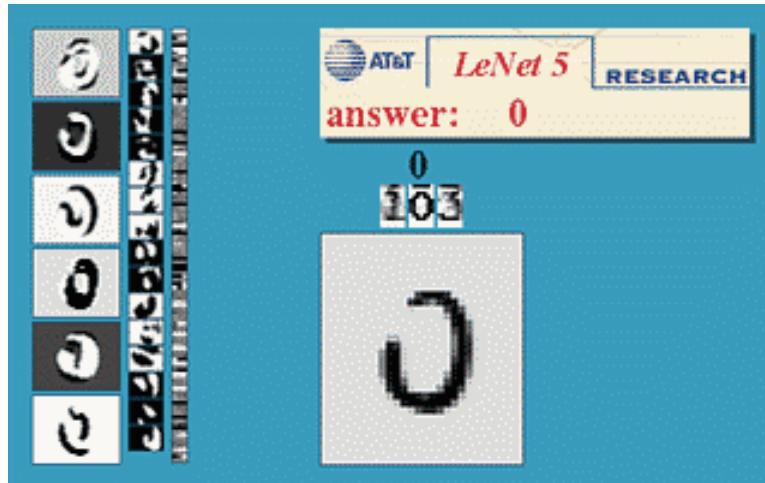


Face recognition systems now beginning
to appear more widely
<http://www.sensiblevision.com/>

Optical character recognition (OCR)

Technology to convert scanned docs to text

- If you have a scanner, it probably came with OCR software



Digit recognition, AT&T labs



License plate readers

http://en.wikipedia.org/wiki/Automatic_number_plate_recognition

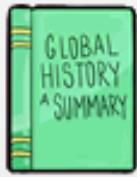
Mobile visual search: Google Goggles

Google Goggles in Action

Click the icons below to see the different ways Google Goggles can be used.



[Landmark](#)



[Book](#)



[Contact Info.](#)



[Artwork](#)



[Places](#)



[Wine](#)



[Logo](#)



Automotive safety

▷▷ manufacturer products consumer products ◀◀

Our Vision. Your Safety.

rear looking camera forward looking camera side looking camera

EyeQ Vision on a Chip

> read more

Vision Applications

Road, Vehicle, Pedestrian Protection and more

> read more

AWS Advance Warning System

> read more

News

- Mobileye Advanced Technologies Power Volvo Cars World First Collision Warning With Auto Brake System
- Volvo: New Collision Warning with Auto Brake Helps Prevent Rear-end

> all news

Events

- Mobileye at Equip Auto, Paris, France
- Mobileye at SEMA, Las Vegas, NV

> read more

- Mobileye: Vision systems in high-end BMW, GM, Volvo models
 - “In mid 2010 Mobileye will launch a world's first application of full emergency braking for collision mitigation for pedestrians where vision is the key technology for detecting pedestrians.”

Vision for robotics, space exploration



[NASA'S Mars Exploration Rover Spirit](#) captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

Vision systems (JPL) used for several tasks

- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read “[Computer Vision on Mars](#)” by Matthies et al.

Everything Changed with Deep Learning

Deep Learning

Computer Vision + Natural Language Processing

- image captioning



"man in black shirt is playing guitar."



"construction worker in orange safety vest is working on road."



"two young girls are playing with lego toy."



"boy is doing backflip on wakeboard."



"girl in pink dress is jumping in air."



"black and white dog jumps over bar."



"young girl in pink shirt is swinging on swing."



