

GANs (Generative Adversarial Nets)

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Abstract

Introduction

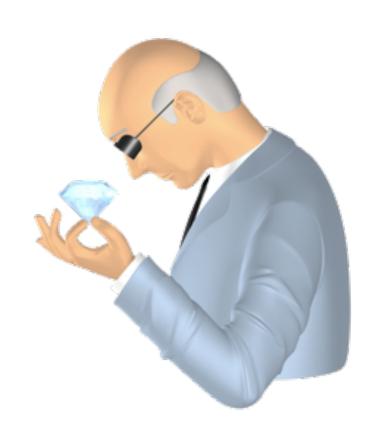
Adversarial Nets

Theoretical Results

Experiments & Conclusions



Alchemist (Generator)



Jeweler (Discriminator)

The coolest idea in ML in the last twenty years - Yann Lecun



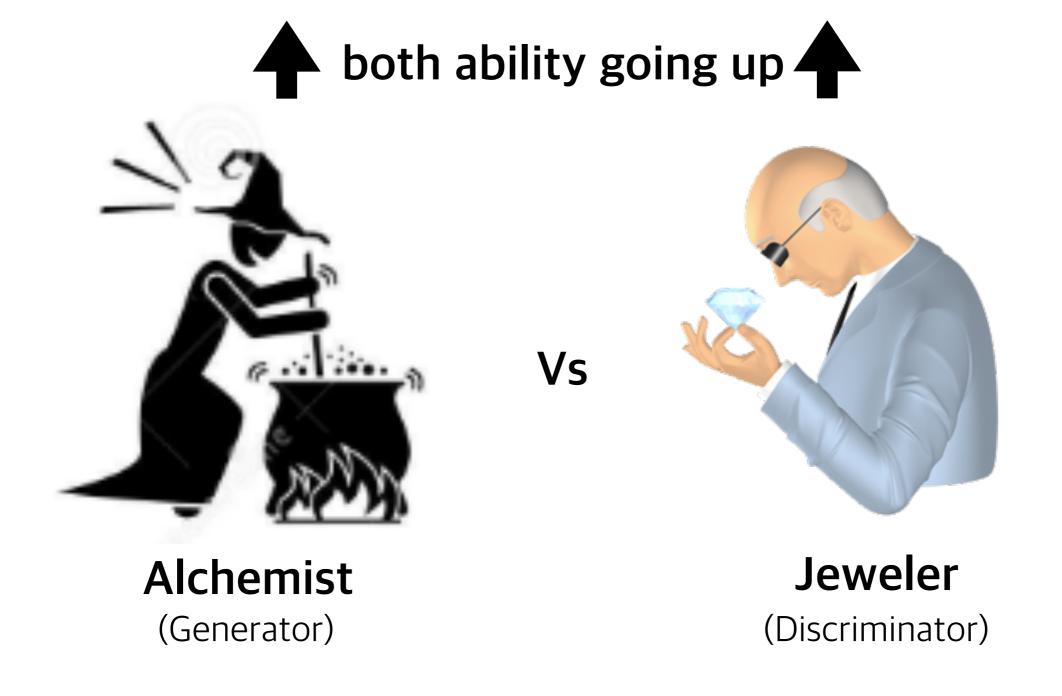
Alchemist (Generator)

She have to make gold bars that others can not distinguish.

He must distinguish the Fake.



Jeweler (Discriminator)



