

```

#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include <sys/socket.h>
#include <arpa/inet.h>

#include <wiringPi.h>

#define PORT 9000

#define SCK          11      // 온습도 모듈의 TEMP의 SCK를 GPIO 11번에 연결
#define SDA          9      // 온습도 모듈의 TEMP의 SDA를 GPIO 9번에 연결

#define NOACK 0
#define ACK      1

// Addr      Code(command)  r/w
#define MEASURE_TEMP      0x03  // 000      0001
    1
#define MEASURE_HUMI      0x05  // 000      0010
    1
#define READ_STATUS_REG    0x07  // 000      0011
    1
#define WRITE_STATUS_REG   0x06  // 000      0011      0
#define RESET              0x1e  // 000      1111
    0

enum { TEMP, HUMI }; // 온도와 습도를 나타내는 문자열 변수 선언

#define P_PIN  6
#define N_PIN  12 // fan전원은 5v에 연결

////////////////////////////////////

void SHT11_Init (void);
void Connection_reset (void);
void Transmission_start (void);
float get_SHT11_data (unsigned char type);
unsigned char Write_byte (unsigned char value);
unsigned char Read_byte (unsigned char ack);
unsigned char Measure (unsigned short *p_value, unsigned short *p_checksum,

```

```

        unsigned char mode);
void calc_SHT11 (unsigned short p_humidity ,unsigned short p_temperature);

float    val_temp, val_humi;
unsigned short SHT11_humi, SHT11_temp;
unsigned short error, checksum;

// SHT11 센서의 TWI(I2C) 사용을 위한 초기화 작업
void SHT11_Init (void)
{
    pinMode(SDA, OUTPUT);
    pinMode(SCK, OUTPUT);
    Connection_reset ();
}

// TWI통신 연결
//-----
// communication reset: DATA-line=1 and at least 9 SCK cycles followed by
transstart
//
//-----
// DATA:                                     |_____|
//
// SCK : _ _ | _ _ | _ _ | _ _ | _ _ | _ _ | _ _ | _ _ | _ _ | _ _ | _ _ | _ _ |
//-----
//-----
void Connection_reset (void)
{
    unsigned char i;
    digitalWrite(SDA, 1);                // Initial state
    digitalWrite(SCK, 0);                // Initial state
    delayMicroseconds(1);
    for (i=0; i<9; i++) {                // 9 SCK cycles
        digitalWrite(SCK, 1);
        delayMicroseconds(1);
        digitalWrite(SCK, 0);
        delayMicroseconds(1);
    }
}

```

```

// 전송 시작 신호
//-----
-----
// generates a transmission start
//      -----
// DATA:      |_____|
//      ---      ---
// SCK :  ___|   |___|   |_____|
//-----
-----
void Transmission_start (void)
{
    digitalWrite(SDA, 1);           //Initial state
    digitalWrite(SCK, 0);           //Initial state
    delayMicroseconds(1);

    digitalWrite(SCK, 1);
    delayMicroseconds(1);

    digitalWrite(SDA, 0);
    delayMicroseconds(1);

    digitalWrite(SCK, 0);
    delayMicroseconds(1);

    digitalWrite(SCK, 1);
    delayMicroseconds(1);

    digitalWrite(SDA, 1);
    delayMicroseconds(1);

    digitalWrite(SCK, 0);
}

//온/습도 데이터 획득
float get_SHT11_data (unsigned char type)
{
    error = 0;

    if (type == HUMI) { // 습도 수치 측정
        // measure humidity