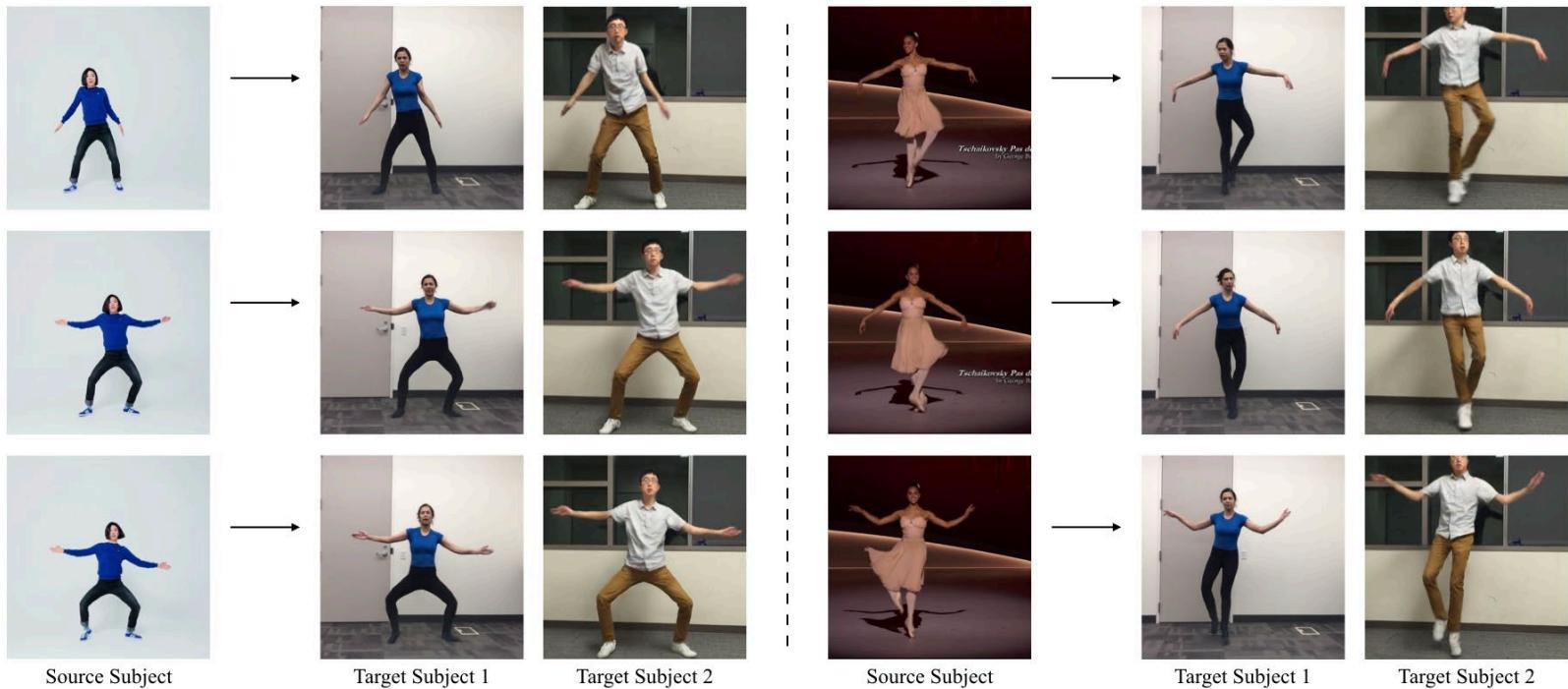
"man in blue wetsuit is surfing on wave."

Amazon Go



<https://www.youtube.com/watch?v=NrmMk1Myrxc>

Everybody dance now



https://www.youtube.com/watch?time_continue=2&v=PCBTZh41Ris

DALL-E 2



DALL-E 2's interpretation of "A photo of an astronaut riding a horse."

NeRF

NeRF

Representing Scenes as Neural Radiance Fields for View Synthesis



<https://www.youtube.com/watch?v=DJ2hcC1orc4>

Computer Vision, where to look for?

- Major Conferences :

CVPR (Computer Vision and Pattern Recognition, every yr)

ICCV (International Conference on Computer Vision, every 2 yr)

ECCV (European Conference on Computer Vision, every 2 yr)

NeurIPS (every year), ICML (every year), ICLR (every year)

SIGGRAPH, SIGGRAPH Asia (computer graphics, every year)

- Major Journals:

IEEE TPAMI (IEEE Transactions on Pattern Analysis and Machine Intelligence)

IJCV (International Journal of Computer Vision)

ACM TOG (Transactions on Graphics)

Excited???