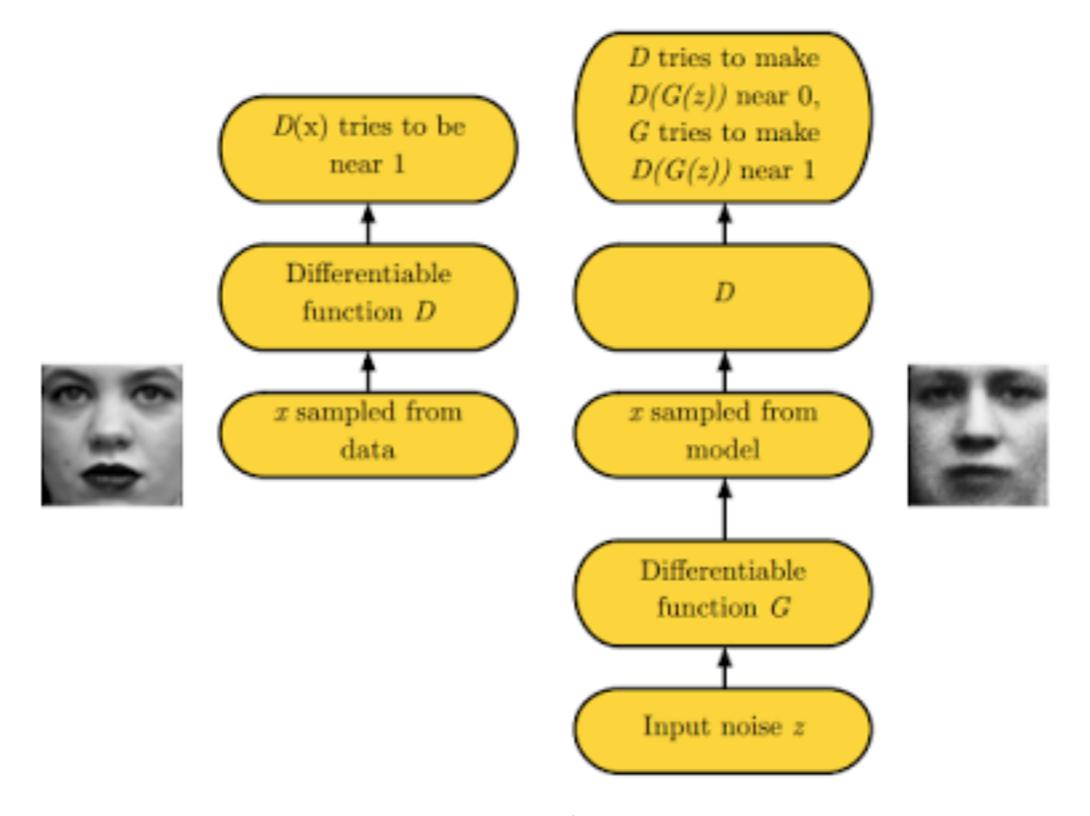
Goal: It can not really tell whether this is real gold or not



Alchemist

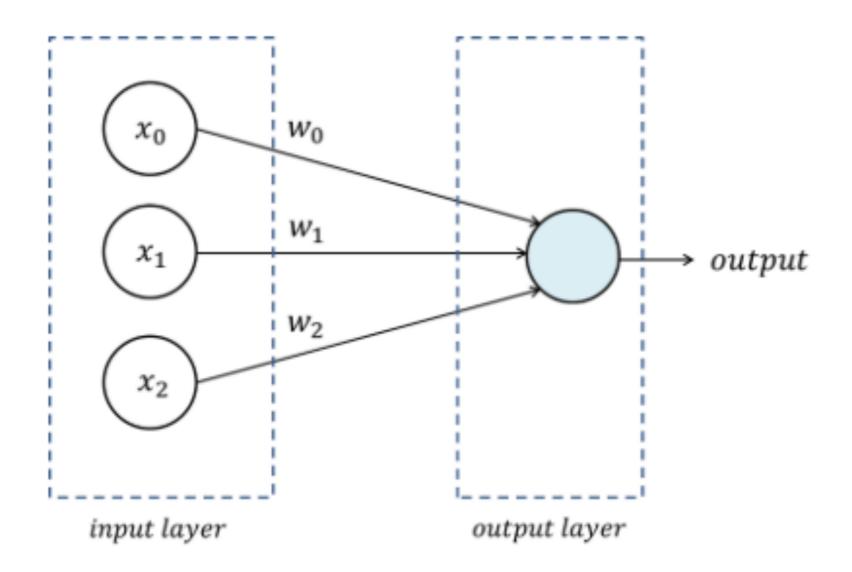
Discriminator (D)