```

```

        error += Measure (&SHT11_humi, &checksum, HUMI);
        if (error != 0) // 에러 발생 시, Connection reset
            Connection_reset ();
        else // - 측정된 값을 바탕으로 온/습도 값
            계산
                calc_SHT11 (SHT11_humi, SHT11_temp);
            return val_humi;
    }
    else if (type == TEMP) { // 온도 수치 측정
        // measure temperature
        error += Measure (&SHT11_temp, &checksum, TEMP);
        if (error != 0) // 에러 발생 시, Connection reset
            Connection_reset ();
        else // - 측정된 값을 바탕으로 온/습도 값
            계산
                calc_SHT11 (SHT11_humi, SHT11_temp);
            return val_temp;
    }
    else {
        return 0;
    }
}

// makes a measurement (humidity/temperature) with checksum
unsigned char Measure (unsigned short *p_value, unsigned short *p_checksum,
    unsigned char mode)
{
    unsigned short error = 0;
    unsigned short SHT11_msb, SHT11_lsb;

    switch (mode) //send command to sensor
    {
        case TEMP : // 온도 요청 신호 송신(센서 디바이스 주소 및 온도 Read
            명령)
                error += Write_byte (MEASURE_TEMP);
                break;
        case HUMI : // 습도 요청 신호 송신(센서 디바이스 주소 및 습도 Read
            명령)
                error += Write_byte (MEASURE_HUMI);
                break;
        default :

```

```

        break;
    }
    if (error != 0)
        return error;

    pinMode(SDA, INPUT); // 데이터 수신 대기

    while (digitalRead(SDA)); // 센서가 센싱한 데이터를 보내 줄 때까지 대기
                                //
    pinMode(SDA, INPUT);

    // 데이터 수신
    SHT11_msb = Read_byte (ACK); // read the first
byte (MSB)
    SHT11_lsb = Read_byte (ACK); // read the second
byte (LSB)
    *p_value = (SHT11_msb * 256) + SHT11_lsb;
    *p_checksum = Read_byte (NOACK); // read checksum

    return error;
}

//데이터 송신
// writes a byte on the Sensibus and checks the acknowledge
unsigned char Write_byte (unsigned char value)
{
    unsigned char i, error = 0;
    pinMode(SDA, OUTPUT);
    for (i=0x80; i>0; i/=2) { // shift bit for masking
        if (i & value) digitalWrite(SDA, 1); // masking value with i , write
to SENSI-BUS
        else          digitalWrite(SDA, 0);

        delayMicroseconds(1);
        digitalWrite(SCK, 1); // clk for SENSI-BUS
        delayMicroseconds(1);
        digitalWrite(SCK, 0);
        delayMicroseconds(1);
    }
    digitalWrite(SDA, 1); // release DATA-line
    pinMode(SDA, INPUT);

```

```

    delayMicroseconds(1);
    digitalWrite(SCK, 1);    // clk #9 for ack
    error    =    digitalRead(SDA); // check ack (DATA will be pulled down
by SHT11)

```

```

    digitalWrite(SCK, 0);
    pinMode(SDA, OUTPUT);

```

```

    return error; // error=1 in case of no acknowledge
}

```

//데이터 수신

// reads a byte from the Sensibus and gives an acknowledge in case of "ack=1"

```

unsigned char Read_byte(unsigned char ack)

```

```

{

```

```

    unsigned char i, val    =    0;

```

```

    digitalWrite(SDA, 1); // release DATA-line
    pinMode(SDA, INPUT);
    delayMicroseconds(1);

```

```

    for (i=0x80; i>0; i/=2) { // shift bit for masking
        digitalWrite(SCK, 1); // clk for SENSI-BUS
        delayMicroseconds(1);
        if (digitalRead(SDA)) // read bit
            val = (val | i);
        digitalWrite(SCK, 0);
        delayMicroseconds(1);
    }

```

```

    pinMode(SDA, OUTPUT);

```

```

    if (ack) digitalWrite(SDA, 0); // in case of "ack==1" pull down DATA-Line
    else          digitalWrite(SDA, 1);

```

```

    digitalWrite(SCK, 1);    // clk #9 for ack
    delayMicroseconds(1);
    digitalWrite(SCK, 0);
    delayMicroseconds(1);
    digitalWrite(SDA, 1);    // release DATA-line

```

```

    return val;

```

```
}
```

```
//온/습도 값 계산 함수(센서로부터 수신한 값은 변환이 필요)
```

```
void calc_SHT11 (unsigned short humidity, unsigned short temperature)
```

```
{
```

```
    const float C1 =      -2.0468;          // for 12 Bit
```

```
    const float C2 =      0.0367;          // for 12 Bit
```

```
    const float C3 =     -0.0000015955;    // for 12 Bit
```

```
    const float T1 =      0.01;             // for 12 Bit
```

```
    const float T2 =      0.00008;         // for 12 Bit
```

```
    float rh_lin;           // Relative Humidity
```

```
    float rh_true;         // Humidity Sensor RH/Temperature compensation
```

```
    float t_C;             // Temperature
```

```
    float rh =             (float)humidity;
```

```
    float t                =      (float)temperature;
```

```
    t_C                    =      ((t * 0.01) - 40.1) - 5;
```

```
    rh_lin                 =      (C3 * rh * rh) + (C2 * rh) + C1;
```

```
    rh_true                =      (t_C - 25) * (T1 + (T2 * rh)) + rh_lin;
```

```
    if (rh_true > 100)      rh_true = 100;
```

```
    if (rh_true < 0.1)      rh_true = 0.1;
```

```
    val_temp               =      t_C;
```

```
    val_humi               =      rh_true;
```

```
}
```

```
float temp;
```

```
int main (void)
```

```
{
```

```
    if(wiringPiSetupGpio() == -1)
```

```
        return 1;
```

```
    SHT11_Init(); //온/습도 센서 초기 설정
```

```
    pinMode(P_PIN, OUTPUT);
```

```
    pinMode(N_PIN, OUTPUT);
```

```

int s_socket, c_socket;
struct sockaddr_in s_addr, c_addr;

int n;
int len;
char rcvBuffer[BUFSIZ];

s_socket = socket(PF_INET, SOCK_STREAM, IPPROTO_TCP);

memset(&s_addr, 0, sizeof(s_addr));
s_addr.sin_addr.s_addr = htonl(INADDR_ANY);
s_addr.sin_family = AF_INET;
s_addr.sin_port = htons(PORT);

if(bind(s_socket, (struct sockaddr*)&s_addr, sizeof(s_addr)) == -1){
    printf("Can not Bind!!!\n");
    return -1;
}

if(listen(s_socket, 5) == -1){
    printf("Listen Fail!!!\n");
    return -1;
}

printf("Temp Server started...\n");

while(1){
    len = sizeof(c_addr);
    c_socket = accept(s_socket, (struct sockaddr*)&c_addr, &len);
    printf("Connected IP : %s\n", inet_ntoa(c_addr.sin_addr));

    while((n = read(c_socket, rcvBuffer, sizeof(rcvBuffer))) > 0){
        rcvBuffer[n] = '\0';
        //printf("%s", rcvBuffer);
        if(strncmp(rcvBuffer, "temp", 4) == 0){

            Transmission_start(); // 전송 시작
            temp = get_SHT11_data (TEMP); // Sensing Temp
            delay(10);

            printf("Temp = %2.2f [C]\n", temp);

```



```

        sprintf(rcvBuffer, "%2.2f", temp);

        rcvBuffer[5] = '\n';
        delay(1);
        write(c_socket, rcvBuffer, 6);
    }else if(strncmp(rcvBuffer, "on", 2) == 0){
        digitalWrite(P_PIN, HIGH);
        digitalWrite(N_PIN, LOW);
        rcvBuffer[2] = '\n';

        delay(1);
        write(c_socket, rcvBuffer, 3);
    }else if(strncmp(rcvBuffer, "off", 2) == 0){
        digitalWrite(P_PIN, LOW);
        digitalWrite(N_PIN, LOW);
        rcvBuffer[3] = '\n';
        delay(1);
        write(c_socket, rcvBuffer, 4);
    }
}

}

return 0;
}

```