Jeweler



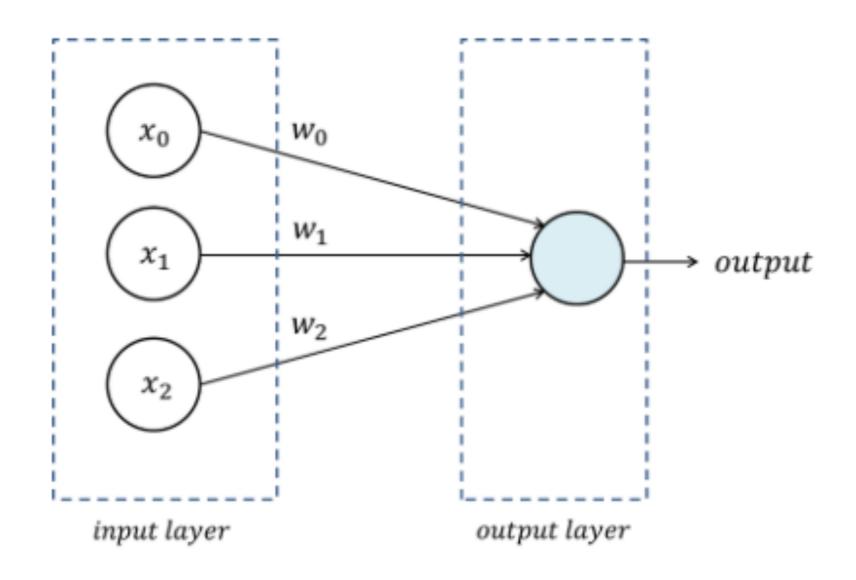
출처: NIPS 2016 Tutorial: Generative Adversarial Networks

Single-layer Perceptron



출처: http://untitledtblog.tistory.com/27

Multi-layer Perceptron



+ Hidden Layer + backpropagation

출처: http://untitledtblog.tistory.com/27

Define multilayer perceptron G (Generator)

Generator distribution: Pg

generator input : noise variables $P_z(z)$

Data space : G (z; θ_g)

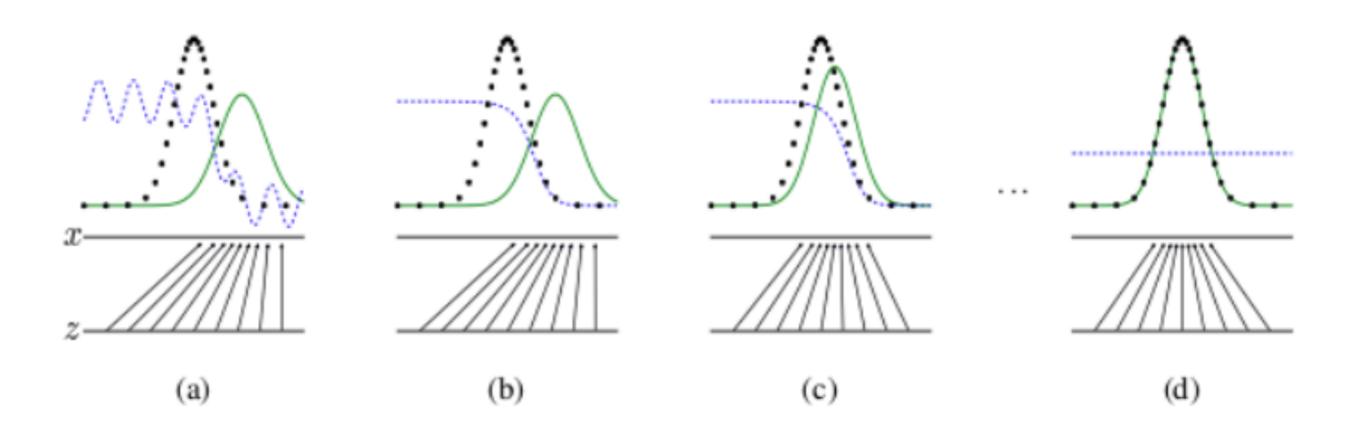
Define multilayer perceptron D(Discriminator)

Data space : D (x; θ_d)

Output: Probability (Fake or not)

It could use another method, but this paper used multilayer perceptron model for D and G.

$$\min_{G} \max_{D} V(D, G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})} [\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})} [\log (1 - D(G(\boldsymbol{z})))].$$



 \dots : data generating distribution x, z: domain

==== : generative distribution === : x = G(z) mapping

: discriminator distribution

Two result

- 1. Introduced method will get global optimum when $P_g = P_{data}$
- 2. They prove that the algorithm presented in the paper finds the global optimum

Proposition

For G fixed, the optimal discriminator D is

$$D_G^*(x) = rac{p_{data}\left(x
ight)}{p_{data}\left(x
ight) + p_g(x)}.$$

Proof. The training criterion for the discriminator D, given any generator G, is to maximize the quantity V(G,D)

$$egin{aligned} V(G,D) &= \int_x p_{data} \; (x) log(D(x)) dx + \int_z p_z(z) log(1-D(G(z))) dz \ &= \int_x p_{data} \; (x) log(D(x)) + p_g(x) log(1-D(x)) dx \end{aligned}$$

For any $(a,b) \in \mathbb{R}^2 \setminus \{0,0\}$, the function $y \to alog(y) + blog(1-y)$ achieves its maximum in [0,1] at $\frac{a}{a+b}$. The discriminator does not need to be defined outside of $Supp(p_{data}) \cup Supp(p_g)$, concluding the proof.

Main Theorem

The global minimum of the virtual training criterion C(G) is Achieved if and only if $P_g = P_{data}$. At that point, C(G) achieves the value -log4

$$egin{aligned} C(G) &= \max_D V(G,D) \ &= \mathbb{E}_{x \sim p_{data}} \left[log D_G^*(x)
ight] + \mathbb{E}_{z \sim p_z} \left[log (1 - D_G^*(G(z)))
ight] \ &= \mathbb{E}_{x \sim p_{data}} \left[log D_G^*(x)
ight] + \mathbb{E}_{x \sim p_g} \left[log (1 - D_G^*(x))
ight] \ &= \mathbb{E}_{x \sim p_{data}} \left[log rac{p_{data} \left(x
ight)}{p_{data} \left(x
ight) + p_g(x)}
ight] + \mathbb{E}_{x \sim p_g} \left[log rac{p_g(x)}{p_{data} \left(x
ight) + p_g(x)}
ight] \end{aligned}$$

Kullback-Leibler divergence

$$C(G) = -\log(4) + KL\left(p_{\text{data}} \middle| \frac{p_{\text{data}} + p_g}{2}\right) + KL\left(p_g \middle| \frac{p_{\text{data}} + p_g}{2}\right)$$

Jensen-Shannon divergence

$$C(G) = -\log(4) + 2 \cdot JSD \left(p_{\text{data}} \| p_g\right)$$

Algorithm 1 Minibatch stochastic gradient descent training of generative adversarial nets. The number of steps to apply to the discriminator, k, is a hyperparameter. We used k = 1, the least expensive option, in our experiments.

for number of training iterations do

for k steps do

- Sample minibatch of m noise samples $\{z^{(1)}, \dots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Sample minibatch of m examples $\{x^{(1)}, \dots, x^{(m)}\}$ from data generating distribution $p_{\text{data}}(x)$.
- Update the discriminator by ascending its stochastic gradient:

$$abla_{\theta_d} \frac{1}{m} \sum_{i=1}^m \left[\log D\left(oldsymbol{x}^{(i)} \right) + \log \left(1 - D\left(G\left(oldsymbol{z}^{(i)} \right) \right) \right) \right].$$

end for

- Sample minibatch of m noise samples $\{z^{(1)}, \ldots, z^{(m)}\}$ from noise prior $p_q(z)$.
- Update the generator by descending its stochastic gradient:

$$abla_{ heta_g} rac{1}{m} \sum_{i=1}^m \log \left(1 - D\left(G\left(oldsymbol{z}^{(i)}
ight)
ight)
ight).$$

end for

The gradient-based updates can use any standard gradient-based learning rule. We used momentum in our experiments.

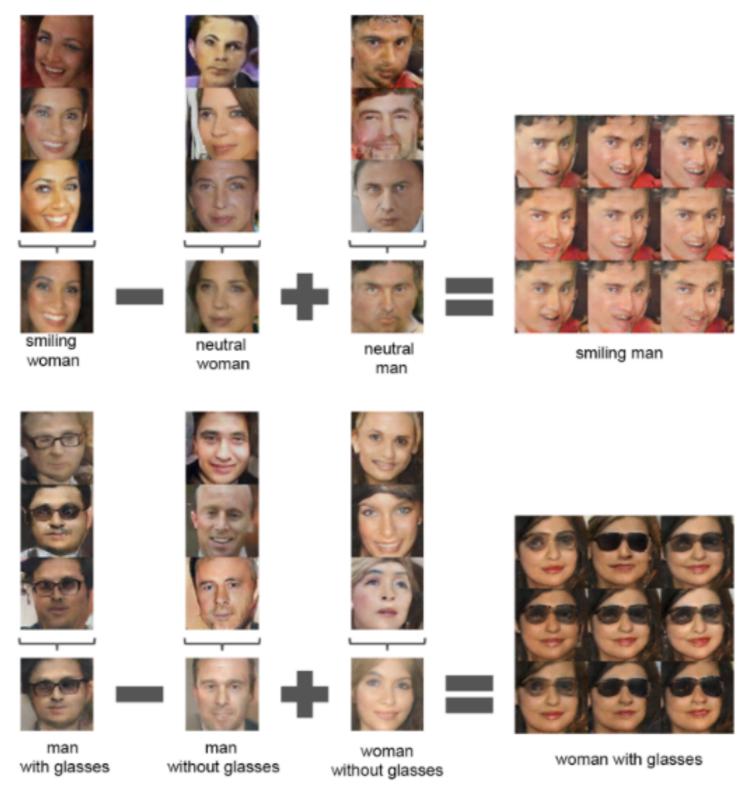
Convergence of Algorithm

Proposition 2. If G and D have enough capacity, and at each step of Algorithm 1, the discriminator is allowed to reach its optimum given G, and p_a is updated so as to improve the criterion

$$\mathbb{E}_{\boldsymbol{x} \sim p_{data}}[\log D_G^*(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{x} \sim p_g}[\log(1 - D_G^*(\boldsymbol{x}))]$$

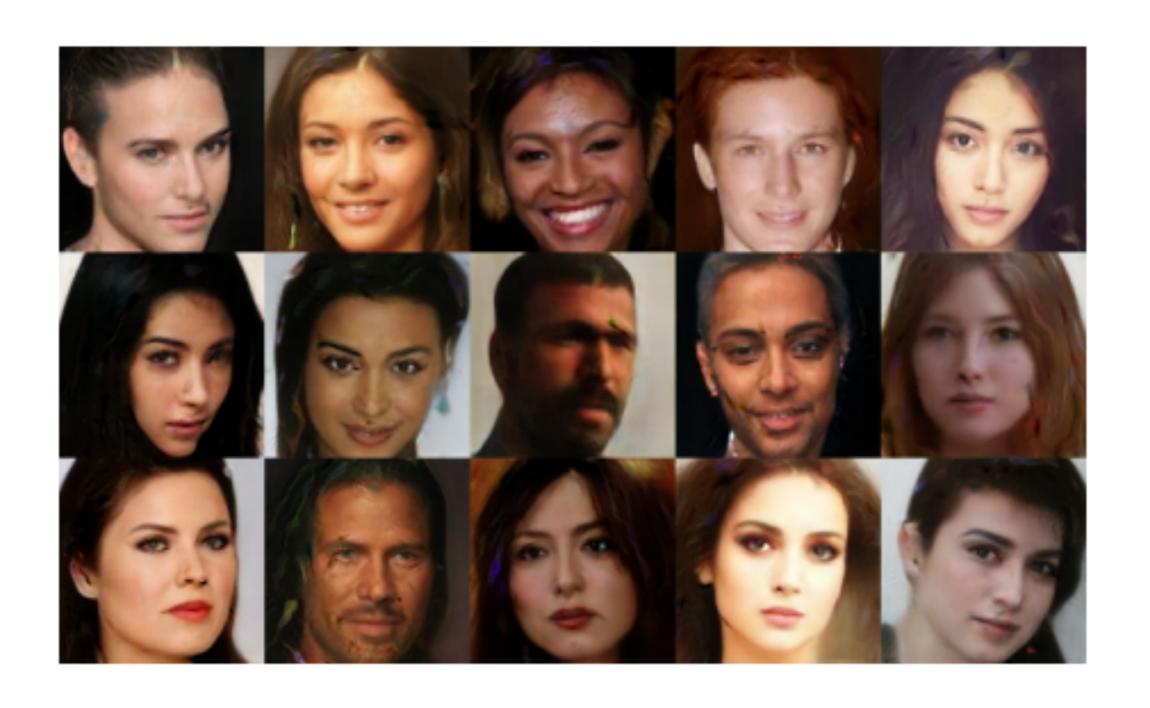
Proof. Consider $V(G,D) = U(p_g,D)$ as a function of p_g as done in the above criterion. Note that $U(p_g,D)$ is convex in p_g . The subderivatives of a supremum of convex functions include the derivative of the function at the point where the maximum is attained. In other words, if $f(x) = \sup_{\alpha \in \mathcal{A}} f_{\alpha}(x)$ and $f_{\alpha}(x)$ is convex in x for every α , then $\partial f_{\beta}(x) \in \partial f$ if $\beta = \arg \sup_{\alpha \in \mathcal{A}} f_{\alpha}(x)$. This is equivalent to computing a gradient descent update for p_g at the optimal D given the corresponding G. $\sup_D U(p_g,D)$ is convex in p_g with a unique global optima as proven in Thm 1, therefore with sufficiently small updates of p_g , p_g converges to p_x , concluding the proof.

Experiments & Conclusions



DCGAN, Alec Radford et al. 2016

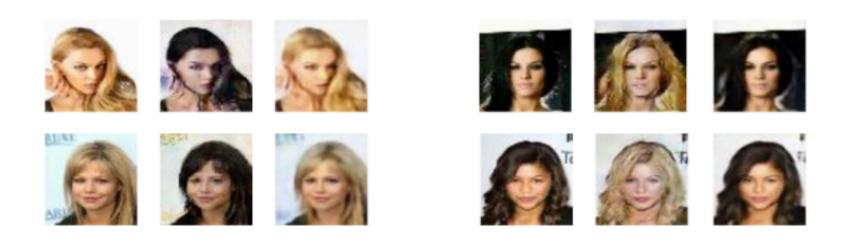
Experiments & Conclusions



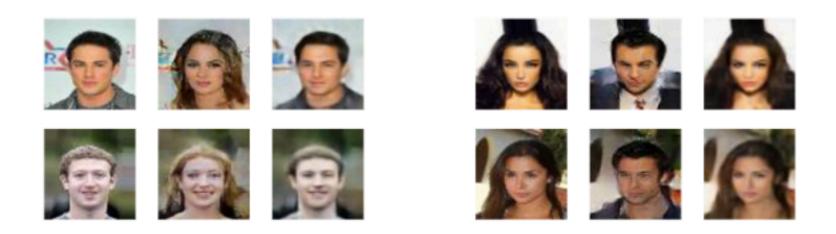
BEGAN, David Berthelot et al. 2017

Experiments & Conclusions

Example results of hair color conversion



Example results of gender conversion (CelebA)



DiscoGAN, Kim taeksoo et al.2017

QnA